Quantum Computer Outreach Project

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Contents

1	1 Todo List	1
2	2 Data Structure Index	3
	2.1 Data Structures	 3
3	3 File Index	5
	3.1 File List	 5
4	4 Data Structure Documentation	7
	4.1 cycle_node Struct Reference	 7
	4.1.1 Detailed Description	 8
	4.2 LED Struct Reference	 8
	4.2.1 Detailed Description	 8
	4.3 LED_GLOBAL Struct Reference	 8
	4.3.1 Detailed Description	 9
	4.4 RGB Struct Reference	 9
	4.4.1 Detailed Description	9

ii CONTENTS

5	File	Docum	entation	11
	5.1	dspic3	3e/qcomp-sim-c.X/algo.c File Reference	11
		5.1.1	Detailed Description	12
		5.1.2	Function Documentation	12
			5.1.2.1 gate()	12
			5.1.2.2 two_gate()	12
	5.2	dspic3	3e/qcomp-sim-c.X/algo.h File Reference	13
		5.2.1	Detailed Description	14
		5.2.2	Function Documentation	14
			5.2.2.1 gate()	14
			5.2.2.2 two_gate()	14
	5.3	dspic3	3e/qcomp-sim-c.X/config.h File Reference	15
		5.3.1	Detailed Description	15
	5.4	dspic3	3e/qcomp-sim-c.X/consts.c File Reference	15
		5.4.1	Detailed Description	16
		5.4.2	Variable Documentation	16
			5.4.2.1 H	16
			5.4.2.2 rX	16
			5.4.2.3 X	17
			5.4.2.4 Y	17
			5.4.2.5 Z	17
	5.5	dspic3	3e/qcomp-sim-c.X/consts.h File Reference	18
		5.5.1	Detailed Description	19
		5.5.2	Variable Documentation	19
			5.5.2.1 H	19
			5.5.2.2 rX	19
			5.5.2.3 X	19
			5.5.2.4 Y	19
			5.5.2.5 Z	20
	5.6	dspic3	3e/qcomp-sim-c.X/display.c File Reference	20

CONTENTS

	5.6.1	Detailed	Description	21
	5.6.2	Macro De	efinition Documentation	21
		5.6.2.1	NUM_MAX_AMPS	21
	5.6.3	Function	Documentation	21
		5.6.3.1	display_average()	21
		5.6.3.2	display_cycle()	23
		5.6.3.3	remove_zero_amp_states()	24
		5.6.3.4	sort_states()	24
5.7	dspic3	3e/qcomp-	sim-c.X/display.h File Reference	25
	5.7.1	Detailed	Description	26
	5.7.2	Function	Documentation	26
		5.7.2.1	display_average()	26
		5.7.2.2	display_cycle()	28
		5.7.2.3	remove_zero_amp_states()	28
		5.7.2.4	sort_states()	29
5.8	dspic3	3e/qcomp-	sim-c.X/io.c File Reference	29
	5.8.1	Detailed	Description	31
	5.8.2	Macro De	efinition Documentation	31
		5.8.2.1	BTN_CHIP_NUM	31
	5.8.3	Function	Documentation	32
		5.8.3.1	attribute()	32
		5.8.3.2	add_to_cycle()	32
		5.8.3.3	flash_all()	33
		5.8.3.4	flash_led()	33
		5.8.3.5	led_color_int()	33
		5.8.3.6	led_cycle_test()	34
		5.8.3.7	read_btn()	34
		5.8.3.8	read_external_buttons()	34
		5.8.3.9	reset_cycle()	35
		5.8.3.10	set_external_led()	35

iv CONTENTS

		5.8.3.11	set_led()	35
		5.8.3.12	set_strobe()	36
		5.8.3.13	setup_external_leds()	36
		5.8.3.14	setup_io()	36
		5.8.3.15	TLC591x_mode_switch()	37
		5.8.3.16	toggle_strobe()	37
		5.8.3.17	update_display_buffer()	37
		5.8.3.18	write_display_driver()	38
	5.8.4	Variable	Documentation	38
		5.8.4.1	buttons	39
		5.8.4.2	isr_counter	39
		5.8.4.3	led_global	39
5.9	dspic3	3e/qcomp-	-sim-c.X/io.h File Reference	39
	5.9.1	Detailed	Description	42
	5.9.2	Function	Documentation	42
		5.9.2.1	add_to_cycle()	42
		5.9.2.2	flash_all()	43
		5.9.2.3	flash_led()	43
		5.9.2.4	led_color_int()	43
		5.9.2.5	led_cycle_test()	44
		5.9.2.6	read_btn()	44
		5.9.2.7	read_external_buttons()	44
		5.9.2.8	reset_cycle()	45
		5.9.2.9	set_external_led()	45
		5.9.2.10	set_led()	45
		5.9.2.11	set_strobe()	46
		5.9.2.12	setup_external_leds()	46
		5.9.2.13	setup_io()	46
		5.9.2.14	toggle_strobe()	47
		5.9.2.15	update_display_buffer()	47

CONTENTS

		5.9.2.16 write_display_driver()	48
5.10	dspic33	3e/qcomp-sim-c.X/main.c File Reference	48
	5.10.1	Detailed Description	49
	5.10.2	Function Documentation	49
		5.10.2.1 main()	49
5.11	dspic33	3e/qcomp-sim-c.X/quantum.c File Reference	50
	5.11.1	Detailed Description	50
	5.11.2	Function Documentation	50
		5.11.2.1 absolute()	51
		5.11.2.2 controlled_qubit_op()	52
		5.11.2.3 mat_mul()	52
		5.11.2.4 single_qubit_op()	53
		5.11.2.5 zero_state()	54
5.12	dspic33	3e/qcomp-sim-c.X/quantum.h File Reference	55
	5.12.1	Detailed Description	56
	5.12.2	Function Documentation	56
		5.12.2.1 absolute()	56
		5.12.2.2 controlled_qubit_op()	56
		5.12.2.3 mat_mul()	57
		5.12.2.4 single_qubit_op()	58
		5.12.2.5 zero_state()	59
5.13	dspic33	3e/qcomp-sim-c.X/spi.c File Reference	59
	5.13.1	Detailed Description	60
	5.13.2	Function Documentation	60
		5.13.2.1 send_byte_spi_1()	60
		5.13.2.2 setup_spi()	61
5.14	dspic33	3e/qcomp-sim-c.X/spi.h File Reference	62
	5.14.1	Detailed Description	63
	5.14.2	Function Documentation	63
		5.14.2.1 send_byte_spi_1()	63

vi CONTENTS

		5.14.2.2	setup_	spi()				 	 	 	 	 	 	63
5.15	dspic3	3e/qcomp-	·sim-c.X	tests.c	File R	Referer	nce	 	 	 	 	 	 	64
	5.15.1	Detailed	Descript	ion .				 	 	 	 	 	 	65
	5.15.2	Function	Docume	entation	n			 	 	 	 	 	 	65
		5.15.2.1	dim_le	ds() .				 	 	 	 	 	 	65
		5.15.2.2	swap_f	test().				 	 	 	 	 	 	65
5.16	dspic3	3e/qcomp-	·sim-c.X	tests.h	ı File R	Refere	nce	 	 	 	 	 	 	66
	5.16.1	Detailed	Descript	ion .				 	 	 	 	 	 	67
	5.16.2	Function	Docume	entation	n			 	 	 	 	 	 	67
		5.16.2.1	delay()					 	 	 	 	 	 	67
		5.16.2.2	dim_le	ds() .				 	 	 	 	 	 	67
		5.16.2.3	swap_t	test().				 	 	 	 	 	 	68
5.17	dspic3	3e/qcomp-	sim-c.X	time.c	File R	eferen	ice .	 	 	 	 	 	 	68
	5.17.1	Detailed	Descript	ion .				 	 	 	 	 	 	68
	5.17.2	Function	Docume	entation	n			 	 	 	 	 	 	69
		5.17.2.1	delay()					 	 	 	 	 	 	69
		5.17.2.2	setup_	timer()				 	 	 	 	 	 	69
5.18	dspic3	3e/qcomp-	sim-c.X	time.h	File R	eferen	ice .	 	 	 	 	 	 	69
	5.18.1	Detailed	Descript	ion .				 	 	 	 	 	 	70
	5.18.2	Function	Docume	entation	n			 	 	 	 	 	 	70
		5.18.2.1	delay()					 	 	 	 	 	 	71
		5.18.2.2	setup_	timer()				 	 	 	 	 	 	71
Index														73

Chapter 1

Todo List

```
Global absolute (Complex x)
    Check that the complex part is small
Global BTN_CHIP_NUM
    read buttons
Global controlled_qubit_op (Complex op[2][2], int ctrl, int targ, Complex state[], int N)
    This expression can probably be simplified or broken over lines.
Global display_average (Complex state[], int Qnum)
    rename to display_average
Global display_average (Complex state[], int Qnum)
    rename to display_average
Global led_cycle_test (void)
    This won't work now: write_display_driver(counter);
Global mat_mul (Complex M[2][2], Complex V[], int i, int j)
    Because of the way the array types work (you can't pass a multidimensional array of unknown size) we will also
    need a function for 4x4 matrix multiplication.
Global read_external_buttons (void)
   How long should this be?
   button remappings...
Global reset_cycle (void)
   do it
Global setup_timer ()
    distinguish between the two different timers here...
Global sort_states (Complex state[], int num_qubits)
    this function...
   this
Global TLC591x mode switch (int mode)
    mode switcher for LED Driver
Global write_display_driver (void)
   How long should this be?
```

2 Todo List

Chapter 2

Data Structure Index

2.1 Data Structures

Here are the data structures with brief descriptions:

rcle_node
The basis for a linked list of states to cycle
Each LED has the following type
ED_GLOBAL
Pin mappings
GB
A type for holding red, green, blue values

Data Structure Index

Chapter 3

File Index

3.1 File List

Here is a list of all documented files with brief descriptions:

dspic33e/qcomp-sim-c.X/algo.c	
Contains quantum algorithms to be run	11
dspic33e/qcomp-sim-c.X/algo.h	
Header file for algorithms	13
dspic33e/qcomp-sim-c.X/config.h	
General config settings #pragma for microcontroller	15
dspic33e/qcomp-sim-c.X/consts.c	
All (global) constants)	15
dspic33e/qcomp-sim-c.X/consts.h	
Header file for (global) constants	18
dspic33e/qcomp-sim-c.X/display.c	
For all the state display functions	20
dspic33e/qcomp-sim-c.X/display.h	
Description: Header file containing all the functions for displaying the qubits state vector	25
dspic33e/qcomp-sim-c.X/io.c	
Contains all the functions for reading buttons and writing to LEDs	29
dspic33e/qcomp-sim-c.X/io.h	
Description: Header file for input output functions	39
dspic33e/qcomp-sim-c.X/main.c	
The main function	48
dspic33e/qcomp-sim-c.X/quantum.c	
Description: Contains matrix and vector arithmetic for simulating one qubit	50
dspic33e/qcomp-sim-c.X/quantum.h	
Description: Header file containing all the matrix arithmetic for simulating a single qubit	55
dspic33e/qcomp-sim-c.X/spi.c	
Description: Functions for communicating with serial devices	59
dspic33e/qcomp-sim-c.X/spi.h	
Description: SPI communication functions	62
dspic33e/qcomp-sim-c.X/tests.c	
Description: Contains all the tests we have performed on the micro- controller	64
dspic33e/qcomp-sim-c.X/tests.h	
Description: Header file containing all the tests we performed	66
dspic33e/qcomp-sim-c.X/time.c	
Description: Functions to control the on chip timers	68
dspic33e/qcomp-sim-c.X/time.h	
Description: Header file containing all the timing functions	69

6 File Index

Chapter 4

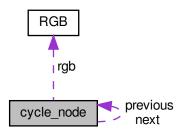
Data Structure Documentation

4.1 cycle_node Struct Reference

The basis for a linked list of states to cycle.

#include <io.h>

Collaboration diagram for cycle_node:



Data Fields

• RGB * rgb

Array of corresponding RGB values.

• int size

The size of the above arrays.

struct cycle_node * next

Pointer to the next item.

• struct cycle_node * previous

Pointer to the previous item.

4.1.1 Detailed Description

The basis for a linked list of states to cycle.

The documentation for this struct was generated from the following file:

• dspic33e/qcomp-sim-c.X/io.h

4.2 LED Struct Reference

```
Each LED has the following type.
```

```
#include <io.h>
```

Data Fields

- int **R** [2]
- int G [2]

Red mapping array: [chip number, line number].

• int B [2]

Green mapping array.

unsigned _Fract N_R

Blue mapping array.

unsigned _Fract N_G

The R brightness.

unsigned _Fract N_B

The G brightness.

4.2.1 Detailed Description

Each LED has the following type.

The type holds the information about the position of the RGB lines in the display driver array and also the brightness of the RGB lines. The counters are used by a timer interrupt service routine pulse the RGB LEDs at a specified rate.

The position of the LED lines are contained in an array

The type of the counter is Fract to facilitate easy comparison with the N* variables which used the fractional type.

The documentation for this struct was generated from the following file:

• dspic33e/qcomp-sim-c.X/io.h

4.3 LED_GLOBAL Struct Reference

pin mappings

```
#include <io.h>
```

4.4 RGB Struct Reference 9

Data Fields

· int strobe_leds

Bit set the LEDs which are strobing.

· int strobe_state

Bit zero is the current state (on/off)

4.3.1 Detailed Description

pin mappings

```
// Pins for LE and OE on port D
// OE = RD4 = uC:81 = J1:28 = J10:14
// LE = RD3 = uC:78 = J1:40 = J11:18
//
// Pins for SH and CLK_INH on port D
// SH = RD5 = uC:82 = J1:25 = J10:13
// CLK_INH = RD8 = uC:68 = J1:58 = J11:25
//
```

Global LED strobing state parameter

The documentation for this struct was generated from the following file:

• dspic33e/qcomp-sim-c.X/io.h

4.4 RGB Struct Reference

A type for holding red, green, blue values.

```
#include <io.h>
```

Data Fields

- unsigned _Fract R
- · unsigned _Fract G
- unsigned _Fract B

4.4.1 Detailed Description

A type for holding red, green, blue values.

The documentation for this struct was generated from the following file:

• dspic33e/qcomp-sim-c.X/io.h

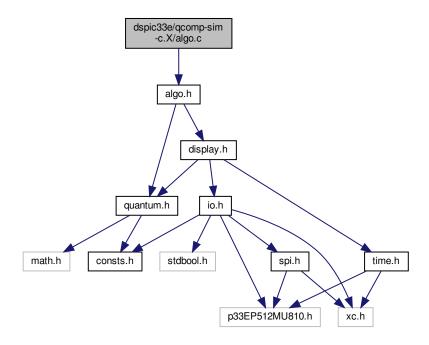
Chapter 5

File Documentation

5.1 dspic33e/qcomp-sim-c.X/algo.c File Reference

Contains quantum algorithms to be run.

#include "algo.h"
Include dependency graph for algo.c:



Functions

• void gate (Complex op[2][2], int qubit, Complex state[], int num_qubits) perform single qubit gate

```
• void two_gate (Complex op[2][2], int ctrl, int targ, Complex state[], int num_qubits) perform controlled single qubit gate
```

```
    void swap (int q1, int q2, Complex state[], int num_qubits)
    swap using 3 cNots
```

```
    void toffoli_gate (Complex state[])
    Toffoli gate.
```

5.1.1 Detailed Description

Contains quantum algorithms to be run.

5.1.2 Function Documentation

5.1.2.1 gate()

perform single qubit gate

does 2x2 operator on state vector displays the average state of the qubit by tracing over all waits to let the user see the state (LEDs)

5.1.2.2 two_gate()

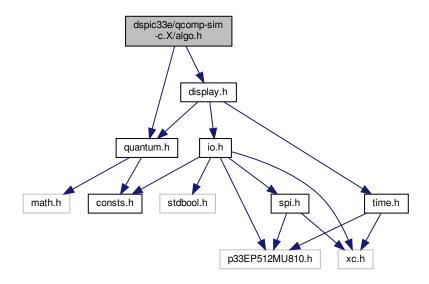
perform controlled single qubit gate

does controlled 2x2 operator

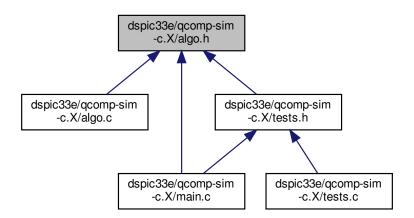
5.2 dspic33e/qcomp-sim-c.X/algo.h File Reference

header file for algorithms

```
#include "quantum.h"
#include "display.h"
Include dependency graph for algo.h:
```



This graph shows which files directly or indirectly include this file:



Functions

• void gate (Complex op[2][2], int qubit, Complex state[], int num_qubits)

perform single qubit gate

• void two_gate (Complex op[2][2], int ctrl, int targ, Complex state[], int num_qubits) perform controlled single qubit gate

• void swap (int q1, int q2, Complex state[], int num_qubits)

```
swap using 3 cNots
```

void toffoli_gate (Complex state[])

Toffoli gate.

5.2.1 Detailed Description

header file for algorithms

5.2.2 Function Documentation

5.2.2.1 gate()

perform single qubit gate

does 2x2 operator on state vector displays the average state of the qubit by tracing over all waits to let the user see the state (LEDs)

5.2.2.2 two_gate()

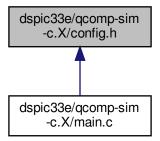
perform controlled single qubit gate

does controlled 2x2 operator

5.3 dspic33e/qcomp-sim-c.X/config.h File Reference

General config settings #pragma for microcontroller.

This graph shows which files directly or indirectly include this file:



5.3.1 Detailed Description

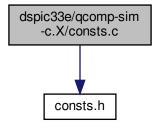
General config settings #pragma for microcontroller.

Description: Include this once at the top of main

5.4 dspic33e/qcomp-sim-c.X/consts.c File Reference

contains all (global) constants)

#include "consts.h"
Include dependency graph for consts.c:



Variables

- Complex rX [2][2]
- Complex X [2][2]
- Complex Y [2][2]
- Complex Z [2][2]
- Complex H [2][2]

5.4.1 Detailed Description

contains all (global) constants)

5.4.2 Variable Documentation

```
5.4.2.1 H
```

```
Complex H[2][2]
```

Initial value:

```
 = \{ \{ \{0.7071067812, \ 0.0\}, \ \{0.7071067812, \ 0.0\}, \ \{ -0.7071067812, \ 0.0\}, \ \{ -0.7071067812, \ 0.0\} \} \}
```

Parameters

H Hadamard gate

5.4.2.2 rX

```
Complex rX[2][2]
```

Initial value:

```
= {{ {0.5, 0.5}, {0.5, -0.5} },
 { {0.5, -0.5}, {0.5, 0.5} }}
```

Parameters

```
rX sqrt X gate (0.5+0.5i 0.5-0.5i) (0.5-0.5i 0.5+0.5i)
```

5.4.2.3 X

Complex X[2][2]

Initial value:

```
= \{ \{ \{0.0, 0.0\}, \{ONE\_015, 0.0\} \}, \{ONE\_015, 0.0\}, \{0.0, 0.0\} \} \}
```

Parameters

```
X pauli X gate
```

5.4.2.4 Y

Complex Y[2][2]

Initial value:

Parameters

```
Y Pauli y gate
```

5.4.2.5 Z

Complex Z[2][2]

Initial value:

```
= \{ \{ \{ ONE\_015, 0.0 \}, \{ 0.0, 0, 0 \} \}, \\ \{ \{ 0.0, 0.0 \}, \{ -1.0, 0.0 \} \} \}
```

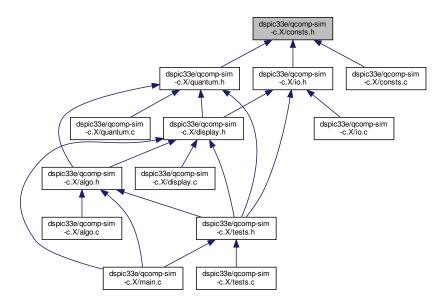
Parameters

Z Pauli z gate

5.5 dspic33e/qcomp-sim-c.X/consts.h File Reference

header file for (global) constants

This graph shows which files directly or indirectly include this file:



Macros

- #define NUM_QUBITS 4
- #define **STATE_LENGTH** 16
- #define ONE_Q15 0.9999694824

Typedefs

• typedef signed _Fract Q15

Basic fractional time.

• typedef Q15 Complex[2]

Complex type.

Variables

- Complex rX [2][2]
- Complex X [2][2]
- Complex Y [2][2]
- Complex Z [2][2]
- Complex H [2][2]

5.5.1 Detailed Description

header file for (global) constants

5.5.2 Variable Documentation

5.5.2.1 H

Complex H[2][2]

Parameters

H Hadamard gate

5.5.2.2 rX

Complex rX[2][2]

Parameters

rX	is square root of X
rX	sqrt X gate (0.5+0.5i 0.5-0.5i) (0.5-0.5i 0.5+0.5i)

5.5.2.3 X

Complex X[2][2]

Parameters

X pauli X gate

5.5.2.4 Y

Complex Y[2][2]

Parameters

Y Pauli y gate

5.5.2.5 Z

Complex Z[2][2]

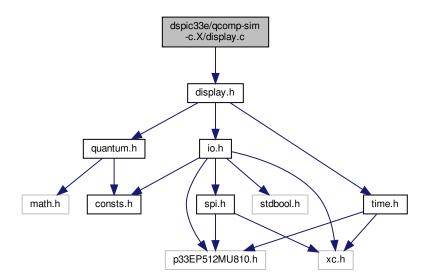
Parameters

Z Pauli z gate

5.6 dspic33e/qcomp-sim-c.X/display.c File Reference

for all the state display functions

#include "display.h"
Include dependency graph for display.c:



Macros

• #define NUM_MAX_AMPS 4

Functions

• void display_average (Complex state[], int N)

Display the state amplitudes on LEDs.

• void display_cycle (Complex state[], int N)

cycles through the non-zero amplitude states

- int sort_states (Complex state[], int num_qubits)
- int remove_zero_amp_states (Complex state[], int num_qubits, int disp_state[])

takes state vector, number of qubits and vector to write the nonzero elements of the statevector to.

5.6.1 Detailed Description

for all the state display functions

5.6.2 Macro Definition Documentation

5.6.2.1 NUM_MAX_AMPS

```
#define NUM_MAX_AMPS 4
```

Parameters

state	The state vector
num_qubits	The number of qubits in the state vector

Returns

This function finds the amplitude of the state vector with the largest magnitude.

5.6.3 Function Documentation

5.6.3.1 display_average()

Display the state amplitudes on LEDs.

Parameters

state	Pass in the state vector
N	The total number of qubits

Note

Currently the function only displays superpositions using the red and blue colors.

The routine works by adding up the squares of the amplitudes corresponding to each state of a given qubit. Suppose there are three qubits. Then the state vector is given by

*	index	binary	amplitude
*			
*	0	0 0 0	a0
*	1	0 0 1	a1
*	2	0 1 0	a2
*	3	0 1 1	a3
*	4	1 0 0	a4
*	5	1 0 1	a5
*	6	1 1 0	аб
*	7	1 1 1	a7
*			
*	Qubit:	2 1 0	
+			

Consider qubit 2. The value of the ZERO state is formed by adding up all the amplitudes corresponding to its ZERO state. That is, indices 0, 1, 2 and 3. The ONE state is obtained by adding up the other indices: 4, 5, 6 and

1.

So the amplitudes for qubit 2 are

ZERO:
$$(a_0)^2 + (a_1)^2 + (a_2)^2 + (a_3)^2$$
 ONE: $(a_4)^2 + (a_5)^2 + (a_6)^2 + (a_7)^2$

Corresponding to the following indices:

ZERO: 0+0, 1+0, 2+0, 3+0 ONE: 4+0, 5+0, 6+0, 7+0

For qubit 1 the indices are:

ZERO: 0+0, 0+4, 1+0, 1+4 ONE: 2+0, 2+4, 3+0, 3+4

And for qubit 0 the indices are:

ZERO: 0+0, 0+2, 0+4, 0+6 ONE: 1+0, 1+2, 1+4, 1+6

The examples above are supposed to show the general pattern. For N qubits, qubit number k, the ZERO and ONE states are given by summing all the square amplitudes corresponding to the following indices:

ZERO:
$$n + (2^{(k+1)} * j)$$
, where $n = 0, 1, ..., 2^{k} - 1$ and $j = 0, 1, ..., 2^{(N-k-2)}$

ONE:
$$n + (2^{\wedge}(k+1) * j)$$
, where $n = 2^{\wedge}k$, $2^{\wedge}k + 1$, ..., $2^{\wedge}(k+1) - 1$ and $j = 0, 1, ..., 2^{\wedge}(N-k-2)$

The amplitudes are obtained by summing over both n and j. Notice that there is an edge condition when k = N-1. There, j acycle_lengthpparently ranges from 0 to -1. In this case, the only value of j is 0. The condition arises because of the way that $2^{(N-k-2)}$ is obtained (i.e. such that multiplying it by $2^{(k+1)}$ gives $2^{(N-1)}$.) However, if k = N-1, then $2^{(k+1)} = 2^{N}$ already, so it must be multiplied by $2^{(-1)}$. The key point is that the second term should not ever equal 2^{N} , so j should stop at 0.

The above indices can be expressed as the sum of a ROOT and a STEP as follows:

```
index = ROOT + STEP
```

where ROOT ranges from 0 to 2^k-1 . This corresponds to the n values that give rise to ZERO. The indices for ONE can be obtained by adding 2^k to root. The STEP = j is a multiple of 2^k+1 starting from zero that does not equal or exceed 2^k . ROOT can be realised using the following for loop:

```
for(int root = 0; root < 2^k; root ++) { ... // ZERO index root; // ONE index root + 2^k; }
```

Then the STEP component can be realised as

```
for(int step = 0; step < 2^N; step += 2^(k+1)) { // Add the following to root... step; } Loop over all qubits k = 0, 1, 2, ... N-1
```

ROOT loop: starts at 0, increases in steps of 1

```
STEP loop: starts at 0, increases in steps of 2^{(k+1)}
```

Zeros are at the index root + step

Ones are at the index root + 2^k + step

update leds for each qubits average zero and one amps

5.6.3.2 display_cycle()

cycles through the non-zero amplitude states

Parameters

state	The state to display
Ν	The length of the state vector

Filter the state

Allocate RGB array

Decode

Look at the jth bit

Reset the cycle

Each iteration of this loop writes

Loop here to add stuff

5.6.3.3 remove_zero_amp_states()

takes state vector, number of qubits and vector to write the nonzero elements of the statevector to.

updates disp_state where the first 'return value of the function'elements are the nonzero elements of the state vector 'state'

the disp_state elements are the nonzero elements of the state

```
/// e.g. state = (00) = (1/r2) (Bell state)
/// (01) (0)
/// (10) (0)
/// (11) (1/r2)
/// Then displ_state would have 2 elements
/// disp_state = (0) standing for (00)
/// (3) (11)
```

Note

we have to allocate disp_state to be the size of state, the function returns count which tells us the first 'count' elements of disp_state to use. In the Bell state example there are 2 values in disp_state, 0 & 3, count is returned as 3 which means take the first count-1 elements (in this case 2) of disp_state which is 0,1 which is the correct elements

5.6.3.4 sort_states()

Todo this

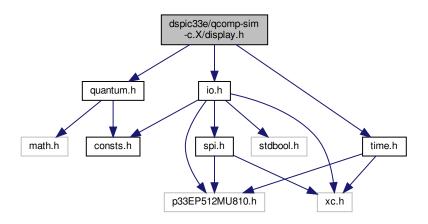
Todo this function...

5.7 dspic33e/qcomp-sim-c.X/display.h File Reference

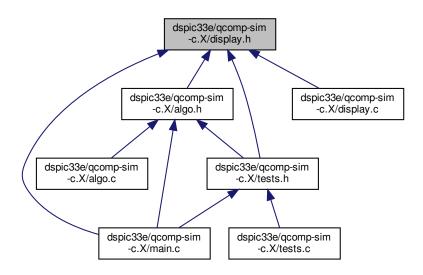
Description: Header file containing all the functions for displaying the qubits state vector.

```
#include "quantum.h"
#include "time.h"
#include "io.h"
```

Include dependency graph for display.h:



This graph shows which files directly or indirectly include this file:



Functions

• void display_average (Complex state[], int Qnum)

Display the state amplitudes on LEDs.

void display_cycle (Complex state[], int N)
 cycles through the non-zero amplitude states

• int remove_zero_amp_states (Complex state[], int num_qubits, int disp_state[])

updates disp_state where the first 'return value of the function'elements are the nonzero elements of the state vector 'state'

int sort_states (Complex state[], int num_qubits)

5.7.1 Detailed Description

Description: Header file containing all the functions for displaying the qubits state vector.

5.7.2 Function Documentation

5.7.2.1 display_average()

Display the state amplitudes on LEDs.

Parameters

state	Pass in the state vector
Qnum	The total number of qubits

Note

Currently the function only displays superpositions using the red and blue colors.

Todo rename to display average

Parameters

state	Pass in the state vector
Ν	The total number of qubits

Note

Currently the function only displays superpositions using the red and blue colors.

The routine works by adding up the squares of the amplitudes corresponding to each state of a given qubit. Suppose there are three qubits. Then the state vector is given by

*	index	binary	amplitude
*			
*	0	0 0 0	a0
*	1	0 0 1	a1
*	2	0 1 0	a2
*	3	0 1 1	a3
*	4	1 0 0	a4
*	5	1 0 1	a5
*	6	1 1 0	a6
*	7	1 1 1	a7
*			
*	Qubit:	2 1 0	
*			

Consider qubit 2. The value of the ZERO state is formed by adding up all the amplitudes corresponding to its ZERO state. That is, indices 0, 1, 2 and 3. The ONE state is obtained by adding up the other indices: 4, 5, 6 and

1.

So the amplitudes for qubit 2 are

ZERO:
$$(a_0)^2 + (a_1)^2 + (a_2)^2 + (a_3)^2$$
 ONE: $(a_4)^2 + (a_5)^2 + (a_6)^2 + (a_7)^2$

Corresponding to the following indices:

ZERO: 0+0, 1+0, 2+0, 3+0 ONE: 4+0, 5+0, 6+0, 7+0

For gubit 1 the indices are:

ZERO: 0+0, 0+4, 1+0, 1+4 ONE: 2+0, 2+4, 3+0, 3+4

And for qubit 0 the indices are:

ZERO: 0+0, 0+2, 0+4, 0+6 ONE: 1+0, 1+2, 1+4, 1+6

The examples above are supposed to show the general pattern. For N qubits, qubit number k, the ZERO and ONE states are given by summing all the square amplitudes corresponding to the following indices:

ZERO:
$$n + (2^{\wedge}(k+1) * j)$$
, where $n = 0, 1, ..., 2^{\wedge}k - 1$ and $j = 0, 1, ..., 2^{\wedge}(N-k-2)$
ONE: $n + (2^{\wedge}(k+1) * j)$, where $n = 2^{\wedge}k$, $2^{\wedge}k + 1$, ..., $2^{\wedge}(k+1) - 1$ and $j = 0, 1, ..., 2^{\wedge}(N-k-2)$

The amplitudes are obtained by summing over both n and j. Notice that there is an edge condition when k = N-1. There, j acycle_lengthpparently ranges from 0 to -1. In this case, the only value of j is 0. The condition arises because of the way that $2^{(N-k-2)}$ is obtained (i.e. such that multiplying it by $2^{(k+1)}$ gives $2^{(N-1)}$.) However, if k = N-1, then $2^{(k+1)} = 2^{N}$ already, so it must be multiplied by $2^{(-1)}$. The key point is that the second term should not ever equal $2^{(k+1)}$ so j should stop at 0.

The above indices can be expressed as the sum of a ROOT and a STEP as follows:

```
index = ROOT + STEP
```

where ROOT ranges from 0 to 2^k-1 . This corresponds to the n values that give rise to ZERO. The indices for ONE can be obtained by adding 2^k to root. The STEP = j is a multiple of 2^k+1 starting from zero that does not equal or exceed 2^n . ROOT can be realised using the following for loop:

for(int root = 0; root $< 2^k$; root ++) { ... // ZERO index root; // ONE index root + 2^k ; }

Then the STEP component can be realised as

for(int step = 0; step < 2^N ; step += $2^(k+1)$) { // Add the following to root... step; } Loop over all qubits k = 0, 1, 2, ... N-1

ROOT loop: starts at 0, increases in steps of 1

STEP loop: starts at 0, increases in steps of $2^{(k+1)}$

Zeros are at the index root + step

Ones are at the index root + 2^k + step

update leds for each qubits average zero and one amps

5.7.2.2 display_cycle()

cycles through the non-zero amplitude states

Parameters

state	The state to display
N	The length of the state vector

Filter the state

Allocate RGB array

Decode

Look at the jth bit

Reset the cycle

Each iteration of this loop writes

Loop here to add stuff

5.7.2.3 remove_zero_amp_states()

updates disp_state where the first 'return value of the function'elements are the nonzero elements of the state vector 'state'

Parameters

state	complex state vector in
num_qubits	int number of qubits in
disp_state	complex inout vector where the first n entries are the nonzero elements of 'state'

Returns

returns the number of elements to look at in disp_state.

updates disp_state where the first 'return value of the function'elements are the nonzero elements of the state vector 'state'

the disp_state elements are the nonzero elements of the state

```
/// e.g. state = (00) = (1/r2) (Bell state)
/// (01) (0)
/// (10) (0)
/// (11) (1/r2)
/// Then displ_state would have 2 elements
/// disp_state = (0) standing for (00)
/// (3) (11)
```

Note

we have to allocate disp_state to be the size of state, the function returns count which tells us the first 'count' elements of disp_state to use. In the Bell state example there are 2 values in disp_state, 0 & 3, count is returned as 3 which means take the first count-1 elements (in this case 2) of disp_state which is 0,1 which is the correct elements

5.7.2.4 sort_states()

Todo this

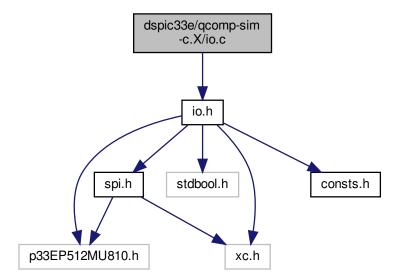
Todo this function...

5.8 dspic33e/qcomp-sim-c.X/io.c File Reference

Contains all the functions for reading buttons and writing to LEDs.

```
#include "io.h"
```

Include dependency graph for io.c:



Macros

- #define DISPLAY CHIP NUM 2
- #define MAX_CYCLE_LENGTH 16
- #define **PERIOD** 500000
- #define BTN CHIP NUM 2

Read external buttons.

Functions

• int led_color_int (int device, int R, int G, int B)

Takes led number & RGB -> returns integer for sending via SPI to set the LED.

• int setup_io (void)

Set up LEDs and buttons on port D.

void <u>__attribute__</u> ((<u>__interrupt__</u>, no_auto_psv))

The max value for isr_counter.

void setup_external_leds (void)

Set external variable RGB LEDs.

int add_to_cycle (RGB colors[], int size)

Add an item to the list of states to cycle.

int reset_cycle (void)

Reset the LED display cycle _*.

void stop_external_leds (void)

Stop LEDs flashing.

• void set_strobe (int color, int state)

Set an LED strobing.

• void toggle_strobe (int color)

Toggle LED strobe.

• int set_led (int color, int state)

Turn a particular LED on or off.

int read_btn (int btn)

Read the state of a push button.

void leds_off (void)

Turn all the LEDs off.

void flash_led (int color, int number)

Flash LED a number of times.

void flash_all (int number)

Flash all the LEDs a number of times.

- int update_display_buffer (int n, bool R, bool G, bool B)
- int write_display_driver (void)

Turn on an LED via the external display driver.

• int TLC591x_mode_switch (int mode)

Switch between normal and special mode.

int set_external_led (int index, unsigned _Fract R, unsigned _Fract G, unsigned _Fract B)

Updates color properties of global led array.

• int read external buttons (void)

Update the buttons array (see declaration above)

int led_cycle_test (void)

Loop to cycle through LEDs 0 - 15.

void varying_leds (void)

Routine to test the set_external_led function.

Variables

• int buttons [16]

Contains the button states.

- LED_GLOBAL led_global = {0}
- LED led [LED_NUM]

The LED array - global in this file.

• int display_buf [DISPLAY_CHIP_NUM] = {0}

Display buffer to be written to display driver.

unsigned _Fract isr_counter = 0

Counter for the interrupt service routine _T5Interrupt.

• unsigned _Fract isr_res = 0.01

Counter value.

const unsigned _Fract isr_limit = 0.95

Counter resolution.

- RGB cycle_colors [MAX_CYCLE_LENGTH][NUM_QUBITS]
- int **last row** = 0
- int cycle_counter = 0

5.8.1 Detailed Description

Contains all the functions for reading buttons and writing to LEDs.

Author

J Scott

Date

8/11/18

5.8.2 Macro Definition Documentation

```
5.8.2.1 BTN_CHIP_NUM
```

```
#define BTN_CHIP_NUM 2
```

Read external buttons.

The external buttons are interfaced to the microcontroller via a shift register. Data is shifted in a byte at a time using the SPI 3 module. The sequence to read the buttons is as follows:

1) Momentarily bring SH low to latch button data into the shift registers 2) Bring CLK_INH low to enable the clock input on the shift register 3) Start the SPI 3 clock and read data in via the SDI 3 line

The control lines SH and CLK_INH are on port D

Todo read buttons

5.8.3 Function Documentation

The max value for isr_counter.

Timer 6 and 7 for cycling superposition states.

Interrupt service routine for timer 4

Interrupt service routines are automatically called by the microcontroller when an event occurs. In this case, _ T5Interrupt is called when the 32 bit timer formed from T4 and T5 reaches its preset period. The silly name and sill attributes are so that the compiler can correctly map the function in the microcontroller memory. More details of interrupts and interrupt vectors can be found in the compiler manual and the dsPIC33E datasheet.

The job of this routine is to control the modulated brightnesses of the RBG LEDs. This routine is set to be called periodically with a very long period on the time scale of microcontroller operations, but very fast in comparison to what the eye can see. For example, once every 100us. Loop over all the LEDs (the index i).

Decide whether R, G or B should be turned off

Write the display buffer data to the display drivers It's important this line goes here rather than after the the final update_display_buffer below. Otherwise you get a flicker due to the LEDs all coming on at the start of this loop

Reset the counter

Turn on all the LEDs back on

Write a row to the leds

5.8.3.2 add_to_cycle()

Add an item to the list of states to cycle.

Add an element to the states to be cycled.

Parameters

leds	An array of LED indices
colors	Corresponding RGB values for each LED
size	The size of both the above arrays

This function is used to add a set of LED states (RGB values) into the list of states being cycled.

Repeatedly calling this function adds a new state to the end of the list of displayed states. LED states are shown in the order this function is called.

The implementation uses the linked list type cycle_node. Each call of this function adds a new element to the end of cycle node Add the new colors to top of array

5.8.3.3 flash_all()

```
void flash_all (
          int number )
```

Flash all the LEDs a number of times.

Parameters

number

5.8.3.4 flash_led()

Flash LED a number of times.

Flash one LED a number of times.

5.8.3.5 led_color_int()

Takes led number & RGB -> returns integer for sending via SPI to set the LED.

Parameters

input LED number to change
red value between 0 & 1
green value between 0 & 1
blue value between 0 & 1

Returns

Returns int to be sent to LED Driver

convention RGB -> 000

Each LED takes 3 lines, assumes there are no gaps between LED channels "device" goes between 0 to 2[^]n -1

```
5.8.3.6 led_cycle_test()
```

```
int led_cycle_test (
     void )
```

Loop to cycle through LEDs 0 - 15.

Todo This won't work now: write_display_driver(counter);

```
5.8.3.7 read_btn()
```

```
int read_btn (
          int btn )
```

Read the state of a push button.

Parameters

btn

Note

How well do you know C

5.8.3.8 read_external_buttons()

Update the buttons array (see declaration above)

SH pin

Todo How long should this be?

Todo button remappings...

5.8.3.9 reset_cycle()

```
int reset_cycle (
     void )
```

Reset the LED display cycle _*.

Reset the display cycle. Called before adding anything.

Todo do it

5.8.3.10 set_external_led()

```
int set_external_led (
    int index,
    unsigned _Fract R,
    unsigned _Fract G,
    unsigned _Fract B)
```

Updates color properties of global led array.

Parameters

led_index	
R	red value between 0 & 1
G	green value between 0 & 1
В	blue value between 0 & 1

Returns

0 if successful, -1 otherwise

Use the function to set the RGB level of an LED. The LED is chosen using the

Parameters

led_index.	The
R	

5.8.3.11 set_led()

```
int set_led (
          int color,
          int state )
```

Turn a particular LED on or off.

Parameters

color	
state	

5.8.3.12 set_strobe()

```
void set_strobe (
                int color,
                int state )
```

Set an LED strobing.

Parameters

color	
state	

5.8.3.13 setup_external_leds()

Set external variable RGB LEDs.

Initialise LED lines

Initialise parameters to zero

Initialise display buffer to zero

Set flashing period

Turn timer 6 on

5.8.3.14 setup_io()

```
int setup_io (
     void )
```

Set up LEDs and buttons on port D.

< Set port c digital for spi3

Set the OE pin high

Set OE(ED2) pin

Set the SH pin high

Set SH pin

set CLK_INH high while buttons are pressed

5.8.3.15 TLC591x_mode_switch()

Switch between normal and special mode.

The mode switch for the TLC591x chip is a bit tricky because it involves synchronising the control lines LE(ED1) and OE(ED2) on Port D with the SPI 1 clock. To initiate a mode switch, OE(ED2) must be brought low for one clock cycle, and then the value of LE(ED1) two clock cycles later determines the new mode. See the diagrams on page 19 of the datasheet

So long as the timing is not strict, we can probably implement the mode switch by starting a non-blocking transfer of 1 byte to the device (which starts the SPI 1 clock), followed by clearing OE(ED2) momentarily and then setting the value of LE(ED1) as required. So long as those two things happen before the SPI 1 clock finishes the procedure will probably work. (The reason is the lack of max timing parameters on page 9 for the setup and hold time for ED1 and ED2, which can therefore presumably be longer than one clock cycle.)

Parameters

mode

Todo mode switcher for LED Driver

5.8.3.16 toggle_strobe()

```
void toggle_strobe (
    int color )
```

Toggle LED strobe.

Parameters

color

5.8.3.17 update_display_buffer()

```
int update_display_buffer (
                int n,
               bool R,
                bool G,
                bool B)
```

Parameters

index LED number to modify

Parameters

R	Intended value of the R led
G	Intended value of the G led
В	Intended value of the B led

Returns

0 if successful

Could this get any worse!

This function is supposed to make the display writing process more efficient. It updates a global display buffer which is written periodically to the led display drivers. Instead of the display driver function re-reading the desired state of all the LED lines every time it is called, this function can be used to update only the lines that have changed.

There are quite a few potential bugs in here, mainly array out of bounds if the DISPLAY_CHIP_NUM is not set correctly or the LED RGB lines are wrong. (Or if there are just bugs.) Set or clear the red LED of the nth LED

Set or clear the red LED of the nth LED

Set or clear the red LED of the nth LED

5.8.3.18 write_display_driver()

Turn on an LED via the external display driver.

Send a byte to the display driver.

On power on, the chip (TLC591x) is in normal mode which means that the clocked bytes sent to the chip set which LEDs are on and which are off (as opposed to setting the current of the LEDs)

To write to the device, use the SPI module to write a byte to the SDI 1 pin on the chip. Then momentarily set the LE(ED1) pin to latch the data onto the output register. Finally, bring the OE(ED2) pin low to enable the current sinking to turn on the LEDs. See the timing diagram on page 17 of the datasheet for details.

LE(ED1) and OE(ED2) will be on Port D Set LE(ED1) pin

Todo How long should this be?

5.8.4 Variable Documentation

5.8.4.1 buttons

```
int buttons[16]
```

Contains the button states.

Each entry in the array is either 1 if the button is pressed or 0 if not. The array is accessed globally using 'extern buttons;' in a *.c file. Read buttons array us updated by calling read external buttons

5.8.4.2 isr_counter

```
unsigned _Fract isr_counter = 0
```

Counter for the interrupt service routine _T5Interrupt.

These variables are for keeping track of the interrupt based LED pulsing. The type is _Fract because it is easier to directly compare two _Fracts than attempt multiplication of integers and _Fracts (which isn't supported) The limit is not 1 because Fract types do not go up to 1.

It's probably a good idea to make sure the isr_res counter doesn't overflow (by ensuring that isr_res + isr_limit does not exceed 0.999..., the max value of unsigned _Fract).

5.8.4.3 led_global

```
LED_GLOBAL led_global = {0}
```

Parameters

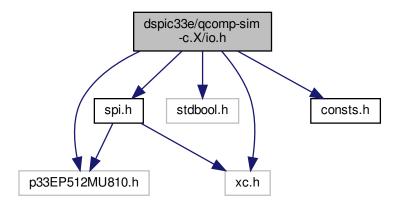
led global Global LED strobing state parameter

5.9 dspic33e/qcomp-sim-c.X/io.h File Reference

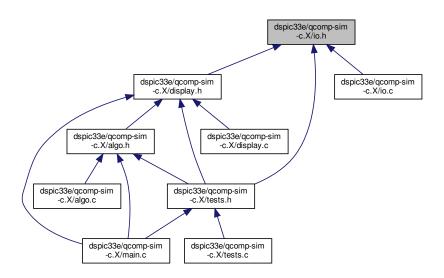
Description: Header file for input output functions.

```
#include "p33EP512MU810.h"
#include "xc.h"
#include <stdbool.h>
#include "spi.h"
#include "consts.h"
```

Include dependency graph for io.h:



This graph shows which files directly or indirectly include this file:



Data Structures

struct LED_GLOBAL

pin mappings

struct LED

Each LED has the following type.

struct RGB

A type for holding red, green, blue values.

• struct cycle_node

The basis for a linked list of states to cycle.

Macros

#define red 0

Locations of LEDs and buttons on Port D.

- #define amber 1
- #define green 2
- #define **sw1** 6
- #define sw2 7
- #define sw3 13
- #define off 0
- #define **on** 1
- #define LE 3

Control for TLC591x chip on Port D.

- #define OE 4
- #define SH 5

COntrol lines for SNx4HC165 chip.

- #define CLK_INH 8
- #define LED_NUM 4

The number of external LEDs.

Typedefs

• typedef struct cycle_node cycle_node_t

The basis for a linked list of states to cycle.

Functions

• int setup_io (void)

Set up LEDs and buttons on port D.

void setup_external_leds (void)

Set external variable RGB LEDs.

• int set_led (int color, int state)

Turn a particular LED on or off.

• int read btn (int btn)

Read the state of a push button.

void leds_off (void)

Turn all the LEDs off.

void flash_led (int color, int number)

Flash one LED a number of times.

void flash_all (int number)

Flash all the LEDs a number of times.

• void set_strobe (int color, int state)

Set an LED strobing.

void toggle_strobe (int color)

Toggle LED strobe.

- int update_display_buffer (int led_index, bool R, bool G, bool B)
- int write_display_driver (void)

Send a byte to the display driver.

• int set external led (int led index, unsigned Fract R, unsigned Fract B)

Updates color properties of global led array.

• int led_color_int (int device, int R, int G, int B)

Takes led number & RGB -> returns integer for sending via SPI to set the LED.

int led_cycle_test (void)

Loop to cycle through LEDs 0 - 15.

int read_external_buttons (void)

Update the buttons array (see declaration above)

• int add_to_cycle (RGB colors[], int size)

Add an element to the states to be cycled.

int reset_cycle (void)

Reset the display cycle. Called before adding anything.

5.9.1 Detailed Description

Description: Header file for input output functions.

Include it at the top of any C source file which uses buttons and LEDs. It also defines various constants representing the positions of the buttons and LEDs on port D.

5.9.2 Function Documentation

5.9.2.1 add_to_cycle()

Add an element to the states to be cycled.

Add an element to the states to be cycled.

Parameters

leds	An array of LED indices
colors	Corresponding RGB values for each LED
size	The size of both the above arrays

This function is used to add a set of LED states (RGB values) into the list of states being cycled.

Repeatedly calling this function adds a new state to the end of the list of displayed states. LED states are shown in the order this function is called.

The implementation uses the linked list type cycle_node. Each call of this function adds a new element to the end of cycle node Add the new colors to top of array

5.9.2.2 flash_all()

```
void flash_all (
          int number )
```

Flash all the LEDs a number of times.

Parameters

```
number
```

5.9.2.3 flash_led()

Flash one LED a number of times.

Parameters

color	
number	

Flash one LED a number of times.

5.9.2.4 led_color_int()

Takes led number & RGB -> returns integer for sending via SPI to set the LED.

Parameters

device	input LED number to change
R	red value between 0 & 1
G	green value between 0 & 1
В	blue value between 0 & 1

Returns

Returns int to be sent to LED Driver

convention RGB -> 000

Each LED takes 3 lines, assumes there are no gaps between LED channels "device" goes between 0 to 2^n -1

```
5.9.2.5 led_cycle_test()
```

Loop to cycle through LEDs 0 - 15.

Todo This won't work now: write_display_driver(counter);

5.9.2.6 read_btn()

```
int read_btn ( int \ btn \ )
```

Read the state of a push button.

Parameters



Note

How well do you know C

5.9.2.7 read_external_buttons()

Update the buttons array (see declaration above)

SH pin

Todo How long should this be?

Todo button remappings...

5.9.2.8 reset_cycle()

```
int reset_cycle (
     void )
```

Reset the display cycle. Called before adding anything.

Reset the display cycle. Called before adding anything.

Todo do it

5.9.2.9 set_external_led()

```
int set_external_led (
    int index,
    unsigned _Fract R,
    unsigned _Fract G,
    unsigned _Fract B)
```

Updates color properties of global led array.

Parameters

led_index	
R	red value between 0 & 1
G	green value between 0 & 1
В	blue value between 0 & 1

Returns

0 if successful, -1 otherwise

Use the function to set the RGB level of an LED. The LED is chosen using the

Parameters

led_index.	The
R	

5.9.2.10 set_led()

```
int set_led (
          int color,
          int state )
```

Turn a particular LED on or off.

Parameters

color	
state	

5.9.2.11 set_strobe()

Set an LED strobing.

Parameters

color	
state	

5.9.2.12 setup_external_leds()

Set external variable RGB LEDs.

Initialise LED lines

Initialise parameters to zero

Initialise display buffer to zero

Set flashing period

Turn timer 6 on

5.9.2.13 setup_io()

```
int setup_io (
     void )
```

Set up LEDs and buttons on port D.

< Set port c digital for spi3

Set the OE pin high

Set OE(ED2) pin

Set the SH pin high

Set SH pin

set CLK_INH high while buttons are pressed

5.9.2.14 toggle_strobe()

```
void toggle_strobe (
    int color )
```

Toggle LED strobe.

Parameters

color

5.9.2.15 update_display_buffer()

```
int update_display_buffer (
    int n,
    bool R,
    bool G,
    bool B)
```

Parameters

led_index	LED number to modify
R	Intended value of the R led
G	Intended value of the G led
В	Intended value of the B led

Returns

0 if successful

Parameters

index	LED number to modify
R	Intended value of the R led
G	Intended value of the G led
В	Intended value of the B led

Returns

0 if successful

Could this get any worse!

This function is supposed to make the display writing process more efficient. It updates a global display buffer which is written periodically to the led display drivers. Instead of the display driver function re-reading the desired state of all the LED lines every time it is called, this function can be used to update only the lines that have changed.

There are quite a few potential bugs in here, mainly array out of bounds if the DISPLAY_CHIP_NUM is not set correctly or the LED RGB lines are wrong. (Or if there are just bugs.) Set or clear the red LED of the nth LED

Set or clear the red LED of the nth LED

Set or clear the red LED of the nth LED

5.9.2.16 write_display_driver()

Send a byte to the display driver.

Don't use this function to write to LEDs – use the set external led function

Send a byte to the display driver.

On power on, the chip (TLC591x) is in normal mode which means that the clocked bytes sent to the chip set which LEDs are on and which are off (as opposed to setting the current of the LEDs)

To write to the device, use the SPI module to write a byte to the SDI 1 pin on the chip. Then momentarily set the LE(ED1) pin to latch the data onto the output register. Finally, bring the OE(ED2) pin low to enable the current sinking to turn on the LEDs. See the timing diagram on page 17 of the datasheet for details.

LE(ED1) and OE(ED2) will be on Port D Set LE(ED1) pin

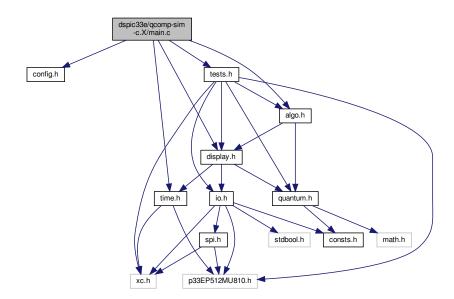
Todo How long should this be?

5.10 dspic33e/qcomp-sim-c.X/main.c File Reference

The main function.

```
#include "config.h"
#include "time.h"
#include "tests.h"
#include "algo.h"
#include "display.h"
```

Include dependency graph for main.c:



Functions

• int main (void)

5.10.1 Detailed Description

The main function.

Author

J R Scott

Date

8/11/18

Contains an example of fixed precision 2x2 matrix multiplication for applying operations to a single qubit. The only operations included are H, X and Z so that everything is real (this can be extended later).

All the functions have now been moved into separate files. io.h and io.c contain functions for reading and controlling the buttons and LEDs, and quantum.h/quantum.c contain the matrix arithmetic for simulating one qubit.

Compile command: make (on linux). But if you want to program the micro- controller too or if you're using windows you're better of downloading and installing MPLAB-X https://www.microchip.ecom/mplab/mplab-x-ide.

Note

You also need the microchip xc16 compilers which are available from $https://www.microchip. \leftarrow com/mplab/compilers$

5.10.2 Function Documentation

```
5.10.2.1 main()
```

```
int main (
     void )
```

Reading button state

The button states are written into an array of type BUTTON ARRAY whose

Global variable for button state

Update the buttons variable

Do something if button 0 has been pressed...

Start of the PROGRAM!

<

Note

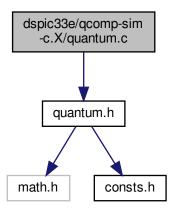
Really important!

5.11 dspic33e/qcomp-sim-c.X/quantum.c File Reference

Description: Contains matrix and vector arithmetic for simulating one qubit.

#include "quantum.h"

Include dependency graph for quantum.c:



Functions

- void cadd (Complex a, Complex b, Complex result)
- · void cmul (Complex a, Complex b, Complex result)
- Q15 absolute (Complex x)

abs function

• void zero_state (Complex state[], int Qnum)

Initialise state to the vacuum (zero apart from the first position) Specify the dimension – of the matrix, i.e.

- void mat_mul (Complex M[2][2], Complex V[], int i, int j)
 - 2x2 complex matrix multiplication
- void single_qubit_op (Complex op[2][2], int k, Complex state[], int N)

apply operator

• void controlled_qubit_op (Complex op[2][2], int ctrl, int targ, Complex state[], int N)

selective 2 qubit op function

5.11.1 Detailed Description

Description: Contains matrix and vector arithmetic for simulating one qubit.

5.11.2 Function Documentation

5.11.2.1 absolute()

```
Q15 absolute ( {\tt Complex}\ x\ )
```

abs function

Parameters

x A complex number to find the absolute value of

Returns

The absolute value

Todo Check that the complex part is small

5.11.2.2 controlled_qubit_op()

selective 2 qubit op function

apply controlled 2x2 op

```
/// 00 01 10 11
/// 00(1 0 0 0 )
/// 01(0 1 0 0 0)
/// 10(0 0 u00 u01)
/// 11(0 0 u10 u11)
```

checks that the control qubit is |1> then does 2x2 unitary on remaining state vector ROOT loop: starts at 0, increases in steps of 1

STEP loop: starts at 0, increases in steps of $2^{(k+1)}$

First index is ZERO, second index is ONE

Note

for 2 qubit case check if the index in the ctrl qubit is a 1 then apply the 2x2 unitary else do nothing sorry. this checks for the first element of the state vector i.e. the target qubits $|0\rangle$ and checks that the state vector element is one which the control qubit has a $|1\rangle$ state -> (root + step)

The second element of the state vector to take is then the first $+2^{\wedge}$ (target qubit number). This also needs to be checked that the control qubit is in the |1>.

Todo This expression can probably be simplified or broken over lines.

5.11.2.3 mat_mul()

2x2 complex matrix multiplication

Parameters

М	complex matrix
V	complex vector
i	integer first element of state vector
j	integer second element of state vector

Todo Because of the way the array types work (you can't pass a multidimensional array of unknown size) we will also need a function for 4x4 matrix multiplication.

5.11.2.4 single_qubit_op()

apply operator

Parameters

state	state vector containing amplitudes
qubit	qubit number to apply 2x2 matrix to
Ν	total number of qubits in the state
ор	2x2 operator to be applied

This routine applies a single qubit gate to the state vector

Parameters

state.	Consider the three qubit case, with amplitudes shown in the table]
	below:	

*	index	binary	amplitude
*			
*	0	0 0 0	a0
*	1	0 0 1	a1
*	2	0 1 0	a2
*	3	0 1 1	a3
*	4	1 0 0	a4
*	5	1 0 1	a5
*	6	1 1 0	a6
*	7	1 1 1	a7
*			
*	Qubit:	2 1 0	
*			

If a single qubit operation is applied to qubit 2, then the 2x2 matrix must be applied to all pairs of (0,1) in the first column, with the numbers in the other columns fixed. In other words, the following indices are paired:

```
(0+0) (1+0) (2+0) (3+0)
(4+0) (5+0) (6+0) (7+0)
```

where the top line corresponds to the ZERO amplitude and the bottom row corresponds to the ONE amplitude.

Similarly, for qubit 1 the pairings are:

```
(0+0) (0+4) (1+0) (1+4)
(2+0) (2+4) (3+0) (3+4)
```

And for qubit 0 the pairings are:

```
(0+0) (0+2) (0+4) (0+6) (1+0) (1+2) (1+4) (1+6)
```

These numbers are exactly the same as the previous function, which means the same nested loops can be used to perform operation. Now the index

```
root + step
```

refers to the ZERO amplitude (the first element in the column vector to be multiplied by the 2x2 matrix), and the index Complex state[], int N root + 2^k k + step

corresponds to the ONE entry. ROOT loop: starts at 0, increases in steps of 1

STEP loop: starts at 0, increases in steps of $2^{\wedge}(k+1)$

First index is ZERO, second index is ONE

```
5.11.2.5 zero_state()
```

Initialise state to the vacuum (zero apart from the first position) Specify the dimension – of the matrix, i.e.

2^(number of qubits)

Note

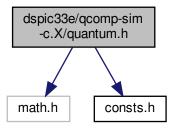
oh the clarity!

5.12 dspic33e/qcomp-sim-c.X/quantum.h File Reference

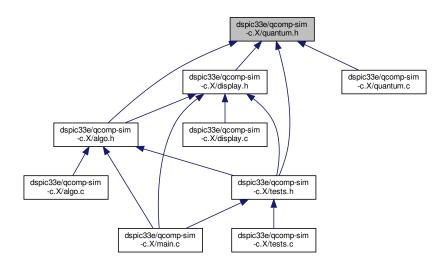
Description: Header file containing all the matrix arithmetic for simulating a single qubit.

```
#include <math.h>
#include "consts.h"
```

Include dependency graph for quantum.h:



This graph shows which files directly or indirectly include this file:



Enumerations

enum State {ZERO, ONE, PLUS, MINUS,iPLUS, iMINUS }

Basis states.

Functions

```
    void zero_state (Complex state[], int Qnum)
```

Initialise state to the vacuum (zero apart from the first position) Specify the dimension - of the matrix, i.e.

void mat_mul (Complex M[2][2], Complex V[], int i, int j)

2x2 complex matrix multiplication

- void single_qubit_op (Complex op[2][2], int qubit, Complex state[], int Qnum)
- void controlled_qubit_op (Complex op[2][2], int ctrl, int targ, Complex state[], int N)

apply controlled 2x2 op

• Q15 absolute (Complex x)

abs function

5.12.1 Detailed Description

Description: Header file containing all the matrix arithmetic for simulating a single qubit.

5.12.2 Function Documentation

5.12.2.1 absolute()

```
Q15 absolute ( \operatorname{Complex} x )
```

abs function

Parameters

 $x \mid A$ complex number to find the absolute value of

Returns

The absolute value

Todo Check that the complex part is small

5.12.2.2 controlled_qubit_op()

apply controlled 2x2 op

Parameters

ор	single qubit unitary 2x2
ctrl	control qubit number (0,1,,n-1)
targ	target qubit number (0,1,,n-1)
state	complex state vector
N	total number of qubits

apply controlled 2x2 op

```
/// 00 01 10 11
/// 00(1 0 0 0 )
/// 01(0 1 0 0 0)
/// 10(0 0 u00 u01)
/// 11(0 0 u10 u11)
```

checks that the control qubit is $|1\rangle$ then does 2x2 unitary on remaining state vector ROOT loop: starts at 0, increases in steps of 1

STEP loop: starts at 0, increases in steps of $2^{(k+1)}$

First index is ZERO, second index is ONE

Note

for 2 qubit case check if the index in the ctrl qubit is a 1 then apply the 2x2 unitary else do nothing sorry. this checks for the first element of the state vector i.e. the target qubits $|0\rangle$ and checks that the state vector element is one which the control qubit has a $|1\rangle$ state -> (root + step)

The second element of the state vector to take is then the first $+2^{\wedge}$ (target qubit number). This also needs to be checked that the control qubit is in the $|1\rangle$.

Todo This expression can probably be simplified or broken over lines.

5.12.2.3 mat_mul()

2x2 complex matrix multiplication

Parameters

М	complex matrix
V	complex vector
i	integer first element of state vector
Genera	teintegerysecond element of state vector

Todo Because of the way the array types work (you can't pass a multidimensional array of unknown size) we will also need a function for 4x4 matrix multiplication.

5.12.2.4 single_qubit_op()

apply operator

Parameters

state	state vector containing amplitudes
qubit qubit number to apply 2x2 matrix	
Qnum	total number of qubits in the state
ор	2x2 operator to be applied
state	state vector containing amplitudes
qubit	qubit number to apply 2x2 matrix to
N	total number of qubits in the state
ор	2x2 operator to be applied

This routine applies a single qubit gate to the state vector

Parameters

state.	Consider the three qubit case, with amplitudes shown in the table	
	below:	

*	index	binary	amplitude
*			
*	0	0 0 0	a0
*	1	0 0 1	a1
*	2	0 1 0	a2
*	3	0 1 1	a3
*	4	1 0 0	a4
*	5	1 0 1	a5
*	6	1 1 0	a6
*	7	1 1 1	a7
*			
*	Qubit:	2 1 0	

If a single qubit operation is applied to qubit 2, then the 2x2 matrix must be applied to all pairs of (0,1) in the first column, with the numbers in the other columns fixed. In other words, the following indices are paired:

```
(0+0) (1+0) (2+0) (3+0)
(4+0) (5+0) (6+0) (7+0)
```

where the top line corresponds to the ZERO amplitude and the bottom row corresponds to the ONE amplitude.

Similarly, for qubit 1 the pairings are:

```
(0+0) (0+4) (1+0) (1+4) (2+0) (2+4) (3+0) (3+4)
```

And for qubit 0 the pairings are:

```
(0+0) (0+2) (0+4) (0+6)
(1+0) (1+2) (1+4) (1+6)
```

These numbers are exactly the same as the previous function, which means the same nested loops can be used to perform operation. Now the index

```
root + step
```

refers to the ZERO amplitude (the first element in the column vector to be multiplied by the 2x2 matrix), and the index Complex state[], int N root + 2^k + step

corresponds to the ONE entry. ROOT loop: starts at 0, increases in steps of 1

STEP loop: starts at 0, increases in steps of $2^{(k+1)}$

First index is ZERO, second index is ONE

5.12.2.5 zero_state()

Initialise state to the vacuum (zero apart from the first position) Specify the dimension - of the matrix, i.e.

2^(number of qubits)

Parameters

state	complex state vector	
Qnum	int total number of qubits	

2[^](number of qubits)

Note

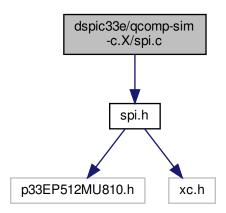
oh the clarity!

5.13 dspic33e/qcomp-sim-c.X/spi.c File Reference

Description: Functions for communicating with serial devices.

```
#include "spi.h"
```

Include dependency graph for spi.c:



Functions

• int setup_spi (void)

Set up serial peripheral interface.

• int send_byte_spi_1 (int data)

Send a byte to the SPI1 peripheral.

• int read_byte_spi_3 ()

Recieve a byte from the SPI3 peripheral.

5.13.1 Detailed Description

Description: Functions for communicating with serial devices.

5.13.2 Function Documentation

5.13.2.1 send_byte_spi_1()

Send a byte to the SPI1 peripheral.

Parameters

data	byte to be sent to SPI1	
aaia	Dyle to be sent to SPTI	

```
5.13.2.2 setup_spi()
int setup_spi (
              void )
Set up serial peripheral interface.
Pin mappings — Pin mappings and codes —
J10:41 = J1:91 = uC:70 = RPI74 (PPS code: 0100 1010)
J10:44 = J1:93 = uC:9 = RPI52 (PPS code: 0011 0100)
J10:47 = J1:101 = uC:34 = RPI42 (PPS code: 0010 1010)
J10:43 = J1:95 = uC:72 = RP64 (PPS reg: RPOR0 L; code: 0100 0000)
J10:46 = J1:97 = uC:69 = RPI73 (PPS code: 0100 1001)
J10:7 = J1:13 = uC:3 = RP85 (PPS reg: RPOR6_L; code: 0101 0101)
J10:5 = J1:7 = uC:5 = RP87 (PPS reg: RPOR6 H)
J10:55 = J1:117 = uC:10 = RP118 (PPS reg: RPOR13 H)
— Pin mappings for SPI 1 module —
SPI 1 Clock Out (SCK1) PPS code: 000110 (0x06)
SPI 1 Data Out (SDO1) PPS code: 000101 (0x05)
SPI 1 Slave Select PPS code: 000111
— Pin mappings for SPI 3 module —
SPI 3 Clock Out (SCK3) PPS code: 100000 (0x20)
SPI 3 Data Out (SDO3) PPS code: 011111 (0x1F)
SPI 3 Slave Select PPS code: 100001
Configure the SPI 1 pins
< Put SCK1 on J10:43
< Put SDO1 on J10:55
The clock pin also needs to be configured as an input
< Set SCK1 on J10:43 as input
Configure the SPI 3 output pins
< Put SCK3 on J10:7
< Put SDO3 on J10:5
< Put SDI3 on J10:44
< Set SCK3 on J10:7 as input
    @note
SPI 1 clock configuration
SCK1 = F_CY / (Primary Prescaler * Secondary Prescaler)
Assuming that F_CY = 50MHz, and the prescalers are 4 and 1, the SPI clock frequency will be 12.5MHz.
```

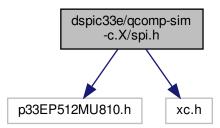
5.14 dspic33e/qcomp-sim-c.X/spi.h File Reference

Description: SPI communication functions.

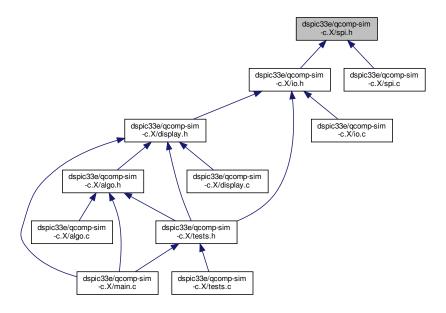
#include "p33EP512MU810.h"

#include "xc.h"

Include dependency graph for spi.h:



This graph shows which files directly or indirectly include this file:



Functions

• int setup_spi (void)

Set up serial peripheral interface.

• int send_byte_spi_1 (int data)

Send a byte to the SPI1 peripheral.

• int read_byte_spi_3 ()

Recieve a byte from the SPI3 peripheral.

5.14.1 Detailed Description

Description: SPI communication functions.

5.14.2 Function Documentation

```
5.14.2.1 send_byte_spi_1()
```

Send a byte to the SPI1 peripheral.

Parameters

```
data byte to be sent to SPI1
```

5.14.2.2 setup_spi()

```
int setup_spi (
     void )
```

Set up serial peripheral interface.

```
Pin mappings — Pin mappings and codes —
J10:41 = J1:91 = uC:70 = RPI74 (PPS code: 0100 1010)
J10:44 = J1:93 = uC:9 = RPI52 (PPS code: 0011 0100)
J10:47 = J1:101 = uC:34 = RPI42 (PPS code: 0010 1010)
J10:43 = J1:95 = uC:72 = RP64 (PPS reg: RPOR0_L; code: 0100 0000)
J10:46 = J1:97 = uC:69 = RPI73 (PPS code: 0100 1001)
J10:7 = J1:13 = uC:3 = RP85 (PPS reg: RPOR6 L; code: 0101 0101)
J10:5 = J1:7 = uC:5 = RP87 (PPS reg: RPOR6 H)
J10:55 = J1:117 = uC:10 = RP118 (PPS reg: RPOR13 H)
— Pin mappings for SPI 1 module —
SPI 1 Clock Out (SCK1) PPS code: 000110 (0x06)
SPI 1 Data Out (SDO1) PPS code: 000101 (0x05)
SPI 1 Slave Select PPS code: 000111
— Pin mappings for SPI 3 module —
SPI 3 Clock Out (SCK3) PPS code: 100000 (0x20)
SPI 3 Data Out (SDO3) PPS code: 011111 (0x1F)
SPI 3 Slave Select PPS code: 100001
```

Configure the SPI 1 pins

< Put SCK1 on J10:43

< Put SDO1 on J10:55

The clock pin also needs to be configured as an input

< Set SCK1 on J10:43 as input

Configure the SPI 3 output pins

- < Put SCK3 on J10:7
- < Put SDO3 on J10:5
- < Put SDI3 on J10:44
- < Set SCK3 on J10:7 as input

@note

SPI 1 clock configuration

SCK1 = F_CY / (Primary Prescaler * Secondary Prescaler)

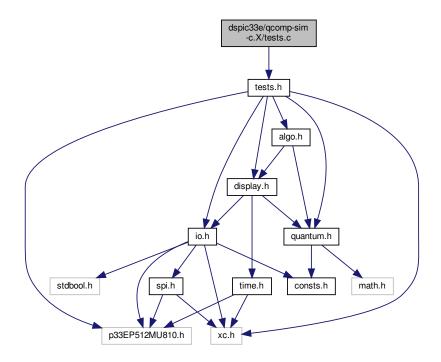
Assuming that F_CY = 50MHz, and the prescalers are 4 and 1, the SPI clock frequency will be 12.5MHz.

5.15 dspic33e/qcomp-sim-c.X/tests.c File Reference

Description: Contains all the tests we have performed on the micro-controller.

#include "tests.h"

Include dependency graph for tests.c:



Functions

```
    void swap_test (Complex state[])
        swap test nice visuals
    void dim_leds ()
        Testing the speed of 2<sup>\( \)</sup> 15 2x2 real matrix multiplications void mat_mul_test() {.
```

5.15.1 Detailed Description

Description: Contains all the tests we have performed on the micro-controller.

5.15.2 Function Documentation

```
5.15.2.1 dim_leds()
void dim_leds ( )
Testing the speed of 2<sup>15</sup> 2x2 real matrix multiplications void mat_mul_test() {.
Define state vector |0\rangle = (1,0) |1\rangle = (0,1) \text{ Vector V}; init_state(V, ZERO);
Matrix2 X = \{\{0\}\}, Z = \{\{0\}\}, H = \{\{0\}\}; make\_ops(X, Z, H);
Start the timer start_timer();
Do a matrix multiplication test unsigned int n = 0; while (n < 32768) \{ mat_mul(X, V); n++; \}
Read the timer unsigned long int time = read_timer();
Show that the test is finished set_led(red, on);
wait (add a breakpoint here) while(1 == 1);
}
5.15.2.2 swap_test()
void swap_test (
                Complex state[] )
swap test nice visuals
```

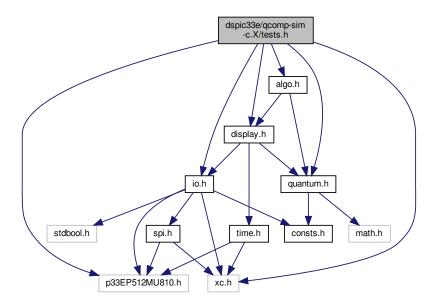
swap for ever!

5.16 dspic33e/qcomp-sim-c.X/tests.h File Reference

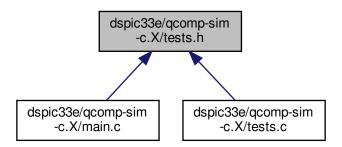
Description: Header file containing all the tests we performed.

```
#include "p33EP512MU810.h"
#include "xc.h"
#include "quantum.h"
#include "display.h"
#include "algo.h"
#include "io.h"
```

Include dependency graph for tests.h:



This graph shows which files directly or indirectly include this file:



Functions

```
void mat_mul_test ()
void mat_mul_test_cmplx ()
void one_qubit ()
void one_qubit_cmplx ()
void dim_leds ()

Testing the speed of 2^ 15 2x2 real matrix multiplications void mat_mul_test() {.
void multi_led_strobe ()
void delay ()

delays for 100,000
void swap_test (Complex state[])

swap test nice visuals
```

5.16.1 Detailed Description

Description: Header file containing all the tests we performed.

5.16.2 Function Documentation

```
5.16.2.1 delay()  \begin{tabular}{ll} void delay ( ) \\ delays for 100,000 \\ \hline 5.16.2.2 dim_leds() \\ \hline void dim_leds ( ) \\ \hline Testing the speed of 2^15 2x2 real matrix multiplications void mat_mul_test() {.} \\ \hline Define state vector <math>|0>=(1,0)|1>=(0,1) Vector V; init_state(V, ZERO); Matrix2 X = {{0}}, Z = {{0}}, H = {{0}}; make_ops(X, Z, H); \\ \hline Start the timer start_timer(); \\ \hline Do a matrix multiplication test unsigned int n = 0; while (n < 32768) { mat_mul(X, V); n++; } \\ \hline Read the timer unsigned long int time = read_timer(); \\ \hline Show that the test is finished set_led(red, on); \\ \hline wait (add a breakpoint here) while(1 == 1); \\ \hline \}
```

5.16.2.3 swap_test()

swap test nice visuals

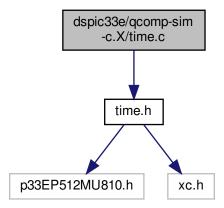
swap for ever!

5.17 dspic33e/qcomp-sim-c.X/time.c File Reference

Description: Functions to control the on chip timers.

```
#include "time.h"
```

Include dependency graph for time.c:



Functions

- void setup_clock ()
- void setup_timer ()
- void reset_timer ()
- void start_timer ()
- void stop_timer ()
- unsigned long int read_timer ()
- void delay ()

Delay function!

5.17.1 Detailed Description

Description: Functions to control the on chip timers.

5.17.2 Function Documentation

```
5.17.2.1 delay()

void delay ( )

Delay function!

delays for 100,000

5.17.2.2 setup_timer()

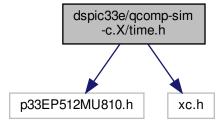
void setup_timer ( )
```

Todo distinguish between the two different timers here...

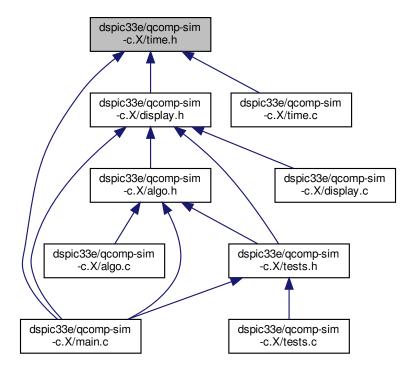
5.18 dspic33e/qcomp-sim-c.X/time.h File Reference

Description: Header file containing all the timing functions.

```
#include "p33EP512MU810.h"
#include "xc.h"
Include dependency graph for time.h:
```



This graph shows which files directly or indirectly include this file:



Functions

- void setup_clock ()
- void setup_timer ()
- void reset_timer ()
- void start_timer ()
- void stop_timer ()
- unsigned long int read_timer ()
- void delay ()

Delay function!

5.18.1 Detailed Description

Description: Header file containing all the timing functions.

5.18.2 Function Documentation

```
5.18.2.1 delay()

void delay ( )

Delay function!

delays for 100,000

5.18.2.2 setup_timer()

void setup_timer ( )
```

Todo distinguish between the two different timers here...

Index

attribute	sort_states, 24
io.c, 32	display.h
alaaduda	display_average, 26
absolute	display_cycle, 27
quantum.c, 50	remove_zero_amp_states, 28
quantum.h, 56	sort_states, 29
add_to_cycle	display_average
io.c, 32	display.c, 21
io.h, 42	display.h, 26
algo.c	display_cycle
gate, 12	display.c, 23
two_gate, 12	display.h, 27
algo.h	dspic33e/qcomp-sim-c.X/algo.c, 11
gate, 14	dspic33e/qcomp-sim-c.X/algo.h, 13
two_gate, 14	dspic33e/qcomp-sim-c.X/config.h, 15
	dspic33e/qcomp-sim-c.X/consts.c, 15
BTN_CHIP_NUM	dspic33e/qcomp-sim-c.X/consts.h, 18
io.c, 31	dspic33e/qcomp-sim-c.X/display.c, 20
buttons	dspic33e/qcomp-sim-c.X/display.h, 25
io.c, 38	dspic33e/qcomp-sim-c.X/io.c, 29
	dspic33e/qcomp-sim-c.X/io.h, 39
consts.c	dspic33e/qcomp-sim-c.X/main.c, 48
H, 16	dspic33e/qcomp-sim-c.X/quantum.c, 50
rX, 16	dspic33e/qcomp-sim-c.X/quantum.h, 55
X, 16	dspic33e/qcomp-sim-c.X/spi.c, 59
Y, 17	dspic33e/qcomp-sim-c.X/spi.h, 62
Z, 17	dspic33e/qcomp-sim-c.X/tests.c, 64
consts.h	dspic33e/qcomp-sim-c.X/tests.h, 66
H, 19	dspic33e/qcomp-sim-c.X/time.c, 68
rX, 19	dspic33e/qcomp-sim-c.X/time.h, 69
X, 19	dopieced/quemp em en quiment, ee
Y, 19	flash_all
Z, 20	io.c, 33
controlled_qubit_op	io.h, 42
quantum.c, 52	flash led
quantum.h, 56	io.c, 33
cycle_node, 7	io.h, 43
• - /	10.11, 40
delay	gate
tests.h, 67	algo.c, 12
time.c, 69	algo.h, 14
time.h, 70	algon, 11
dim_leds	Н
tests.c, 65	consts.c, 16
tests.h, 67	consts.h, 19
display.c	conoton, iv
display average, 21	io.c
display_cycle, 23	attribute, 32
NUM_MAX_AMPS, 21	add_to_cycle, 32
remove_zero_amp_states, 23	BTN_CHIP_NUM, 31
	5.11_0110M, 01

74 INDEX

	buttons, 38	display.c, 21
	flash_all, 33	<u>.</u>
	flash_led, 33	quantum.c
	isr_counter, 39	absolute, 50
	led_color_int, 33	controlled_qubit_op, 52
	led_cycle_test, 34	mat_mul, 52
	led_global, 39	single_qubit_op, 53
	read_btn, 34	zero_state, 54
	read_external_buttons, 34	quantum.h
	reset_cycle, 34	absolute, 56
	set_external_led, 35	controlled_qubit_op, 56 mat_mul, 57
	set_led, 35	single_qubit_op, 58
	set_strobe, 36	zero_state, 59
	setup_external_leds, 36	zero_state, 55
	setup_io, 36 TLC591x_mode_switch, 36	RGB, 9
	toggle_strobe, 37	read btn
	update_display_buffer, 37	 io.c, <mark>34</mark>
	write_display_driver, 38	io.h, 44
io.h	write_display_driver, 50	read external buttons
10.11	add_to_cycle, 42	io.c, 34
	flash_all, 42	io.h, 44
	flash_led, 43	remove_zero_amp_states
	led_color_int, 43	display.c, 23
	led_cycle_test, 44	display.h, 28
	read_btn, 44	reset_cycle
	read_external_buttons, 44	io.c, 34
	reset_cycle, 44	io.h, 44
	set_external_led, 45	rX
	set_led, 45	consts.c, 16
	set_strobe, 46	consts.h, 19
	setup external leds, 46	
	setup_io, 46	send_byte_spi_1
	toggle_strobe, 46	spi.c, 60
	update_display_buffer, 47	spi.h, 63
	write_display_driver, 48	set_external_led
isr_c	counter	io.c, 35
	io.c, 39	io.h, 45
		set_led
	_GLOBAL, 8	io.c, 35
LED		io.h, 45 set strobe
led_	color_int	io.c, 36
	io.c, 33	io.h, 46
	io.h, 43	setup_external_leds
led_	cycle_test	io.c, 36
	io.c, 34	io.h, 46
	io.h, 44	setup_io
lea_	global	io.c, 36
	io.c, 39	io.h, 46
mair		setup_spi
mail	main.c, 49	spi.c, 61
mair		spi.h, 63
man	main, 49	setup_timer
mat		time.c, 69
	quantum.c, 52	time.h, 71
	quantum.h, 57	single_qubit_op
	, -	quantum.c, 53
NUN	M_MAX_AMPS	quantum.h, 58

```
sort_states
     display.c, 24
     display.h, 29
spi.c
     send_byte_spi_1, 60
     setup_spi, 61
spi.h
     send_byte_spi_1, 63
     setup_spi, 63
swap_test
    tests.c, 65
     tests.h, 67
TLC591x_mode_switch
     io.c, 36
tests.c
     dim_leds, 65
     swap_test, 65
tests.h
     delay, 67
     dim_leds, 67
     swap_test, 67
time.c
     delay, 69
     setup_timer, 69
time.h
     delay, 70
     setup_timer, 71
toggle_strobe
     io.c, 37
     io.h, 46
two_gate
     algo.c, 12
     algo.h, 14
update_display_buffer
     io.c, 37
     io.h, 47
write_display_driver
     io.c, 38
     io.h, 48
Χ
     consts.c, 16
     consts.h, 19
Υ
     consts.c, 17
     consts.h, 19
Ζ
     consts.c, 17
    consts.h, 20
zero_state
     quantum.c, 54
     quantum.h, 59
```