Quantum Computer Outreach Project

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Contents

1	Todo	o List	1
2	Bug	List	3
3	Data	a Structure Index	5
	3.1	Data Structures	5
4	File	Index	7
	4.1	File List	7
5	Data	a Structure Documentation	9
	5.1	BTN Struct Reference	9
		5.1.1 Detailed Description	9
	5.2	cycle_node Struct Reference	10
		5.2.1 Detailed Description	10
	5.3	LED Struct Reference	10
		5.3.1 Detailed Description	11
	5.4	LED_GLOBAL Struct Reference	11
		5.4.1 Detailed Description	11
	5.5	RGB Struct Reference	12
		5.5.1 Detailed Description	10

ii CONTENTS

6	File	Docum	entation		13
	6.1	dspic3	3e/qcomp-	sim-c.X/algo.c File Reference	13
		6.1.1	Detailed	Description	15
		6.1.2	Function	Documentation	15
			6.1.2.1	gate()	15
			6.1.2.2	gate_display()	15
			6.1.2.3	swap_test()	15
			6.1.2.4	toffoli_gate()	16
			6.1.2.5	two_gate()	16
			6.1.2.6	two_gate_display()	17
	6.2	dspic3	3e/qcomp-	sim-c.X/algo.h File Reference	17
		6.2.1	Detailed	Description	18
		6.2.2	Function	Documentation	18
			6.2.2.1	gate()	19
			6.2.2.2	gate_display()	19
			6.2.2.3	swap_test()	19
			6.2.2.4	toffoli_gate()	19
			6.2.2.5	two_gate()	20
			6.2.2.6	two_gate_display()	20
	6.3	dspic3	3e/qcomp-	sim-c.X/config.h File Reference	21
		6.3.1	Detailed	Description	21
	6.4	dspic3	3e/qcomp-	sim-c.X/consts.c File Reference	21
		6.4.1	Detailed	Description	22
		6.4.2	Variable I	Documentation	22
			6.4.2.1	$H \ldots \ldots \ldots \ldots$	22
			6.4.2.2	rX	23
			6.4.2.3	rXT	23
			6.4.2.4	x	23
			6.4.2.5	Y	24
			6.4.2.6	z	24

CONTENTS

6.5	dspic3	3e/qcomp-	-sim-c.X/consts.h File Reference	. 24
	6.5.1	Detailed	Description	. 26
	6.5.2	Variable	Documentation	. 26
		6.5.2.1	Н	. 26
		6.5.2.2	rX	. 26
		6.5.2.3	rXT	. 27
		6.5.2.4	x	. 27
		6.5.2.5	Y	. 27
		6.5.2.6	Z	. 27
6.6	dspic3	3e/qcomp-	-sim-c.X/display.c File Reference	. 28
	6.6.1	Detailed	Description	. 29
	6.6.2	Macro De	efinition Documentation	. 29
		6.6.2.1	NUM_MAX_AMPS	. 29
	6.6.3	Function	Documentation	. 29
		6.6.3.1	display_average()	. 29
		6.6.3.2	display_cycle()	. 31
		6.6.3.3	remove_zero_amp_states()	. 32
		6.6.3.4	sort_states()	. 32
6.7	dspic3	3e/qcomp-	-sim-c.X/display.h File Reference	. 33
	6.7.1	Detailed	Description	. 34
	6.7.2	Function	Documentation	. 34
		6.7.2.1	display_average()	. 34
		6.7.2.2	display_cycle()	. 36
		6.7.2.3	remove_zero_amp_states()	. 37
		6.7.2.4	sort_states()	. 37
6.8	dspic3	3e/qcomp-	-sim-c.X/io.c File Reference	. 38
	6.8.1	Detailed	Description	. 40
	6.8.2	Function	Documentation	. 40
		6.8.2.1	attribute()	. 40
		6.8.2.2	add_to_cycle()	. 41

iv CONTENTS

		6.8.2.3	flash_all()	41
		6.8.2.4	flash_led()	41
		6.8.2.5	led_color_int()	42
		6.8.2.6	led_cycle_test()	42
		6.8.2.7	read_btn()	42
		6.8.2.8	read_external_buttons()	43
		6.8.2.9	reset_cycle()	43
		6.8.2.10	set_external_led()	43
		6.8.2.11	set_led()	44
		6.8.2.12	set_strobe()	44
		6.8.2.13	setup_external_leds()	45
		6.8.2.14	setup_io()	45
		6.8.2.15	TLC591x_mode_switch()	45
		6.8.2.16	toggle_strobe()	46
		6.8.2.17	update_display_buffer()	46
		6.8.2.18	write_display_driver()	47
	6.8.3	Variable	Documentation	47
		6.8.3.1	btn_func	47
		6.8.3.2	btn_qubit	47
		6.8.3.3	buttons	48
		6.8.3.4	chip	48
		6.8.3.5	isr_counter	48
		6.8.3.6	led_global	48
6.9	dspic3	3e/qcomp-	-sim-c.X/io.h File Reference	49
	6.9.1	Detailed	Description	51
	6.9.2	Function	Documentation	51
		6.9.2.1	add_to_cycle()	51
		6.9.2.2	flash_all()	52
		6.9.2.3	flash_led()	52
		6.9.2.4	led_color_int()	52

CONTENTS

		6.9.2.5	led_cycle_test()	54
		6.9.2.6	read_btn()	54
		6.9.2.7	read_external_buttons()	54
		6.9.2.8	reset_cycle()	55
		6.9.2.9	set_external_led()	55
		6.9.2.10	set_led()	56
		6.9.2.11	set_strobe()	56
		6.9.2.12	setup_external_leds()	56
		6.9.2.13	setup_io()	57
		6.9.2.14	toggle_strobe()	57
		6.9.2.15	update_display_buffer()	57
		6.9.2.16	write_display_driver()	58
6.10	dspic33	Be/qcomp-	-sim-c.X/main.c File Reference	59
	6.10.1	Detailed	Description	60
	6.10.2	Function	Documentation	60
		6.10.2.1	main()	60
6.11	dspic33	Be/qcomp-	-sim-c.X/quantum.c File Reference	61
	6.11.1	Detailed	Description	62
	6.11.2	Function	Documentation	62
		6.11.2.1	absolute()	62
		6.11.2.2	controlled_qubit_op()	62
		6.11.2.3	controlled_qubit_op_new()	63
		6.11.2.4	mat_mul()	65
		6.11.2.5	mat_mul_old()	65
		6.11.2.6	pow2()	66
		6.11.2.7	sign()	66
		6.11.2.8	single_qubit_op()	66
		6.11.2.9	square_magnitude()	67
		6.11.2.10) zero_state()	68
6.12	dspic33	Be/qcomp-	-sim-c.X/quantum.h File Reference	68

vi CONTENTS

Index														85
		6.16.2.1	setup_	_timer())			 	 	 	 	 	 	83
	6.16.2	Function	Docum	entatio	n			 	 	 	 	 	 	83
	6.16.1	Detailed	Descrip	tion .				 	 	 	 	 	 	83
6.16	dspic33	3e/qcomp-	-sim-c.X	/time.h	r File R	Referer	nce .	 	 	 	 	 	 	82
		6.15.2.1	setup_	_timer())			 	 	 	 	 	 	82
	6.15.2	Function	Docum	entatio	n			 	 	 	 	 	 	82
	6.15.1	Detailed	Descrip	tion .				 	 	 	 	 	 	81
6.15	dspic33	3e/qcomp-	-sim-c.X	/time.c	: File R	leferer	nce .	 	 	 	 	 	 	81
		6.14.2.2	setup_	_spi() .				 	 	 	 	 	 	79
		6.14.2.1	send_	byte_s	pi_1()			 	 	 	 	 	 	79
	6.14.2	Function	Docum	entatio	n			 	 	 	 	 	 	79
	6.14.1	Detailed	Descrip	tion .				 	 	 	 	 	 	79
6.14	dspic33	3e/qcomp-	-sim-c.X	/spi.h l	File Re	eferenc	ce .	 	 	 	 	 	 	78
		6.13.2.2	setup_	_spi() .				 	 	 	 	 	 	77
		6.13.2.1	send_	byte_s	pi_1()			 	 	 	 	 	 	76
	6.13.2	Function	Docum	entatio	n			 	 	 	 	 	 	 75
	6.13.1	Detailed	Descrip	tion .				 	 	 	 	 	 	75
6.13	dspic33	3e/qcomp-	-sim-c.X	/spi.c l	File Re	ferenc	ce .	 	 	 	 	 	 	 75
		6.12.2.8	zero_s	state()				 	 	 	 	 	 	74
		6.12.2.7	square	e_magi	nitude(<u>)</u>		 	 	 	 	 	 	74
		6.12.2.6	- "											72
		6.12.2.5												72
		6.12.2.4												72
		6.12.2.3												71
		6.12.2.2												70
		6.12.2.1												70
	6.12.2	Function	Docum	entatio	n			 	 	 	 	 	 	70
	6.12.1	Detailed	Descrip	tion .				 	 	 	 	 	 	70

Chapter 1

Todo List

Global absolute (Complex x)

Check that the complex part is small

Global controlled_qubit_op (const Complex op[2][2], int ctrl, int targ, Complex state[])

This expression can probably be simplified or broken over lines. The condition for the if statement is that root+step and root + step + root_max contain 1 in the ctrl-th bit.

Global controlled_qubit_op_new (const Complex op[2][2], int ctrl, int targ, Complex state[])

Replace pow2 with left rotations

The problem is the formula for the increment

Global display_average (Complex state[])

Bring all constants out of the loops. Don't use pow. Loop over all qubits k = 0, 1, 2, ... N-1

Rewrite pow for Q15

rename to display_average

Global led_cycle_test (void)

This won't work now: write_display_driver(counter);

Global mat_mul (const Complex M[2][2], Complex V[], int i, int j)

Is static enough? Or should we declare outside the function?

Should we use for loops? Or is it better not to ..?

Because of the way the array types work (you can't pass a multidimensional array of unknown size) we will also need a function for 4x4 matrix multiplication.

Global mat_mul_old (const Complex M[2][2], Complex V[], int i, int j)

Should these be outside the function?

File quantum.c

split into a complex math and operator files

Global read_external_buttons (void)

read buttons

How long should this be?

button remappings...

Global reset_cycle (void)

do it

Global setup_external_leds (void)

CURRENTLY CYCLING IS OFF

2 Todo List

Global setup timer ()

distinguish between the two different timers here...

Global single_qubit_op (const Complex op[2][2], int qubit, Complex state[])

Should we inline mat_mul here?

Global single_qubit_op (const Complex op[2][2], int qubit, Complex state[])

Should we inline mat_mul here?

Global sort_states (Complex state[], int num_qubits)

this function...

this

Global square_magnitude (Complex x)

Maybe we should inline this

Maybe we should inline this

Global TLC591x_mode_switch (int mode)

mode switcher for LED Driver

Global toffoli_gate (int q1, int q2, int q3, Complex state[])

Fancy non-blocking Interrupt routine { if(no button) return;

Global write_display_driver (void)

How long should this be?

Chapter 2

Bug List

Global btn_func [NUM_BTNS - NUM_QUBITS] this.

4 Bug List

Chapter 3

Data Structure Index

3.1 Data Structures

Here are the data structures with brief descriptions:

Pin mappings	9
ode Control of the Co	
The basis for a linked list of states to cycle	10
Each LED has the following type	10
OBAL	
Global LED strobing state parameter	11
A type for holding red, green, blue values	12
	The basis for a linked list of states to cycle

6 Data Structure Index

Chapter 4

File Index

4.1 File List

Here is a list of all documented files with brief descriptions:

aspicsse/qcomp-sim-c.x/aigo.c	
Contains quantum algorithms to be run	13
dspic33e/qcomp-sim-c.X/algo.h	
Header file for algorithms	17
dspic33e/qcomp-sim-c.X/config.h	
General config settings #pragma for microcontroller	21
dspic33e/qcomp-sim-c.X/consts.c	
All (global) constants)	21
dspic33e/qcomp-sim-c.X/consts.h	
Header file for (global) constants	24
dspic33e/qcomp-sim-c.X/display.c	
For all the state display functions	28
dspic33e/qcomp-sim-c.X/display.h	
Description: Header file containing all the functions for displaying the qubits state vector	33
dspic33e/qcomp-sim-c.X/io.c	
Contains all the functions for reading buttons and writing to LEDs	38
dspic33e/qcomp-sim-c.X/io.h	
Description: Header file for input output functions	49
dspic33e/qcomp-sim-c.X/main.c	
The main function	59
dspic33e/qcomp-sim-c.X/quantum.c	
Description: Contains matrix and vector arithmetic for simulating one qubit	61
dspic33e/qcomp-sim-c.X/quantum.h	
Description: Header file containing all the matrix arithmetic for simulating a single qubit	68
dspic33e/qcomp-sim-c.X/spi.c	
Description: Functions for communicating with serial devices	75
dspic33e/qcomp-sim-c.X/spi.h	
Description: SPI communication functions	78
dspic33e/qcomp-sim-c.X/time.c	
Description: Functions to control the on chip timers	81
dspic33e/qcomp-sim-c.X/time.h	
Description: Header file containing all the timing functions	82

8 File Index

Chapter 5

Data Structure Documentation

5.1 BTN Struct Reference

```
pin mappings
```

```
#include <io.h>
```

Data Fields

- · int chip
- int line

[chip number]

5.1.1 Detailed Description

pin mappings

```
// Pins for LE and OE on port D
// OE = RD4 = uC:81 = J1:28 = J10:14
// LE = RD3 = uC:78 = J1:40 = J11:18
//
// Pins for SH and CLK_INH on port D
// SH = RD5 = uC:82 = J1:25 = J10:13
// CLK_INH = RD8 = uC:68 = J1:58 = J11:25
```

button mapping type

The documentation for this struct was generated from the following file:

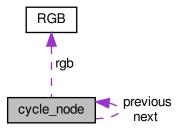
• dspic33e/qcomp-sim-c.X/io.h

5.2 cycle_node Struct Reference

The basis for a linked list of states to cycle.

```
#include <io.h>
```

Collaboration diagram for cycle_node:



Data Fields

• RGB * rgb

Array of corresponding RGB values.

• int size

The size of the above arrays.

struct cycle_node * next

Pointer to the next item.

• struct cycle_node * previous

Pointer to the previous item.

5.2.1 Detailed Description

The basis for a linked list of states to cycle.

The documentation for this struct was generated from the following file:

• dspic33e/qcomp-sim-c.X/io.h

5.3 LED Struct Reference

Each LED has the following type.

#include <io.h>

Data Fields

- int **R** [2]
- int G [2]

Red mapping array: [chip number, line number].

• int B [2]

Green mapping array.

unsigned _Fract N_R

Blue mapping array.

unsigned _Fract N_G

The R brightness.

unsigned _Fract N_B

The G brightness.

5.3.1 Detailed Description

Each LED has the following type.

The type holds the information about the position of the RGB lines in the display driver array and also the brightness of the RGB lines. The counters are used by a timer interrupt service routine pulse the RGB LEDs at a specified rate.

The position of the LED lines are contained in an array

The type of the counter is Fract to facilitate easy comparison with the N* variables which used the fractional type.

The documentation for this struct was generated from the following file:

• dspic33e/qcomp-sim-c.X/io.h

5.4 LED_GLOBAL Struct Reference

Global LED strobing state parameter.

```
#include <io.h>
```

Data Fields

• int strobe_leds

Bit set the LEDs which are strobing.

int strobe_state

Bit zero is the current state (on/off)

5.4.1 Detailed Description

Global LED strobing state parameter.

The documentation for this struct was generated from the following file:

dspic33e/qcomp-sim-c.X/io.h

5.5 RGB Struct Reference

A type for holding red, green, blue values.

```
#include <io.h>
```

Data Fields

- unsigned _Fract R
- unsigned _Fract G
- unsigned _Fract B

5.5.1 Detailed Description

A type for holding red, green, blue values.

The documentation for this struct was generated from the following file:

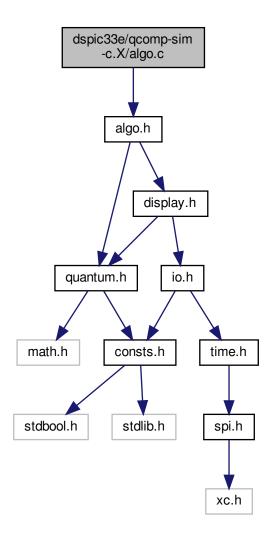
• dspic33e/qcomp-sim-c.X/io.h

Chapter 6

File Documentation

6.1 dspic33e/qcomp-sim-c.X/algo.c File Reference

#include "algo.h"
Include dependency graph for algo.c:



Functions

- void gate (const Complex op[2][2], int qubit, Complex state[])
 single qubit gate
- void gate_display (const Complex op[2][2], int qubit, Complex state[])
 single qubit gate with display
- void two_gate (const Complex op[2][2], int ctrl, int targ, Complex state[])
 two-qubit gate
- void two_gate_display (const Complex op[2][2], int ctrl, int targ, Complex state[])
 two-qubit gate with display
- void swap (int q1, int q2, Complex state[])
 swap using 3 cNots
- void swap_test (Complex state[])

from tests.c

• void toffoli_gate (int q1, int q2, int q3, Complex state[])

Toffoli gate.

void toffoli_test (Complex state[])

6.1.1 Detailed Description

Contains quantum algorithms to be run.

Authors

J Scott, O Thomas

Date

Nov 2018

6.1.2 Function Documentation

```
6.1.2.1 gate()
```

single qubit gate

perform single qubit gate does 2x2 operator on state vector

6.1.2.2 gate_display()

single qubit gate with display

Display gates!!! does 2x2 operator on state vector displays the average state of the qubit by tracing over all waits to let the user see the state (LEDs)

6.1.2.3 swap_test()

from tests.c

swap for ever!

```
6.1.2.4 toffoli_gate()
```

Toffoli gate.

Todo Fancy non-blocking Interrupt routine { if(no button) return;

pause and do display cycling();

Make this a low priority interrupt so that everything else can interrupt it.

Do stuff for a while

return when you're done.

```
/// -o-- -----o---o--o----
/// -|-- ----|----|-----
/// -o-- = ---o--X--o--X--|-----
/// -|- ---|----|-----
/// -X-- -rX---rX*--rX----
/// a b c d e
```

q1 ctrl 1 q2 ctrl 2 q3 target < a

```
< b
```

}

< c

 $<\mathsf{d}$

< e

6.1.2.5 two_gate()

two-qubit gate

perform controlled single qubit gate does controlled 2x2 operator

6.1.2.6 two_gate_display()

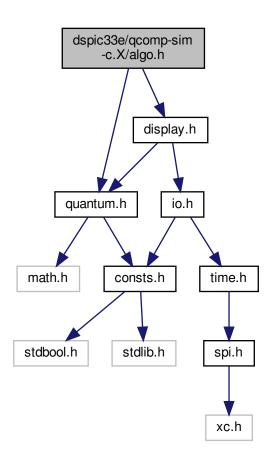
two-qubit gate with display

does controlled 2x2 operator displays the state waits to let the user see the state

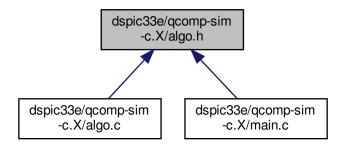
6.2 dspic33e/qcomp-sim-c.X/algo.h File Reference

header file for algorithms

```
#include "quantum.h"
#include "display.h"
Include dependency graph for algo.h:
```



This graph shows which files directly or indirectly include this file:



Functions

- void gate (const Complex op[2][2], int qubit, Complex state[])
 perform single qubit gate
- void two_gate (const Complex op[2][2], int ctrl, int targ, Complex state[])
 perform controlled single qubit gate
- void gate_display (const Complex op[2][2], int qubit, Complex state[])
 Display gates!!!
- void two_gate_display (const Complex op[2][2], int ctrl, int targ, Complex state[])
 two-qubit gate with display
- void swap (int q1, int q2, Complex state[]) swap using 3 cNots
- void swap_test (Complex state[])

from tests.c

- void toffoli_gate (int q1, int q2, int q3, Complex state[])
 Toffoli gate.
- void toffoli_test (Complex state[])

6.2.1 Detailed Description

header file for algorithms

Authors

J Scott, O Thomas

Date

Nov 2018

6.2.2 Function Documentation

```
6.2.2.1 gate()
```

perform single qubit gate

perform single qubit gate does 2x2 operator on state vector

6.2.2.2 gate_display()

Display gates!!!

Display gates!!! does 2x2 operator on state vector displays the average state of the qubit by tracing over all waits to let the user see the state (LEDs)

6.2.2.3 swap_test()

from tests.c

swap for ever!

6.2.2.4 toffoli_gate()

```
void toffoli_gate (
                int q1,
                int q2,
                int q3,
                Complex state[] )
```

Toffoli gate.

Todo Fancy non-blocking Interrupt routine { if(no button) return;

pause and do display cycling();

Make this a low priority interrupt so that everything else can interrupt it.

Do stuff for a while

return when you're done.

}

```
/// -o-- = ---o--X--o--X--|-----
/// -|-- ---|----|-----|
/// -X-- -rX---rX*--rX----
/// a b c d e
///
q1 ctrl 1 q2 ctrl 2 q3 target < a
< b
< c
< d
< e
6.2.2.5 two_gate()
void two_gate (
             const Complex op[2][2],
             int ctrl,
             int targ,
              Complex state[] )
perform controlled single qubit gate
perform controlled single qubit gate does controlled 2x2 operator
```

6.2.2.6 two_gate_display()

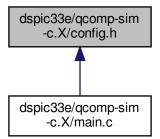
two-qubit gate with display

does controlled 2x2 operator displays the state waits to let the user see the state

6.3 dspic33e/qcomp-sim-c.X/config.h File Reference

General config settings #pragma for microcontroller.

This graph shows which files directly or indirectly include this file:



6.3.1 Detailed Description

General config settings #pragma for microcontroller.

Authors

J Scott, O Thomas

Date

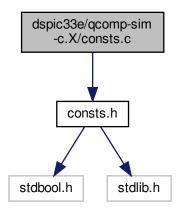
Nov 2018

Description: Include this once at the top of main

6.4 dspic33e/qcomp-sim-c.X/consts.c File Reference

contains all (global) constants)

```
#include "consts.h"
Include dependency graph for consts.c:
```



Variables

- const Complex rX [2][2]
- const Complex rXT [2][2]
- const Complex X [2][2]
- const Complex Y [2][2]
- const Complex Z [2][2]
- const Complex H [2][2]

6.4.1 Detailed Description

contains all (global) constants)

Authors

J Scott, O Thomas

Date

Nov 2018

6.4.2 Variable Documentation

```
6.4.2.1 H
```

```
const Complex H[2][2]
```

Initial value:

```
 \begin{array}{lll} = & \{ \{ \{ 0.7071067812, \ 0.0 \}, \ \{ 0.7071067812, \ 0.0 \} \}, \\ & \{ \{ 0.7071067812, \ 0.0 \}, \ \{ -0.7071067812, \ 0.0 \} \} \} \end{array}
```

Parameters

```
Hadamard gate
```

6.4.2.2 rX

```
const Complex rX[2][2]
```

Initial value:

```
= {{{0.5, 0.5},{0.5, -0.5}},
{{0.5, -0.5},{0.5, 0.5}}}
```

Parameters

```
rX | sqrt X gate ( 0.5+0.5i 0.5-0.5i ) ( 0.5-0.5i 0.5+0.5i )
```

6.4.2.3 rXT

```
const Complex rXT[2][2]
```

Initial value:

```
= {{{0.5, -0.5},{0.5, 0.5}},
{{0.5, 0.5},{0.5, -0.5}}}
```

Parameters

```
rXT Adjoint of rX
```

6.4.2.4 X

```
const Complex X[2][2]
```

Initial value:

```
= \{\{\{0.0, 0.0\}, \{ONE\_Q15, 0.0\}\}, \\ \{\{ONE\_Q15, 0.0\}, \{0.0, 0.0\}\}\}
```

Parameters

```
X pauli X gate
```

6.4.2.5 Y

```
const Complex Y[2][2]
```

Initial value:

```
= {{{0.0, 0.0}, {0.0, -1.0}}, {{0.0, 0NE_Q15}, {0.0, 0.0}}}
```

Parameters

```
Y Pauli y gate
```

6.4.2.6 Z

```
const Complex Z[2][2]
```

Initial value:

```
= {{{ONE_Q15, 0.0}, {0.0, 0.0}}, {0.0, 0.0}}, {-1.0, 0.0}}
```

Parameters

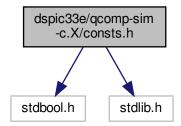
Z Pauli z gate

6.5 dspic33e/qcomp-sim-c.X/consts.h File Reference

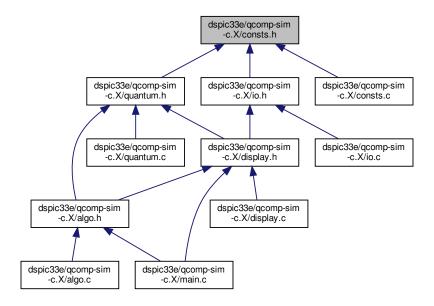
header file for (global) constants

```
#include <stdbool.h>
#include <stdlib.h>
```

Include dependency graph for consts.h:



This graph shows which files directly or indirectly include this file:



Macros

- #define NUM_QUBITS 4
- #define STATE LENGTH 16
- #define FULL_PHASE 0.124996185
- #define HALF_PHASE 0.062498093
- #define LED_NUM 4

The number of external LEDs.

• #define NUM_BTNS 9

number of total buttons

- #define ONE_Q15 0.9999694824
- #define BTN_CHIP_NUM 2

Typedefs

- typedef signed _Fract Q15
 Basic fractional time.
- typedef Q15 Complex[2] Complex type.

Variables

- const Complex rX [2][2]
- const Complex rXT [2][2]
- const Complex X [2][2]
- const Complex Y [2][2]
- const Complex Z [2][2]
- const Complex H [2][2]

6.5.1 Detailed Description

header file for (global) constants

Authors

J Scott, O Thomas

Date

Nov 2018

6.5.2 Variable Documentation

6.5.2.1 H

```
const Complex H[2][2]
```

Parameters

Hadamard gate

6.5.2.2 rX

const Complex rX[2][2]

Parameters

rX	is square root of X
rΧ	sqrt X gate (0.5+0.5i 0.5-0.5i) (0.5-0.5i 0.5+0.5i)

6.5.2.3 rXT

const Complex rXT[2][2]

Parameters

rXT Adjoint of rX

6.5.2.4 X

const Complex X[2][2]

Parameters

X pauli X gate

6.5.2.5 Y

const Complex Y[2][2]

Parameters

Y Pauli y gate

6.5.2.6 Z

const Complex Z[2][2]

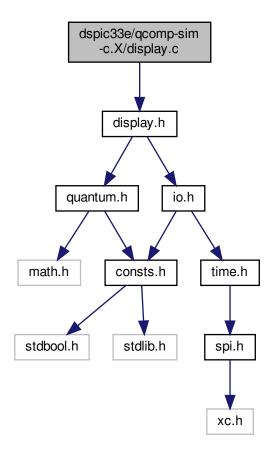
Parameters

Z Pauli z gate

6.6 dspic33e/qcomp-sim-c.X/display.c File Reference

for all the state display functions

#include "display.h"
Include dependency graph for display.c:



Macros

• #define NUM_MAX_AMPS 4

Functions

- void display_average (Complex state[])
 - Display the state amplitudes on LEDs.
- void display_cycle (Complex state[])
 - cycles through the non-zero amplitude states
- int sort_states (Complex state[], int num_qubits)
- int remove_zero_amp_states (Complex state[], int disp_state[])
 - takes state vector, number of qubits and vector to write the nonzero elements of the statevector to.

6.6.1 Detailed Description

for all the state display functions

6.6.2 Macro Definition Documentation

6.6.2.1 NUM_MAX_AMPS

```
#define NUM_MAX_AMPS 4
```

Parameters

state	The state vector
num_qubits	The number of qubits in the state vector

Returns

This function finds the amplitude of the state vector with the largest magnitude.

6.6.3 Function Documentation

6.6.3.1 display_average()

Display the state amplitudes on LEDs.

Parameters

```
state Pass in the state vector
```

Note

Currently the function only displays superpositions using the red and blue colors.

The routine works by adding up the squares of the amplitudes corresponding to each state of a given qubit. Suppose there are three qubits. Then the state vector is given by

*	index	binary	amplitude
*			
*	0	0 0 0	a0
*	1	0 0 1	a1
*	2	0 1 0	a2
*	3	0 1 1	a3
*	4	1 0 0	a4
*	5	1 0 1	a5
*	6	1 1 0	a6
*	7	1 1 1	a7
*			
*	Qubit:	2 1 0	
*			

Consider qubit 2. The value of the ZERO state is formed by adding up all the amplitudes corresponding to its ZERO state. That is, indices 0, 1, 2 and 3. The ONE state is obtained by adding up the other indices: 4, 5, 6 and

1.

So the amplitudes for qubit 2 are

ZERO:
$$(a_0)^2 + (a_1)^2 + (a_2)^2 + (a_3)^2$$
 ONE: $(a_4)^2 + (a_5)^2 + (a_6)^2 + (a_7)^2$

Corresponding to the following indices:

ZERO: 0+0, 1+0, 2+0, 3+0 ONE: 4+0, 5+0, 6+0, 7+0

For qubit 1 the indices are:

ZERO: 0+0, 0+4, 1+0, 1+4 ONE: 2+0, 2+4, 3+0, 3+4

And for qubit 0 the indices are:

ZERO: 0+0, 0+2, 0+4, 0+6 ONE: 1+0, 1+2, 1+4, 1+6

The examples above are supposed to show the general pattern. For N qubits, qubit number k, the ZERO and ONE states are given by summing all the square amplitudes corresponding to the following indices:

ZERO:
$$n + (2^{\wedge}(k+1) * j)$$
, where $n = 0, 1, ..., 2^{\wedge}k - 1$ and $j = 0, 1, ..., 2^{\wedge}(N-k-2)$

ONE:
$$n + (2^{\wedge}(k+1) * j)$$
, where $n = 2^{\wedge}k$, $2^{\wedge}k + 1$, ..., $2^{\wedge}(k+1) - 1$ and $j = 0, 1, ..., 2^{\wedge}(N-k-2)$

The amplitudes are obtained by summing over both n and j. Notice that there is an edge condition when k = N-1. There, j acycle_lengthpparently ranges from 0 to -1. In this case, the only value of j is 0. The condition arises because of the way that $2^{(N-k-2)}$ is obtained (i.e. such that multiplying it by $2^{(k+1)}$ gives $2^{(N-1)}$.) However, if k = N-1, then $2^{(k+1)} = 2^{N}$ already, so it must be multiplied by $2^{(-1)}$. The key point is that the second term should not ever equal $2^{(k+1)}$ so j should stop at 0.

The above indices can be expressed as the sum of a ROOT and a STEP as follows:

where ROOT ranges from 0 to 2^k-1 . This corresponds to the n values that give rise to ZERO. The indices for ONE can be obtained by adding 2^k to root. The STEP = j is a multiple of 2^k+1 starting from zero that does not equal or exceed 2^k . ROOT can be realised using the following for loop:

for(int root = 0; root $< 2^k$; root ++) $\{ \dots // ZERO \text{ index root}; // ONE \text{ index root} + 2^k; \}$

Then the STEP component can be realised as

for(int step = 0; step < 2^{N} ; step += $2^{(k+1)}$) { // Add the following to root... step; }

Todo Bring all constants out of the loops. Don't use pow. Loop over all qubits k = 0, 1, 2, ... N-1

Compute powers of 2

ROOT loop: starts at 0, increases in steps of 1

STEP loop: starts at 0, increases in steps of $2^{(k+1)}$

sign returns an int between 0 & 3 depending which quadrant the amp is in get the difference between quadrants if 0&3 do modulo 2 to get 1.

absolute value of the difference phase zero state - phase 1 state

```
/// c now equals 0 - no phase diff /// 1 or 3 - re or im phase diff /// 2 - complete phase diff ///
```

Zeros are at the index root + step

Todo Rewrite pow for Q15

Ones are at the index root + 2^k + step

write phase update leds for each qubits average zero and one amps

6.6.3.2 display_cycle()

cycles through the non-zero amplitude states

Parameters

state	The state to display
N	The length of the state vector

Filter the state

Allocate RGB array

Decode

Look at the jth bit

Reset the cycle

Each iteration of this loop writes

Loop here to add stuff

6.6.3.3 remove_zero_amp_states()

takes state vector, number of qubits and vector to write the nonzero elements of the statevector to.

updates disp_state where the first 'return value of the function'elements are the nonzero elements of the state vector 'state'

the disp_state elements are the nonzero elements of the state

```
/// e.g. state = (00) = (1/r2) (Bell state)
/// (01) (0 )
/// (10) (0 )
/// (11) (1/r2)
/// Then displ_state would have 2 elements
/// disp_state = (0) standing for (00)
/// (3) (11)
```

Note

we have to allocate disp_state to be the size of state, the function returns count which tells us the first 'count' elements of disp_state to use. In the Bell state example there are 2 values in disp_state, 0 & 3, count is returned as 3 which means take the first count-1 elements (in this case 2) of disp_state which is 0,1 which is the correct elements

6.6.3.4 sort_states()

Todo this

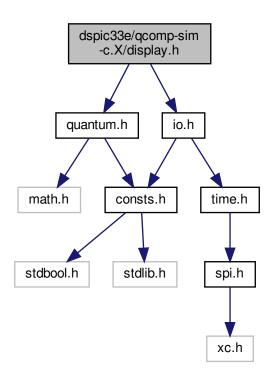
Todo this function...

6.7 dspic33e/qcomp-sim-c.X/display.h File Reference

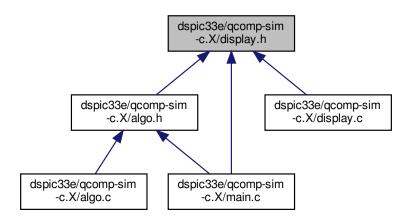
Description: Header file containing all the functions for displaying the qubits state vector.

```
#include "quantum.h"
#include "io.h"
```

Include dependency graph for display.h:



This graph shows which files directly or indirectly include this file:



Functions

void display_average (Complex state[])

Display the state amplitudes on LEDs.

• void display_cycle (Complex state[])

cycles through the non-zero amplitude states

• int remove_zero_amp_states (Complex state[], int disp_state[])

updates disp_state where the first 'return value of the function'elements are the nonzero elements of the state vector 'state'

• int sort_states (Complex state[], int num_qubits)

6.7.1 Detailed Description

Description: Header file containing all the functions for displaying the qubits state vector.

Authors

J Scott, O Thomas

Date

Nov 2018

6.7.2 Function Documentation

6.7.2.1 display_average()

Display the state amplitudes on LEDs.

Parameters

ctata	Pass in the state vector

Note

Currently the function only displays superpositions using the red and blue colors.

Todo rename to display_average

Parameters

state Pass in the state vector	
--------------------------------	--

Note

Currently the function only displays superpositions using the red and blue colors.

The routine works by adding up the squares of the amplitudes corresponding to each state of a given qubit. Suppose there are three qubits. Then the state vector is given by

*	index	binary	amplitude
*			
*	0	0 0 0	a0
*	1	0 0 1	a1
*	2	0 1 0	a2
*	3	0 1 1	a3
*	4	1 0 0	a4
*	5	1 0 1	a5
*	6	1 1 0	a6
*	7	1 1 1	a7
*			
*	Qubit:	2 1 0	

Consider qubit 2. The value of the ZERO state is formed by adding up all the amplitudes corresponding to its ZERO state. That is, indices 0, 1, 2 and 3. The ONE state is obtained by adding up the other indices: 4, 5, 6 and

1.

So the amplitudes for qubit 2 are

ZERO:
$$(a_0)^2 + (a_1)^2 + (a_2)^2 + (a_3)^2$$
 ONE: $(a_4)^2 + (a_5)^2 + (a_6)^2 + (a_7)^2$

Corresponding to the following indices:

ZERO: 0+0, 1+0, 2+0, 3+0 ONE: 4+0, 5+0, 6+0, 7+0

For qubit 1 the indices are:

ZERO: 0+0, 0+4, 1+0, 1+4 ONE: 2+0, 2+4, 3+0, 3+4

And for qubit 0 the indices are:

The examples above are supposed to show the general pattern. For N qubits, qubit number k, the ZERO and ONE states are given by summing all the square amplitudes corresponding to the following indices:

ZERO:
$$n + (2^{\wedge}(k+1) * j)$$
, where $n = 0, 1, ..., 2^{\wedge}k - 1$ and $j = 0, 1, ..., 2^{\wedge}(N-k-2)$
ONE: $n + (2^{\wedge}(k+1) * j)$, where $n = 2^{\wedge}k$, $2^{\wedge}k + 1$, ..., $2^{\wedge}(k+1) - 1$ and $j = 0, 1, ..., 2^{\wedge}(N-k-2)$

The amplitudes are obtained by summing over both n and j. Notice that there is an edge condition when k = N-1. There, j acycle_lengthpparently ranges from 0 to -1. In this case, the only value of j is 0. The condition arises because of the way that $2^{(N-k-2)}$ is obtained (i.e. such that multiplying it by $2^{(k+1)}$ gives $2^{(N-1)}$.) However, if k = N-1, then $2^{(k+1)} = 2^N$ already, so it must be multiplied by $2^{(-1)}$. The key point is that the second term should not ever equal 2^N , so j should stop at 0.

The above indices can be expressed as the sum of a ROOT and a STEP as follows:

$$index = ROOT + STEP$$

where ROOT ranges from 0 to 2^k-1 . This corresponds to the n values that give rise to ZERO. The indices for ONE can be obtained by adding 2^k to root. The STEP = j is a multiple of 2^k+1 starting from zero that does not equal or exceed 2^k-1 . ROOT can be realised using the following for loop:

for(int root = 0; root $< 2^k$; root ++) $\{ \dots // ZERO \text{ index root}; // ONE \text{ index root} + 2^k; \}$

Then the STEP component can be realised as

for (int step = 0; step < 2^N; step += 2^(k+1)) { // Add the following to root... step; }

Todo Bring all constants out of the loops. Don't use pow. Loop over all qubits k = 0, 1, 2, ... N-1

Compute powers of 2

ROOT loop: starts at 0, increases in steps of 1

STEP loop: starts at 0, increases in steps of $2^{(k+1)}$

sign returns an int between 0 & 3 depending which quadrant the amp is in get the difference between quadrants if 0&3 do modulo 2 to get 1.

absolute value of the difference phase zero state - phase 1 state

```
/// c now equals 0 - no phase diff /// 1 or 3 - re or im phase diff /// 2 - complete phase diff ///
```

Zeros are at the index root + step

Todo Rewrite pow for Q15

Ones are at the index root + 2^k + step

write phase update leds for each qubits average zero and one amps

6.7.2.2 display_cycle()

cycles through the non-zero amplitude states

Parameters

	state	The state to display
Ī	Ν	The length of the state vector

Filter the state

Allocate RGB array

Decode

Look at the jth bit

Reset the cycle

Each iteration of this loop writes

Loop here to add stuff

6.7.2.3 remove_zero_amp_states()

updates disp_state where the first 'return value of the function'elements are the nonzero elements of the state vector 'state'

Parameters

state	complex state vector in
disp_state	complex inout vector where the first n entries are the nonzero elements of 'state'

Returns

returns the number of elements to look at in disp state.

updates disp_state where the first 'return value of the function'elements are the nonzero elements of the state vector 'state'

the disp_state elements are the nonzero elements of the state

```
/// e.g. state = (00) = (1/r2) (Bell state)
/// (01) (0)
/// (10) (0)
/// (11) (1/r2)
/// Then displ_state would have 2 elements
/// disp_state = (0) standing for (00)
/// (3) (11)
```

Note

we have to allocate disp_state to be the size of state, the function returns count which tells us the first 'count' elements of disp_state to use. In the Bell state example there are 2 values in disp_state, 0 & 3, count is returned as 3 which means take the first count-1 elements (in this case 2) of disp_state which is 0,1 which is the correct elements

6.7.2.4 sort_states()

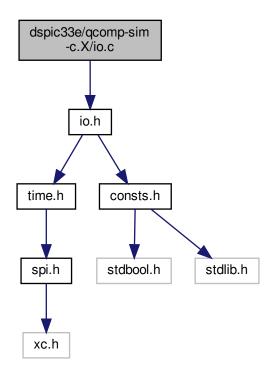
Todo this

Todo this function...

6.8 dspic33e/qcomp-sim-c.X/io.c File Reference

Contains all the functions for reading buttons and writing to LEDs.

#include "io.h"
Include dependency graph for io.c:



Macros

- #define **DISPLAY_CHIP_NUM** 2
- #define MAX CYCLE LENGTH 16
- #define **PERIOD** 500000

Functions

• int led_color_int (int device, int R, int G, int B)

Takes led number & RGB -> returns integer for sending via SPI to set the LED.

• int setup_io (void)

Set up LEDs and buttons on port D.

void <u>attribute</u> ((<u>interrupt</u>, no_auto_psv))

The max value for isr_counter.

void setup_external_leds (void)

Set external variable RGB LEDs.

• int add_to_cycle (RGB colors[], int size)

Add an item to the list of states to cycle.

int reset_cycle (void)

Reset the LED display cycle _*.

void stop_external_leds (void)

Stop LEDs flashing.

void set_strobe (int color, int state)

Set an LED strobing.

• void toggle_strobe (int color)

Toggle LED strobe.

• int set_led (int color, int state)

Turn a particular LED on or off.

• int read_btn (int btn)

Read the state of a push button.

void leds_off (void)

Turn all the LEDs off.

• void flash led (int color, int number)

Flash LED a number of times.

void flash all (int number)

Flash all the LEDs a number of times.

- int update_display_buffer (int n, bool R, bool G, bool B)
- int write_display_driver (void)

Turn on an LED via the external display driver.

int TLC591x_mode_switch (int mode)

Switch between normal and special mode.

• int set_external_led (int index, unsigned _Fract R, unsigned _Fract G, unsigned _Fract B)

Updates color properties of global led array.

• int read_external_buttons (void)

Read external buttons.

int led_cycle_test (void)

Loop to cycle through LEDs 0 - 15.

void varying_leds (void)

Routine to test the set_external_led function.

Variables

• int buttons [BTN_CHIP_NUM]

Contains the button states.

- LED_GLOBAL led_global = {0}
- LED led [LED_NUM]

The LED array – global in this file.

int display_buf [DISPLAY_CHIP_NUM] = {0}

Display buffer to be written to display driver.

• unsigned Fract isr counter = 0

Counter for the interrupt service routine _T5Interrupt.

unsigned _Fract isr_res = 0.01

Counter value.

• const unsigned Fract isr limit = 0.95

Counter resolution.

• RGB cycle_colors [MAX_CYCLE_LENGTH][NUM_QUBITS]

```
    int last_row = 0
    int cycle_counter = 0
    BTN btn_qubit [NUM_QUBITS] = 1
        button mapping 1st byte 00000100 btn A26-28 -> logical 0 00000010 btn A7-9 -> logical 6 00000001 btn A4-6 -> logical 7 00001000 btn A1-3 -> logical 8
    btn_qubit [0] chip = 0
        logical 0
    btn_qubit [0] line = 2
    BTN btn_func [NUM_BTNS - NUM_QUBITS] = 1
        logical 4
```

6.8.1 Detailed Description

Contains all the functions for reading buttons and writing to LEDs.

Authors

J Scott, O Thomas

Date

Nov 2018

6.8.2 Function Documentation

The max value for isr_counter.

Timer 6 and 7 for cycling superposition states.

Interrupt service routine for timer 4

Interrupt service routines are automatically called by the microcontroller when an event occurs. In this case, _ T5Interrupt is called when the 32 bit timer formed from T4 and T5 reaches its preset period. The silly name and sill attributes are so that the compiler can correctly map the function in the microcontroller memory. More details of interrupts and interrupt vectors can be found in the compiler manual and the dsPIC33E datasheet.

The job of this routine is to control the modulated brightnesses of the RBG LEDs. This routine is set to be called periodically with a very long period on the time scale of microcontroller operations, but very fast in comparison to what the eye can see. For example, once every 100us. Loop over all the LEDs (the index i).

Decide whether R, G or B should be turned off

Write the display buffer data to the display drivers It's important this line goes here rather than after the the final update_display_buffer below. Otherwise you get a flicker due to the LEDs all coming on at the start of this loop

Reset the counter

Turn on all the LEDs back on

Write a row to the leds

6.8.2.2 add_to_cycle()

Add an item to the list of states to cycle.

Add an element to the states to be cycled.

Parameters

leds	An array of LED indices
colors	Corresponding RGB values for each LED
size	The size of both the above arrays

This function is used to add a set of LED states (RGB values) into the list of states being cycled.

Repeatedly calling this function adds a new state to the end of the list of displayed states. LED states are shown in the order this function is called.

The implementation uses the linked list type cycle_node. Each call of this function adds a new element to the end of cycle node Add the new colors to top of array

6.8.2.3 flash_all()

```
void flash_all (
          int number )
```

Flash all the LEDs a number of times.

Parameters

number

6.8.2.4 flash_led()

```
void flash_led (
          int color,
          int number )
```

Flash LED a number of times.

Flash one LED a number of times.

6.8.2.5 led_color_int()

Takes led number & RGB -> returns integer for sending via SPI to set the LED.

Parameters

device	input LED number to change
R	red value between 0 & 1
G	green value between 0 & 1
В	blue value between 0 & 1

Returns

Returns int to be sent to LED Driver

convention RGB -> 000

Each LED takes 3 lines, assumes there are no gaps between LED channels "device" goes between 0 to 2ⁿ -1

```
6.8.2.6 led_cycle_test()
```

```
int led_cycle_test (
          void )
```

Loop to cycle through LEDs 0 - 15.

Todo This won't work now: write_display_driver(counter);

6.8.2.7 read_btn()

```
int read_btn (
    int btn )
```

Read the state of a push button.

Parameters

btn

Note

How well do you know C

6.8.2.8 read_external_buttons()

Read external buttons.

Update the buttons array (see declaration above)

The external buttons are interfaced to the microcontroller via a shift register. Data is shifted in a byte at a time using the SPI 3 module. The sequence to read the buttons is as follows:

1) Momentarily bring SH low to latch button data into the shift registers 2) Bring CLK_INH low to enable the clock input on the shift register 3) Start the SPI 3 clock and read data in via the SDI 3 line

The control lines SH and CLK_INH are on port D

Todo read buttons

SH pin

Todo How long should this be?

Todo button remappings...

6.8.2.9 reset_cycle()

```
int reset_cycle (
     void )
```

Reset the LED display cycle _*.

Reset the display cycle. Called before adding anything.

Todo do it

6.8.2.10 set_external_led()

Updates color properties of global led array.

Parameters

led_index	
R	red value between 0 & 1
G	green value between 0 & 1
В	blue value between 0 & 1

Returns

0 if successful, -1 otherwise

Use the function to set the RGB level of an LED. The LED is chosen using the

Parameters

led_index.	The
R	

6.8.2.11 set_led()

```
int set_led (
                int color,
                int state )
```

Turn a particular LED on or off.

Parameters

color	
state	

6.8.2.12 set_strobe()

```
void set_strobe (
                int color,
                int state )
```

Set an LED strobing.

Parameters

color	
state	

6.8.2.13 setup_external_leds()

Set external variable RGB LEDs.

Initialise LED lines

Initialise parameters to zero

Initialise display buffer to zero

Set flashing period

Turn timer 6 on

Todo CURRENTLY CYCLING IS OFF

```
6.8.2.14 setup_io()
```

```
int setup_io (
     void )
```

Set up LEDs and buttons on port D.

< Set port c digital for spi3

Set the OE pin high

Set OE(ED2) pin

Set the SH pin high

Set SH pin

set CLK_INH high while buttons are pressed

6.8.2.15 TLC591x_mode_switch()

```
int TLC591x_mode_switch (
          int mode )
```

Switch between normal and special mode.

The mode switch for the TLC591x chip is a bit tricky because it involves synchronising the control lines LE(ED1) and OE(ED2) on Port D with the SPI 1 clock. To initiate a mode switch, OE(ED2) must be brought low for one clock cycle, and then the value of LE(ED1) two clock cycles later determines the new mode. See the diagrams on page 19 of the datasheet

So long as the timing is not strict, we can probably implement the mode switch by starting a non-blocking transfer of 1 byte to the device (which starts the SPI 1 clock), followed by clearing OE(ED2) momentarily and then setting the value of LE(ED1) as required. So long as those two things happen before the SPI 1 clock finishes the procedure will probably work. (The reason is the lack of max timing parameters on page 9 for the setup and hold time for ED1 and ED2, which can therefore presumably be longer than one clock cycle.)

Parameters

mode

Todo mode switcher for LED Driver

6.8.2.16 toggle_strobe()

```
void toggle_strobe (
    int color )
```

Toggle LED strobe.

Parameters

color

6.8.2.17 update_display_buffer()

```
int update_display_buffer (
    int n,
    bool R,
    bool G,
    bool B)
```

Parameters

index	LED number to modify
R	Intended value of the R led
G	Intended value of the G led
В	Intended value of the B led

Returns

0 if successful

Could this get any worse!

This function is supposed to make the display writing process more efficient. It updates a global display buffer which is written periodically to the led display drivers. Instead of the display driver function re-reading the desired state of all the LED lines every time it is called, this function can be used to update only the lines that have changed.

There are quite a few potential bugs in here, mainly array out of bounds if the DISPLAY_CHIP_NUM is not set correctly or the LED RGB lines are wrong. (Or if there are just bugs.) Set or clear the red LED of the nth LED

Set or clear the red LED of the nth LED

Set or clear the red LED of the nth LED

6.8.2.18 write_display_driver()

Turn on an LED via the external display driver.

Send a byte to the display driver.

On power on, the chip (TLC591x) is in normal mode which means that the clocked bytes sent to the chip set which LEDs are on and which are off (as opposed to setting the current of the LEDs)

To write to the device, use the SPI module to write a byte to the SDI 1 pin on the chip. Then momentarily set the LE(ED1) pin to latch the data onto the output register. Finally, bring the OE(ED2) pin low to enable the current sinking to turn on the LEDs. See the timing diagram on page 17 of the datasheet for details.

LE(ED1) and OE(ED2) will be on Port D Set LE(ED1) pin

Todo How long should this be?

6.8.3 Variable Documentation

6.8.3.1 btn_func

```
btn_func = 1
```

logical 4

logical 5

Bug this.

6.8.3.2 btn_qubit

```
btn_qubit = 1
```

button mapping 1st byte 00000100 btn A26-28 -> logical 0 00000010 btn A7-9 -> logical 6 00000001 btn A4-6 -> logical 7 00001000 btn A1-3 -> logical 8

logical 3

logical 2

logical 1

2nd byte 10000000 btn A23-25 -> logical 1 00000010 btn A20-22 -> logical 2 00000100 btn A17-19 -> logical 3 00000001 btn A13-15 -> logical 4 00001000 btn A10-12 -> logical 5

6.8.3.3 buttons

```
int buttons[BTN_CHIP_NUM]
```

Contains the button states.

Each entry in the array is either 1 if the button is pressed or 0 if not. The array is accessed globally using 'extern buttons;' in a *.c file. Read buttons array us updated by calling read external buttons

6.8.3.4 chip btn func [4] chip = 0 logical 0 logical 8 logical 7 logical 6 logical 5 logical 4 logical 3 logical 2 logical 1

6.8.3.5 isr_counter

```
unsigned _Fract isr_counter = 0
```

Counter for the interrupt service routine _T5Interrupt.

These variables are for keeping track of the interrupt based LED pulsing. The type is _Fract because it is easier to directly compare two _Fracts than attempt multiplication of integers and _Fracts (which isn't supported) The limit is not 1 because _Fract types do not go up to 1.

It's probably a good idea to make sure the isr_res counter doesn't overflow (by ensuring that isr_res + isr_limit does not exceed 0.999..., the max value of unsigned _Fract).

6.8.3.6 led_global

```
LED_GLOBAL led_global = {0}
```

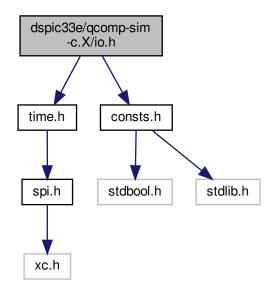
Parameters

led alobal	Global LED strobing state parameter
.ou_g.ou	chesa: === chesang chare parameter

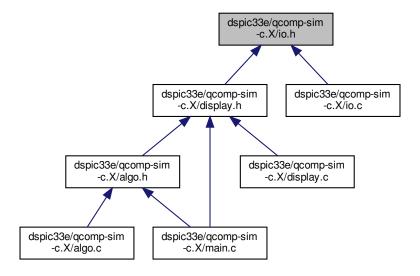
6.9 dspic33e/qcomp-sim-c.X/io.h File Reference

Description: Header file for input output functions.

```
#include "time.h"
#include "consts.h"
Include dependency graph for io.h:
```



This graph shows which files directly or indirectly include this file:



Data Structures

struct BTN

pin mappings

struct LED_GLOBAL

Global LED strobing state parameter.

struct LED

Each LED has the following type.

struct RGB

A type for holding red, green, blue values.

• struct cycle_node

The basis for a linked list of states to cycle.

Macros

• #define red 0

Locations of LEDs and buttons on Port D.

- · #define amber 1
- #define green 2
- #define **sw1** 6
- #define sw2 7
- #define sw3 13
- #define off 0
- #define on 1
- #define LE 3

Control for TLC591x chip on Port D.

- #define OE 4
- #define SH 5

COntrol lines for SNx4HC165 chip.

• #define CLK_INH 8

Typedefs

• typedef struct cycle_node cycle_node_t

The basis for a linked list of states to cycle.

Functions

• int setup_io (void)

Set up LEDs and buttons on port D.

void setup_external_leds (void)

Set external variable RGB LEDs.

• int set led (int color, int state)

Turn a particular LED on or off.

• int read_btn (int btn)

Read the state of a push button.

· void leds off (void)

Turn all the LEDs off.

• void flash_led (int color, int number)

Flash one LED a number of times.

void flash_all (int number)

Flash all the LEDs a number of times.

· void set strobe (int color, int state)

Set an LED strobing.

• void toggle_strobe (int color)

Toggle LED strobe.

- int update_display_buffer (int led_index, bool R, bool G, bool B)
- int write_display_driver (void)

Send a byte to the display driver.

• int set_external_led (int led_index, unsigned _Fract R, unsigned _Fract B)

Updates color properties of global led array.

• int led_color_int (int device, int R, int G, int B)

Takes led number & RGB -> returns integer for sending via SPI to set the LED.

int led_cycle_test (void)

Loop to cycle through LEDs 0 - 15.

int read_external_buttons (void)

Update the buttons array (see declaration above)

int add_to_cycle (RGB colors[], int size)

Add an element to the states to be cycled.

• int reset cycle (void)

Reset the display cycle. Called before adding anything.

6.9.1 Detailed Description

Description: Header file for input output functions.

Include it at the top of any C source file which uses buttons and LEDs. It also defines various constants representing the positions of the buttons and LEDs on port D.

Authors

J Scott, O Thomas

Date

Nov 2018

6.9.2 Function Documentation

```
6.9.2.1 add_to_cycle()
```

Add an element to the states to be cycled.

Add an element to the states to be cycled.

Parameters

leds	An array of LED indices
colors	Corresponding RGB values for each LED
size	The size of both the above arrays

This function is used to add a set of LED states (RGB values) into the list of states being cycled.

Repeatedly calling this function adds a new state to the end of the list of displayed states. LED states are shown in the order this function is called.

The implementation uses the linked list type cycle_node. Each call of this function adds a new element to the end of cycle node Add the new colors to top of array

6.9.2.2 flash_all()

```
void flash_all (
          int number )
```

Flash all the LEDs a number of times.

Parameters

number

6.9.2.3 flash_led()

Flash one LED a number of times.

Parameters



Flash one LED a number of times.

6.9.2.4 led_color_int()

int
$$G$$
, int B)

Takes led number & RGB -> returns integer for sending via SPI to set the LED.

Parameters

device	input LED number to change
R	red value between 0 & 1
G	green value between 0 & 1
В	blue value between 0 & 1

Returns

Returns int to be sent to LED Driver

convention RGB -> 000

Each LED takes 3 lines, assumes there are no gaps between LED channels "device" goes between 0 to 2^n -1

6.9.2.5 led_cycle_test()

Loop to cycle through LEDs 0 - 15.

Todo This won't work now: write_display_driver(counter);

6.9.2.6 read_btn()

```
int read_btn ( int \ btn \ )
```

Read the state of a push button.

Parameters

```
btn
```

Note

How well do you know C

6.9.2.7 read_external_buttons()

Update the buttons array (see declaration above)

Update the buttons array (see declaration above)

The external buttons are interfaced to the microcontroller via a shift register. Data is shifted in a byte at a time using the SPI 3 module. The sequence to read the buttons is as follows:

1) Momentarily bring SH low to latch button data into the shift registers 2) Bring CLK_INH low to enable the clock input on the shift register 3) Start the SPI 3 clock and read data in via the SDI 3 line

The control lines SH and CLK_INH are on port D

Todo read buttons

SH pin

Todo How long should this be?

Todo button remappings...

6.9.2.8 reset_cycle()

```
int reset_cycle (
     void )
```

Reset the display cycle. Called before adding anything.

Reset the display cycle. Called before adding anything.

Todo do it

6.9.2.9 set_external_led()

Updates color properties of global led array.

Parameters

led_index	
R	red value between 0 & 1
Generated by Doxygreen value between 0 & 1	
В	blue value between 0 & 1

Returns

0 if successful, -1 otherwise

Use the function to set the RGB level of an LED. The LED is chosen using the

Parameters

led_index.	The
R	

6.9.2.10 set_led()

```
int set_led (
                int color,
                int state )
```

Turn a particular LED on or off.

Parameters

color	
state	

6.9.2.11 set_strobe()

Set an LED strobing.

Parameters

color	
state	

6.9.2.12 setup_external_leds()

Set external variable RGB LEDs.

```
6.9 dspic33e/qcomp-sim-c.X/io.h File Reference
Initialise LED lines
Initialise parameters to zero
Initialise display buffer to zero
Set flashing period
Turn timer 6 on
Todo CURRENTLY CYCLING IS OFF
6.9.2.13 setup_io()
int setup_io (
              void )
Set up LEDs and buttons on port D.
< Set port c digital for spi3
Set the OE pin high
Set OE(ED2) pin
Set the SH pin high
Set SH pin
set CLK_INH high while buttons are pressed
6.9.2.14 toggle_strobe()
void toggle_strobe (
             int color )
Toggle LED strobe.
Parameters
 color
```

Generated by Doxygen

6.9.2.15 update_display_buffer()

int update_display_buffer (int n_{i}

```
bool R,
bool G,
bool B )
```

Parameters

led_index	LED number to modify
R	Intended value of the R led
G	Intended value of the G led
В	Intended value of the B led

Returns

0 if successful

Parameters

index	LED number to modify
R	Intended value of the R led
G	Intended value of the G led
В	Intended value of the B led

Returns

0 if successful

Could this get any worse!

This function is supposed to make the display writing process more efficient. It updates a global display buffer which is written periodically to the led display drivers. Instead of the display driver function re-reading the desired state of all the LED lines every time it is called, this function can be used to update only the lines that have changed.

There are quite a few potential bugs in here, mainly array out of bounds if the DISPLAY_CHIP_NUM is not set correctly or the LED RGB lines are wrong. (Or if there are just bugs.) Set or clear the red LED of the nth LED

Set or clear the red LED of the nth LED

Set or clear the red LED of the nth LED

6.9.2.16 write_display_driver()

Send a byte to the display driver.

Don't use this function to write to LEDs – use the set_external_led function

Send a byte to the display driver.

On power on, the chip (TLC591x) is in normal mode which means that the clocked bytes sent to the chip set which LEDs are on and which are off (as opposed to setting the current of the LEDs)

To write to the device, use the SPI module to write a byte to the SDI 1 pin on the chip. Then momentarily set the LE(ED1) pin to latch the data onto the output register. Finally, bring the OE(ED2) pin low to enable the current sinking to turn on the LEDs. See the timing diagram on page 17 of the datasheet for details.

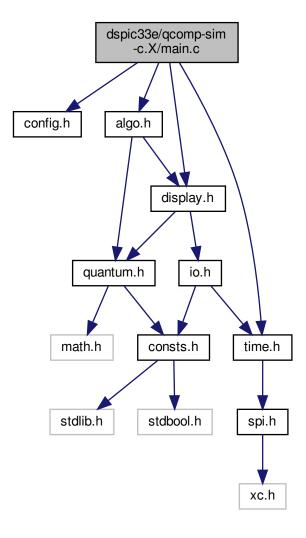
LE(ED1) and OE(ED2) will be on Port D Set LE(ED1) pin

Todo How long should this be?

6.10 dspic33e/qcomp-sim-c.X/main.c File Reference

The main function.

```
#include "config.h"
#include "time.h"
#include "algo.h"
#include "display.h"
Include dependency graph for main.c:
```



Functions

• int main (void)

6.10.1 Detailed Description

The main function.

Authors

J Scott, O Thomas

Date

Nov 2018

Contains an example of fixed precision 2x2 matrix multiplication for applying operations to a single qubit. The only operations included are H, X and Z so that everything is real (this can be extended later).

All the functions have now been moved into separate files. io.h and io.c contain functions for reading and controlling the buttons and LEDs, and quantum.h/quantum.c contain the matrix arithmetic for simulating one qubit.

Compile command: make (on linux). But if you want to program the micro- controller too or if you're using windows you're better of downloading and installing MPLAB-X https://www.microchip.ecom/mplab/mplab-x-ide.

Note

You also need the microchip xc16 compilers which are available from $https://www.microchip. \leftarrow com/mplab/compilers$

6.10.2 Function Documentation

```
6.10.2.1 main()
```

```
int main (
     void )
```

button reading test.

<

Note

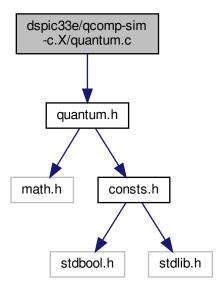
Really important!

6.11 dspic33e/qcomp-sim-c.X/quantum.c File Reference

Description: Contains matrix and vector arithmetic for simulating one qubit.

#include "quantum.h"

Include dependency graph for quantum.c:



Functions

• int pow2 (int k)

A simple function to compute integer powers of 2.

• int sign (Complex a)

returns phase quadrant

- void cadd (const Complex a, const Complex b, Complex result)
- void cmul (const Complex a, const Complex b, Complex result)
- Q15 absolute (Complex x)

abs function

• Q15 square_magnitude (Complex x)

Compute the magnitude squared of a complex number.

void zero_state (Complex state[])

Initialise state to the vacuum (zero apart from the first position) Specify the dimension – of the matrix, i.e.

void mat_mul_old (const Complex M[2][2], Complex V[], int i, int j)

This is an old version of the mat_mul function.

• void mat_mul (const Complex M[2][2], Complex V[], int i, int j)

This version uses inlined cadd and cmul.

• void single_qubit_op (const Complex op[2][2], int k, Complex state[])

apply operator

• void controlled_qubit_op_new (const Complex op[2][2], int ctrl, int targ, Complex state[])

selective 2 qubit op function

void controlled_qubit_op (const Complex op[2][2], int ctrl, int targ, Complex state[])

Old controlled qubit operations.

6.11.1 Detailed Description

Description: Contains matrix and vector arithmetic for simulating one qubit.

Authors

J Scott, O Thomas

Date

Nov 2018

Todo split into a complex math and operator files

6.11.2 Function Documentation

6.11.2.1 absolute()

```
Q15 absolute ( {\tt Complex}\ x\ )
```

abs function

Parameters

x A complex number to find the absolute value of

Returns

The absolute value

Todo Check that the complex part is small

6.11.2.2 controlled_qubit_op()

```
void controlled_qubit_op (
          const Complex op[2][2],
          int ctrl,
          int targ,
          Complex state[])
```

Old controlled qubit operations.

apply controlled 2x2 op ROOT loop: starts at 0, increases in steps of 1

STEP loop: starts at 0, increases in steps of $2^{\land}(k+1)$

First index is ZERO, second index is ONE

Note

for 2 qubit case check if the index in the ctrl qubit is a 1 then apply the 2x2 unitary else do nothing sorry. this checks for the first element of the state vector i.e. the target qubits $|0\rangle$ and checks that the state vector element is one which the control qubit has a $|1\rangle$ state $|1\rangle$ (root + step)

The second element of the state vector to take is then the first $+2^{\wedge}$ (target qubit number). This also needs to be checked that the control qubit is in the $|1\rangle$.

Todo This expression can probably be simplified or broken over lines. The condition for the if statement is that root+step and root + step + root_max contain 1 in the ctrl-th bit.

6.11.2.3 controlled_qubit_op_new()

selective 2 qubit op function

checks that the control qubit is |1> then does 2x2 unitary on remaining state vector elements

This routine implements a controlled unitary gate. Controlled unitaries can be expressed as single qubit unitaries that are conditionally applied if the control qubit state (ctrl) is 1. Otherwise no operation is performed.

The following example is for the three qubit case. Suppose the following operation is performed.

```
* 00 01 10 11

* 00 (1 0 0 0 )

* 01 (0 1 0 0 0)

* 10 (0 0 u00 u01)

* 11 (0 0 u10 u11)
```

The first qubit is the control (ctrl) and the second qubit is the target (targ). If the control is 0 the identity operation is performed. If the control qubit is 1, then a unitary U (the second block above) is performed.

For three qubits, the state vector is shown below:

```
index
       binary amplitude
         0 0 0
                    a0
  1
         0 0 1
                    a1
        0 1 0
                   a2
         0 1 1
  3
                    a3
  4
         1 0 0
                    a4
         1 0 1
                   a5
         1 1 0
  6
                    a 6
  7
         1 1 1
                    a7
Qubit: 2 1 0
```

Suppose the controlled unitary is to be performed between qubits 0 and 1, with the control qubit on 0. Suppose the controlled gate is a CNOT, so that the 2x2 matrices involved are I and X. X and I are performed on the following (vertical) pairs of indices

i: (0+0) (0+4) (1+0) (1+4) (ctrl = 0, targ = 1) j: (0+2) (0+6) (1+2) (1+6)

If the control and target are reversed (ctrl on 1), then the pairings of the indices are

I

i: (0+0) (0+4) (2+0) (2+4) (ctrl = 1, targ = 0) j: (0+1) (0+5) (2+1) (2+5)

For control and target qubits on 0 and 2 the indices are

[

i: (0+0) (0+2) (1+0) (1+2) (ctrl = 0, targ = 2) j: (0+4) (0+6) (1+4) (1+6)

If the control and target are reversed (ctrl on 2), then the pairings of the indices are

I

i: (0+0) (0+2) (4+0) (4+4) (ctrl = 2, targ = 0) j: (0+1) (0+3) (4+1) (4+5)

Finally, if the control and target are 1 and 2, then

i: (0+0) (0+1) (2+0) (2+1) (ctrl = 1, targ = 2) j: (0+4) (0+5) (2+4) (2+5)

If the control and target are reversed (ctrl on 2), then the pairings of the indices are

i:
$$(0+0)(0+1)(4+0)(4+1)$$
 (ctrl = 2, targ = 1) j: $(0+2)(0+3)(4+2)(4+3)$

The pattern in the general case is as follows. Firstly, similarly to the single qubit case, the index required can be expressed as the sum of a root and another contribution. In this case, the root depends only on the ctrl qubit number:

root =
$$x * 2^{\land} ctrl$$

where x is the state of the ctrl qubit (either 1 or 0). This will determine whether I or (in the case of CNOT) X is applied. That the root only depends on the ctrl qubit number is due to the interpretation of root – it is the base index of all the ctrl states of a particular value. For example, whatever the qubit number, the starting index of the zero ctrl state is always zero. Then, the first occurance of a 1 in the ctrl qubit depends on the ctrl qubit number, and is just a power of 2 into the state vector.

The other contributions to the index depend on the the target qubit number (targ). The offset between indices of the same operation (either I or X) are separated by

$$sep = 2^{\wedge} targ$$

The logic for this is similar to the case for ctrl: the way to get from a 0 in the target to a 1 in the target is to add 2^{targ} to the index in the state vector.

Finally, there is the offset due to moving from the 0 to 1 state within a particular operation (I or X). This depends on both the values of the ctrl and targ qubit numbers as follows:

offset =
$$2^{\wedge}$$
(N-ctrl-targ) * v

where N is the number of _qubits (3 in the above case). Here, y is either zero or one, and enumerates the operations that must be performed In other words, the index is given by the following expression

```
i: root + offset = x*2^{\text{ctrl}} + y*2^{\text{(N-ctrl-targ)}} j: root + sep + offset = x*2^{\text{ctrl}} + 2^{\text{targ}} + y*2^{\text{(N-ctrl-targ)}}
```

where x is the value of the ctrl qubit (do X when x is 1, I when x is zero) and y ranges from 0 to $2^{(N-1)}$ where N is the number of qubits. Since it is only necessary to do the non-trivial unitary, x is always 1.

Todo Replace pow2 with left rotations

Todo The problem is the formula for the increment

6.11.2.4 mat_mul()

This version uses inlined cadd and cmul.

2x2 complex matrix multiplication

Parameters

М	A 2x2 complex matrix
V	A Nx1 complex vector
i	The first index to pick from the vector V
j	The second index to pick from the vector V

Todo Is static enough? Or should we declare outside the function?

Todo Should we use for loops? Or is it better not to..?

This is necessary because the previous computations use V

6.11.2.5 mat_mul_old()

This is an old version of the mat_mul function.

Parameters

М	A 2x2 complex matrix
V	A Nx1 complex vector
i	The first index to pick from the vector V
j	The second index to pick from the vector V

The function uses cadd and cmul

Todo Should these be outside the function?

6.11.2.6 pow2()

```
int pow2 (  \qquad \qquad \text{int $k$ )} \\
```

A simple function to compute integer powers of 2.

Parameters

```
k The exponent of 2 to compute
```

Returns

 $2^{\wedge}k$

Multiply by 2

6.11.2.7 sign()

returns phase quadrant

```
/// Im
// 1 | 0
// 1 | Re
// 2 | 3
// |
```

if real negative and im neg return -1 if real negative and im pos return -0.5

else if real pos and im negative return -0.5

else if both pos return 0

6.11.2.8 single_qubit_op()

apply operator

Parameters

state	state vector containing amplitudes
qubit	qubit number to apply 2x2 matrix to
N	total number of qubits in the state
ор	2x2 operator to be applied

This routine applies a single qubit gate to the state vector

Parameters

state.	Consider the three qubit case, with amplitudes shown in the table		
	below:		

*	index	binary	amplitude
*			
*	0	0 0 0	a0
*	1	0 0 1	a1
*	2	0 1 0	a2
*	3	0 1 1	a3
*	4	1 0 0	a4
*	5	1 0 1	a5
*	6	1 1 0	a6
*	7	1 1 1	a7
*			
*	Qubit:	2 1 0	
at.			

If a single qubit operation is applied to qubit 2, then the 2x2 matrix must be applied to all pairs of (0,1) in the first column, with the numbers in the other columns fixed. In other words, the following indices are paired:

```
(0+0) (1+0) (2+0) (3+0)
(4+0) (5+0) (6+0) (7+0)
```

where the top line corresponds to the ZERO amplitude and the bottom row corresponds to the ONE amplitude.

Similarly, for qubit 1 the pairings are:

```
(0+0) (0+4) (1+0) (1+4) (2+0) (2+4) (3+0) (3+4)
```

And for qubit 0 the pairings are:

```
(0+0) (0+2) (0+4) (0+6)
(1+0) (1+2) (1+4) (1+6)
```

These numbers are exactly the same as the previous function, which means the same nested loops can be used to perform operation. Now the index

```
root + step
```

refers to the ZERO amplitude (the first element in the column vector to be multiplied by the 2x2 matrix), and the index Complex state[], int N root + 2^k k + step

corresponds to the ONE entry. ROOT loop: starts at 0, increases in steps of 1

STEP loop: starts at 0, increases in steps of $2^{(k+1)}$

First index is ZERO, second index is ONE

Todo Should we inline mat mul here?

6.11.2.9 square_magnitude()

```
Q15 square_magnitude ( Complex x)
```

Compute the magnitude squared of a complex number.

Parameters

x The input complex number x

Returns

The value of $|x|^2$

Todo Maybe we should inline this

```
6.11.2.10 zero_state()
```

Initialise state to the vacuum (zero apart from the first position) Specify the dimension – of the matrix, i.e.

2[^](number of qubits)

Note

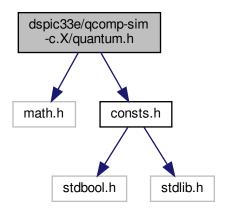
oh the clarity!

6.12 dspic33e/qcomp-sim-c.X/quantum.h File Reference

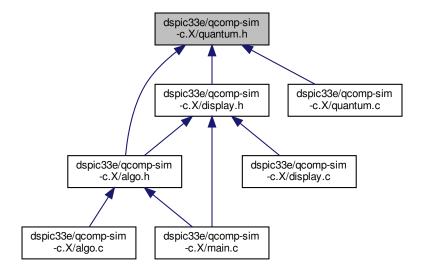
Description: Header file containing all the matrix arithmetic for simulating a single qubit.

```
#include <math.h>
#include "consts.h"
```

Include dependency graph for quantum.h:



This graph shows which files directly or indirectly include this file:



Enumerations

enum State { ZERO, ONE, PLUS, MINUS, iPLUS, iMINUS }

Basis states.

Functions

void zero_state (Complex state[])

Initialise state to the vacuum (zero apart from the first position) Specify the dimension – of the matrix, i.e.

• int sign (Complex a)

returns phase quadrant

void mat_mul (const Complex M[2][2], Complex V[], int i, int j)

2x2 complex matrix multiplication

• void single_qubit_op (const Complex op[2][2], int qubit, Complex state[])

apply operator

• void controlled_qubit_op (const Complex op[2][2], int ctrl, int targ, Complex state[])

apply controlled 2x2 op

• Q15 absolute (Complex x)

abs function

• int pow2 (int k)

A simple function to compute integer powers of 2.

• Q15 square_magnitude (Complex x)

Compute the magnitude squared of a complex number.

6.12.1 Detailed Description

Description: Header file containing all the matrix arithmetic for simulating a single qubit.

Authors

J Scott, O Thomas

Date

Nov 2018

6.12.2 Function Documentation

```
6.12.2.1 absolute()
```

```
Q15 absolute ( {\tt Complex}\ x\ )
```

abs function

Parameters

x A complex number to find the absolute value of

Returns

The absolute value

Todo Check that the complex part is small

6.12.2.2 controlled_qubit_op()

apply controlled 2x2 op

Parameters

ор	single qubit unitary 2x2	
ctrl	control qubit number (0,1,,n-1)	
targ	target qubit number (0,1,,n-1)	
state	complex state vector	

apply controlled 2x2 op ROOT loop: starts at 0, increases in steps of 1

STEP loop: starts at 0, increases in steps of $2^{(k+1)}$

First index is ZERO, second index is ONE

Note

for 2 qubit case check if the index in the ctrl qubit is a 1 then apply the 2x2 unitary else do nothing sorry. this checks for the first element of the state vector i.e. the target qubits $|0\rangle$ and checks that the state vector element is one which the control qubit has a $|1\rangle$ state -> (root + step)

The second element of the state vector to take is then the first $+2^{\wedge}$ (target qubit number). This also needs to be checked that the control qubit is in the $|1\rangle$.

Todo This expression can probably be simplified or broken over lines. The condition for the if statement is that root+step and root + step + root max contain 1 in the ctrl-th bit.

6.12.2.3 mat_mul()

2x2 complex matrix multiplication

Parameters

М	complex matrix
V	complex vector
i	integer first element of state vector
j	integer second element of state vector

Todo Because of the way the array types work (you can't pass a multidimensional array of unknown size) we will also need a function for 4x4 matrix multiplication.

2x2 complex matrix multiplication

Parameters

М	A 2x2 complex matrix
V	A Nx1 complex vector
i	The first index to pick from the vector V
j	The second index to pick from the vector V

Todo Is static enough? Or should we declare outside the function?

Todo Should we use for loops? Or is it better not to ..?

This is necessary because the previous computations use $\ensuremath{\mathsf{V}}$

A simple function to compute integer powers of 2.

Parameters

```
k The exponent of 2 to compute
```

Returns

 2^{k}

Multiply by 2

```
6.12.2.5 sign()
```

```
int sign ( Complex a )
```

returns phase quadrant

if real negative and im neg return -1 if real negative and im pos return -0.5 $\,$

else if real pos and im negative return -0.5

else if both pos return 0

```
6.12.2.6 single_qubit_op()
```

apply operator

Parameters

state	state vector containing amplitudes
qubit	qubit number to apply 2x2 matrix to
ор	2x2 operator to be applied
state	state vector containing amplitudes
qubit	qubit number to apply 2x2 matrix to
N	total number of qubits in the state
ор	2x2 operator to be applied

This routine applies a single qubit gate to the state vector

Parameters

state.	Consider the three qubit case, with amplitudes shown in the table
	below:

*	index	binary	amplitude
*			
*	0	0 0 0	a0
*	1	0 0 1	a1
*	2	0 1 0	a2
*	3	0 1 1	a3
*	4	1 0 0	a4
*	5	1 0 1	a5
*	6	1 1 0	a6
*	7	1 1 1	a7
*			
*	Qubit:	2 1 0	

If a single qubit operation is applied to qubit 2, then the 2x2 matrix must be applied to all pairs of (0,1) in the first column, with the numbers in the other columns fixed. In other words, the following indices are paired:

```
(0+0) (1+0) (2+0) (3+0)
(4+0) (5+0) (6+0) (7+0)
```

where the top line corresponds to the ZERO amplitude and the bottom row corresponds to the ONE amplitude. Similarly, for qubit 1 the pairings are:

```
(0+0) (0+4) (1+0) (1+4) (2+0) (2+4) (3+0) (3+4)
```

And for qubit 0 the pairings are:

```
(0+0) (0+2) (0+4) (0+6) (1+0) (1+2) (1+4) (1+6)
```

These numbers are exactly the same as the previous function, which means the same nested loops can be used to perform operation. Now the index

```
root + step
```

refers to the ZERO amplitude (the first element in the column vector to be multiplied by the 2x2 matrix), and the index Complex state[], int N root + 2^k k + step

corresponds to the ONE entry. ROOT loop: starts at 0, increases in steps of 1

STEP loop: starts at 0, increases in steps of $2^{(k+1)}$

First index is ZERO, second index is ONE

Todo Should we inline mat_mul here?

6.12.2.7 square_magnitude()

```
Q15 square_magnitude ( {\tt Complex}\ x\ )
```

Compute the magnitude squared of a complex number.

Parameters

x The input complex number x

Returns

The value of $|x|^2$

Todo Maybe we should inline this

Parameters

x The input complex number x

Returns

The value of $|x|^{\wedge}2$

Todo Maybe we should inline this

6.12.2.8 zero_state()

Initialise state to the vacuum (zero apart from the first position) Specify the dimension – of the matrix, i.e.

2[^](number of qubits)

Parameters

state complex state vector

2[^](number of qubits)

Note

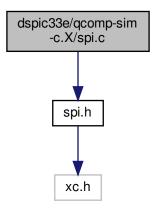
oh the clarity!

6.13 dspic33e/qcomp-sim-c.X/spi.c File Reference

Description: Functions for communicating with serial devices.

#include "spi.h"

Include dependency graph for spi.c:



Functions

• int setup_spi (void)

Set up serial peripheral interface.

• int send_byte_spi_1 (int data)

Send a byte to the SPI1 peripheral.

• int read_byte_spi_3 ()

Recieve a byte from the SPI3 peripheral.

6.13.1 Detailed Description

Description: Functions for communicating with serial devices.

Authors

J Scott, O Thomas

Date

Nov 2018

6.13.2 Function Documentation

```
6.13.2.1 send_byte_spi_1()
```

Send a byte to the SPI1 peripheral.

Parameters

```
data
      byte to be sent to SPI1
```

```
6.13.2.2 setup_spi()
int setup_spi (
              void )
Set up serial peripheral interface.
Pin mappings — Pin mappings and codes —
J10:41 = J1:91 = uC:70 = RPI74 (PPS code: 0100 1010)
J10:44 = J1:93 = uC:9 = RPI52 (PPS code: 0011 0100)
J10:47 = J1:101 = uC:34 = RPI42 (PPS code: 0010 1010)
J10:43 = J1:95 = uC:72 = RP64 (PPS reg: RPOR0_L; code: 0100 0000)
J10:46 = J1:97 = uC:69 = RPI73 (PPS code: 0100 1001)
J10:7 = J1:13 = uC:3 = RP85 (PPS reg: RPOR6 L; code: 0101 0101)
J10:5 = J1:7 = uC:5 = RP87 (PPS reg: RPOR6 H)
J10:55 = J1:117 = uC:10 = RP118 (PPS reg: RPOR13 H)
— Pin mappings for SPI 1 module —
SPI 1 Clock Out (SCK1) PPS code: 000110 (0x06)
SPI 1 Data Out (SDO1) PPS code: 000101 (0x05)
SPI 1 Slave Select PPS code: 000111
— Pin mappings for SPI 3 module —
SPI 3 Clock Out (SCK3) PPS code: 100000 (0x20)
SPI 3 Data Out (SDO3) PPS code: 011111 (0x1F)
SPI 3 Slave Select PPS code: 100001
Configure the SPI 1 pins
< Put SCK1 on J10:43
< Put SDO1 on J10:55
The clock pin also needs to be configured as an input
< Set SCK1 on J10:43 as input
Configure the SPI 3 output pins
< Put SCK3 on J10:7
< Put SDO3 on J10:5
< Put SDI3 on J10:44
< Set SCK3 on J10:7 as input
    @note
SPI 1 clock configuration
```

SCK1 = F CY / (Primary Prescaler * Secondary Prescaler)

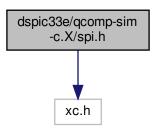
Assuming that F_CY = 50MHz, and the prescalers are 4 and 1, the SPI clock frequency will be 12.5MHz.

6.14 dspic33e/qcomp-sim-c.X/spi.h File Reference

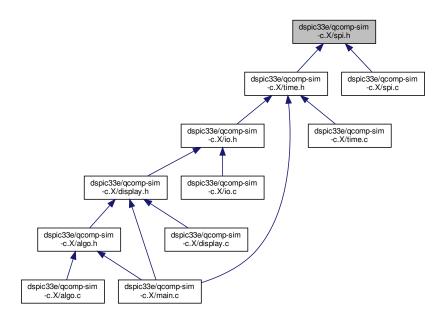
Description: SPI communication functions.

#include "xc.h"

Include dependency graph for spi.h:



This graph shows which files directly or indirectly include this file:



Functions

• int setup_spi (void)

Set up serial peripheral interface.

• int send_byte_spi_1 (int data)

Send a byte to the SPI1 peripheral.

• int read_byte_spi_3 ()

Recieve a byte from the SPI3 peripheral.

6.14.1 Detailed Description

Description: SPI communication functions.

Authors

J Scott, O Thomas

Date

Nov 2018

6.14.2 Function Documentation

```
6.14.2.1 send_byte_spi_1()
```

Send a byte to the SPI1 peripheral.

Parameters

```
data byte to be sent to SPI1
```

6.14.2.2 setup_spi()

```
int setup_spi (
     void )
```

Set up serial peripheral interface.

```
Pin mappings — Pin mappings and codes —

J10:41 = J1:91 = uC:70 = RPI74 (PPS code: 0100 1010)

J10:44 = J1:93 = uC:9 = RPI52 (PPS code: 0011 0100)

J10:47 = J1:101 = uC:34 = RPI42 (PPS code: 0010 1010)

J10:43 = J1:95 = uC:72 = RP64 (PPS reg: RPOR0_L; code: 0100 0000)

J10:46 = J1:97 = uC:69 = RPI73 (PPS code: 0100 1001)

J10:7 = J1:13 = uC:3 = RP85 (PPS reg: RPOR6_L; code: 0101 0101)

J10:5 = J1:7 = uC:5 = RP87 (PPS reg: RPOR6_H)

J10:55 = J1:117 = uC:10 = RP118 (PPS reg: RPOR13_H)

— Pin mappings for SPI 1 module —

SPI 1 Clock Out (SCK1) PPS code: 000110 (0x06)
```

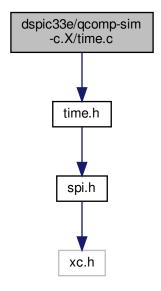
SPI 1 Data Out (SDO1) PPS code: 000101 (0x05) SPI 1 Slave Select PPS code: 000111 — Pin mappings for SPI 3 module — SPI 3 Clock Out (SCK3) PPS code: 100000 (0x20) SPI 3 Data Out (SDO3) PPS code: 011111 (0x1F) SPI 3 Slave Select PPS code: 100001 Configure the SPI 1 pins < Put SCK1 on J10:43 < Put SDO1 on J10:55 The clock pin also needs to be configured as an input < Set SCK1 on J10:43 as input Configure the SPI 3 output pins < Put SCK3 on J10:7 < Put SDO3 on J10:5 < Put SDI3 on J10:44 < Set SCK3 on J10:7 as input @note SPI 1 clock configuration SCK1 = F_CY / (Primary Prescaler * Secondary Prescaler) Assuming that F_CY = 50MHz, and the prescalers are 4 and 1, the SPI clock frequency will be 12.5MHz.

6.15 dspic33e/qcomp-sim-c.X/time.c File Reference

Description: Functions to control the on chip timers.

#include "time.h"

Include dependency graph for time.c:



Functions

- void setup_clock ()
- void setup_timer ()
- void reset_timer ()
- void start_timer ()
- void stop_timer ()
- unsigned long int read_timer ()
- void delay ()

Delay function!

6.15.1 Detailed Description

Description: Functions to control the on chip timers.

Authors

J Scott, O Thomas

Date

Nov 2018

6.15.2 Function Documentation

```
6.15.2.1 setup_timer()
```

```
void setup_timer ( )
```

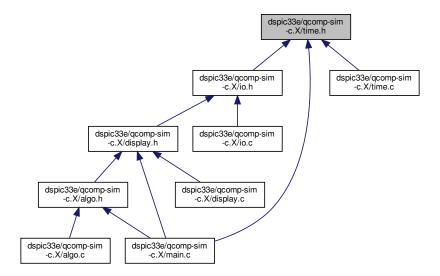
Todo distinguish between the two different timers here...

6.16 dspic33e/qcomp-sim-c.X/time.h File Reference

Description: Header file containing all the timing functions.

```
#include "spi.h"
Include dependency graph for time.h:
```

dspic33e/qcomp-sim -c.X/time.h This graph shows which files directly or indirectly include this file:



Functions

- void setup_clock ()
- void setup_timer ()
- void reset_timer ()
- void start_timer ()
- void stop_timer ()
- unsigned long int read_timer ()
- void delay ()

Delay function!

6.16.1 Detailed Description

Description: Header file containing all the timing functions.

Authors

J Scott, O Thomas

Date

Nov 2018

6.16.2 Function Documentation

6.16.2.1 setup_timer()

```
void setup_timer ( )
```

Todo distinguish between the two different timers here...

Index

attribute	quantum.h, 70
io.c, 40	controlled_qubit_op_new
	quantum.c, 63
absolute	cycle_node, 10
quantum.c, 62	
quantum.h, 70	display.c
add_to_cycle	display_average, 29
io.c, 40	display_cycle, 31
io.h, 51	NUM_MAX_AMPS, 29
algo.c	remove_zero_amp_states, 31
gate, 15	sort_states, 32
gate_display, 15	display.h
swap_test, 15	display_average, 34
toffoli_gate, 15	display_cycle, 36
two_gate, 16	remove_zero_amp_states, 36
two_gate_display, 16	sort_states, 37
algo.h	display_average
gate, 18	display.c, 29
gate_display, 19	display.h, 34
swap_test, 19	display_cycle
toffoli_gate, 19	display.c, 31
two_gate, 20	display.h, 36
two_gate_display, 20	dspic33e/qcomp-sim-c.X/algo.c, 13
	dspic33e/qcomp-sim-c.X/algo.h, 17
BTN, 9	dspic33e/qcomp-sim-c.X/config.h, 21
btn_func	dspic33e/qcomp-sim-c.X/consts.c, 21
io.c, 47	dspic33e/qcomp-sim-c.X/consts.h, 24
btn_qubit	dspic33e/qcomp-sim-c.X/display.c, 28
io.c, 47	dspic33e/qcomp-sim-c.X/display.h, 33
buttons	dspic33e/qcomp-sim-c.X/io.c, 38
io.c, 47	dspic33e/qcomp-sim-c.X/io.h, 49
	dspic33e/qcomp-sim-c.X/main.c, 59
chip	dspic33e/qcomp-sim-c.X/quantum.c, 61
io.c, 48	dspic33e/qcomp-sim-c.X/quantum.h, 68
consts.c	dspic33e/qcomp-sim-c.X/spi.c, 75
H, 22	dspic33e/qcomp-sim-c.X/spi.h, 78
rXT, 23	dspic33e/qcomp-sim-c.X/time.c, 81
rX, 23	dspic33e/qcomp-sim-c.X/time.h, 82
X, 23	
Y, 24	flash_all
Z, 24	_ io.c, 41
consts.h	io.h, <mark>52</mark>
H, 26	flash_led
rXT, 27	io.c, 41
rX, 26	io.h, 52
X, 27	,
Y, 27	gate
Z, 27	algo.c, 15
controlled_qubit_op	algo.h, 18
quantum.c, 62	gate_display
g	S7

86 INDEX

	algo.c, 15	io.h, <mark>54</mark>
	algo.h, 19	led_global
		io.c, 48
Н		
	consts.c, 22	main
	consts.h, 26	main.c, 60
io		main.c
io.c	attributa 40	main, 60
	attribute, 40	mat_mul
	add_to_cycle, 40 btn_func, 47	quantum.c, 64
		quantum.h, 71
	btn_qubit, 47	mat_mul_old
	buttons, 47	quantum.c, 65
	chip, 48	AU INA MANY AMADO
	flash_all, 41	NUM_MAX_AMPS
	flash_led, 41	display.c, 29
	isr_counter, 48	now?
	led_color_int, 41	pow2
	led_cycle_test, 42	quantum.c, 65
	led_global, 48	quantum.h, 72
	read_btn, 42	quantum a
	read_external_buttons, 43	quantum.c
	reset_cycle, 43	absolute, 62
	set_external_led, 43	controlled_qubit_op, 62
	set_led, 44	controlled_qubit_op_new, 63
	set_strobe, 44	mat_mul_old_65
	setup_external_leds, 45	mat_mul_old, 65
	setup_io, 45	pow2, 65 sign, 66
	TLC591x_mode_switch, 45	single_qubit_op, 66
	toggle_strobe, 46	
	update_display_buffer, 46	square_magnitude, 67
	write_display_driver, 46	zero_state, 68
io.h	add to suple E1	quantum.h
	add_to_cycle, 51	absolute, 70
	flash_all, 52	controlled_qubit_op, 70
	flash_led, 52	mat_mul, 71
	led_color_int, 52	pow2, 72
	led_cycle_test, 54	sign, 72
	read_btn, 54	single_qubit_op, 72
	read_external_buttons, 54	square_magnitude, 73
	reset_cycle, 55	zero_state, 74
	set_external_led, 55	RGB, 12
	set_led, 56	rXT
	set_strobe, 56	consts.c, 23
	setup_external_leds, 56	consts.h, 27
	setup_io, 57	read btn
	toggle_strobe, 57	io.c, 42
	update_display_buffer, 57	io.h, 54
ior	write_display_driver, 58	read_external_buttons
151_0	counter io.c, 48	io.c, 43
	10.0, 40	io.h, 54
LED	_GLOBAL, 11	remove_zero_amp_states
LED		display.c, 31
	color_int	display.h, 36
.54_	io.c, 41	reset_cycle
	io.h, 52	io.c, 43
led	cycle_test	io.h, 55
.54_	io.c, 42	rX
	,	

INDEX 87

consts.c, 23	io.c, 46
consts.h, 26	io.h, 57
send_byte_spi_1	two_gate
spi.c, 75	algo.c, 16 algo.h, 20
spi.h, 79	two_gate_display
set_external_led	algo.c, 16
io.c, 43	algo.h, 20
io.h, <u>55</u>	-
set_led	update_display_buffer
io.c, 44	io.c, 46
io.h, 56	io.h, 57
set_strobe io.c, 44	write_display_driver
io.h, 56	io.c, 46
setup_external_leds	io.h, 58
io.c, 45	
io.h, <mark>56</mark>	X
setup_io	consts.c, 23
io.c, 45	consts.h, 27
io.h, 57	Υ
setup_spi	consts.c, 24
spi.c, 77	consts.h, 27
spi.h, 79 setup_timer	_
time.c, 82	Z
time.h, 83	consts.c, 24
sign	consts.h, 27
quantum.c, 66	zero_state quantum.c, 68
quantum.h, 72	quantum.h, 74
single_qubit_op	4
quantum.c, 66	
quantum.h, 72	
sort_states	
display.c, 32 display.h, 37	
spi.c	
send_byte_spi_1, 75	
setup_spi, 77	
spi.h	
send_byte_spi_1, 79	
setup_spi, 79	
square_magnitude	
quantum.c, 67 quantum.h, 73	
swap test	
algo.c, 15	
algo.h, 19	
TLC591x_mode_switch	
io.c, 45	
time.c setup_timer, 82	
time.h	
setup_timer, 83	
toffoli_gate	
algo.c, 15	
algo.h, 19	
toggle_strobe	