

# Naïve bayes

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- Let  $I$  be the event that you have a deadly incurable disease, called *incuritis*.
  - $I = 1$  means you have it;  $I = 0$  means you don't.
  - Abbreviation:  $i$ ,  $\neg i$ .
- Let  $K$  represent the event that your knee is itchy.
  - $K = 1$  means your knees itch;  $K = 0$  the opposite.
  - Abbreviation:  $k$ ,  $\neg k$ .
- Medical science tells us that 80% of people who have incuritis also suffer from itchy knees.

$$P(k|i) = 0.8$$

- But you're not terrified, because you know Bayes Rule:

$$P(i|k) = \frac{P(k|i)P(i)}{P(k)}$$

- You consult medical clinicians, and you are told  $P(i) = 10^{-5}$  and  $P(k) = 0.5$
- A little math, and you show  $P(i|k) = 1.6 \times 10^{-5}$
- Probably not incuritis after all!

# Bayes' Rule

- The most important formula in probabilistic machine learning

$$P(A|B) = \frac{P(B|A) \times P(A)}{P(B)}$$

(Super Easy) Derivation:

$$\begin{aligned} P(A \wedge B) &= P(A|B) \times P(B) \\ P(B \wedge A) &= P(B|A) \times P(A) \end{aligned}$$

Just set equal...

$$P(A|B) \times P(B) = P(B|A) \times P(A)$$

and solve...



**Bayes, Thomas (1763)** An essay towards solving a problem in the doctrine of chances. *Philosophical Transactions of the Royal Society of London*, 53:370-418

# Common terminology for Bayes' Rule

$$P(Y|\mathbf{X}) = \frac{P(\mathbf{X}|Y)P(Y)}{P(\mathbf{X})}$$

- Posterior probability (distribution):  $P(Y|\mathbf{X})$ 
  - The probability of  $Y$  **after** considering the data.
- Prior probability (distribution):  $P(Y)$ 
  - The probability of  $Y$  **before** considering the data.
- Likelihood (distribution):  $P(\mathbf{X}|Y)$ 
  - Describes how the data depends on  $Y$ .
- Normalization constant:  $P(\mathbf{X})$ 
  - Always boring. Sometimes written  $\alpha^{-1}$ .

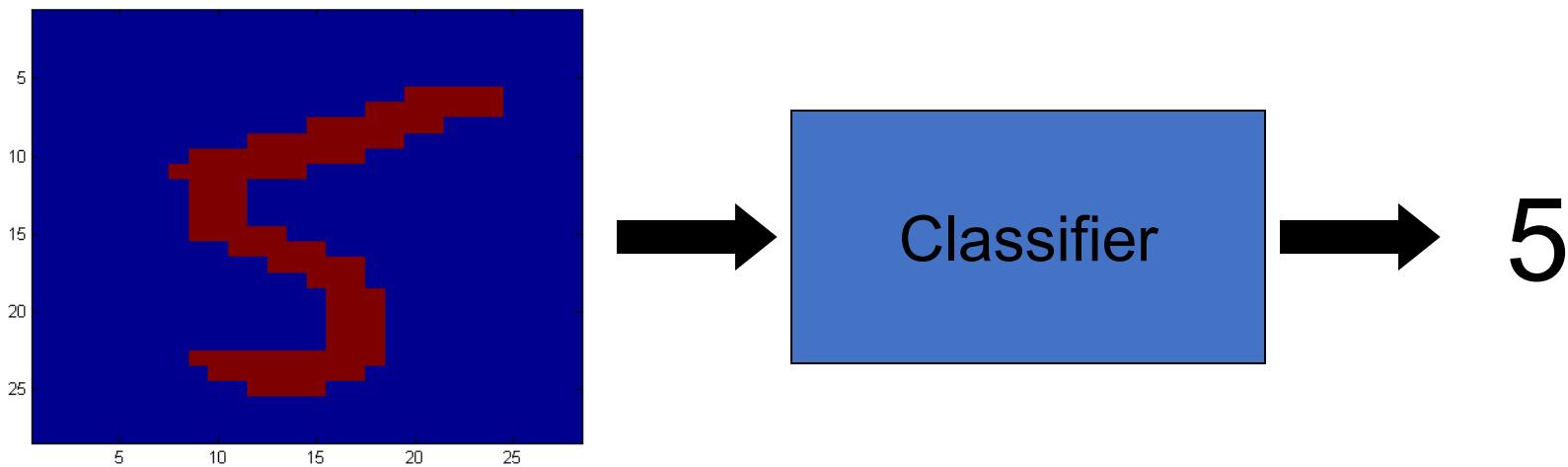
- The model comprises two types of probabilities that can be calculated directly from the training data:
  - the probability of each class
  - the conditional probability for each class given each  $x$  value.

# Bayesian Classification

- Problem statement:
  - Given features  $X_1, X_2, \dots, X_n$
  - Predict a label Y

# Another Application

- **Digit Recognition**



- $X_1, \dots, X_n \in \{0,1\}$  (Black vs. White pixels)
- $Y \in \{5,6\}$  (predict whether a digit is a 5 or a 6)

# The Bayes Classifier

- A good strategy is to predict:

$$\arg \max_Y P(Y|X_1, \dots, X_n)$$

- (for example: what is the probability that the image represents a 5 given its pixels?)

- So ... How do we compute that?

# The Bayes Classifier

- Use Bayes Rule!

$$P(Y|X_1, \dots, X_n) = \frac{P(X_1, \dots, X_n|Y)P(Y)}{P(X_1, \dots, X_n)}$$

↑  
Likelihood                                      ↑  
  Prior  
  ↑  
  Normalization Constant

- Why did this help? Well, we think that we might be able to specify how features are “generated” by the class label

# The Bayes Classifier

- Let's expand this for our digit recognition task:

$$P(Y = 5|X_1, \dots, X_n) = \frac{P(X_1, \dots, X_n|Y = 5)P(Y = 5)}{P(X_1, \dots, X_n|Y = 5)P(Y = 5) + P(X_1, \dots, X_n|Y = 6)P(Y = 6)}$$
$$P(Y = 6|X_1, \dots, X_n) = \frac{P(X_1, \dots, X_n|Y = 6)P(Y = 6)}{P(X_1, \dots, X_n|Y = 5)P(Y = 5) + P(X_1, \dots, X_n|Y = 6)P(Y = 6)}$$

- To classify, we'll simply compute these two probabilities and predict based on which one is greater

# Model Parameters

- How many parameters are required to specify the likelihood?
  - (Supposing that each image is 30x30 pixels)

?

# Model Parameters

- The problem with explicitly modeling  $P(X_1, \dots, X_n | Y)$  is that there are usually way too many parameters:
  - We'll run out of space
  - We'll run out of time
  - And we'll need tons of training data (which is usually not available)

# The Naïve Bayes Model

- The *Naïve Bayes Assumption*: Assume that all features are independent **given the class label Y**
- Equationally speaking:

$$P(X_1, \dots, X_n | Y) = \prod_{i=1}^n P(X_i | Y)$$

# Naïve Bayes Example

$$v_{NB} = \operatorname{argmax}_{v_j \in V} P(v_j) \prod_i P(x_i | v_j)$$

| Day | Outlook  | Temperature | Humidity | Wind   | PlayTennis |
|-----|----------|-------------|----------|--------|------------|
| 1   | Sunny    | Hot         | High     | Weak   | No         |
| 2   | Sunny    | Hot         | High     | Strong | No         |
| 3   | Overcast | Hot         | High     | Weak   | Yes        |
| 4   | Rain     | Mild        | High     | Weak   | Yes        |
| 5   | Rain     | Cool        | Normal   | Weak   | Yes        |
| 6   | Rain     | Cool        | Normal   | Strong | No         |
| 7   | Overcast | Cool        | Normal   | Strong | Yes        |
| 8   | Sunny    | Mild        | High     | Weak   | No         |
| 9   | Sunny    | Cool        | Normal   | Weak   | Yes        |
| 10  | Rain     | Mild        | Normal   | Weak   | Yes        |
| 11  | Sunny    | Mild        | Normal   | Strong | Yes        |
| 12  | Overcast | Mild        | High     | Strong | Yes        |
| 13  | Overcast | Hot         | Normal   | Weak   | Yes        |
| 14  | Rain     | Mild        | High     | Strong | No         |

# Estimating Probabilities

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- $v_{NB} = \operatorname{argmax}_{v \in \{yes,no\}} P(v) \prod_i P(x_i = observation | v)$
- How do we estimate  $P(observation | v)$ ?

# Example

$$v_{NB} = \operatorname{argmax}_{v_j \in V} P(v_j) \prod_i P(x_i | v_j)$$

- Compute  $P(\text{PlayTennis} = \text{yes})$ ;  $P(\text{PlayTennis} = \text{no})$
- Compute  $P(\text{outlook} = s/\text{oc}/r \mid \text{PlayTennis} = \text{yes/no})$  (6 numbers)
- Compute  $P(\text{Temp} = h/\text{mild}/\text{cool} \mid \text{PlayTennis} = \text{yes/no})$  (6 numbers)
- Compute  $P(\text{humidity} = \text{hi}/\text{nor} \mid \text{PlayTennis} = \text{yes/no})$  (4 numbers)
- Compute  $P(\text{wind} = w/\text{st} \mid \text{PlayTennis} = \text{yes/no})$  (4 numbers)

# Example

$$v_{NB} = \operatorname{argmax}_{v_j \in V} P(v_j) \prod_i P(x_i | v_j)$$

- Compute  $P(\text{PlayTennis} = \text{yes})$ ;  $P(\text{PlayTennis} = \text{no})$
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- Compute  $P(\text{wind} = w/\text{st} \mid \text{PlayTennis} = \text{yes/no})$  (4 numbers)
- Given a new instance:  
(Outlook=sunny; Temperature=cool; Humidity=high; Wind=strong)
- Predict:  $\text{PlayTennis} = ?$

# Example

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$$v_{NB} = \operatorname{argmax}_{v_j \in V} P(v_j) \prod_i P(x_i | v_j)$$

- Given: (Outlook=sunny; Temperature=cool; Humidity=high; Wind=strong)
- $P(\text{PlayTennis} = \text{yes}) = 9/14 = 0.64$
- $P(\text{PlayTennis} = \text{no}) = 5/14 = 0.36$
- $P(\text{outlook} = \text{sunny} | \text{yes}) = 2/9$        $P(\text{outlook} = \text{sunny} | \text{no}) = 3/5$
- $P(\text{temp} = \text{cool} | \text{yes}) = 3/9$        $P(\text{temp} = \text{cool} | \text{no}) = 1/5$
- $P(\text{humidity} = \text{hi} | \text{yes}) = 3/9$        $P(\text{humidity} = \text{hi} | \text{no}) = 4/5$
- $P(\text{wind} = \text{strong} | \text{yes}) = 3/9$        $P(\text{wind} = \text{strong} | \text{no}) = 3/5$
- $P(\text{yes}, \dots) \sim 0.0053$
- $P(\text{no}, \dots) \sim 0.0206$

# Example

---

$$v_{NB} = \operatorname{argmax}_{v_j \in V} P(v_j) \prod_i P(x_i | v_j)$$

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  - $P(\text{temp} = \text{cool} | \text{yes}) = 3/9$
  - $P(\text{temp} = \text{cool} | \text{no}) = 1/5$
  - $P(\text{humidity} = \text{hi} | \text{yes}) = 3/9$
  - $P(\text{humidity} = \text{hi} | \text{no}) = 4/5$
  - $P(\text{wind} = \text{strong} | \text{yes}) = 3/9$
  - $P(\text{wind} = \text{strong} | \text{no}) = 3/5$
  - $P(\text{yes}, \dots) \sim 0.0053$
  - $P(\text{no}, \dots) \sim 0.0206$
  - $P(\text{no} | \text{instance}) = 0.0206 / (0.0053 + 0.0206) = 0.795$
- What if we were asked about Outlook=OC ?

- Advantages of Using Naive Bayes Classifier
  - Simple to Implement. The conditional probabilities are easy to evaluate.
  - Very fast – no iterations since the probabilities can be directly computed.
  - If the conditional Independence assumption holds, it could give great results.
- Disadvantages of Using Naive Bayes Classifier
  - Conditional Independence Assumption does not always hold. In most situations, the feature show some form of dependency.

- Naive Bayes is called naive because it assumes that each input variable is independent.
- This is a strong assumption and unrealistic for real data; however, the technique is very effective on a large range of complex problems.

# Learning Resources

1. <https://brilliant.org/wiki/classification/>
2. <https://www.toptal.com/machine-learning/machine-learning-theory-an-introductory-primer>
3. <https://developers.google.com/machine-learning/problem-framing/cases>
4. [https://learning.oreilly.com/library/view/hyperparameter-tuning-with/9781803235875/B18753\\_02\\_ePub.xhtml](https://learning.oreilly.com/library/view/hyperparameter-tuning-with/9781803235875/B18753_02_ePub.xhtml)
5. [https://learning.oreilly.com/library/view/hyperparameter-tuning-with/9781803235875/B18753\\_03\\_ePub.xhtml](https://learning.oreilly.com/library/view/hyperparameter-tuning-with/9781803235875/B18753_03_ePub.xhtml)
6. <https://scikit-learn.org/stable/>
7. <https://learning.oreilly.com/library/view/hands-on-machine-learning/9781492032632/ch04.html#idm45022192214984>

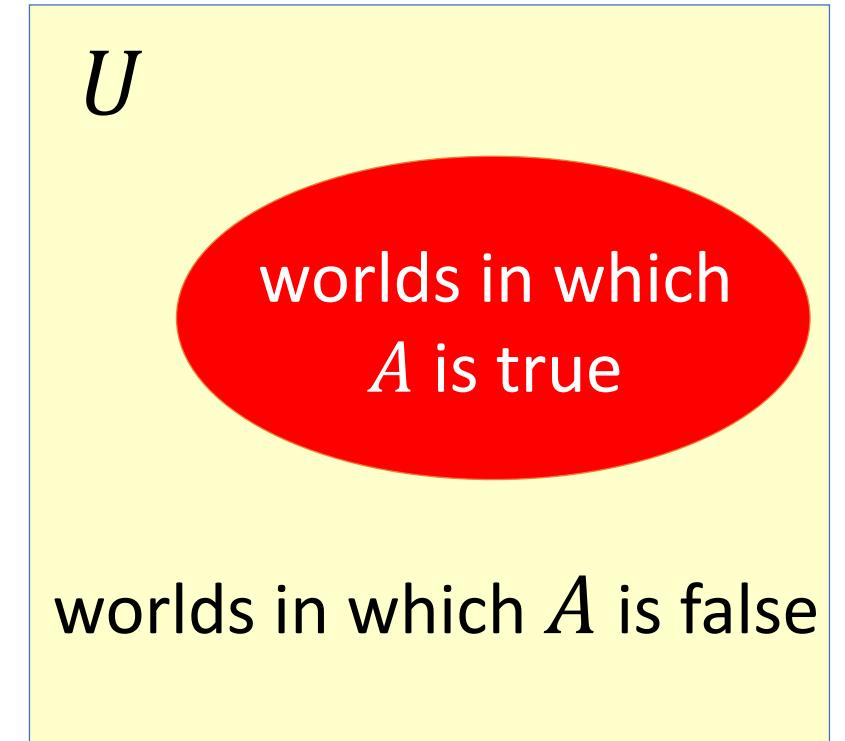
# Probability

# Probability

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- Universe  $U$  is the event space of all possible worlds
  - Its area is 1
  - $P(U) = 1$
- $P(A)$  = area of red oval
- Therefore:

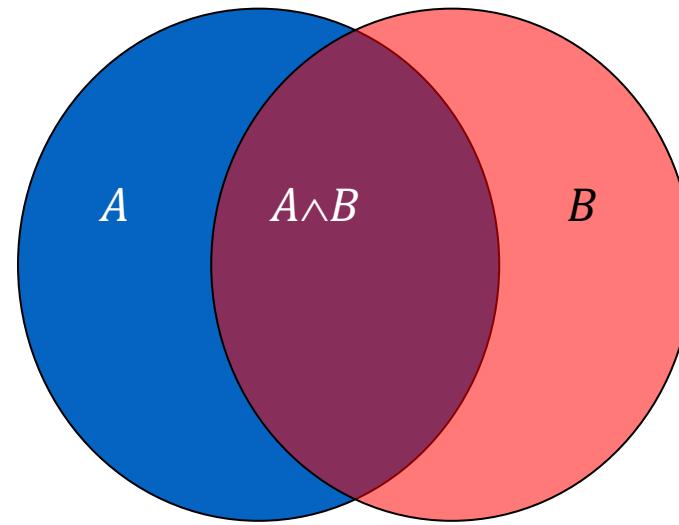
$$P(A) + P(\neg A) = 1$$
$$P(\neg A) = 1 - P(A)$$



# Interpreting the Axioms

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- $0 \leq P(A) \leq 1$
- $P(\text{true}) = 1$
- $P(\text{false}) = 0$
- $P(A \vee B) = P(A) + P(B) - P(A \wedge B)$



- From these you can prove other properties:
- $P(\neg A) = 1 - P(A)$
- $P(A) = P(A \wedge B) + P(A \wedge \neg B)$

# Example: Conditional Probabilities

$$P(A|B) = \frac{P(A \wedge B)}{P(B)}$$

$$P(A \wedge B) = P(A|B) \times P(B)$$

$$P(alarm, burglary) =$$

|                 | alarm | $\neg$ alarm |
|-----------------|-------|--------------|
| burglary        | 0.09  | 0.01         |
| $\neg$ burglary | 0.1   | 0.8          |

$$\begin{aligned} P(burglary | alarm) &= P(burglary \wedge alarm) / P(alarm) \\ &= 0.09 / 0.19 = 0.47 \end{aligned}$$

$$\begin{aligned} P(alarm | burglary) &= P(burglary \wedge alarm) / P(burglary) \\ &= 0.09 / 0.1 = 0.9 \end{aligned}$$

$$\begin{aligned} P(burglary \wedge alarm) &= P(burglary | alarm) P(alarm) \\ &= 0.47 * 0.19 = 0.09 \end{aligned}$$

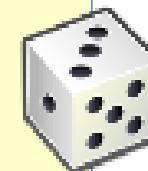
# Independence

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- When two events do not affect each others' probabilities, we call them **independent**
- Formal definition:

$$A \perp\!\!\!\perp B$$

$$\begin{aligned} &\leftrightarrow P(A \wedge B) = P(A) \times P(B) \\ &\leftrightarrow P(A|B) = P(A) \end{aligned}$$



# Exercise: Independence

| P( <b>smart</b> $\wedge$ <b>study</b> $\wedge$ <b>prep</b> ) | <b>smart</b> |                     | $\neg$ <b>smart</b> |                     |
|--|--------------|---------------------|---------------------|---------------------|
|  | <b>study</b> | $\neg$ <b>study</b> | <b>study</b>        | $\neg$ <b>study</b> |
| <b>prepared</b>  | 0.432        | 0.16                | 0.084               | 0.008               |
| $\neg$ <b>prepared</b>                                       | 0.048        | 0.16                | 0.036               | 0.072               |

Is *smart* independent of *study*?

$$P(\text{study} \wedge \text{smart}) = 0.432 + 0.048 = 0.48$$

$$P(\text{study}) = 0.432 + 0.048 + 0.084 + 0.036 = 0.6$$

$$P(\text{smart}) = 0.432 + 0.048 + 0.16 + 0.16 = 0.8$$

$$P(\text{study}) \times P(\text{smart}) = 0.6 \times 0.8 = 0.48$$

So yes!

Is *prepared* independent of *study*?

# Bayes' Rule for Machine Learning

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- Allows us to reason from **evidence** to **hypotheses**
- Another way of thinking about Bayes' rule:

$$P(\text{hypothesis} \mid \text{evidence}) = \frac{P(\text{evidence} \mid \text{hypothesis}) \times P(\text{hypothesis})}{P(\text{evidence})}$$

**Goal:**

find the best hypothesis from some space  $H$  of hypotheses, **given** the observed data (evidence)  $D$ .

# Bayesian Classifier

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- $f: X \rightarrow V$ , finite set of values
- Instances  $x \in X$  can be described as a collection of features

$$x = (x_1, x_2, \dots, x_n) \quad x_i \in \{0,1\}$$

- Given an example, assign it the most probable value in  $V$
- Bayes Rule:

$$v_{MAP} = \operatorname{argmax}_{v_j \in V} P(v_j | x) = \operatorname{argmax}_{v_j \in V} P(v_j | x_1, x_2, \dots, x_n)$$

$$v_{MAP} = \operatorname{argmax}_{v_j \in V} \frac{P(x_1, x_2, \dots, x_n | v_j) P(v_j)}{P(x_1, x_2, \dots, x_n)} = \operatorname{argmax}_{v_j \in V} P(x_1, x_2, \dots, x_n | v_j) P(v_j)$$

- Notational convention:  $P(y)$  means  $P(Y = y)$

# Naive Bayes

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$$V_{MAP} = \operatorname{argmax}_v P(x_1, x_2, \dots, x_n | v)P(v)$$

$$\begin{aligned} P(x_1, x_2, \dots, x_n | v_j) &= P(x_1 | x_2, \dots, x_n, v_j)P(x_2, \dots, x_n | v_j) \\ &= P(x_1 | x_2, \dots, x_n, v_j) P(x_2 | x_3, \dots, x_n, v_j)P(x_3, \dots, x_n | v_j) \\ &\quad = \dots \\ &= P(x_1 | x_2, \dots, x_n, v_j) P(x_2 | x_3, \dots, x_n, v_j)P(x_3 | x_4, \dots, x_n, v_j) \dots P(x_n | v_j) \\ &= \prod_{i=1}^n P(x_i | v_j) \end{aligned}$$

- **Assumption:** feature values are independent given the target value

# Naive Bayes (2)

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$$V_{MAP} = \operatorname{argmax}_v P(x_1, x_2, \dots, x_n | v)P(v)$$

- Assumption: feature values are independent given the target value

$$P(x_1 = b_1, x_2 = b_2, \dots, x_n = b_n | v = v_j) \prod_{i=1}^n (x_i = b_i | v = v_j)$$

- Generative model:
- First choose a value  $v_j \in V$  according to  $P(v)$
- For each  $v_j$ : choose  $x_1, x_2, \dots, x_n$  according to  $P(x_k | v_j)$

# Naive Bayes (3)

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$$V_{MAP} = \operatorname{argmax}_v P(x_1, x_2, \dots, x_n | v)P(v)$$

- Assumption: feature values are independent given the target value

$$P(x_1 = b_1, x_2 = b_2, \dots, x_n = b_n | v = v_j) \prod_{i=1}^n (x_i = b_i | v = v_j)$$

- Learning method: Estimate  $n|V| + |V|$  parameters and use them to make a prediction. (How to estimate?)
- Notice that this is learning without search. Given a collection of training examples, you just compute the best hypothesis (given the assumptions).
- This is learning without trying to achieve consistency or even approximate consistency.
- Why does it work?