

• Demo 1 : def des w_{eff}

$$MSE = \|s - s'\|^2 = (s - s')^T (s - s') = s^T s - s^T s' - s'^T s + s'^T s'$$

$$\frac{\partial MSE}{\partial w_{eff}} = 0 - (s^T b)^T - b^T s + b^T b w_{eff} + (w_{eff}^T b^T s - w_{eff}^T b^T b w_{eff}) = 0$$

$$\Rightarrow -2 b^T s + 2 b^T b w_{eff} = 0 \Rightarrow w_{eff} = (b^T b)^{-1} b^T s$$

• Demo 2 : $C_s = C_{w_{eff}}$

$$C_s = E(s s^T) = \begin{bmatrix} \sigma_s^2(1) & \dots & \dots \\ \vdots & & \sigma_s^2(N) \end{bmatrix} \quad C_{w_{eff}} = E(w_{eff} w_{eff}^T) = (b^T s s^T b) = b^T C_s b$$

$$\text{trace}(C_s) = \text{trace}(C_{w_{eff}})$$

$$C_{w_{eff}}' = \begin{bmatrix} \sigma_{w_{eff}}^2(1) & \dots & \dots \\ \vdots & & \sigma_{w_{eff}}^2(L) \\ & & & 0 \end{bmatrix} \Rightarrow \text{trace}(C_{w_{eff}}') = \text{trace}(C_{w_{eff}}) - \sigma_{w_{eff}}^2(L+1) - \dots - \sigma_{w_{eff}}^2(N)$$

$$= \text{trace}(C_s) - \sum_{k=L+1}^N \sigma_{w_{eff}}^2(k)$$

• Demo 3 : $C_s b = b \Lambda$

$$E(MSE) = E((s - s')^T (s - s')) = E(s^T s) + E(s'^T s') - E(s^T s') - E(s'^T s)$$

$$= \text{tr}(C_s) + \text{tr}(C_{w_{eff}}') - \text{tr}(C_{w_{eff}}) - \text{tr}(C_{w_{eff}}')$$

$$= \text{tr}(C_s) - \text{tr}(C_{w_{eff}}') = \text{tr}(C_s) - \text{tr}(C_s) + \sum_{k=L+1}^N \sigma_{w_{eff}}^2(k)$$

$$= \sum_{k=L+1}^N \sigma_{w_{eff}}^2(k)$$

$$\frac{\partial MSE}{\partial w_{eff}} = 0 \Rightarrow \sum_{k=L+1}^N \sigma_{w_{eff}}^2(k) \text{ doit être min.}$$

$$y \ L=1 \Rightarrow \begin{cases} \sigma_{w_{eff}}^2(1) = C_{w_{eff}}(1,1) = b_1^T C_s b_1 \\ b_1^T b_1 = 1 \end{cases} \Rightarrow \frac{d}{db_1} (b_1^T C_s b_1 - \lambda (b_1^T b_1 - 1)) = 0$$

$$\frac{d}{db_1} (b_1^T (C_s - \lambda I) b_1) = 0$$

$$[b_1^T (C_s - \lambda I)]^T + [(C_s - \lambda I) b_1] = 0$$

$$2 (C_s b_1 - \lambda b_1) = 0$$

$$C_s b_1 = \lambda b_1 \Rightarrow \text{on a } \lambda_1 \text{ max}$$

$$C_s b = \underline{b} \Lambda \text{ avec } \Lambda = \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_L \end{bmatrix} \text{ avec } \lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_L$$

et comme C_s diag avec σ_s^2 sur diag $\Rightarrow \Lambda$ doit être matrice des valeurs

$$C_{w_{eff}} = b^T C_s b = \underline{b}^{-1} \underline{b} \Lambda = \Lambda \Rightarrow b^T = b^{-1} \text{ for orthonormal basis.}$$

+ demo propriétés de Fourier

• Démon 4: $I_t' = \frac{I_t}{s}$

$I_t \in [-T, T]$ pour $f(t)$ alors $f'(t) := f(st) \Rightarrow -T \leq st \leq T$
 $\Rightarrow -\frac{T}{s} \leq t \leq \frac{T}{s}$

$$\begin{aligned} I\omega \in [\omega_{\min}; \omega_{\max}] \text{ pour } F(\omega) \text{ alors } F'(\omega) &= \int_{-T}^T f'(t) e^{-j\omega t} dt \\ &= \int_{-T}^T f(st) e^{-j\omega t} dt, \mu = st \\ &= \int_{-\frac{T}{s}}^{\frac{T}{s}} f(\mu) e^{-j\omega \frac{\mu}{s}} \frac{d\mu}{s} \\ &= \frac{1}{s} F\left(\frac{\omega}{s}\right) \end{aligned}$$

• Démon 5: normalisation factor

$$\int |\psi(t)|^2 dt = \int |\psi_{a,0}(t)|^2 dt$$

$$\int |\psi_{a,0}(t)|^2 = \int \frac{1}{\sqrt{a}} \psi\left(\frac{t}{a}\right) \frac{1}{\sqrt{a}} \psi^*\left(\frac{t}{a}\right) dt = \frac{1}{a} \int \psi\left(\frac{t}{a}\right) \psi^*\left(\frac{t}{a}\right) dt$$

$$\mu = \frac{t}{a} \quad = \frac{1}{a} \int \psi(\mu) \psi^*(\mu) a d\mu = \int \psi(\mu) \psi^*(\mu) d\mu = \int |\psi(t)|^2 dt$$

• Démon 6: uncertainty principle

$$\text{resolution in time } \Delta t^2 = \frac{\int t^2 |\psi(t)|^2 dt}{\int |\psi(t)|^2 dt}$$

$$\text{resolution in frequency } \Delta \omega^2 = \frac{\int \omega^2 |\Phi(\omega)|^2 d\omega}{\int |\Phi(\omega)|^2 d\omega}$$

$$\text{uncertainty principle: } \Delta t^2 \cdot \Delta \omega^2 \geq \frac{1}{4}$$

$$\int t^2 |\psi(t)|^2 dt \cdot \int \omega^2 |\Phi(\omega)|^2 d\omega \geq \frac{1}{4} \int |\psi(t)|^2 dt \int |\Phi(\omega)|^2 d\omega$$

$$\text{par normalisation: } \int |\psi(t)|^2 dt = \frac{1}{2\pi} \int |\Phi(\omega)|^2 d\omega$$

$$\text{par rel. de Fourier: } \psi'(t) = -j\omega \Phi(\omega) \Rightarrow |\psi'(t)|^2 = -\omega^2 |\Phi(\omega)|^2$$

$$\int t^2 |\psi(t)|^2 dt \cdot 2\pi \int |\psi'(t)|^2 dt \geq \frac{2\pi}{4} \left(\int |\psi(t)|^2 dt \right)^2 \quad (1)$$

$$\text{Cauchy-Schwarz inequality: } \left(\int |f(t)|^2 dt \right) \left(\int |g(t)|^2 dt \right) \geq \left| \int f(t) g(t) dt \right|^2$$

$$\int t^2 |\psi(t)|^2 dt \int |\psi'(t)|^2 dt \geq \left(\int t |\psi(t)| |\psi'(t)| dt \right)^2 =: I^2 \quad (2)$$

$$I = \int \underbrace{t}_{f'} \underbrace{|\psi(t)| |\psi'(t)|}_{g'} dt = t \psi^2(t) \Big|_{-\infty}^{\infty} - \int (\psi(t) + t \psi'(t)) \psi(t) dt = 0 - \int \psi^2(t) dt = -I$$

$$I = \frac{1}{2} \int \psi^2(t) dt \Rightarrow I^2 = \frac{1}{4} \left(\int \psi^2(t) dt \right)^2$$

$$\Rightarrow \text{equality for } \psi'(t) = kt \psi(t), k = -2\alpha, \psi(0) = 1 \Rightarrow \psi = \sqrt{\frac{2\alpha}{\pi}} e^{-\alpha t^2}$$

Demo 7: shift property of CWT

$$f(t) = f(t - \tau') \rightarrow \text{CWT}_f(0, \tau) = \text{CWT}_f(0, \tau - \tau')$$

$$\text{CWT}_f(0, \tau) = \frac{1}{\sqrt{a}} \int f(t) \psi^*\left(\frac{t - \tau}{a}\right) dt = \frac{1}{\sqrt{a}} \int f(t - \tau') \psi^*\left(\frac{t - \tau}{a}\right) dt$$

$$\begin{aligned} u = t - \tau' \quad du = dt &= \frac{1}{\sqrt{a}} \int f(u) \psi^*\left(\frac{u + \tau' - \tau}{a}\right) du = \frac{1}{\sqrt{a}} \int f(u) \psi^*\left(\frac{u - (\tau - \tau')}{a}\right) du \\ &= \text{CWT}_f(0, \tau - \tau') \end{aligned}$$

Demo 8: scaling property of CWT

$$g(t) = \frac{1}{\sqrt{s}} f\left(\frac{t}{s}\right) \rightarrow \text{CWT}_g(0, \tau) = \text{CWT}_f\left(\frac{0}{s}, \frac{\tau}{s}\right)$$

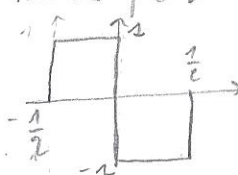
$$\text{CWT}_g(0, \tau) = \frac{1}{\sqrt{a}} \int g(t) \psi^*\left(\frac{t - \tau}{a}\right) dt = \frac{1}{\sqrt{a}} \int \frac{1}{\sqrt{s}} f\left(\frac{t}{s}\right) \psi^*\left(\frac{t - \tau}{a}\right) dt$$

$$\begin{aligned} u = \frac{t}{s} \quad du = \frac{dt}{s} &= \frac{1}{\sqrt{a}} \frac{1}{\sqrt{s}} \int f(u) \psi^*\left(\frac{su - \tau}{a}\right) s du \\ &= \sqrt{\frac{s}{a}} \int f(u) \psi^*\left(\frac{u - \frac{\tau}{s}}{\frac{a}{s}}\right) du = \text{CWT}_f\left(\frac{\tau}{s}, \frac{a}{s}\right) \end{aligned}$$

Demo 9: time localization of LWT

CWT Haar wavelet of Dirac pulse: $\text{CWT}_\delta(0, \tau) = \frac{1}{\sqrt{a}} \psi^*\left(\frac{t_0 - \tau}{a}\right)$

Haar $\psi(t) = \begin{cases} 1 & -\frac{a}{2} \leq t < 0 \\ -1 & 0 \leq t < \frac{a}{2} \\ 0 & \text{else} \end{cases}$



$$\begin{aligned} \rightarrow \frac{t_0 - \tau}{a} = -\frac{1}{2} &\Rightarrow t_0 - \tau = -\frac{a}{2} \\ \tau = t_0 + \frac{a}{2} \end{aligned}$$

$$\rightarrow \frac{t_0 - \tau}{a} = \frac{1}{2} \Rightarrow t_0 - \tau = \frac{a}{2}$$

$$\tau = t_0 - \frac{a}{2}$$

$$\rightarrow \frac{t_0 - \tau}{a} = 0 \Rightarrow \tau = t_0$$

$$\text{CWT}_{\psi, \tau}(t) = \begin{cases} \frac{1}{\sqrt{a}} & |t_0| \leq \tau \leq t_0 + \frac{a}{2} \\ -\frac{1}{\sqrt{a}} & t_0 - \frac{a}{2} \leq \tau < t_0 \end{cases}$$

CWT Haver valeur of step : $\text{CWT}_v(0, \tau) = \frac{1}{\sqrt{a}} \int_{-\infty}^{+\infty} g(t) \psi^*\left(\frac{t-\tau}{a}\right) dt$

$\frac{t-\tau}{a} = -\frac{1}{2} \Rightarrow t = -\frac{a}{2} + \tau$

$\frac{t-\tau}{a} = 0 \Rightarrow t = \tau$

$\frac{t-\tau}{a} = \frac{1}{2} \Rightarrow t = \frac{a}{2} + \tau$

$= \frac{1}{\sqrt{a}} \int_{t_0}^{+\infty} \psi^*\left(\frac{t-\tau}{a}\right) dt$

$= \frac{1}{\sqrt{a}} \left(\dots + \frac{1}{\dots} \right)$

• Démonstration : fréquence localisation of CWT

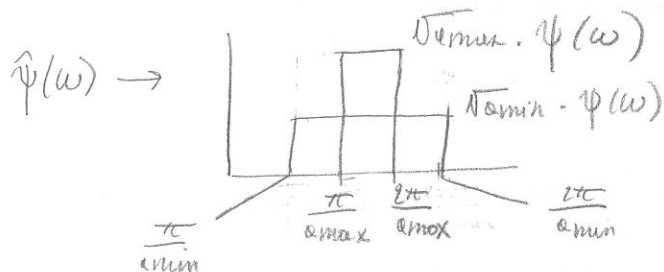
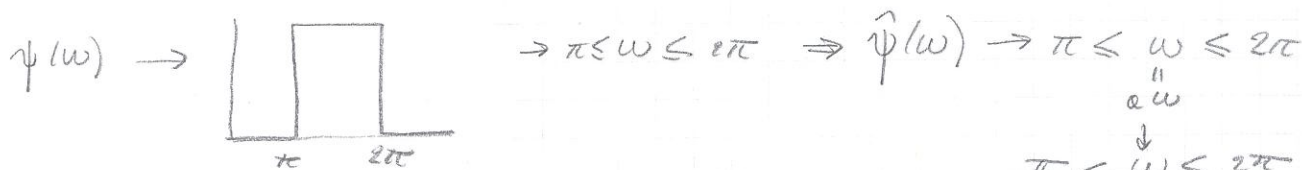
$\psi(\omega) = \int_{-\infty}^{+\infty} \psi(t) e^{-j\omega t} dt$ donc $\hat{\psi}(\omega) = \int_{-\infty}^{+\infty} \psi\left(\frac{t}{a}\right) e^{-j\omega t} dt$

on pose $t_2 = \frac{t}{a} \Rightarrow t = at_2$ et $t \Big|_{-\infty}^{+\infty} \Rightarrow t_2 \Big|_{-\infty}^{+\infty} a > 0$
 $t_2 \Big|_{-\infty}^{-\infty} a < 0$

donc $\hat{\psi}(\omega) = \frac{|a|}{a} \int_{-\infty}^{+\infty} \psi(t_2) e^{-j\omega at_2} dt_2$

donc $\hat{\psi}(\omega) = |a| \psi(a\omega)$

donc $\frac{1}{\sqrt{a}} \psi\left(\frac{t}{a}\right) \xrightarrow{FT} \sqrt{a} \psi(a\omega)$



$\frac{\pi}{a} \leq \omega \leq \frac{2\pi}{a}$
en ω_0
 $\frac{\pi}{a} \leq \omega_0 \leq \frac{2\pi}{a}$
 $\frac{\pi}{\omega_0} \leq a \leq \frac{2\pi}{\omega_0}$

• Demo 11: $\psi'(t) = j\omega \Phi(\omega)$

$$F(\psi(t)) = \int \psi(t) e^{-j\omega t} dt = \Phi(\omega) \quad (1)$$

$$\psi(t) = \frac{1}{2\pi} \int \Phi(\omega) e^{j\omega t} d\omega \quad (2)$$

$$\begin{aligned} \text{from (2): } \psi'(t) &= \frac{d\psi(t)}{dt} = \frac{d}{dt} \left(\frac{1}{2\pi} \int \Phi(\omega) e^{j\omega t} d\omega \right) \\ &= \frac{1}{2\pi} \int \Phi(\omega) j\omega e^{j\omega t} d\omega \\ &= F^{-1}(j\omega \Phi(\omega)) \end{aligned}$$

$$F(\psi'(t)) = F(F^{-1}(j\omega \Phi(\omega))) = j\omega \Phi(\omega)$$

• Demo 12: $(f * \psi_s^2)(x, y) = s \frac{d}{dx} (f * \theta_s)(x, y)$

1D: $\psi(x) = \frac{d}{dx} \theta(x) \quad \psi_s(x) = \frac{1}{s} \psi\left(\frac{x}{s}\right) = \frac{1}{s} \frac{d}{d(x/s)} \theta\left(\frac{x}{s}\right)$

$$f = \frac{x}{s}, g = \theta(x), g \circ f = \theta\left(\frac{x}{s}\right) = f'(g' \circ f)$$

$$\theta_s(x) = \frac{1}{s} \theta\left(\frac{x}{s}\right)$$

$$\begin{aligned} &= (g \circ f)' \\ &= \frac{d}{dx} \left(\theta\left(\frac{x}{s}\right) \right) \\ &= \frac{d}{dx} (s \cdot \theta_s(x)) \end{aligned}$$

2D: $(f * \psi_s^2)(x, y) = \left(f * s \frac{d}{dx} (\theta_s(x, y)) \right) = s \cdot \left(f * \frac{d}{dx} \theta_s \right)(x, y)$

$$= s \frac{d}{dx} (f * \theta_s)(x, y) \text{ by property of convolution:}$$

$$\frac{\partial}{\partial x} (f * g) = \frac{\partial f}{\partial x} * g = f * \frac{\partial g}{\partial x}$$

• Demo 13: $Z\{x[n] * y[n]\} = X(z) Y(z)$

$$X(z) Y(z) = \left(\sum_{n=-\infty}^{\infty} x[n] z^{-n} \right) \left(\sum_{m=-\infty}^{\infty} y[m] z^{-m} \right) = \sum_n \sum_m x[n] y[m] z^{-n-m}$$

$$n+m=p$$

$$= \sum_p \sum_m x[p-m] y[m] z^{-p} = \sum_p \left(\sum_m x[p-m] y[m] \right) z^{-p}$$

$$=: \underbrace{x[p] * y[p]}_{=: s[p]} = s[p]$$

$$= \sum_p s[p] z^{-p} = Z\{s[p]\} = S(z)$$

• Demo 14: $y[n] = x[n] \rightarrow Z(y[n]) = Y(z) = \frac{1}{2} [X(z^{1/2}) + (-z^{1/2})]$

$$X_e(z) = \sum_n x[2n] z^{-n}$$

$$X(z) = \sum_n x[n] z^{-n} = \sum_m x[2m] z^{-2m} + \sum_m x[2m+1] z^{-(2m+1)}$$

$$X_o(z) = \sum_n x[2n+1] z^{-n}$$

$$= X_e(z^2) + X_o(z^2) z^{-1} \quad (1)$$

$$X(-z) = X_e(z^2) - X_o(z^2) z^{-1} \quad (2)$$

$$Y(z) = X_e(z) = \frac{(1) + (2)}{2} = \frac{1}{2} (X(z^{1/2}) + X(-z^{1/2}))$$

• Demo 15: $y[2m] = x[m], y[2m+1] = 0 \rightarrow Z(y[n]) = Y(z) = X(z^2)$

$$\begin{aligned} Y(z) &= \sum_n y[n] z^{-n} = \sum_m y[2m] z^{-2m} + \sum_m y[2m+1] z^{-(2m+1)} \\ &= \sum_m x[m] z^{-2m} + 0 \\ &= X(z^2) \end{aligned}$$

• Demo 16: perfect reconstruction condition

$$\begin{aligned} Y_H(z) &= \frac{1}{2} [H(z^{1/2}) X(z^{1/2}) + H(-z^{1/2}) X(-z^{1/2})] \\ Y_G(z) &= \frac{1}{2} [G(z^{1/2}) X(z^{1/2}) + G(-z^{1/2}) X(-z^{1/2})] \end{aligned} \quad \left. \vphantom{\begin{aligned} Y_H(z) \\ Y_G(z) \end{aligned}} \right\} \text{ANALYSIS}$$

$$\begin{aligned} \hat{Y}_H(z) &= \tilde{H}(z) Y_H(z^2) = \frac{1}{2} \tilde{H}(z) [H(z) X(z) + H(-z) X(-z)] \\ \hat{Y}_G(z) &= \tilde{G}(z) Y_G(z^2) = \frac{1}{2} \tilde{G}(z) [G(z) X(z) + G(-z) X(-z)] \end{aligned} \quad \left. \vphantom{\begin{aligned} \hat{Y}_H(z) \\ \hat{Y}_G(z) \end{aligned}} \right\} \text{SYNTHESIS}$$

$$\hat{X}(z) = \hat{Y}_H(z) + \hat{Y}_G(z) = \frac{1}{2} (\tilde{H}(z) \tilde{G}(z)) \underbrace{\begin{pmatrix} H(z) & H(-z) \\ G(z) & G(-z) \end{pmatrix}}_{H_m(z)} \begin{pmatrix} X(z) \\ X(-z) \end{pmatrix}$$

$$\begin{aligned} \hat{X}(z) = X(z) &\Rightarrow \begin{cases} \tilde{H}(z) H(z) + \tilde{G}(z) G(z) = 2 \cdot I \\ \tilde{H}(z) H(-z) + \tilde{G}(z) G(-z) = 0 \end{cases} \Rightarrow (\tilde{H}(z) \tilde{G}(z)) H_m(z) = \begin{pmatrix} 2 & 0 \\ 0 & 0 \end{pmatrix} \\ &\quad \left(\begin{pmatrix} \tilde{H}(z) \\ \tilde{G}(z) \end{pmatrix} \right) = \frac{2}{\det H_m(z)} \begin{pmatrix} G(-z) \\ -H(-z) \end{pmatrix} \end{aligned}$$

$$\begin{aligned} \Phi(z) &= \tilde{H}(z) H(z) = \frac{2}{\det H_m(z)} G(-z) H(z) \\ \Psi(-z) &= \tilde{G}(z) G(z) = \frac{2}{\det H_m(z)} -H(-z) G(z) \end{aligned} \quad \left. \vphantom{\begin{aligned} \Phi(z) \\ \Psi(-z) \end{aligned}} \right\} (\Phi) = P(z) + P(-z) = 2$$

$$\Psi(-z) = \tilde{G}(z) G(z) = \frac{2}{\det H_m(z)} -H(-z) G(z)$$

Demo 17: 2 channel filter banks: verification of perfect reconstruction

$$h[m] = \left\{ \frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2} \mid m=0, 1 \right\} \quad \tilde{h}[m] = \left\{ \frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2} \mid m=0, -1 \right\}$$

$$g[m] = \left\{ \frac{\sqrt{2}}{2}, -\frac{\sqrt{2}}{2} \mid m=0, 1 \right\} \quad \tilde{g}[m] = \left\{ \frac{\sqrt{2}}{2}, -\frac{\sqrt{2}}{2} \mid m=0, -1 \right\}$$

$$H(z) = \sum_{n=0}^{\infty} h[n] z^{-n} = \frac{\sqrt{2}}{2} (z^{-1} + 1)$$

$$\tilde{H}(z) = \sum_{n=0}^{\infty} \tilde{h}[n] z^{-n} = \frac{\sqrt{2}}{2} (1 + z)$$

$$G(z) = \sum_{n=0}^{\infty} g[n] z^{-n} = \frac{\sqrt{2}}{2} (1 - z^{-1})$$

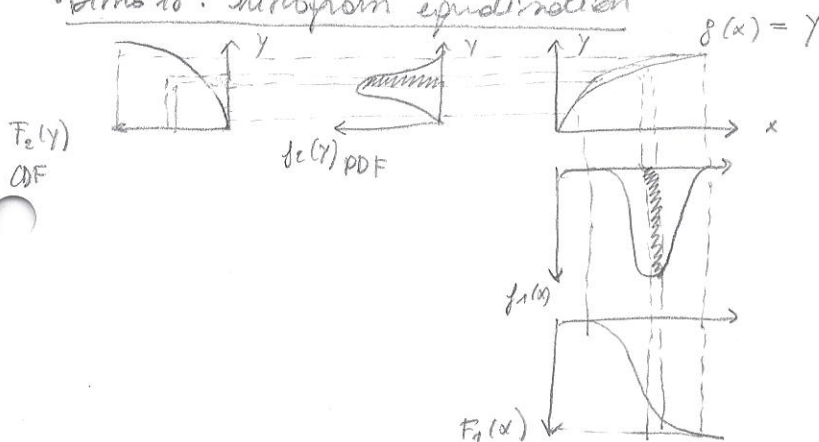
$$\tilde{G}(z) = \sum_{n=0}^{\infty} \tilde{g}[n] z^{-n} = \frac{\sqrt{2}}{2} (1 - z)$$

$$P(z) + P(-z) = 2 \Leftrightarrow \tilde{H}(z)H(z) + \tilde{G}(z)G(z) = 2 \Leftrightarrow \frac{1}{2} \left((z^{-1}+1)(1+z) + (1-z^{-1})(1-z) \right) = 2$$

$$\Leftrightarrow \frac{1}{2} (z^{-1} + 1 + 1 + z + 1 - z - z^{-1} + 1) = 2$$

$$\Leftrightarrow \frac{1}{2} \cdot 4 = 2 \quad \text{CQ.E.D.}$$

Demo 18: histogram equalization



$$f_2(y) dy = f_1(x) dx$$

$$\forall y: F_2(y) = P(Y \leq y) = P(x \leq g^{-1}(y)) = F_1(g^{-1}(y))$$

$$f_2(y) = \frac{dF_2(y)}{dy} = \frac{dF_1(g^{-1}(y))}{dg^{-1}(y)} \frac{dg^{-1}(y)}{dy} = f_1(g^{-1}(y)) \frac{dg^{-1}(y)}{dy} = f_1(x) \frac{dx}{dy}$$

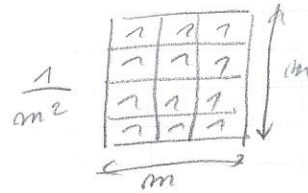
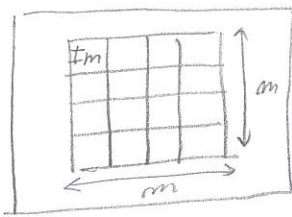
$$\text{if } f_2(y) = \text{uniform} \Rightarrow g = ?$$

$$\begin{cases} 0 \leq y \leq 1 \rightarrow f_2(y) = 1 \\ \text{else} \quad f_2(y) = 0 \end{cases} \quad \text{result is } \begin{cases} f_2(y) = f_1(x) \frac{dx}{dy} \\ f_2(y) = 1 \end{cases} \Rightarrow dy = f_1(x) dx$$

$$y = \int_0^x f_1(x) dx$$

$$y = F_1(x) = g(x)$$

Demo 18: anisotropy reduces noise variance



$$I_m = s_m + n_m$$

\downarrow noisy pixel \downarrow pixel \downarrow noise

Average patch: $A = \frac{1}{m^2} \sum_{i=1}^{m^2} I_m$

$\text{Var}(A) = \dots$

$$E(A) = \frac{1}{m^2} \sum_{i=1}^{m^2} E(s_m + n_m) = \frac{1}{m^2} \sum_{i=1}^{m^2} s_m \text{ for } n_m \sim \mathcal{N}(0, \sigma^2)$$

$$\text{Var}(A) = E \left\{ \left(\frac{1}{m^2} \sum_{i=1}^{m^2} (s_m + n_m) - \frac{1}{m^2} \sum_{i=1}^{m^2} s_m \right)^2 \right\}$$

$$= E \left\{ \left(\frac{1}{m^2} \sum_{i=1}^{m^2} n_m \right)^2 \right\} = E \left\{ \left(\frac{1}{m^2} \sum_{i=1}^{m^2} n_m \right) \left(\frac{1}{m^2} \sum_{i=1}^{m^2} n_m \right) \right\}$$

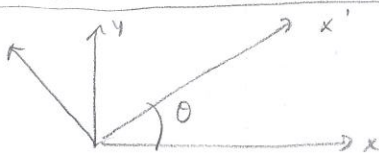
$$= E \left\{ \frac{1}{m^2 m^2} \sum_{i=1}^{m^2} \sum_{j=1}^{m^2} n_m n_m \right\}$$

$$\rho_{ij} = \begin{cases} \sigma^2 & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases}$$

$$= E \left\{ \frac{1}{m^4} \sum_{i=1}^{m^2} \sigma_{ii}^2 \right\}$$

$$= \frac{\sigma^2 m^2}{m^4} = \frac{\sigma^2}{m^2}$$

Demo 18: rotation invariance of gradient



$$x = x' \cos \theta - y' \sin \theta$$

$$y = x' \sin \theta + y' \cos \theta$$

$$\frac{\partial f}{\partial x'} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial x'} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial x'} = \frac{\partial f}{\partial x} \cos \theta + \frac{\partial f}{\partial y} \sin \theta$$

$$\frac{\partial f}{\partial y'} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial y'} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial y'} = -\frac{\partial f}{\partial x} \sin \theta + \frac{\partial f}{\partial y} \cos \theta$$

$$\begin{aligned} \left(\frac{\partial f}{\partial x'} \right)^2 + \left(\frac{\partial f}{\partial y'} \right)^2 &= \left(\frac{\partial f}{\partial x} \right)^2 \cos^2 \theta + \left(\frac{\partial f}{\partial y} \right)^2 \sin^2 \theta + \left(\frac{\partial f}{\partial x} \right)^2 \sin^2 \theta + \left(\frac{\partial f}{\partial y} \right)^2 \cos^2 \theta \\ &= \left[\left(\frac{\partial f}{\partial x} \right)^2 + \left(\frac{\partial f}{\partial y} \right)^2 \right] (\cos^2 \theta + \sin^2 \theta) \\ &= \left[\left(\frac{\partial f}{\partial x} \right)^2 + \left(\frac{\partial f}{\partial y} \right)^2 \right] \cdot 2 \end{aligned}$$

Demo 20: rotation invariance of Laplacian

$$\frac{\partial^2 z}{\partial x'^2} = \left(\frac{\partial z}{\partial x}\right)^2 \cos^2 \theta + \frac{\partial^2 z}{\partial x \partial y} \cos \theta \sin \theta + \frac{\partial^2 z}{\partial y^2} \sin^2 \theta + \frac{\partial z}{\partial y} \cos \theta + \frac{\partial z}{\partial x} \sin \theta$$

Demo 21: SNR

$$SNR = \frac{A \left| \int_{-\infty}^{\infty} f(x) dx \right|}{n_0 \sqrt{\int_{-\infty}^{\infty} f(x)^2 dx}}$$

$$\frac{G(x) + m(x)}{f} \rightarrow H(x)$$

key identity, complete output of $G(x)$ and of $m(x)$ synchronously:

$$H_c(x) = G(x) * f(x) = \int_{-\infty}^{\infty} G(x-u) f(u) du = A \int_{-\infty}^{\infty} f(u) du$$

$$S_{H_c}(x) = |H_c(x)| = A \left| \int_{-\infty}^{\infty} f(u) du \right|$$

$$S_{H_m}(\omega) = \mathcal{F}(\rho_{H_m}(\tau)) \text{ by W-K}$$

$$= S_m(\omega) \cdot |F(\omega)|^2 \text{ for LTI system}$$

$$\rho_{H_m}(\tau) = \rho_{nn}(\tau) \cdot \mathcal{F}^{-2}(|F(\omega)|^2)$$

$$\mathcal{F}(\omega) \cdot \mathcal{F}(\omega)^* = \delta(\tau) \text{ by 11}$$

$$f(\tau) * f(-\tau)$$

$$= \rho_{nn}(\tau) * f(\tau) * f(-\tau)$$

$$= \tau^2 * f(0) * f(0) = \tau^2 \int_{-\infty}^{\infty} f(u)^2 du$$

$$S_{H_m}(x) = n_0 \sqrt{\int_{-\infty}^{\infty} f^2(u) du}$$

$$SNR = \frac{A \left| \int_{-\infty}^{\infty} f(u) du \right|}{n_0 \sqrt{\int_{-\infty}^{\infty} f^2(u) du}}$$

Demo 22: ...

Demo 22: LOC

No noise : $H_b(0)$ mean and $H_b'(0) = 0$

Noise : $H_b'(x_0) + H_m'(x_0) = 0 \Rightarrow H_b'(x_0) = -H_m'(x_0)$

Taylor : $H_b'(x_0) = H_b'(0) + x_0 H_b''(0)$
 $= x_0 H_b''(0)$

$$x_0 = \frac{H_b'(x_0)}{H_b''(0)} = \frac{-H_m'(x_0)}{H_b''(0)}$$

$$\begin{cases} E[H_m'(x_0)^2] = m_0^2 \int_{-\infty}^{+\infty} f'^2(x) dx \\ H_b''(0) = \left(\int_{-\infty}^{+\infty} b'(-x) f'(x) dx \right)^2 \end{cases}$$

$$E(x_0^2) = \frac{m_0^2 \int_{-\infty}^{+\infty} f'^2(x) dx}{\left(\int_{-\infty}^{+\infty} b'(-x) f'(x) dx \right)^2} \rightarrow LOC = \frac{1}{E(x_0)^2}$$

Demo 23: $(A \oplus B)^c = (A^c \oplus B)$

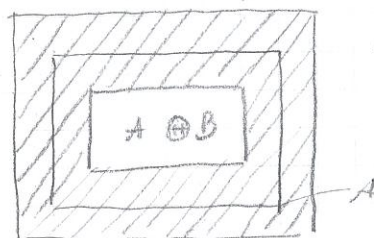
$$(A \oplus B)^c = \{x : B_x \subseteq A\}^c$$

$$y B_x \subseteq A \Rightarrow B_x \cap A^c = \emptyset \Rightarrow (A \oplus B)^c = \{x : B_x \cap A^c = \emptyset\}^c$$

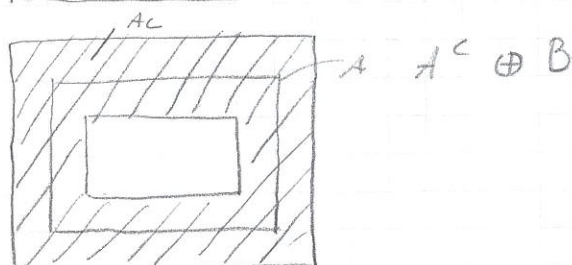
complement of $(B_x \cap A^c = \emptyset) = (B_x \cap A^c \neq \emptyset)$

$$(A \oplus B)^c = \{x : B_x \cap A^c = \emptyset\}^c = \{x : B_x \cap A^c \neq \emptyset\} = A^c \oplus B$$

[B]



// $(A \oplus B)^c$



+ demo une loi de LUT de logique avec les log!

Demo 24: properties of tilts

$$g(t) = f(t) e^{j\omega_0 t}$$

$$\begin{aligned}\mathcal{F}(g(t)) &= \int g(t) e^{-j\omega t} dt = \int f(t) e^{j\omega_0 t} e^{-j\omega t} dt \\ &= \int f(t) e^{-j(\omega - \omega_0)t} dt \\ &= F(\omega - \omega_0)\end{aligned}$$

