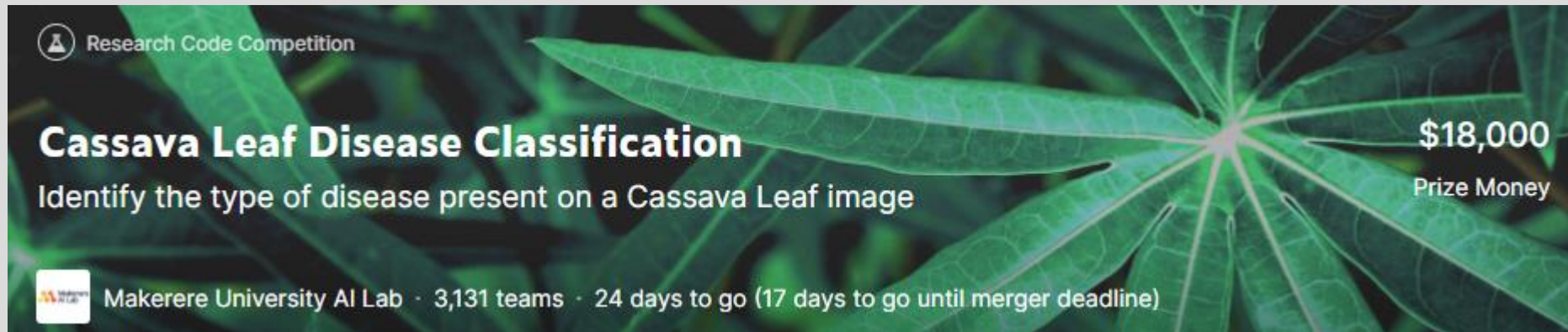




# Cassava Leaf Disease Classification

수학과 오서영

# Overview



## Introduction

**Cassava** is a key food security crop in Africa

But **viral diseases** are major sources of poor yields.

Existing methods of disease detection require experts to visually inspect and diagnose the plants -> labor-intensive, low-supply and costly.

So I want to solve this problem through **data science**.

-> classify each cassava image into **5** category

# 1. Data Exploration and Visualization

```
BASE_DIR = os.getcwd()
with open(os.path.join(BASE_DIR, "label_num_to_disease_map.json")) as file:
    map_classes = json.loads(file.read())
    map_classes = {int(k) : v for k, v in map_classes.items()}

print(json.dumps(map_classes, indent=4))

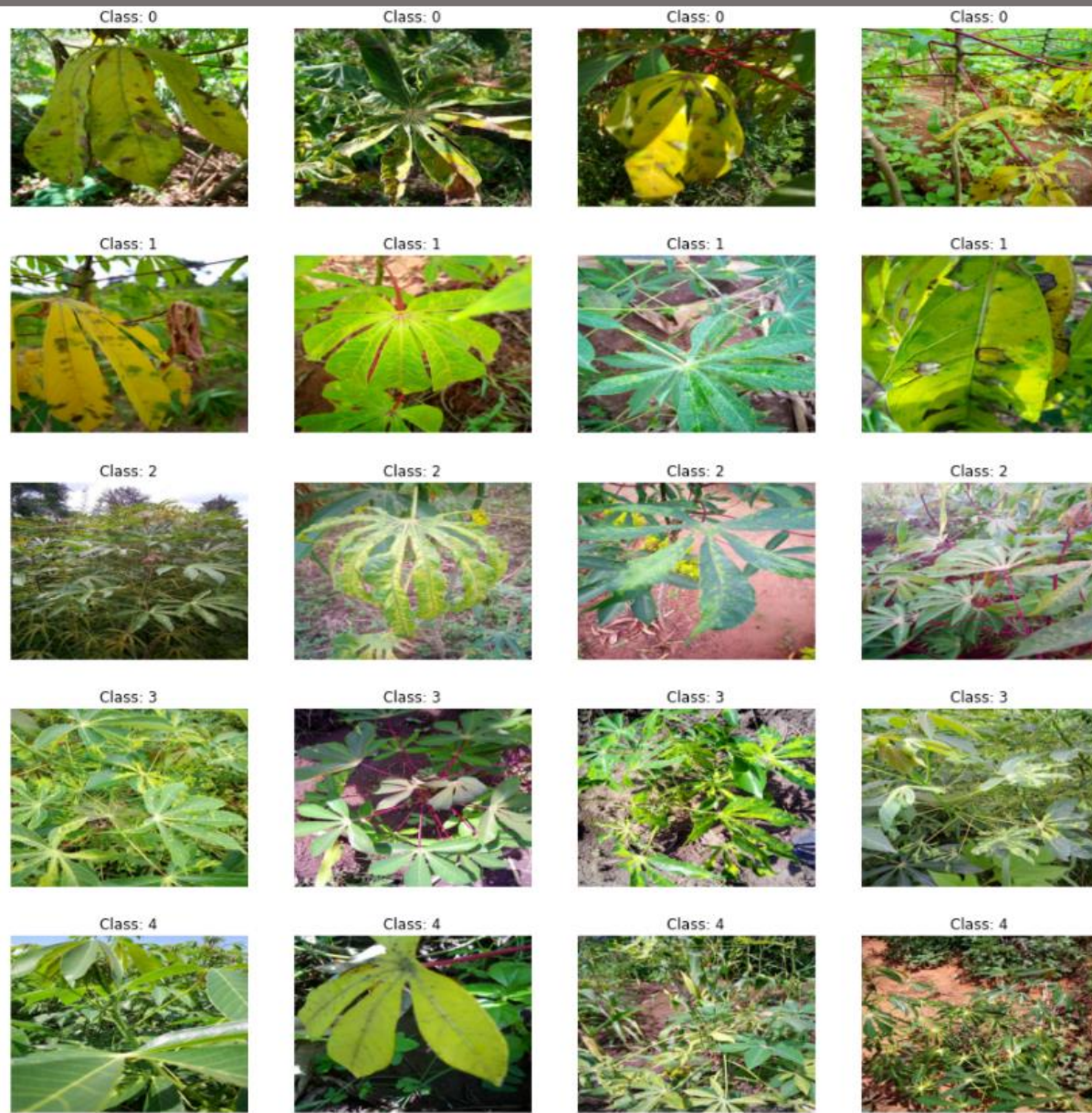
{
  "0": "Cassava Bacterial Blight (CBB)",
  "1": "Cassava Brown Streak Disease (CBSD)",
  "2": "Cassava Green Mottle (CGM)",
  "3": "Cassava Mosaic Disease (CMD)",
  "4": "Healthy"
}
```

```
img_shapes = {}
for image_name in os.listdir(os.path.join(BASE_DIR, "train_images"))[:300]:
    image = cv2.imread(os.path.join(BASE_DIR, "train_images", image_name))
    img_shapes[image.shape] = img_shapes.get(image.shape, 0) + 1

print(img_shapes)

{(600, 800, 3): 300}
```

# 1. Data Exploration and Visualization

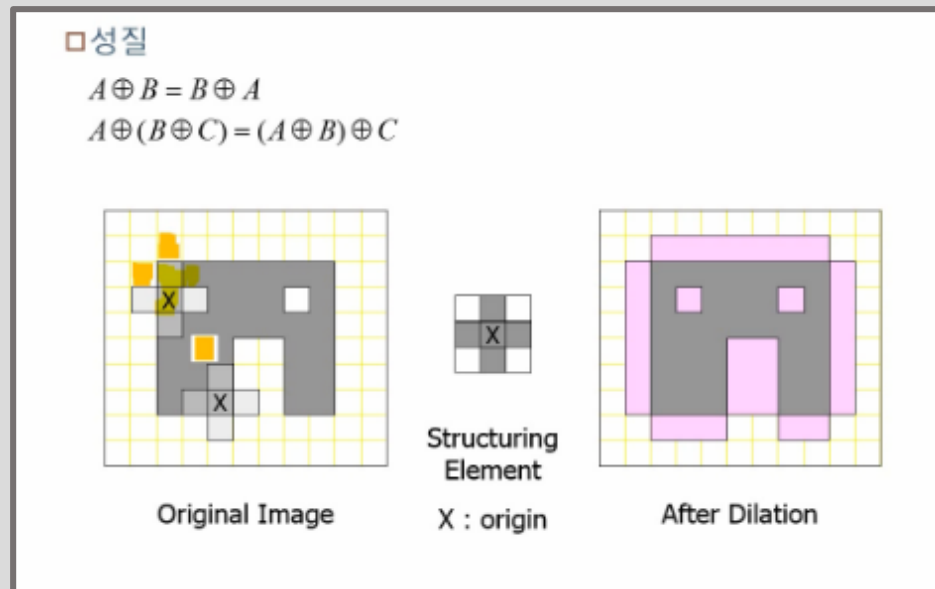
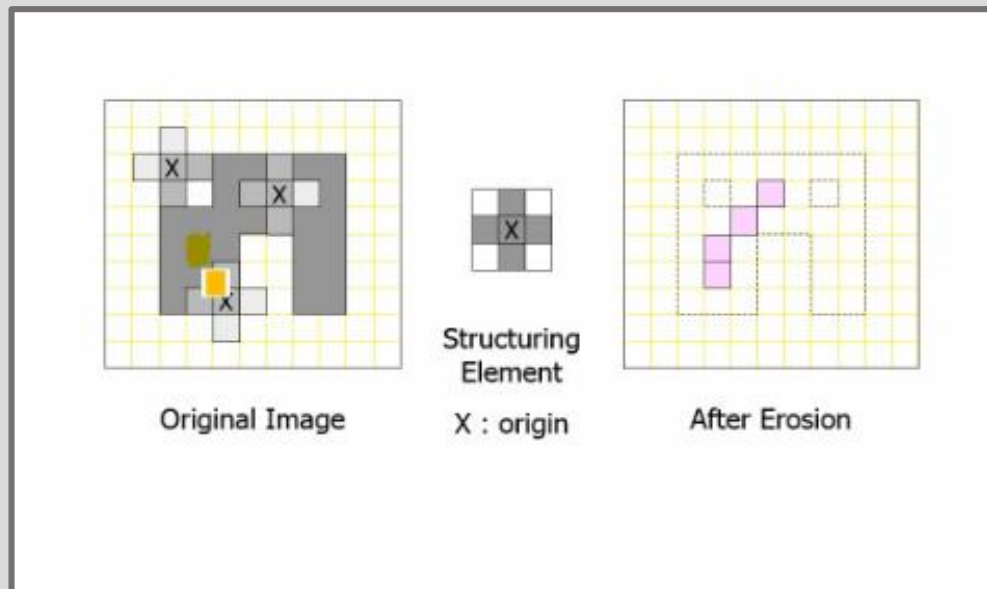


```
input_files = os.listdir(os.path.join(BASE_DIR, "train_images"))  
print(f"Number of train images: {len(input_files)}")
```

Number of train images: 21397

## 2. Data Preprocessing

### Segmentation with Opencv



### Erosion

: 각 Pixel에 structuring element를 적용하여 안겹치는 부분이 하나라도 있으면 그 중심 pixel을 제거하는 방법

### Dilation

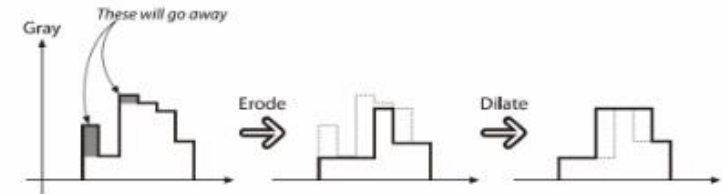
: 각 pixel에 structuring element를 적용하여 겹치는 부분이 하나라도 있으면 이미지를 확장



## 2. Data Preprocessing

### Segmentation with Opencv

```
def read_image(image_id , label):  
    plt.figure(figsize=(15, 10))  
    image = cv2.imread(os.path.join(BASE_DIR, "train_images", image_id))  
  
    return image  
  
def create_masks(image):  
    image_hsv = cv2.cvtColor(image, cv2.COLOR_BGR2HSV)  
    lower_hsv = np.array([0,0,250])  
    upper_hsv = np.array([250,255,255])  
  
    mask = cv2.inRange(image_hsv, lower_hsv, upper_hsv)  
    kernel = cv2.getStructuringElement(cv2.MORPH_ELLIPSE, (11,11))  
    mask = cv2.morphologyEx(mask, cv2.MORPH_CLOSE, kernel)  
    return mask  
  
def segment_image(image):  
    mask = create_masks(image)  
    output = cv2.bitwise_and(image, image, mask=mask)  
    return output/255
```



*Morphological opening operation*

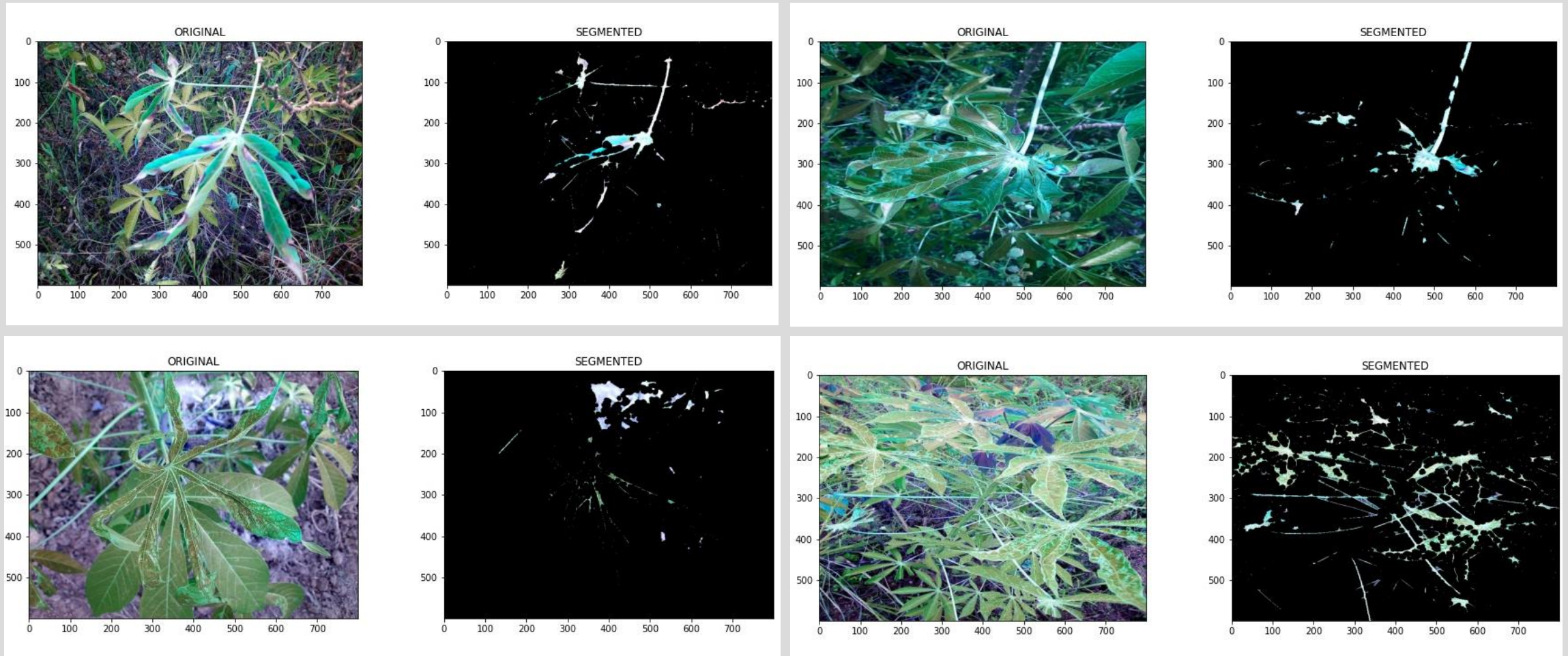


*Morphological closing operation*

### Opening & Closing

## 2. Data Preprocessing

Segmentation -> **X**



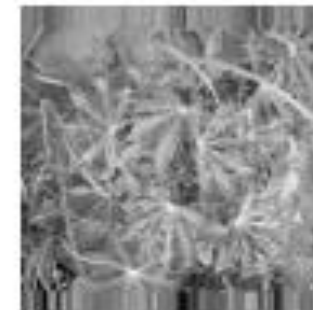
## 2. Data Preprocessing

### Image Augmentation + Grayscale

```
train_labels.label = train_labels.label.astype('str')

train_datagen = ImageDataGenerator(validation_split = 0.2,
                                    rescale = 1./255,
                                    zoom_range = 0.2,
                                    horizontal_flip = True,
                                    shear_range = 0.1)

train_generator = train_datagen.flow_from_dataframe(train_labels,
                                                    directory = os.path.join(BASE_DIR, "train_images"),
                                                    subset = "training",
                                                    x_col = "image_id",
                                                    y_col = "label",
                                                    target_size = (target_size, target_size),
                                                    batch_size = batch_size,
                                                    color_mode = 'grayscale',
                                                    class_mode = "categorical")
```





### 3. Training – Vanilla CNN

```
model = Sequential()
model.add(Conv2D(64, kernel_size=(3, 3), strides=(1, 1), padding='same',
                activation='relu',
                input_shape=(32, 32, 3)))
model.add(MaxPooling2D(pool_size=(2, 2)))

model.add(Conv2D(32, (3, 3), activation='relu', padding='same'))
model.add(MaxPooling2D(pool_size=(2, 2)))
model.add(Dropout(0.25))

model.add(Flatten())
model.add(Dense(256, activation='relu'))
model.add(Dropout(0.5))

model.add(Dense(num_classes, activation='softmax'))
model.summary()
```

**Test accuracy**  
less than 60%

Layer (type)	Output Shape	Param #
=====		
conv2d_2 (Conv2D)	(None, 32, 32, 64)	1792
max_pooling2d_2 (MaxPooling2D)	(None, 16, 16, 64)	0
conv2d_3 (Conv2D)	(None, 16, 16, 32)	18464
max_pooling2d_3 (MaxPooling2D)	(None, 8, 8, 32)	0
dropout_2 (Dropout)	(None, 8, 8, 32)	0
flatten_1 (Flatten)	(None, 2048)	0
dense_1 (Dense)	(None, 256)	524544
dropout_3 (Dropout)	(None, 256)	0
dense_2 (Dense)	(None, 5)	1285
=====		
Total params: 546,085		
Trainable params: 546,085		
Non-trainable params: 0		

### 3. Training - EfficientNet

The traditional way to improve CNN performance  
: increase the depth of model

-> **EfficientNet**

: consider not only **depth**  
but also **width** and **resolution** together

Information :  $128 \times 128 > 64 \times 64$ .

But high-resolution input can result in a large calculation cost,

and does not provide a significant benefit to model performance after certain values.

-> **Balancing** the width, depth, and resolution of a network is very important for improving performance.

Stage $i$	Operator $\hat{\mathcal{F}}_i$	Resolution $\hat{H}_i \times \hat{W}_i$	#Channels $\hat{C}_i$	#Layers $\hat{L}_i$
1	Conv3x3	$224 \times 224$	32	1
2	MBConv1, k3x3	$112 \times 112$	16	1
3	MBConv6, k3x3	$112 \times 112$	24	2
4	MBConv6, k5x5	$56 \times 56$	40	2
5	MBConv6, k3x3	$28 \times 28$	80	3
6	MBConv6, k5x5	$14 \times 14$	112	3
7	MBConv6, k5x5	$14 \times 14$	192	4
8	MBConv6, k3x3	$7 \times 7$	320	1
9	Conv1x1 & Pooling & FC	$7 \times 7$	1280	1

**Quantitative Analysis**

### 3. Training - EfficientNet

```
early_stopping = EarlyStopping(monitor='val_accuracy', patience=5)
mc = ModelCheckpoint('best_model.h5', monitor='val_loss', mode='min', save_best_only=True)
```

```
model = Sequential()
optimizer = Adam(lr=0.00105)

b4model = EfficientNetB4(include_top=False,
                        weights=None,
                        pooling='avg')

model.add(b4model)
model.add(Dense(5, activation='softmax'))
model.add(Dense(256, activation='relu'))

model.summary()
```

Model: "sequential\_6"

Layer (type)	Output Shape	Param #
efficientnetb4 (Functional)	(None, 1792)	17673823
dense_11 (Dense)	(None, 5)	8965
Total params: 17,682,788		
Trainable params: 17,557,581		
Non-trainable params: 125,207		

### 3. Training - EfficientNet

```
model.compile(loss="categorical_crossentropy", optimizer=optimizer, metrics=["accuracy"])
```

```
%%time  
hist10 = model.fit(  
    train_generator,  
    steps_per_epoch = steps_per_epoch,  
    epochs = epochs,  
    validation_data = validation_generator,  
    validation_steps = validation_steps,  
    callbacks=[early_stopping, mc],  
    verbose = 1)
```

#### Test accuracy

79~81%

Training on a single epoch is extremely slow... (3 hours)

-> **GPU?**



# Kaggle Competition

**[1] Cassava Leaf Disease Classification,**

<https://www.kaggle.com/c/cassava-leaf-disease-classification/overview>

## References

**[1] The shortest way to Tensorflow baseline,**

<https://www.kaggle.com/nozarchos/the-shortest-way-to-tensorflow-baseline>

**[2] Tensorflow ViT and Image Pre-processing,**

<https://www.kaggle.com/digvijayyadav/tensorflow-vit-and-image-pre-processing>

**[3] Convolutional Neural Network의 성능을 높이는 현명한 방법 : EfficientNet Google AI,**

<https://ichi.pro/ko/convolutional-neural-networkui-seongneung-eul-nop-ineun-hyeonmyeonghan-bangbeob-efficientnet-google-ai-220426838454404>