# Learning representations by back-propagating errors

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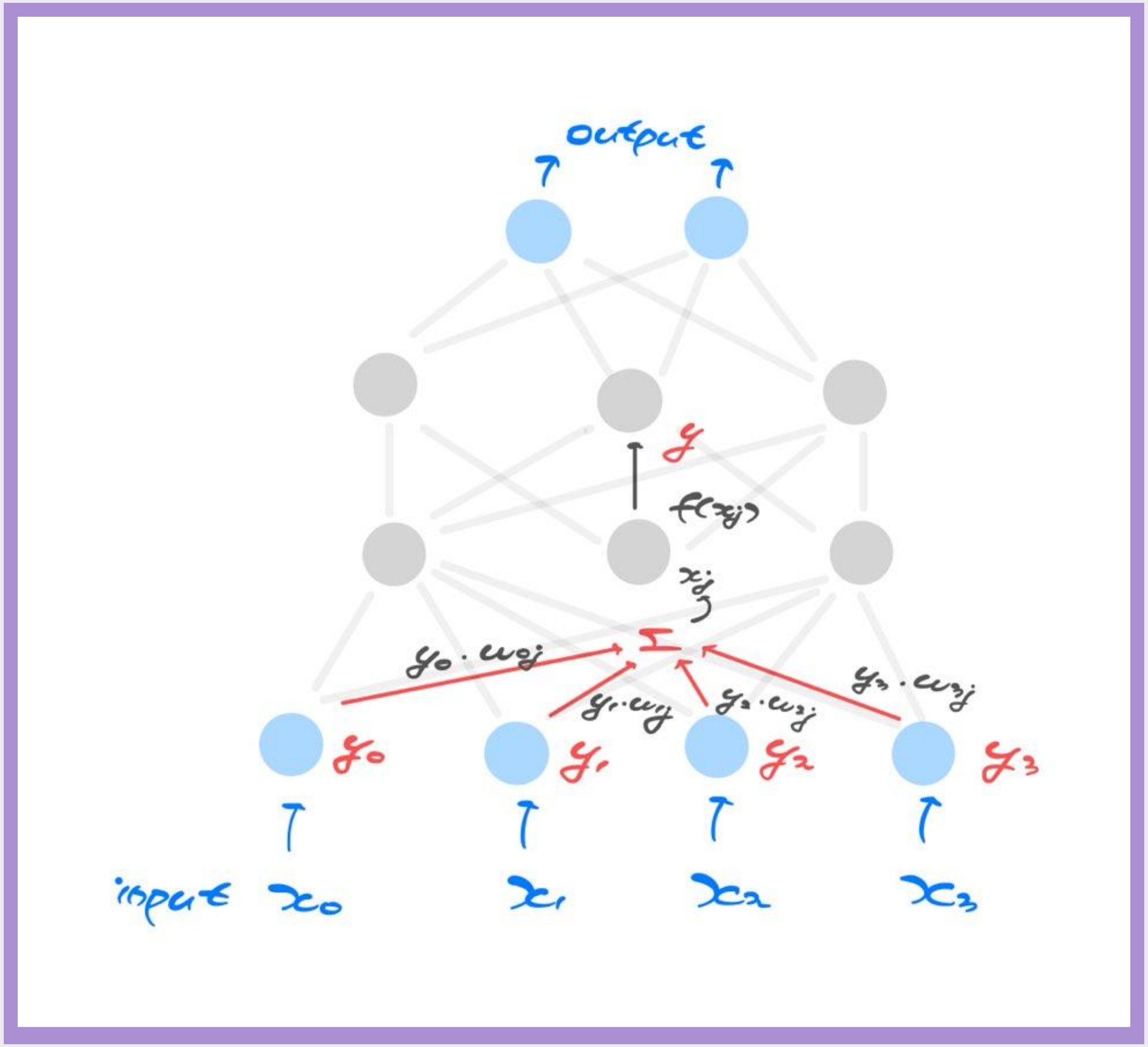
# Neural Network



# Back-propagation

**If input units are directly connected to the output units**

-> easy to find learning rules
(iteratively adjust the relative strengths)
-> progressively reduce the difference
between the actual and desired output

**Hidden units**

-> Learning procedure decides under what
circumstances the hidden units should be active in order to achieve the desired input-output
-> Hidden units are going to learn to represent some features of input domain
-> **Back propagation**

# Feed Forward

**Input $x_j$**

-> input of higher layer will be a weighted sum of the outputs of all of the lower layer units that feed into it
-> i feeds into j

**Output $y_i$**
**Adjusted by a weight on the link between i and j** $w_{ij}$

$$x_j = \sum y_i w_{ij}$$

# Feed Forward

**Output** $y_j$

-> **Activation function** in this paper is the **sigmoid function**

$$y_j = \frac{1}{1 + e^{-x_j}}$$

-> By repeating this procedure, starting with the **input layer**,
we can feed-forward through the network layers and arrive at a set of **outputs for the output layer**

# Error Function

The aim is to find a set of weights that ensure that
the output vector is the same as the desired output vector

-> computed output value of j in output layer $y_j$
-> its desired state $d_j$

$$E = \frac{1}{2}\sum_{j}(y_j - d_j)^2$$

-> minimize
-> need to adjust the weights

# Error Function

To minimize E by gradient descent it is necessary to compute the **partial derivative** of E with respect to each weight in the network

-> $\frac{\partial E}{\partial w}$ -> $\frac{\partial E}{\partial y_j}$ (E and y are directly related) -> $\frac{\partial y_j}{\partial x_j}$

$$\frac{\partial}{\partial y_j}\frac{1}{2}\sum_j (y_j - d_j)^2 = y_j - d_j \qquad y_j = \text{sigmoid}(x_j)$$

$$\frac{\partial y_j}{\partial x_j} = \text{sigmoid}(x_j) * (1 - \text{sigmoid}(x_j))$$

# Error Function

$$x_j = \sum y_i w_{ij}$$

-> $\frac{\partial x_j}{\partial w_{ij}} = y_i$

We can chain them together to figure out how the error changes with the weights

$$\frac{\partial E}{\partial w} = \frac{\partial E}{\partial y} * \frac{\partial y}{\partial x} * \frac{\partial x}{\partial w}$$

# Gradient Descent

Simplest form of **gradient descent** would be to change each weight by an amount proportional to the accumulated gradient

$$\Delta \mathrm{w} = -\mathrm{a} * \frac{\partial E}{\partial w}$$

# Code implementation

```
display(Math(r'x_j = \sum_{i=0}y_iw_{ij}'))
display(Math(r'y_j = \frac{1}{1+e^{-x_j}}'))
display(Math(r'E = \frac{1}{2}\sum_{j}(y_j-d_j)^2'))
display(Math(r'\frac{\partial E}{\partial y_j} = y_j - d_j'))
display(Math(r'\frac{\partial y_j}{\partial x_j} = y_j*(1-y_j)'))
display(Math(r'\frac{\partial x_j}{\partial w_{ij}} = y_i'))
```

$$x_j = \sum_{i=0} y_i w_{ij}$$

$$y_j = \frac{1}{1+e^{-x_j}}$$

$$E = \frac{1}{2}\sum_{j}(y_j-d_j)^2$$

$$\frac{\partial E}{\partial y_j} = y_j - d_j$$

$$\frac{\partial y_j}{\partial x_j} = y_j * (1-y_j)$$

$$\frac{\partial x_j}{\partial w_{ij}} = y_i$$

```
def sigmoid(xj):

    s = 1/(1+np.exp(-xj))

    return s
```

# Code implementation

```
def propagate(w, yi, yj, dj):

    m = yi.shape[1]

    yj = sigmoid(np.dot(w.T, yi))        # compute activation
    cost = 1/m*(np.sum(yj-dj))          # compute cost

    dw = 1/m*np.dot((np.dot(yi, ((yj-dj).T))), yj*(1-yj))

    cost = np.squeeze(cost)


    return dw, cost
```

# Code implementation

```
def optimize(w, yi, dj, num_iterations, learning_rate):

    costs = []

    for i in range(num_iterations):

        dw, cost = propagate(w, yi, yj, dj)

        w = w - learning_rate*dw

        if i % 1 == 0:
            costs.append(cost)

        if i % 1 == 0:
            print ("Cost after iteration %i: %f" %(i, cost))

    return w, dw, yj, costs
```

# Code implementation

```
w, yi, dj = np.array([[1.],[2.]]), np.array([[1,2,-1],[3,4,-3.2]]), np.array([[1,0,1]])
```

```
w, dw, yj, costs = optimize(w, yi, dj, num_iterations= 10, learning_rate = 0.1)

print ("w = " + str(w) + '₩n')
print ("dw = " + str(dw) + '₩n')
print("prediction = " + str(yj))
```

```
Cost after iteration 0: -0.000115
Cost after iteration 1: -0.000346
Cost after iteration 2: -0.000346
Cost after iteration 3: -0.000347
Cost after iteration 4: -0.000347
Cost after iteration 5: -0.000347
Cost after iteration 6: -0.000348
Cost after iteration 7: -0.000348
Cost after iteration 8: -0.000349
Cost after iteration 9: -0.000349
w = [[0.997439   0.99987199 0.99828173]
 [1.99385446 1.99969281 1.99587673]]

dw = [[0.00275869 0.00013821 0.0018515 ]
 [0.00661992 0.00033165 0.00444297]]

prediction = [[1 0 1]]
```