

# Reducing the Dimensionality of Data with Neural Networks

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# Overview

## **Dimensionality reduction**

- classification, visualization, communication, storage of high-dimensional data

**Goal** : use a deep neural to reduce the dimensionality of an input.

-> the reduction techniques described are compared to principal component analysis (PCA) and logistic PCA

## **PCA**

: Find the directions of greatest variance in the data set and  
Represent each data point by its coordinates along each of these directions.

# Overview

## Autoencoder

- Nonlinear generalization of PCA
- Encoder transform the high-dimensional data into a low-dimensional code
- Decoder recover the data from the code
  
- Starts with random weights in the two networks
- Trained by minimizing the discrepancy between the original data and its reconstruction.
- Gradients are obtained by the chain rule to back-propagate error from the decoder network to encoder network.

# Overview

## It is difficult to optimize multilayer autoencoder

1. With large initial weights  
: autoencoders typically find poor local minima
2. With small initial weights  
: the gradients in the early layers are tiny, making it infeasible to train autoencoders with many hidden layers
3. If initial weights are close to a good solution  
: gradient descent works well  
-> **But finding such initial weights is very difficult**

**Pretraining** procedure for binary data, generalize it to real-valued data, and show that it works well for a variety of data sets.

-> based on **Restricted Boltzmann Machine (RBM)**

# Methods

## Restricted Boltzmann Machine (RBM)

The input data correspond to **visible** units of the RBM and the feature detectors correspond to hidden units.

A joint configuration  $(\mathbf{v}, \mathbf{h})$  of the visible and hidden units has an **energy**  
The network assigns a probability to every possible data via this energy function

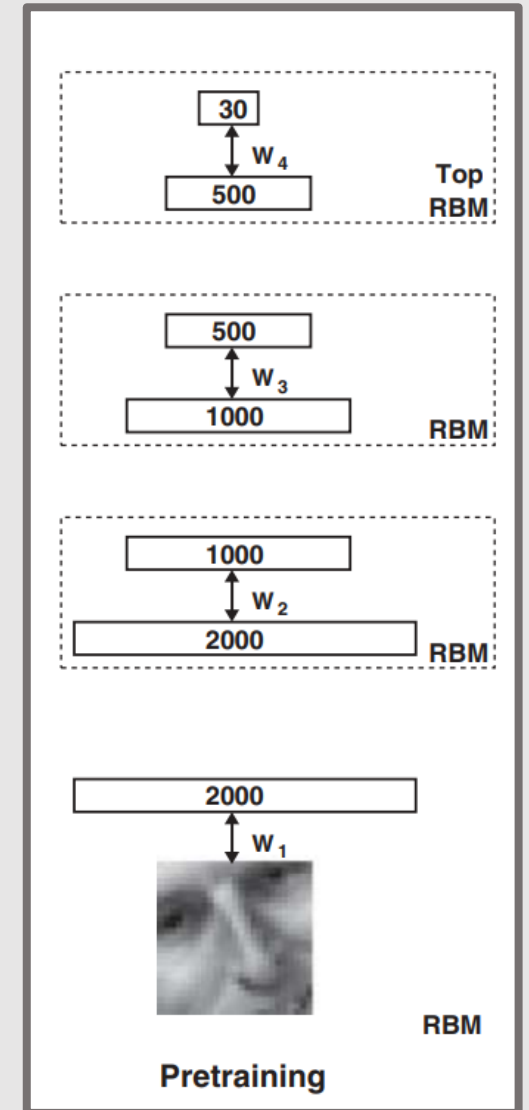
$$E(\mathbf{v}, \mathbf{h}) = - \sum_{i \in \text{pixels}} b_i v_i - \sum_{j \in \text{features}} b_j h_j - \sum_{i,j} v_i h_j w_{ij}$$

# Methods

Training a large neural network through greedy layer-wise pretraining

He took an input (50\*50 images), and trained a RBM to reduce the feature space of the image.

Each set of weights are learned individually, so in the first step,  $W_1$  is learned and once  $W_1$  is learned, the data is then all restored as the result of the first transfer and  $W_2$  is learned, and so on.



# Methods

RBM is generative models, so the weights are bidirectional.  
-> activation in layer two can be used to generate a corresponding set of activations in layer one.

The weights between the layers are effectively re-used to map the data back to its original dimensionality.

-> the input weights for a NN that can be trained with backpropagation to fine-tune the weights using the input weights as the outputs to the network

**Code layer** : used for classification, regression, clustering, etc.

