

Package ‘DeepPatientLevelPrediction’

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Type Package

Title Deep Learning For Patient Level Prediction Using Data In The OMOP Common Data Model

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Description A package for creating deep learning patient level prediction models following the OHDSI PatientLevelPrediction framework.

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URL <https://ohdsi.github.io/PatientLevelPrediction>, <https://github.com/OHDSI/DeepPatientLevelPrediction>

BugReports <https://github.com/OHDSI/DeepPatientLevelPrediction/issues>

VignetteBuilder knitr

Depends R (>= 3.5.0)

Imports dplyr,
data.table,
FeatureExtraction (>= 3.0.0),
ParallelLogger (>= 2.0.0),
PatientLevelPrediction,
rlang,
torch (>= 0.8.0)

Suggests devtools,
Eunomia,
knitr,
markdown,
plyr,
testthat

Remotes ohdsi/PatientLevelPrediction@develop,
ohdsi/FeatureExtraction,
ohdsi/Eunomia

RoxygenNote 7.2.1

Encoding UTF-8

Config/testthat/edition 3

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Dataset	<i>A torch dataset</i>
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Description

A torch dataset

Usage

Dataset(data, labels = NULL, numericalIndex = NULL)

Arguments

- data a dataframe like object with the covariates
- labels a dataframe with the labels
- numericalIndex in what column numeric data is in (if any)
- all if True then returns all features instead of splitting num/cat

DeepPatientLevelPrediction
<i>DeepPatientLevelPrediction</i>

Description

A package containing deep learning extensions for developing prediction models using data in the OMOP CDM

EarlyStopping

Earlystopping class

Description

Stops training if a loss or metric has stopped improving

Methods

Public methods:

- `EarlyStopping$new()`
- `EarlyStopping$call()`
- `EarlyStopping$clone()`

Method `new()`: Creates a new earlystopping object

Usage:

```
EarlyStopping$new(patience = 3, delta = 0, verbose = TRUE)
```

Arguments:

`patience` Stop after this number of epochs if loss doesn't improve

`delta` How much does the loss need to improve to count as improvement

`verbose` If information should be printed out

Returns: a new earlystopping object

Method `call()`: call the earlystopping object and increment a counter if loss is not improving

Usage:

```
EarlyStopping$call(metric)
```

Arguments:

`metric` the current metric value

Method `clone()`: The objects of this class are cloneable with this method.

Usage:

```
EarlyStopping$clone(deep = FALSE)
```

Arguments:

`deep` Whether to make a deep clone.

Estimator

Estimator

Description

A generic R6 class that wraps around a torch nn module and can be used to fit and predict the model defined in that module.

Methods

Public methods:

- `Estimator$new()`
- `Estimator$fit()`
- `Estimator$fitEpoch()`
- `Estimator$score()`
- `Estimator$finishFit()`
- `Estimator$fitWholeTrainingSet()`
- `Estimator$save()`
- `Estimator$predictProba()`
- `Estimator$predict()`
- `Estimator$batchToDevice()`
- `Estimator$itemOrDefaults()`
- `Estimator$clone()`

Method `new()`: Creates a new estimator

Usage:

```
Estimator$new(
  baseModel,
  modelParameters,
  fitParameters,
  optimizer = torch::optim_adam,
  criterion = torch::nn_bce_with_logits_loss,
  scheduler = torch::lr_reduce_on_plateau,
  device = "cpu",
  patience = 4
)
```

Arguments:

`baseModel` The torch nn module to use as model

`modelParameters` Parameters to initialize the `baseModel`

`fitParameters` Parameters required for the estimator fitting

`optimizer` A torch optimizer to use, default is Adam

`criterion` The torch loss function to use, defaults to binary cross entropy with logits

`scheduler` learning rate scheduler to use

device Which device to use for fitting, default is cpu
patience Patience to use for early stopping

Method fit(): fits the estimator

Usage:

Estimator\$fit(dataset, testDataset)

Arguments:

dataset a torch dataset to use for model fitting
testDataset a torch dataset to use for early stopping

Method fitEpoch(): fits estimator for one epoch (one round through the data)

Usage:

Estimator\$fitEpoch(dataset, batchIndex)

Arguments:

dataset torch dataset to use for fitting
batchIndex indices of batches

Method score(): calculates loss and auc after training for one epoch

Usage:

Estimator\$score(dataset, batchIndex)

Arguments:

dataset The torch dataset to use to evaluate loss and auc
batchIndex Indices of batches in the dataset

Returns: list with average loss and auc in the dataset

Method finishFit(): operations that run when fitting is finished

Usage:

Estimator\$finishFit(valAUCs, modelStateDict, valLosses, epoch, learnRates)

Arguments:

valAUCs validation AUC values
modelStateDict fitted model parameters
valLosses validation losses
epoch list of epochs fit
learnRates learning rate sequence used so far

Method fitWholeTrainingSet(): Fits whole training set on a specific number of epochs
TODO What happens when learning rate changes per epochs? Ideally I would copy the learning rate strategy from before and adjust for different sizes ie more iterations/updates???

Usage:

Estimator\$fitWholeTrainingSet(dataset, learnRates = NULL)

Arguments:

dataset torch dataset

learnRates learnRateSchedule from CV

Method save(): save model and those parameters needed to reconstruct it

Usage:

Estimator\$save(path, name)

Arguments:

path where to save the model

name name of file

Returns: the path to saved model

Method predictProba(): predicts and outputs the probabilities

Usage:

Estimator\$predictProba(dataset)

Arguments:

dataset Torch dataset to create predictions for

Returns: predictions as probabilities

Method predict(): predicts and outputs the class

Usage:

Estimator\$predict(dataset, threshold = NULL)

Arguments:

dataset A torch dataset to create predictions for

threshold Which threshold to use for predictions

Returns: The predicted class for the data in the dataset

Method batchToDevice(): sends a batch of data to device assumes batch includes lists of tensors to arbitrary nested depths

Usage:

Estimator\$batchToDevice(batch)

Arguments:

batch the batch to send, usually a list of torch tensors

Returns: the batch on the required device

Method itemOrDefaults(): select item from list, and if it's null sets a default

Usage:

Estimator\$itemOrDefaults(list, item, default = NULL)

Arguments:

list A list with items

item Which list item to retrieve

default The value to return if list doesn't have item

Returns: the list item or default

Method clone(): The objects of this class are cloneable with this method.

Usage:

```
Estimator$clone(deep = FALSE)
```

Arguments:

deep Whether to make a deep clone.

fitEstimator	<i>fitEstimator</i>
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Description

fits a deep learning estimator to data.

Usage

```
fitEstimator(trainData, modelSettings, analysisId, ...)
```

Arguments

trainData	the data to use
modelSettings	modelSettings object
analysisId	Id of the analysis
...	Extra inputs

gridCvDeep	<i>gridCvDeep</i>
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Description

Performs grid search for a deep learning estimator

Usage

```
gridCvDeep(mappedData, labels, settings, modelLocation, paramSearch)
```

Arguments

mappedData	Mapped data with covariates
labels	Dataframe with the outcomes
settings	Settings of the model
modelLocation	Where to save the model
paramSearch	model parameters to perform search over

predictDeepEstimator	<i>predictDeepEstimator</i>
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Description

the prediction function for the estimator

Usage

```
predictDeepEstimator(plpModel, data, cohort)
```

Arguments

plpModel	the plpModel
data	plp data object or a torch dataset
cohort	data.frame with the rowIds of the people

setEstimator	<i>setEstimator</i>
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Description

creates settings for the Estimator, which takes a model and trains it

Arguments

learningRate	what learning rate to use
weightDecay	what weight_decay to use
optimizer	which optimizer to use
scheduler	which learning rate scheduler to use
criterion	loss function to use
posWeight	If more weight should be added to positive labels during training - will result in miscalibrated models
earlyStopping	If earlyStopping should be used which stops the training of your metric is not improving
earlyStoppingMetric	Which parameter to use for early stopping
patience	patience for earlyStopper
hyperparameterMetric	which metric to use for hyperparameter, loss, auc, auprc or a custom function

```
setMultiLayerPerceptron
    setMultiLayerPerceptron
```

Description

Creates settings for a Multilayer perceptron model

Usage

```
setMultiLayerPerceptron(
    numLayers = c(1:8),
    sizeHidden = c(2^(6:9)),
    dropout = c(seq(0, 0.5, 0.05)),
    sizeEmbedding = c(2^(6:9)),
    weightDecay = c(1e-06, 0.001),
    learningRate = c(0.01, 3e-04, 1e-05),
    seed = NULL,
    hyperParamSearch = "random",
    randomSample = 100,
    device = "cpu",
    batchSize = 1024,
    epochs = 30
)
```

Arguments

numLayers	Number of layers in network, default: 1:16
sizeHidden	Amount of neurons in each default layer, default: 2^(6:10) (64 to 1024)
dropout	How much dropout to apply after first linear, default: seq(0, 0.3, 0.05)
sizeEmbedding	Size of embedding layer, default: 2^(6:9) (64 to 512)
weightDecay	Weight decay to apply, default: c(1e-6, 1e-3)
learningRate	Learning rate to use. default: c(1e-2, 1e-5)
seed	Seed to use for sampling hyperparameter space
hyperParamSearch	Which kind of hyperparameter search to use random sampling or exhaustive grid search. default: 'random'
randomSample	How many random samples from hyperparameter space to use
device	Which device to run analysis on, either 'cpu' or 'cuda', default: 'cpu'
batchSize	Size of batch, default: 1024
epochs	Number of epochs to run, default: 10

Details

Model architecture

setResNet

*setResNet***Description**

Creates settings for a ResNet model

Usage

```
setResNet(
  numLayers = c(1:8),
  sizeHidden = c(2^(6:9)),
  hiddenFactor = c(1:4),
  residualDropout = c(seq(0, 0.5, 0.05)),
  hiddenDropout = c(seq(0, 0.5, 0.05)),
  sizeEmbedding = c(2^(6:9)),
  weightDecay = c(1e-06, 0.001),
  learningRate = c(0.01, 3e-04, 1e-05),
  seed = NULL,
  hyperParamSearch = "random",
  randomSample = 100,
  device = "cpu",
  batchSize = 1024,
  epochs = 30
)
```

Arguments

numLayers	Number of layers in network, default: 1:16
sizeHidden	Amount of neurons in each default layer, default: 2^(6:10) (64 to 1024)
hiddenFactor	How much to grow the amount of neurons in each ResLayer, default: 1:4
residualDropout	How much dropout to apply after last linear layer in ResLayer, default: seq(0, 0.3, 0.05)
hiddenDropout	How much dropout to apply after first linear layer in ResLayer, default: seq(0, 0.3, 0.05)
sizeEmbedding	Size of embedding layer, default: 2^(6:9) (64 to 512)
weightDecay	Weight decay to apply, default: c(1e-6, 1e-3)
learningRate	Learning rate to use. default: c(1e-2, 1e-5)
seed	Seed to use for sampling hyperparameter space
hyperParamSearch	Which kind of hyperparameter search to use random sampling or exhaustive grid search. default: 'random'
randomSample	How many random samples from hyperparameter space to use

device	Which device to run analysis on, either 'cpu' or 'cuda', default: 'cpu'
batchSize	Size of batch, default: 1024
epochs	Number of epochs to run, default: 10

Details

Model architecture from by <https://arxiv.org/abs/2106.11959>

setTransformer	<i>create settings for training a non-temporal transformer</i>
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Description

A transformer model

Usage

```
setTransformer(
  numBlocks = 3,
  dimToken = 96,
  dimOut = 1,
  numHeads = 8,
  attDropout = 0.25,
  ffnDropout = 0.25,
  resDropout = 0,
  dimHidden = 512,
  weightDecay = 1e-06,
  learningRate = 3e-04,
  batchSize = 1024,
  epochs = 10,
  device = "cpu",
  hyperParamSearch = "random",
  randomSamples = 100,
  seed = NULL
)
```

Arguments

numBlocks	number of transformer blocks
dimToken	dimension of each token (embedding size)
dimOut	dimension of output, usually 1 for binary problems
numHeads	number of attention heads
attDropout	dropout to use on attentions
ffnDropout	dropout to use in feedforward block
resDropout	dropout to use in residual connections

dimHidden	dimension of the feedforward block
weightDecay	weightdecay to use
learningRate	learning rate to use
batchSize	batchSize to use
epochs	How many epochs to run the model for
device	Which device to use, cpu or cuda
hyperParamSearch	what kind of hyperparameter search to do, default 'random'
randomSamples	How many samples to use in hyperparameter search if random
seed	Random seed to use

Details

from <https://arxiv.org/abs/2106.11959>

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