



Introduction: Sensing & Actuation

Dr. Sudip Misra

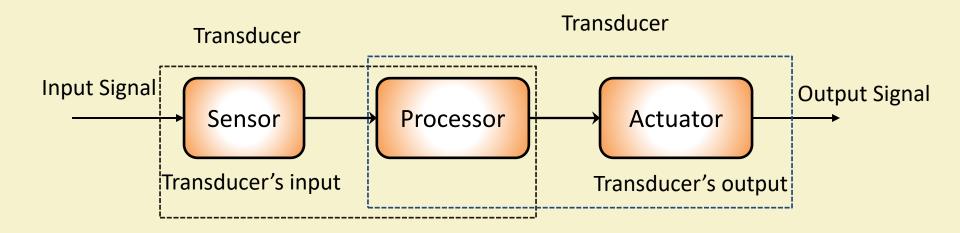
Professor

Department of Computer Science and Engineering Indian Institute of Technology Kharagpur

Email: smisra@sit.iitkgp.ernet.in

Website: http://cse.iitkgp.ac.in/~smisra/
Research Lab: cse.iitkgp.ac.in/~smisra/swan/

Transducer



Source: "Sensor" Online: https://ielm.ust.hk/dfaculty/ajay/courses/alp/ieem110/lecs/sensors/sensors.html





Transducer (Contd.)

- > Transducer:
 - > Converts a signal from one physical form to another physical form
 - Physical form: thermal, electric, mechanical, magnetic, chemical, and optical
 - > Energy converter
 - > Example:
 - ➤ Microphone : Converts sound to electrical signal
 - > Speaker : Converts electrical signal to sound
 - > Antenna: Converts electromagnetic energy into electricity and vice versa
 - > Strain gauge : Converts strain to electrical





Definition of Sensor

- The characteristic of any device or material to detect the presence of a particular <u>physical quantity</u>
- ➤ The output of sensor is signal, which is converted to human readable form



Sensor

- Performs some function of input by sensing or feeling the physical changes in the characteristic of a system in response to <u>stimuli</u>
- > Input: Physical parameter or stimuli
 - Example: Temperature, light, gas, pressure, and sound
- Output: Response to stimuli



Sensor (Contd.)



Temperature and Humidity sensor - DH22



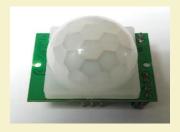
Gas (LPG, CH4, and CO) detector sensor - MQ-5



Ultrasonic sensor - HC-SR04



CMOS Camera



PIR sensor



Rain detector sensor



Fire detector sensor





Sensor Characteristics

- Static characteristics
 - ➤ After steady state condition, how the output of a sensor change in response to an input change
- Dynamic characteristics
 - > The properties of the system's transient response to an input



Static characteristics

Accuracy

- Represents the <u>correctness</u> of the output compared to a superior system
- > The different between the standard and the measured value

Range

- > Gives the highest and the lowest value of the physical quantity within which the sensor can actually sense
- > Beyond this value there is no sensing or no kind of response





Static Characteristics (Contd.)

> Resolution

- Provides the <u>smallest change</u> in the input that a sensor is capable of sensing
- Resolution is an important specification towards selection of sensors.
- ➤ Higher the resolution better the precision

> Errors

➤ The difference between the standard value and the value produced by sensor





Static Characteristics (Contd.)

- Sensitivity
 - > Sensitivity indicates ratio of <u>incremental change in the response of</u> the system with respect to incremental change in input parameter.
 - > It can be found from slope of output characteristic curve of a sensor
- > Linearity
 - > The deviation of sensor value curve from a particular straight line



Sensor Characteristics (Contd.)

- > Drift
 - The difference in the measurements of sensor from a specific reading when kept at that value for a long period of time
- Repeatability
 - ➤ The deviation between measurements in a sequence under same conditions

Source: "Sensor", Hong Kong University of Science and Technology, online: https://ielm.ust.hk/dfaculty/ajay/courses/alp/ieem110/lecs/sensors/sensors.html Source: "Repeatability", MIT, Online: https://ocw.mit.edu/courses/mechanical-engineering/2-693-principles-of-oceanographic-instrument-systems-sensors-and-measurements-13-998-spring-2004/





Dynamic Characteristics

How well a sensor responds to changes in its input

- Zero order system
 - Output shows a response to the input signal with no delay
 - Does not include energy-storing elements
 - > Example: Potentiometer measures linear and rotary displacements

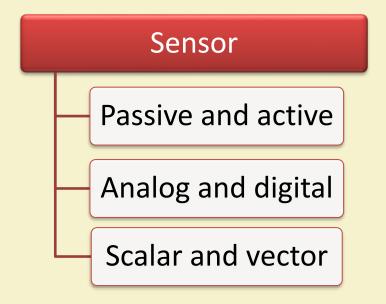


Dynamic Characteristics (Contd.)

- > First order system
 - > When the <u>output approaches its final value gradually</u>
 - > Consists of an energy storage and dissipation element
- Second order system
 - Complex output response
 - > The output response of sensor oscillates before steady state



Sensor Classification







Passive Sensor

- > Cannot independently sense the input
- Example: Accelerometer, soil moisture, water-level, and temperature sensors



Active Sensor

- > Independently sense the input
- Example: Radar, sounder, and laser altimeter sensors



Analog Sensor

- The response or output of the sensor is some <u>continuous</u> <u>function</u> of its input parameter
 - Example: Temperature sensor, LDR, analog pressure sensor, and Analog Hall effect/Magnetic Sensor
 - ➤ A LDR shows continuous variation in its resistance as a function of intensity of light falling on it



Digital Sensor

- Responses in binary nature
- Designs to overcome the disadvantages of analog sensors
- ➤ Along with the analog sensor it also comprises of extra electronics for bit conversion
- Example: Passive infrared (PIR) sensor and digital temperature sensor (DS1620)



Scalar Sensor

- > Detects the input parameter only based on its magnitude
- ➤ The response of the sensor is a function of magnitude of the input parameter
- Not affected by the direction of the input parameter
- Example: Temperature, gas, strain, color, and smoke sensors

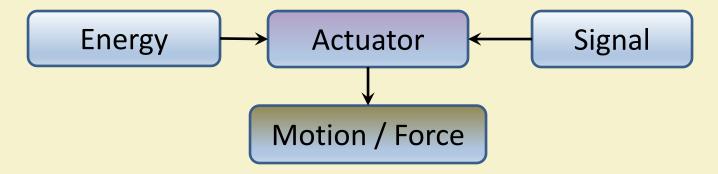


Vector Sensor

- The response of the sensor depends on the <u>magnitude</u> of the <u>direction</u> and <u>orientation</u> of input parameter
- Example : Accelerometer, gyroscope, magnetic field, and motion detector sensors



Actuator



- An actuator is part of the system that deals with the <u>control</u> action required (mechanical action)
- Mechanical or electro-mechanical devices

Actuator (Contd.)

- A <u>control signal</u> is input to an actuator and an <u>energy source</u> is necessary for its operation
- Available in both micro and macro scales
- Example: Electric motor, solenoid, hard drive stepper motor, comb drive, hydraulic cylinder, piezoelectric actuator, and pneumatic actuator



DC Motor

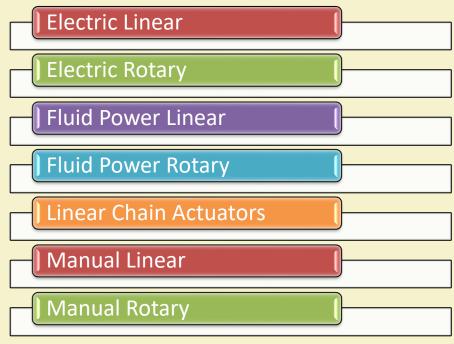


Relay





Classification of Actuators

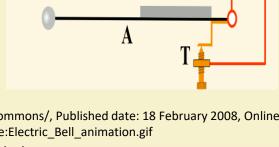






Electric Linear Actuator

- Powered by electrical signal
- Mechanical device containing linear guides, motors, and drive mechanisms
- > Converts electrical energy into linear displacement
- Used in automation applications including electrical bell, opening and closing dampers, locking doors, and braking machine motions
 Source: "Electric bell", HOK/ Wikimedia Commons/, Published date: 18 February 2008, Online:



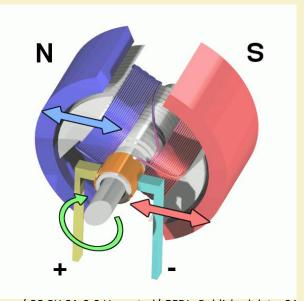
https://commons.wikimedia.org/wiki/File:Electric_Bell_animation.gif





Electric Rotary Actuator

- Powered by electrical signal
- Converts <u>electrical energy</u> into <u>rotational</u> <u>motion</u>
- Applications including quarter-turn valves, windows, and robotics



Source: "Electric motor", Abnormaal / Wikimedia Commons / CC-BY-SA-3.0 Unported/ GFDL. Published date: 21 May 2008, Online: https://commons.wikimedia.org/wiki/File:Electric_motor.gif





Fluid Power Linear Actuator

- Powered by <u>hydraulic fluid</u>, gas, or differential air pressure
- Mechanical devices have cylinder and piston mechanisms
- Produces <u>linear displacement</u>
- Primarily used in automation applications including clamping and welding





Fluid Power Rotary Actuator

- Powered by <u>fluid</u>, gas, or differential air pressure
- Consisting of gearing, and cylinder and piston mechanisms
- Converts hydraulic fluid, gas, or differential air pressure into <u>rotational motion</u>
- Primarily applications of this actuator are opening and closing dampers, doors, and clamping

 Source: "Axial piston pump", MichaelFrey / Wikimedia Commons wikimedia org/wiki/File:Axial piston pump", MichaelFrey / Wikimedia Org/wiki/File:Axial piston pump / Wikimedia Org

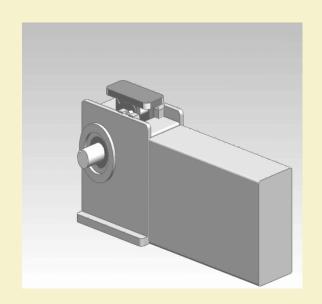
Source: "Axial piston pump", MichaelFrey / Wikimedia Commons / CC-BY-SA-4.0 International/. Published date: 11 August 2017, Online: https://commons.wikimedia.org/wiki/File:Axialkolbenpumpe_-_einfache_Animation.gif





Linear Chain Actuator

- Mechanical devices containing <u>sprockets</u> and <u>sections of chain</u>
- Provides <u>linear motion</u> by the free ends of the specially designed chains
- Primarily used in motion control applications



Source: "Rigid chain actuator", Catsquisher/ Wikimedia Commons/, Published date: 11 January 2011, Online: https://commons.wikimedia.org/wiki/File:Rigid_Chain_Actuator.gif





Manual Linear Actuator

- Provides <u>linear displacement</u> through the translation of <u>manually rotated</u> screws or gears
- Consists of gearboxes, and hand operated knobs or wheels
- > Primarily used for manipulating tools and workpieces





Manual Rotary Actuator

- Provides <u>rotary output</u> through the translation of <u>manually</u> <u>rotated</u> screws, levers, or gears
- Consists of hand operated knobs, levers, handwheels, and gearboxes
- Primarily used for the operation of valves





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Thank You!!



