# **EEE I - Problem Set 2**

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Worked with Keisuke Ito and had chatgpt help revise code and improve style

### Set up

```
import numpy as np
from scipy.sparse import csr_matrix
from scipy.stats import norm
import scipy.integrate as integrate
import altair as alt
import pandas as pd
from math import exp
import warnings
warnings.filterwarnings('ignore')
alt.renderers.enable("png")
# part (c)
def utility1(y: int) -> float:
   return 2 * y ** (1/2)
def marginal_utility1(y):
    return np.where(y > 0, y ** (-0.5), np.inf)
def utility2(y: int) -> float:
    return 5 * y - 0.05 * y ** 2
def marginal_utility2(y: int) -> float:
    return 5 - 0.1 * y
# Set up starting values
```

```
stock = 1000

discount_rate = 0.05
delta = 1 / (1 + discount_rate)

N = 501 # number of states
nA = 501 # number of actions
step_size = stock / (N - 1)
```

```
# part a) and b)
# state space and action space are 0 to 1000 by 2
state_space = np.linspace(0, stock, N)
action_space = np.linspace(0, stock, nA)
state_space_matrix = np.tile(state_space.reshape(N, 1), (1, nA)) # N x nA
action_space_matrix = np.tile(action_space.reshape(1, nA), (N, 1)) # N x nA
feasible_actions = action_space_matrix <= state_space_matrix</pre>
# part (d)
utility_matrix1 = np.where(feasible_actions,
                           utility1(action_space_matrix), -np.inf)
utility_matrix2 = np.where(feasible_actions,
                               utility2(action_space_matrix), -np.inf)
utility_matrix1_flat = utility_matrix1.flatten() # N * nA 1D array to use in

→ Bellman with trnasition matrix

utility_matrix2_flat = utility_matrix2.flatten()
# get next state_indices
update_state_matrix = state_space_matrix - action_space_matrix
next_state_indices = np.zeros((N, nA), dtype=int)
# part (e)
next_state_indices[feasible_actions] = (update_state_matrix[feasible_actions]
# part (f)
```

```
# create (N * nA, N) matrix transition matrix
row_indices = []
col_indices = []
data = []
for i in range(N): # state index
    for j in range(nA): # action index
        if feasible_actions[i, j]:
            next_state_index = next_state_indices[i, j] # state after action
            row_index = i * nA + j # Correct row index for (state, action)
            col_index = next_state_index # Next state index
            row_indices.append(row_index)
            col_indices.append(col_index)
            data.append(1) # deterministic transition
transition_matrix = csr_matrix((data, (row_indices, col_indices)), shape=(N *
 \hookrightarrow nA, N))
# part (g)
def bellman(v, U_flat, transition_matrix, delta, N, nA):
    '''Evaluated RHS of bellman before max
    - v: current value function (N, )
    - U_flat: flattened utility matrix (N * nA, )
    - transition_matrix: (N, N * nA) sparse matrix
    - delta: dicsount factor
    - N: number of states
    - nA: number of actions
    v_next = transition_matrix.dot(v) # N * nA, 1
    B_flat = U_flat + delta * v_next # (N * nA, 1)
    B_sa = B_flat.reshape(N, nA) # (N, nA) sa for state action
    return B_sa
# Value function iteration function
max_iterations = 1000
np.random.seed(454)
# start with value function of zeros
value function = np.zeros(N)
utility_matrix = utility_matrix1
iteration = 0
tolerance = 1e-8
```

```
def value_function_iteration(U_flat, transition_matrix, delta, N, nA,

    tolerance, max_iterations):

   Performs value function iteration using the Bellman function.
   Parameters:
   - U: Utility matrix (N x nA array)
   - next_state_indices: Next state indices matrix (N x nA array)
    - delta: Discount factor
   - N: Number of states
    - nA: Number of actions
    - tolerance: Convergence tolerance
    - max_iterations: Maximum number of iterations
   Returns:
    - v: Value function (N x nA array)
    - policy: Optimal action indices for each state (N x 1 array)
   v = value_function
    for iteration in range(max_iterations):
        B_sa = bellman(v, U_flat, transition_matrix, delta, N, nA)
        v_new = np.max(B_sa, axis=1) # find value of best action for each
  state
        policy = np.argmax(B_sa, axis=1) # find index of best action for each
  state
        diff = np.max(np.abs(v_new - v))
        v = v new
        if diff < tolerance:</pre>
            print(f'Converged in {iteration + 1} iterations')
            break
    else:
        print('Did not converge within max iterations')
    return v, policy
def get_optimal_transition_matrix(N, C, next_state_indices):
    Constructs the optimal transition matrix Topt.
   Parameters:
    - N: Number of states
    - C: Optimal action indices for each state (array of size N)
    - next_state_indices: Next state indices matrix (N x nA array)
```

```
Returns:
    - Topt: Optimal transition matrix (N x N sparse matrix)
    row_indices = np.arange(N)
    col_indices = next_state_indices[np.arange(N), C]
    data = np.ones(N)
    Topt = csr_matrix((data, (row_indices, col_indices)), shape=(N, N))
    return Topt
# Solve for utility function 1
print("Solving for utility function 1:")
v u1, C u1 = value function iteration(utility matrix1 flat,

    transition_matrix, delta, N, nA, tolerance, max_iterations)

# Part (h) Find optimal transition matrix
Topt_u1 = get_optimal_transition_matrix(N, C_u1, next_state_indices)
# Solve for utility function 2
print("Solving for utility function 2:")
v_u2, C_u2 = value_function_iteration(utility_matrix2_flat,

    transition_matrix, delta, N, nA, tolerance, max_iterations)

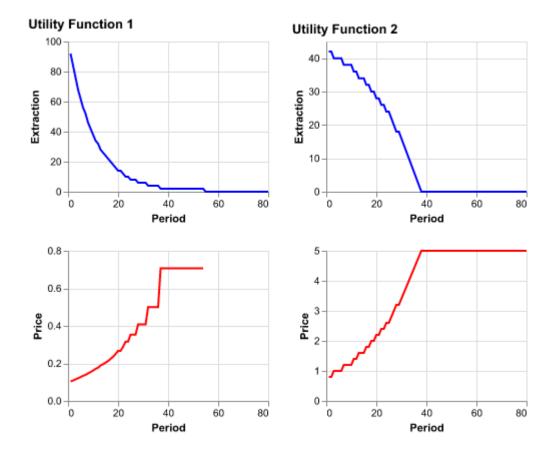
# Part (h) Find optimal transition matrix
Topt_u2 = get_optimal_transition_matrix(N, C_u2, next_state_indices)
# Part (i) Simulate the model for t= 80 periods
T = 80
remaining_stock = stock
extraction_path = []
stock_path = []
price_path = []
def simulation(T, starting_stock, price_function, C, action_space,

    step_size):

   remaining_stock = starting_stock
    extraction_path = []
    stock_path = []
    price_path = []
    for t in range(T):
        stock_path.append(remaining_stock)
        current_state = int(remaining_stock / step_size)
```

```
if current_state >= N:
            print("Error: State index out of bounds")
            break
        action_index = C[current_state]
        action = action_space[action_index]
        remaining_stock -= action
        if remaining_stock < 0:</pre>
            print("Error: Negative stock")
            break
        extraction_path.append(action)
        price = price_function(action)
        price_path.append(price)
    return extraction_path, stock_path, price_path
def make_extraction_plot(extraction_path, stock_path, price_path, title):
   periods = np.arange(1, len(extraction_path) + 1)
    df = pd.DataFrame({
        'Period': periods,
        'Extraction': extraction_path,
        'Price': price_path,
        'Stock': stock path
    })
    extraction_chart = alt.Chart(df).mark_line(color='blue').encode(
        x=alt.X('Period', axis=alt.Axis(title='Period')),
        y=alt.Y('Extraction', axis=alt.Axis(title='Extraction'))
    ).properties(
        width=200,
        height=150
    )
   price_chart = alt.Chart(df).mark_line(color='red').encode(
        x=alt.X('Period', axis=alt.Axis(title='Period')),
        y=alt.Y('Price', axis=alt.Axis(title='Price')),
    ).properties(
        width=200,
        height=150
    )
```

Solving for utility function 1: Converged in 55 iterations Solving for utility function 2: Converged in 38 iterations



```
# action space is the same as before
action_space = np.linspace(0, stock, nA)

# create statespace even over the squre root of the action space
state_space = np.linspace(0, stock ** 0.5, N) ** 2

# constant on the columns, state space on the rows
state_space_matrix = np.tile(state_space.reshape(N, 1), (1, nA)) # N x nA

# constant on the rows, action space on the columns
action_space_matrix = np.tile(action_space.reshape(1, nA), (N, 1)) # N x nA
feasible_actions = action_space_matrix <= state_space_matrix</pre>
```

```
utility_matrix1 = np.where(feasible_actions,
                            utility1(action_space_matrix), -1e10)
utility_matrix2 = np.where(feasible_actions,
                                utility2(action_space_matrix), -1e10)
utility_matrix1_flat = utility_matrix1.flatten() # N * nA 1D array to use in

→ Bellman with trnasition matrix

utility_matrix2_flat = utility_matrix2.flatten()
update_state_matrix = state_space_matrix - action_space_matrix
# make sparse transition matrix
row_indices = []
col_indices = []
data = []
for i in range(N): # state index
    for j in range(nA): # action index
        if feasible_actions[i, j]:
            current_state = state_space[i]
            action = action_space[j]
            next_state = current_state - action
            row_index = i * nA + j # row index for (state, action)
            if next_state in state_space:
                next_state_index = np.where(state_space == next_state)[0][0]
                col_indices.append(next_state_index)
                row_indices.append(row_index)
                data.append(1.0)
            else:
                if next_state <= state_space[0]:</pre>
                    next_state_index_low = 0
                    next_state_index_high = 0
                    weight_low = 1.0
                    weight_high = 0.0
                elif next_state >= state_space[-1]:
                    next_state_index_low = N - 1
                    next_state_index_high = N - 1
                    weight low = 1.0
                    weight_high = 0.0
```

```
else:
                    next_state_index_low = np.searchsorted(state_space,
→ next_state, side='right') - 1
                    next_state_index_high = next_state_index_low + 1
                    s_low = state_space[next_state_index_low]
                    s_high = state_space[next_state_index_high]
                    weight_high = (next_state - s_low) / (s_high - s_low)
                    weight_low = 1.0 - weight_high
                row_indices.extend([row_index, row_index])
                col_indices.extend([next_state_index_low,
→ next_state_index_high])
                data.extend([weight_low, weight_high])
transition matrix = csr_matrix((data, (row_indices, col_indices)), shape=(N *
\rightarrow nA, N))
# Bellman Function
def bellman(v, U_flat, transition_matrix, delta, N, nA):
    v_next = transition_matrix.dot(v) # (N * nA,)
   B_flat = U_flat + delta * v_next # (N * nA,)
   B sa = B flat.reshape(N, nA)
                                    # (N, nA)
   return B_sa
# Value Function Iteration
def value_function_iteration(U_flat, transition_matrix, delta, N, nA,
→ tolerance, max_iterations):
   v = np.zeros(N)
   for iteration in range(max_iterations):
        B_sa = bellman(v, U_flat, transition_matrix, delta, N, nA)
        v_{new} = np.max(B_sa, axis=1)
        policy = np.argmax(B_sa, axis=1)
        diff = np.max(np.abs(v_new - v))
        if diff < tolerance:</pre>
            print(f'Converged in {iteration + 1} iterations')
           break
        v = v new
    else:
        print('Did not converge within max iterations')
   return v, policy
```

```
# Get Optimal Transition Matrix
def get_optimal_transition_matrix(N, nA, transition_matrix, C):
    row_indices = []
    col_indices = []
    data = []
    for i in range(N):
        optimal_action = C[i]
        row_index = i * nA + optimal_action
        row = transition_matrix.getrow(row_index)
        cols = row.indices
        probs = row.data
        for col, prob in zip(cols, probs):
            if prob > 0:
                row_indices.append(i)
                col_indices.append(col)
                data.append(prob)
    Topt = csr_matrix((data, (row_indices, col_indices)), shape=(N, N))
    return Topt
# Value function iteration function
max iterations = 1000
np.random.seed(454)
# start with value function of zeros
value_function = np.zeros(N)
tolerance = 1e-8
# Solve for utility function 1
print("Solving for utility function 1:")
v_u1, C_u1 = value_function_iteration(utility_matrix1_flat,

    transition_matrix, delta, N, nA, tolerance, max_iterations)

# Part (h) Find optimal transition matrix
Topt_u1 = get_optimal_transition_matrix(N, nA, transition_matrix, C_u1)
# Solve for utility function 2
print("Solving for utility function 2:")
v_u2, C_u2 = value_function_iteration(utility_matrix2_flat,

    transition_matrix, delta, N, nA, tolerance, max_iterations)
```

```
# Part (h) Find optimal transition matrix
Topt_u2 = get_optimal_transition_matrix(N, nA, transition_matrix, C_u2)
def simulation(T, starting_stock, price_function, C, action_space,

    state_space):

    remaining_stock = starting_stock
    extraction_path = []
    stock path = []
    price_path = []
    for t in range(T):
        stock_path.append(remaining_stock)
        current_state = np.searchsorted(state_space, remaining_stock,

    side='right') - 1

        if current_state < 0 or current_state >= N:
            print("Error: State index out of bounds")
            break
        action_index = C[current_state]
        action = action_space[action_index]
        extraction_path.append(action)
        price = price_function(action)
        price_path.append(price)
        remaining_stock -= action
        if remaining stock < 0:</pre>
            break
    return extraction_path, stock_path, price_path
def make_extraction_plot(extraction_path, stock_path, price_path, title):
    periods = np.arange(1, len(extraction_path) + 1)
    df = pd.DataFrame({
        'Period': periods,
        'Extraction': extraction_path,
        'Price': price_path,
        'Stock': stock_path
    })
    extraction_chart = alt.Chart(df).mark_line(color='blue').encode(
        x=alt.X('Period', axis=alt.Axis(title='Period')),
        y=alt.Y('Extraction', axis=alt.Axis(title='Extraction'))
    ).properties(
        width=200,
        height=150
```

```
)
    price_chart = alt.Chart(df).mark_line(color='red').encode(
        x=alt.X('Period', axis=alt.Axis(title='Period')),
        y=alt.Y('Price', axis=alt.Axis(title='Price'),

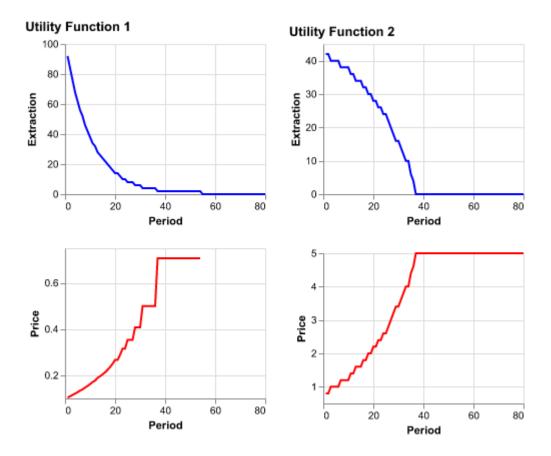
    scale=alt.Scale(zero=False))

    ).properties(
        width=200,
        height=150
    )
    combined_chart = alt.vconcat(extraction_chart, price_chart).properties(
        title=title
    )
    return combined_chart
# Part (i) Simulate the model for t=80 periods
T = 80
# Simulation for Utility Function 1
extraction_path, stock_path, price_path = simulation(
    T, stock, marginal_utility1, C_u1, action_space, state_space
)
# round prices to 3 decimal places
price_path = np.round(price_path, 3)
chart_1 = make_extraction_plot(extraction_path, stock_path, price_path,
→ "Utility Function 1")
# Simulation for Utility Function 2
extraction_path, stock_path, price_path = simulation(
    T, stock, marginal_utility2, C_u2, action_space, state_space
chart_2 = make_extraction_plot(extraction_path, stock_path, price_path,

→ "Utility Function 2")

# Display the charts
chart_1 | chart_2
```

Solving for utility function 1: Converged in 58 iterations Solving for utility function 2:



```
# Part (a): Define extraction functions
def extraction_function1(mu_0, t):
    """
    Computes the extraction rate y1 at time t given initial mu_0.
    """
    mu_t = mu_0 * exp(0.05 * t)
    return 1 / (mu_t ** 2)

def extraction_function2(mu_0, t):
    """
    Computes the extraction rate y2 at time t given initial mu_0.
```

```
mu_t = mu_0 * exp(0.05 * t)
   return 50 - 10 * mu_t
# Part (b): Compute cumulative extraction over time
def cumulative_extraction1(mu_0, k):
    Computes the cumulative extraction of y1 from time 0 to k.
   result, _ = integrate.quad(lambda t: extraction_function1(mu_0, t), 0, k)
    return result
def cumulative_extraction2(mu_0, k):
    Computes the cumulative extraction of y2 from time 0 to k.
   result, _ = integrate.quad(lambda t: extraction_function2(mu_0, t), 0, k)
   return result
# Part (c): Find mu_0 that results in cumulative extraction close to 1000
def find_closest_mu(func_cumulative_extraction, target=1000,

→ mu_values=np.linspace(0.5, 0.01, 100)):
   11 11 11
   Finds the value of mu 0 that brings cumulative extraction closest to the

    target.

   11 11 11
   closest_mu = min(mu_values, key=lambda mu:
→ abs(func_cumulative_extraction(mu)[0] - target))
   return closest_mu
def cumulative_extraction_with_time1(mu_0):
    11 11 11
   Finds cumulative extraction and time k where cumulative extraction
\hookrightarrow reaches or exceeds the target for y1.
   11 11 11
   for k in range(1001):
        cumulative_value = cumulative_extraction1(mu_0, k)
        if cumulative_value >= 1000:
            return cumulative value, k
   return cumulative_value, 1000
```

```
def cumulative_extraction_with_time2(mu_0):
    Finds cumulative extraction and time k where cumulative extraction
 → reaches or exceeds the target for y2.
    11 11 11
    for k in range(1001):
        cumulative_value = cumulative_extraction2(mu_0, k)
        if cumulative value >= 1000:
            return cumulative_value, k
    return cumulative value, 1000
# Generate a range of mu_0 values to search
mu_values = np.linspace(0.5, 0.01, 100)
# Find the mu_0 that gives cumulative extraction closest to 1000
closest mu1 = find closest mu(cumulative extraction with time1,

→ mu_values=mu_values)

closest_mu2 = find_closest_mu(cumulative_extraction_with_time2,

    mu_values=mu_values)

print(f"The value of mu_0 that gives cumulative extraction closest to 1000

    for extraction function 1 is: {closest_mu1}")
print(f"The value of mu 0 that gives cumulative extraction closest to 1000

    for extraction function 2 is: {closest_mu2}")
# Part (d): Plot the time paths of the extraction functions
def generate_extraction_paths(mu_0_1, mu_0_2, time_horizon=100,

¬ num_points=500):

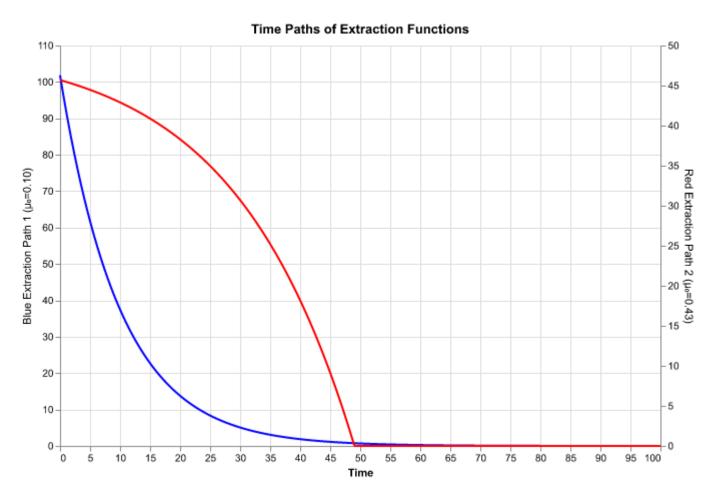
    11 11 11
    Generates extraction paths for y1 and y2 over the specified time horizon.
    t_values = np.linspace(0, time_horizon, num_points)
    y1_values = []
    y2_values = []
    for t in t_values:
        y1_val = extraction_function1(mu_0_1, t)
        y2_val = extraction_function2(mu_0_2, t)
        y1_values.append(max(y1_val, 0)) # Ensure non-negative values
```

```
y2_values.append(max(y2_val, 0))
    return t_values, y1_values, y2_values
# Generate the extraction paths
t_values, y1_values, y2_values = generate_extraction_paths(closest_mu1,

    closest_mu2)

# Create a DataFrame for plotting
df = pd.DataFrame({
    'Time': t_values,
    'Extraction Path 1': y1_values,
    'Extraction Path 2': y2_values
})
# Create the plots using Altair
def create_extraction_plot(df, mu_0_1, mu_0_2):
    Creates an Altair plot showing the extraction paths of y1 and y2.
    base = alt.Chart(df).encode(x='Time')
    y1_chart = base.mark_line(color='blue').encode(
        y=alt.Y('Extraction Path 1', axis=alt.Axis(title=f'Blue Extraction
 → Path 1 ( ={mu_0_1:.2f})'))
    )
    y2_chart = base.mark_line(color='red').encode(
        y=alt.Y('Extraction Path 2', axis=alt.Axis(title=f'Red Extraction
 \rightarrow Path 2 ( ={mu_0_2:.2f})'))
    )
    combined_chart = alt.layer(y1_chart, y2_chart).resolve_scale(
        y='independent'
    ).properties(
        width=600,
        height=400,
        title='Time Paths of Extraction Functions'
    return combined_chart
# Display the combined chart
```

```
chart = create_extraction_plot(df, closest_mu1, closest_mu2)
chart.show()
```



```
from math import exp
import numpy as np
import scipy.integrate as integrate
import matplotlib.pyplot as plt

## (a)
def y1(mu_0, t):
```

```
mu_t = mu_0 * exp(0.05 * t)
    return 1 / (mu_t ** 2)
def y2(mu_0, t):
   mu_t = mu_0 * exp(0.05 * t)
   return 50 - 10 * mu_t
## (b)
def cum1(mu_0, k):
   result, _ = integrate.quad(lambda t: y1(mu_0, t), 0, k)
   return result
def cum2(mu_0, k):
   result, _ = integrate.quad(lambda t: y2(mu_0, t), 0, k)
   return result
## (c)
def cum_mu_1(mu):
    for k in range(1001): # Loop from k = 0 to k = 1000
        cumulative_value = cum1(mu, k)
        # Check if cumulative_value has reached or exceeded 1000
        if cumulative_value >= 1000:
            return cumulative_value, k
    # If we reach k = 1000 without hitting the threshold, return the last

    value

    return cumulative_value, 1000
def cum_mu_2(mu):
    for k in range(1001): # Loop from k = 0 to k = 1000
        cumulative_value = cum2(mu, k)
        # Check if cumulative_value has reached or exceeded 1000
        if cumulative_value >= 1000:
            return cumulative_value, k
    # If we reach k = 1000 without hitting the threshold, return the last

    value

    return cumulative_value, 1000
# get a rough idea of the value of mu
```

```
mu_values = np.linspace(0.5, 0.01, 100)
# find the value of 1 that gives the closest value to 1000
closest_mu1 = min(mu_values, key=lambda mu: abs(cum_mu_1(mu)[0] - 1000))
closest_mu2 = min(mu_values, key=lambda mu: abs(cum_mu_2(mu)[0] - 1000))
print(f"The value of mu that gives the closest value to 1000 for cum mu 1 is:
print(f"The value of mu that gives the closest value to 1000 for cum mu 2 is:
t_{values} = np.linspace(0, 100, 500)
y1_values = []
y2_values = []
for t in t_values:
   y1_val = y1(closest_mu1, t)
   y2_val = y2(closest_mu2, t)
    if y1_val < 0:</pre>
        break
   y1_values.append(y1_val)
    if y2 val < 0:
        break
    y2_values.append(y2_val)
# add zeros to the end of the shorter list
if len(y1_values) < len(y2_values):</pre>
    y1_values.extend([0] * (len(y2_values) - len(y1_values)))
elif len(y2_values) < len(y1_values):</pre>
    y2_values.extend([0] * (len(y1_values) - len(y2_values)))
# Create a DataFrame
df = pd.DataFrame({
    'Time': t_values[:len(y1_values)],
    'y1': y1_values,
    'y2': y2_values
})
# Create the y1 plot
y1_chart = alt.Chart(df).mark_line(color='blue').encode(
```

```
x=alt.X('Time', axis=alt.Axis(title='Time (t)')),
    y=alt.Y('y1', axis=alt.Axis(title=f'Blue Extraction Path 1:

    (mu0={closest_mu1:.2f}, t)'))

).properties(
    width=200,
    height=150
)
# Create the y2 plot
y2_chart = alt.Chart(df).mark_line(color='red').encode(
    x=alt.X('Time', axis=alt.Axis(title='Time (t)')),
    y=alt.Y('y2', axis=alt.Axis(title=f'Red Extraction Path 2:

    (mu0={closest_mu2:.2f}, t)'))

).properties(
    width=200,
    height=150
)
# Combine the charts
combined_chart = alt.layer(y1_chart, y2_chart).resolve_scale(
    y='independent'
).properties(
    title='Time Path of y1 and y2'
combined chart.show()
```

The value of mu that gives the closest value to 1000 for  $cum_mu_1$  is: 0.099090909090912

The value of mu that gives the closest value to 1000 for  $cum_mu_2$  is: 0.4307070707070707



```
# Part (a): Define price space and compute profit function
# Define the price space from 0 to 80 with a step size of 1
price_space = np.arange(0, 81, 1) # Prices from 0 to 80

# Define the profit function
def profit_function(price):
    """
    Compute profit for a given price.

Parameters:
    - price: Price value or array of prices

Returns:
    - Profit corresponding to the price(s)
    """
    return price * 100000 - 3000000

# Compute profit for each price in the price space
profit_values = profit_function(price_space)
# Display the profit values
print(f"Profit values for price space:\n{profit_values}")
```

```
# Part (b): Construct the transition matrix
# Parameters for the transition
mean_increment = 0  # Mean of the price increment
std_increment = 4  # Standard deviation of the price increment
# Number of price states
num_price_states = len(price_space)
# Initialize the transition matrix (num_price_states x num_price_states)
transition_matrix = np.zeros((num_price_states, num_price_states))
# Define cutoffs for state transitions
price_cutoffs = np.arange(-0.5, num_price_states, 1) # Cutoffs between

→ states

# Populate the transition matrix
for current_state_index in range(num_price_states):
    for next_state_index in range(num_price_states):
        if next_state_index == 0:
            lower_bound = -np.inf # For the first state, lower bound is
 → -infinity
        else:
            lower_bound = price_cutoffs[next_state_index]
        if next_state_index == num_price_states - 1:
            upper_bound = np.inf # For the last state, upper bound is
 → infinity
        else:
            upper_bound = price_cutoffs[next_state_index + 1]
        # Calculate the probability of transitioning from current state to

→ next state

        probability = norm.cdf(upper_bound,
 → loc=price_space[current_state_index], scale=std_increment) - \
                      norm.cdf(lower_bound,
 → loc=price_space[current_state_index], scale=std_increment)
        transition_matrix[current_state_index, next_state_index] =
   probability
# Verify that each row of the transition matrix sums to 1
row_sums = transition_matrix.sum(axis=1)
```

```
print("Transition Matrix:")
print(transition_matrix)
print("\nRow sums (should be 1):")
print(row_sums)
# Part (c): Solve for the value function using value function iteration
def value_function_iteration(transition_matrix, profit_values,

    discount factor, tolerance, max iterations):
    Performs value function iteration to solve for the value function V(p t).
    Parameters:
    - transition_matrix: State transition probability matrix (num_states x

    num_states)

    - profit_values: Profit function values for each state (num_states,)
    - discount_factor: Discount factor
    - tolerance: Convergence tolerance
    - max_iterations: Maximum number of iterations
    Returns:
    - value_function: Value function V(p_t) (num_states,)
    - policy: Optimal decision for each state (num_states,), 1 if choosing

    profit, 0 if waiting

   11 11 11
    num states = len(profit values)
    value_function = np.zeros(num_states)
    policy = np.zeros(num_states, dtype=int)
    for iteration in range(max_iterations):
        value_function_old = value_function.copy()
        # Compute option value (expected continuation value)
        option_value = discount_factor * np.dot(transition_matrix,

¬ value_function_old)

        # Update value function and policy
        value_function = np.maximum(profit_values, option_value)
        policy = (value_function == profit_values).astype(int)
        # Check for convergence
        diff = np.max(np.abs(value_function - value_function_old))
```

```
if diff < tolerance:</pre>
            print(f'Converged in {iteration + 1} iterations')
    else:
        print('Did not converge within max iterations')
    return value_function, policy
# Parameters for value function iteration
discount factor = delta # Discount factor
tolerance = 1e-6
max iterations = 1000
# Solve for the value function and optimal policy
value_function, optimal_policy = value_function_iteration(
    transition_matrix, profit_values, discount_factor, tolerance,

→ max_iterations)
# Find the trigger price (first price where it's optimal to act)
trigger_price = price_space[optimal_policy == 1][0]
print(f"The trigger price is: {trigger_price}")
# Part (d): Plot the value function
def plot_value_function(price_space, value_function):
    Plot the value function V(p_t) against price states.
    Parameters:
    - price_space: Array of price states
    - value_function: Array of value function values
    df = pd.DataFrame({'Price': price_space, 'Value Function':

¬ value_function})
    chart = alt.Chart(df).mark_line().encode(
        x=alt.X('Price', axis=alt.Axis(title='Price')),
        y=alt.Y('Value Function', axis=alt.Axis(title='Value Function
 \hookrightarrow V(p_t)')
    ).properties(
        width=200,
        height=150,
        title='Value Function vs. Price'
```

```
return chart
# Create and display the plot
chart = plot_value_function(price_space, value_function)
chart.show()
Profit values for price space:
[-3000000 -2900000 -2800000 -2700000 -2600000 -2500000 -2400000 -2300000
 -2200000 -2100000 -2000000 -1900000 -1800000 -1700000 -1600000 -1500000
-1400000 -1300000 -1200000 -1100000 -1000000 -900000 -800000 -700000
 -600000 -500000 -400000 -300000 -200000 -100000
                                                     0
                                                         100000
  200000
          300000
                 400000
                        500000
                                600000
                                        700000
                                                 800000
                                                         900000
 1000000 1100000 1200000 1300000 1400000 1500000 1600000
                                                        1700000
         1900000 2000000 2100000 2200000 2300000 2400000
 1800000
                                                        2500000
         2700000 2800000 2900000 3000000 3100000 3200000
 2600000
                                                        3300000
 3400000
         3500000 3600000 3700000 3800000 3900000 4000000
                                                        4100000
 4200000
         4300000 4400000 4500000 4600000 4700000 4800000
                                                        4900000
 5000000]
Transition Matrix:
[[5.49738225e-01 9.64315418e-02 8.78447043e-02 ... 0.00000000e+00
 0.0000000e+00 0.0000000e+00]
 [4.50261775e-01 9.94764497e-02 9.64315418e-02 ... 0.00000000e+00
 0.0000000e+00 0.0000000e+00]
 [3.53830233e-01 9.64315418e-02 9.94764497e-02 ... 0.00000000e+00
 0.0000000e+00 0.0000000e+00]
 [6.27307599e-84\ 7.75594078e-82\ 9.07800780e-80\ \dots\ 9.94764497e-02
 9.64315418e-02 3.53830233e-01]
 [4.72885399e-86\ 6.22578745e-84\ 7.75594078e-82\ \dots\ 9.64315418e-02
 9.94764497e-02 4.50261775e-01]
 [3.34932479e-88 4.69536075e-86 6.22578745e-84 ... 8.78447043e-02
 9.64315418e-02 5.49738225e-01]]
Row sums (should be 1):
1. 1. 1. 1. 1. 1. 1. 1. 1.
Converged in 399 iterations
```

The trigger price is: 41

