

Raspberry Pi Project

온습도 & 미세먼지 모니터링 시스템

손원용, 옥진해, 정지희









01. 개발목표



1개발목표



● 실시간 모니터링

온습도센서, 미세먼지센서, 유해가스 센서를 이용하여 실시간 모니터링 기능

02. 부품 및 개발환경



2 부품 및 개발환경

부품

- 레이저 방식 미세먼지 센서 [PMS7003M]
- PMS7003 어댑터 보드 [SY-PMS7003ab]
- 유해가스 센서 [MQ-135]
- MCP3008
- 온습도센서[DHT11]
- 라즈베리파이 7인치 터치스크린

개발환경



2 부품 및 개발환경

레이저 방식 미세먼지 센서 [PMS7003M] / PMS7003 어댑터 보드 [SY-PMS7003ab]









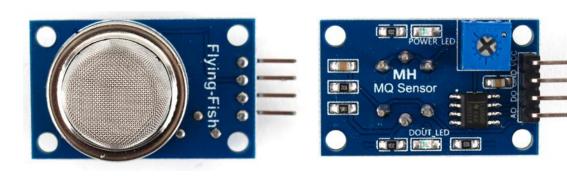


일반형 미세먼지 센서로 대기 중 입자 농도를 감지하고 디지털 인터페이스 형태로 출력

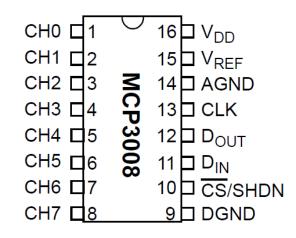
- 입자 검출 최소 크기 : 0.3 ㎞
- 감지 대상: PM2.5/PM10, 0~999ug/m³

2 부품 및 개발환경

유해가스/공기질 센서 모듈 [SZH-SSBH-038] / MCP3008

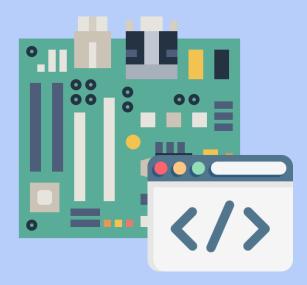




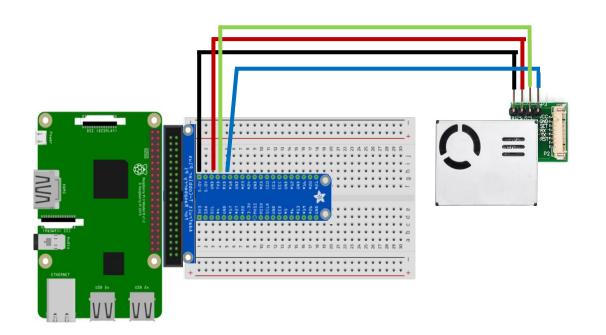


- CO₂, NH₃, smoke, Benzene, alcohol 등을 측정
- 디지털 출력과 아날로그 출력 가능
- 가변저항으로 감도조절 가능

- ADC(Analog-to-digital converter)
- 연속적인 analog 신호를 digital 신호로 변환하는 칩(I/C)

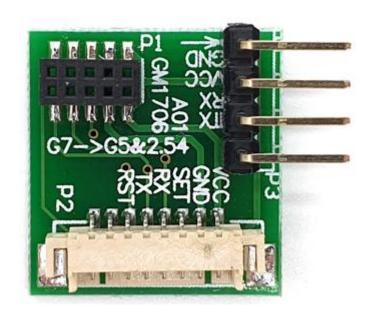


미세먼지 결선도



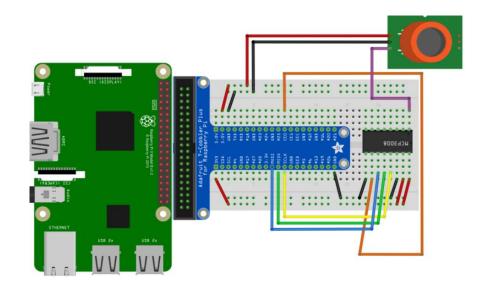
Rpi	PMS7003M
5V	VCC
GND	GND
Tx	Rx
Rx	Tx

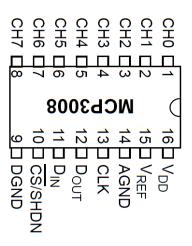
미세먼지 결선도



Rpi	PMS7003M
5V	VCC
GND	GND
Tx	Rx
Rx	Tx

유해가스/공기질 센서 결선도





Rpi	MQ-135	MCP3008
5V	VCC	Vdd, Vref
GND	GND	AGND, DGND
	AO	CH0
SPISCLK		CLK
SPIMISO		Dout
SPIMOSI		Din
SPICEO		CS/SHDN

```
import Adafruit_DHT
                                             form_class = uic.loadUiType("test_window.ui")[0]
from time import *
                                             pin = 4
import sys
                                             sensor = Adafruit DHT.DHT11
from PyQt5.QtWidgets import *
                                             dust = PMS7003()
from PyQt5 import uic
                                             Speed = 9600
from PyQt5 import QtCore,QtGui,QtWidgets
                                             UART = '/dev/ttyAMA0'
from PyQt5.QtCore import *
                                             SERIAL PORT = UART
from PyQt5.QtGui import *
                                             ser = serial.Serial(SERIAL PORT, Speed, timeout = 1)
from PyQt5.QtWidgets import *
from PyQt5.QtCore import QTimer, QTime
from threading import Timer
import datetime
import serial
from PMS7003 import PMS7003
from mq import *
```

```
def on set clicked(self):
                                              def displayTime(self):
                                                      h, t = Adafruit_DHT.read retry(sensor, pin)
    tem = self.t_on_set_spinbox_on.value()
                                                      buffer = ser.read(1024)
    hum = self.h on set spinbox on.value()
    set list1 = [tem, hum]
                                                      data = dust.unpack_data(buffer)
    return set list1
                                                      d = (data[dust.DUST PM2 5 ATM])
                                                      now = datetime.datetime.now()
                                                      nowDate = now.strftime('%Y-%m-%d %H:%M:%S')
def off set clicked(self):
   tem1 = self.t_off_set_spinbox_off.value()
                                                       lpg = round((perc["GAS LPG"] / 10000,7)
    hum1 = self.h_off_set_spinbox_off.value()
                                                      mq = MQ()
    set list2 = [tem1, hum1]
                                                      perc = mq.MQPercentage()
   return set list2
                                                       self.time.setText(str(nowDate))
                                                       self.h label.setText(str(h))
                                                       self.t label.setText(str(t))
                                                       self.d label.setText(str(d))
                                                       self.g label.setText(str(perc["GAS LPG"]))
```

```
Python 3.7.3 Shell
File Edit Shell Debug Options Window Help
DATA read success
______
                      Frame length: 28
PM 1.0 (CF=1): 24
                     I PM 1.0 : 23
PM 2.5 (CF=1): 40
                     I PM 2.5 : 36
PM 10.0 (CF=1): 42
                     I PM 10.0 : 42
0.3um in 0.1L of air : 4149
0.5um in 0.1L of air : 1211
1.0um in 0.1L of air : 237
2.5um in 0.1L of air : 34
5.0um in 0.1L of air : 4
10.0um in 0.1L of air : 0
Reserved F: 152 | Reserved B: 0
CHKSUM : 1065 | read CHKSUM : 1065 | CHKSUM result : True
DATA read success
Header : B M
                      Frame length: 28
PM 1.0 (CF=1): 25
                     I PM 1.0 : 23
PM 2.5 (CF=1): 43
                     I PM 2.5 : 38
PM 10.0 (CF=1): 46
                     I PM 10.0 : 46
0.3um in 0.1L of air : 4257
0.5um in 0.1L of air : 1247
1.0um in 0.1L of air : 250
2.5um in 0.1L of air : 40
5.0um in 0.1L of air : 6
10.0um in 0.1L of air : 0
Reserved F : 152 | Reserved B : 0
CHKSUM : 1244 | read CHKSUM : 1244 | CHKSUM result : True
Header err
DATA read fail...
DATA read success
Header : B M
                      | Frame length : 28
PM 1.0 (CF=1): 23
                     I PM 1.0 : 22
PM 2.5 (CF=1): 41
                     I PM 2.5 : 37
PM 10.0 (CF=1): 44
                     I PM 10.0 : 44
0.3um in 0.1L of air : 3966
0.5um in 0.1L of air : 1182
                                                           Ln: 262 Col: 4
```

```
File Edit Shell Debug Options Window Help
Press CTRL+C to abort.
Calibrating...
Calibration is done...
Ro=-0.027214 kohm
LPG: 0.0139967 ppm, CO: 0.011422 ppm, Smoke: 0.0389112 ppm
LPG: 0.0150702 ppm, CO: 0.0126505 ppm, Smoke: 0.0421071 ppm
LPG: 0.0139967 ppm, CO: 0.011422 ppm, Smoke: 0.0389112 ppm
LPG: 0.0150702 ppm, CO: 0.0126505 ppm, Smoke: 0.0421071 ppm
LPG: 0.013014 ppm, CO: 0.0103286 ppm, Smoke: 0.0360001 ppm
LPG: 0.0139967 ppm, CO: 0.011422 ppm, Smoke: 0.0389112 ppm
LPG: 0.0112864 ppm, CO: 0.00848268 ppm, Smoke: 0.0309193 ppm
LPG: 0.0139967 ppm, CO: 0.011422 ppm, Smoke: 0.0389112 ppm
LPG: 0.0139967 ppm, CO: 0.011422 ppm, Smoke: 0.0389112 ppm
LPG: 0.0121132 ppm, CO: 0.00935353 ppm, Smoke: 0.0333447 ppm
LPG: 0.0159467 ppm, CO: 0.0136787 ppm, Smoke: 0.0447281 ppm
LPG: 0.0139967 ppm, CO: 0.011422 ppm, Smoke: 0.0389112 ppm
LPG: 0.0121132 ppm, CO: 0.00935353 ppm, Smoke: 0.0333447 ppm
LPG: 0.0150702 ppm, CO: 0.0126505 ppm, Smoke: 0.0421071 ppm
LPG: 0.0150702 ppm, CO: 0.0126505 ppm, Smoke: 0.0421071 ppm
LPG: 0.0139967 ppm, CO: 0.011422 ppm, Smoke: 0.0389112 ppm
LPG: 0.013014 ppm, CO: 0.0103286 ppm, Smoke: 0.0360001 ppm
LPG: 0.00950801 ppm, CO: 0.0066926 ppm, Smoke: 0.0257446 ppm
LPG: 0.0101796 ppm, CO: 0.00735474 ppm, Smoke: 0.0276916 ppm
LPG: 0.0139967 ppm, CO: 0.011422 ppm, Smoke: 0.0389112 ppm
LPG: 0.0105266 ppm, CO: 0.00770361 ppm, Smoke: 0.0287012 ppm
LPG: 0.013014 ppm, CO: 0.0103286 ppm, Smoke: 0.0360001 ppm
LPG: 0.0121132 ppm, CO: 0.00935353 ppm, Smoke: 0.0333447 ppm
LPG: 0.0109091 ppm, CO: 0.00809317 ppm, Smoke: 0.0298164 ppm
LPG: 0.0112864 ppm, CO: 0.00848268 ppm, Smoke: 0.0309193 ppm
LPG: 0.00780465 ppm, CO: 0.00509421 ppm, Smoke: 0.0208499 ppm
LPG: 0.0121132 ppm, CO: 0.00935353 ppm, Smoke: 0.0333447 ppm
LPG: 0.0121132 ppm, CO: 0.00935353 ppm, Smoke: 0.0333447 ppm
LPG: 0.0121132 ppm, CO: 0.00935353 ppm, Smoke: 0.0333447 ppm
LPG: 0.0112864 ppm, CO: 0.00848268 ppm, Smoke: 0.0309193 ppm
LPG: 0.0101796 ppm, CO: 0.00735474 ppm, Smoke: 0.0276916 ppm
LPG: 0.0105266 ppm, CO: 0.00770361 ppm, Smoke: 0.0287012 ppm
LPG: 0.0101796 ppm, CO: 0.00735474 ppm, Smoke: 0.0276916 ppm
LPG: 0.0112864 ppm, CO: 0.00848268 ppm, Smoke: 0.0309193 ppm
                                                                    Ln: 372 Col: 0
```

```
if(self.on_set_clicked == True):
    set_list1 = set_on_clicked()
    set_hum1 = set_list1[1]
    set_tem1 = set_list1[0]
    if(set_hum1 < h) | (set_tem1 < t):
        print("온도가 높거나 습도가 높습니다.")
    if(d < 15):
        self.d_image.setText("좋음")
        if(perc["GAS_LPG"] < 0.5):
            self.g_image.setText("정상")
        else:
            self.d_image.setText("경고")
    elif(d < 50):
```

self.d image.setText("보통")

self.g image.setText("정상")

self.d_image.setText("경고")

if(perc["GAS LPG"] < 0.5):</pre>

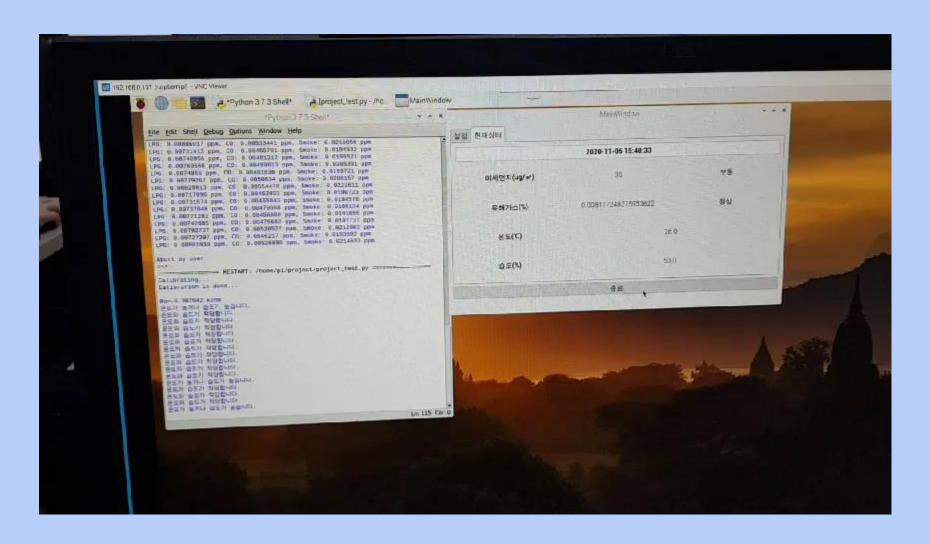
else:

```
elif(d < 100):
    self.d image.setText("나쁨")
    if(perc["GAS LPG"] < 0.5):</pre>
         self.g image.setText("정상")
    else:
         self.d_image.setText("경고")
else:
    self.d_image.setText("매우나쁨")
    if(perc["GAS LPG"] < 0.5):
         self.g image.setText("정상")
    else:
         self.d image.setText("경고")
```

04. Demo



04 Demo











감사합니다.