

Neural Networks

Batch Normalization

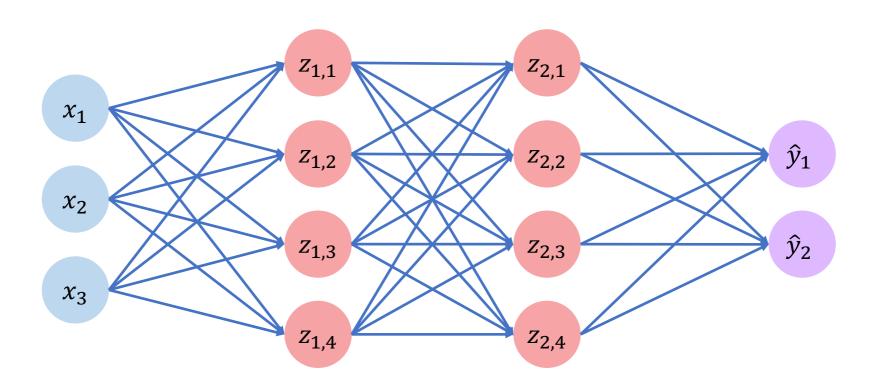
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Internal shift

- Training Deep Neural Networks is complicated by the fact that the distribution of each layer's inputs changes during training, as the parameters of the previous layers change
- We refer to this phenomenon as internal covariate shift
- This slows down the training by requiring lower learning rates, and makes it notoriously
 hard to train models with saturating nonlinearities



- By fixing the distribution of the layer inputs as the training progresses, we expect
 to improve the training speed
- Batch Normalization performs input normalization in a way that is differentiable and does
 not require the analysis of the entire training set after every parameter update
- Normalize each scalar feature independently
- Scale the normalized input with trainable parameters

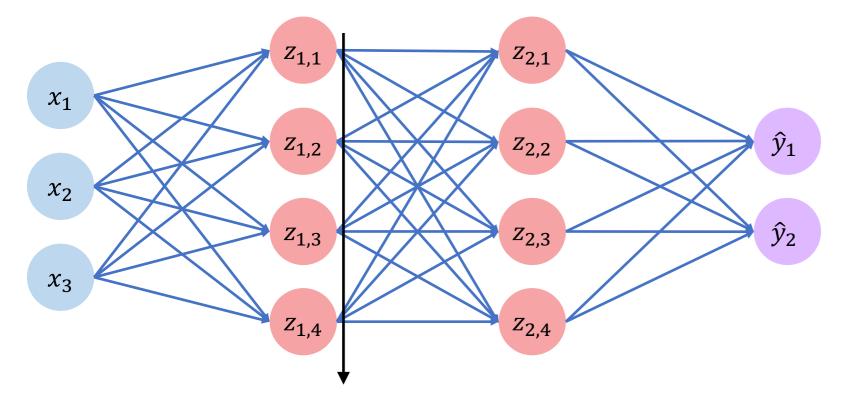
Batch Normalization: Accelerating Deep Network Training by Reducing Internal Covariate Shift

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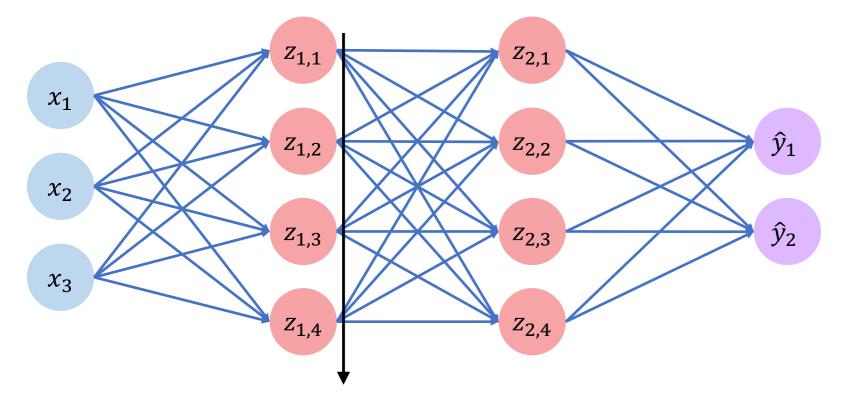
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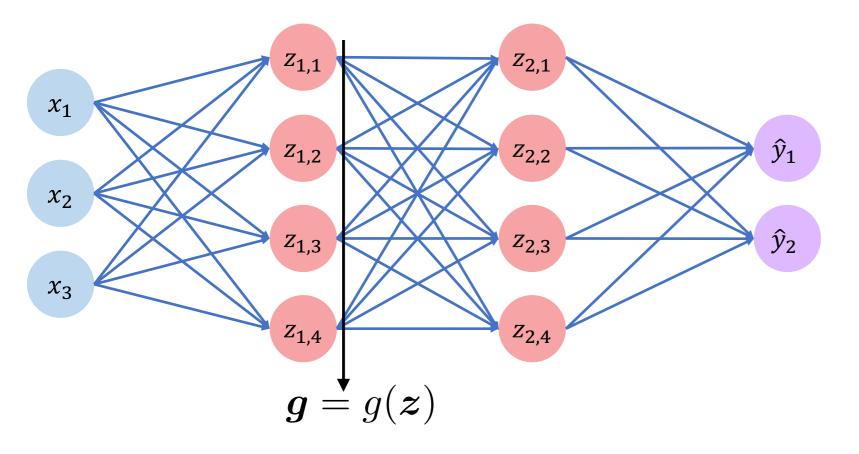
Mini-batch of size M



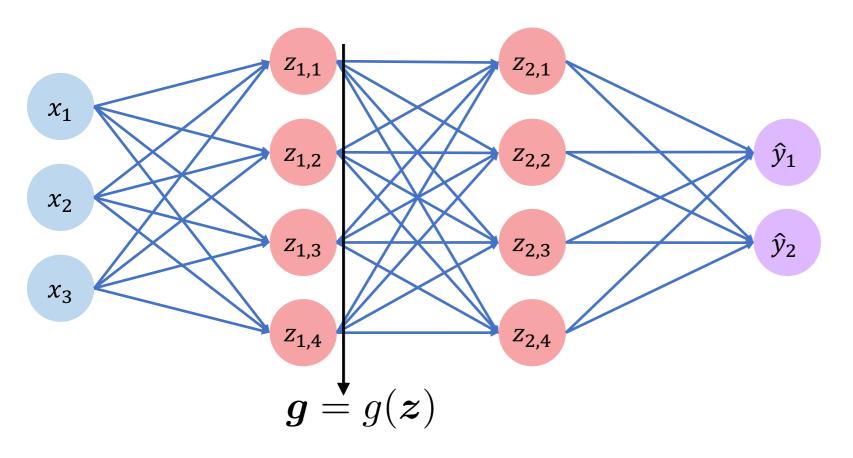
Mini-batch of size M



Mini-batch of size M



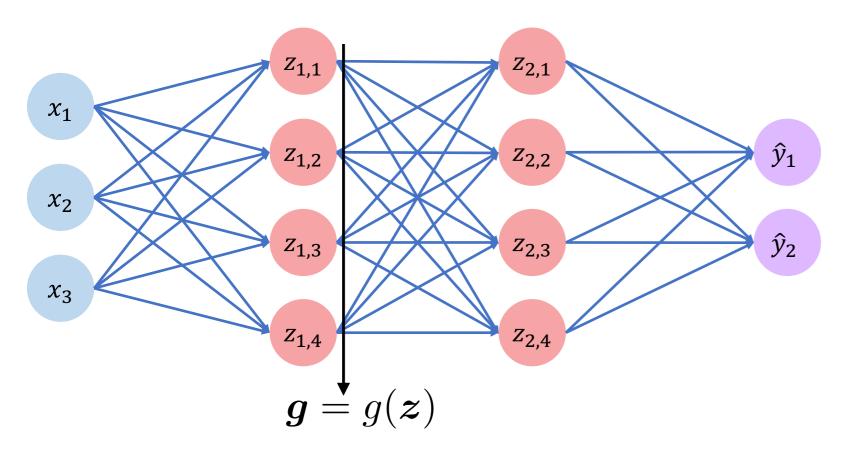
Mini-batch of size M



Mini-batch mean

$$\mu_j \leftarrow \frac{1}{M} \sum_{i=1}^{M} z_j^{(i)}$$

Mini-batch of size M



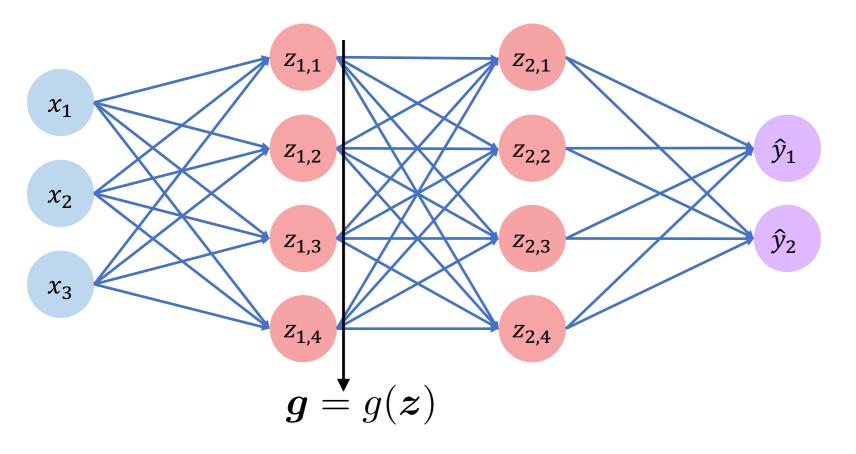
Mini-batch mean

$$\mu_j \leftarrow \frac{1}{M} \sum_{i=1}^{M} z_j^{(i)}$$

Mini-batch variance

$$\sigma_j^2 \leftarrow \frac{1}{M} \sum_{i=1}^{M} (z_j^{(i)} - \mu_j)^2$$

Mini-batch of size M



Mini-batch mean

$$\mu_j \leftarrow \frac{1}{M} \sum_{i=1}^{M} z_j^{(i)}$$

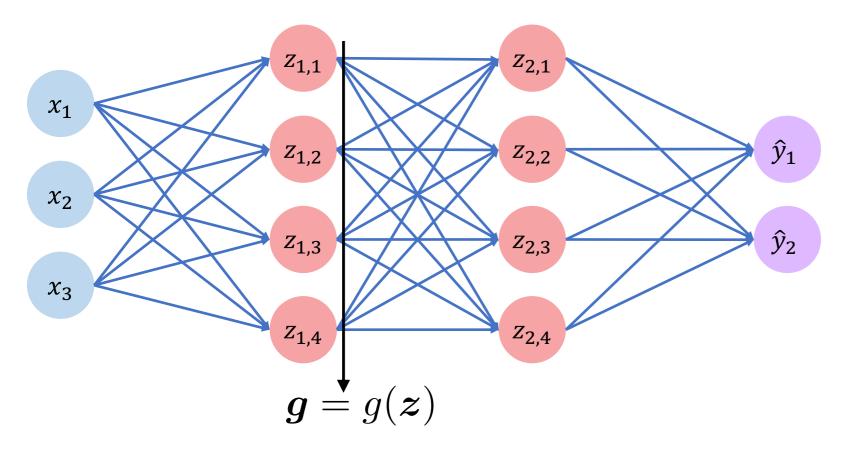
Mini-batch variance

$$\sigma_j^2 \leftarrow \frac{1}{M} \sum_{i=1}^M (z_j^{(i)} - \mu_j)^2$$

Normalize

$$\hat{z}_j^{(i)} = \frac{z_j - \mu_j}{\sqrt{\sigma_j^2}}$$

Mini-batch of size M



Mini-batch mean

$$\mu_j \leftarrow \frac{1}{M} \sum_{i=1}^{M} z_j^{(i)}$$

Mini-batch variance

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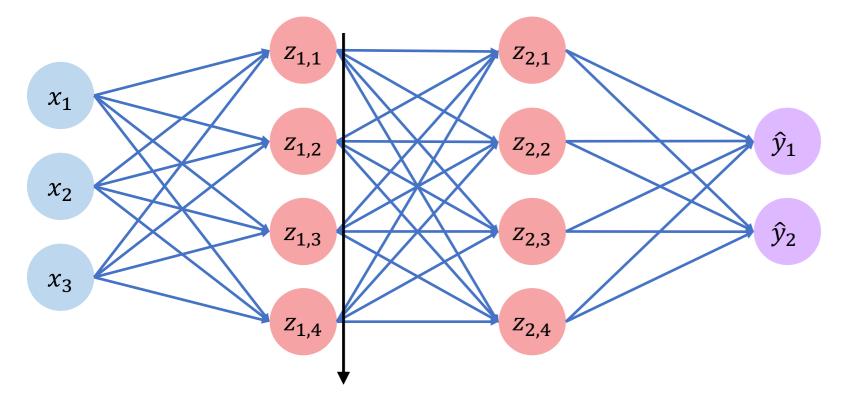
Normalize

$$\hat{z}_j^{(i)} = \frac{z_j - \mu_j}{\sqrt{\sigma_j^2}}$$

Scale and shift

$$a_j^{(i)} = \gamma \hat{z}_j^{(i)} + \beta$$

Mini-batch of size M



Mini-batch mean

$$\mu_j \leftarrow \frac{1}{M} \sum_{i=1}^{M} z_j^{(i)}$$

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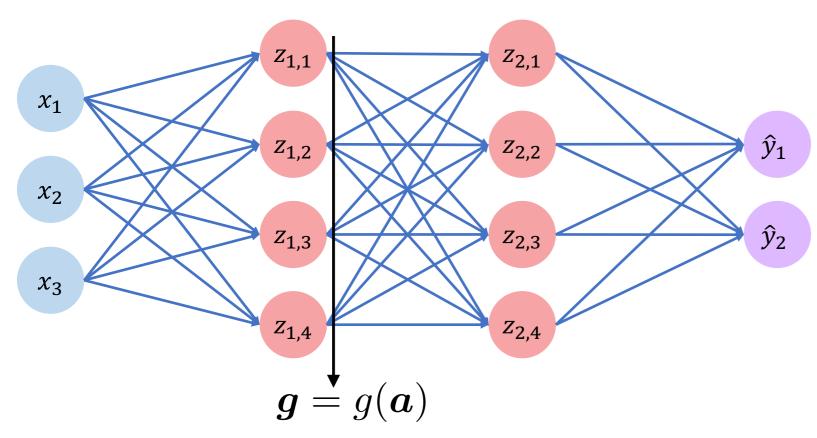
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Mini-batch of size M



Input to the non-linear activation

Mini-batch mean

$$\mu_j \leftarrow \frac{1}{M} \sum_{i=1}^{M} z_j^{(i)}$$

Mini-batch variance

$$\sigma_j^2 \leftarrow \frac{1}{M} \sum_{i=1}^{M} (z_j^{(i)} - \mu_j)^2$$

Normalize

$$\hat{z}_j^{(i)} = \frac{z_j - \mu_j}{\sqrt{\sigma_j^2}}$$

Scale and shift

$$a^{(i)} = \gamma \hat{z}_j^{(i)} + \beta$$

• During evaluation, we normalize according to the whole validation/test datasets. γ, β parameters are fixed!

For CNNs, we jointly normalise all pixels in the same feature map

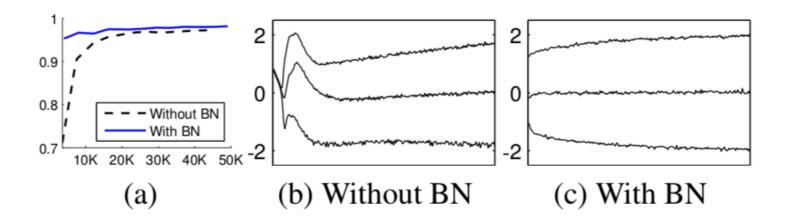


Figure 1. (a) The test accuracy of the MNIST network trained with and without Batch Normalization, vs. the number of training steps. Batch Normalization helps the network train faster and achieve higher accuracy. (b, c) The evolution of input distributions to a typical sigmoid, over the course of training, shown as {15, 50, 85}th percentiles. Batch Normalization makes the distribution more stable and reduces the internal covariate shift.