4ITRC2 Operating System Lab Lab Assignment 3

<u>Aim:</u> To Study and learn about various system call

<u>To Perform</u>: Comprehensive Study of different categories of linux system calls, categorized as

1. Process Management System calls fork(), exec(), wait(), exit().

1.1. fork()

The fork() system call is used to create a new process by duplicating the calling process. The new process is called the child process, and it gets a unique process ID (PID). The child process gets a copy of the parent's memory space.

Syntax:

pid_t fork(void);

Return Value:

- On success, it returns the child process ID to the parent and returns 0 to the child.
- On failure, it returns -1 and sets the errno variable.

Example:

```
#include <stdio.h>
#include <unistd.h>

int main() {
   pid_t pid = fork();
   if (pid == 0) {
      printf("Child Process\n");
   } else {
      printf("Parent Process\n");
   }
   return 0;
}
```

1.2. exec()

The exec() family of system calls replaces the current process with a new process. It loads the program into the process's memory and runs it. The most commonly used version is execl(), but there are other versions like execp(), execv(), etc.

Syntax:

```
int execvp(const char *file, char *const argv[]);
Example:
#include <stdio.h>
#include <unistd.h>

int main() {
    execlp("/bin/ls", "Is", NULL);
    printf("This will not be printed\n");
    return 0;
}
```

1.3. wait()

The wait() system call is used by a process to wait for the termination of one of its child processes. It returns the PID of the terminated child process.

Syntax:

```
pid_t wait(int *status);

Example:
#include <stdio.h>
#include <sys/wait.h>
#include <unistd.h>

int main() {
    pid_t pid = fork();
    if (pid == 0) {
        // Child process
        printf("Child Process\n");
    } else {
```

```
// Parent process
    wait(NULL);
    printf("Parent Process: Child terminated\n");
  }
  return 0;
}
1.4. exit()
The exit() system call terminates the calling process and returns an exit status to the parent process.
Syntax:
void exit(int status);
Example:
#include <stdio.h>
#include <stdlib.h>
int main() {
  printf("This program will exit now.\n");
  exit(0);
}
```

2. File Management System calls open(), read(), write(), close().

2.1. open()

The open() system call is used to open a file and return a file descriptor.

Syntax:

int open(const char *pathname, int flags, mode_t mode);

Example:

```
#include <stdio.h>
```

#include <fcntl.h>
#include <unistd.h>

```
int main() {
  int fd = open("test.txt", O_CREAT | O_WRONLY, 0644);
  if (fd == -1) {
    perror("Error opening file");
    return -1;
  }
  close(fd);
  return 0;
}
2.2. read()
The read() system call reads data from a file descriptor into a buffer.
Syntax:
ssize_t read(int fd, void *buf, size_t count);
Example:
#include <stdio.h>
#include <unistd.h>
#include <fcntl.h>
int main() {
  int fd = open("test.txt", O_RDONLY);
  char buffer[100];
  if (fd == -1) {
    perror("Error opening file");
    return -1;
  }
  read(fd, buffer, sizeof(buffer));
  printf("Data from file: %s\n", buffer);
  close(fd);
  return 0;
}
```

```
2.3. write()
```

```
The write() system call writes data to a file descriptor.
```

```
Syntax:
ssize_t write(int fd, const void *buf, size_t count);
Example:
#include <stdio.h>
#include <fcntl.h>
#include <unistd.h>
int main() {
  int fd = open("test.txt", O_WRONLY);
  if (fd == -1) {
    perror("Error opening file");
    return -1;
  }
  write(fd, "Hello, World!", 13);
  close(fd);
  return 0;
}
```

2.4. close()

The close() system call closes a file descriptor.

Syntax:

```
int close(int fd);
```

Example:

```
#include <stdio.h>
```

#include <fcntl.h>

#include <unistd.h>

```
int main() {
```

```
int fd = open("test.txt", O_CREAT | O_WRONLY, 0644);
if (fd == -1) {
    perror("Error opening file");
    return -1;
}
close(fd);
return 0;
}
```

3. Device Management System calls read(), write(), ioctl(), select().

3.1. ioctl()

The ioctl() system call controls devices by sending various control commands to a device.

Syntax:

```
int ioctl(int fd, unsigned long request, ...);
Example:
#include <stdio.h>
#include <sys/ioctl.h>
#include <unistd.h>

int main() {
    int fd = open("/dev/sda", O_RDWR);
    if (fd == -1) {
        perror("Error opening device");
        return -1;
    }
    // Example: Get device size using ioctl (this is just an example)
    ioctl(fd, BLKGETSIZE, &size);
    close(fd);
    return 0;
```

```
}
```

3.2. select()

The select() system call is used to monitor multiple file descriptors to see if any are ready for I/O operations.

Syntax:

int select(int nfds, fd_set *readfds, fd_set *writefds, fd_set *exceptfds, struct timeval *timeout);

Example:

```
#include <stdio.h>
#include <sys/select.h>
#include <unistd.h>
int main() {
  fd_set readfds;
  struct timeval timeout;
  FD_ZERO(&readfds);
  FD_SET(0, &readfds); // Monitor stdin
  timeout.tv_sec = 5;
  timeout.tv_usec = 0;
  int ret = select(1, &readfds, NULL, NULL, &timeout);
  if (ret == 0) {
    printf("Timeout occurred! No data input.\n");
  } else {
    printf("Data is available for reading.\n");
  }
  return 0;
}
```

4. Network Management System calls socket(), connect(), send(), recv().

```
4.1. socket()
The socket() system call creates a new socket.
Syntax:
int socket(int domain, int type, int protocol);
Example:
#include <stdio.h>
#include <sys/socket.h>
#include <netinet/in.h>
int main() {
  int sockfd = socket(AF_INET, SOCK_STREAM, 0);
  if (sockfd == -1) {
    perror("Socket creation failed");
    return -1;
  }
  printf("Socket created successfully\n");
  return 0;
}
4.2. connect()
The connect() system call establishes a connection to a specified socket.
Syntax:
int connect(int sockfd, const struct sockaddr *addr, socklen_t addrlen);
Example:
#include <stdio.h>
#include <sys/socket.h>
#include <netinet/in.h>
int main() {
```

int sockfd = socket(AF_INET, SOCK_STREAM, 0);

```
struct sockaddr_in server_addr;
  server_addr.sin_family = AF_INET;
  server_addr.sin_port = htons(8080);
  server_addr.sin_addr.s_addr = inet_addr("127.0.0.1");
  connect(sockfd, (struct sockaddr *)&server_addr, sizeof(server_addr));
  printf("Connected to server\n");
  return 0;
}
4.3. send() and recv()
The send() system call sends data to a socket, and recv() receives data from a socket.
Syntax:
ssize_t send(int sockfd, const void *buf, size_t len, int flags);
ssize_t recv(int sockfd, void *buf, size_t len, int flags);
Example:
#include <stdio.h>
#include <sys/socket.h>
int main() {
  int sockfd = socket(AF_INET, SOCK_STREAM, 0);
  char message[] = "Hello Server!";
  send(sockfd, message, sizeof(message), 0);
  recv(sockfd, message, sizeof(message), 0);
  printf("Received message: %s\n", message);
  return 0;
}
```

5. System Information Management System calls getpid(), getuid(), gethostname(), sysinfo().

5.1. getpid() The getpid() system call returns the process ID of the calling process. Syntax: pid_t getpid(void); **Example:** #include <stdio.h> #include <unistd.h> int main() { printf("Process ID: %d\n", getpid()); return 0; } 5.2. getuid() The getuid() system call returns the user ID of the calling process. Syntax: uid_t getuid(void); Example: #include <stdio.h> #include <unistd.h> int main() { printf("User ID: %d\n", getuid()); return 0;

}

5.3. gethostname()

The gethostname() system call retrieves the hostname of the system.

```
Syntax:
```

```
int gethostname(char *name, size_t len);
Example:
#include <stdio.h>
#include <unistd.h>
int main() {
  char hostname[256];
  gethostname(hostname, sizeof(hostname));
  printf("Hostname: %s\n", hostname);
  return 0;
}
5.4. sysinfo()
The sysinfo() system call provides system statistics like uptime, load average, and available memory.
Syntax:
int sysinfo(struct sysinfo *info);
Example:
#include <stdio.h>
#include <sys/sysinfo.h>
int main() {
  struct sysinfo info;
  sysinfo(&info);
  printf("System uptime: %ld seconds\n", info.uptime);
  return 0;
}
```