

1. Realizar el grafo computacional de las siguientes funciones

a.  $Y = \sin(x^2 + 5x + 2)$

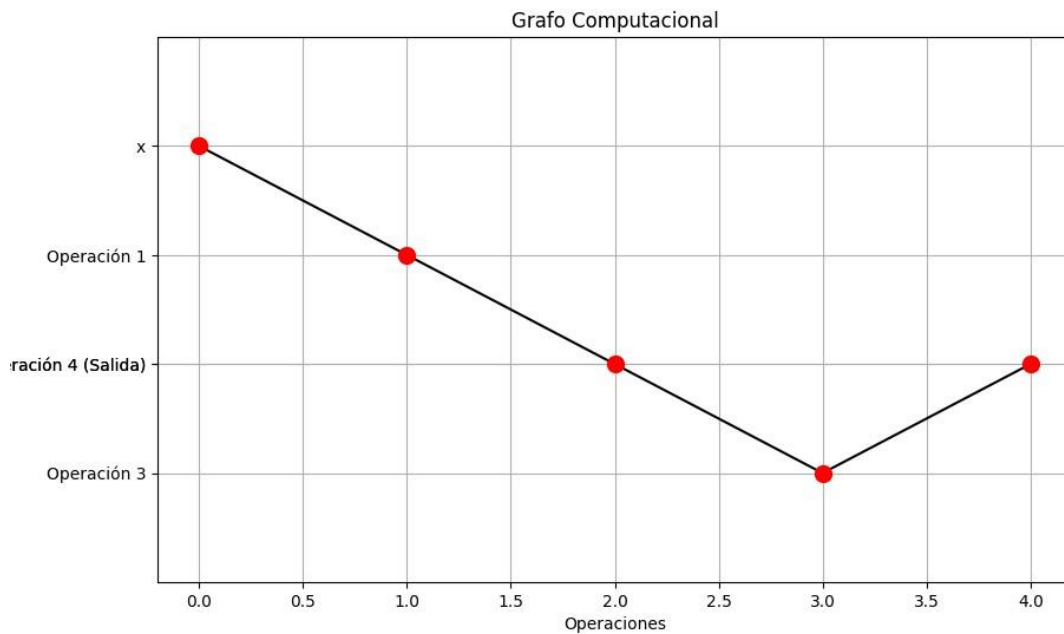
b.  $Y = \cos(2x + 3) - \text{relu}(x)$

c.  $y = \frac{2x}{e^x - 3}$

Cada operación se representa como un nodo en el grafo, y la conexión indica la dirección del flujo de datos.

**a.  $y = \sin(x^2 + 5x + 2)$**

- Operación 1:  $x^2$
- Operación 2:  $x^2 + 5x$
- Operación 3:  $x^2 + 5x + 2$
- Operación 4:  $\sin(x^2 + 5x + 2)$



### Código Python:

```
import matplotlib.pyplot as plt

# Definir las operaciones
operaciones = ["x", "Operación 1", "Operación 2", "Operación 3", "Operación 4 (Salida)"]

# Definir las conexiones entre las operaciones
conexiones = [("x", "Operación 1"), ("Operación 1", "Operación 2"),
              ("Operación 2", "Operación 3"), ("Operación 3", "Operación 4 (Salida)")]

# Crear el gráfico
plt.figure(figsize=(10, 6))

# Asignar alturas a las operaciones en el eje y
alturas = [4, 3, 2, 1, 2]

for conexion in conexiones:
    # Obtener las coordenadas x e y de los nodos
    x_coords = [operaciones.index(conexion[0]), operaciones.index(conexion[1])]
    y_coords = [alturas[operaciones.index(conexion[0])], alturas[operaciones.index(conexion[1])]]
    alturas[operaciones.index(conexion[1])]
    plt.plot(x_coords, y_coords, 'k-') # Dibujar líneas entre nodos

# Dibujar nodos
for op, alt in zip(operaciones, alturas):
    plt.plot(operaciones.index(op), alt, 'ro', markersize=10)

plt.yticks(alturas, operaciones) # Etiquetas del eje y
plt.title("Grafo Computacional")
plt.xlabel("Operaciones")
plt.ylabel("Nivel")
plt.grid(True)
plt.ylim(0, 5) # Limitar el rango del eje y
plt.show()
```

**b.  $y = \cos(2x + 3) - \text{ReLU}(x)$**

- Operación 1:  $2x$
- Operación 2:  $2x + 3$
- Operación 3:  $\cos(2x+3)$
- Operación 4:  $\text{ReLU}(x)$
- Operación 5: Resta  $\cos(2x + 3) - \text{ReLU}(x)$

**Código Python:**

```
import matplotlib.pyplot as plt

# Definir las operaciones
operaciones = ["x", "Operación 1", "Operación 2", "Operación 3", "Operación 4 (Salida)", "Operación 5 (Salida)"]

# Definir las conexiones entre las operaciones
conexiones = [("x", "Operación 1"), ("Operación 1", "Operación 2"),
              ("Operación 2", "Operación 3"), ("Operación 2", "Operación 4 (Salida)",
              ("Operación 3", "Operación 5 (Salida)")]

# Crear el gráfico
plt.figure(figsize=(10, 8))

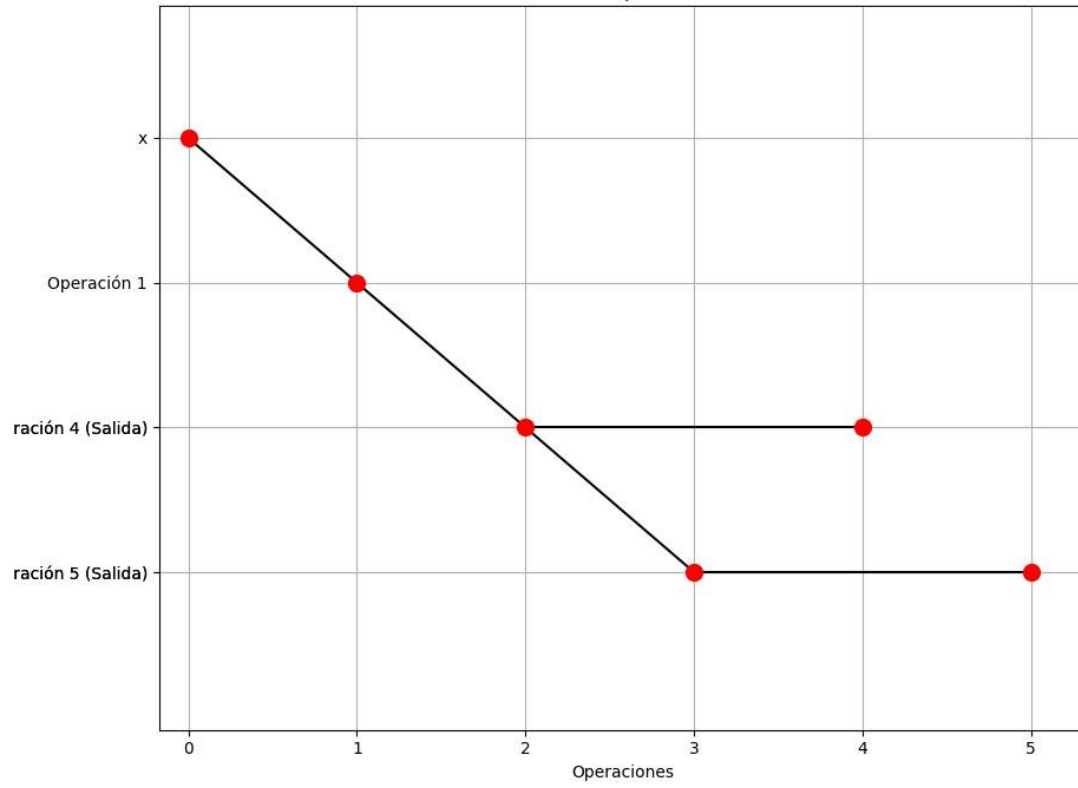
# Asignar alturas a las operaciones en el eje y
alturas = [4, 3, 2, 1, 2, 1]

for conexion in conexiones:
    x_coords = [operaciones.index(conexion[0]), operaciones.index(conexion[1])]
    y_coords = [alturas[operaciones.index(conexion[0])],
    alturas[operaciones.index(conexion[1])]
    plt.plot(x_coords, y_coords, 'k-')

# Dibujar nodos
for op, alt in zip(operaciones, alturas):
    plt.plot(operaciones.index(op), alt, 'ro', markersize=10)

plt.yticks(alturas, operaciones)
plt.title("Grafo Computacional")
plt.xlabel("Operaciones")
plt.ylabel("Nivel")
plt.grid(True)
plt.ylim(0, 5)
plt.show()
```

Grafo Computacional



**c.  $y = 2x / e^x - 3$**

- Operación 1:  $e^x$
- Operación 2:  $e^x - 3$
- Operación 3:  $2x / e^x - 3$

**Código Python:**

```
import matplotlib.pyplot as plt

# Definir las operaciones
operaciones = ["x", "Operación 1", "Operación 2", "Operación 3 (Salida)"]
conexiones = [("x", "Operación 1"), ("Operación 1", "Operación 2"),
               ("Operación 2", "Operación 3 (Salida)")]

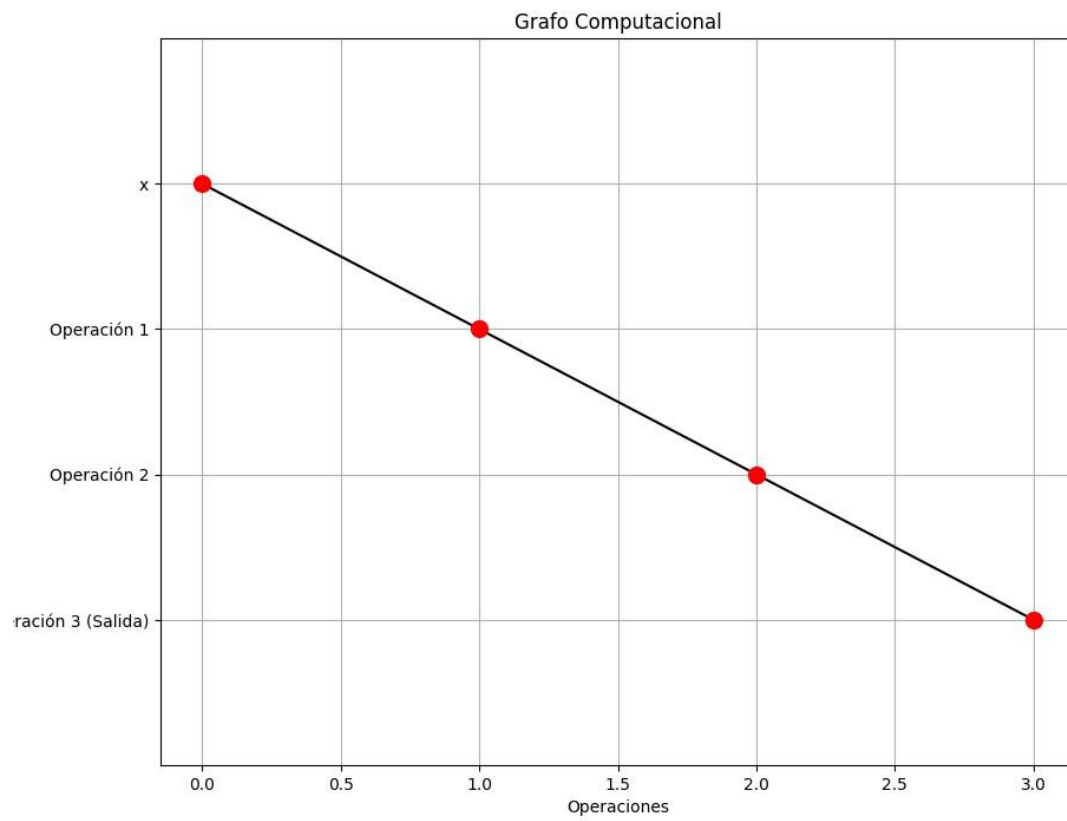
# Crear el gráfico
plt.figure(figsize=(10, 8))

# Asignar alturas a las operaciones en el eje y
alturas = [4, 3, 2, 1]

for conexion in conexiones:
    x_coords = [operaciones.index(conexion[0]), operaciones.index(conexion[1])]
    y_coords = [alturas[operaciones.index(conexion[0])],
                alturas[operaciones.index(conexion[1])]]
    plt.plot(x_coords, y_coords, 'k-')

# Dibujar nodos
for op, alt in zip(operaciones, alturas):
    plt.plot(operaciones.index(op), alt, 'ro', markersize=10)

plt.yticks(alturas, operaciones)
plt.title("Grafo Computacional")
plt.xlabel("Operaciones")
plt.ylabel("Nivel")
plt.grid(True)
plt.ylim(0, 5)
plt.show()
```

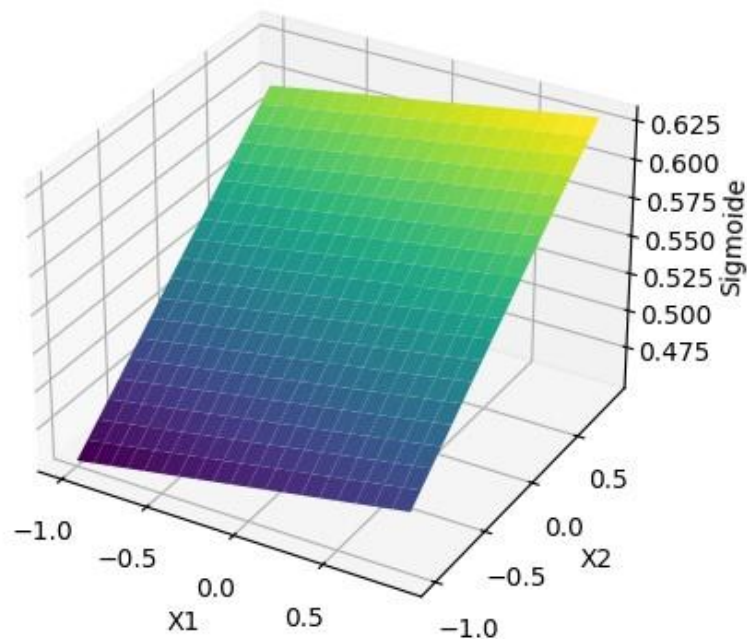


2. Para 5 épocas mostrar los pesos sinápticos, de la función sigmoide en 3d donde los pesos iniciales son [0.1,0.3,-0.7] y el bias es 0.25. las entradas del grafo se colocan en la siguiente tabla.

X1	X2	X3	Y
.3	.2	.1	.7
.1	.1	-.1	.0
.5	-.2	-.4	-.5

- Época 1: Pesos = [ 0.09549605    0.30146127   -0.69594019], Bias = 0.23732116342219975
- Época 2: Pesos = [ 0.09100841    0.3029286   -0.69187558], Bias = 0.22469082984016928
- Época 3: Pesos = [ 0.0865375    0.30440185   -0.68780681], Bias = 0.2121107037594517
- Época 4: Pesos = [ 0.08208374    0.30588089   -0.68373452], Bias = 0.19958244728887575
- Época 5: Pesos = [ 0.07764753    0.30736562   -0.67965934], Bias = 0.18710767864096078

Función Sigmoide con Pesos Sinápticos en 3D



### Código Python:

```
import numpy as np
import matplotlib.pyplot as plt

# Función sigmoide
def sigmoid(x):
    return 1 / (1 + np.exp(-x))

# Datos de entrada y salida
X = np.array([[0.3, 0.2, 0.1],
              [0.1, 0.1, -0.1],
              [0.5, -0.2, -0.4]])
y = np.array([[0.7],
              [0.0],
              [-0.5]])

# Pesos iniciales y bias
weights = np.array([0.1, 0.3, -0.7])
bias = 0.25

# Parámetros del modelo
learning_rate = 0.1
epochs = 5

# Entrenamiento del modelo
for epoch in range(epochs):
    # Forward pass
    weighted_sum = np.dot(X, weights) + bias
    predictions = sigmoid(weighted_sum)

    # Cálculo del error
    error = y - predictions

    # Cálculo de los gradientes
    d_weights = np.mean(X * error * predictions * (1 - predictions), axis=0)
    d_bias = np.mean(error * predictions * (1 - predictions))

    # Actualización de los pesos y el bias
    weights += learning_rate * d_weights
    bias += learning_rate * d_bias

    # Mostrar los pesos sinápticos
    print(f'Época {epoch + 1}: Pesos = {weights}, Bias = {bias}')

# Calcular Z utilizando los valores de X e Y del meshgrid
```



```
Z = sigmoid(weights[0] * X[:, 0] + weights[1] * X[:, 1] + weights[2] * X[:, 2] + bias)
```

```
# Gráfico de los pesos sinápticos
```

```
fig = plt.figure()
```

```
ax = fig.add_subplot(111, projection='3d')
```

```
x = np.arange(-1, 1, 0.1)
```

```
y = np.arange(-1, 1, 0.1)
```

```
X, Y = np.meshgrid(x, y)
```

```
Z = sigmoid(weights[0] * X + weights[1] * Y + bias)
```

```
ax.plot_surface(X, Y, Z, cmap='viridis')
```

```
ax.set_xlabel('X1')
```

```
ax.set_ylabel('X2')
```

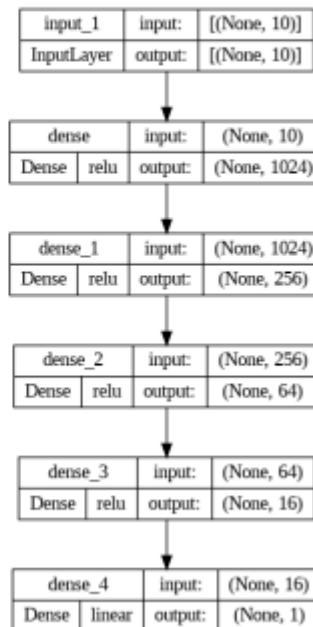
```
ax.set_zlabel('Sigmoide')
```

```
plt.title('Función Sigmoide con Pesos Sinápticos en 3D')
```

```
plt.show()
```

3. Realizar el código fuente que representa los siguientes modelos.

a. Para regresión



**Código Python:**

```
from tensorflow import keras
```

```
# Crear el modelo
```

```
model = keras.models.Sequential()
```

```
# Agregar la capa de entrada
```

```
model.add(keras.layers.Input(shape=(10,)))
```

```
# Agregar capas densas con activación relu
```

```
model.add(keras.layers.Dense(units=1024, activation='relu'))
```

```
model.add(keras.layers.Dense(units=256, activation='relu'))
```

```
model.add(keras.layers.Dense(units=64, activation='relu'))
```

```
model.add(keras.layers.Dense(units=16, activation='relu'))
```

```
# Agregar capa densa con activación lineal
```

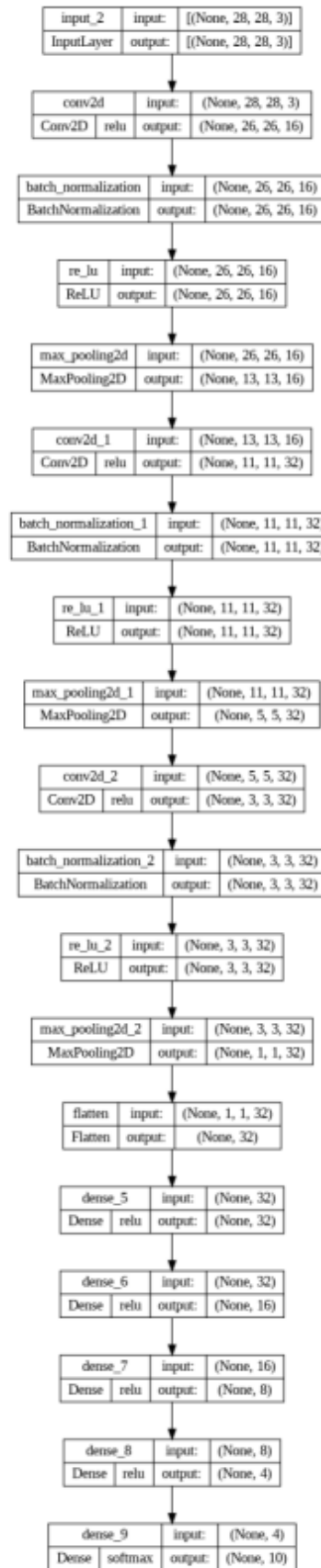
```
model.add(keras.layers.Dense(units=1, activation='linear'))
```

```
# Mostrar el resumen del modelo
```

```
model.summary()
```

Layer (type)	Output Shape	Param #
dense	(None, 1024)	11,264
dense_1	(None, 256)	262,400
dense_2	(None, 64)	16,448
dense_3	(None, 16)	1,040
dense_4	(None, 1)	17

b. Para clasificación



### Código Python:

```
import tensorflow as tf
from tensorflow.keras.models import Model
from tensorflow.keras.layers import Input, Conv2D, BatchNormalization, ReLU,
MaxPooling2D, Flatten, Dense
import pandas as pd

# Define the model
input_layer = Input(shape=(28, 28, 3))
x = Conv2D(16, kernel_size=(3, 3), activation='relu')(input_layer)
x = BatchNormalization()(x)
x = MaxPooling2D(pool_size=(2, 2))(x)
x = Conv2D(32, kernel_size=(3, 3), activation='relu')(x)
x = BatchNormalization()(x)
x = MaxPooling2D(pool_size=(2, 2))(x)
x = Flatten()(x)
x = Dense(32, activation='relu')(x)
x = Dense(16, activation='relu')(x)
x = Dense(8, activation='relu')(x)
x = Dense(4, activation='relu')(x)
output_layer = Dense(10, activation='softmax')(x)
model = Model(inputs=input_layer, outputs=output_layer)

# Compile the model
model.compile(optimizer='adam', loss='categorical_crossentropy',
metrics=['accuracy'])

# Crear un DataFrame con los datos de la tabla
data = {
    "Capa": ["Input", "Conv2D-1", "BatchNormalization-1", "MaxPooling2D-1",
            "Conv2D-2", "BatchNormalization-2", "MaxPooling2D-2",
            "Flatten", "Dense-1", "Dense-2", "Dense-3", "Dense-4", "Output"],
    "Tipo": ["Input", "Conv2D", "BatchNormalization", "MaxPooling2D",
            "Conv2D", "BatchNormalization", "MaxPooling2D",
            "Flatten", "Dense", "Dense", "Dense", "Dense", "Dense"],
    "Salida": ["(28, 28, 3)", "(26, 26, 16)", "(26, 26, 16)", "(13, 13, 16)",
            "(11, 11, 32)", "(11, 11, 32)", "(5, 5, 32)",
            "800", "32", "16", "8", "4", "10"],
    "Parámetros": [0, 448, 64, 0, 4640, 128, 0, 0, 25632, 528, 136, 36, 50]
}

df = pd.DataFrame(data)

# Imprimir el modelo
print("Arquitectura del Modelo:")
```

```

print(model.summary())
print("\n")

# Imprimir el DataFrame como tabla
print("Tabla de Capas:")
print(df)

```

Layer (type)	Output Shape	Param #
input_layer (InputLayer)	(None, 28, 28, 3)	0
conv2d (Conv2D)	(None, 26, 26, 16)	448
batch_normalization (BatchNormalization)	(None, 26, 26, 16)	64
max_pooling2d (MaxPooling2D)	(None, 13, 13, 16)	0
conv2d_1 (Conv2D)	(None, 11, 11, 32)	4,640
batch_normalization_1 (BatchNormalization)	(None, 11, 11, 32)	128
max_pooling2d_1 (MaxPooling2D)	(None, 5, 5, 32)	0
	(None, 800)	0
dense (Dense)	(None, 32)	25,632
dense_1 (Dense)	(None, 16)	528
dense_2 (Dense)	(None, 8)	136
dense_3 (Dense)	(None, 4)	36
dense_4 (Dense)	(None, 10)	50

4. Configurar un autoencoder para el conjunto de datos fashion mnist [https://keras.io/api/datasets/fashion\\_mnist/](https://keras.io/api/datasets/fashion_mnist/), para ello:
  - a. aplanar las imágenes y normalizar.
  - b. Configurar para el encoder la siguiente arquitectura [256,128,64,32].
  - c. Entrenar el modelo con Early Stopping y BatchNormalization, para 1000 épocas.
  - d. Mostrar 12 salidas aleatorias del autoencoder y compararlas con las imágenes originales.

### Código Python:

```
import numpy as np
import matplotlib.pyplot as plt
from keras.datasets import fashion_mnist
from keras.models import Sequential, Model
from keras.layers import Dense, Input
from keras.callbacks import EarlyStopping
# Importar BatchNormalization desde tensorflow.keras.layers
from tensorflow.keras.layers import BatchNormalization

# Cargar el conjunto de datos Fashion MNIST
(x_train, _), (x_test, _) = fashion_mnist.load_data()

# Normalizar y aplanar las imágenes
x_train = x_train.astype('float32') / 255.
x_test = x_test.astype('float32') / 255.
x_train = x_train.reshape((len(x_train), np.prod(x_train.shape[1:])))
x_test = x_test.reshape((len(x_test), np.prod(x_test.shape[1:])))

# Configurar la arquitectura del autoencoder
input_dim = x_train.shape[1]
encoding_dim = 32

input_img = Input(shape=(input_dim,))
encoded = Dense(256, activation='relu')(input_img)
encoded = BatchNormalization()(encoded)
encoded = Dense(128, activation='relu')(encoded)
encoded = BatchNormalization()(encoded)
encoded = Dense(64, activation='relu')(encoded)
encoded = BatchNormalization()(encoded)
encoded = Dense(encoding_dim, activation='relu')(encoded)

decoded = Dense(64, activation='relu')(encoded)
decoded = Dense(128, activation='relu')(decoded)
decoded = Dense(256, activation='relu')(decoded)
decoded = Dense(input_dim, activation='sigmoid')(decoded)
```

```
autoencoder = Model(input_img, decoded)

# Compilar el modelo
autoencoder.compile(optimizer='adam', loss='binary_crossentropy')

# Configurar Early Stopping
early_stopping = EarlyStopping(monitor='val_loss', patience=5, verbose=1)

# Entrenar el modelo
history = autoencoder.fit(x_train, x_train,
                          epochs=1000,
                          batch_size=256,
                          shuffle=True,
                          validation_data=(x_test, x_test),
                          callbacks=[early_stopping])

# Mostrar 12 salidas aleatorias del autoencoder y compararlas con las imágenes
originales
decoded_imgs = autoencoder.predict(x_test)

n = 12
plt.figure(figsize=(20, 4))
for i in range(n):
    # Mostrar la imagen original
    ax = plt.subplot(2, n, i + 1)
    plt.imshow(x_test[i].reshape(28, 28))
    plt.gray()
    ax.get_xaxis().set_visible(False)
    ax.get_yaxis().set_visible(False)

    # Mostrar la reconstrucción
    ax = plt.subplot(2, n, i + 1 + n)
    plt.imshow(decoded_imgs[i].reshape(28, 28))
    plt.gray()
    ax.get_xaxis().set_visible(False)
    ax.get_yaxis().set_visible(False)
plt.show()
```



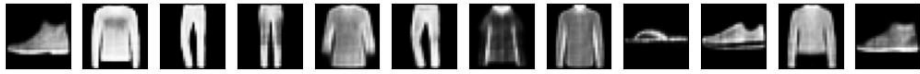
Epoch 1/1000  
235/235 ————— 15s 33ms/step - loss: 0.4215  
- val\_loss: 0.3384  
Epoch 2/1000  
235/235 ————— 8s 33ms/step - loss: 0.3086 -  
val\_loss: 0.3040  
Epoch 3/1000  
235/235 ————— 9s 40ms/step - loss: 0.3015 -  
val\_loss: 0.2978  
Epoch 4/1000  
235/235 ————— 8s 35ms/step - loss: 0.2966 -  
val\_loss: 0.2951  
Epoch 5/1000  
235/235 ————— 9s 39ms/step - loss: 0.2928 -  
val\_loss: 0.2931  
Epoch 6/1000  
235/235 ————— 9s 37ms/step - loss: 0.2907 -  
val\_loss: 0.2914  
Epoch 7/1000  
235/235 ————— 8s 33ms/step - loss: 0.2884 -  
val\_loss: 0.2910  
Epoch 8/1000  
235/235 ————— 8s 35ms/step - loss: 0.2877 -  
val\_loss: 0.2887  
Epoch 9/1000  
235/235 ————— 8s 33ms/step - loss: 0.2865 -  
val\_loss: 0.2878  
Epoch 10/1000  
235/235 ————— 9s 36ms/step - loss: 0.2860 -  
val\_loss: 0.2861  
Epoch 11/1000  
235/235 ————— 8s 32ms/step - loss: 0.2848 -  
val\_loss: 0.2873  
Epoch 12/1000  
235/235 ————— 8s 33ms/step - loss: 0.2840 -  
val\_loss: 0.2845  
Epoch 13/1000  
235/235 ————— 7s 31ms/step - loss: 0.2833 -  
val\_loss: 0.2844  
Epoch 14/1000

235/235 ————— 8s 32ms/step - loss: 0.2822 -  
val\_loss: 0.2843  
Epoch 15/1000  
235/235 ————— 7s 32ms/step - loss: 0.2826 -  
val\_loss: 0.2834  
Epoch 16/1000  
235/235 ————— 8s 33ms/step - loss: 0.2818 -  
val\_loss: 0.2821  
Epoch 17/1000  
235/235 ————— 10s 40ms/step - loss: 0.2811  
- val\_loss: 0.2822  
Epoch 18/1000  
235/235 ————— 8s 32ms/step - loss: 0.2805 -  
val\_loss: 0.2816  
Epoch 19/1000  
235/235 ————— 8s 33ms/step - loss: 0.2800 -  
val\_loss: 0.2818  
Epoch 20/1000  
235/235 ————— 7s 31ms/step - loss: 0.2794 -  
val\_loss: 0.2810  
Epoch 21/1000  
235/235 ————— 8s 34ms/step - loss: 0.2795 -  
val\_loss: 0.2804  
Epoch 22/1000  
235/235 ————— 8s 33ms/step - loss: 0.2784 -  
val\_loss: 0.2815  
Epoch 23/1000  
235/235 ————— 8s 32ms/step - loss: 0.2786 -  
val\_loss: 0.2802  
Epoch 24/1000  
235/235 ————— 8s 33ms/step - loss: 0.2785 -  
val\_loss: 0.2817  
Epoch 25/1000  
235/235 ————— 8s 32ms/step - loss: 0.2778 -  
val\_loss: 0.2789  
Epoch 26/1000  
235/235 ————— 8s 33ms/step - loss: 0.2781 -  
val\_loss: 0.2790  
Epoch 27/1000  
235/235 ————— 9s 37ms/step - loss: 0.2774 -  
val\_loss: 0.2803

Epoch 28/1000  
235/235 ————— 10s 43ms/step - loss: 0.2777  
- val\_loss: 0.2783  
Epoch 29/1000  
235/235 ————— 8s 35ms/step - loss: 0.2770 -  
val\_loss: 0.2779  
Epoch 30/1000  
235/235 ————— 8s 33ms/step - loss: 0.2768 -  
val\_loss: 0.2789  
Epoch 31/1000  
235/235 ————— 12s 50ms/step - loss: 0.2757  
- val\_loss: 0.2780  
Epoch 32/1000  
235/235 ————— 11s 45ms/step - loss: 0.2766  
- val\_loss: 0.2772  
Epoch 33/1000  
235/235 ————— 8s 32ms/step - loss: 0.2756 -  
val\_loss: 0.2771  
Epoch 34/1000  
235/235 ————— 14s 59ms/step - loss: 0.2765  
- val\_loss: 0.2775  
Epoch 35/1000  
235/235 ————— 13s 54ms/step - loss: 0.2760  
- val\_loss: 0.2772  
Epoch 36/1000  
235/235 ————— 11s 48ms/step - loss: 0.2750  
- val\_loss: 0.2771  
Epoch 37/1000  
235/235 ————— 10s 42ms/step - loss: 0.2748  
- val\_loss: 0.2765  
Epoch 38/1000  
235/235 ————— 10s 42ms/step - loss: 0.2751  
- val\_loss: 0.2760  
Epoch 39/1000  
235/235 ————— 12s 49ms/step - loss: 0.2744  
- val\_loss: 0.2757  
Epoch 40/1000  
235/235 ————— 11s 45ms/step - loss: 0.2747  
- val\_loss: 0.2761  
Epoch 41/1000

235/235 ————— 10s 40ms/step - loss: 0.2741  
- val\_loss: 0.2755  
Epoch 42/1000  
235/235 ————— 9s 36ms/step - loss: 0.2740 -  
val\_loss: 0.2760  
Epoch 43/1000  
235/235 ————— 9s 40ms/step - loss: 0.2739 -  
val\_loss: 0.2752  
Epoch 44/1000  
235/235 ————— 9s 37ms/step - loss: 0.2736 -  
val\_loss: 0.2782  
Epoch 45/1000  
235/235 ————— 9s 39ms/step - loss: 0.2732 -  
val\_loss: 0.2748  
Epoch 46/1000  
235/235 ————— 9s 38ms/step - loss: 0.2731 -  
val\_loss: 0.2757  
Epoch 47/1000  
235/235 ————— 9s 37ms/step - loss: 0.2734 -  
val\_loss: 0.2757  
Epoch 48/1000  
235/235 ————— 9s 38ms/step - loss: 0.2734 -  
val\_loss: 0.2744  
Epoch 49/1000  
235/235 ————— 9s 39ms/step - loss: 0.2726 -  
val\_loss: 0.2743  
Epoch 50/1000  
235/235 ————— 11s 46ms/step - loss: 0.2727  
- val\_loss: 0.2745  
Epoch 51/1000  
235/235 ————— 11s 45ms/step - loss: 0.2730  
- val\_loss: 0.2741  
Epoch 52/1000  
235/235 ————— 8s 33ms/step - loss: 0.2718 -  
val\_loss: 0.2744  
Epoch 53/1000  
235/235 ————— 8s 32ms/step - loss: 0.2726 -  
val\_loss: 0.2744  
Epoch 54/1000  
235/235 ————— 8s 34ms/step - loss: 0.2723 -  
val\_loss: 0.2738

Epoch 55/1000  
235/235 ————— 8s 36ms/step - loss: 0.2716 -  
val\_loss: 0.2736  
Epoch 56/1000  
235/235 ————— 8s 33ms/step - loss: 0.2720 -  
val\_loss: 0.2737  
Epoch 57/1000  
235/235 ————— 8s 34ms/step - loss: 0.2717 -  
val\_loss: 0.2730  
Epoch 58/1000  
235/235 ————— 8s 34ms/step - loss: 0.2709 -  
val\_loss: 0.2734  
Epoch 59/1000  
235/235 ————— 8s 35ms/step - loss: 0.2717 -  
val\_loss: 0.2739  
Epoch 60/1000  
235/235 ————— 8s 33ms/step - loss: 0.2714 -  
val\_loss: 0.2738  
Epoch 61/1000  
235/235 ————— 8s 34ms/step - loss: 0.2716 -  
val\_loss: 0.2736  
Epoch 62/1000  
235/235 ————— 8s 34ms/step - loss: 0.2709 -  
val\_loss: 0.2738  
Epoch 62: early stopping  
313/313 ————— 2s 6ms/step



5. Realizar los mismos puntos anteriores pero con una arquitectura convolucional [32,16,8] padding same.

### Código Python:

```
import numpy as np
import matplotlib.pyplot as plt
from tensorflow.keras.datasets import fashion_mnist
from tensorflow.keras.models import Sequential, Model
from tensorflow.keras.layers import Conv2D, MaxPooling2D, UpSampling2D, Input
from tensorflow.keras.callbacks import EarlyStopping
from tensorflow.keras.layers import BatchNormalization

# Cargar el conjunto de datos Fashion MNIST
(x_train, _), (x_test, _) = fashion_mnist.load_data()

# Normalizar y cambiar el formato de las imágenes
x_train = x_train.astype('float32') / 255.
x_test = x_test.astype('float32') / 255.
x_train = np.reshape(x_train, (len(x_train), 28, 28, 1)) # Añadimos una dimensión
para el canal (1 para escala de grises)
x_test = np.reshape(x_test, (len(x_test), 28, 28, 1))

# Configurar la arquitectura del autoencoder
input_img = Input(shape=(28, 28, 1))

# Encoder
x = Conv2D(32, (3, 3), activation='relu', padding='same')(input_img)
x = MaxPooling2D((2, 2), padding='same')(x)
x = BatchNormalization()(x)
x = Conv2D(16, (3, 3), activation='relu', padding='same')(x)
x = MaxPooling2D((2, 2), padding='same')(x)
x = BatchNormalization()(x)
x = Conv2D(8, (3, 3), activation='relu', padding='same')(x)
encoded = MaxPooling2D((2, 2), padding='same')(x)

# Decoder
x = Conv2D(8, (3, 3), activation='relu', padding='same')(encoded)
x = UpSampling2D((2, 2))(x)
x = Conv2D(16, (3, 3), activation='relu', padding='same')(x)
x = UpSampling2D((2, 2))(x)
x = Conv2D(32, (3, 3), activation='relu')(x)
x = UpSampling2D((2, 2))(x)
decoded = Conv2D(1, (3, 3), activation='sigmoid', padding='same')(x)

autoencoder = Model(input_img, decoded)
```

```
# Compilar el modelo
autoencoder.compile(optimizer='adam', loss='binary_crossentropy')

# Configurar Early Stopping
early_stopping = EarlyStopping(monitor='val_loss', patience=5, verbose=1)

# Entrenar el modelo
history = autoencoder.fit(x_train, x_train,
                          epochs=1000,
                          batch_size=256,
                          shuffle=True,
                          validation_data=(x_test, x_test),
                          callbacks=[early_stopping])

# Mostrar 12 salidas aleatorias del autoencoder y compararlas con las imágenes
originales
decoded_imgs = autoencoder.predict(x_test)

n = 12
plt.figure(figsize=(20, 4))
for i in range(n):
    # Mostrar la imagen original
    ax = plt.subplot(2, n, i + 1)
    plt.imshow(x_test[i].reshape(28, 28))
    plt.gray()
    ax.get_xaxis().set_visible(False)
    ax.get_yaxis().set_visible(False)

    # Mostrar la reconstrucción
    ax = plt.subplot(2, n, i + 1 + n)
    plt.imshow(decoded_imgs[i].reshape(28, 28))
    plt.gray()
    ax.get_xaxis().set_visible(False)
    ax.get_yaxis().set_visible(False)
plt.show()
```



235/235	_____	49s	173ms/step	-	loss:
0.4061 - val_loss: 0.5005					
Epoch 2/1000					
235/235	_____	46s	195ms/step	-	loss:
0.3035 - val_loss: 0.3638					
Epoch 3/1000					
235/235	_____	45s	193ms/step	-	loss:
0.2966 - val_loss: 0.2996					
Epoch 4/1000					
235/235	_____	51s	216ms/step	-	loss:
0.2923 - val_loss: 0.2919					
Epoch 5/1000					
235/235	_____	51s	218ms/step	-	loss:
0.2897 - val_loss: 0.2902					
Epoch 6/1000					
235/235	_____	51s	215ms/step	-	loss:
0.2881 - val_loss: 0.2885					
Epoch 7/1000					
235/235	_____	48s	203ms/step	-	loss:
0.2868 - val_loss: 0.2893					
Epoch 8/1000					
235/235	_____	48s	203ms/step	-	loss:
0.2851 - val_loss: 0.2862					
Epoch 9/1000					
235/235	_____	49s	210ms/step	-	loss:
0.2849 - val_loss: 0.2866					
Epoch 10/1000					
235/235	_____	51s	217ms/step	-	loss:
0.2834 - val_loss: 0.2846					
Epoch 11/1000					
235/235	_____	50s	214ms/step	-	loss:
0.2827 - val_loss: 0.2832					
Epoch 12/1000					
235/235	_____	48s	202ms/step	-	loss:
0.2823 - val_loss: 0.2831					
Epoch 13/1000					
235/235	_____	46s	193ms/step	-	loss:
0.2831 - val_loss: 0.2824					
Epoch 14/1000					
235/235	_____	45s	190ms/step	-	loss:
0.2814 - val_loss: 0.2820					

Epoch 15/1000  
235/235 ————— 45s 193ms/step - loss:  
0.2799 - val\_loss: 0.2835  
Epoch 16/1000  
235/235 ————— 46s 195ms/step - loss:  
0.2799 - val\_loss: 0.2808  
Epoch 17/1000  
235/235 ————— 47s 201ms/step - loss:  
0.2799 - val\_loss: 0.2804  
Epoch 18/1000  
235/235 ————— 48s 204ms/step - loss:  
0.2791 - val\_loss: 0.2799  
Epoch 19/1000  
235/235 ————— 47s 200ms/step - loss:  
0.2787 - val\_loss: 0.2802  
Epoch 20/1000  
235/235 ————— 44s 188ms/step - loss:  
0.2784 - val\_loss: 0.2793  
Epoch 21/1000  
235/235 ————— 46s 193ms/step - loss:  
0.2782 - val\_loss: 0.2798  
Epoch 22/1000  
235/235 ————— 45s 193ms/step - loss:  
0.2782 - val\_loss: 0.2794  
Epoch 23/1000  
235/235 ————— 44s 188ms/step - loss:  
0.2770 - val\_loss: 0.2808  
Epoch 24/1000  
235/235 ————— 48s 205ms/step - loss:  
0.2771 - val\_loss: 0.2832  
Epoch 25/1000  
235/235 ————— 46s 197ms/step - loss:  
0.2774 - val\_loss: 0.2837  
Epoch 25: early stopping  
313/313 ————— 7s 19ms/step

