
Computer Graphics

Projection

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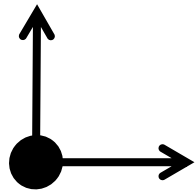
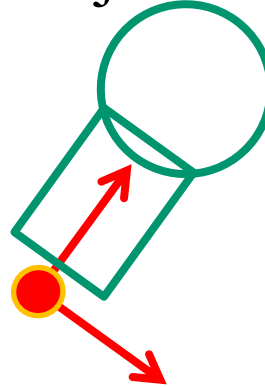
In the previous episodes

- Vectors & Tools

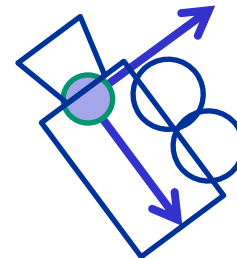


In the previous episodes

Object's frame



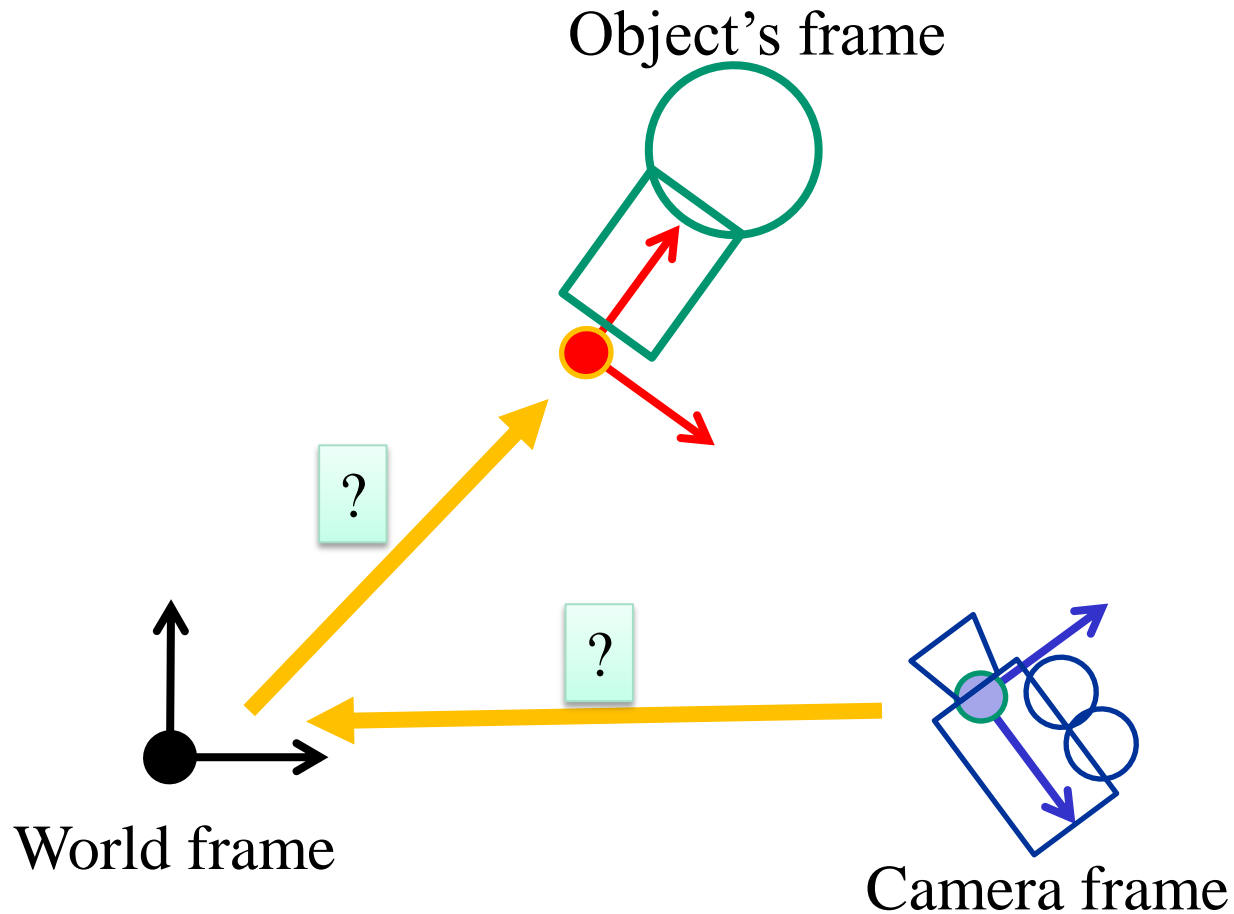
World frame



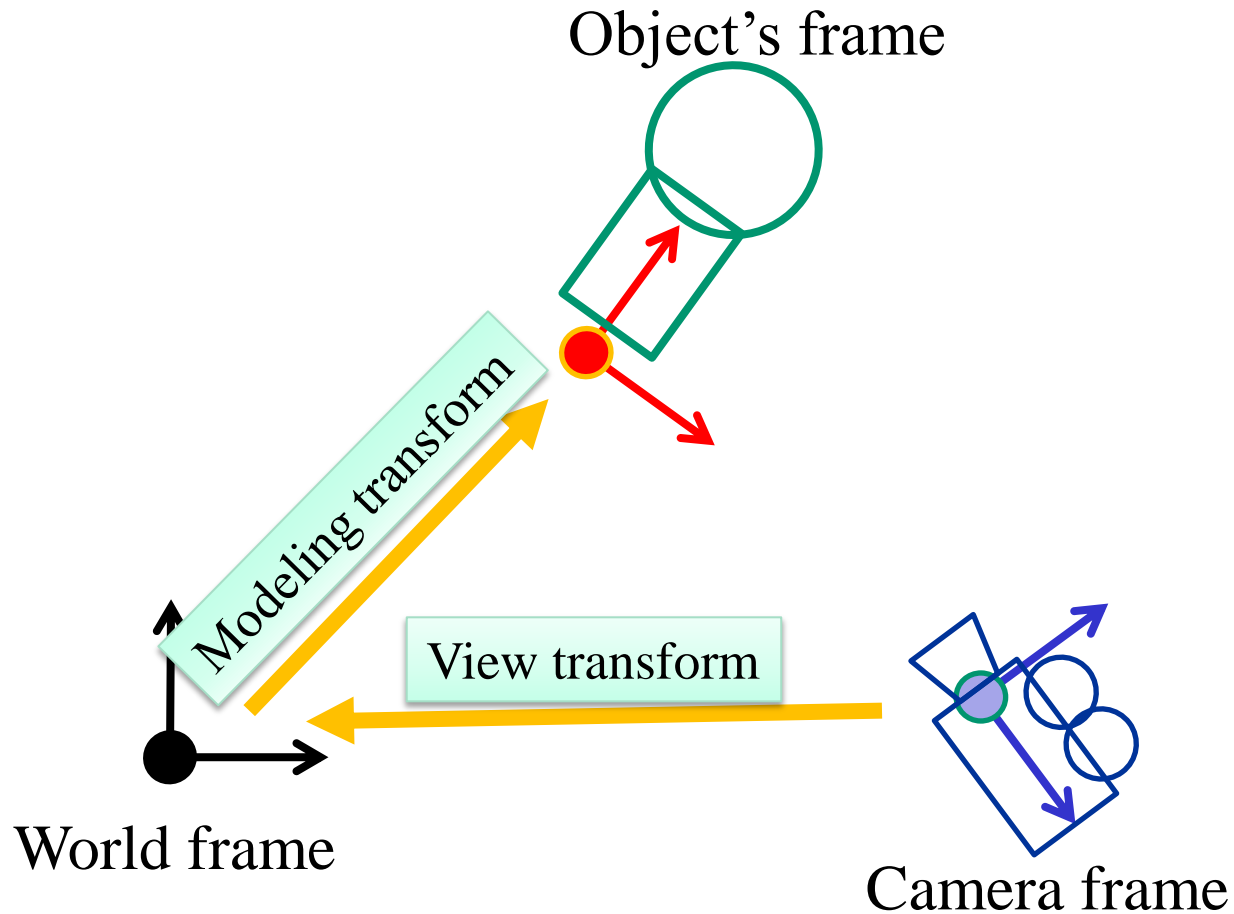
Camera frame



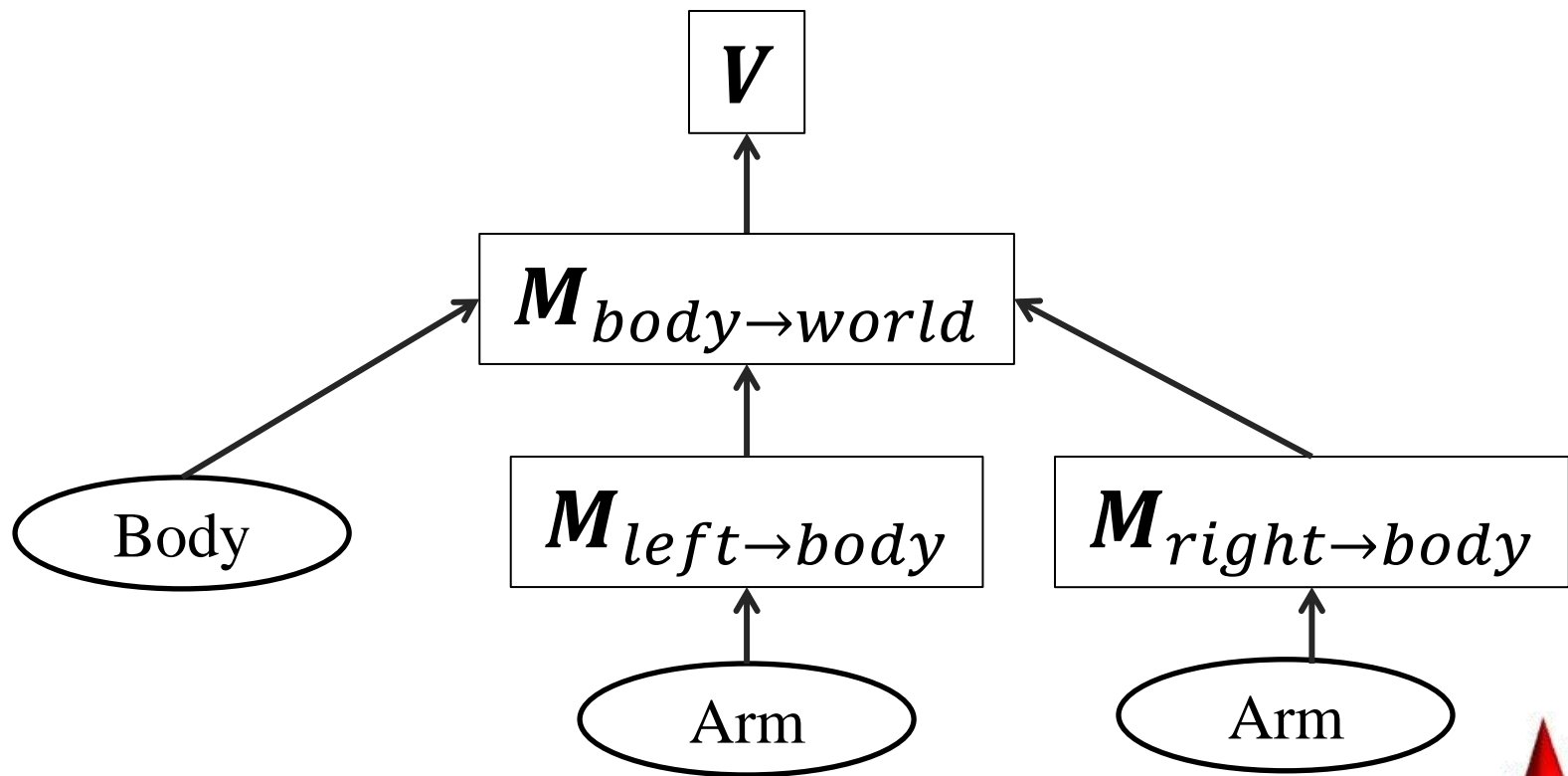
In the previous episodes



Model-View transformations



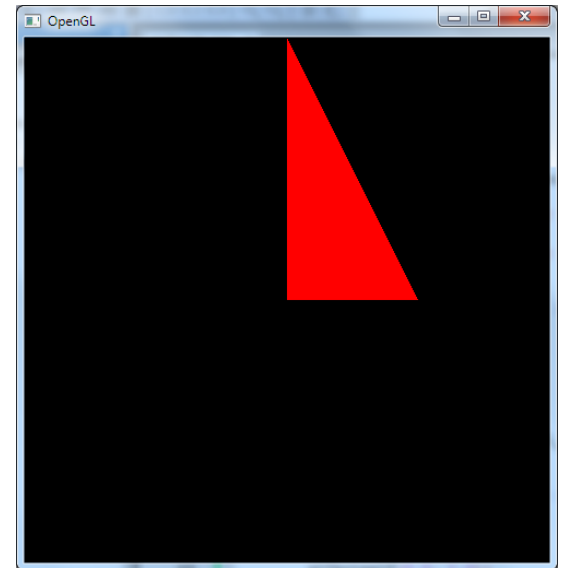
Scene graph



Quiz

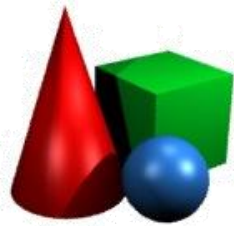
- In OpenGL, the code on the left will always result in the picture of a triangle as shown on the right. True or False?

```
glBegin(GL_TRIANGLES);  
    glVertex2f(0.0, 0.0);  
    glVertex2f(0.5, 0.0);  
    glVertex2f(0.0, 1.0);  
glEnd();
```



Model-view matrix

- The Model-view matrix can be provided explicitly
 - `glLoadMatrix* (.)`
- Or, more commonly, constructed by multiplying with elementary matrices **on the right**.
 - `glLoadIdentity() ;` $\mathcal{M} = I$
 - `glTranslatef(...) ;` $\mathcal{M} = IT$
 - `glRotatef(...) ;` $\mathcal{M} = ITR$



Today

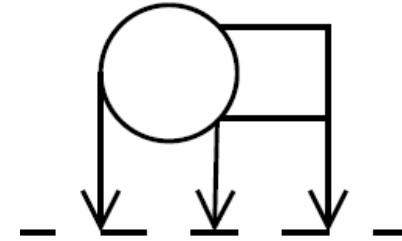
- The Model-View matrix is not the only step that the vertices pass before being displayed.
- After the MV transform the vertices are *projected*.



Planar geometric projections

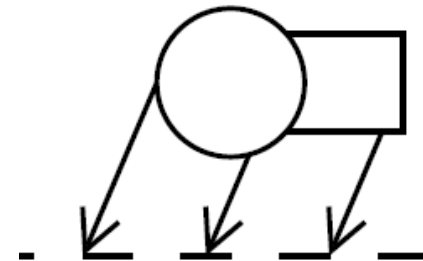
- **Orthographic**

- ▶ Front-top-bottom
- ▶ Axonometric
(isometry, dimetry,...)

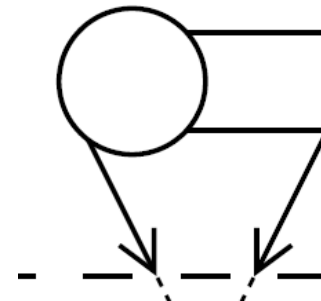


- **Oblique**

- ▶ Cavalier, cabinet



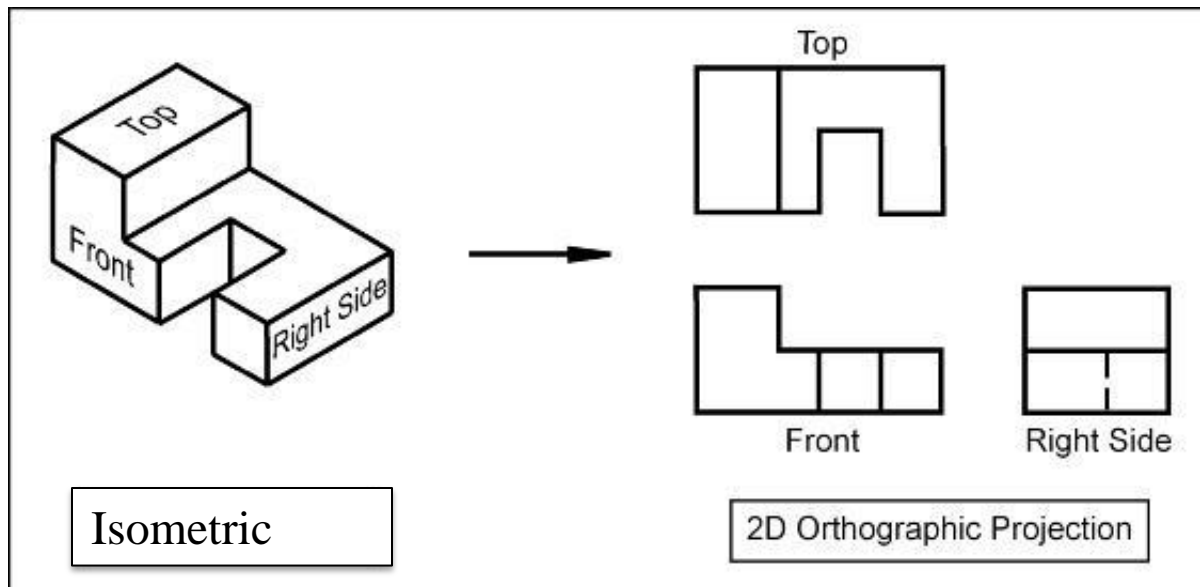
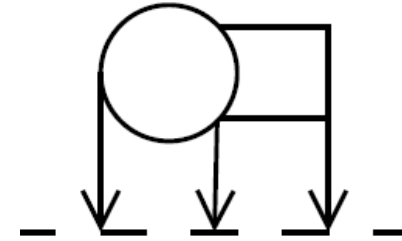
- **Perspective**



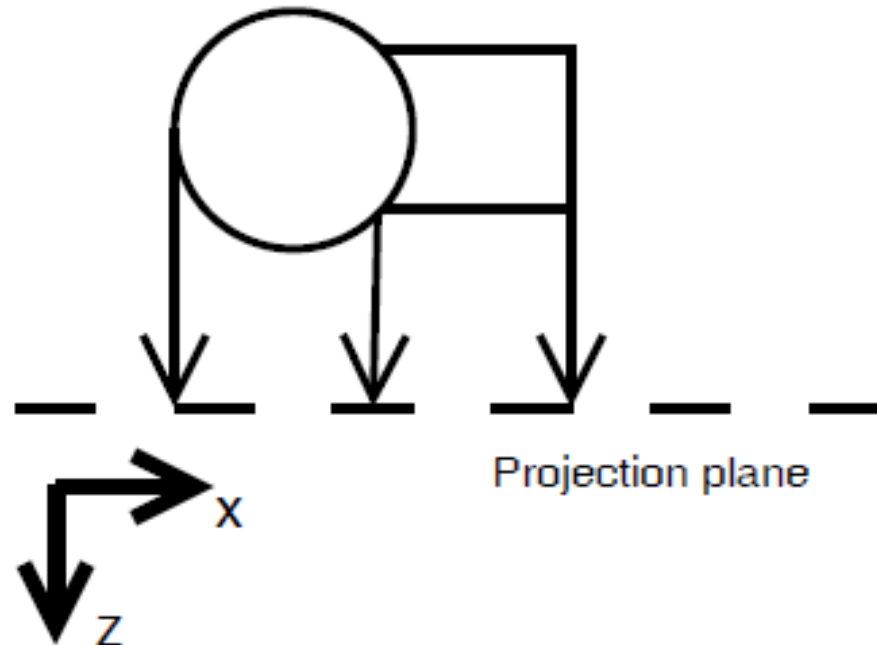
Planar geometric projections

- **Orthographic**

- ▶ Front-top-bottom
- ▶ Axonometric
(isometry, dimetry,...)



Orthographic projection



$$x' = x \quad y' = y \quad z' = 0$$



Quiz

- Represent orthographic projection as an affine transformation matrix.



Quiz

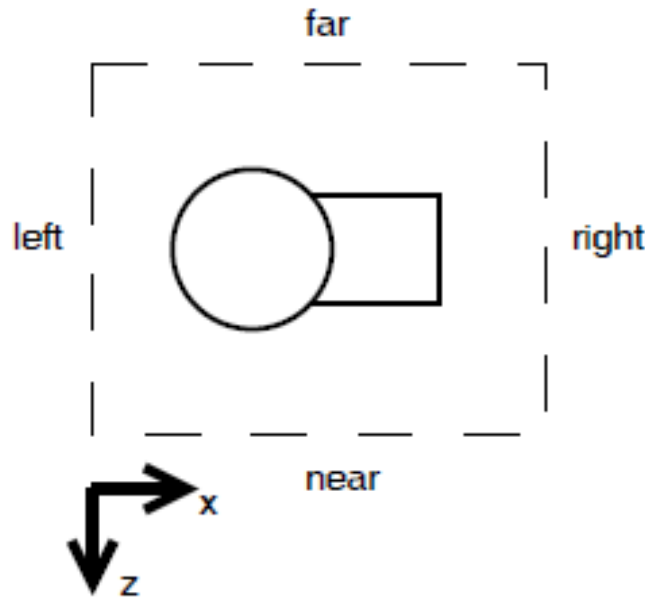
- Represent orthographic projection as an affine transformation matrix.

$$\begin{pmatrix} x' \\ y' \\ z' \\ 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix}$$



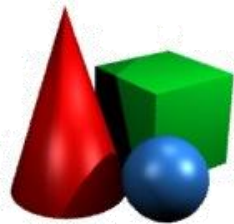
Clipping box

- The screen is not infinite, and we have to specify the actual area that will be displayed: *the clipping box*.



Clipping box

- The clipping box is defined using six *clipping planes*: left, right, top, bottom, near, far.
- It is convenient to transform the space so that the clipping box turns into the cube
$$\{-1 \leq x \leq 1, -1 \leq y \leq 1, -1 \leq z \leq 1\}$$
- The result is often referred to as *normalized device coordinates* or *the clip space*.



Orthographic projection

- Thus, before projecting to (x, y) we normalize to clip space:

$$x' = \frac{2}{x_r - x_l} \left(x - \frac{x_r + x_l}{2} \right)$$

$$y' = \frac{2}{y_t - y_b} \left(y - \frac{y_t + y_b}{2} \right)$$

$$z' = \frac{2}{z_n - z_f} \left(z - \frac{z_n + z_f}{2} \right)$$

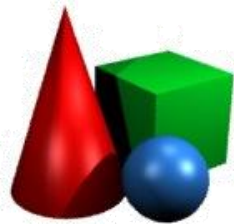


Orthographic projection

$$x' = \frac{2}{x_r - x_l}x - \frac{x_r + x_l}{x_r - x_l}$$

$$y' = \frac{2}{y_t - y_b}y - \frac{y_t + y_b}{y_t - y_b}$$

$$z' = \frac{2}{z_n - z_f}z - \frac{z_n + z_f}{z_n - z_f}$$



Orthographic projection

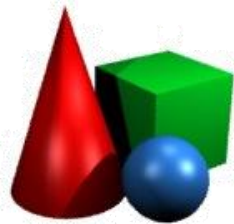
$$\begin{pmatrix} x' \\ y' \\ z' \\ 1 \end{pmatrix} = \begin{pmatrix} \frac{2}{x_r - x_l} & 0 & 0 & -\frac{x_r + x_l}{x_r - x_l} \\ 0 & \frac{2}{y_t - y_b} & 0 & -\frac{y_t + y_b}{y_t - y_b} \\ 0 & 0 & \frac{2}{z_n - z_f} & -\frac{z_n + z_f}{z_n - z_f} \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix}$$



Orthographic projection

$$\begin{pmatrix} x' \\ y' \\ z' \\ 1 \end{pmatrix} = \begin{pmatrix} \frac{2}{x_r - x_l} & 0 & 0 & -\frac{x_r + x_l}{x_r - x_l} \\ 0 & \frac{2}{y_t - y_b} & 0 & -\frac{y_t + y_b}{y_t - y_b} \\ 0 & 0 & \frac{2}{z_n - z_f} & -\frac{z_n + z_f}{z_n - z_f} \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix}$$

- In fact, we do not want to lose the z coordinate just yet.



Orthographic projection

- Denote the matrix shown before by P_{ort} .
Now, given the model & view transformations, the complete mapping for each vertex \mathbf{x}_i to clip space is given by:

$$P_{\text{ort}}VM\mathbf{x}_i$$



Orthographic projection

- The projection matrix is also part of OpenGL state:

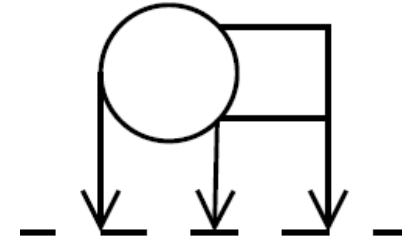
```
glMatrixMode(GL_PROJECTION);  
glLoadIdentity();  
glOrtho(left, right, bottom, top, near, far);  
glMatrixMode(GL_MODELVIEW);
```



Planar geometric projections

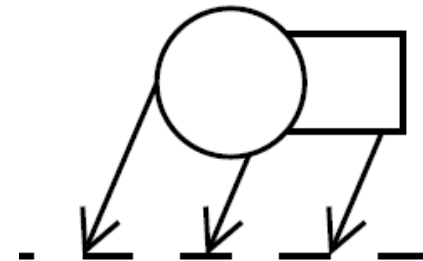
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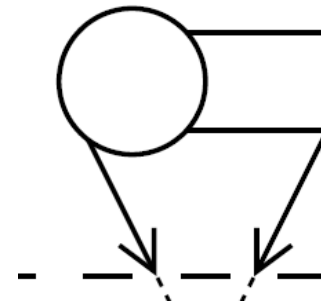


- **Oblique**

- ▶ Cavalier, cabinet



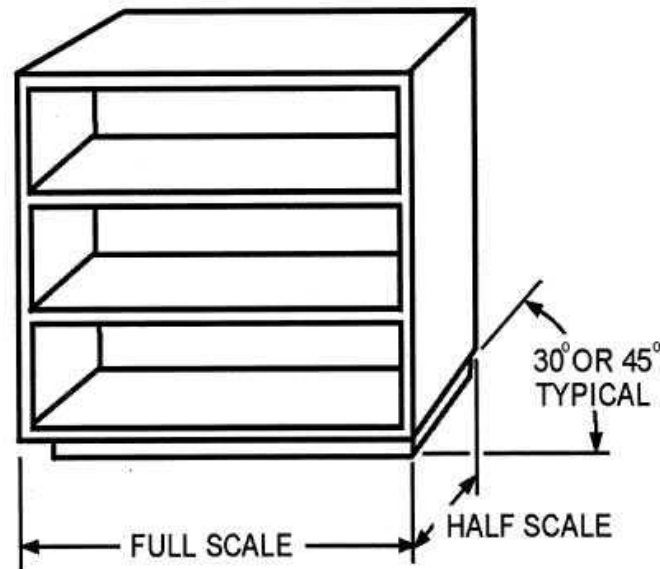
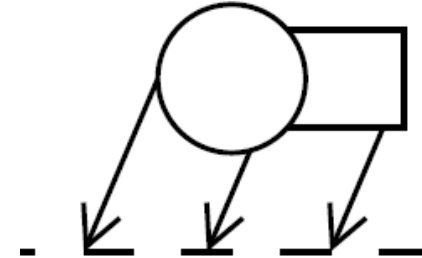
- **Perspective**



Planar geometric projections

- **Oblique**

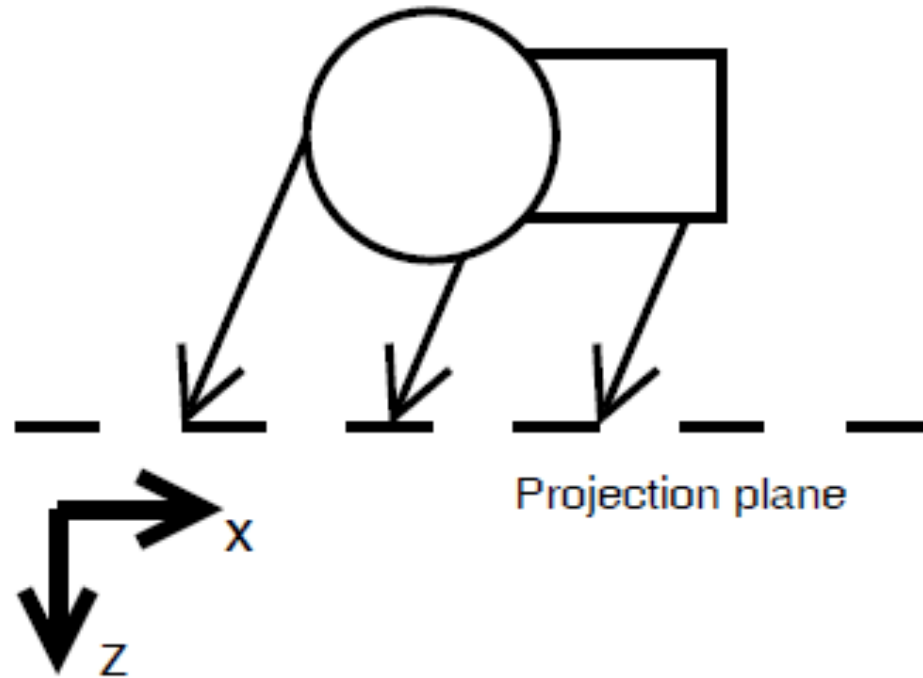
- ▶ Cavalier, cabinet



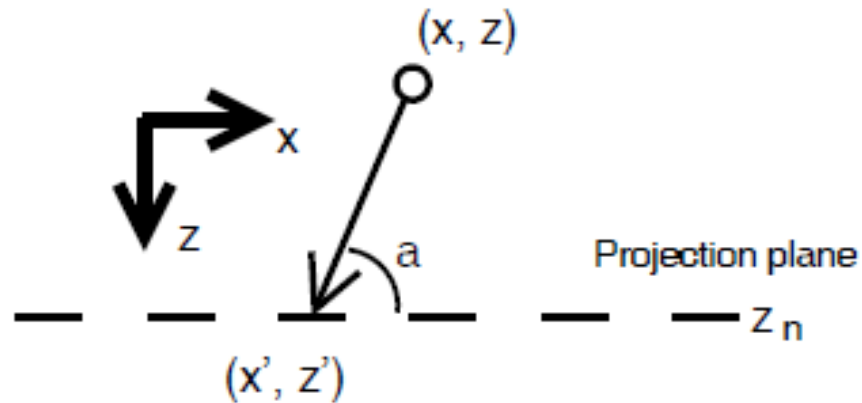
DMV2Ch06f06



Oblique projection



Oblique projection

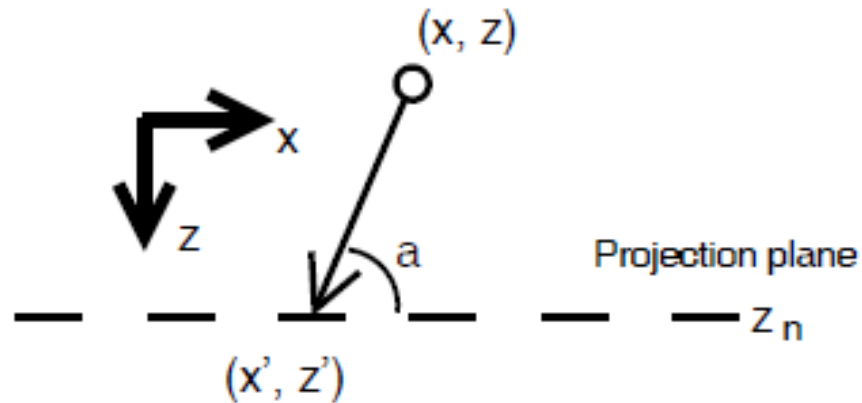


$$x' =$$

$$y' =$$

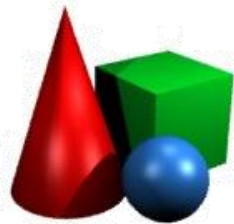


Oblique projection



$$x' = x - (z_n - z) \cot \alpha$$

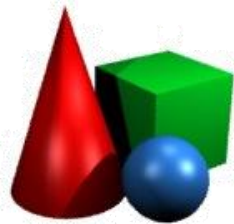
$$y' = y - (z_n - z) \cot \beta$$



Oblique projection

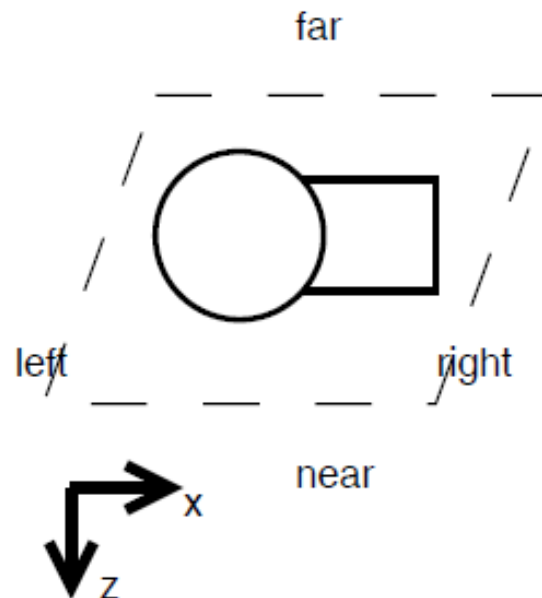
$$\begin{pmatrix} x' \\ y' \\ z' \\ 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & \cot \alpha & -z_n \cot \alpha \\ 0 & 1 & \cot \beta & -z_n \cot \beta \\ 0 & 0 & 1 & 0 \\ \hline 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix}$$

Denote this matrix by ***H***



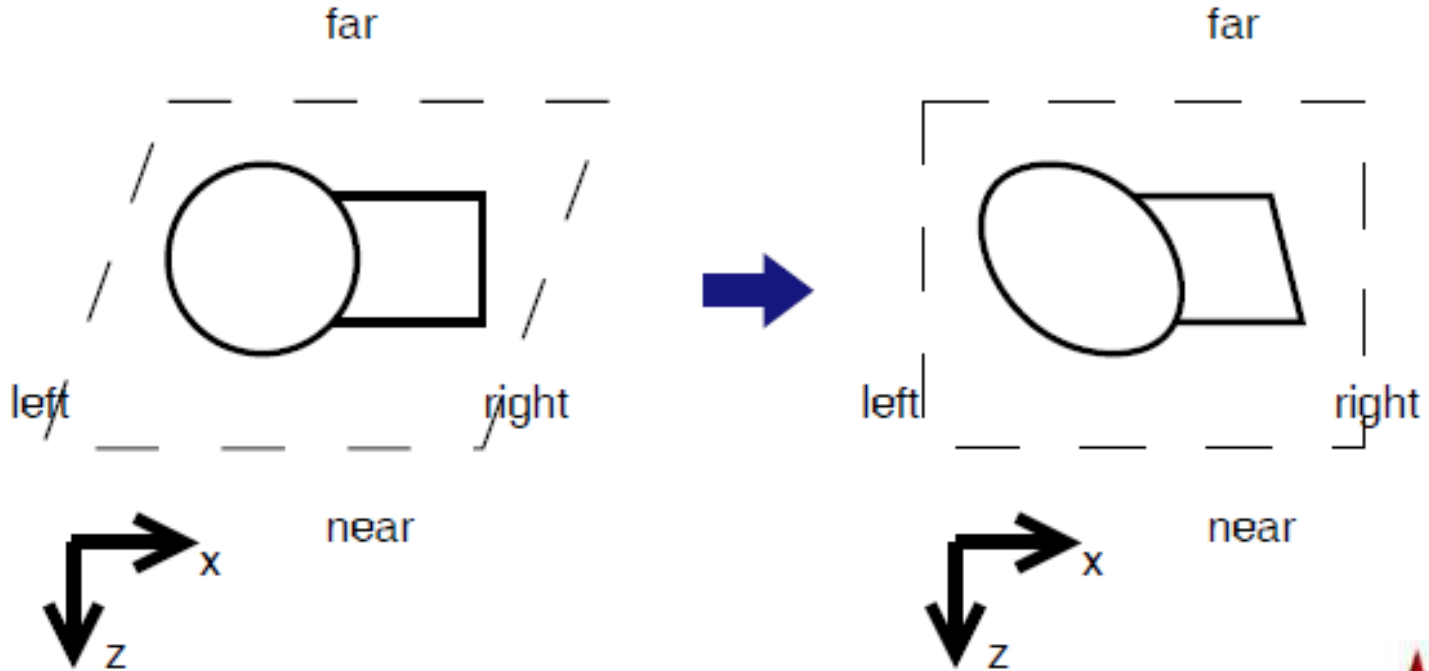
Oblique projection

- Similarly, we can define a *clipping parallelepiped* for the oblique projection.



Oblique projection

- Matrix H would make it rectangular



Oblique projection

- ... we can then further map the resulting box to $(-1, +1)$ clip space using the standard orthogonal projection:

$$P_{\text{obl}} = P_{\text{ort}}H$$



Oblique projection

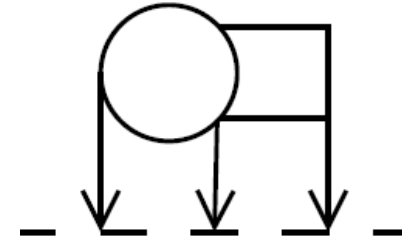
```
glMatrixMode(GL_PROJECTION);  
glLoadIdentity();  
glOrtho(left, right, bottom, top, near, far);  
  
float H[] = {  
            1,      0,      0,      0,  
            0,      1,      0,      0,  
            cot(a), cot(b), 1,      0,  
            0,      0,      0,      1};  
  
glMultMatrixf(H);  
  
glMatrixMode(GL_MODELVIEW);
```



Planar geometric projections

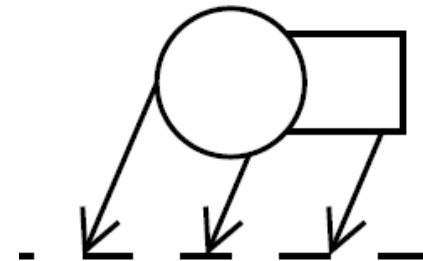
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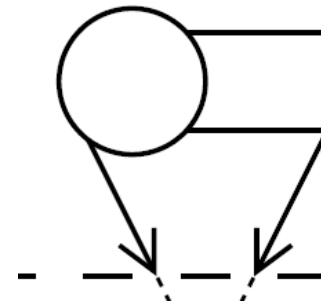


- **Oblique**

- ▶ Cavalier, cabinet

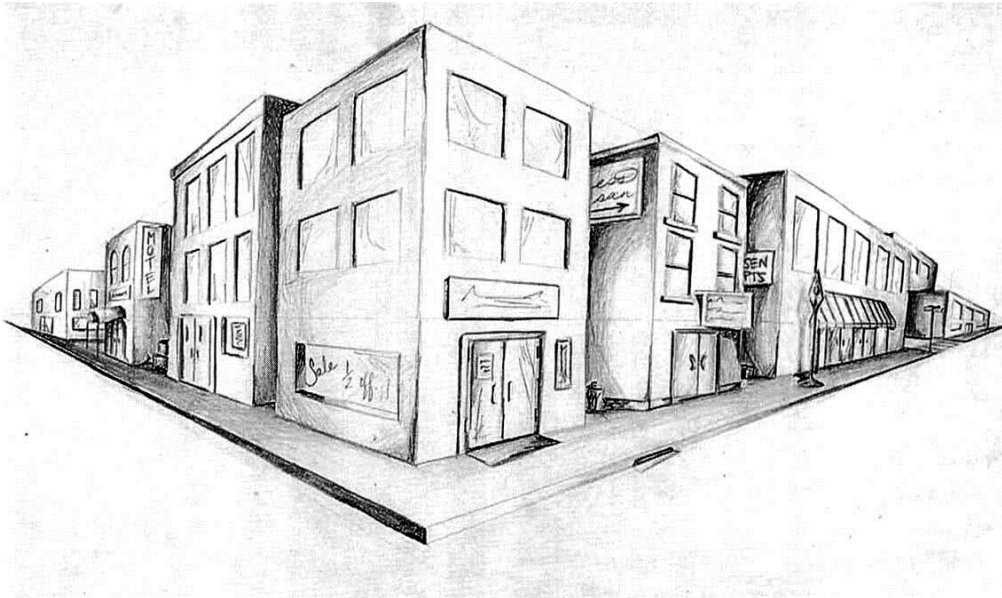
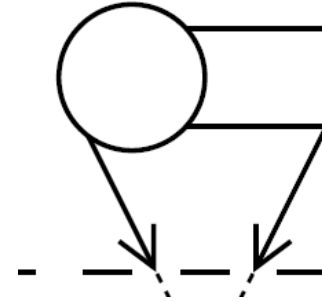


- **Perspective**



Planar geometric projections

- Perspective



Homogeneous coordinates

- Remember we defined a representation for points in homogeneous coordinates:

$$(x, y, z) \rightarrow (x, y, z, 1)$$

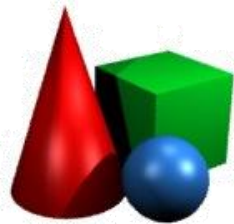
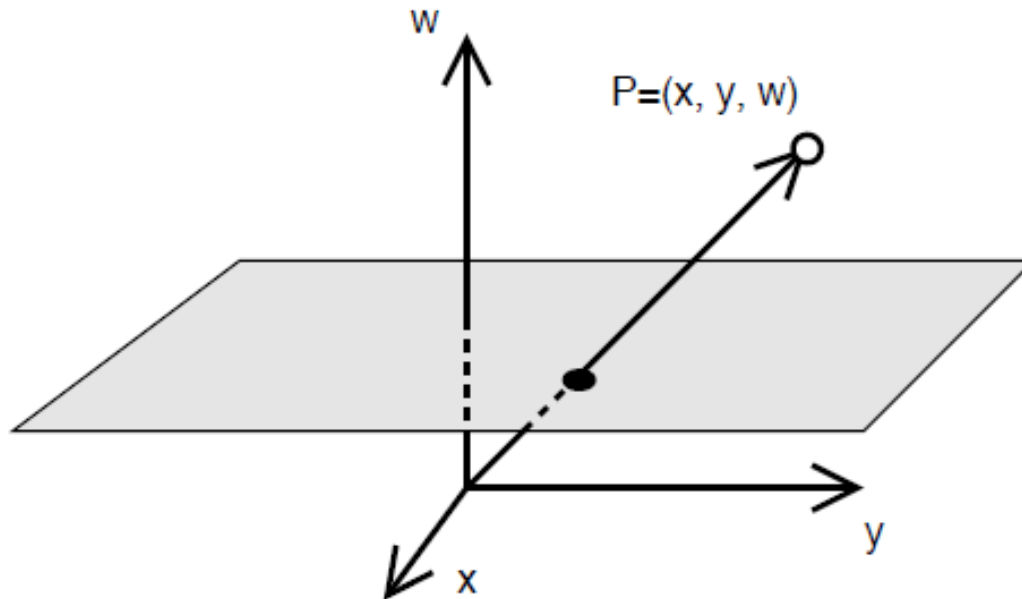
- Let us now define an inverse correspondence: any vector (x, y, z, w) will denote the point $\left(\frac{x}{w}, \frac{y}{w}, \frac{z}{w}\right) \in \mathbb{R}^3$



Homogeneous coordinates

- Similarly for two dimensions:

$$(x, y, w) \leftrightarrow \left(\frac{x}{w}, \frac{y}{w} \right)$$

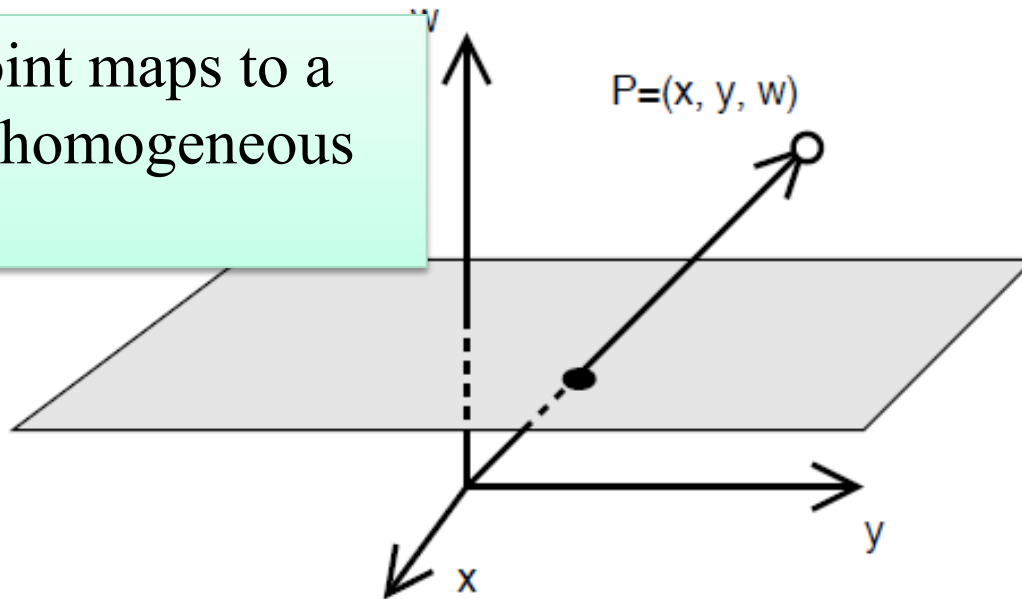


Homogeneous coordinates

- Similarly for two dimensions:

$$(x, y, w) \leftrightarrow \left(\frac{x}{w}, \frac{y}{w} \right)$$

One “actual” point maps to a whole “line” in homogeneous coordinates

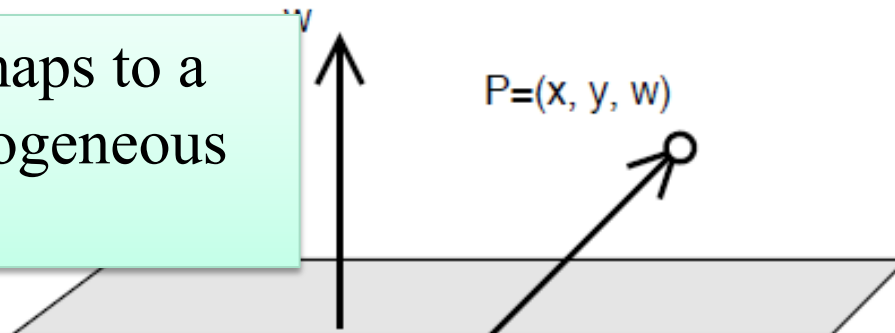


Homogeneous coordinates

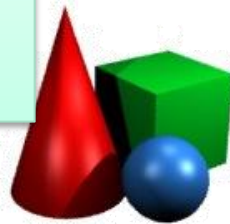
- Similarly for two dimensions:

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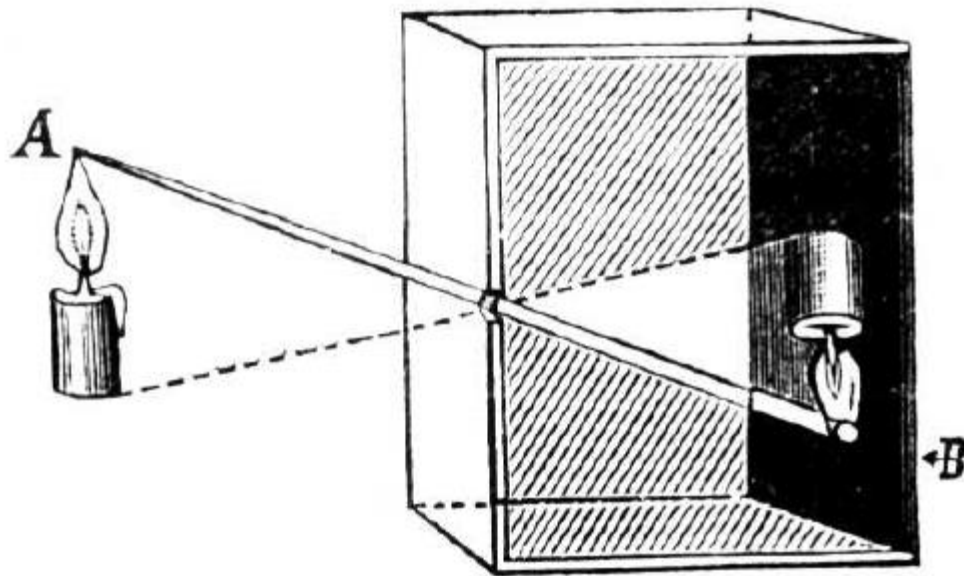
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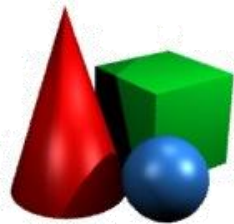
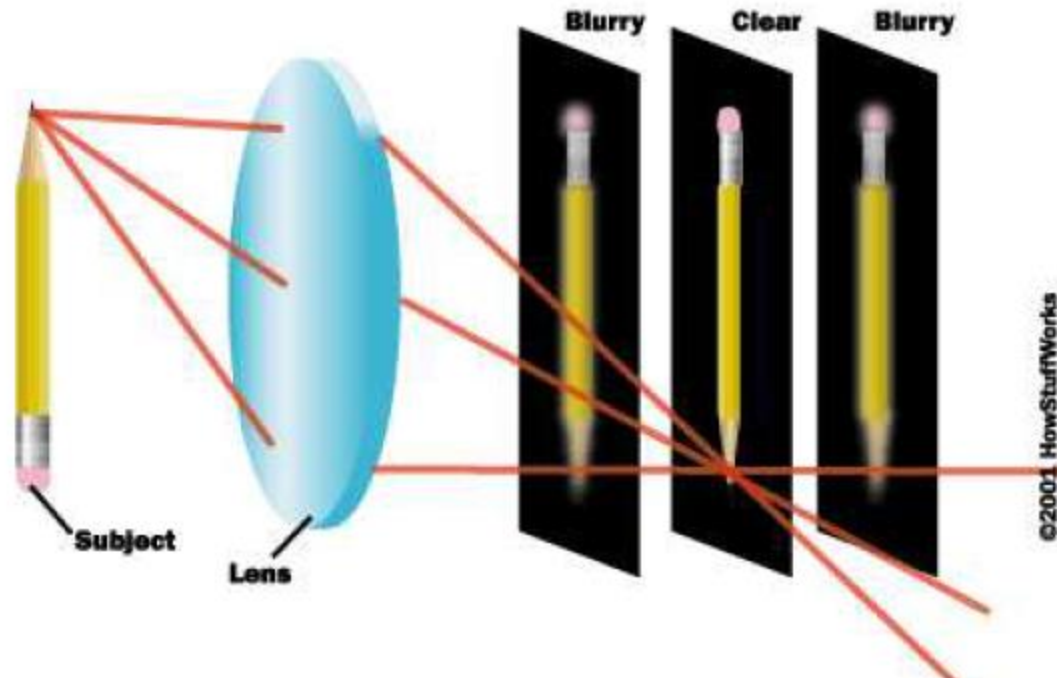
Homogeneous coordinates with $w = 0$, as before, do not correspond to any “actual point”. It is a vector (i.e. a direction) or a “point at infinity”.



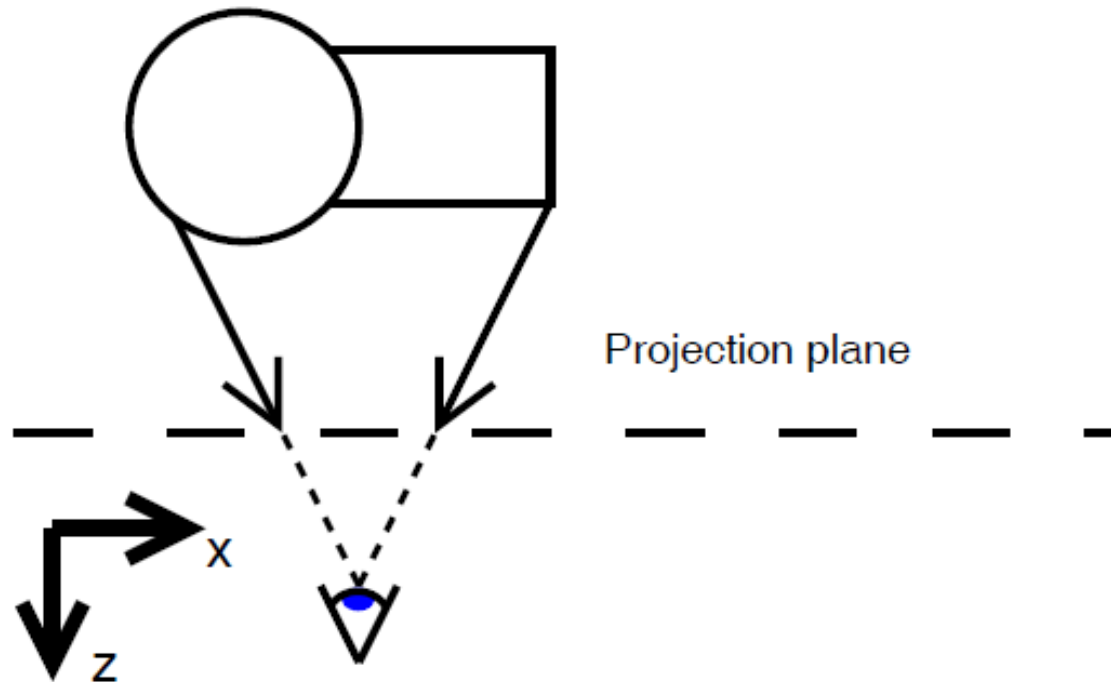
Camera obscura



Actual camera

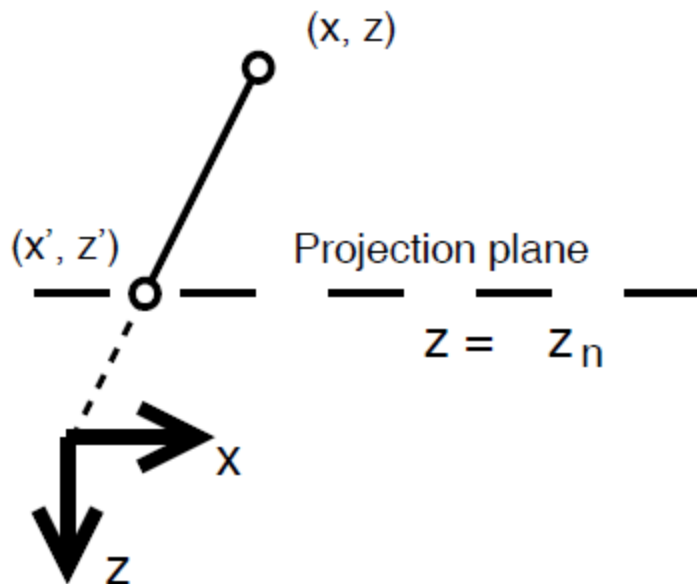


What we shall be doing



Perspective projection

- Suppose the center of projection is $(0, 0, 0)$.
Let us project to the plane $z = z_n$



$$x' =$$

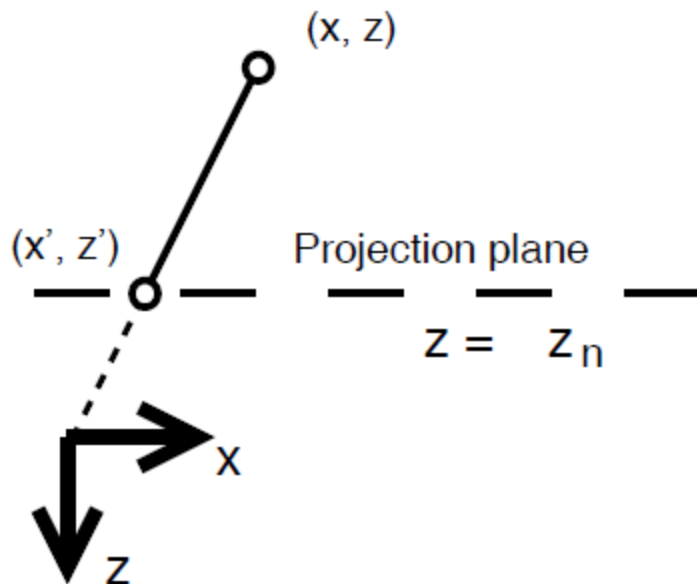
$$y' =$$

$$z' =$$



Perspective projection

- Suppose the center of projection is $(0, 0, 0)$.
Let us project to the plane $z = z_n$



$$x' = x \cdot \frac{z_n}{z}$$

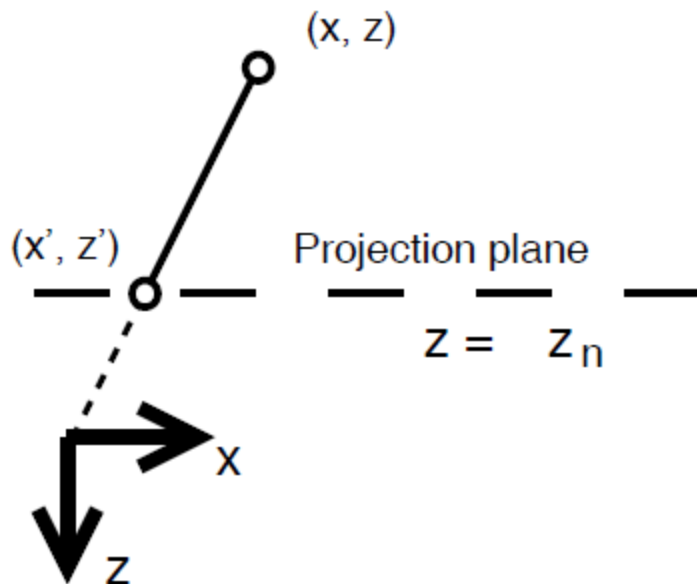
$$y' = y \cdot \frac{z_n}{z}$$

$$z' = z \cdot \frac{z_n}{z}$$



Perspective projection

- Suppose the center of projection is $(0, 0, 0)$.
Let us project to the plane $z = z_n$



$$x' = x \cdot \frac{z_n}{z} = \frac{x}{z/z_n}$$

$$y' = y \cdot \frac{z_n}{z} = \frac{y}{z/z_n}$$

$$z' = z \cdot \frac{z_n}{z} = \frac{z}{z/z_n}$$



Perspective projection

- We need to map

$$(x, y, z) \rightarrow \left(\frac{x}{z/z_n}, \frac{y}{z/z_n}, \frac{z}{z/z_n} \right)$$

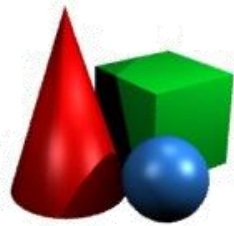


Perspective projection

- We need to map

$$(x, y, z) \rightarrow \left(\frac{x}{z/z_n}, \frac{y}{z/z_n}, \frac{z}{z/z_n} \right)$$

Is this a linear transformation?



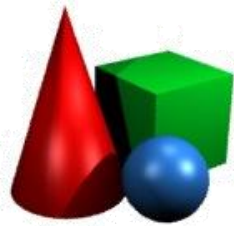
Perspective projection

- We need to map

$$(x, y, z) \rightarrow \left(\frac{x}{z/z_n}, \frac{y}{z/z_n}, \frac{z}{z/z_n} \right)$$

In homogeneous coordinates, though, it corresponds to:

$$(x, y, z, 1) \rightarrow \left(\frac{x}{z/z_n}, \frac{y}{z/z_n}, \frac{z}{z/z_n}, 1 \right)$$



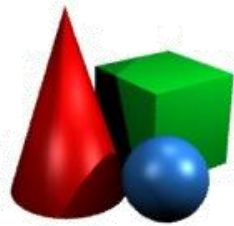
Perspective projection

- We need to map

$$(x, y, z) \rightarrow \left(\frac{x}{z/z_n}, \frac{y}{z/z_n}, \frac{z}{z/z_n} \right)$$

In homogeneous coordinates, though, it corresponds to:

$$(x, y, z, 1) \rightarrow (x, y, z, z/z_n)$$



Perspective projection

- We need to map

$$(x, y, z) \rightarrow \left(\frac{x}{z/z_n}, \frac{y}{z/z_n}, \frac{z}{z/z_n} \right)$$

In homogeneous coordinates, though, it corresponds to:

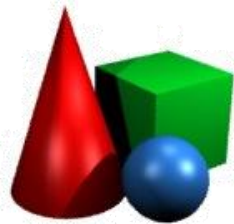
$$(x, y, z, 1) \rightarrow (x, y, z, z/z_n)$$

What matrix performs this?

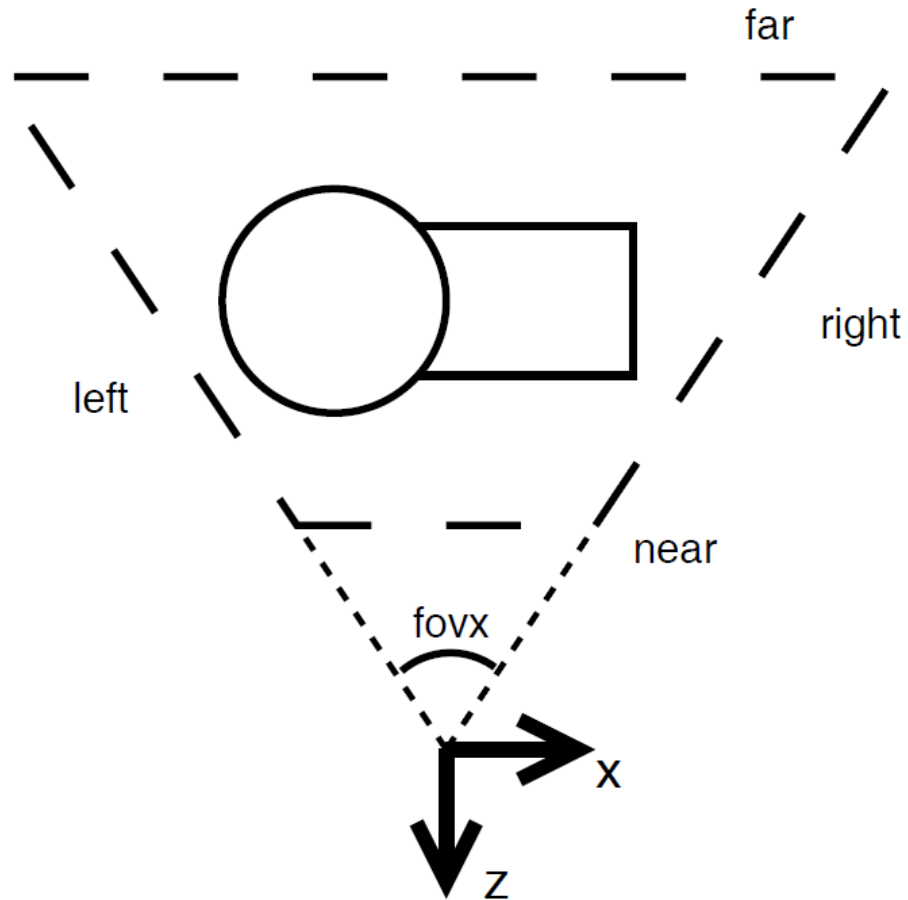


Perspective projection

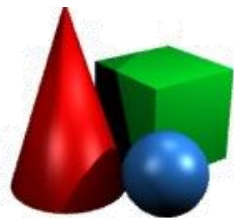
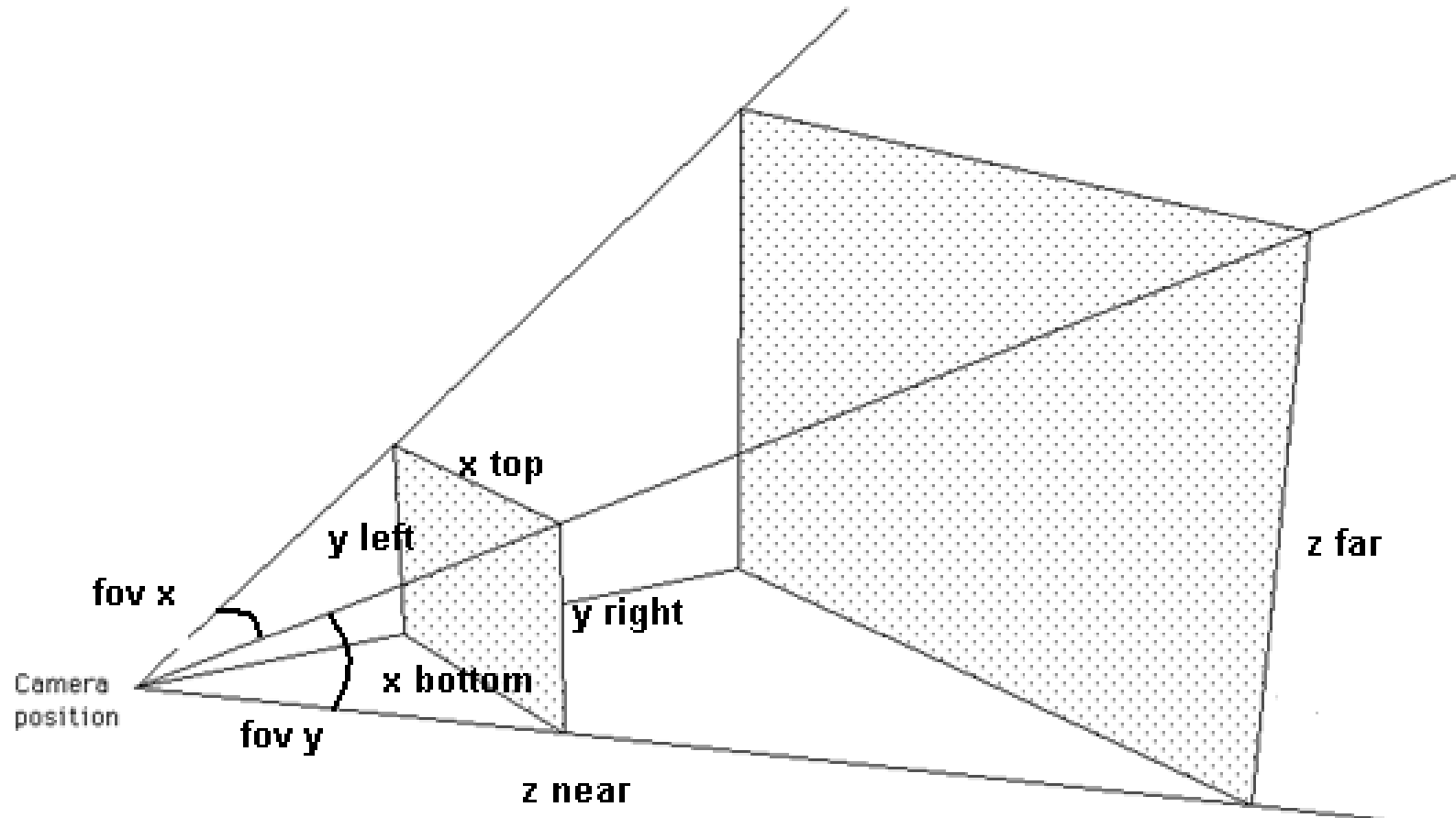
$$\begin{pmatrix} x' \\ y' \\ z' \\ w' \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & | & 0 \\ 0 & 1 & 0 & | & 0 \\ 0 & 0 & 1 & | & 0 \\ \hline 0 & 0 & 1/z_n & | & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix}$$



View frustum

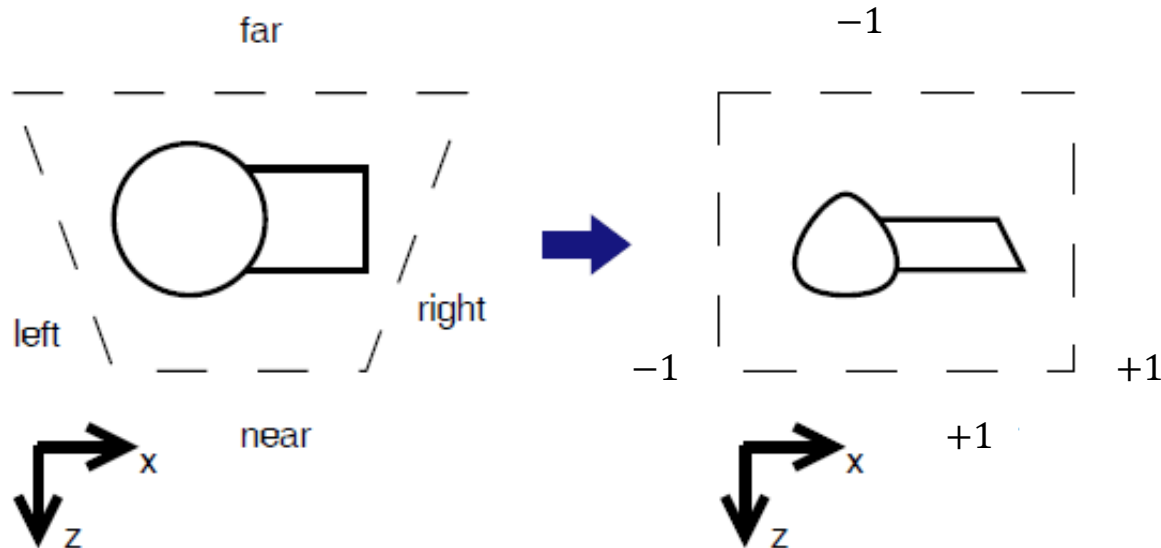


View frustum



View frustum normalization

- We want to do the same trick as before – normalize the view frustum into $2 \times 2 \times 2$ clipping space.



View frustum normalization

- We want to do the same trick as before – normalize the view frustum into $2 \times 2 \times 2$ clipping space.
- Remember, our current mapping is

$$(x, y, z) \rightarrow \left(\frac{x}{z/z_n}, \frac{y}{z/z_n}, z_n \right)$$



View frustum normalization

$$(x, y, z) \rightarrow \left(\frac{x}{z/z_n}, \frac{y}{z/z_n}, z_n \right)$$



View frustum normalization


Rescaling this from {left, right}
to {-1, +1} is straightforward

$$(x, y, z) \rightarrow \left(\frac{x}{z/z_n}, \frac{y}{z/z_n}, z_n \right)$$



View frustum normalization

Rescaling this from {bottom, top}
to {-1, +1} is straightforward


$$(x, y, z) \rightarrow \left(\frac{x}{z/z_n}, \frac{y}{z/z_n}, z_n \right)$$



View frustum normalization

This is a problem!

$$(x, y, z) \rightarrow \left(\frac{x}{z/z_n}, \frac{y}{z/z_n}, z_n \right)$$

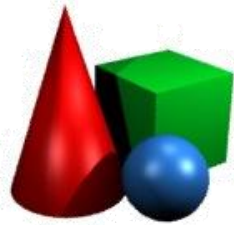


View frustum normalization

This is a problem!

We have lost depth information!

$$(x, y, z) \rightarrow \left(\frac{x}{z/z_n}, \frac{y}{z/z_n}, z_n \right)$$



View frustum normalization

This is a problem!

Turns out a better way
to transform z is:

$$A + \frac{B}{z}$$

We have lost depth
information!

$$(x, y, z) \rightarrow \left(\frac{x}{z/z_n}, \frac{y}{z/z_n}, z_n \right)$$



View frustum normalization

Depth information is preserved

$$(x, y, z) \rightarrow \left(\frac{x}{z/z_n}, \frac{y}{z/z_n}, A + \frac{B}{z} \right)$$



View frustum normalization

Depth information is
preserved

It is a linear transformation in
homogeneous coordinates:

$$(x, y, z, 1) \rightarrow \left(x, y, \frac{Az + B}{z_n}, \frac{z}{z_n} \right)$$

$$(x, y, z) \rightarrow \left(\frac{x}{z/z_n}, \frac{y}{z/z_n}, A + \frac{B}{z} \right)$$



View frustum normalization

Depth information is preserved

It is a linear transformation in homogeneous coordinates:

$$(x, y, z, 1) \rightarrow \left(x, y, \frac{Az + B}{z}, \frac{z}{z} \right)$$

We can choose A and B to ensure that $z_n \rightarrow 1$, $z_f \rightarrow -1$

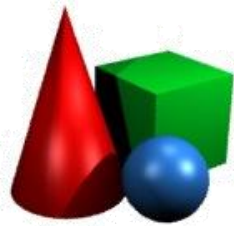
$$(x, y, z) \rightarrow \left(\frac{x}{z/z_n}, \frac{y}{z/z_n}, A + \frac{B}{z} \right)$$



View frustum normalization

We can choose A and B to ensure that $z_n \rightarrow 1$, $z_f \rightarrow -1$

$$(x, y, z) \rightarrow \left(\frac{x}{z/z_n}, \frac{y}{z/z_n}, A + \frac{B}{z} \right)$$



View frustum normalization

We can choose A and B to ensure that $z_n \rightarrow 1$, $z_f \rightarrow -1$

$$A + \frac{B}{z_n} = 1 \quad A + \frac{B}{z_f} = -1$$

$$(x, y, z) \rightarrow \left(\frac{x}{z/z_n}, \frac{y}{z/z_n}, A + \frac{B}{z} \right)$$



View frustum normalization

We can choose A and B to ensure that $z_n \rightarrow 1$, $z_f \rightarrow -1$

$$A = -\frac{(z_f + z_n)}{z_f - z_n} \quad B = \frac{2z_n z_f}{z_f - z_n}$$

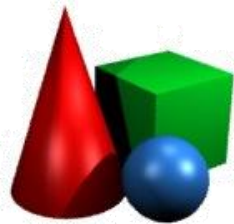
$$(x, y, z) \rightarrow \left(\frac{x}{z/z_n}, \frac{y}{z/z_n}, A + \frac{B}{z} \right)$$



Perspective transformation

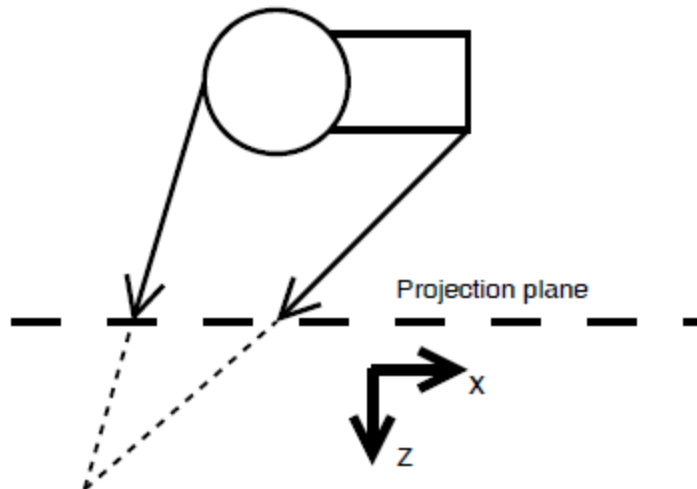
- Putting all together:

$$\mathbf{P}_{\text{persp}} = \left(\begin{array}{ccc|c} \frac{2z_n}{x_r - x_l} & 0 & 0 & 0 \\ 0 & \frac{2z_n}{y_t - y_b} & 0 & 0 \\ 0 & 0 & \frac{-(z_f + z_n)}{z_f - z_n} & \frac{2z_n z_f}{z_f - z_n} \\ \hline 0 & 0 & 1 & 0 \end{array} \right)$$



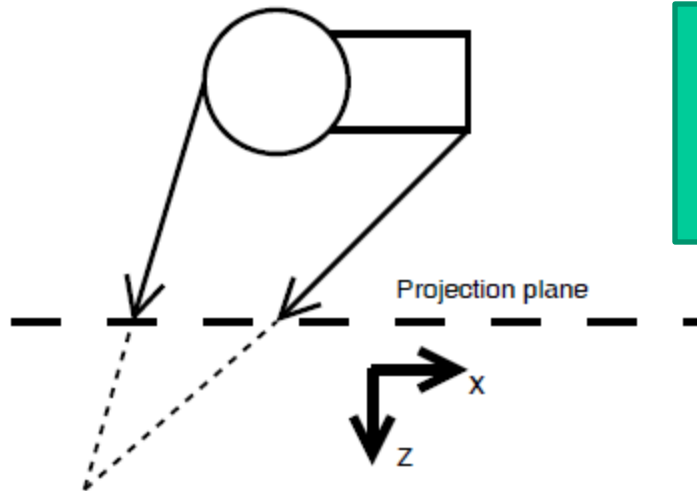
Skewed perspective

- Sometimes you might want to project so that the projection plane is not perpendicular to the viewing direction



Skewed perspective

- Sometimes you might want to project so that the projection plane is not perpendicular to the viewing direction

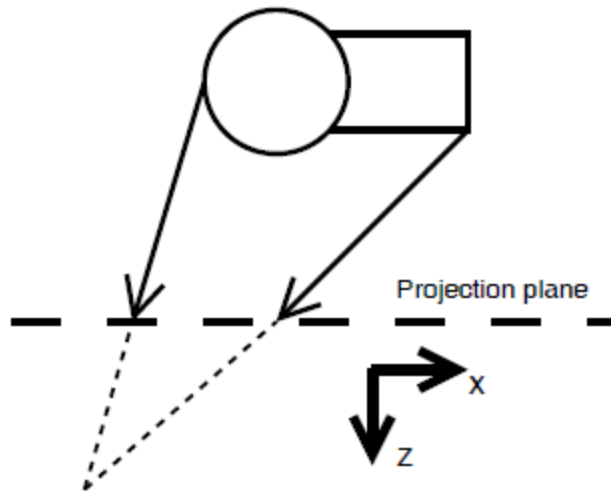


Quiz: How to do this?



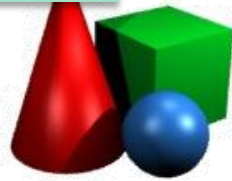
Skewed perspective

- Sometimes you might want to project so that the projection plane is not perpendicular to the viewing direction



Quiz: How to do this?

Apply the “unskewing” H matrix first.



Perspective projection

```
glMatrixMode(GL_PROJECTION);  
glLoadIdentity();  
glFrustum(left, right, bottom, top, dNear, dFar);  
glMatrixMode(GL_MODELVIEW);
```



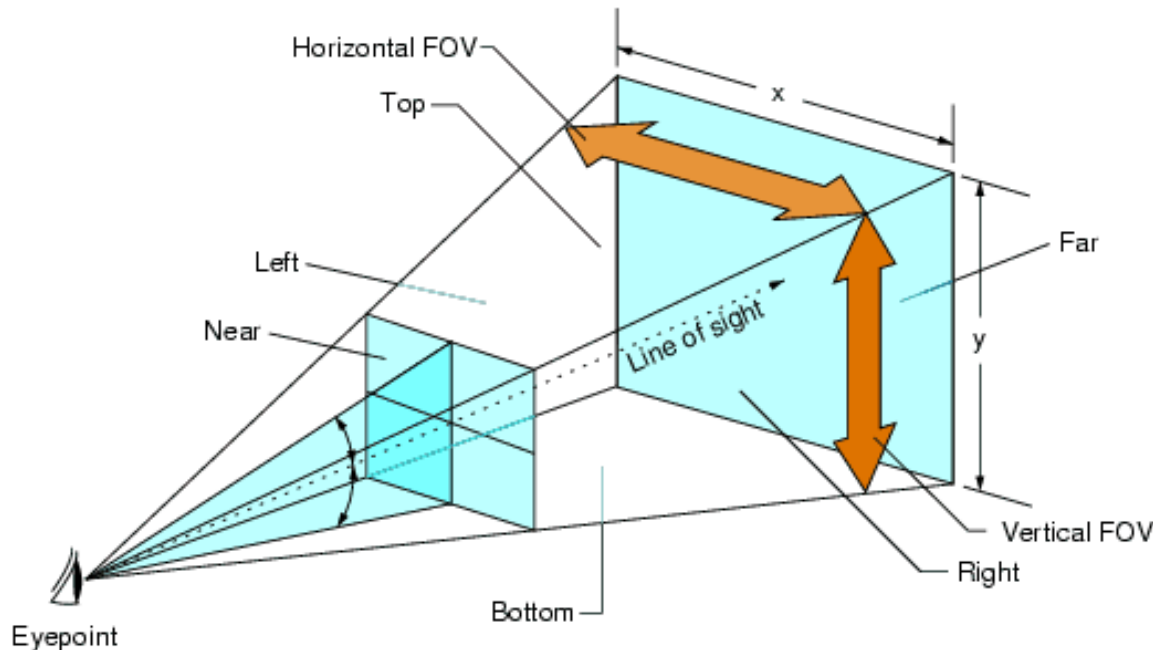
Perspective projection

```
glMatrixMode(GL_PROJECTION);  
glLoadIdentity();  
gluPerspective(fovY, aspect, dNear, dFar);  
glMatrixMode(GL_MODELVIEW);
```



Perspective projection

```
glMatrixMode(GL_PROJECTION);  
glLoadIdentity();  
gluPerspective(fovY, aspect, dNear, dFar);  
glMatrixMode(GL_MODELVIEW);
```



$$\text{Aspect Ratio} = \frac{y}{x} = \frac{\tan(\text{vertical FOV}/2)}{\tan(\text{horizontal FOV}/2)}$$

<http://www.codinghorror.com/blog/2007/08/widescreen-and-fov.html>



Field of View

- Quiz: How does the picture look like when FOV is very large?



Field of View

- Quiz: How does the picture look like when FOV is very large?



“Fisheye lens effect”



Field of View

- Quiz: How does the picture look like when FOV is very large?



<http://strlen.com/gfxengine/panquake/>



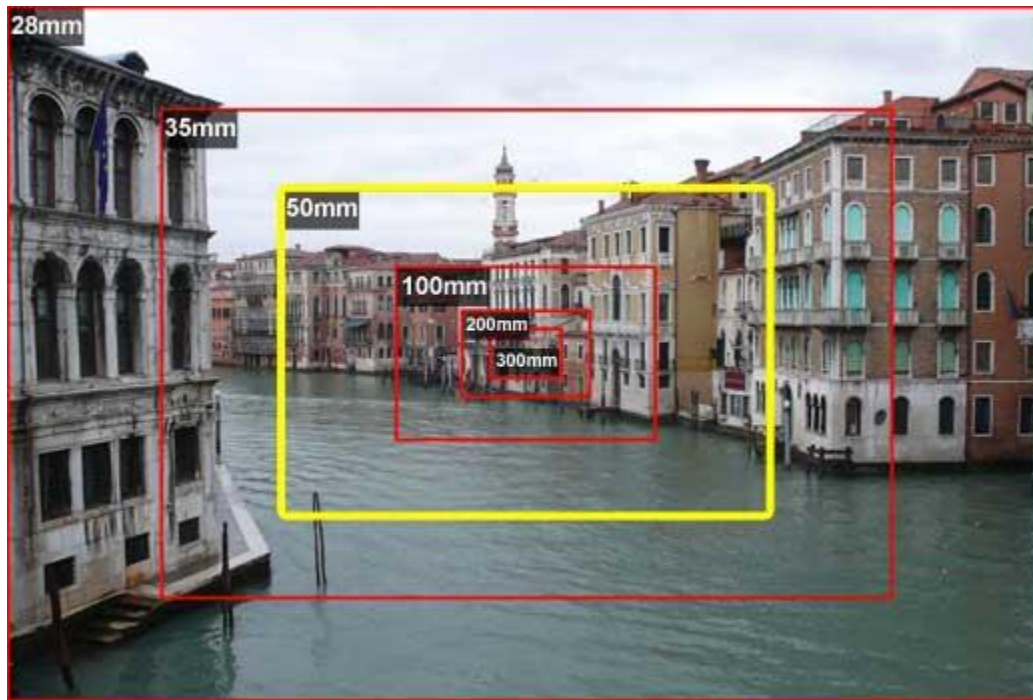
Field of View

- Quiz: How does the picture look like when FOV is very small?



Field of View

- Quiz: How does the picture look like when FOV is very small?



“Zoom effect”



Field of View

- Quiz: How does the picture look like when FOV is very small?



“Zoom effect”

Resembles
orthographic projection



What we know so far

- We need to set up the **Model-View matrix** using
 - `glMatrixMode(GL_MODELVIEW)`
- We need to set up the **Projection matrix** using
 - `glMatrixMode(GL_PROJECTION)`
- When we emit vertices (via `glVertex**`), they are transformed as follows:

$$\mathbf{x} \rightarrow \mathbf{P} \cdot (\mathbf{VM}) \cdot \mathbf{x}$$



Last two steps

- Last two steps of the pipeline:
 - Perspective division
 - ▶ $(x, y, z, w) \rightarrow \left(\frac{x}{w}, \frac{y}{w}, \frac{z}{w}, 1\right)$
 - Viewport transform
 - ▶ x is mapped from $(-1, +1)$ to $(0, \text{screen width})$
 - ▶ y is mapped from $(-1, +1)$ to $(\text{screen height}, 0)$
 - ▶ z is mapped from $(-1, +1)$ to $(0, 1)$



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$$x_{\text{win}} = \frac{\text{screen width}}{2}(x_{\text{norm}} + 1)$$

$$y_{\text{win}} = \frac{\text{screen height}}{2}(1 - y_{\text{norm}})$$



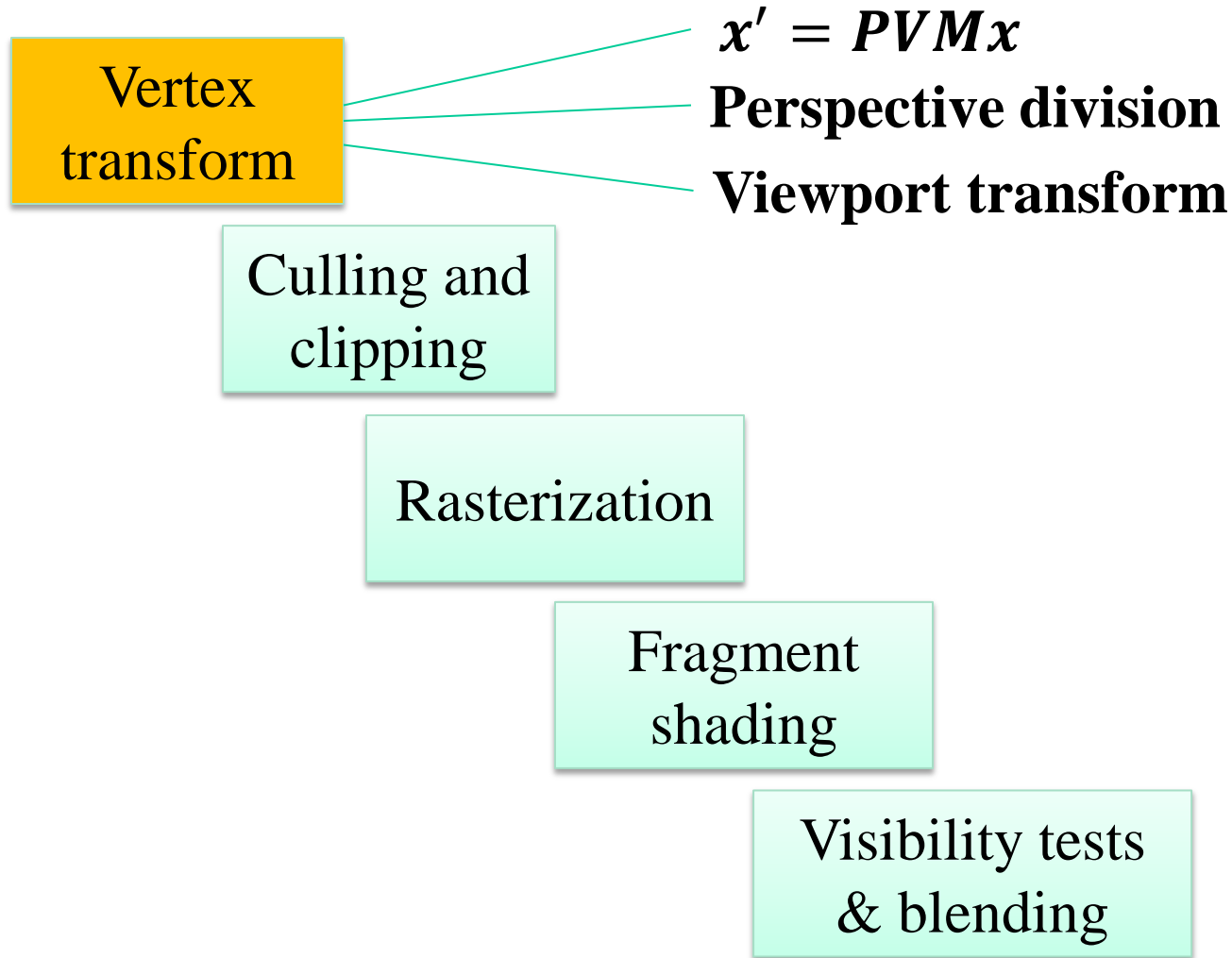
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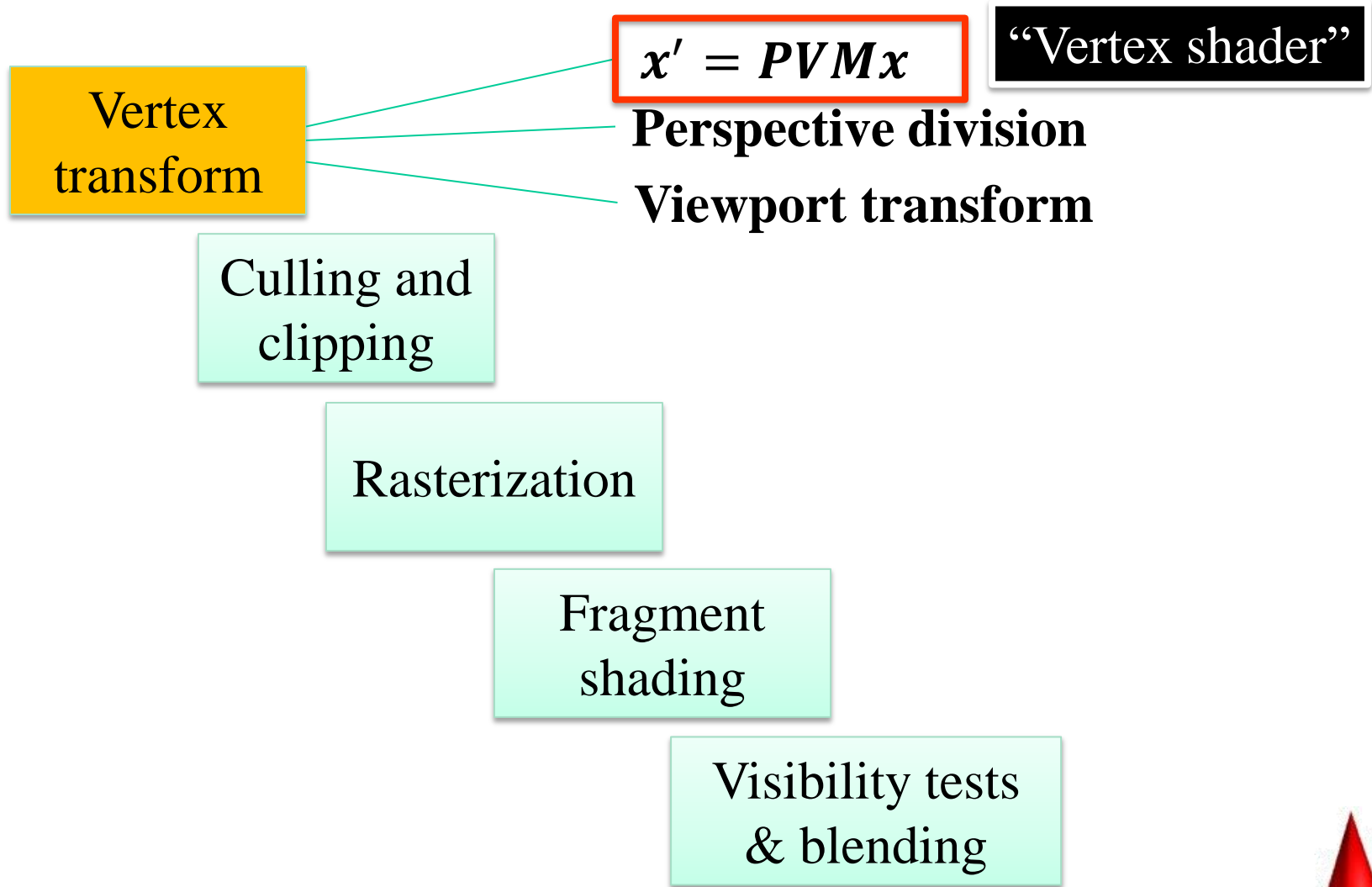
```
glViewport(0, 0, width, height);  
glDepthRange(0, 1);
```



Standard Graphics Pipeline



Standard Graphics Pipeline



Standard Graphics Pipeline

Vertex

$$x' = PVMx$$

“Vertex shader”

```
void main() {  
    gl_Position = gl_ModelViewProjectionMatrix * gl_Vertex;  
}
```

Rasterization

Fragment
shading

Visibility tests
& blending



Standard Graphics Pipeline

Vertex

$$x' = PVMx$$

“Vertex shader”

```
void main() {  
    gl_Position = gl_ModelViewProjectionMatrix * gl_Vertex;  
    normal = gl_NormalMatrix * gl_Normal;  
}
```

Rasterization

Fragment
shading

Visibility tests
& blending



Standard Graphics Pipeline

