

Epidemic Modeller Project Overview

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For Warwick Module MA4J5

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1 Introduction

In this project, I've tried to create a stochastic spatial method of simulating epidemics. I hope that when using completely random movement we get simulations very similar to existing basic methods (like a simple Gillespie stochastic SEIR model), but we could modify this new spatial model to include patterns of movement and then compare the effects of different movement patterns to find new insights.

Another aim of this project is to provide a visual representation of an epidemic. Just looking at graphs of infection levels wouldn't help a school student or member of the public gain intuition on the exponential nature of disease spread, but a model that can be visualised can be used to teach a broader audience on how a new disease spreads through a population, and the effects that interventions have.

Though while the models I create here are overly simplistic, and the renderers I create are not very visually appealing, they could be improved upon and then used to educate larger numbers of people on epidemiology and the importance of the interventions that governments impose. This method makes understanding epidemiology accessible to people who are less educated and, when taught to the wider public, could help inspire public trust in governments implementing strict measures.

The models I create in this project are likely too simple to apply to humans, and wouldn't provide much benefit over a standard Gillespie stochastic SEIR model, but might more closely resemble a different species' nest or colony. Modifying the movement of the individuals to be like bees, bats or ants should not be a difficult extension of the models presented below.

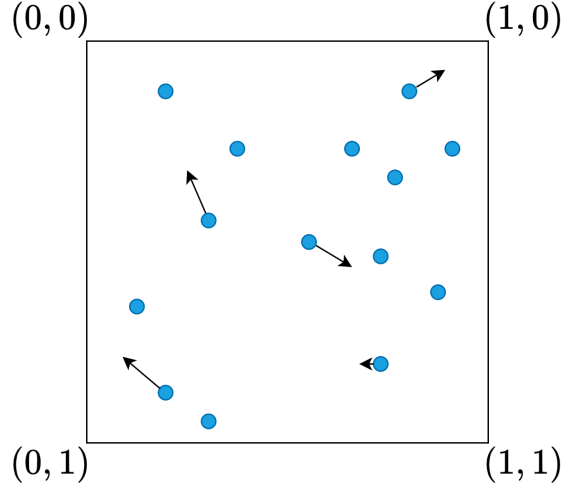
2 Basic Visual Model

In this model, we create a model which is stochastic, and where the individuals in the population move in straight lines in random directions. Each individual will be in either the susceptible class, the exposed class, the infectious class, or the removed class at any one time. We choose to move individuals between classes according to realisations of gamma distributions, except for when an infectious individual infects others around them — where we use the exponential distribution. Gamma distributions are great for this use case as often people tend to be infected a random duration of time, say between n and k days, and gamma random variables can encapsulate this property and they tend to have a large mass near the mean of the distribu-

tion. They are also sums of exponential random variables, a property that we exploit to make feasible the mathematical analysis of the model I set up.

2.1 Setup

We start with a region $A = [0, 1] \times [0, 1]$, and each individual i has coordinates $(x_i, y_i) \in A$. Each individual starts with coordinates $x_i \sim U[0, 1]$, $y_i \sim U[0, 1]$, and has velocity $\frac{dx_i(t)}{dt} \sim U[-v, v]$, $\frac{dy_i(t)}{dt} \sim U[-v, v]$ for some speed parameter v . Whenever an individual hits the boundary, e.g. $x_i = 0$, then they 'bounce' off of the boundary by negating the velocity in the x or y component, whichever boundary we hit.



Each individual has state $s_i \in \{S, E, I, R\}$ and our model starts with N_S people in the S class, N_I in the I class, N_E in the E class, and N_R in the R class. When an individual enters the E class (after getting infected, or by initial condition), then they get assigned a time when their latency period will end, which is distributed $t_L \sim \text{Gamma}(\sigma)$. When an individual enters the I class, they get assigned a time when their infection period will end, which is distributed $t_R \sim \text{Gamma}(\frac{1}{\gamma\lambda}, \lambda)$. Also when an individual enters the I class, they get assigned a time at which they will next attempt to infect, with distribution $t_I \sim \text{Exp}(\lambda)$. Once an infectious person attempts to infect, they get assigned the next time when they will infect (with the same distribution), though they won't be able to attempt to infect any more if they recover before the time to next infect attempt.

We also discretise time and have it increment by a fixed amount each step in a while loop (I've used 0.1 days time-step as the default), and in each iteration we calculate the new locations of the individuals and check if any events occurred since the previous time-step, and then apply the effects of the events that have happened and schedule new events in the future (e.g. if an event causes a new individual to join the exposed class, randomly generate the length of time they will stay in the E class and schedule the end-of-latency-period event to happen at the time in the future).

2.2 Infect attempts

Whenever an individual attempts to infect, we check if there is at least one other individual within l^1 distance $\frac{b}{\sqrt{N}}$. We choose this distance because there is $1/N$ area per individual in the region A , and if that were a square it would have side length $1/\sqrt{N}$, and then we just multiply that by a scalar parameter b which we can choose when setting up the model. If there is no susceptible people in the area then the attempt failed and nobody new got infected. If there was at least one susceptible individual nearby, then one of them gets picked and enters the exposed class.

2.3 Analysis

The recovery rate γ is the inverse of the average number of days spent in the I class. Hence why time spent in the infectious class $t_R \sim \text{Gamma}(\frac{1}{\gamma\lambda}, \lambda)$ was chosen, because $\mathbb{E}(t_R) = \frac{1}{\gamma\lambda}\lambda = \frac{1}{\gamma}$.

The number of people in an l^1 radius $\frac{b}{\sqrt{N}}$ of an infectious individual's position would be effectively distributed with $m \sim \text{Binomial}(S, b/N)$. Hence the probability that there is at least 1 susceptible individual in that area will be $\mathbb{P}(m \geq 1) = 1 - \mathbb{P}(m = 0) = 1 - (1 - \frac{b}{N})^S$. This gives us the probability that a given infection attempt will be successful.

Approximating R_0 : First we assume that $S \approx N$ for calculating the average number of people that the first person will infect. This allows us to simplify our above probability for a successful infection attempt $1 - (1 - \frac{b}{N})^S \approx 1 - \exp(-b)$. For the first infectious individual, the time taken between each infection attempt is distributed $t_I \sim \text{Exp}(\lambda)$ and the time taken to recovery is $t_R \sim \text{Gamma}(\frac{1}{\gamma\lambda}, \lambda)$. This was chosen so that the average length of infection was $1/\gamma$ and because $\text{Gamma}(\frac{1}{\gamma\lambda}, \lambda)$ is effectively the sum of $\frac{1}{\gamma\lambda}$ of $\text{Exp}(\lambda)$ random variables, so the average number of infection attempts over the duration of the first infection should be $\frac{1}{\gamma\lambda}$. This means that

$R_0 \approx \frac{1}{\gamma\lambda}(1 - \exp(-b))$. And so our contact rate β should be approximately $\frac{1}{\lambda}(1 - \exp(-b))$.

So, with this result, given a β value, we can fix either λ or b and then calculate the value of the other parameter that we didn't fix so that $\beta = \frac{1}{\lambda}(1 - \exp(-b))$.

2.4 Implementation

I implement the model in Python and create a renderer to display what's going on in the model throughout the simulated outbreak.

In `basic_model.py`, the model is implemented as explained above. It returns a `BasicModelOutput` object which contains the final size of the outbreak, the duration, the time taken to run the simulation, and a history of each individual's state and position throughout the outbreak. This output object can be passed onto the `render_basic_model` function in the `basic_model_renderer.py` file, which visually displays how the outbreak occurred using the `pygame` module.

2.5 Simulation results and renders

As I can't put videos of renders into this PDF, I've made a video showing an example output and render of the basic model. The second half of the video covers the compartment model, which is covered below. Note that the YouTube player allows you to change the playback speed in case you don't want to spend 6 minutes watching the video.

<https://youtu.be/YRBOYN00fDQ>

See `Examples.ipynb` using JupyterLab so you can run the code yourself so you generate your own examples, and you can modify the parameters and initial conditions to play around with the model. For example, if you set $\gamma = \beta$, then the R_0 number should be 1, and the behaviour of the outbreaks seems quite weird, sometimes spreading very slowly and often dying out at random times.

There is no documentation for this project, so if you want to see how you can input new parameters into the model, then you should read the code for the `__init__` method to see what parameters it accepts.

3 Compartment Model

This model is very similar to the Basic Model defined above, but with this model we have multiple of the previous model running side by side, each called compartments, and individuals occasionally move between the different compartments — which could represent different towns/villages in a region.

3.1 Setup

As this is an extension of the previous model, we use the setup defined previously, and create n different compartments. Each compartment starts with its own set of initial conditions. We will usually start with only one of the compartments having a single infected individual, with the rest of the compartments having none.

For travellers between compartments, we introduce a mixing rate m , defined as the probability that anyone in a single compartment leaves to travel towards a different compartment. They then spend some fixed time t_{travel} (some number of days) travelling to a randomly selected compartment (other than from the one they are starting at). During transit, infectious individuals can't infect anyone else and susceptibles can't get infected while in transit (this doesn't happen in the real world when using public transport, though I've just done it for the sake of model simplicity). After a traveller arrives in a compartment they become another individual in that compartment and start moving around it in a random direction. They don't return to their original compartment, which is another issue with the model that I should have planned when designing it originally. I didn't go back and fix this as I've already spent a while on this project and the current solution is good enough to demonstrate the behaviour of different communities getting infected at different times during the outbreak.

3.2 Implementation

In `compartment_model.py` there is a `CompartmentModel` class, which is similar to the setup of the `BasicModel` class but managing interactions between classes; a `Compartment` class, which effectively runs a small Basic Model; plus a `Traveller` class.

Then there is a `compartment_model_renderer.py` file which renders the output of the model using pygame, just like the renderer for the Basic Model.

3.3 Simulation results and renders

As noted in the previous results and renders section of the Basic Model, I made a video showing the Compartment Model in action. The relevant section of the video starts at 3:07, and the following link will take you to that part of the video.

<https://youtu.be/YRBOYN00fDQ?t=187>

4 Closing Remarks

This project turned out as well as I expected, though I would have liked to create a few more interesting models. It is also quite slow to run the models, and I could have spent more time trying to optimise the model implementations. Plus, I regard my design and implementation of the travellers in the Compartment Model to be quite poor. If I were to spend more time on this project then I would definitely redesign that part.

Overall, I think the project sort of met its objectives, such as being a way to visualise small epidemics. Though this isn't how humans move, another model could have tried to create a small basic village and actually model people's movement throughout the village, with people in their homes, schools, and workplaces. Without this idea, my current models aren't going to have much of an advantage over the standard stochastic SEIR models, and Gillespie and tau-leaping are much more efficient than my models.