


Standard form polyhedra

$$\begin{array}{ll}\min_x & C^T x \\ \text{s.t.} & Ax = b \\ & x \geq 0\end{array}$$

Feasible direction

$$P = \{x \mid Ax = b, x \geq 0\}$$

a vector d is a feasible direction at point $x \in P$



$$\exists \theta > 0 \text{ s.t. } x + \theta d \in P$$

$$Ad = 0$$

$$\text{since } A(x + \theta d) = b$$

$$Ax + \theta Ad = b$$

$$\theta Ad = 0$$

$$Ad = 0$$

$$x + \theta d \geq 0 \text{ since } x + \theta d \in P$$

Basic feasible solution

- A basis: eg. $B = \{1, 4, 5\}$
- A basis matrix $A_B = [A_{B(1)}, \dots, A_{B(m)}]$
- x satisfies
 - $A_B x_B = b$
 - $x_i = 0 \quad \forall i \notin B$
- } satisfies $\begin{cases} Ax = b \\ x \geq 0 \end{cases}$
if $x_B \geq 0$
then we have a basic feasible solution
- basic direction d (also feasible)
- j th basic direction means we are considering adding j to the basis
- Remember, we need $Ad = 0$ and we don't want to add other non-basic variables to the basis

Set $d_j = 1$

Set $d_k = 0$ for all $k \neq j, k \notin B$

Then d_B will be set by solving the linear system

$$Ad = 0$$

$$Ad = \sum_{i=1}^n A_i d_i = A_B d_B + A_j = 0 \Rightarrow A_B d_B = -A_j$$

$$d_B = -A_B^{-1} A_j$$

$$\text{Cost Improvement} = \underbrace{c^T(x + \theta d)}_{\text{new cost}} - \underbrace{c^T x}_{\text{old cost}} = \theta c^T d$$

cost improvement

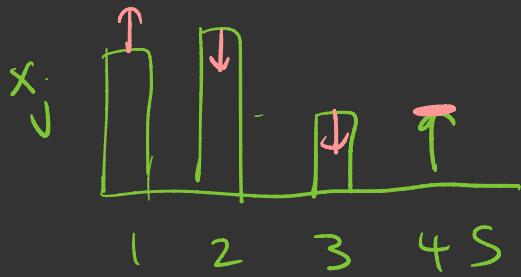
$c^T d$ is the reduced cost associated with this d

$$\bar{c}_j = c^T d = \sum_{i=1}^m c_i d_i = c_j + c_B^T d_B = c_j - c_B^T A_B^{-1} A_j$$

Example : $m=3, n=5$ $A = \begin{pmatrix} & & & & \end{pmatrix}$

$$B = \{1, 2, 3\}$$

want to add 4 to the basis



$$A_B x_B = b$$

$$(A_1, A_2, A_3) \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = b$$

if $\bar{c} \geq 0$ then x is optimal

if some $\bar{c}_j < 0$ then we can decrease the cost by bringing x_j into the basis

$$\theta^* = \max \{ \theta \mid \theta \geq 0, x + \theta d \geq 0 \}$$

- if $d \geq 0$ in this case, then $\theta^* = \infty$, LP is unbounded

Optimality conditions

(a) a feasible solution x is optimal $\Leftrightarrow c^T d \geq 0$ for any feasible direction at x

\Rightarrow proof by contradiction

Suppose \exists a feas. dir. d s.t. $c^T d < 0$

Then $\exists \theta > 0$ s.t. $x + \theta d$ is a feas. soln

Thus $c^T x \geq c^T(x + \theta d)$ contradiction bc x not optimal

\Leftarrow Proof by contradiction

Suppose $c^T d \geq 0$ for every feas. dir. d at x

Let $y \in P$

Then let $d = y - x$

Thus $c^T d \geq 0 \Rightarrow c^T(y - x) \geq 0$

$c^T y \geq c^T x$ so x is optimal

