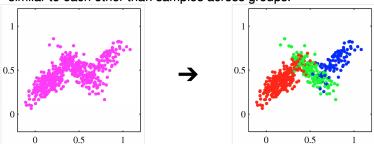
Clustering

ORIE 4741

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Clustering: data segmentation

Discover groups such that samples within a group are more similar to each other than samples across groups.



Clustering: unsupervised methods

A clustering algorithm groups data points into clusters: example:

- medical diagnosis. cluster patients with similar medical histories
- topic model. cluster documents with similar patterns of word usage
- market segmentation. cluster customers with similar purchase patterns

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Clustering ingredients

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 - Quantitative? Ordinal? Categorical?
- A loss function to evaluate clusters.
 - Usually weighted average of pairwise dissimilarity
- Algorithm that optimizes this loss function.

K-means clustering: Objective Function

- All variables are of the quantitative type.
- Use squared Euclidean distance as dissimilarity metric.

$$d(x_i, x_{i'}) = \sum_{j=1}^{p} (x_{ij} - x_{i'j})^2 = ||x_i - x_{i'}||^2$$

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We can then write the within-cluster dissimilarity:

$$W(C) = \frac{1}{2} \sum_{k=1}^{K} \sum_{C(i)=k} \sum_{C(i')=k} ||x_i - x_{i'}||^2$$
$$= \sum_{k=1}^{K} N_k \sum_{C(i)=k} ||x_i - \bar{x}_k||^2$$

where $\bar{x}_k = (\bar{x}_{1k}, \dots, \bar{x}_{pk})$ is the mean vector associated with the kth cluster, and $N_k = \sum_{i=1}^N \mathrm{I}(C(i) = k)$ is the size of kth cluster.

K-means clustering: Algorithm

Optimization problem:

$$C^* = \min_{C} \sum_{k=1}^{K} N_k \sum_{C(i)=k} \|x_i - \bar{x}_k\|^2$$

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For any set of observations S,

$$\bar{x}_{S} = \underset{m}{\operatorname{argmin}} \sum_{i \in S} \|x_{i} - m\|^{2}$$

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$$\min_{C,\{m_k\}_1^K} \sum_{k=1}^K N_k \sum_{C(i)=k} ||x_i - m_k||^2$$

K-means clustering: Alternative Minimization

Consider the enlarged optimization problem

$$\min_{C,\{m_k\}_1^K} \sum_{k=1}^K N_k \sum_{C(i)=k} ||x_i - m_k||^2$$

- ▶ Fix clusters $C_1, ..., C_K$, the minimizers of $\{m_k\}_{k=1}^K$ are the mean of points in each cluster.
- ► Fix cluster centers $\{m_k\}_{k=1}^K$, for each point i the best cluster would be

$$C(i) = \underset{1 \le k \le K}{\operatorname{argmin}} \|x_i - m_k\|^2$$

- Iterate until convergence.
- Multiple random starting points should be used to find the global optimal solution.

Gaussian mixture

 Each cluster is described in terms of a Gaussian density, which has a centroid and a covariance matrix.

Consider "observations" $Y_1 \sim \mathcal{N}(\mu_1, \Sigma_1), \ldots, Y_k \sim \mathcal{N}(\mu_k, \Sigma_k)$, the true observation is X a weighted average:

$$X = \sum_{i=1}^k p_i Y_i, \quad ext{ with } \sum_{i=1}^k p_i = 1 ext{ and } 0 < p_i < 1$$

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▶ Generate X from cluster $\mathcal{N}(\mu_i, \Sigma_i)$ with probability p_i .

Gaussian mixture: Model parameters

Consider "observations" $Y_1 \sim \mathcal{N}(\mu_1, \Sigma_1), \ldots, Y_k \sim \mathcal{N}(\mu_k, \Sigma_k)$, the true observation is X a weighted average:

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Likelihood function:

$$\ell(\{\mu_j, \Sigma_j, p_j\}_{j=1}^k | x) = f_X(x | \{\mu_j, \Sigma_j, p_j\}_{j=1}^k) = \sum_{i=1}^k p_i \phi(x; \mu_j, \Sigma_j)$$

▶ Goal: find the mean and covariance $\{\mu_j, \Sigma_j\}_{j=1}^k$ and the weights $\{p_j\}_{j=1}^k$ that maximize the likelihood function.

Gaussian mixture: Model estimation

$$\ell(\{\mu_j, \Sigma_j, p_j\}_{j=1}^k | x) = f_X(x | \{\mu_j, \Sigma_j, p_j\}_{j=1}^k) = \sum_{j=1}^k p_j \phi(x; \mu_j, \Sigma_j)$$

Fixing the cluster mean and covariance $\{\mu_j, \Sigma_j\}_{j=1}^k$ and weights $\{p_j\}_{j=1}^k$, find the contribution of clusters on each point:

$$\hat{\rho}_{ij} = \frac{p_j \phi(x_i; \mu_j, \Sigma_j)}{\sum_{j=1}^k p_j \phi(x_i; \mu_j, \Sigma_j)}, \quad \text{for each point } x_i$$

Update the mean and covariance matrix and weights, using the weighted average of samples:

$$\mu_{j} = \frac{\sum_{i=1}^{N} \hat{\rho}_{ij} x_{i}}{\sum_{i=1}^{N} \hat{\rho}_{ij}}, \quad \Sigma_{j} = \frac{\sum_{i=1}^{N} \hat{\rho}_{ij} (x_{i} - \mu_{j}) (x_{i} - \mu_{j})^{\top}}{\sum_{i=1}^{N} \hat{\rho}_{ij}}, \quad p_{j} = \frac{\sum_{i=1}^{N} \hat{\rho}_{ij}}{N}$$

Gaussian mixture: EM algorithm

Fixing the cluster mean and covariance $\{\mu_j, \Sigma_j\}_{j=1}^k$ and weights $\{p_j\}_{j=1}^k$, find the contribution of clusters on each point:

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Expectation step: the assignment of cluster on each point is random. Compute its expectation given old model parameters.

Gaussian mixture: EM algorithm

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Maximization step: maximize the likelihood function ruling out the randomness of cluster membership assignment with its expectation.

- ► EM algorithm is guaranteed to increase the objective function value at each iteration.
- Not guaranteed to find the global optimal solution. Multiple starting points needed.

Gaussian mixture vs K-means: cluster description

For each data point x_i and clusters $C_1, ..., C_k$

- K-means: center point for each cluster
- Gaussian mixture: mean and covariance matrix for each cluster

Gaussian mixture vs K-means: soft vs hard assignment

For each data point x_i and clusters $C_1, ..., C_k$

- ► K-means: assign 1 to one cluster and 0 to all other clusters.
- ▶ Gaussian mixture: assign probability $p1, ..., p_k$ to all clusters.

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- ► K-means: assign 1 to one cluster and 0 to all other clusters.
- ▶ Gaussian mixture: assign probability $p1, ..., p_k$ to all clusters.
- When Gaussian mixture has covariance matrix all as σ^2 I, the assigned probability is a monotone function of the distance between data point and the center.
- ▶ When σ^2 approaches 0, Gaussian mixture is identical to K-means.

Gaussian mixture vs K-means: optimization procedure

- ► K-means: iterate between finding cluster center points and assigning cluster membership to each point
- ► Gaussian mixture: iterate between assigning cluster weights and estimate model parameters

Gaussian mixture vs K-means: optimization procedure

- ► K-means: iterate between finding cluster center points and assigning cluster membership to each point
- Gaussian mixture: iterate between assigning cluster weights and estimate model parameters
- K-means: alternative maximization, each step explicitly solve an optimization problem
- Gaussian mixture: EM algorithm, E-step computes expectation,
 M-step maximizes a likelihood function different from the original objective function

K-means and Gaussian mixture for classification

For a new coming point,

- K-means: assign the cluster membership by its distance to the cluster center.
- ► Gaussian mixture: assign the cluster membership weights, and select the cluster with largest weight.
- Majority vote in the selected cluster.

Reference

Elements of Statistical Learning: Section 8.5, Section 13.2 and Section 14.3.