

AUTOMATED TRAFFIC SIGNAL PERFORMANCE MEASURES: CASE STUDIES

INSTITUTE OF TRANSPORTATION ENGINEERS WEBINAR PART 2 – MAY 7, 2014



ITE Webinar Series on Automated Traffic Signal Performance Measures (SPMs)

- ▶ Achieve Your Agency's Objectives Using SPMs
 - April 9, 2014, 12:00 pm to 1:30 pm. Eastern
- ▶ SPM Case Studies
 - May 7, 2014, 12:00 pm to 1:30 pm. Eastern
- ▶ Critical Infrastructure Elements for SPMs
 - June 11, 2014, 12:00 pm to 1:30 pm. Eastern

Automated Traffic Signal Performance Measures

Technology Implementation Group: 2013 Focus Technology

<http://tig.transportation.org>

Mission: Investing time and money to accelerate technology adoption by agencies nationwide



Your Speakers Today



Jamie Mackey, UDOT



Amanda Stevens, INDOT



Alex Hainen, Purdue



Steve Misgen, MnDOT



Rick Denney, FHWA



Moderator

AUTOMATED TRAFFIC SIGNAL PERFORMANCE MEASURES CASE STUDIES: UDOT



INSTITUTE OF TRANSPORTATION ENGINEERS WEBINAR PART 1 – MAY 7, 2014
PRESENTED BY JAMIE MACKEY, UDOT

Automated Signal Performance Measures Goals

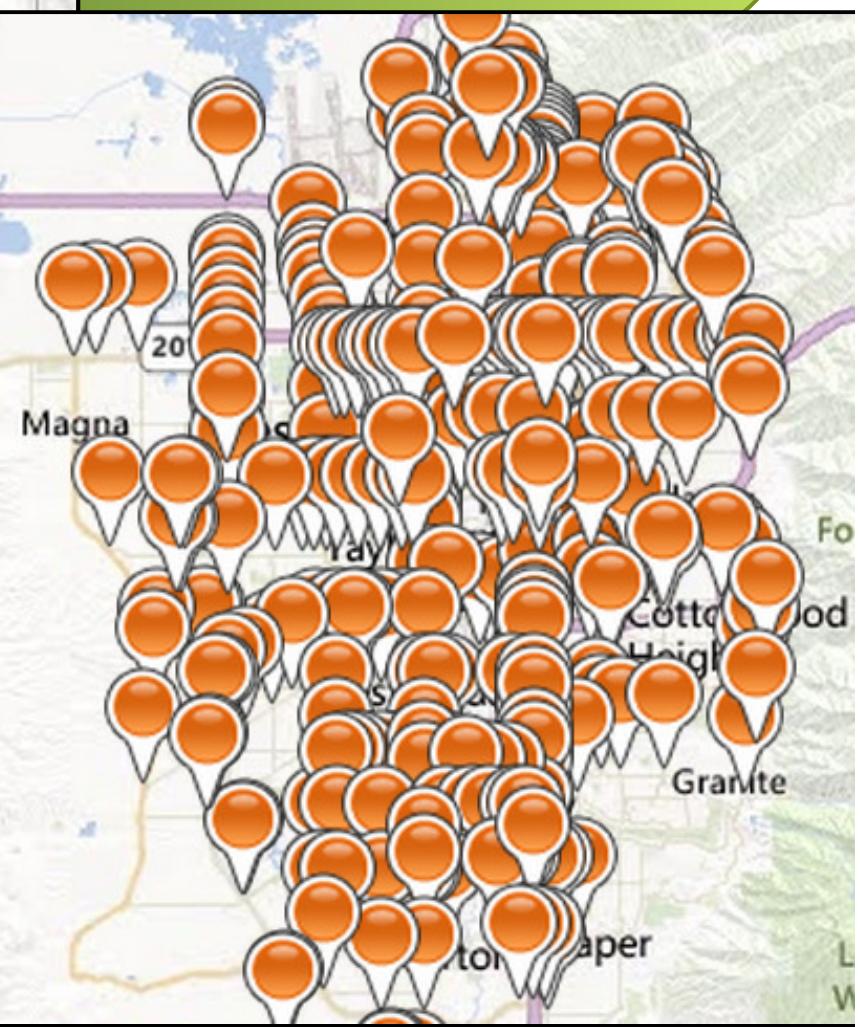
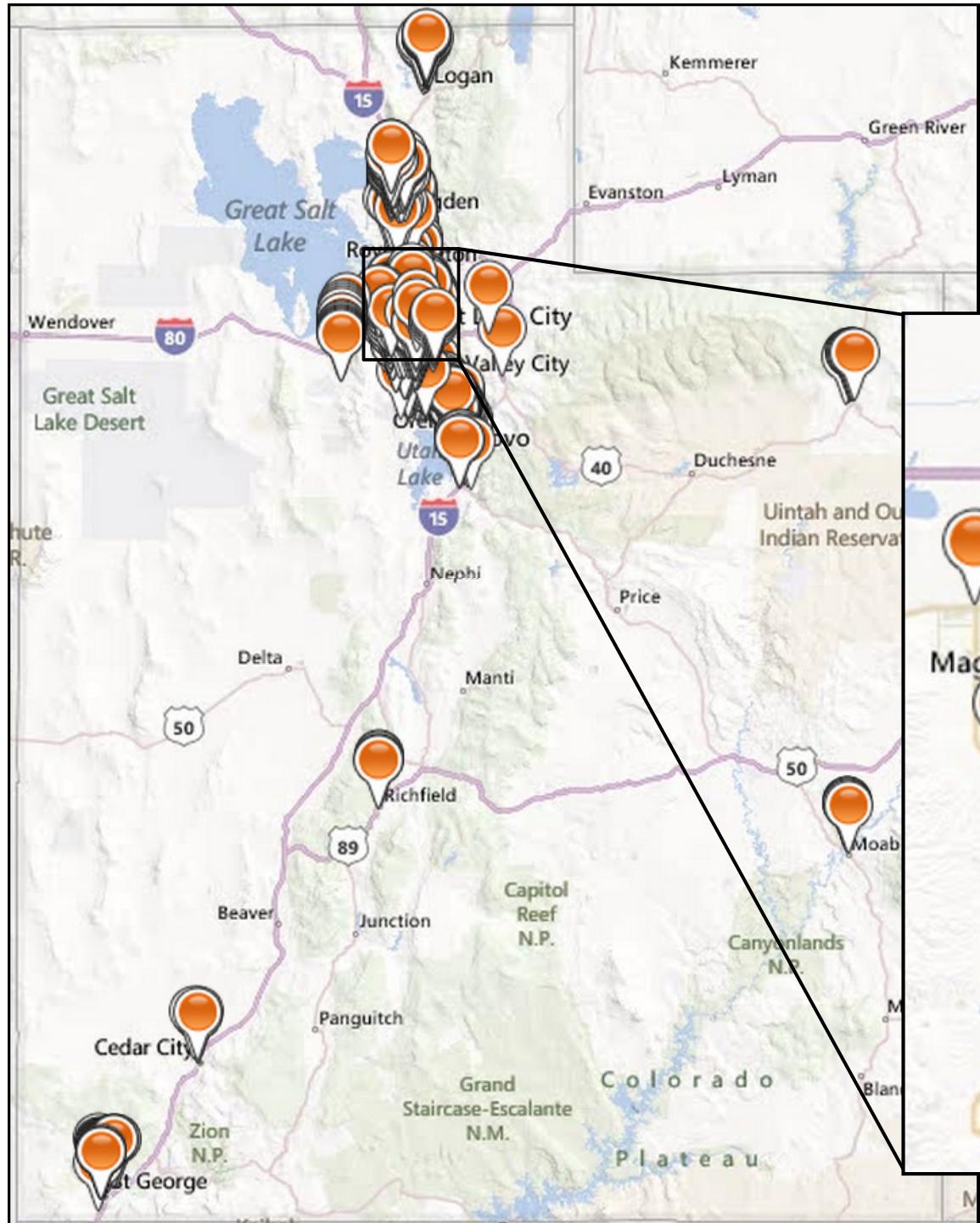
- ▶ Operate & optimize system without field data collection
- ▶ Catch problems as they happen
- ▶ Retime signals as needed, not on a schedule
- ▶ Communicate signal/corridor/system performance to public & agency leaders

Signal Performance Metrics

Charts	Reports	Log Action Taken	Links	FAQ																																																	
->Signal Metrics																																																					
<div style="display: flex; justify-content: space-between;"> <div style="width: 45%;"> <div style="border: 1px solid #ccc; padding: 5px; margin-bottom: 10px;"> Selected Signal <div style="border: 1px solid #ccc; padding: 2px; width: 150px; height: 20px; margin-bottom: 5px;"></div> No Signal Selected </div> <div style="border: 1px solid #ccc; padding: 5px; margin-bottom: 10px;"> Signals <div style="display: flex; justify-content: space-between;"> <div style="width: 40%;"> Region <input style="border: 1px solid #ccc; padding: 2px; width: 100%; height: 25px; margin-bottom: 5px;" type="button" value="All"/> </div> <div style="width: 40%;"> Metric Type <input style="border: 1px solid #ccc; padding: 2px; width: 100%; height: 25px; margin-bottom: 5px;" type="button" value="All"/> </div> </div> <div style="display: flex; justify-content: space-between; align-items: center;"> <div style="width: 40%;"> Filter <input style="border: 1px solid #ccc; padding: 2px; width: 100%; height: 25px; margin-bottom: 5px;" type="button" value="Signal Id"/> </div> <div style="width: 40%;"> <input style="width: 100%; height: 25px; margin-bottom: 5px;" type="text"/> </div> <div style="width: 20%;"> <input style="border: 1px solid #ccc; padding: 2px; width: 100%; height: 25px; margin-bottom: 5px;" type="button" value="Filter"/> </div> <div style="width: 20%;"> <input style="border: 1px solid #ccc; padding: 2px; width: 100%; height: 25px; margin-bottom: 5px;" type="button" value="Clear Filter"/> </div> </div> <div style="border: 1px solid #ccc; padding: 5px; margin-bottom: 10px;"> Signal List </div> <div style="border: 1px solid #ccc; padding: 5px; margin-bottom: 10px;"> Map <div style="border: 1px solid #ccc; padding: 5px; height: 400px; position: relative;">  <div style="position: absolute; top: 0; left: 0; width: 100%; height: 100%; background-color: white; opacity: 0.8; z-index: 1;"></div> <div style="position: absolute; top: 0; left: 0; width: 100%; height: 100%; background-color: black; opacity: 0.2; z-index: 2;"></div> </div> </div> </div> <div style="width: 55%;"> <div style="border: 1px solid #ccc; 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<http://udottraffic.utah.gov/signalperformancemetrics>

Salt Lake Valley



Metrics & Detection Requirements



Controller high-resolution data only

Purdue Phase Termination

Split Monitor

Advanced Count Detection (~400 ft behind stop bar)

Purdue Coordination Diagram & Arrivals on Red

Approach Volume

Approach Delay

Executive Summary Reports

Advanced Detection with Speed

Approach Speed

Lane-by-lane Presence Detection

Split Failure (future)

Lane-by-lane Count Detection

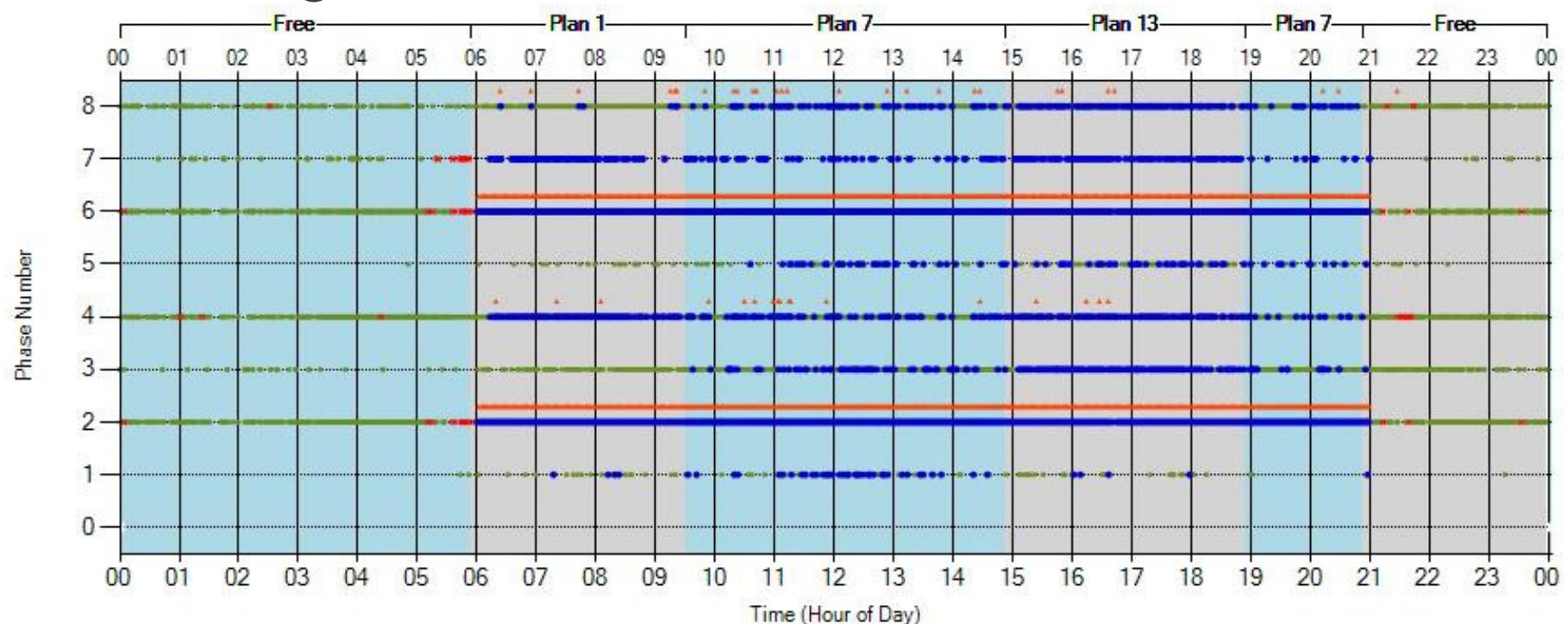
Turning Movement Counts

Probe Travel Time Data (GPS or Bluetooth)

Purdue Travel Time Diagram

Normal Intersection Example: Phase Termination Chart

- ▶ 24-hours of phase data at an 8-phase signal with working detection



● Gapout ● Pedestrian activation (shown above phase line)

● Max out ○ Skip

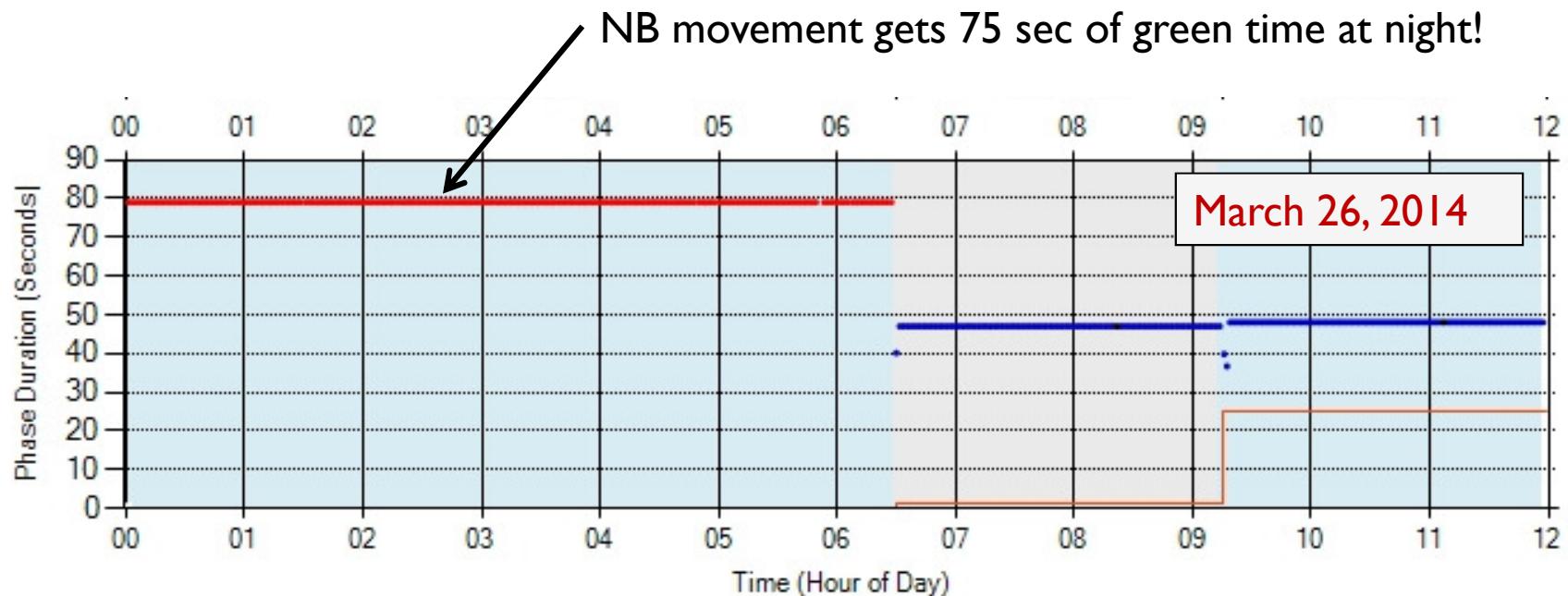
● Force off

Metric: Split Monitor
Detection Requirements: None

Complaint Example: Red light too long



- ▶ Max recall was placed for broken NB detection



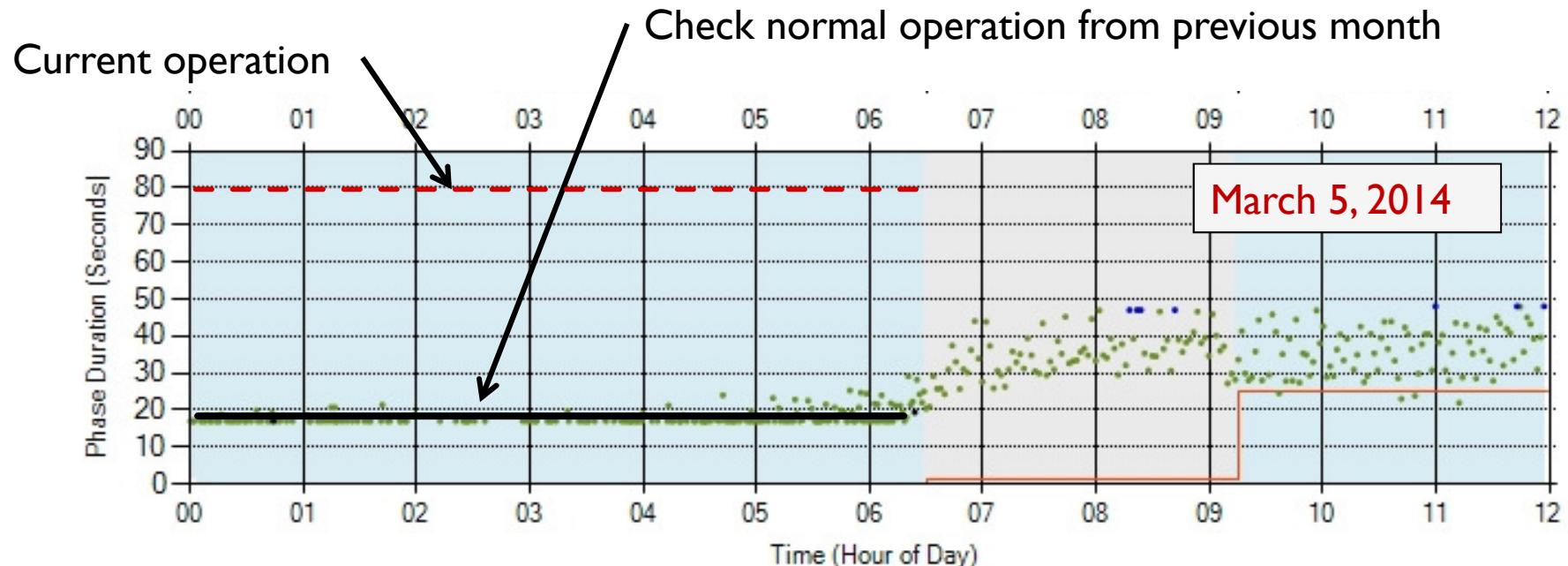
- Gapout
- Max out
- Force off
- Pedestrian activation (shown above phase line)
- Skip

Metric: Split Monitor
Detection Requirements: None

Complaint Example: Red light too long



- ▶ Max recall was placed for broken NB detection



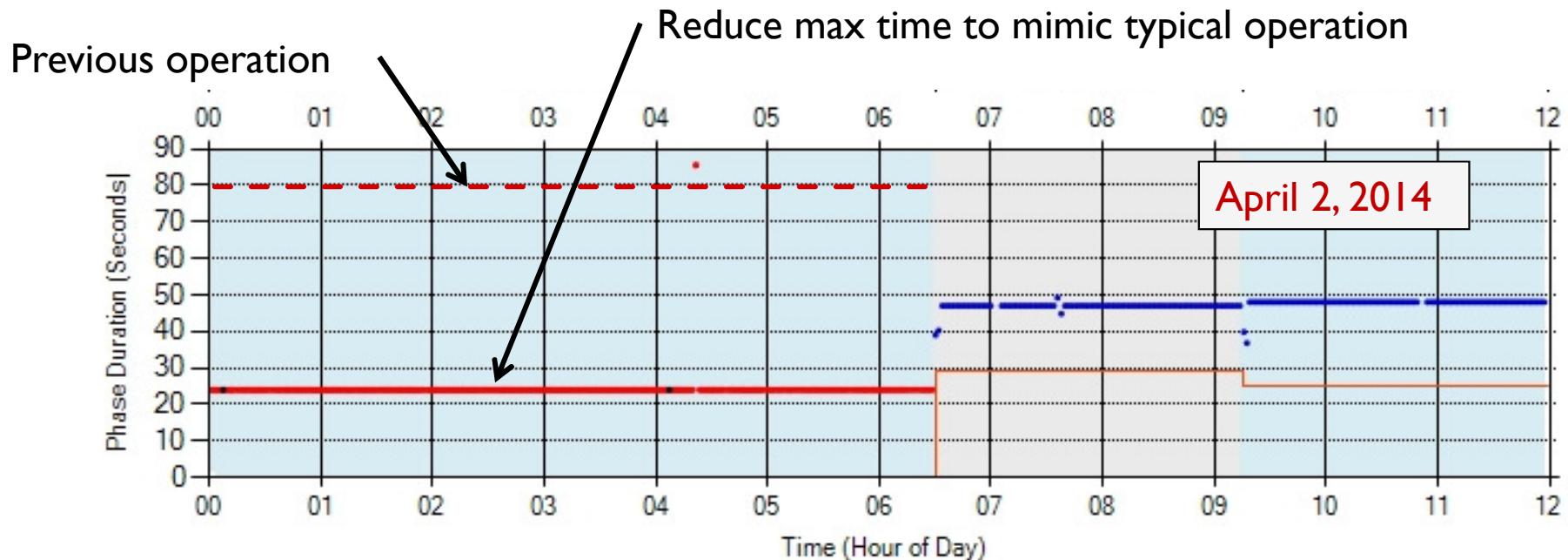
- Gapout
- Max out
- Force off
- Pedestrian activation (shown above phase line)
- Skip

Metric: Split Monitor
Detection Requirements: None

Complaint Example: Red light too long



- ▶ Max recall was placed for broken NB detection



- Gapout
- Max out
- Force off
- Pedestrian activation (shown above phase line)
- Skip

Metric: Split Monitor
Detection Requirements: None

Complaint Example: Split too short

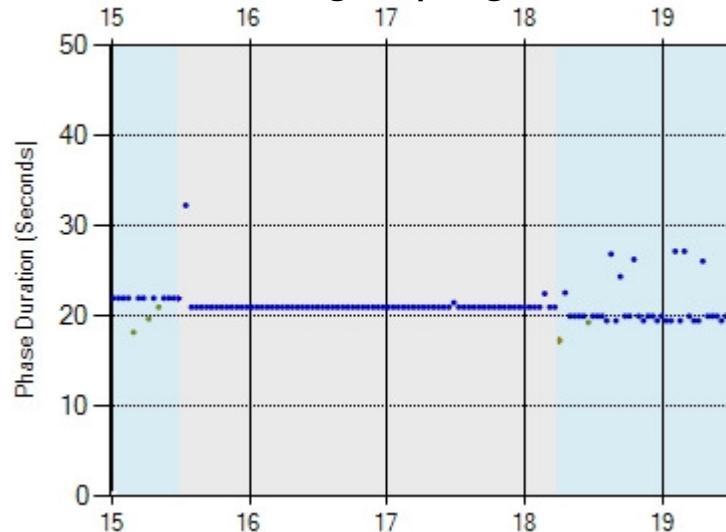


- ▶ Is this a timing or a maintenance issue?

Timing Issue:

Phase always forces off

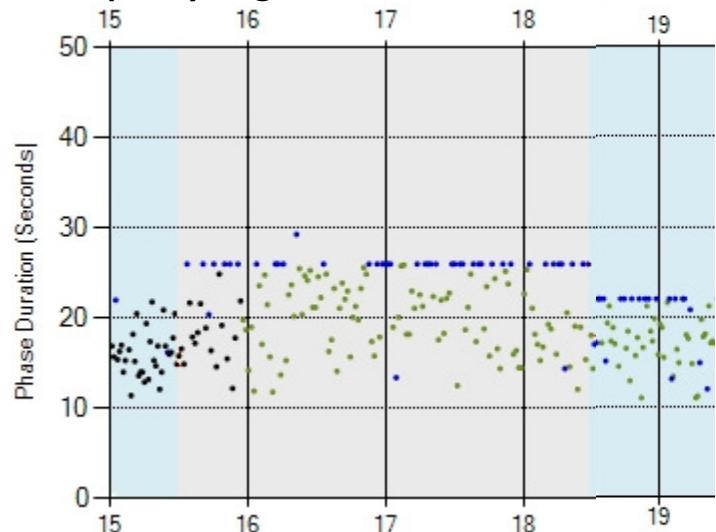
=> Phase is using all programmed time



Maintenance Issue:

Phase often gaps out

=> Spotty right-turn lane detection



● Gapout

● Pedestrian activation (shown above phase line)

● Max out

○ Skip

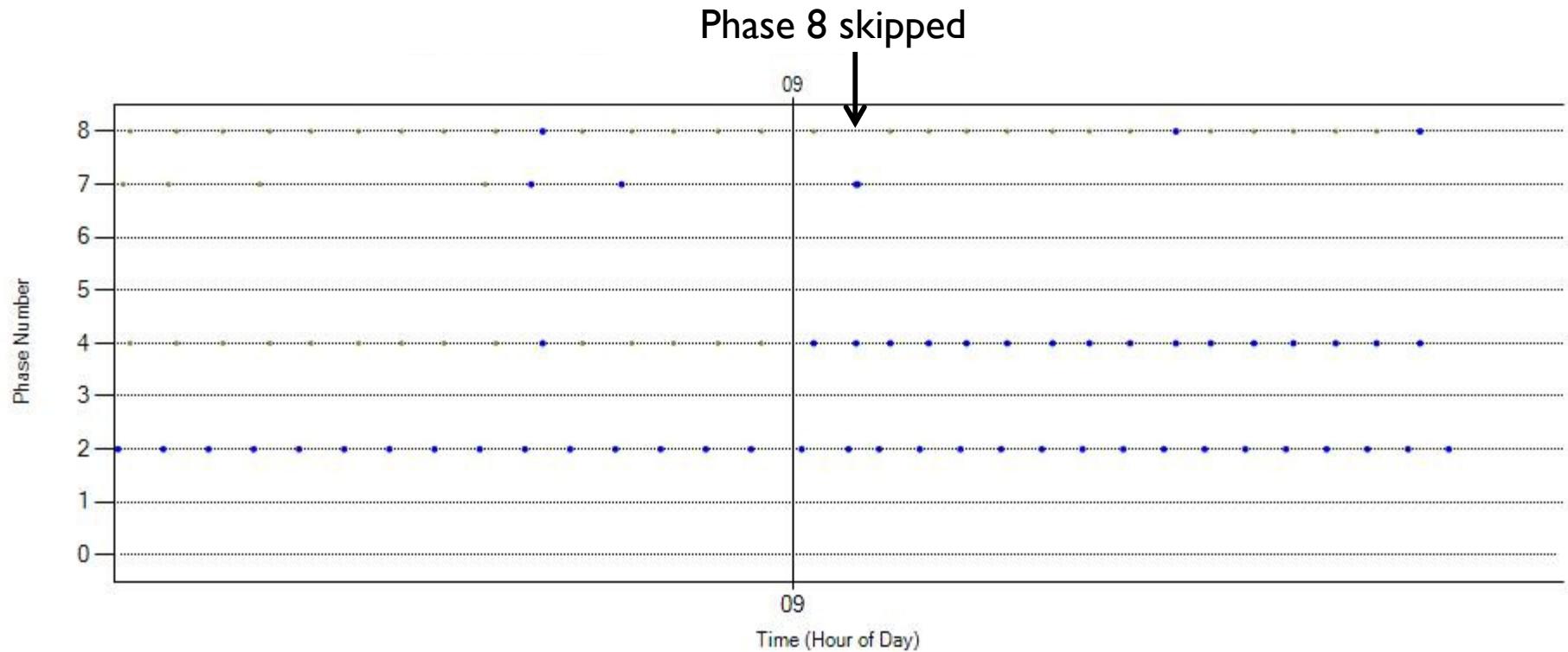
● Force off

Metric: Split Monitor
Detection Requirements: None

Complaint Example: Phase skipped



- ▶ SPMs confirm it was a fluke



● Gapout ● Pedestrian activation (shown above phase line)

● Max out ○ Skip

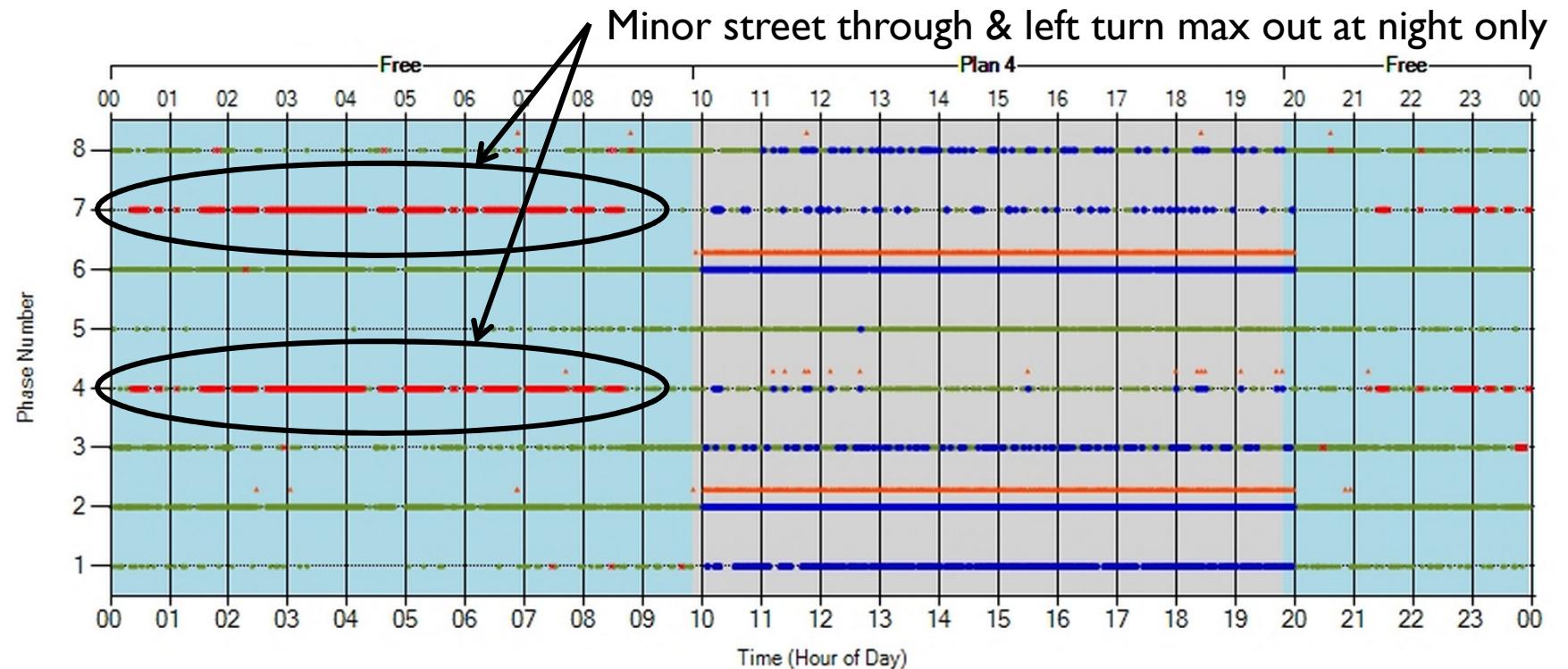
● Force off

Metric: Purdue Phase Termination
Detection Requirements: None

Maintenance Example: Nighttime detection problem



- ▶ BEFORE: Video detection not working at night



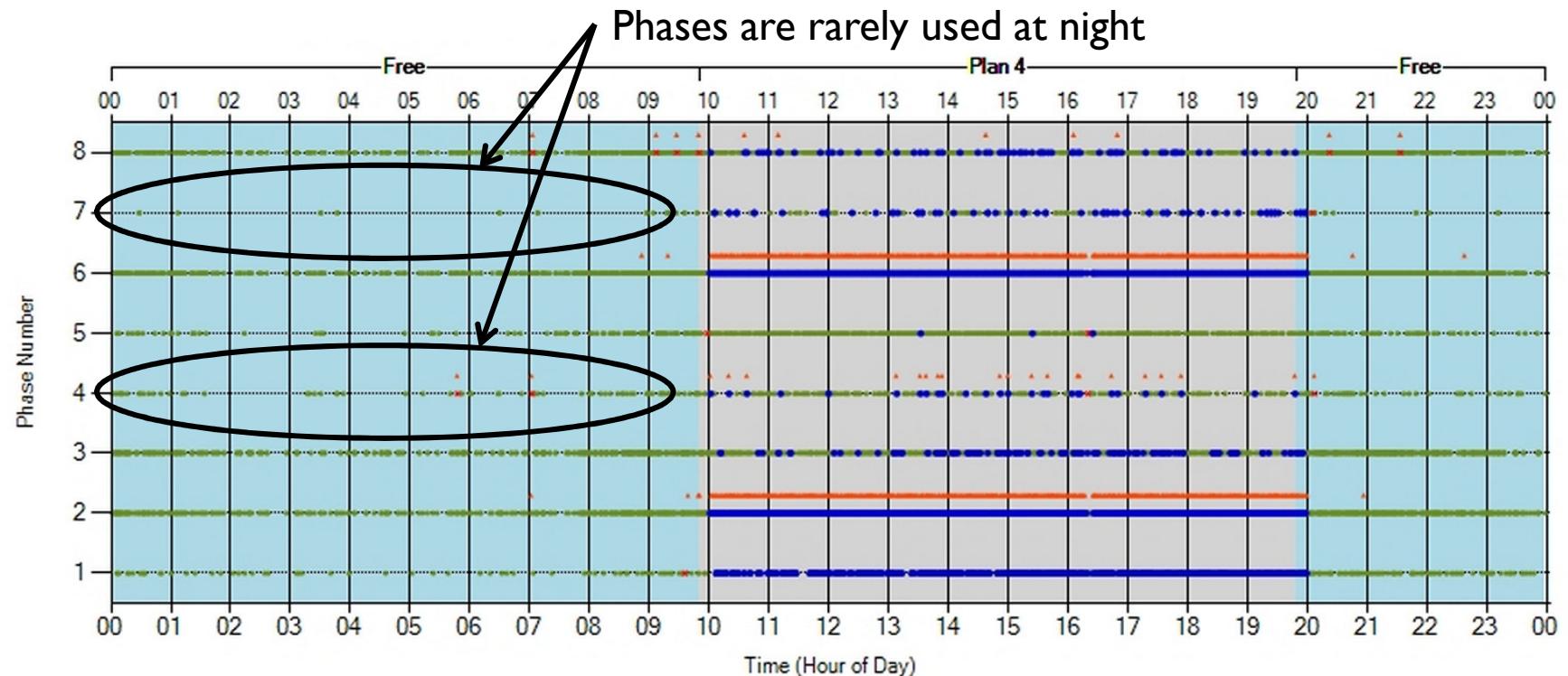
- Gapout
- Max out
- Force off
- Pedestrian activation (shown above phase line)
- Skip

Metric: Purdue Phase Termination
Detection Requirements: None

Maintenance Example: Nighttime detection problem



- ▶ AFTER: New detection technology installed



● Gapout

● Pedestrian activation (shown above phase line)

● Max out

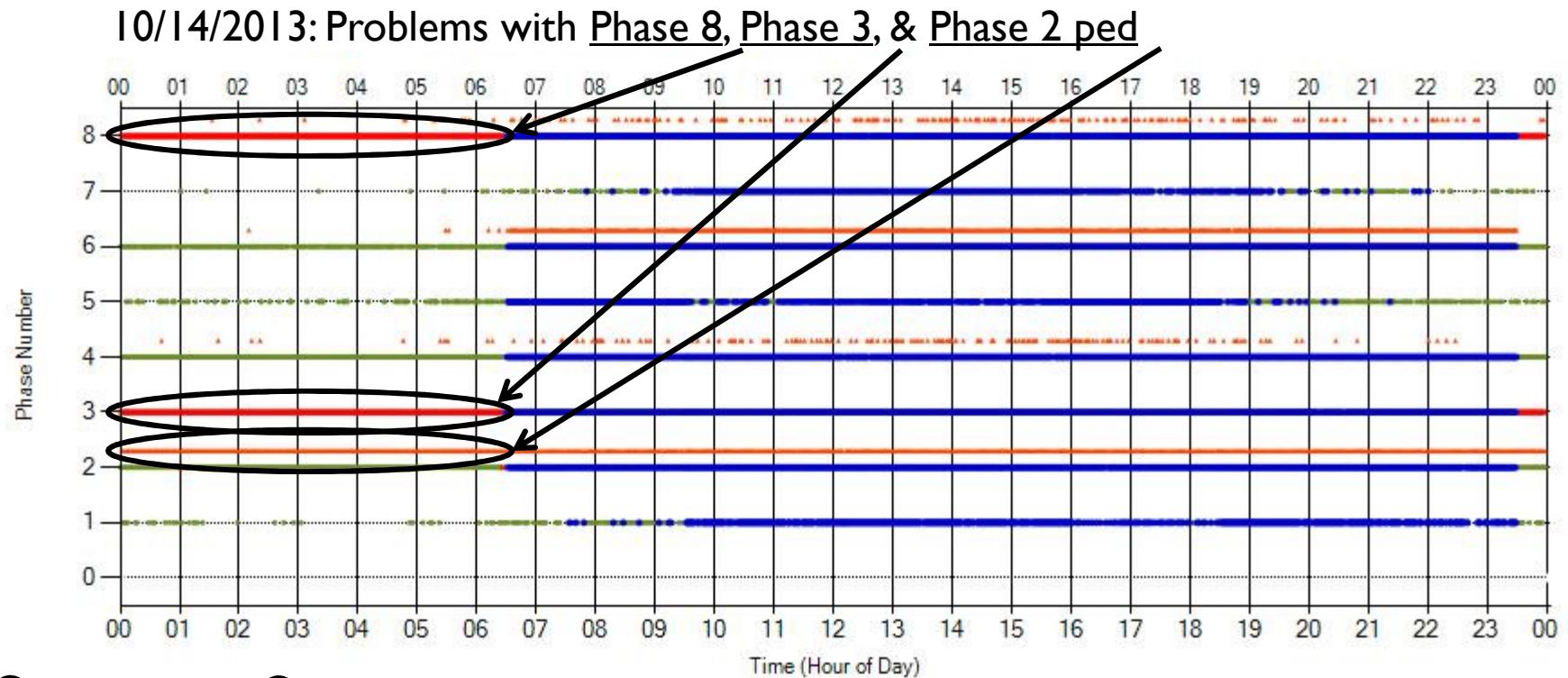
○ Skip

● Force off

Metric: Purdue Phase Termination
Detection Requirements: None

Maintenance Example: Check for additional problems

- ▶ Phase 2 ped problem was not noticed at field visit



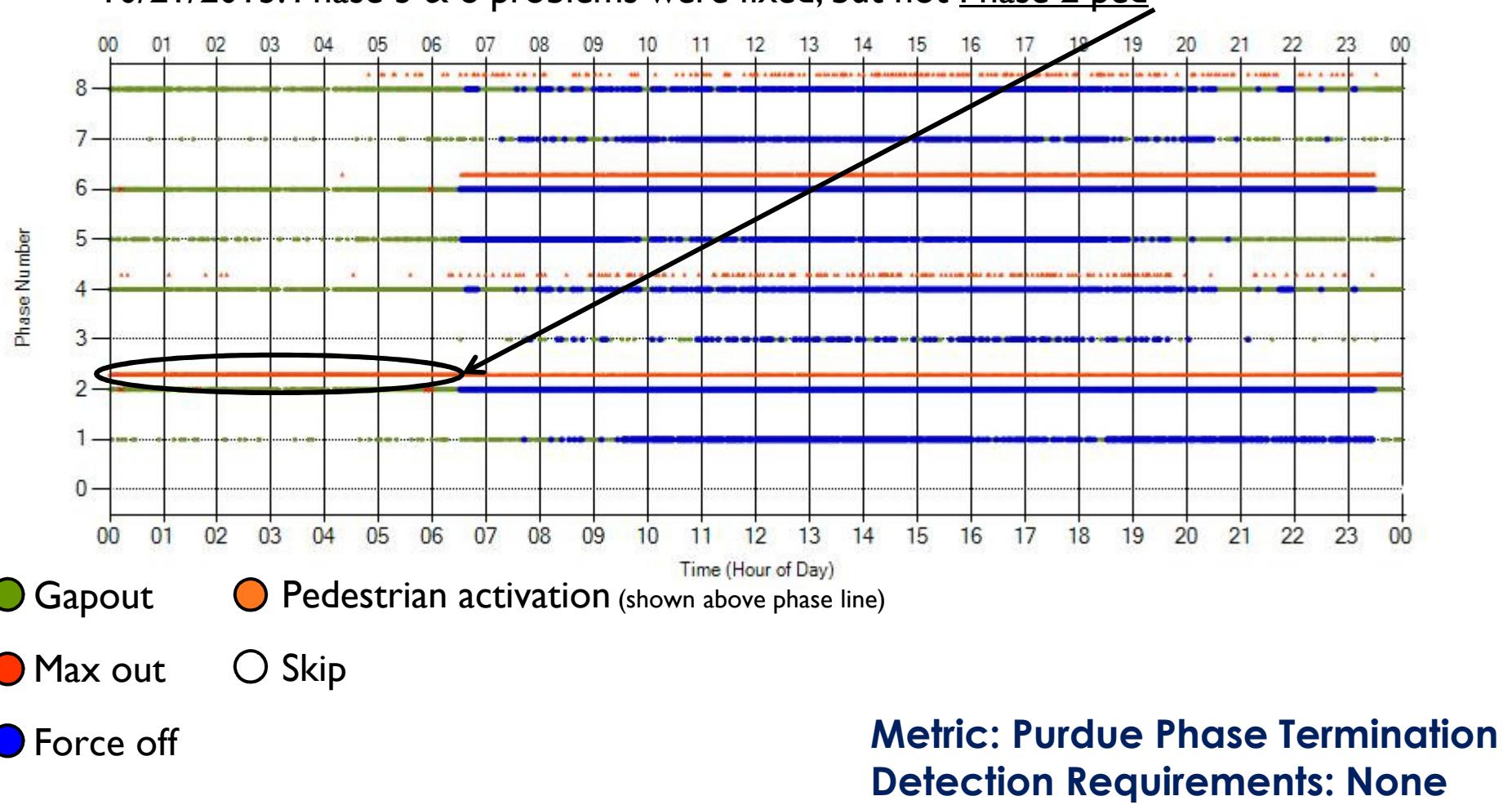
- Gapout
- Max out
- Force off
- Pedestrian activation (shown above phase line)
- Skip

Metric: Purdue Phase Termination
Detection Requirements: None

Maintenance Example: Check for additional problems

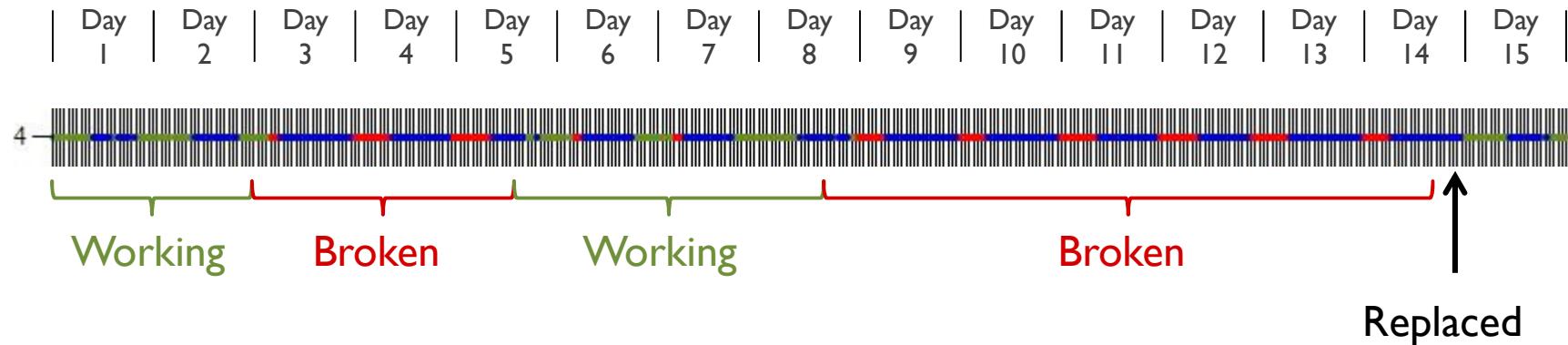
- ▶ Phase 2 ped problem was not noticed at field visit

10/21/2013: Phase 3 & 8 problems were fixed, but not Phase 2 ped



Detection Upgrade Justification

- ▶ Document recurring detection problems



- Gapout
- Max out
- Force off
- Pedestrian activation (shown above phase line)
- Skip

Metric: Purdue Phase Termination
Detection Requirements: None

Alert Example: 100% Max Out



SPM Alerts for 4/9/2014

SPMWatchDog@utah.gov

5092 - SR-126 (1900 W) & Riverdale (5300 S) (Roy) - Phase: 1
5105 - Antelope (SR-108/2000 N) & I-15 NB (Layton) - Phase: 4
6022 - US-89 & Pacific Dr (American Fork) - Phase: 3
6305 - 400 East & 800 North - Phase: 4
6310 - Center Street (Orem) & I-15 SPUI - Phase: 8
7055 - Bangerter Hwy (SR-154) & SR-201 DDI - Phase: 5
7062 - Bangerter Hwy (SR-154) & 4700 South - Phase: 11
7613 - 10600 South & 700 West - Phase: 8
8114 - Bluff Street & I-15 NB Ramps - Phase: 4

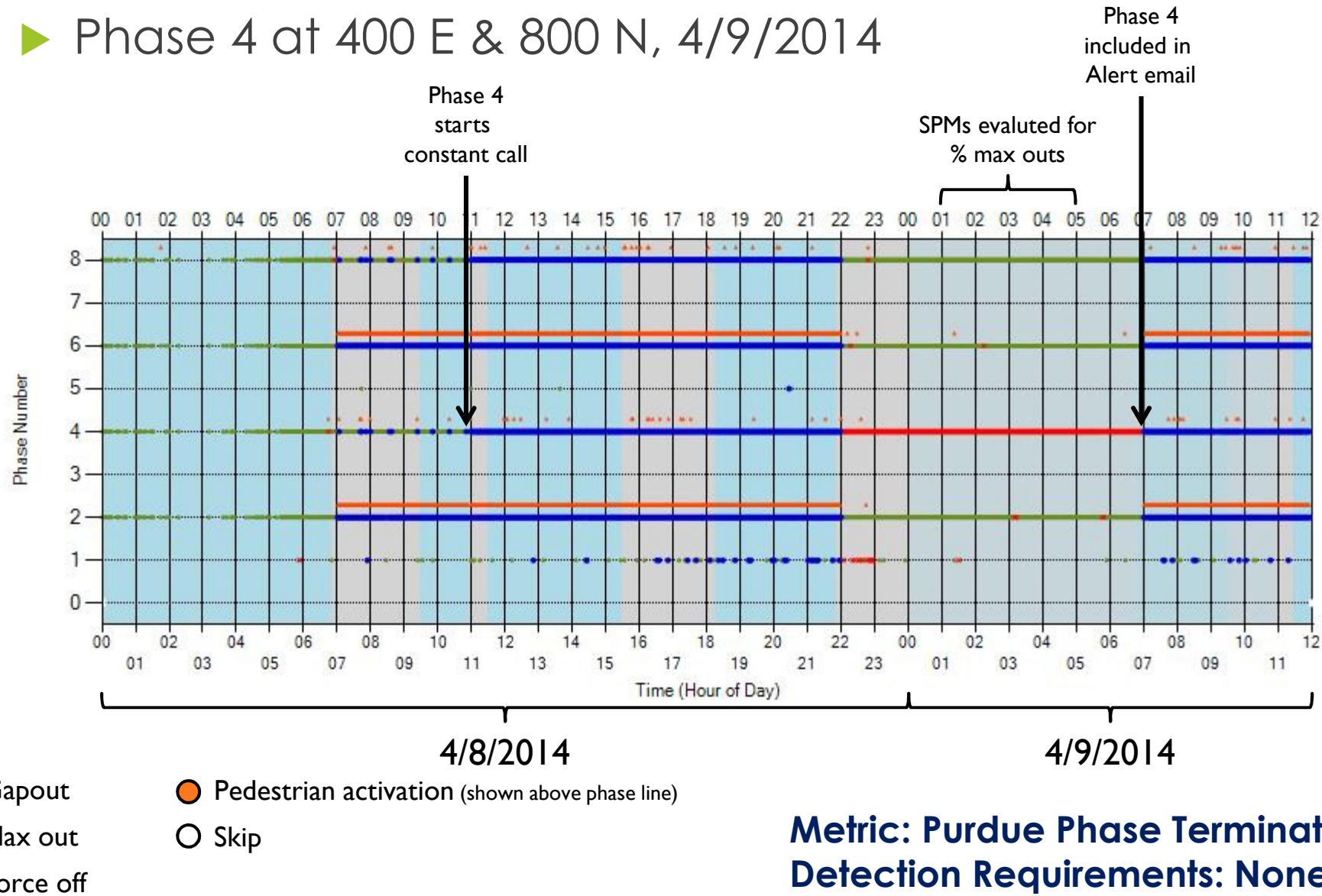
Example

- ▶ Daily email at 7 a.m.
- ▶ Uses Purdue Phase Termination chart data
- ▶ Flags phases with >90% max-outs on each phase between 1 a.m. and 5 a.m.
- ▶ Compare to previous day's list. Only phases with new flags are sent in the email.

Metric: Purdue Phase Termination
Detection Requirements: None

Alert Example: 100% Max Out

► Phase 4 at 400 E & 800 N, 4/9/2014



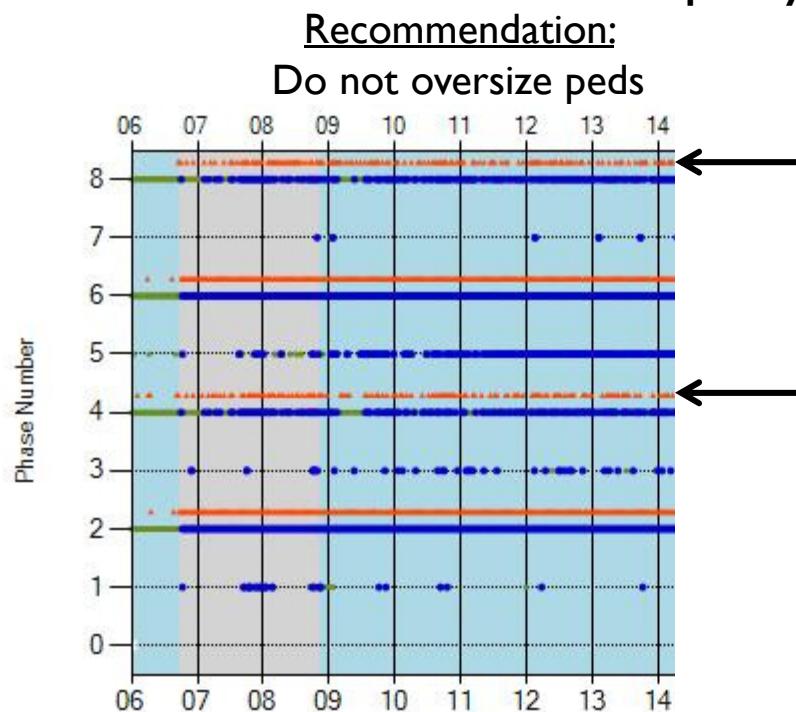
Operations Example: Oversize Peds

- ▶ Check frequency of ped calls

Peds for Phases 4 & 8 are called **frequently**

Recommendation:

Do not oversize peds



← Ped buttons for Phase 4 is rarely pushed

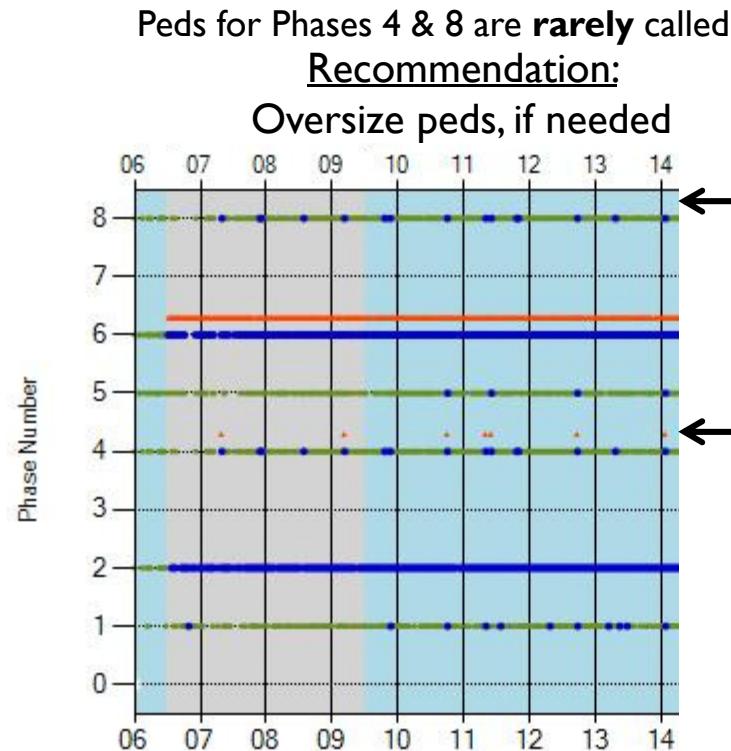
Recommendation:

Oversize peds, if needed

Peds for Phases 4 & 8 are **rarely** called

Recommendation:

Oversize peds, if needed



● Gapout

● Pedestrian activation (shown above phase line)

● Max out

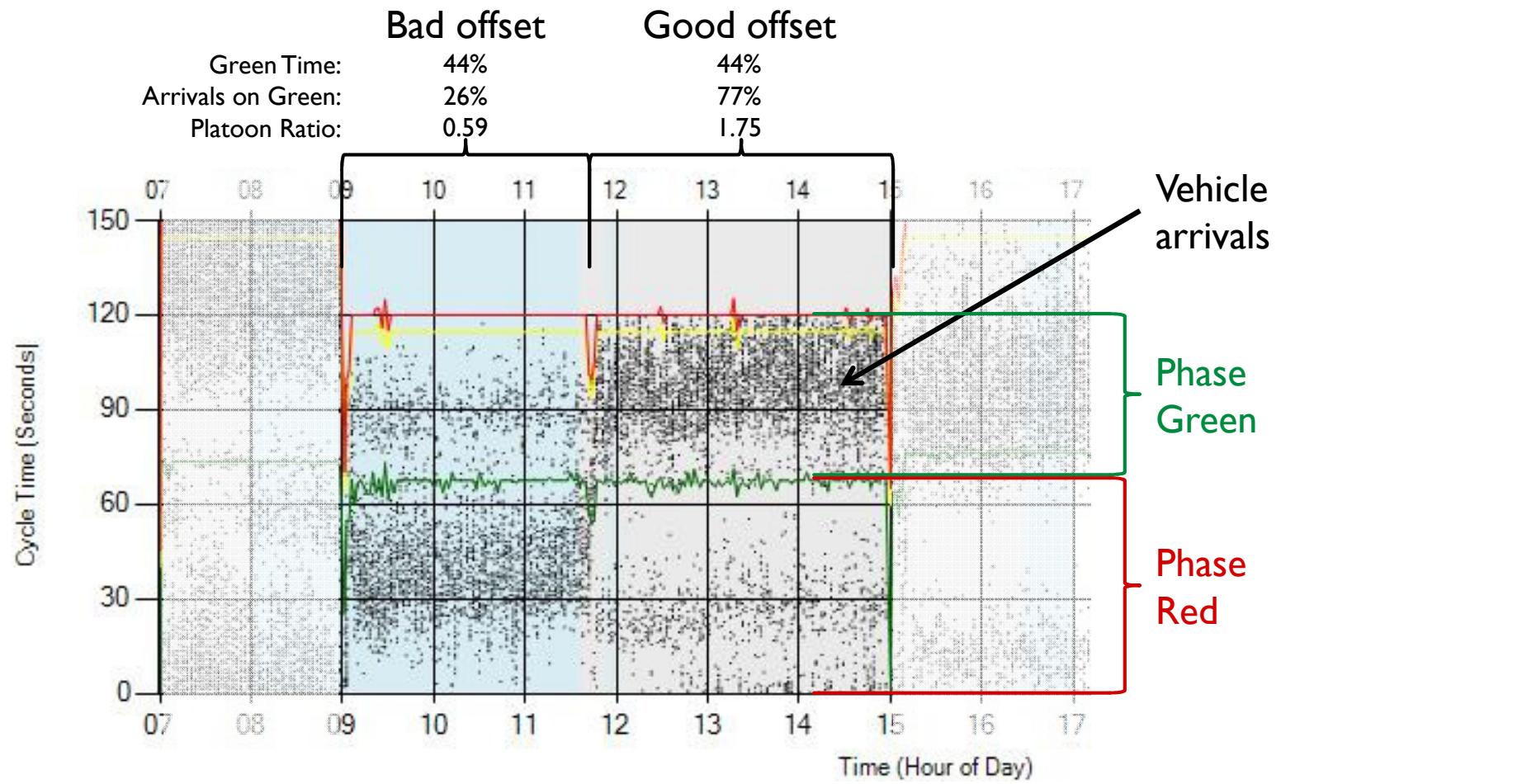
○ Skip

● Force off

Metric: Purdue Phase Termination
Detection Requirements: None

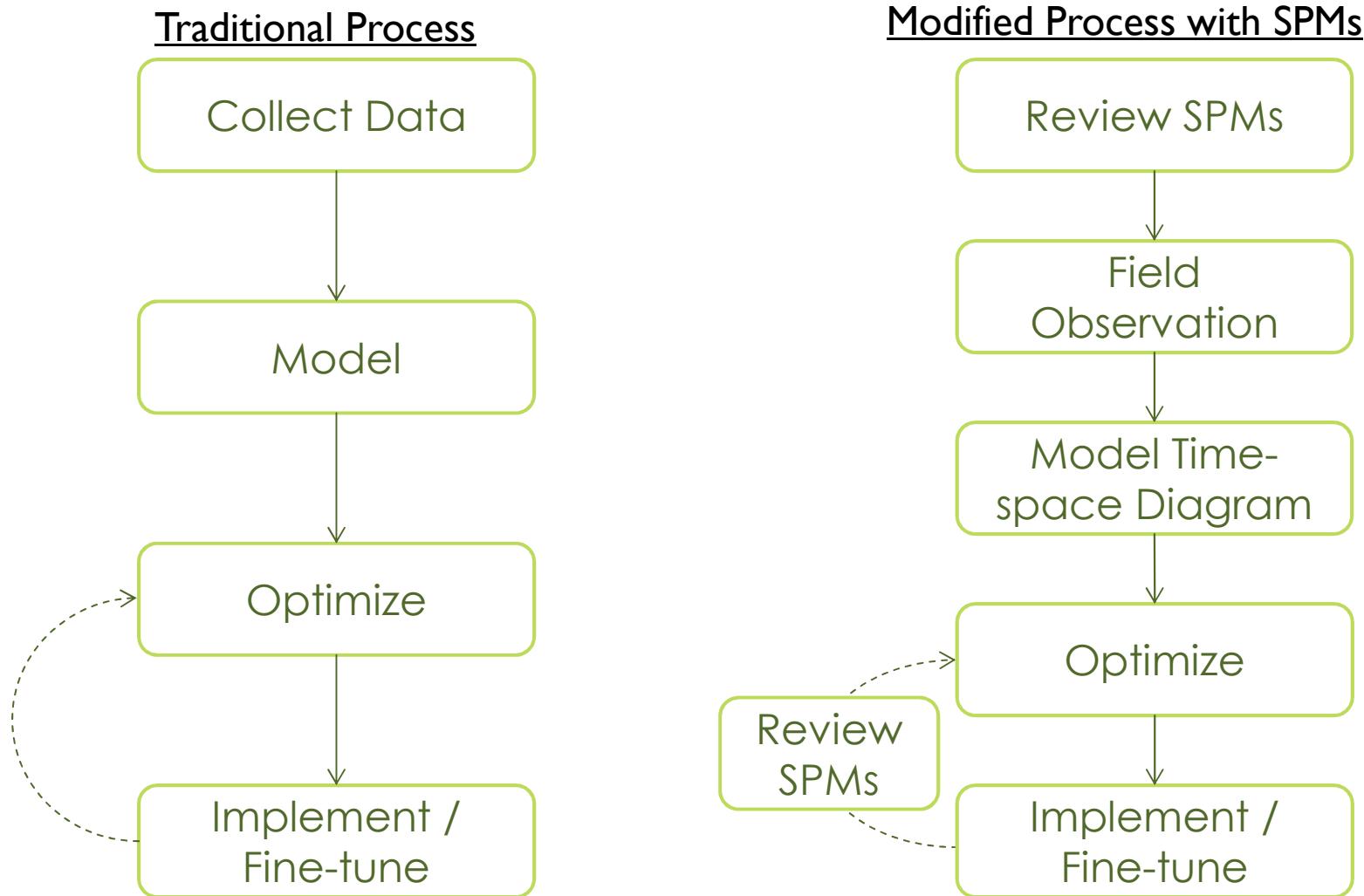
Optimization Example: Progression Quality

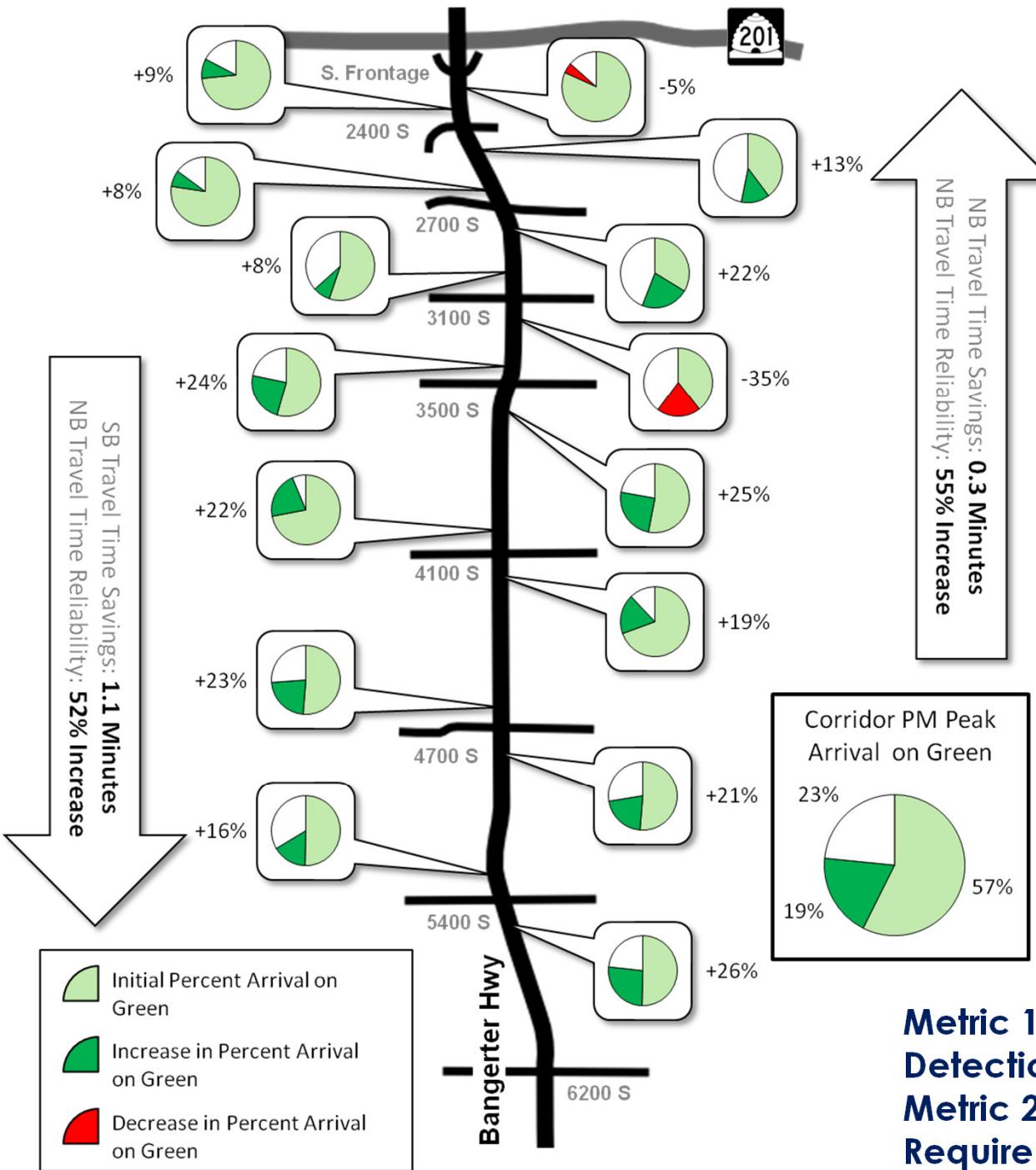
- ▶ Fine-tuning new coordination plans



Metric: Purdue Coordination Diagram
Detection Requirements: Advance

Optimization with SPMs





Before and After Coordination Results

Corridor: Bangerter Hwy, SLC

To/From: SR-201 - 6200 South

Date: March 2013

Time Period: PM Peak

Results:

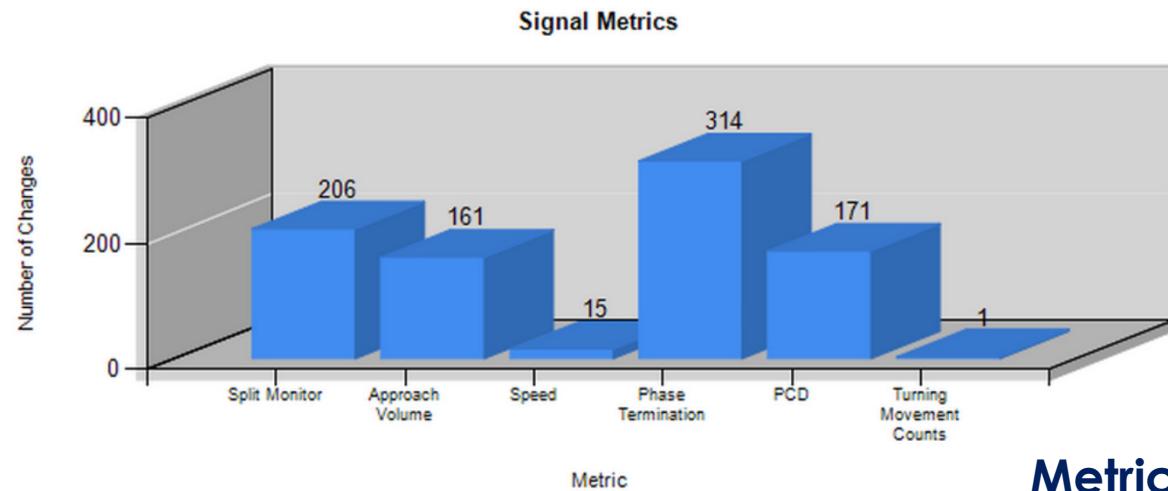
- Arrivals on Green: 19% Increase
- NB TT Savings: 0.3 Minutes
- NB Reliability: 55% Increase
- SB TT Savings: 1.1 Minute
- SB Reliability: 52% Increase

Metric 1: Purdue Coordination Diagram
Detection Requirements: Advance
Metric 2: Purdue Travel Time Diagram
Requirements: Probe data set

Intersection Adjustments using SPMs

January 1, 2013 to December 31, 2013

- ▶ Adjustments made at 325+ intersections
 - ▶ 185 work orders for detector problems
 - ▶ 40 offset adjustments
 - ▶ 5 time-of-day corrections



System Requirements

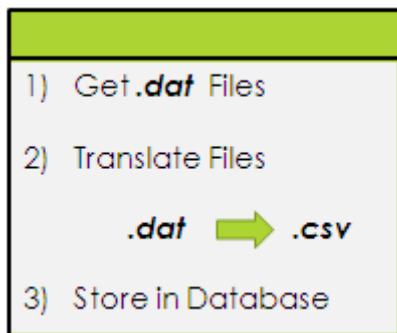
1. Traffic signal controllers with 1/10th s. data logger
 - Econolite (ASC/3; Cobalt)
 - Intelight ATC
 - Naztec (Beta)
 - PEEK ATC
 - Siemens Linux / ATC
2. Communications or storage memory on controllers
3. FTP connection to signal
4. Server to store controller logs
5. Enumerations analyzed and graphed (INDOT & UDOT software developed in-house)

Can be done independent of a Central System!

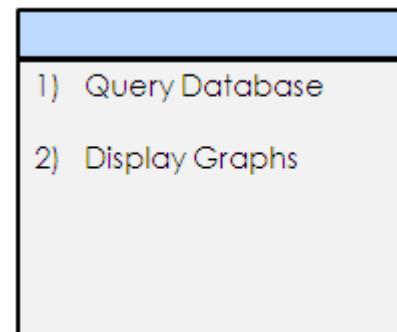
System Requirements



High-resolution Controller



Server



Website



Communications



Detection

Photo courtesy of the Indiana Department of Transportation

AUTOMATED TRAFFIC SIGNAL PERFORMANCE MEASURES CASE STUDIES: INDOT



INSTITUTE OF TRANSPORTATION ENGINEERS WEBINAR PART 1 – MAY 7, 2014
PRESENTED BY AMANDA STEVENS, INDOT AND ALEX HAINEN, PURDUE

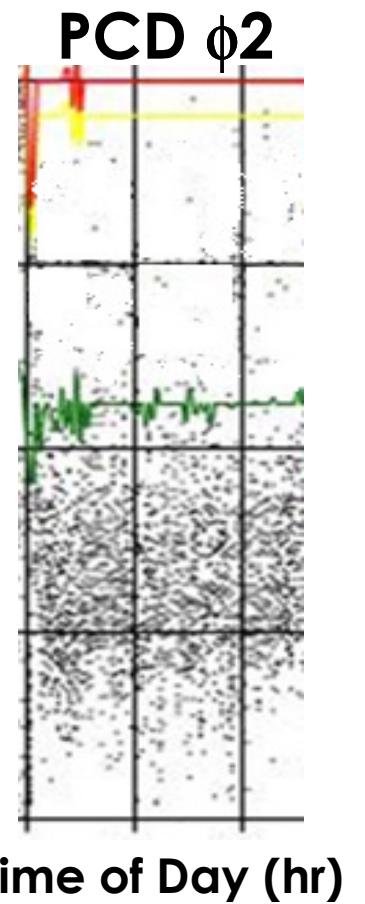


Detection
ON



Single Instance $\phi 2$

Time
in Cycle (s)



Time of Day (hr)

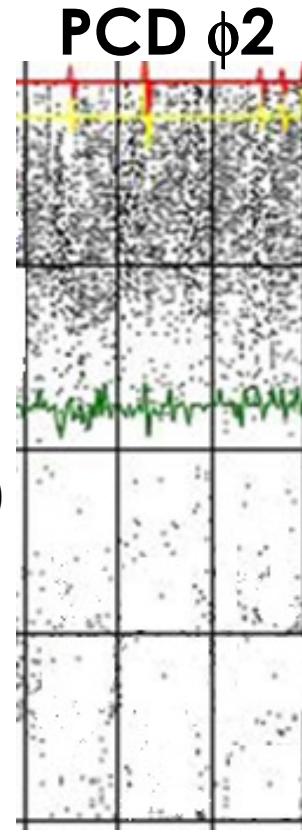
PCD: Red Arrival



Detection
ON

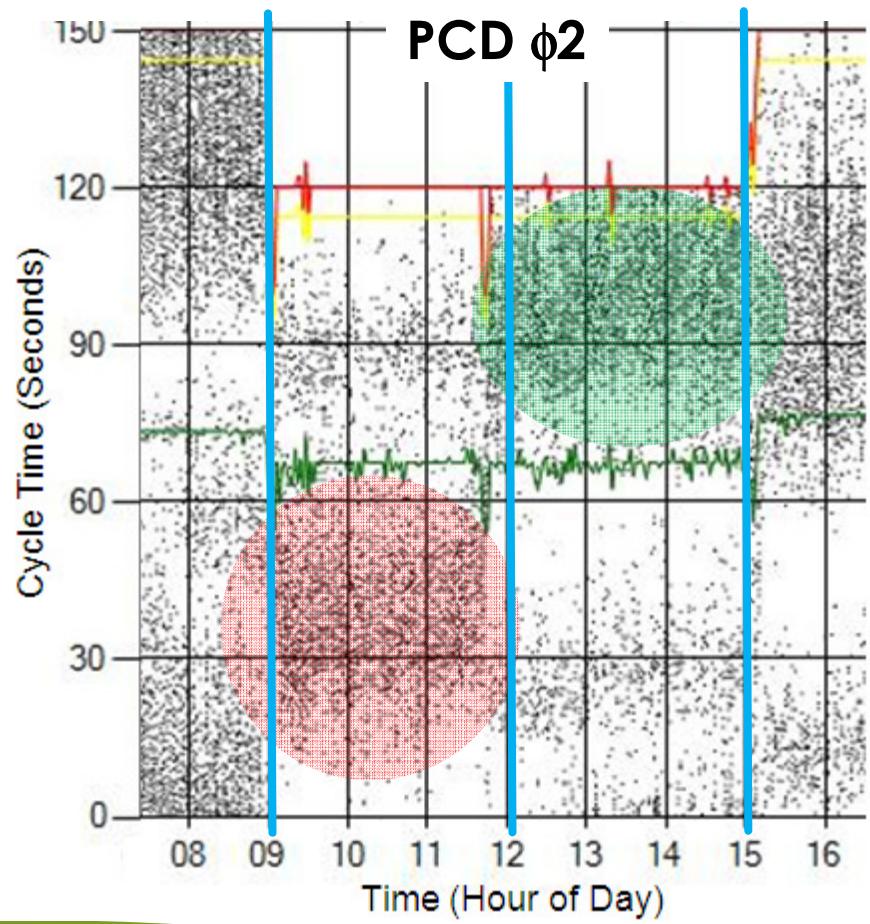


Time
in Cycle (s)



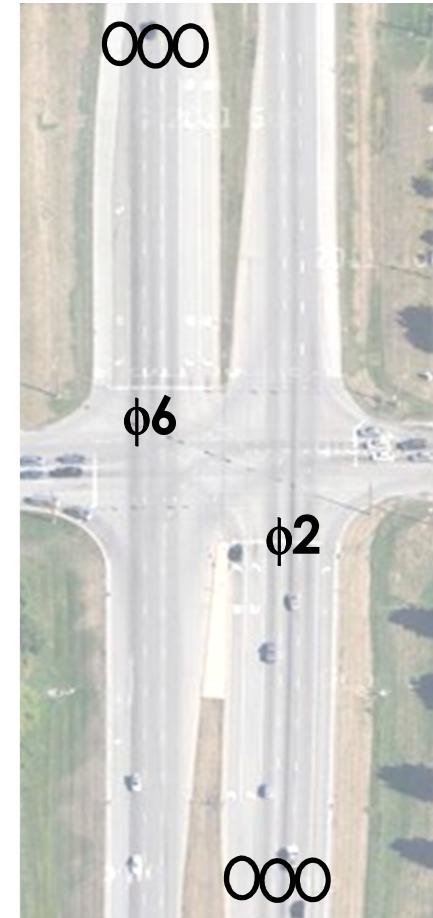
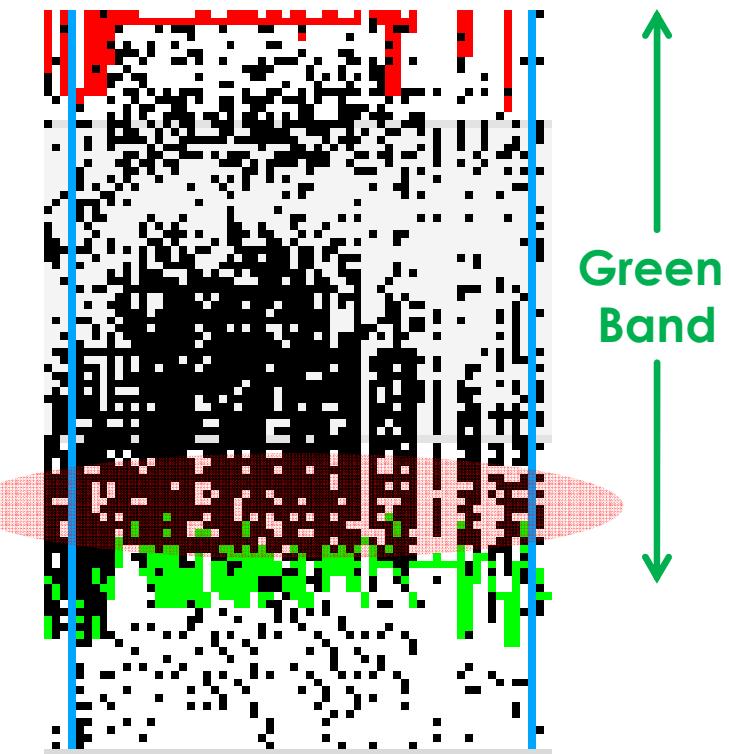
Time of Day (hr)

PCD: Green Arrival

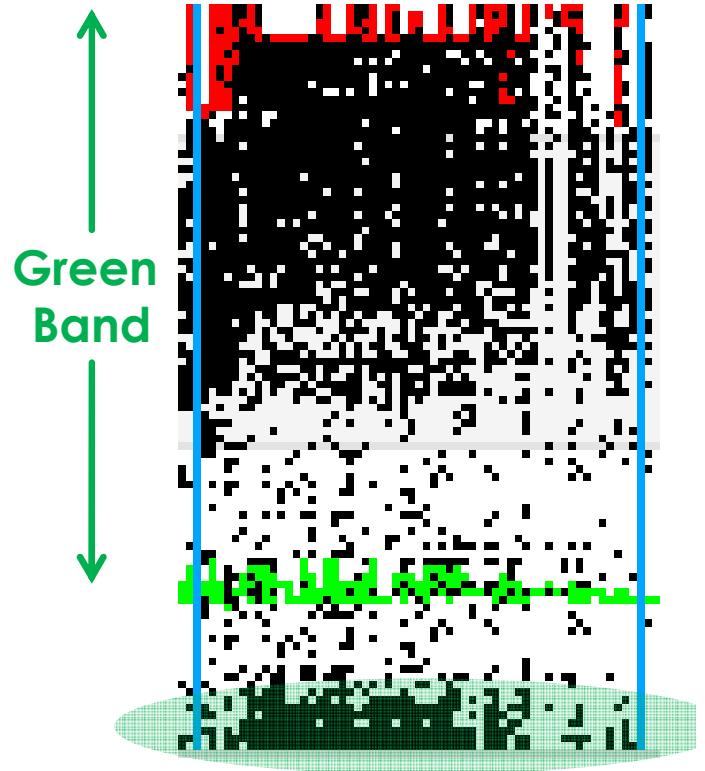


PCD: Platoon Arrival by TOD

PCD $\phi 6$



PCD $\phi 2$



PCD: Adjust Offsets

INDOT System



- **# SIGNALS TOTAL**
- **# SIGNALS ONLINE,
AUTOMATICALLY
STORING DATA &
GENERATING
PERFORMANCE
MEASURE GRAPHS**
- **PEEK ATC, ECONOLITE
ASC/3, SIEMENS M50
SERIES...**

“Human-in-the-Loop-Adaptive”

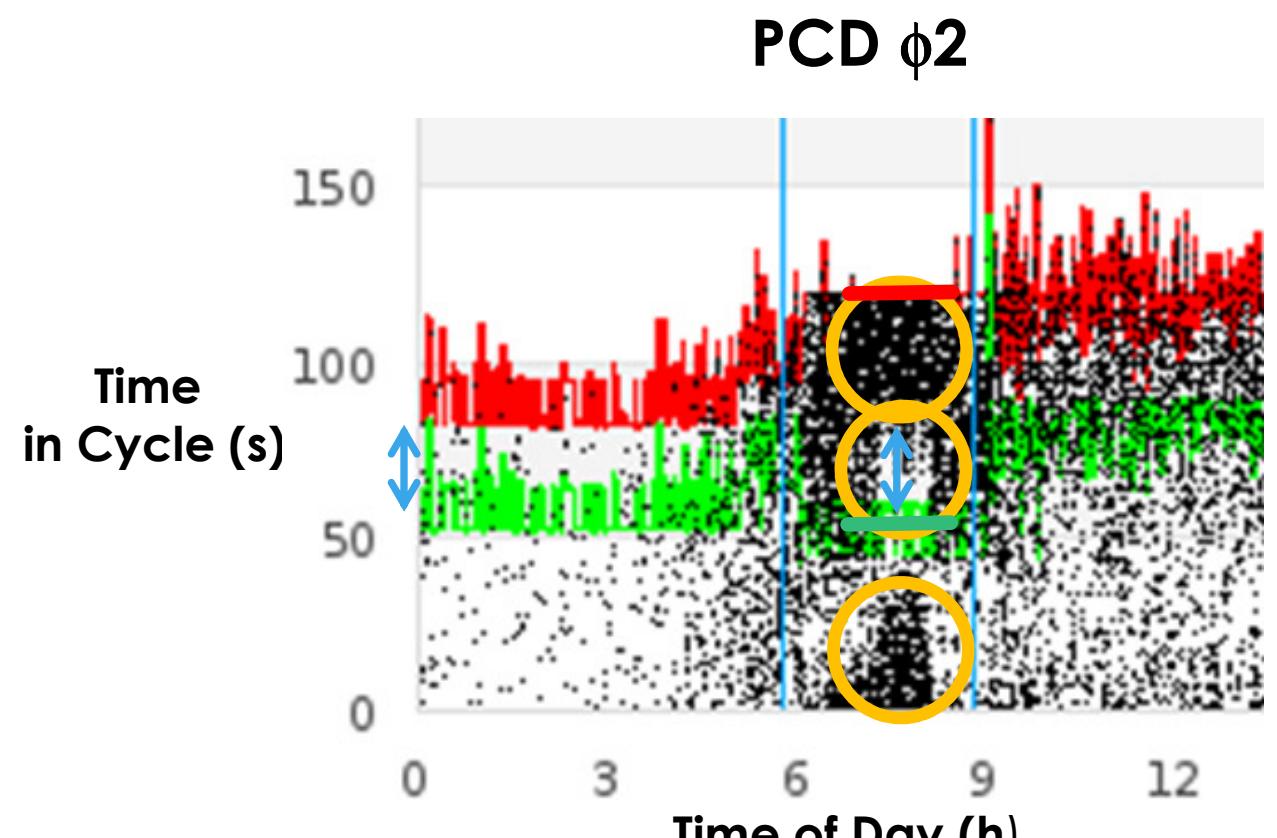


- **WEEKENDS & OFF-PEAKS**
- **ROUTINE RETIMINGS**
- **CONSTRUCTION SEASON:**
 - You cannot be everywhere at once!
 - Could take Months for traffic to settle
 - Project in Flux:
 - Detection
 - Phases
 - Approaches / Lanes
 - Adjacent construction detours

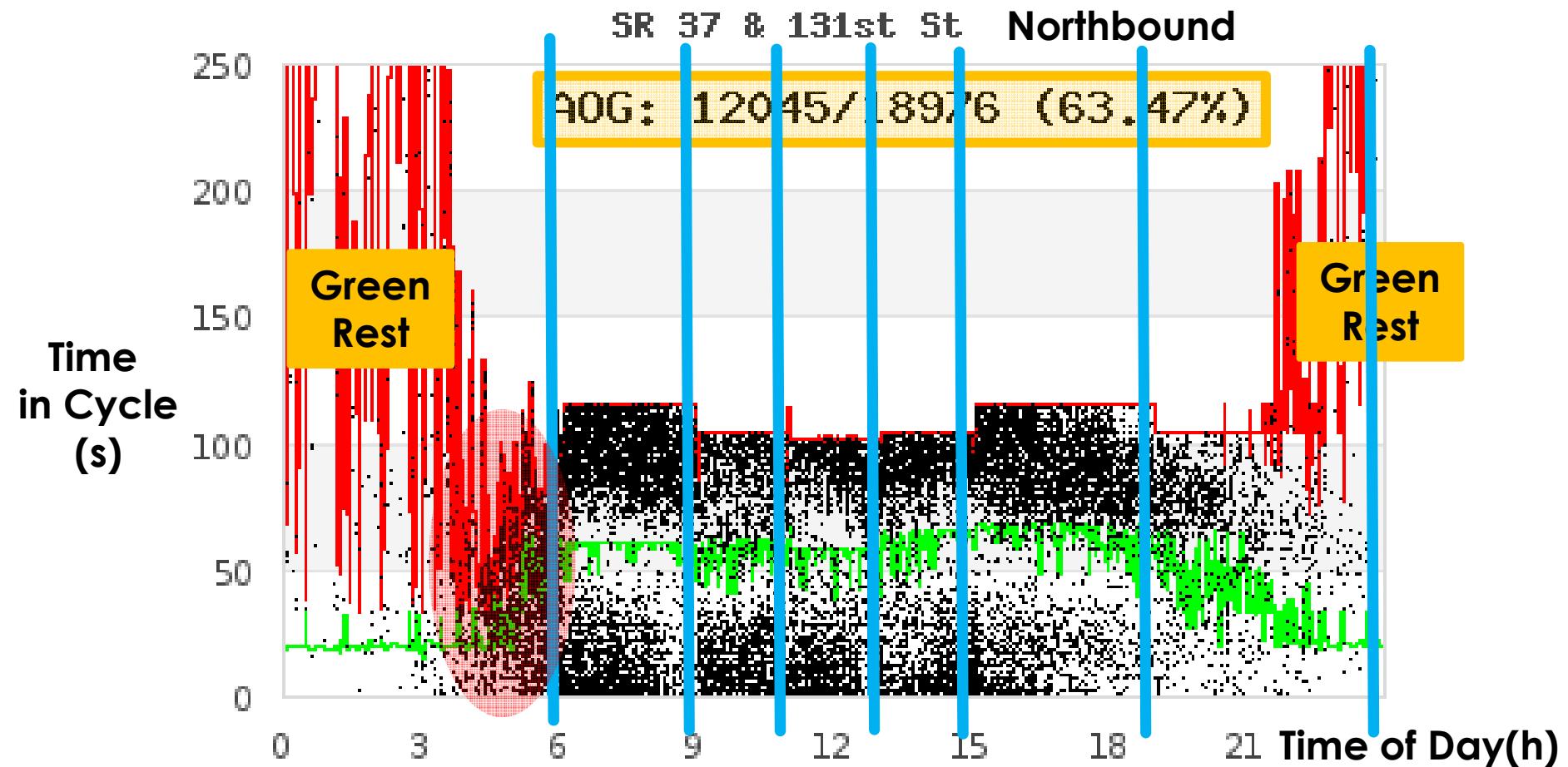
Moving Forward:

- **CLOSELY-SPACED
SIGNALS ALSO NEED
ADVANCED
DETECTION ON LEFT
TURNS**
- **SEPARATE DETECTION
CHANNELS FOR EACH
LANE**





PCD: Cycle Failure



PCD: Pattern Start & End Times



Hi-resolution Event-based Data for Diamond Interchange Operations

ALEX HAINEN

AMANDA STEVENS

CHRIS DAY

RICK FREIJE

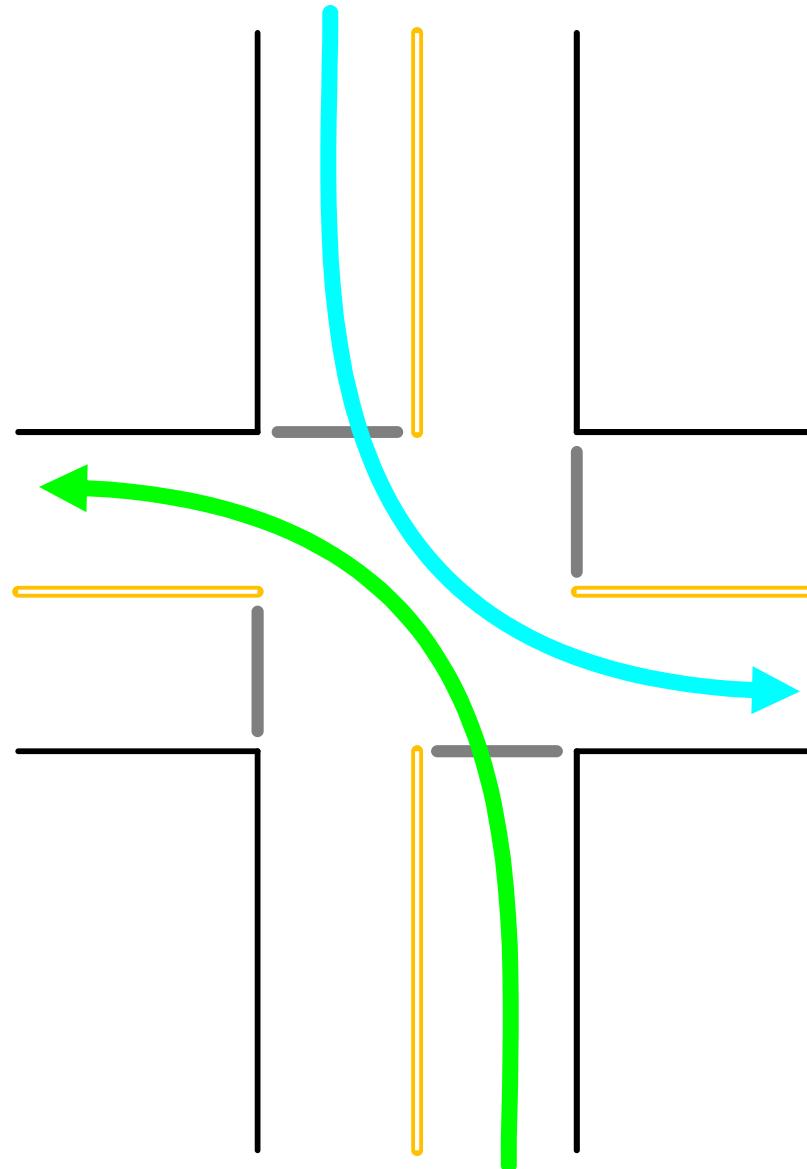
JIM STURDEVANT

DARCY BULLOCK

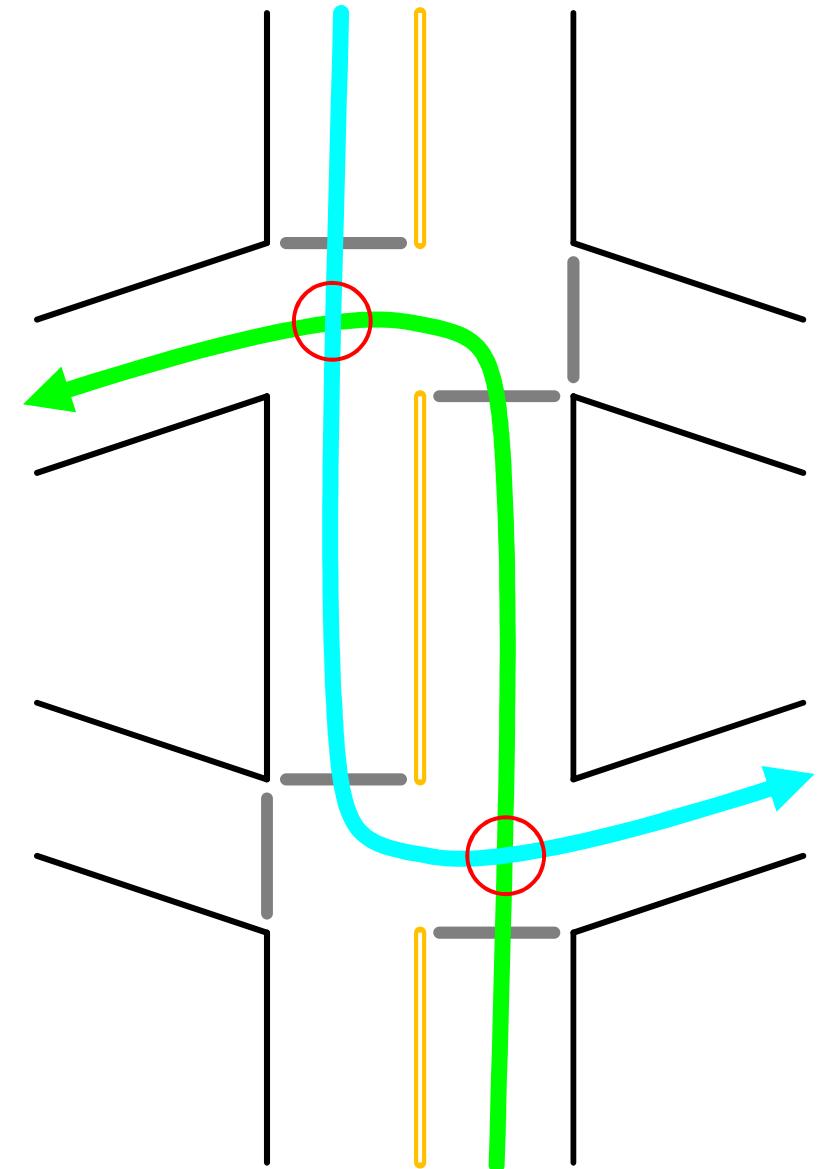
HOWELL LI

Diamond Interchanges

What are they and why do they matter?



Normal Intersection

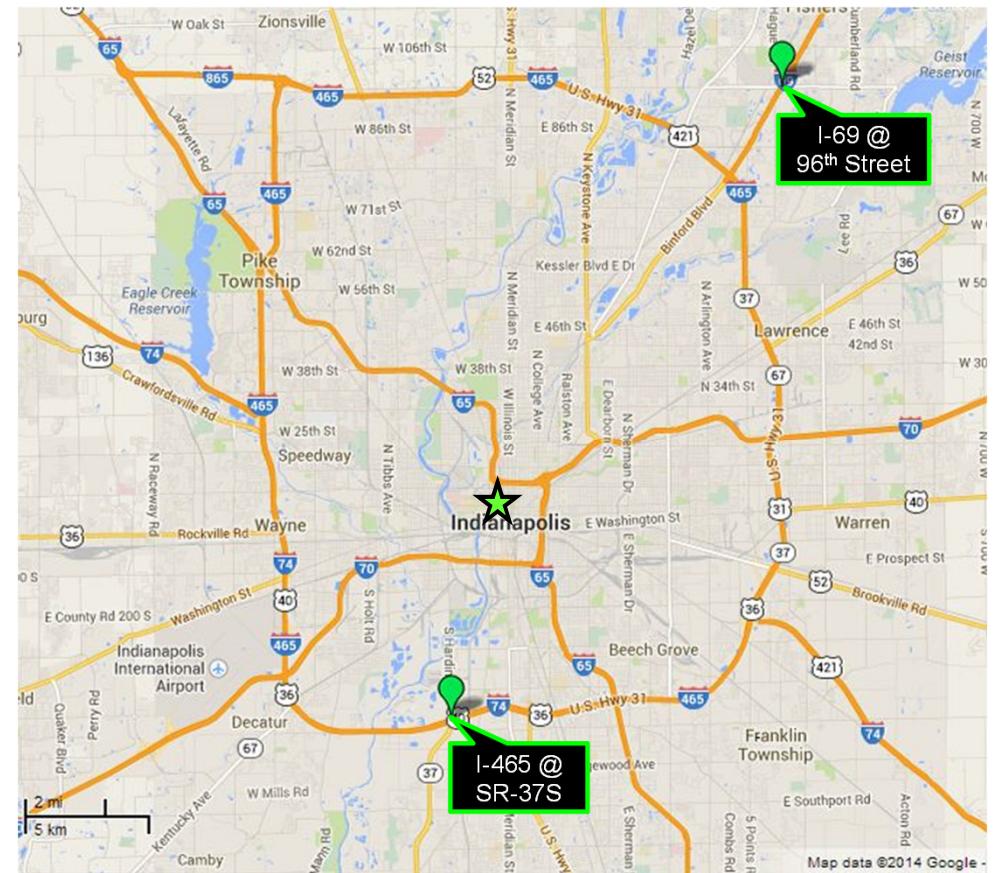
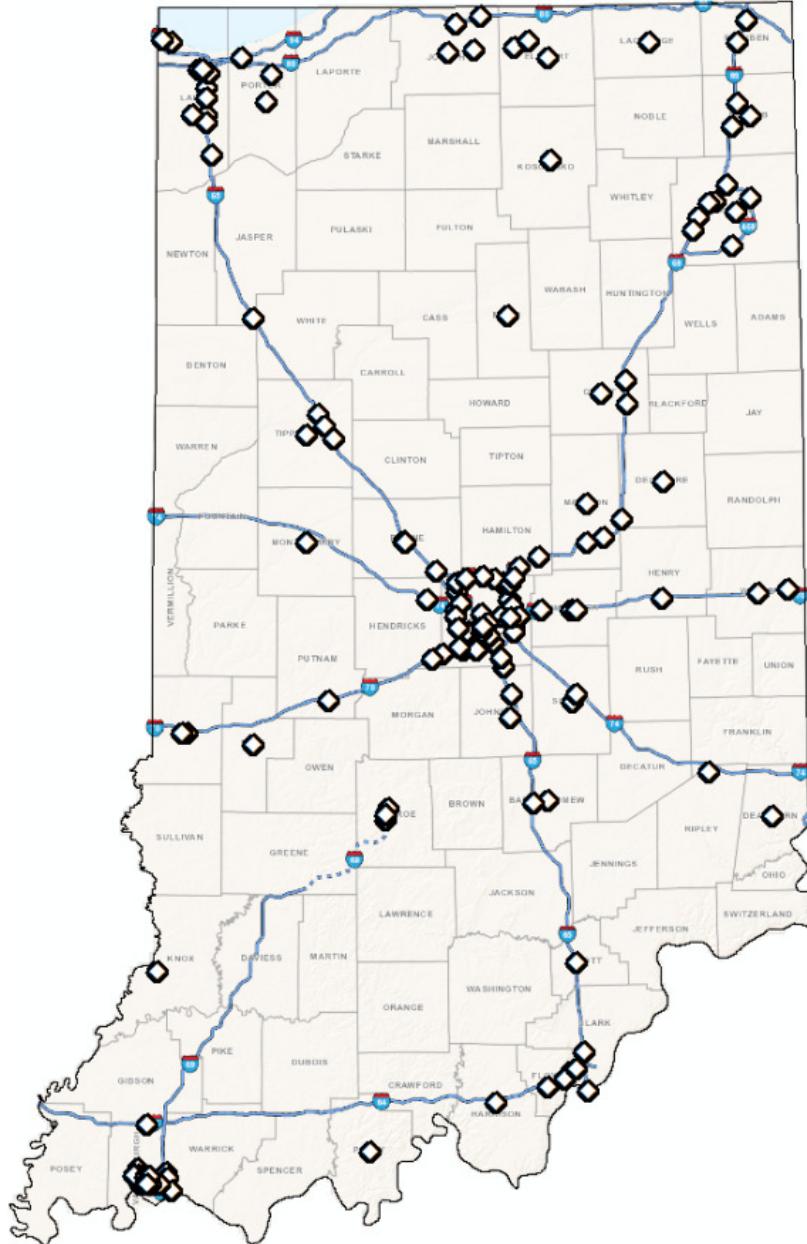


Diamond Interchange

Diamond Interchanges

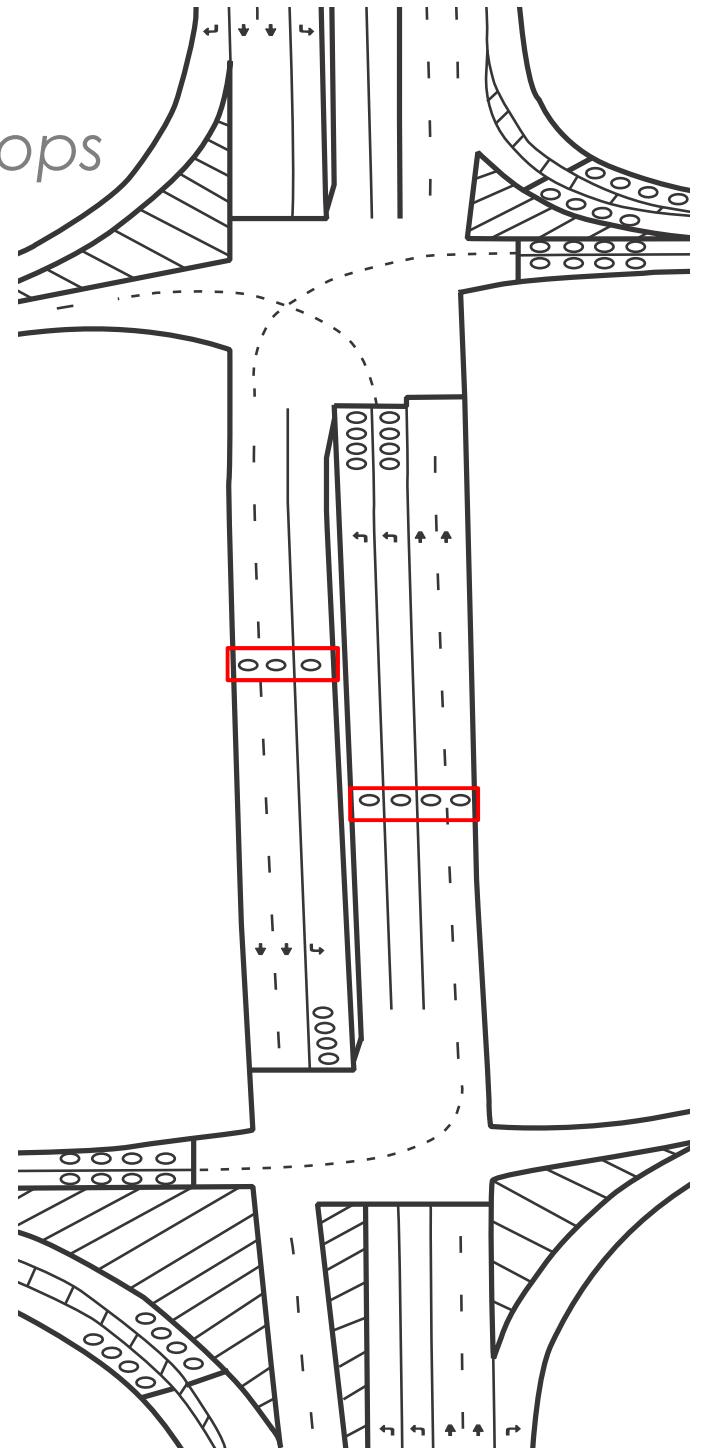
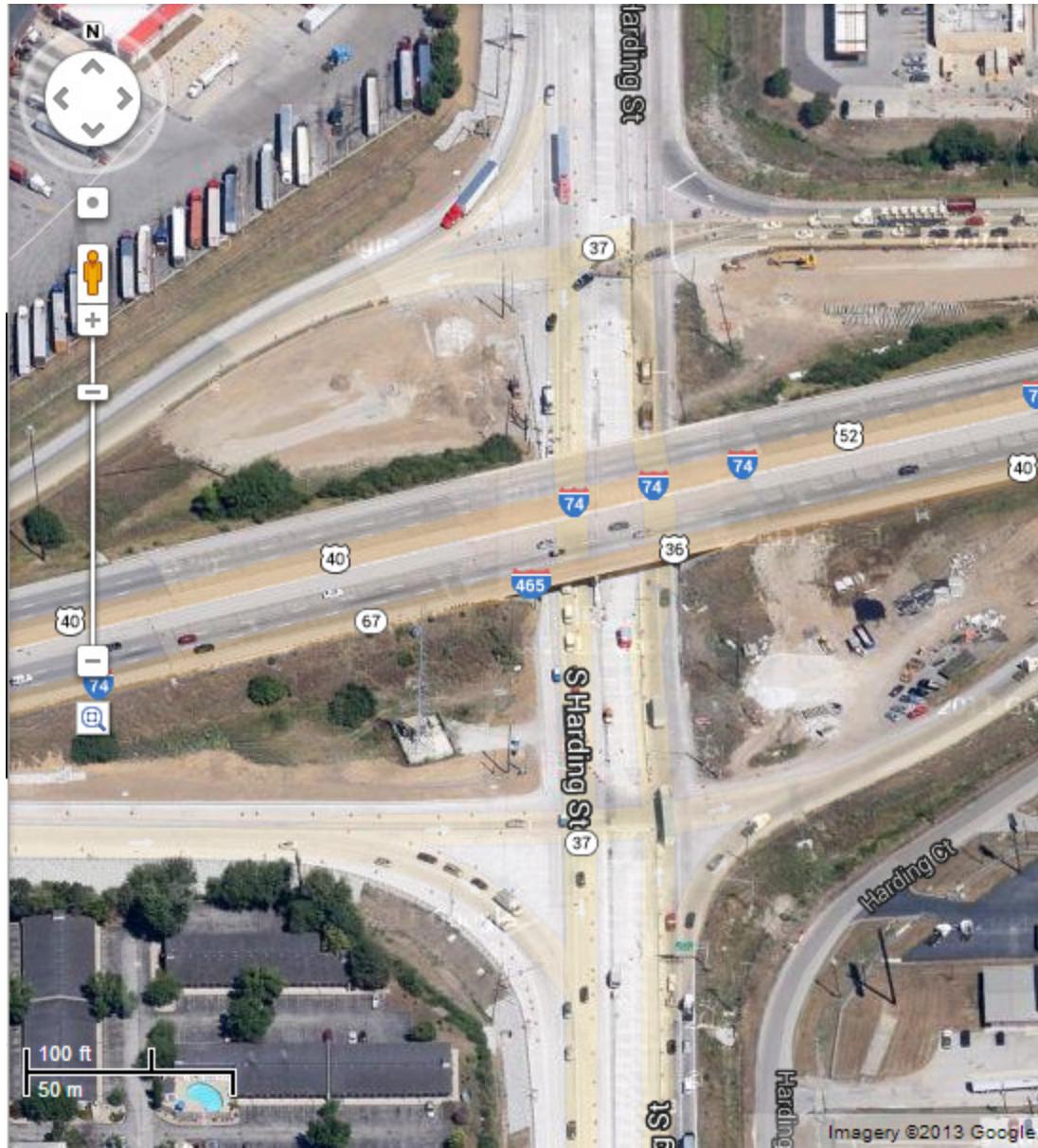
Indiana = 161 Interchanges

Nationally $\geq 10,000$



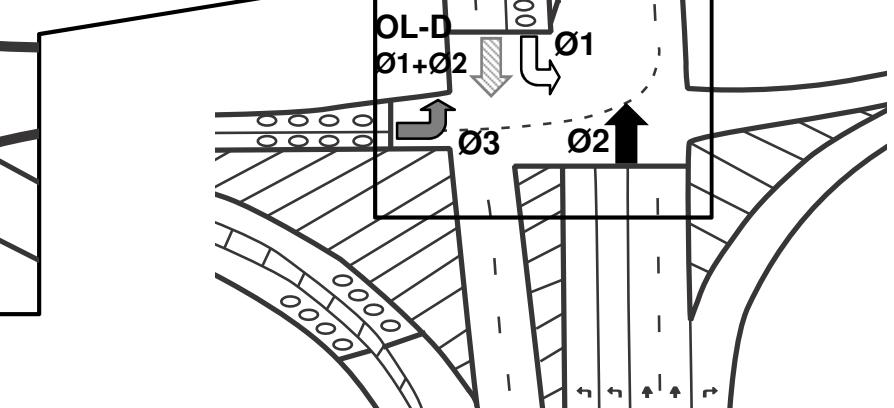
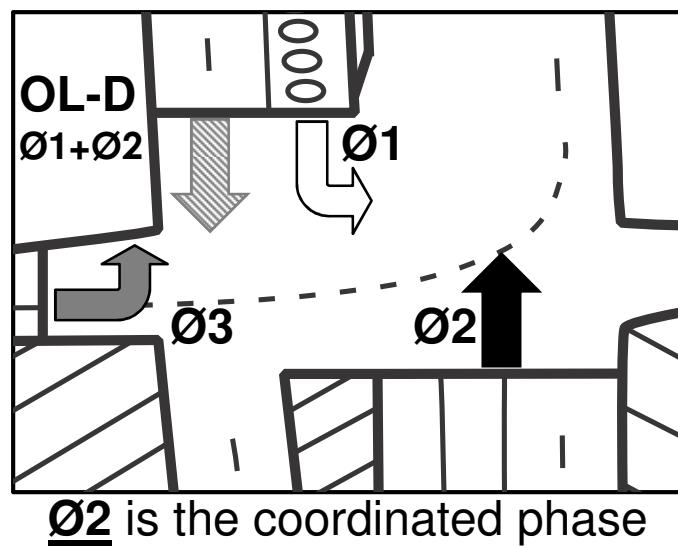
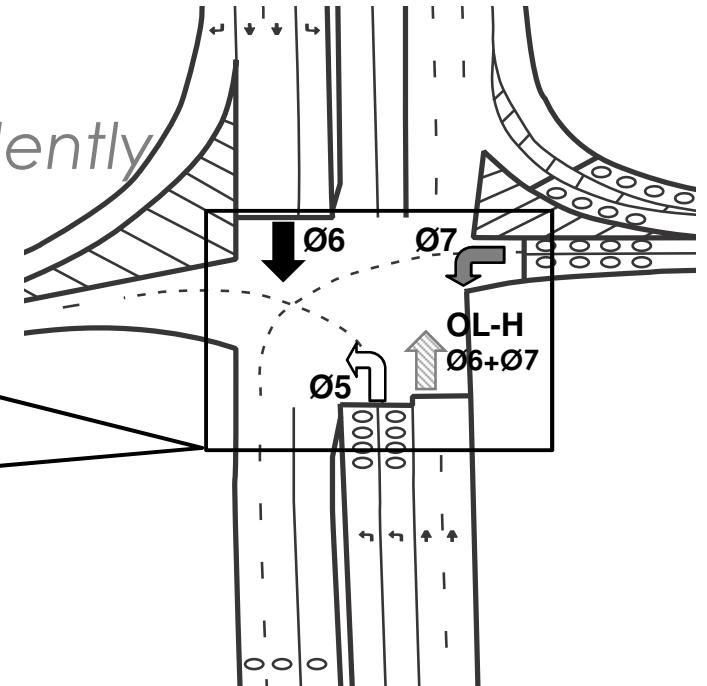
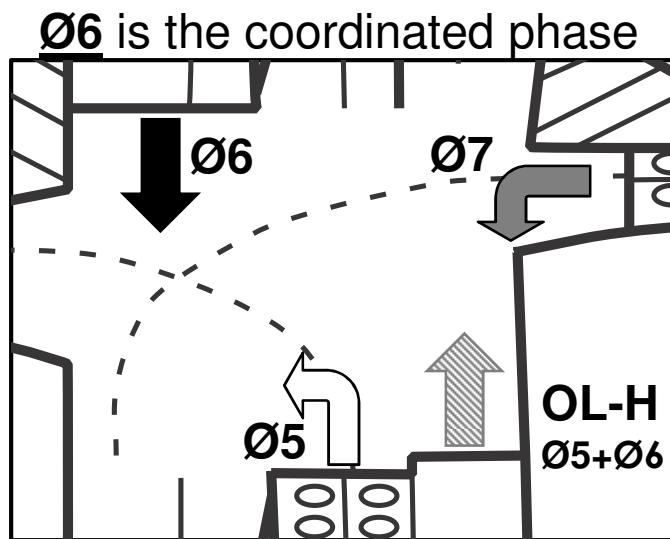
I-465 @ SR-37

Diamond Interchange w/Advanced Loops



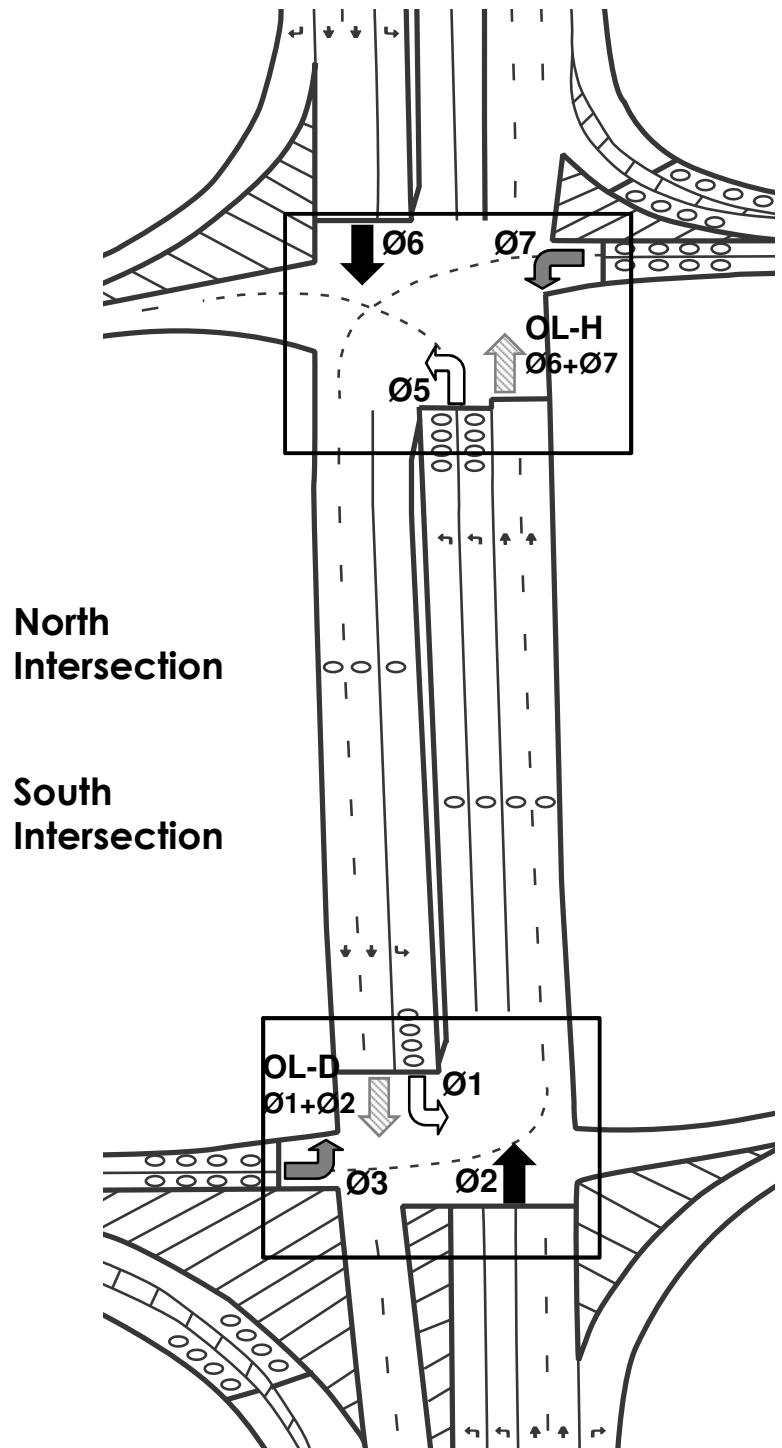
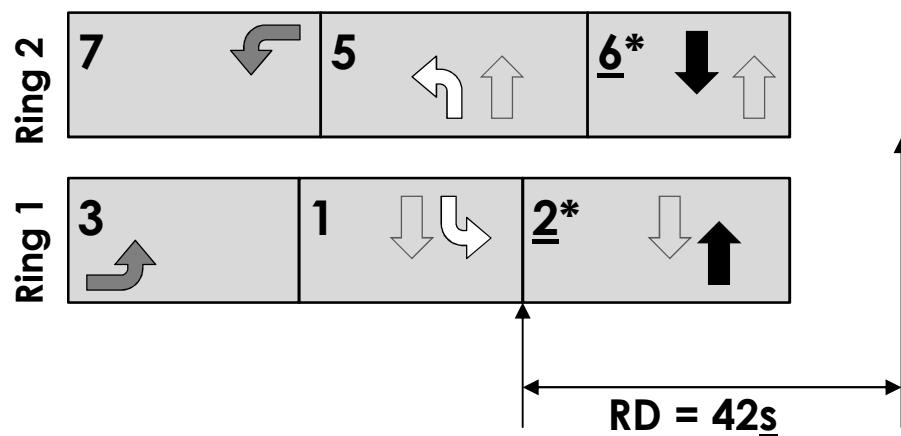
Phasing

Two "T"-Intersections Treated Independently



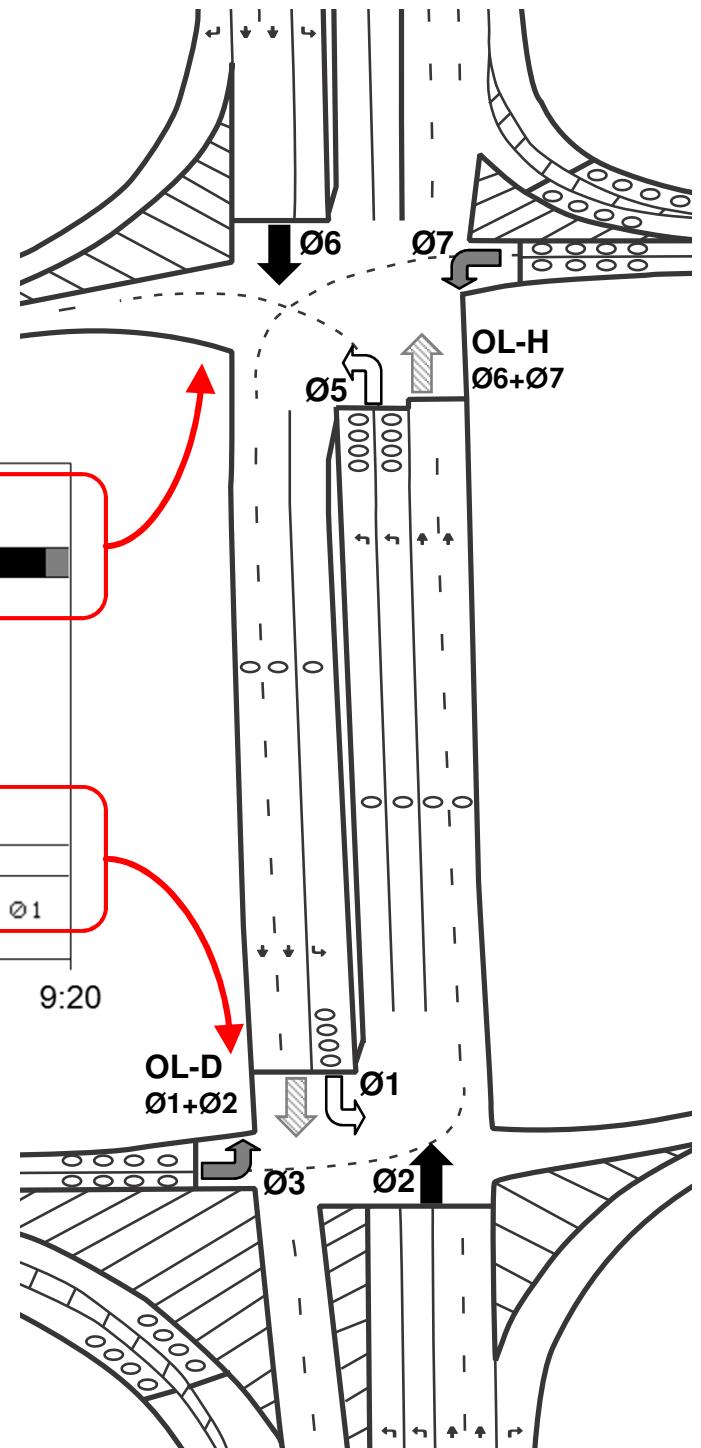
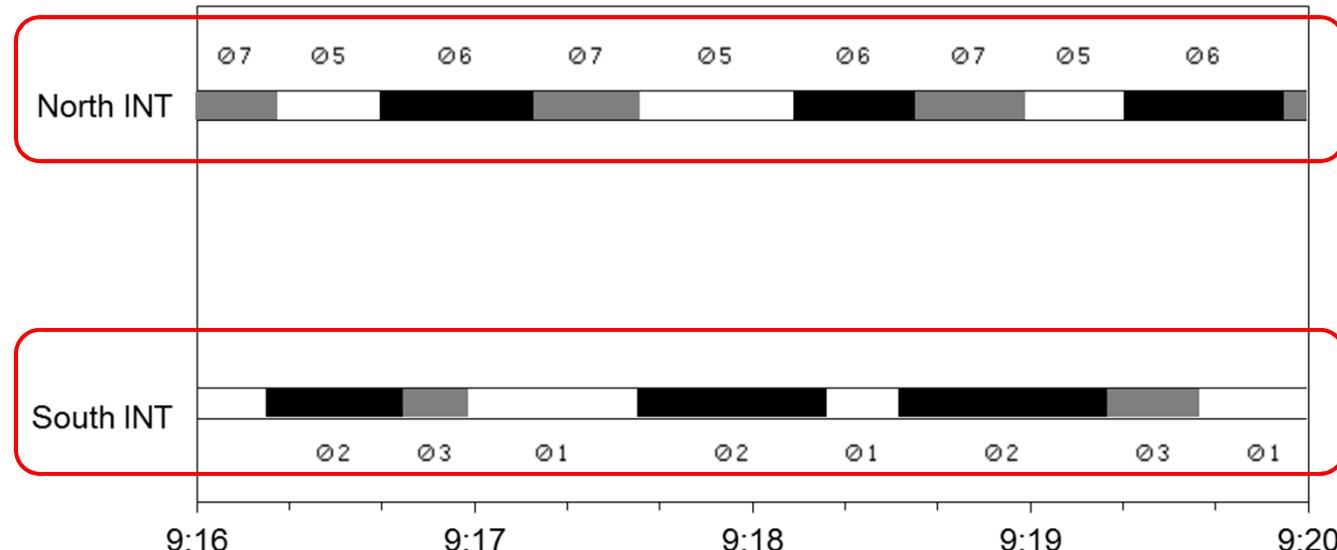
Ring Displacement

Offset Between Coordinated Phases



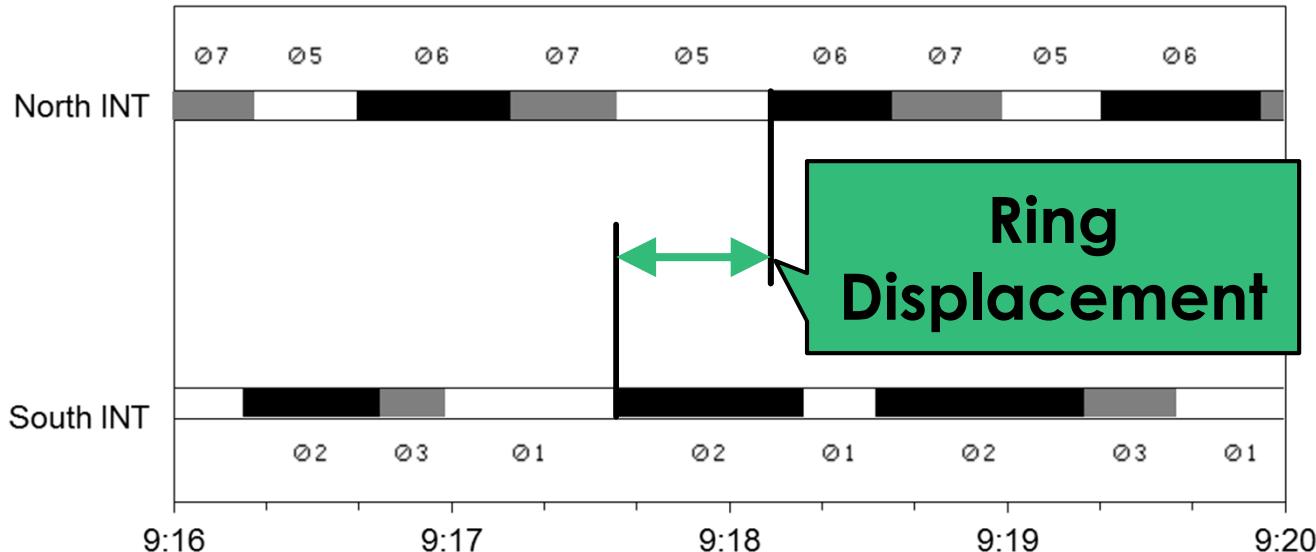
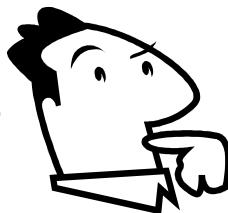
Ring Structure

From the HiRes Data, Plot the Rings



Ring Displacement

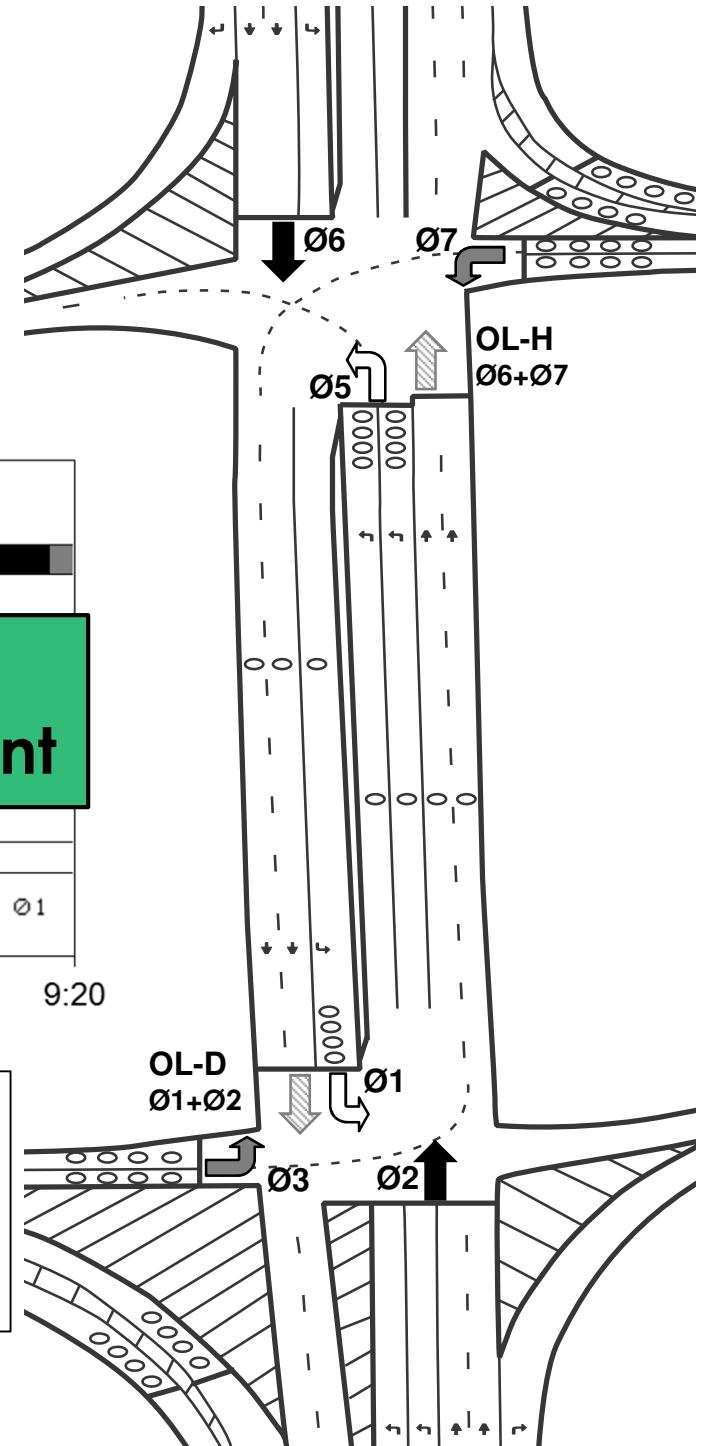
How is this parameter set?



```
COORDINATOR PATTERN [ 1 ] ^v
TS2 (PAT-OFF)... 0-1
CYCLE..... 0s STD (COS).....111
OFFSET VAL..... 0s DWELL/ADD TIME. 0
ACTUATED COORD... NO TIMING PLAN.... ✕
ACT WALK REST... NO SEQUENCE..... ✕
PHASE RESUME.... NO ACTION PLAN.... ✕
MAX SELECT..... NONE FORCE OFF.... NONE
SPLIT PREFERENCE PHASES
PHASE[s] 1 2 3 4 5 6 7 8
SPLT 1J 0 0 0 0 0 0 0 0
PREF 1... 0 0 0 0 0 0 0 0
PREF 2... 0 0 0 0 0 0 0 0
SPLT EXT... 0s. 0s 0s 0s
UEH PERM. 0s 0s 0s DISP
RING DISP - 0s 0s 0s (RING 2-4)
```

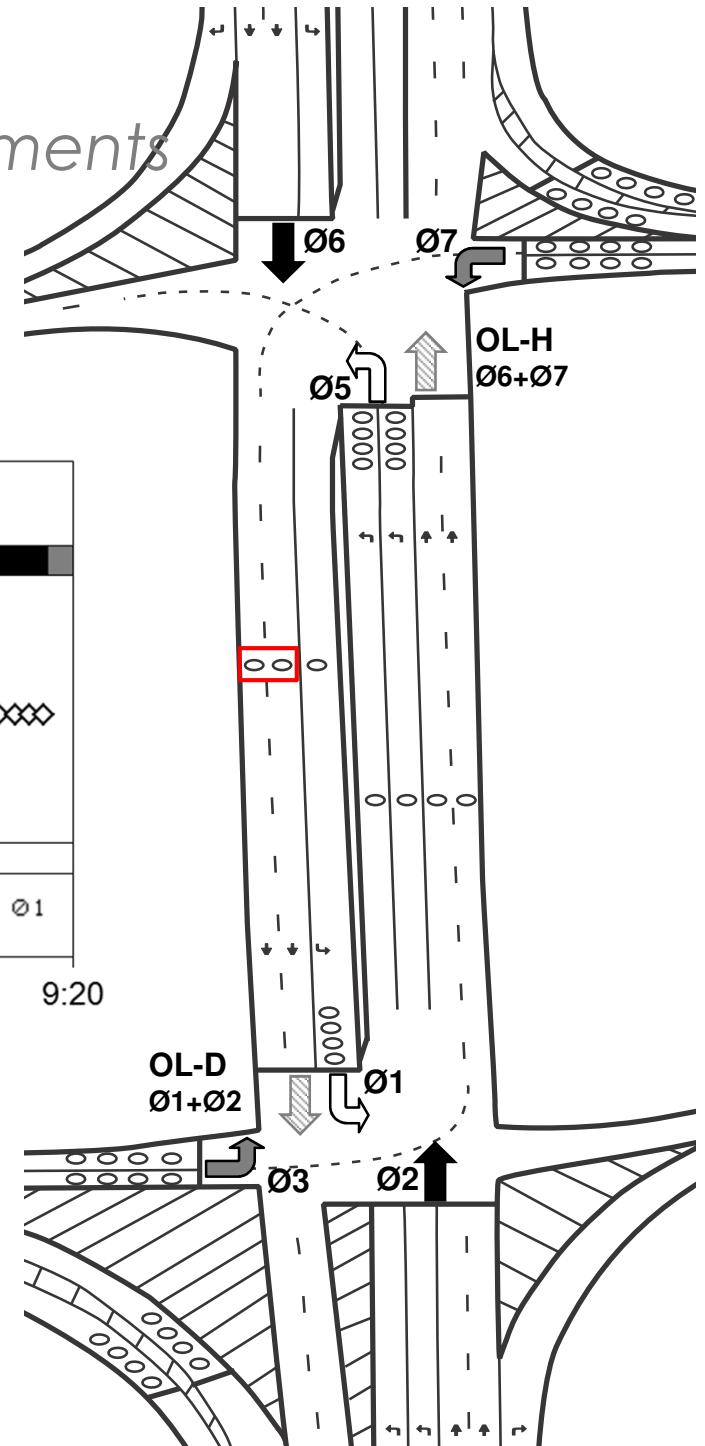
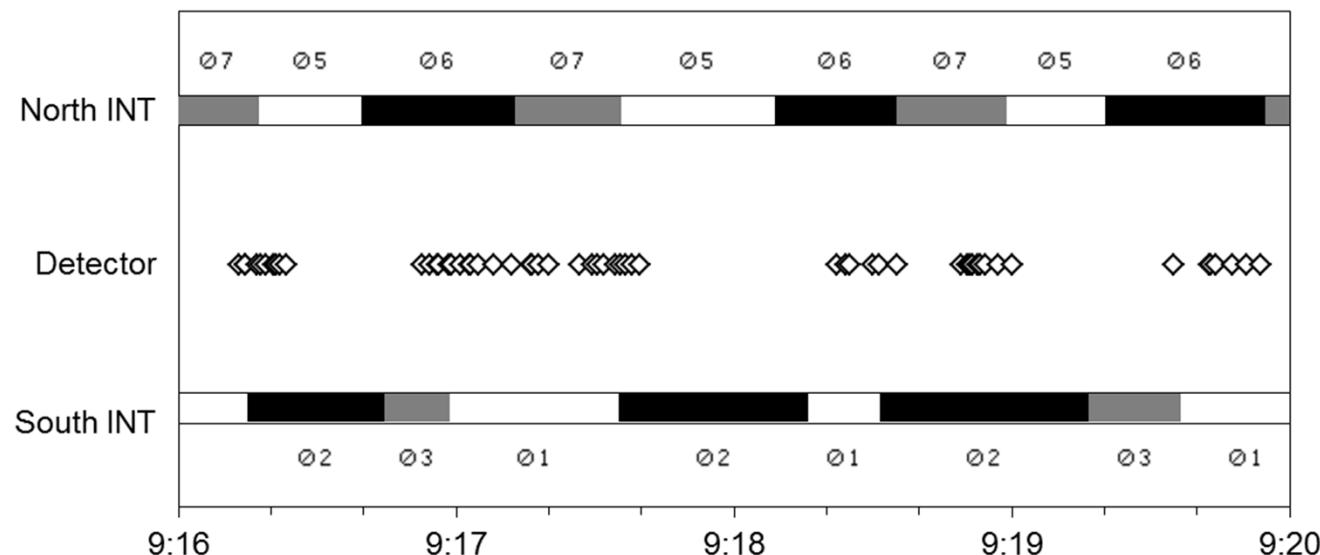
DIAL 1 SPLIT 1 PARAMETERS						
OFFSET	TIME	ALT	PATN	R2	R3	R4
#	SEC	SEQ	MODE	LAG	LAG	LAG
1	0	0	0			
2	0	0	0			
3	0	0	0			

MODE (0-6): NRM/PRM/YLD/PYL/POM/SOM/FAC
A-UP B-DN C-LT D-RT E-ENTER F-PRIOR MENU



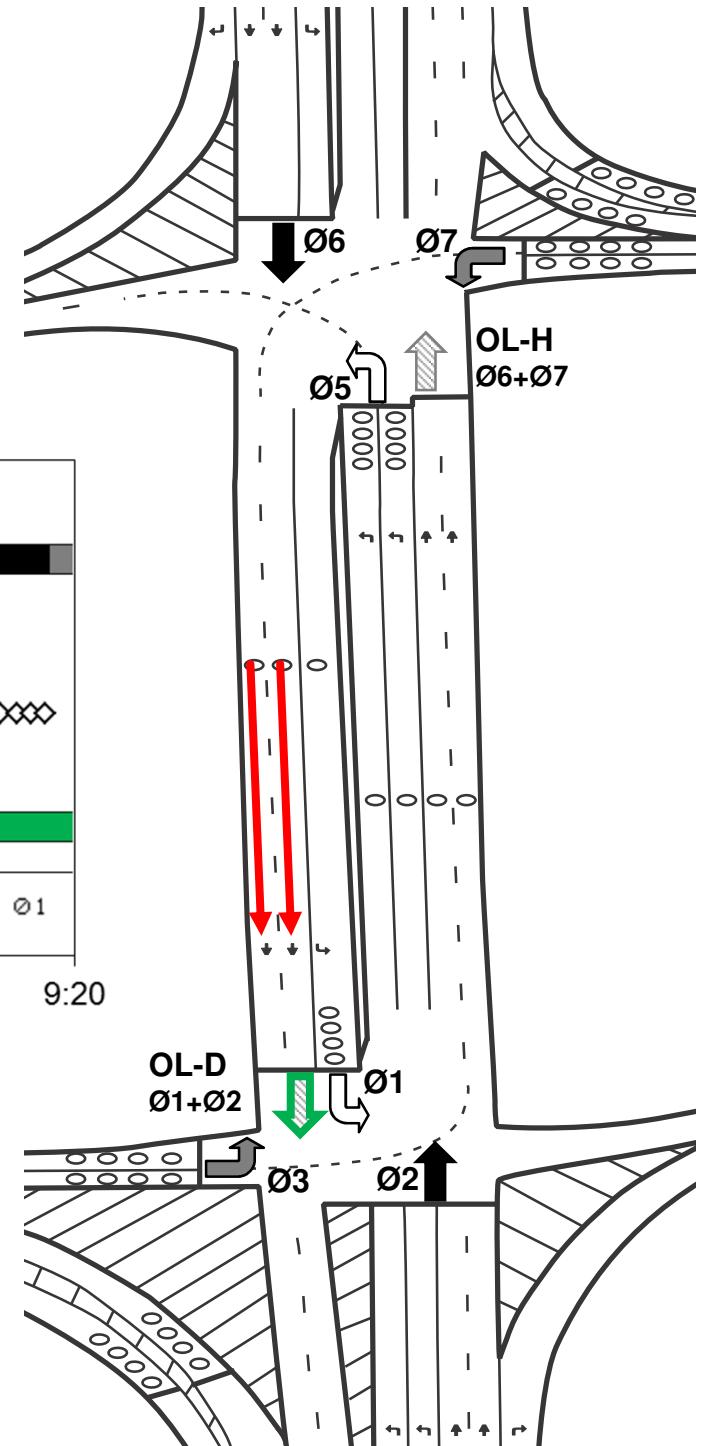
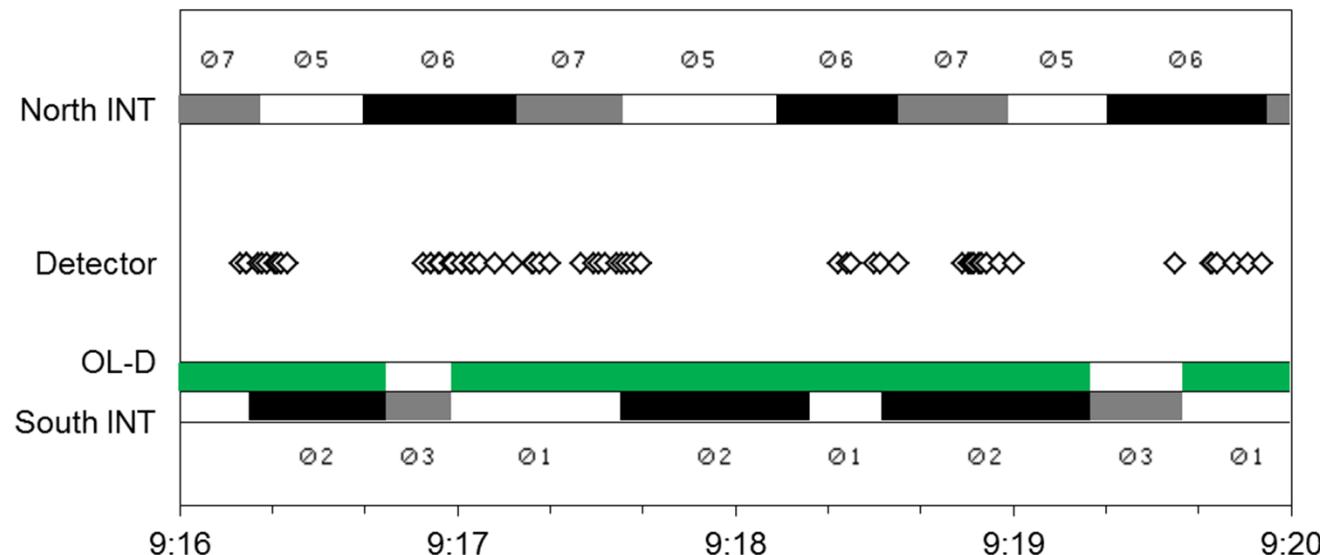
SB Thru Detectors

Consider one of the four internal movements



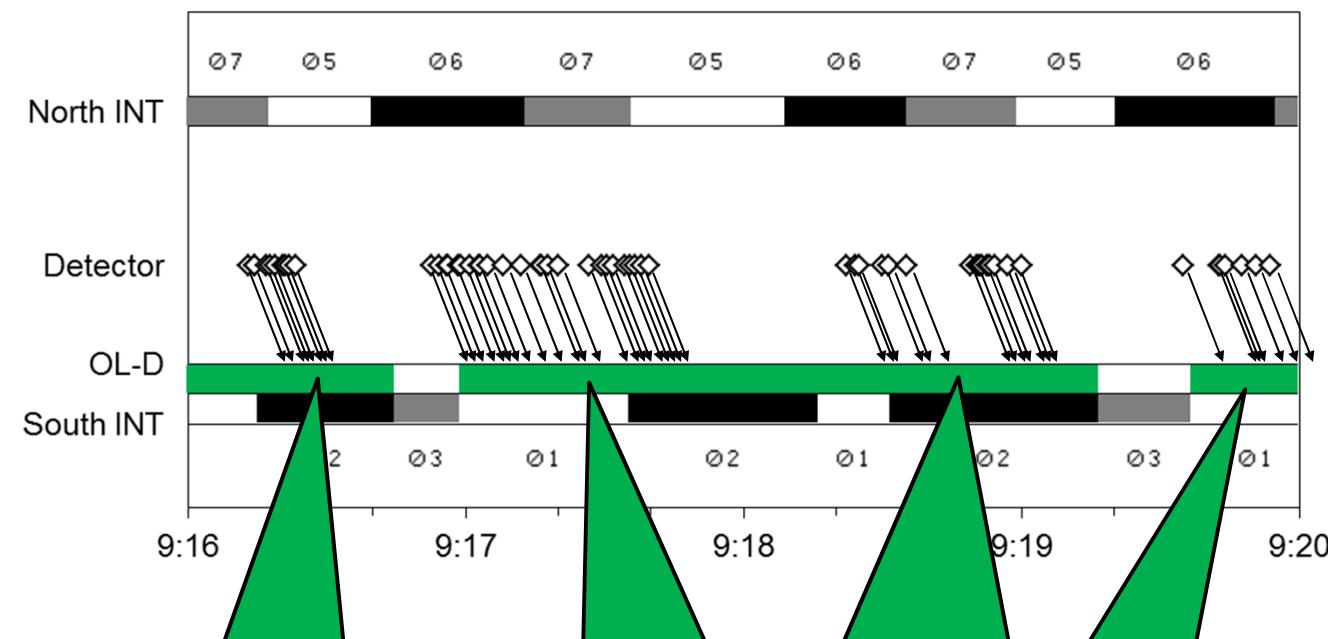
Arrival on Green?

Plot the green status of the overlap

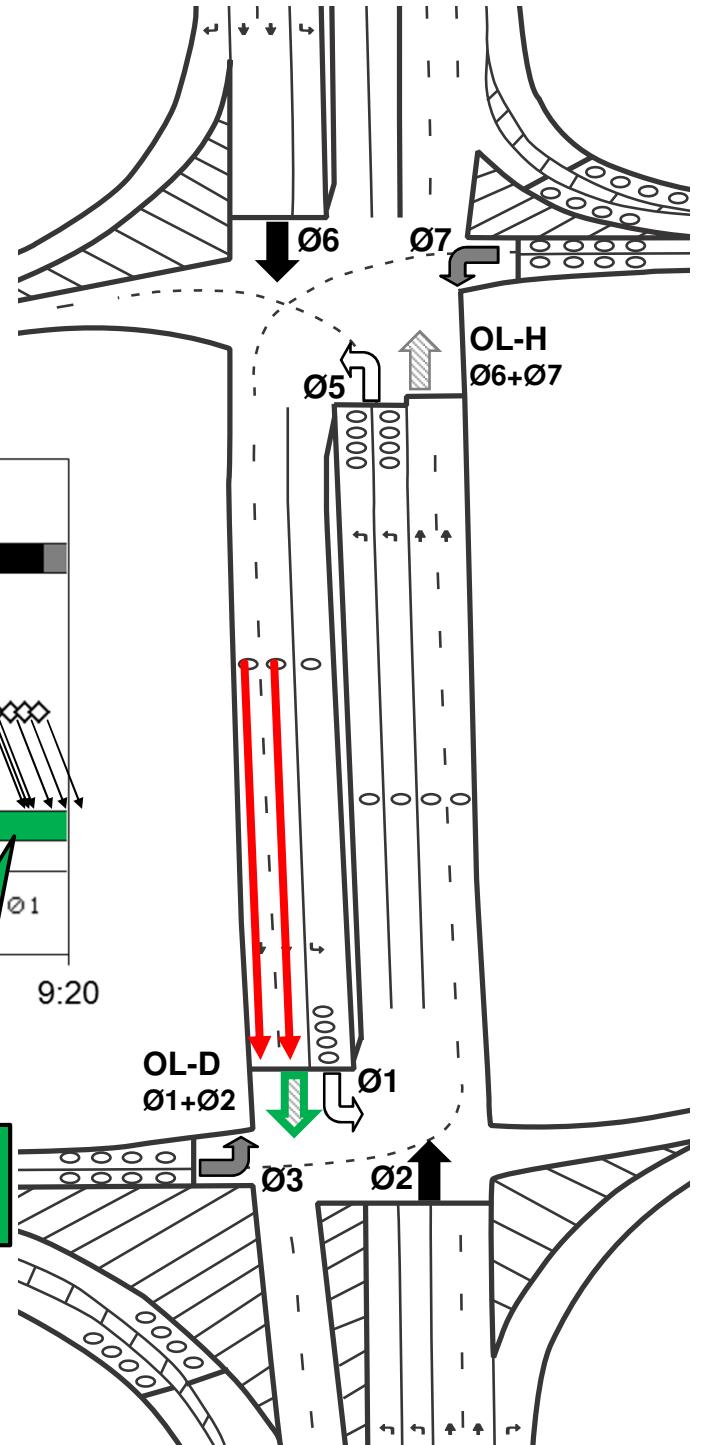


Project the Detector Data

295' upstream \approx 5 seconds @ 40 MPH

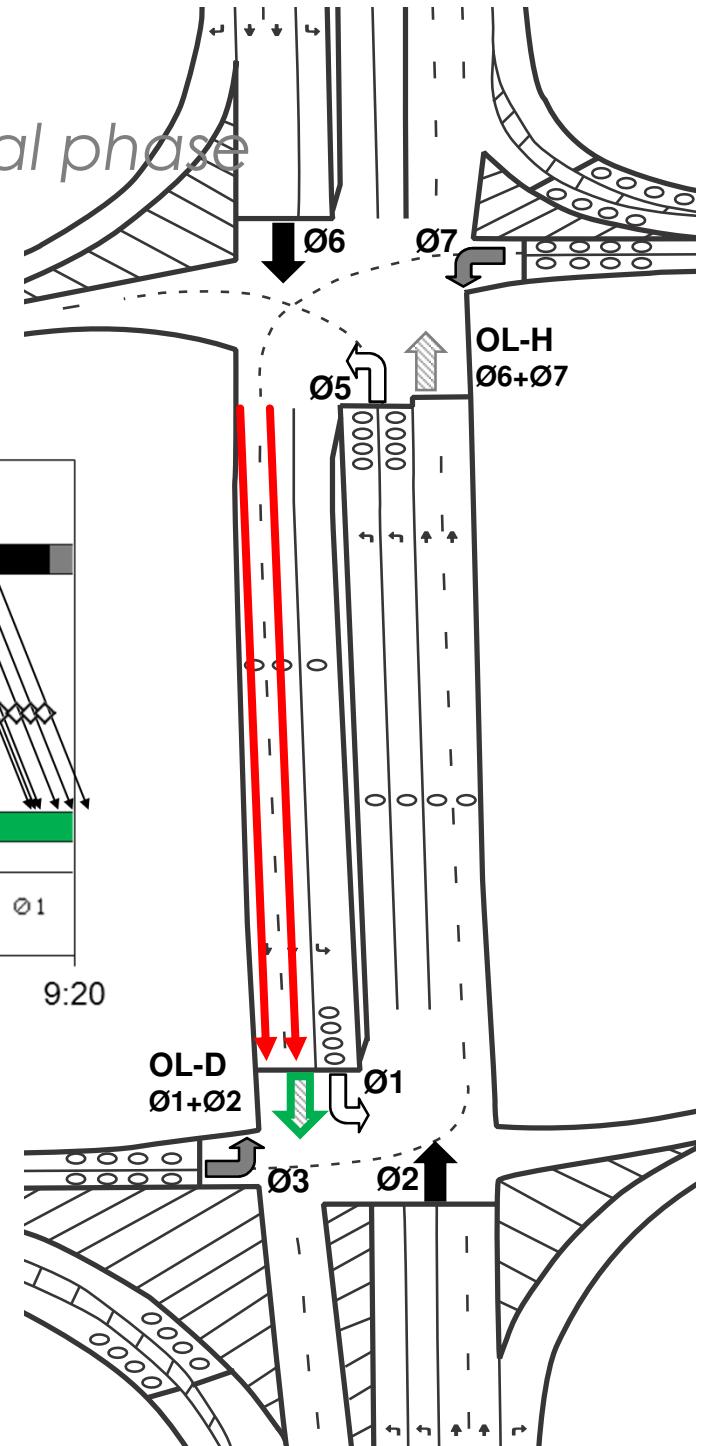
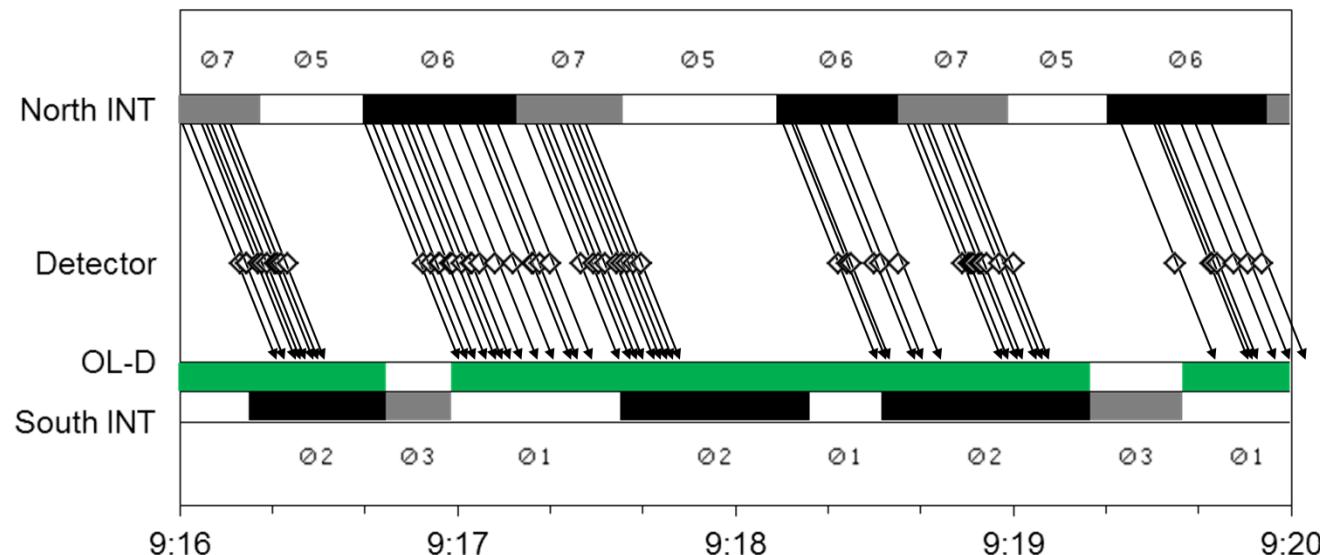


The engineer who set the ring displacement did a fantastic job at arrivals on green for this movement!



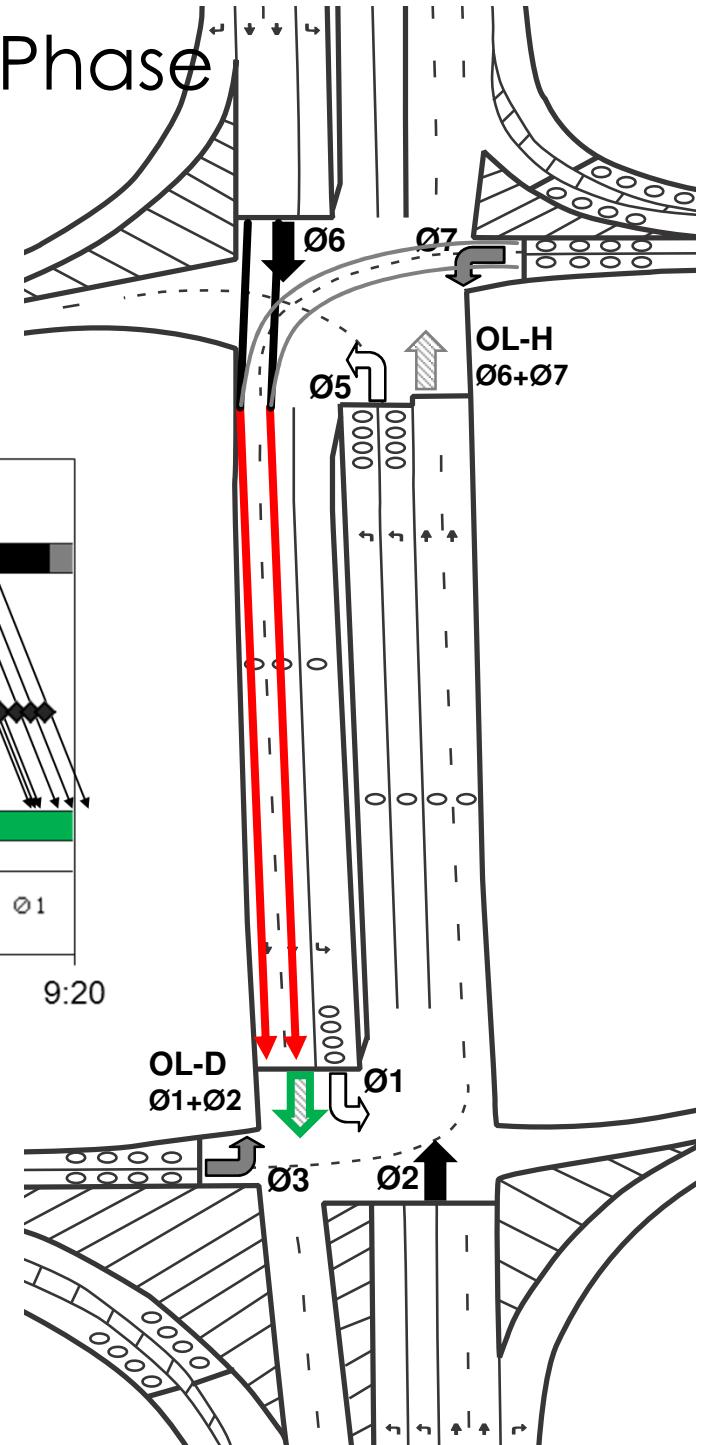
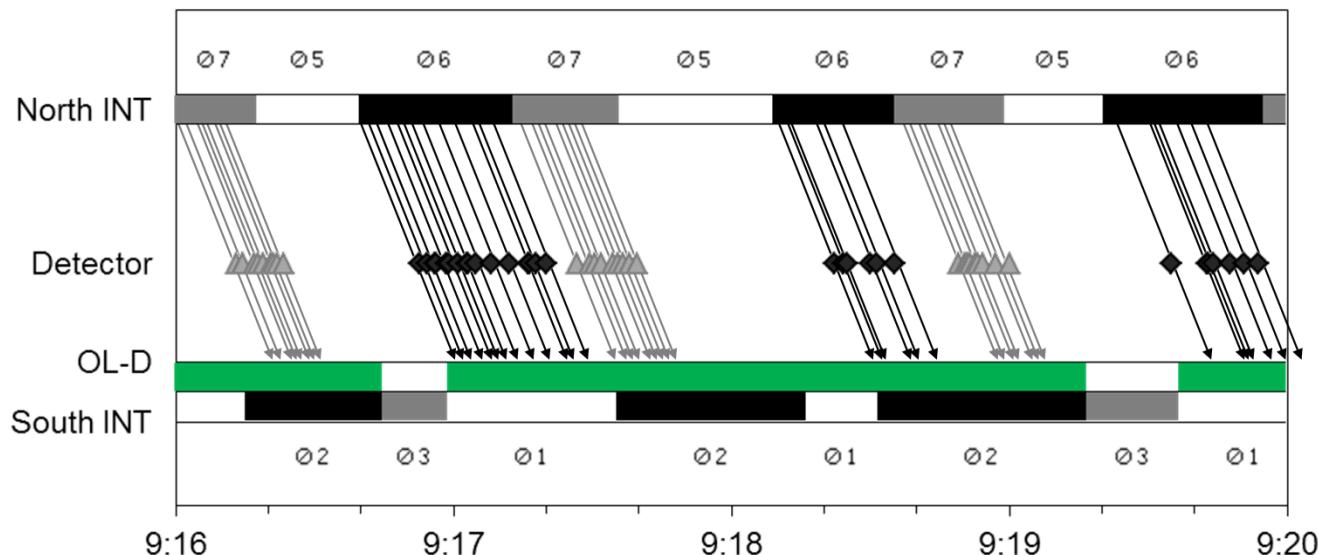
Upstream Source Phase?

Look upstream ~10 seconds at the signal phase

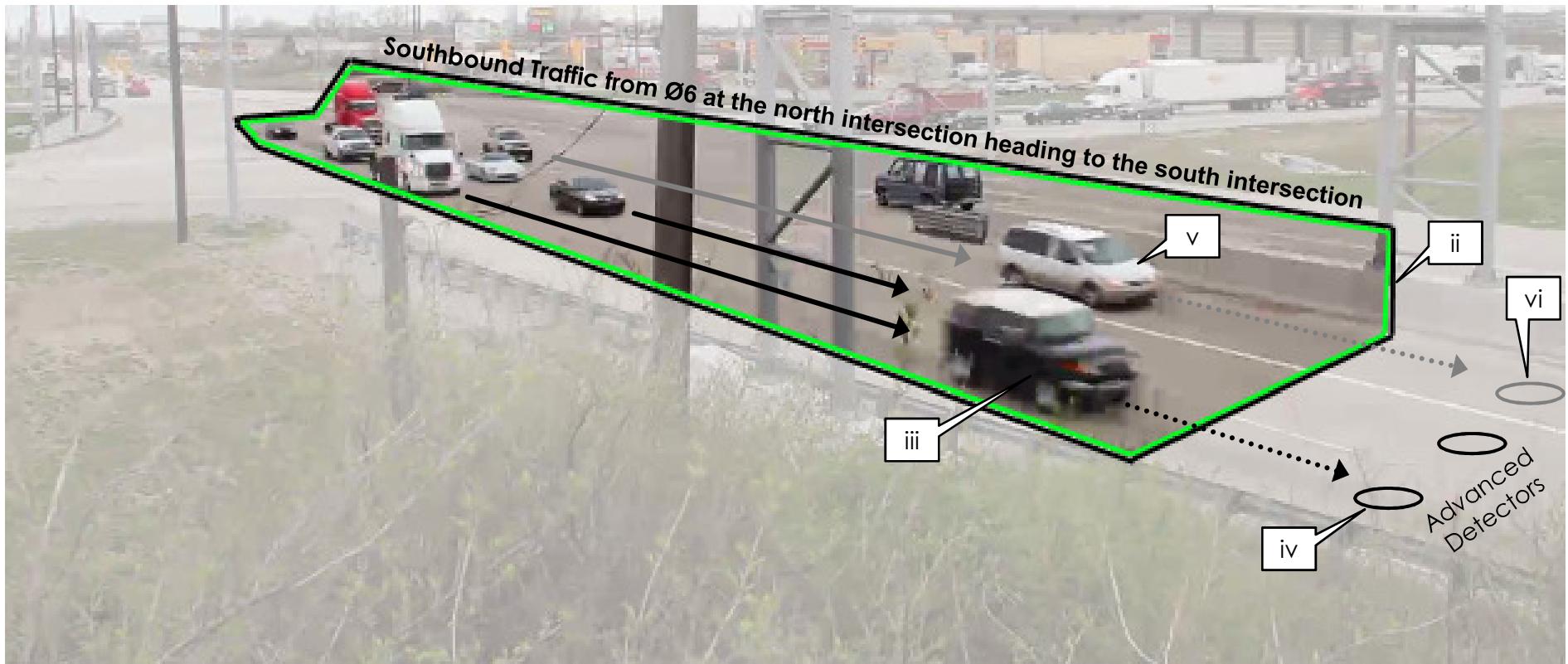
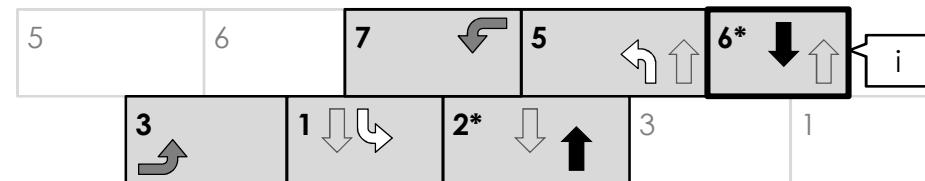
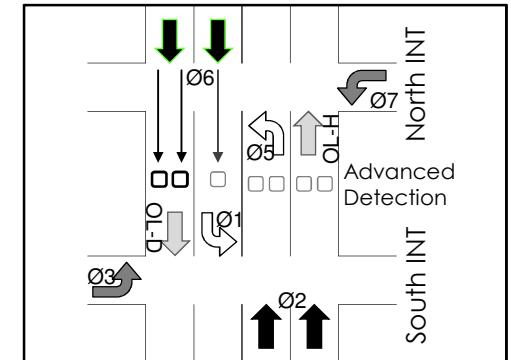
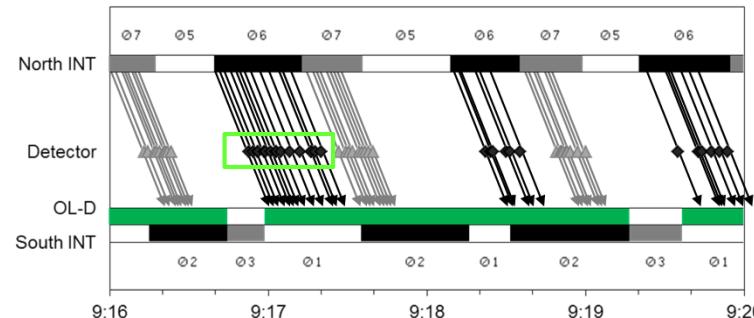


Now Platoons are Attributed to a Phase

The vehicles' sources are known

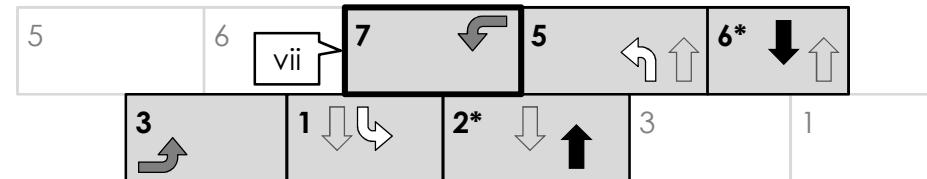
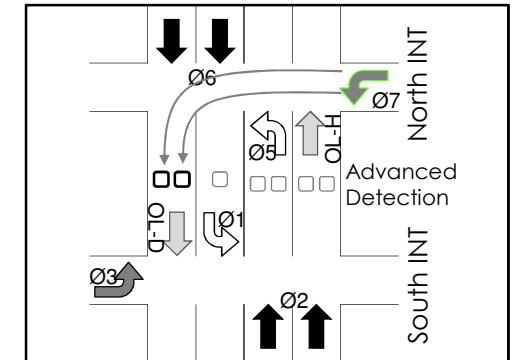
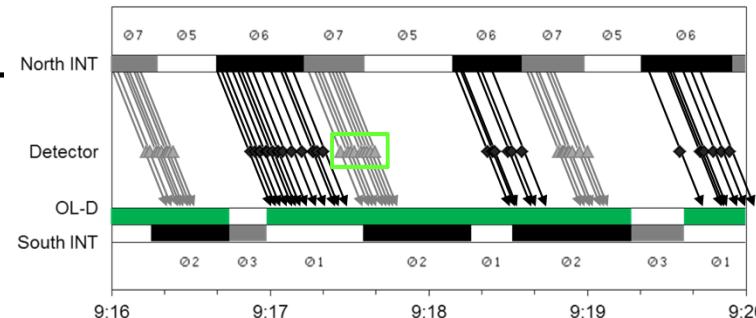


Traffic from SBT Vehicles from Ø6

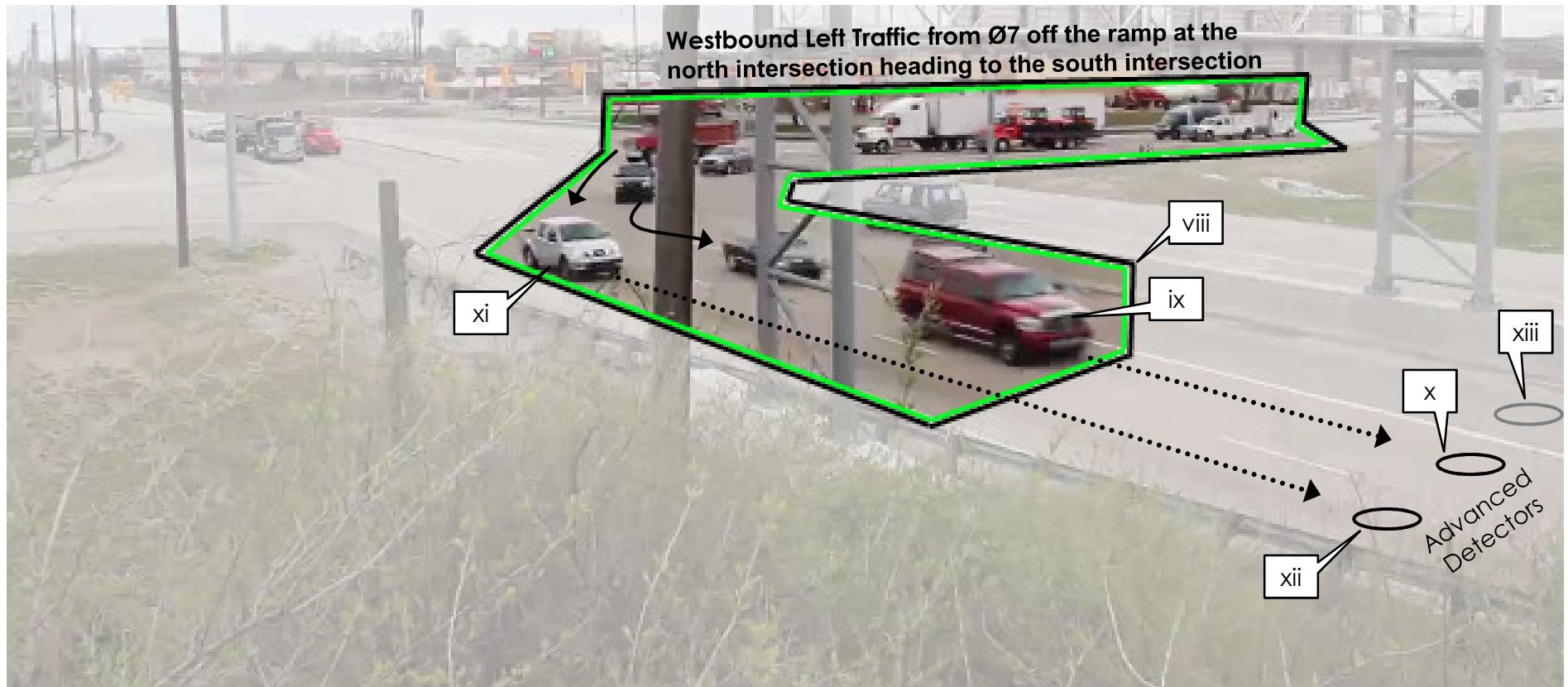


Traffic from WBL

Vehicles from Ø7

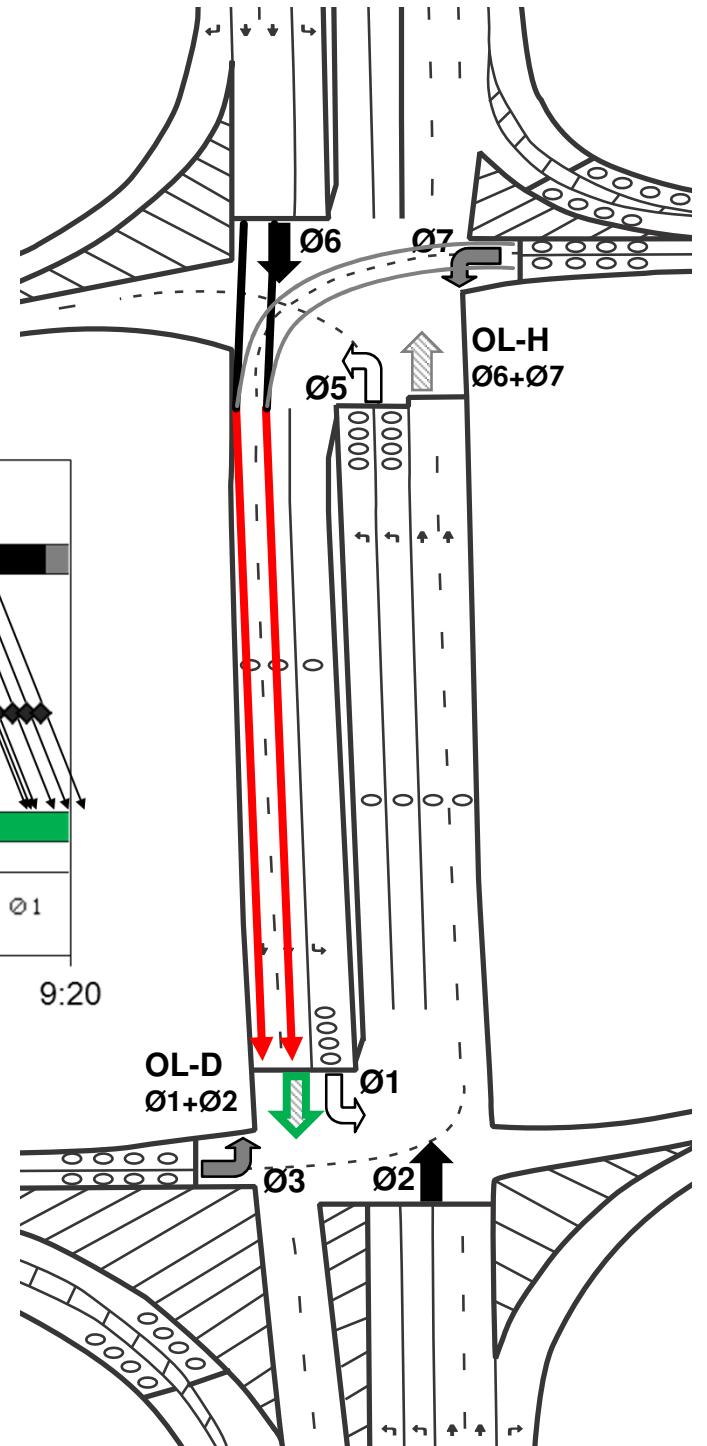
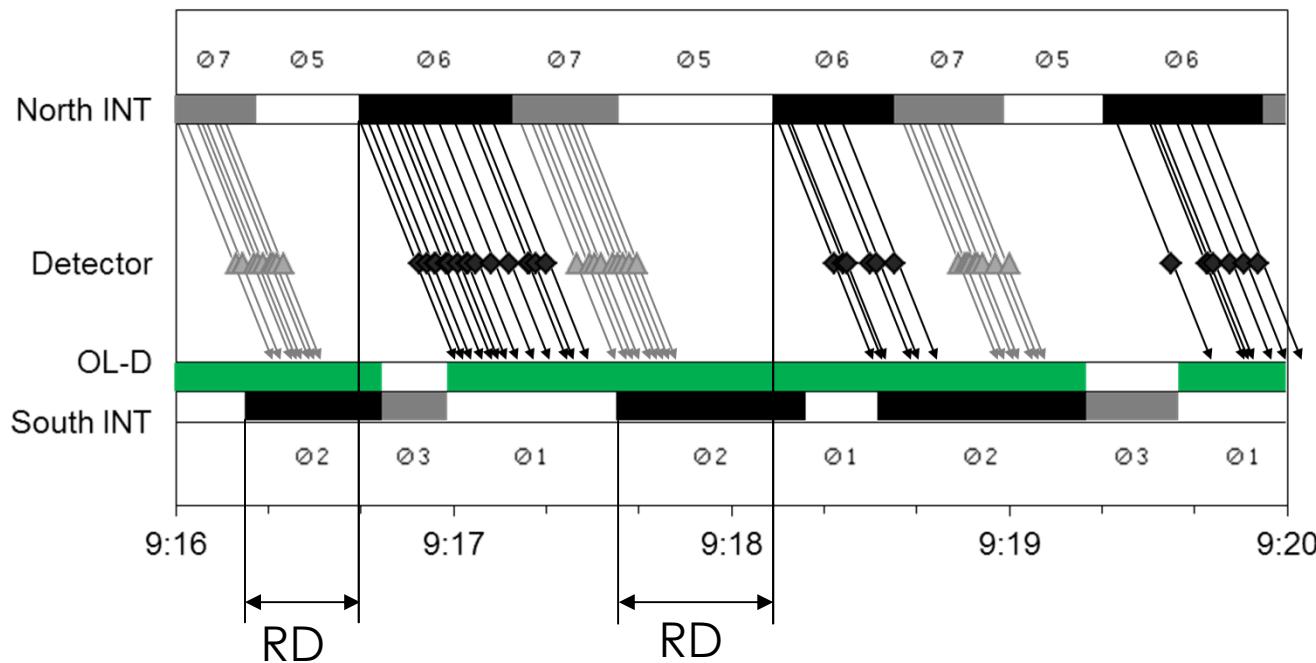


Westbound Left Traffic from Ø7 off the ramp at the north intersection heading to the south intersection



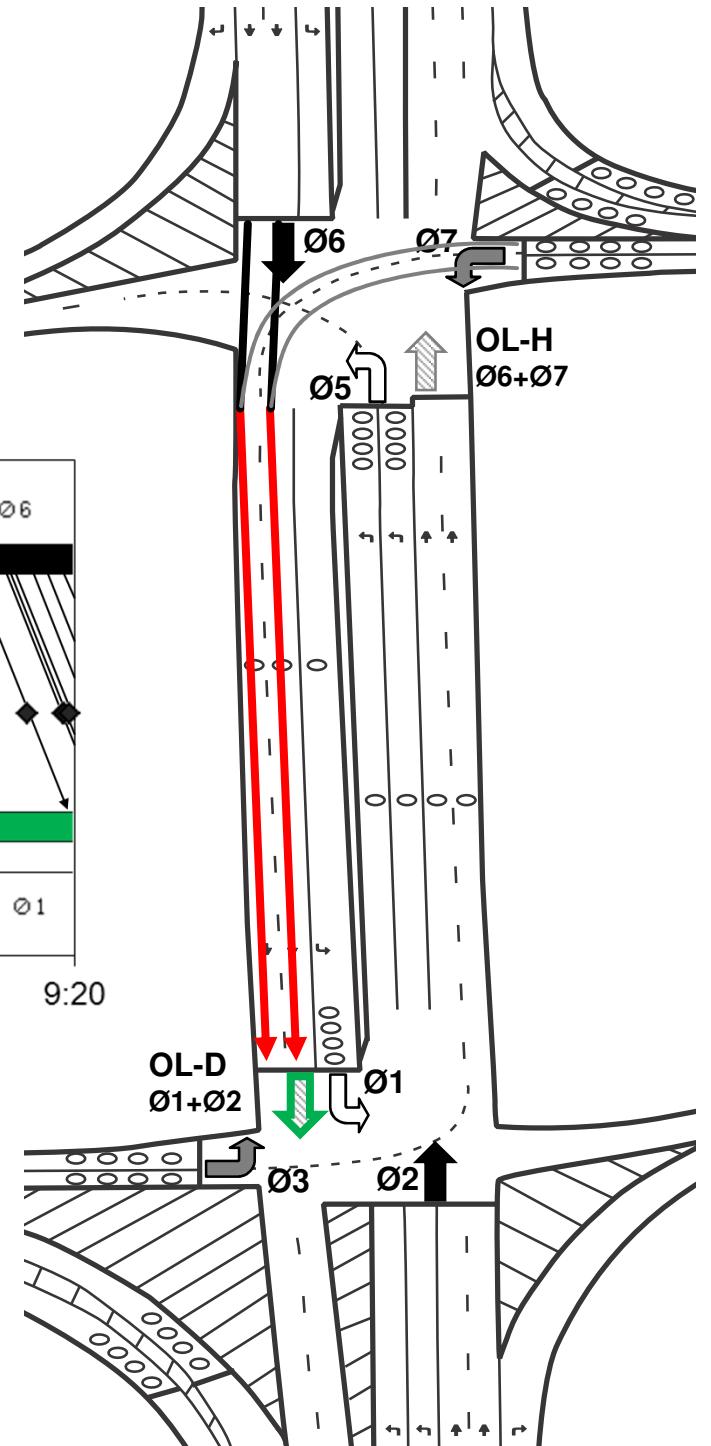
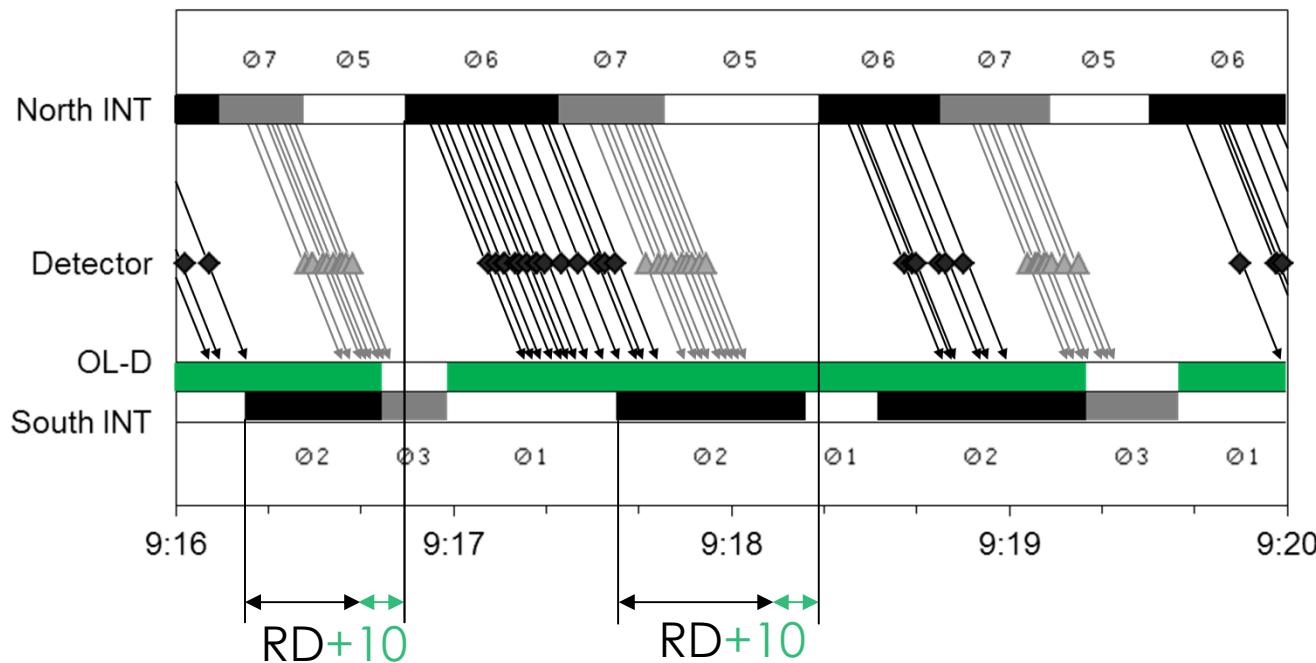
Adjusting the ring displacement

What effect would it have?



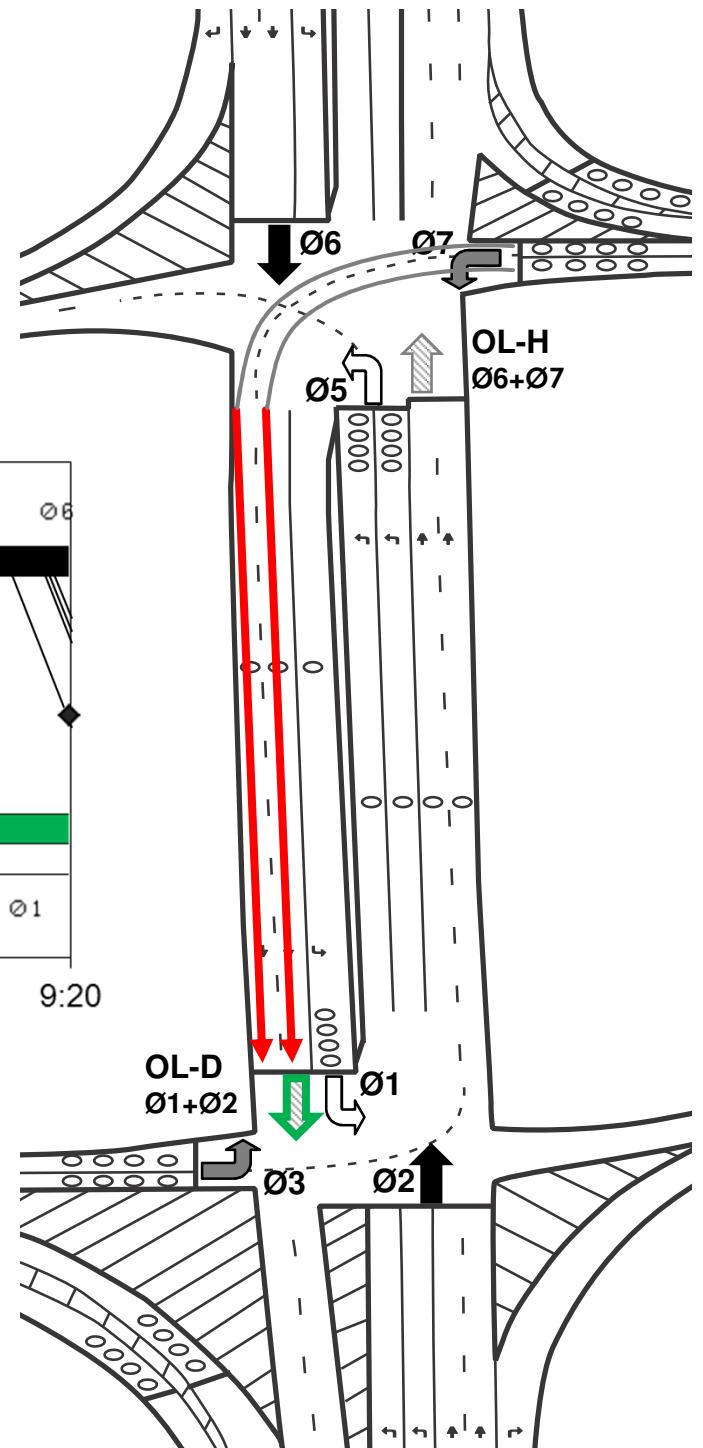
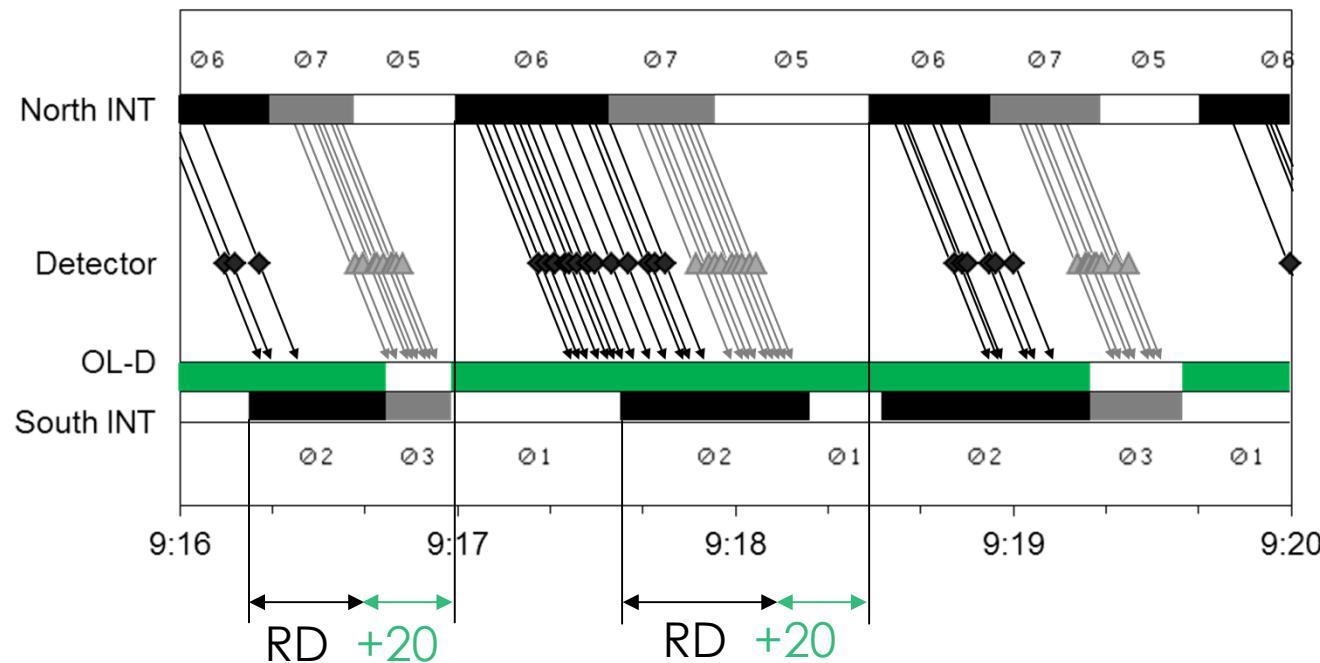
Ring Displacement +10 Seconds

What effect would it have?



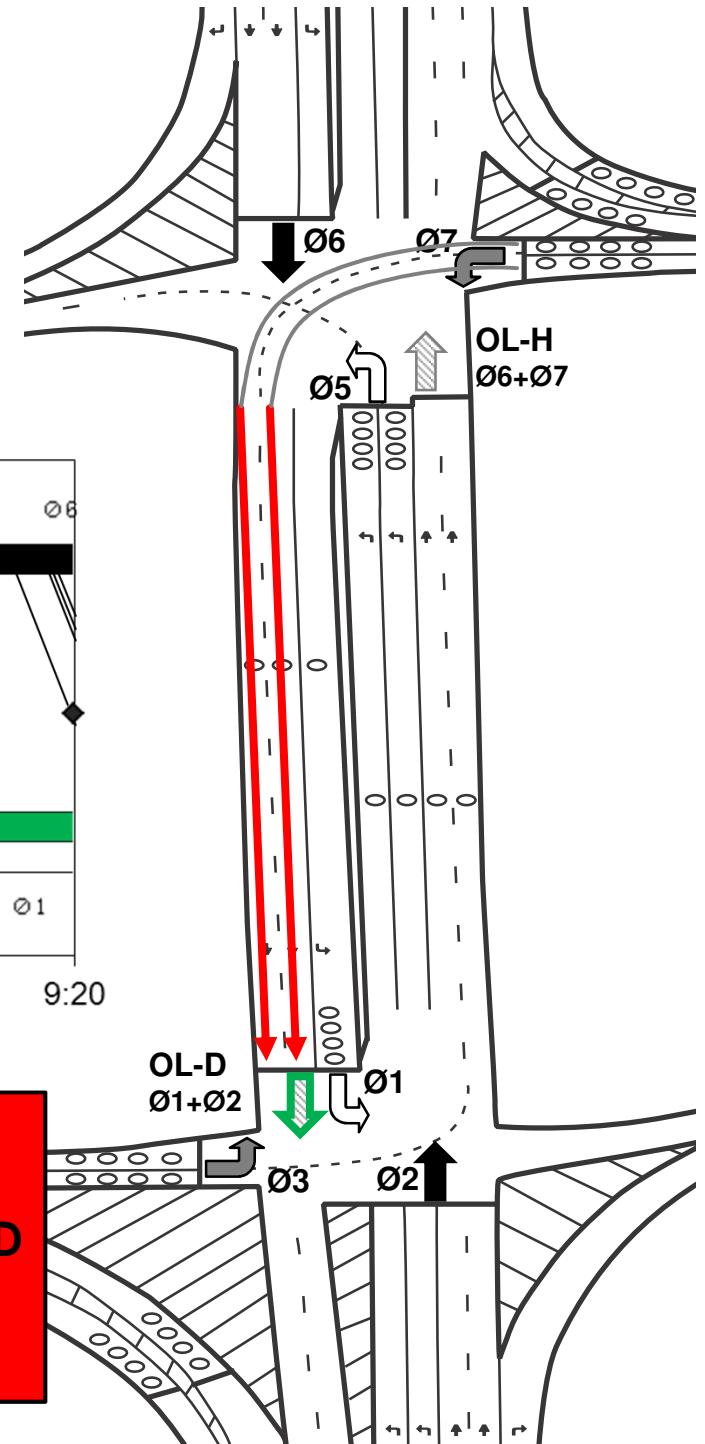
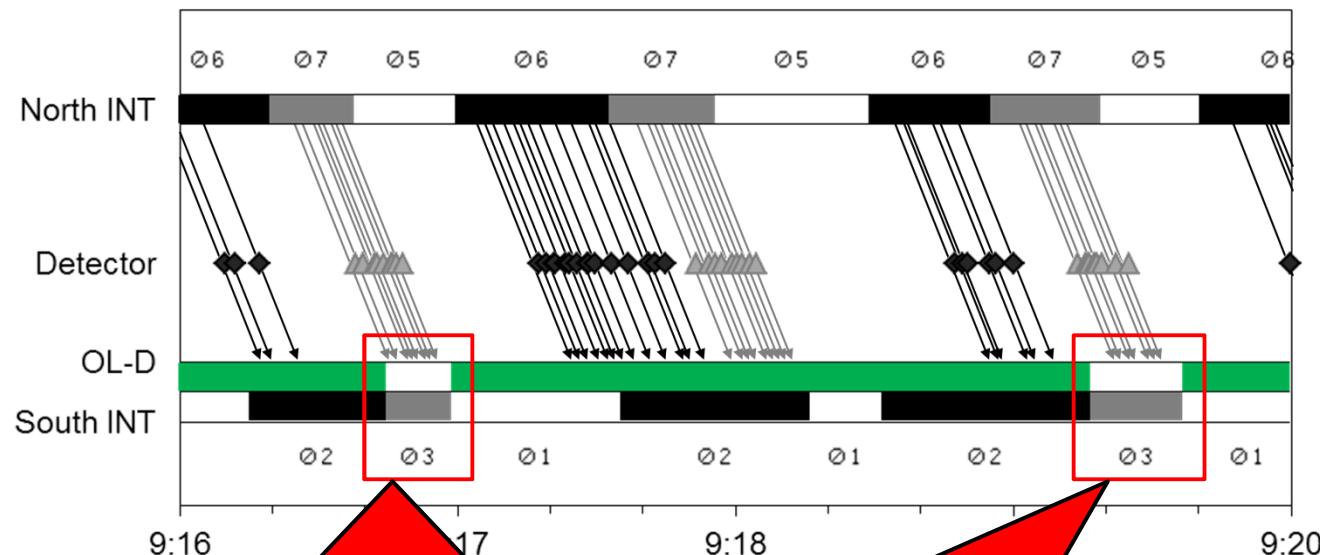
Ring Displacement +20 Seconds

Vehicles from upstream arrive later



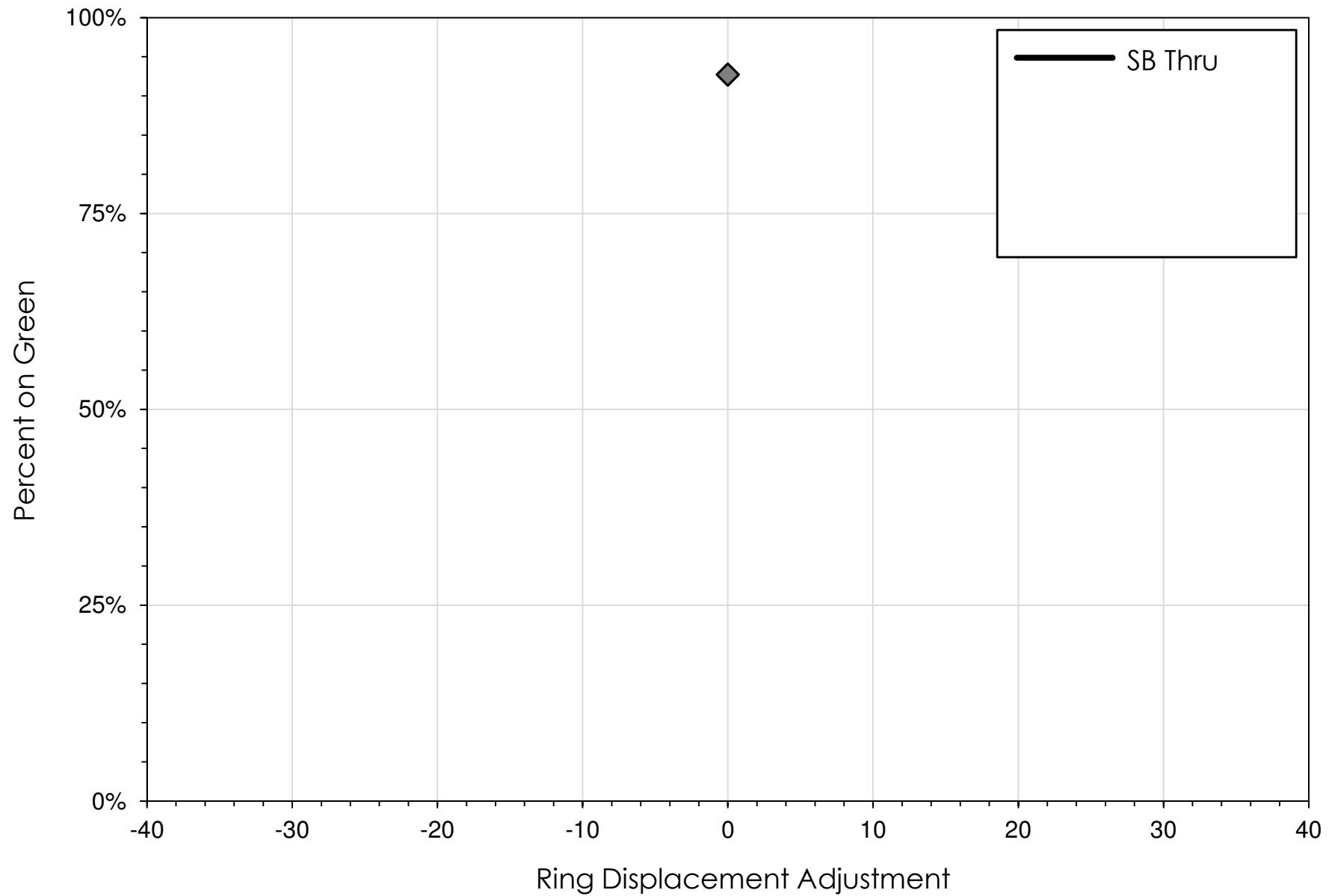
Ring Displacement +20 Seconds

Vehicles from upstream arrive later



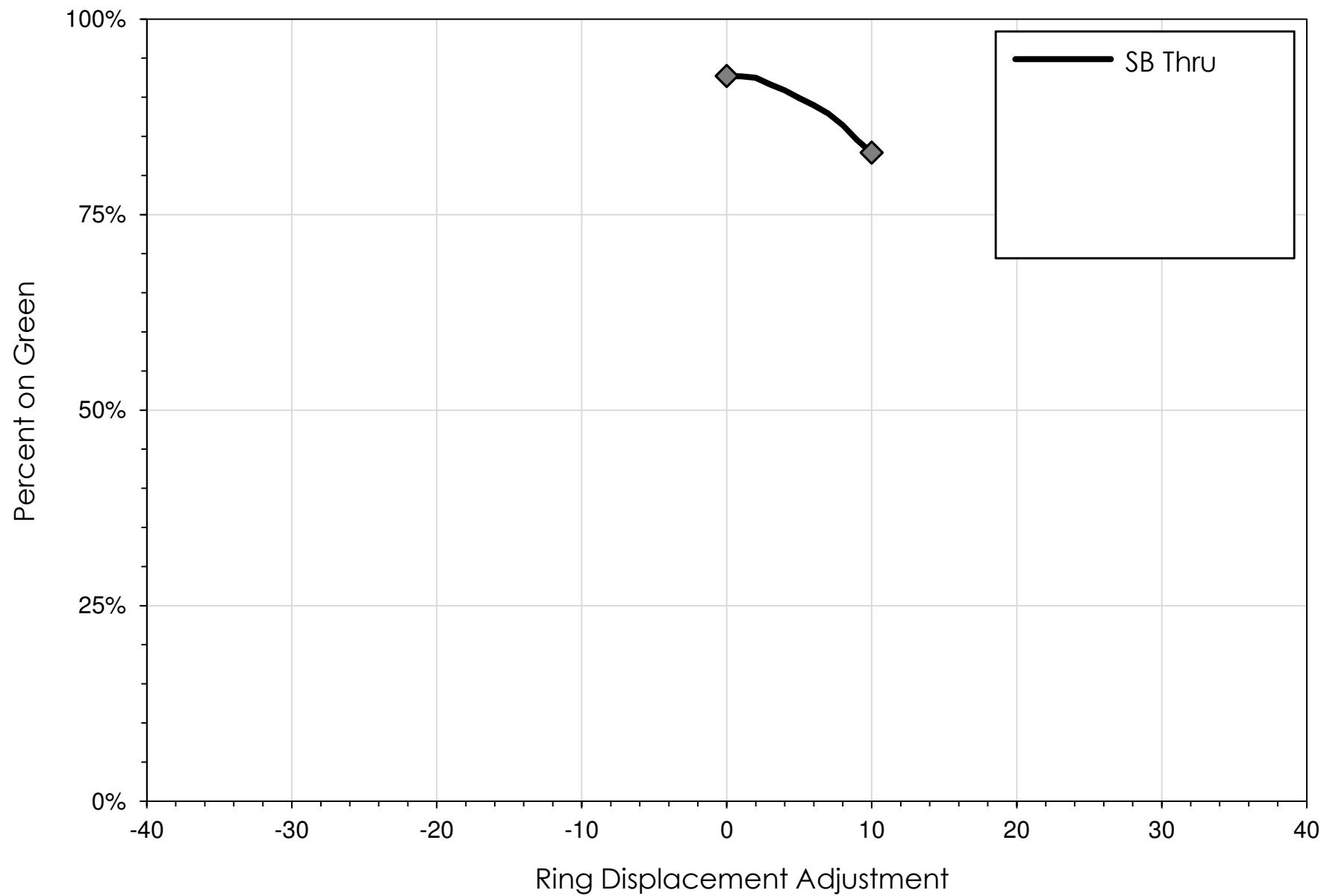
Optimization Curves

Let's Look at the Southbound Thru (Our +0, +10, +20 example)



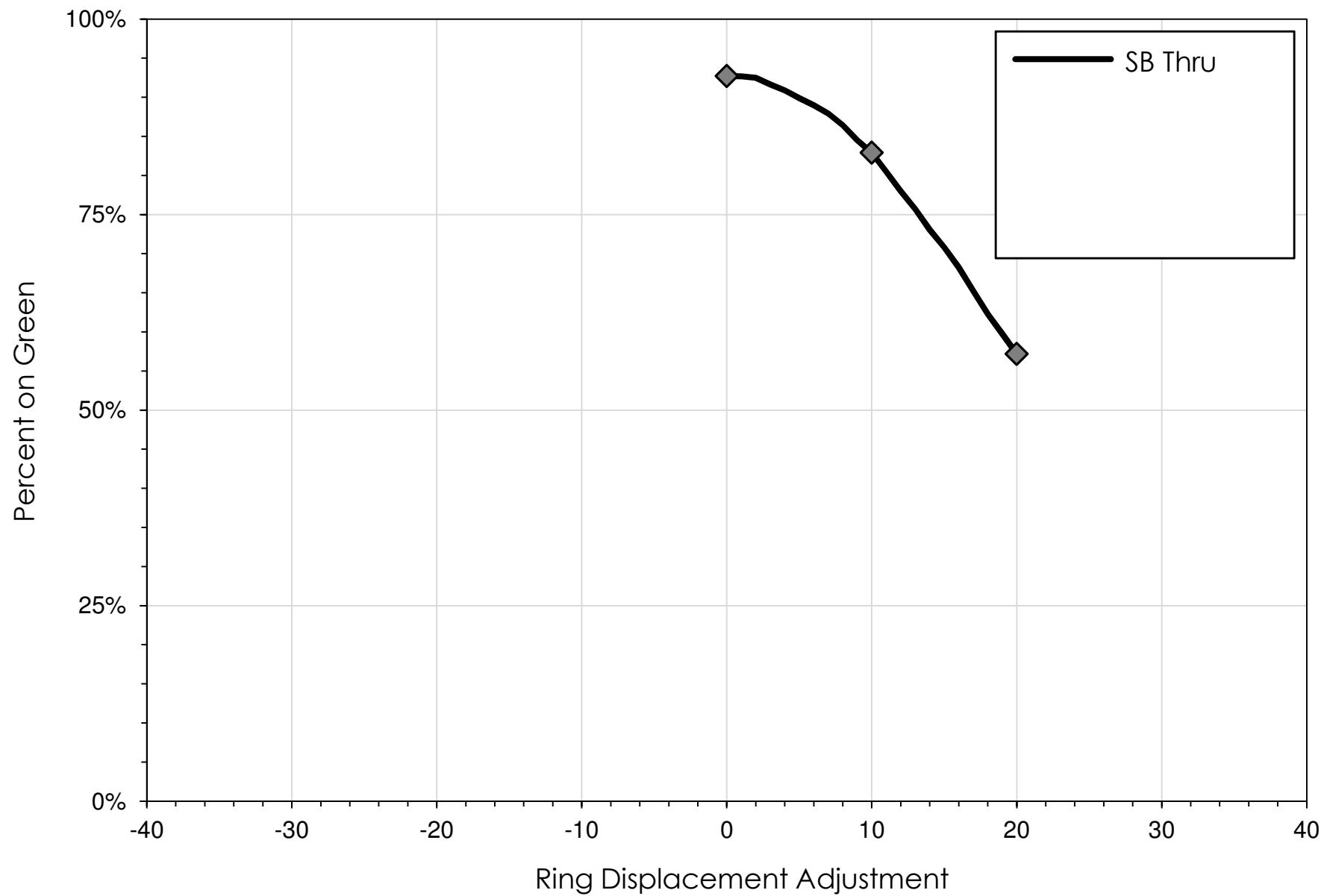
Optimization Curves

Southbound Thru +10



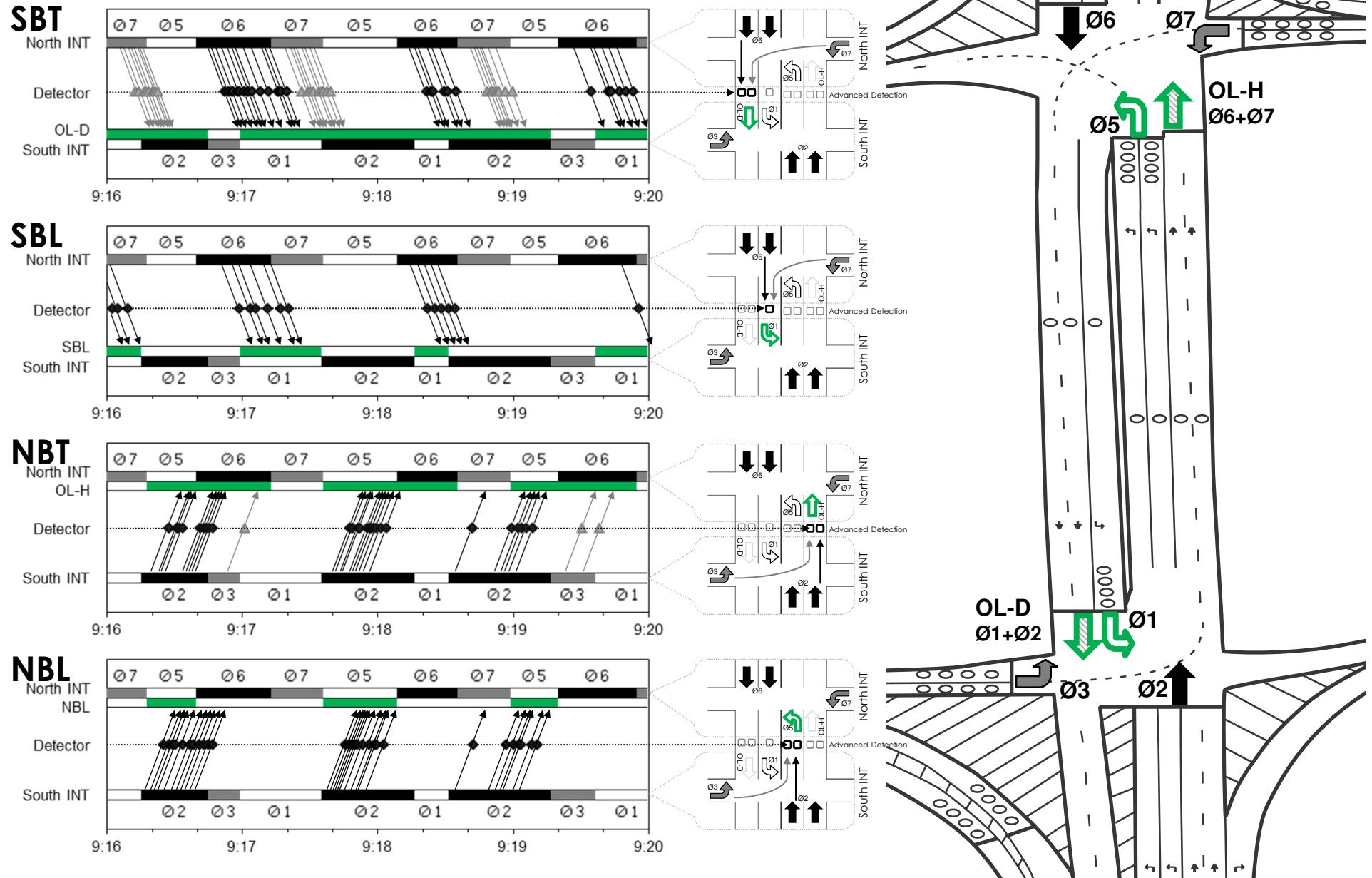
Optimization Curves

Southbound Thru +20



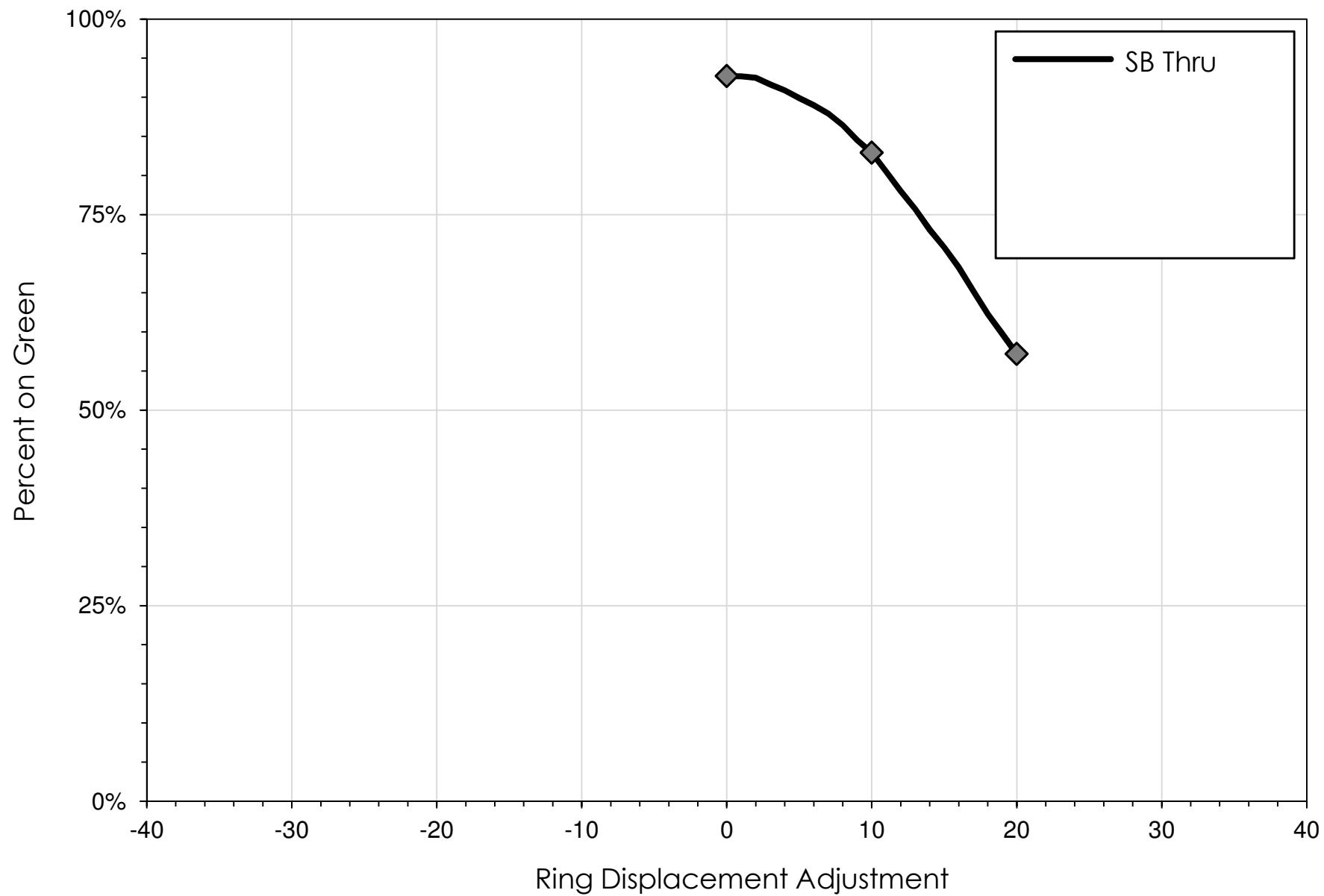
Optimization Consideration

Consider All 4 Movements Simultaneously



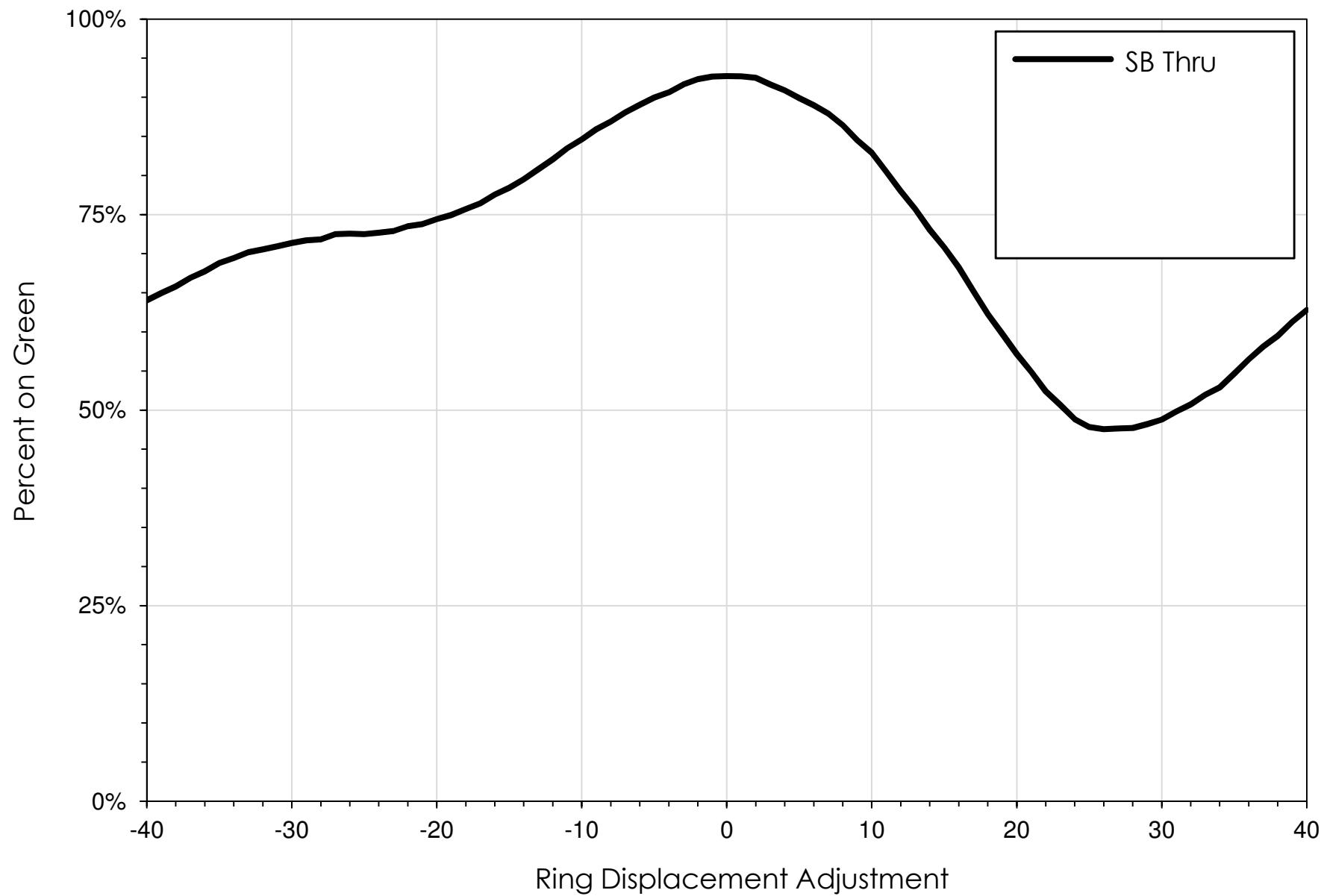
Optimization Curves

Southbound Thru +20



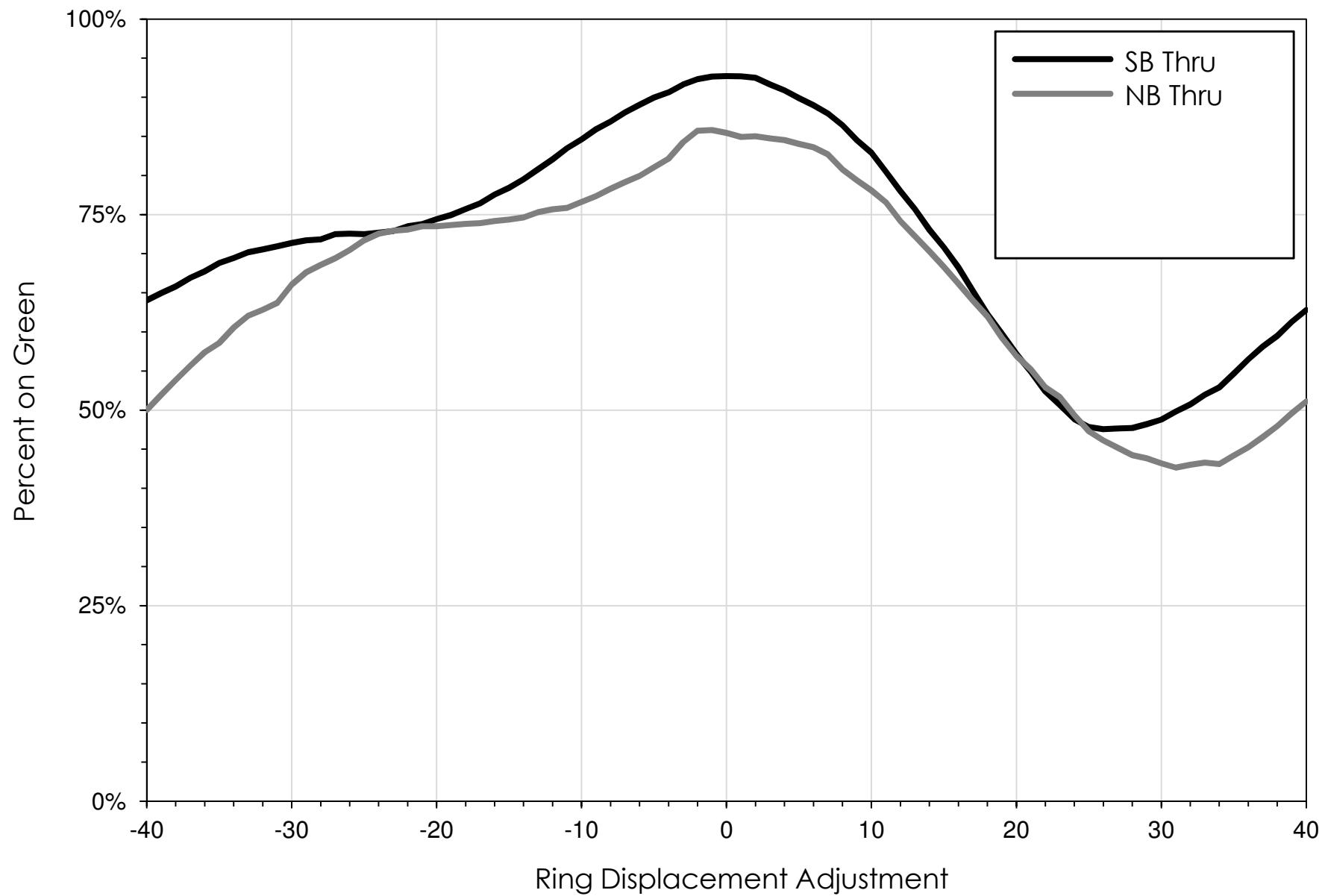
Optimization Curves

Southbound Thru for the Full Sweep



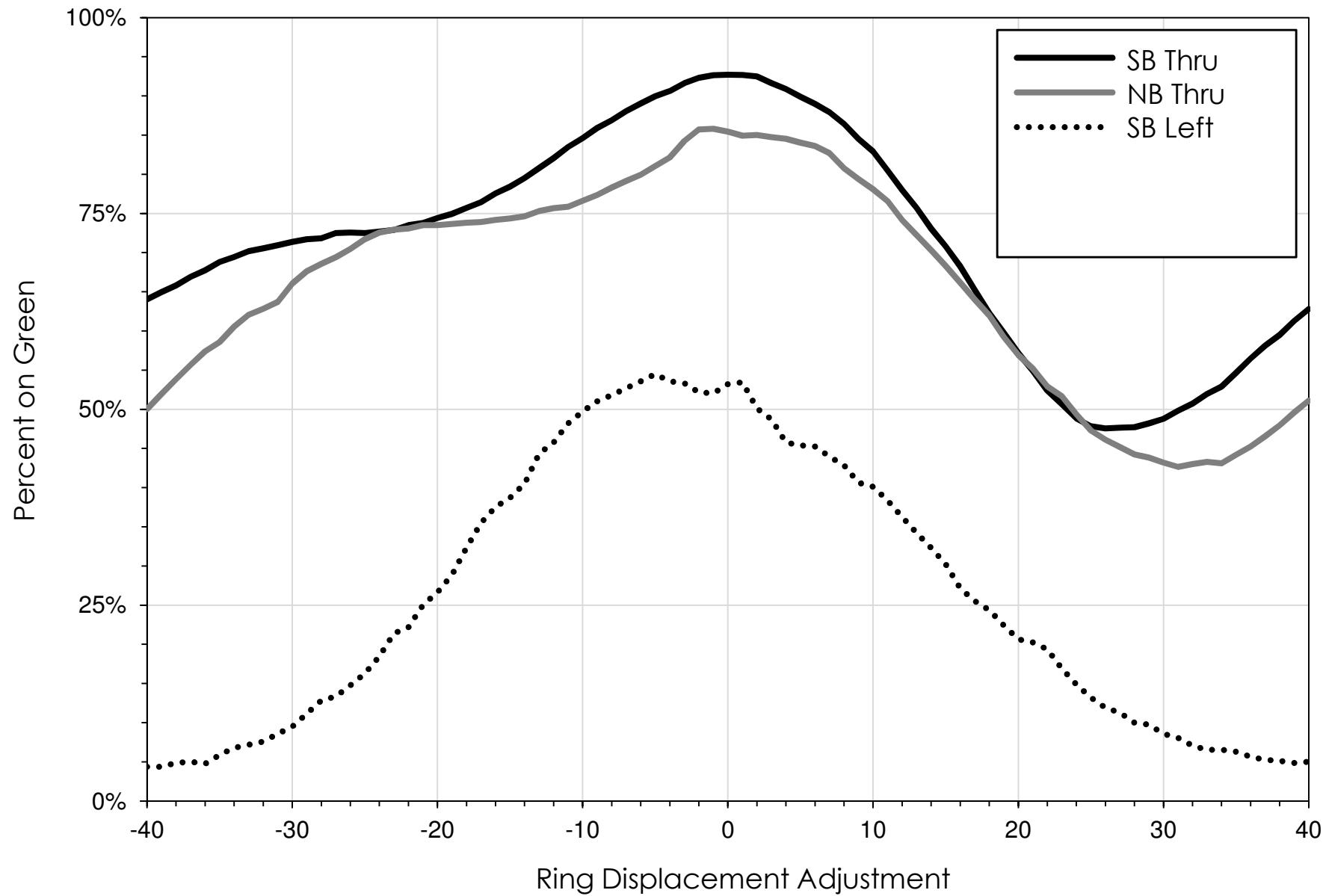
Optimization Curves

Northbound Thru



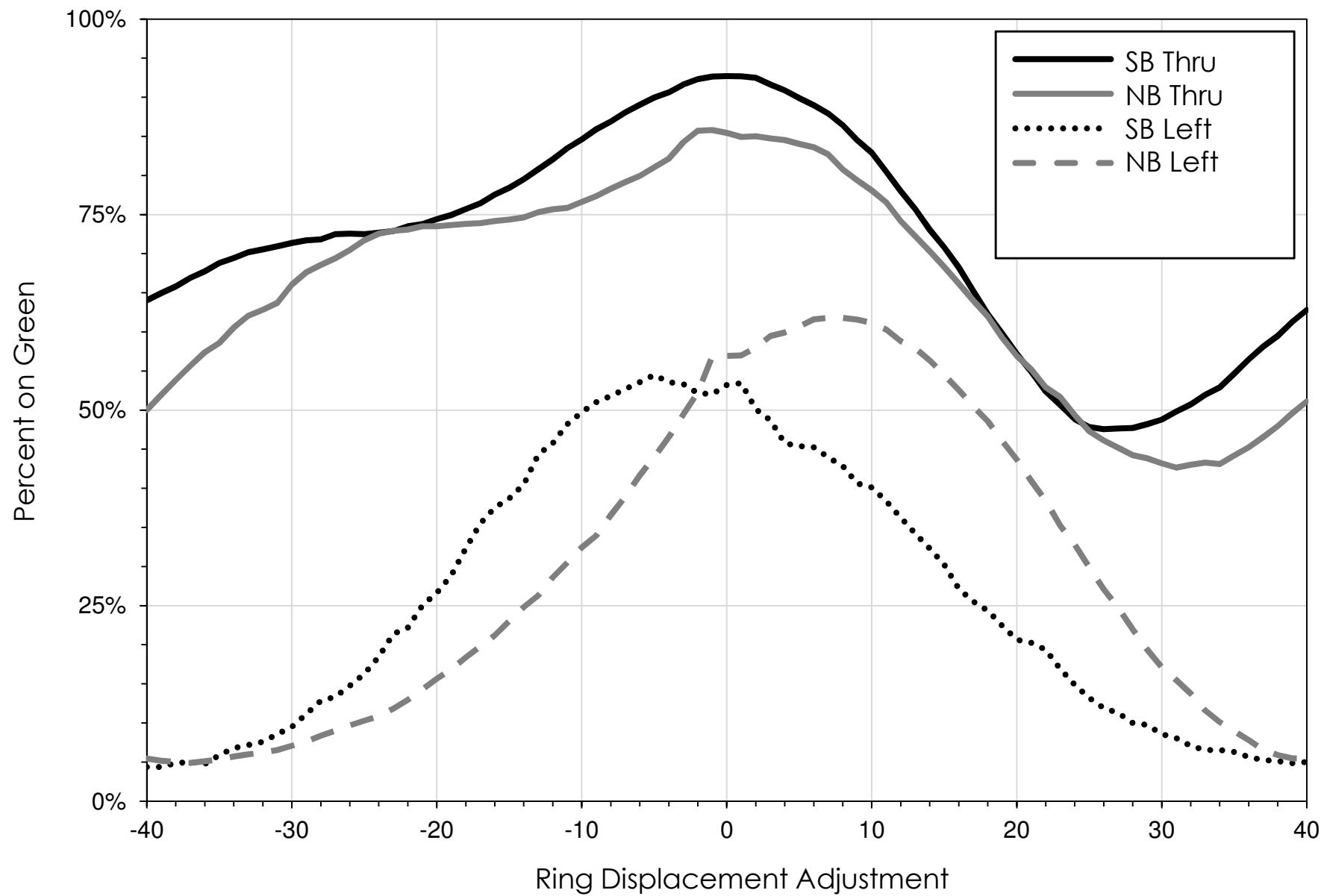
Optimization Curves

Southbound Left



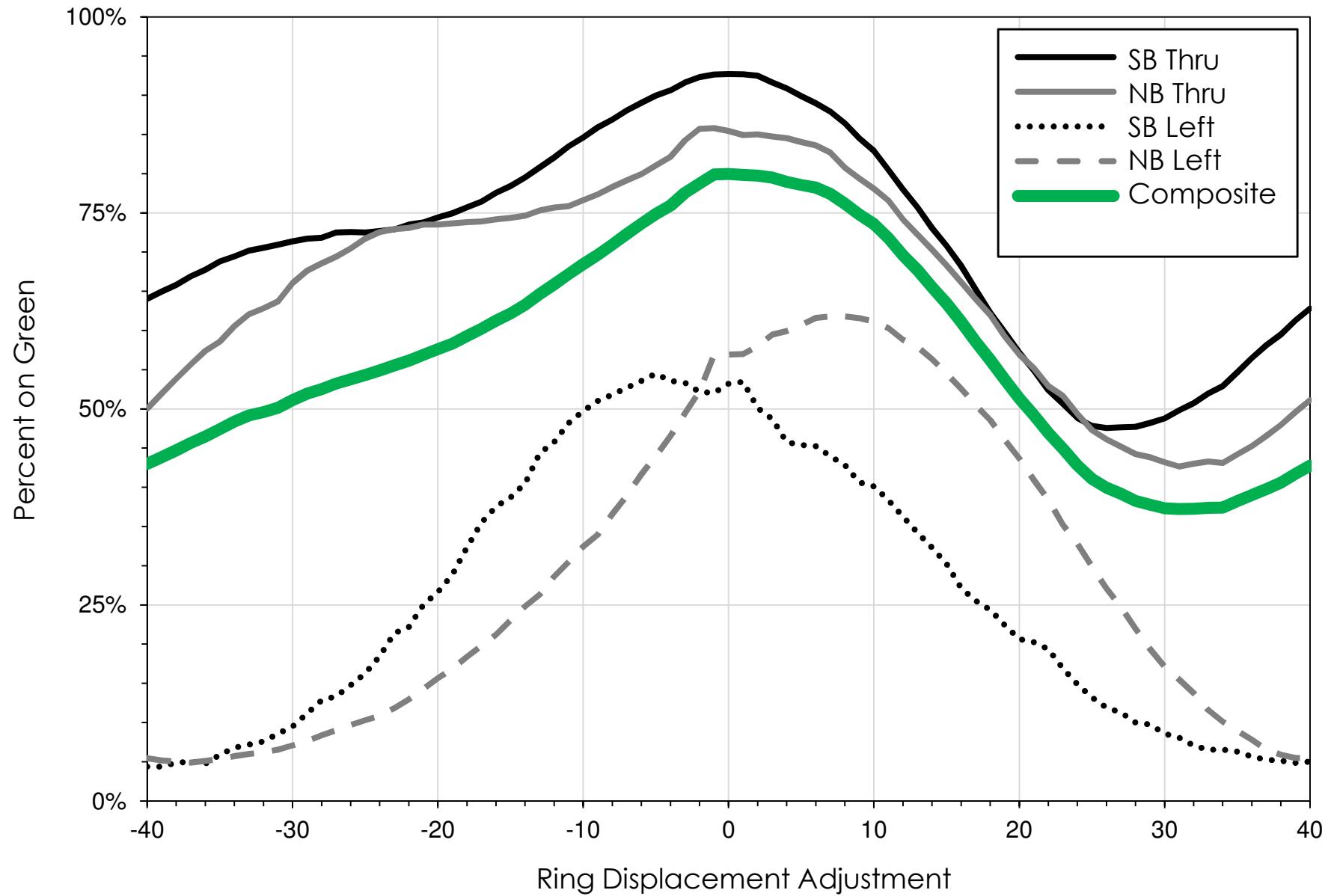
Optimization Curves

Northbound Left



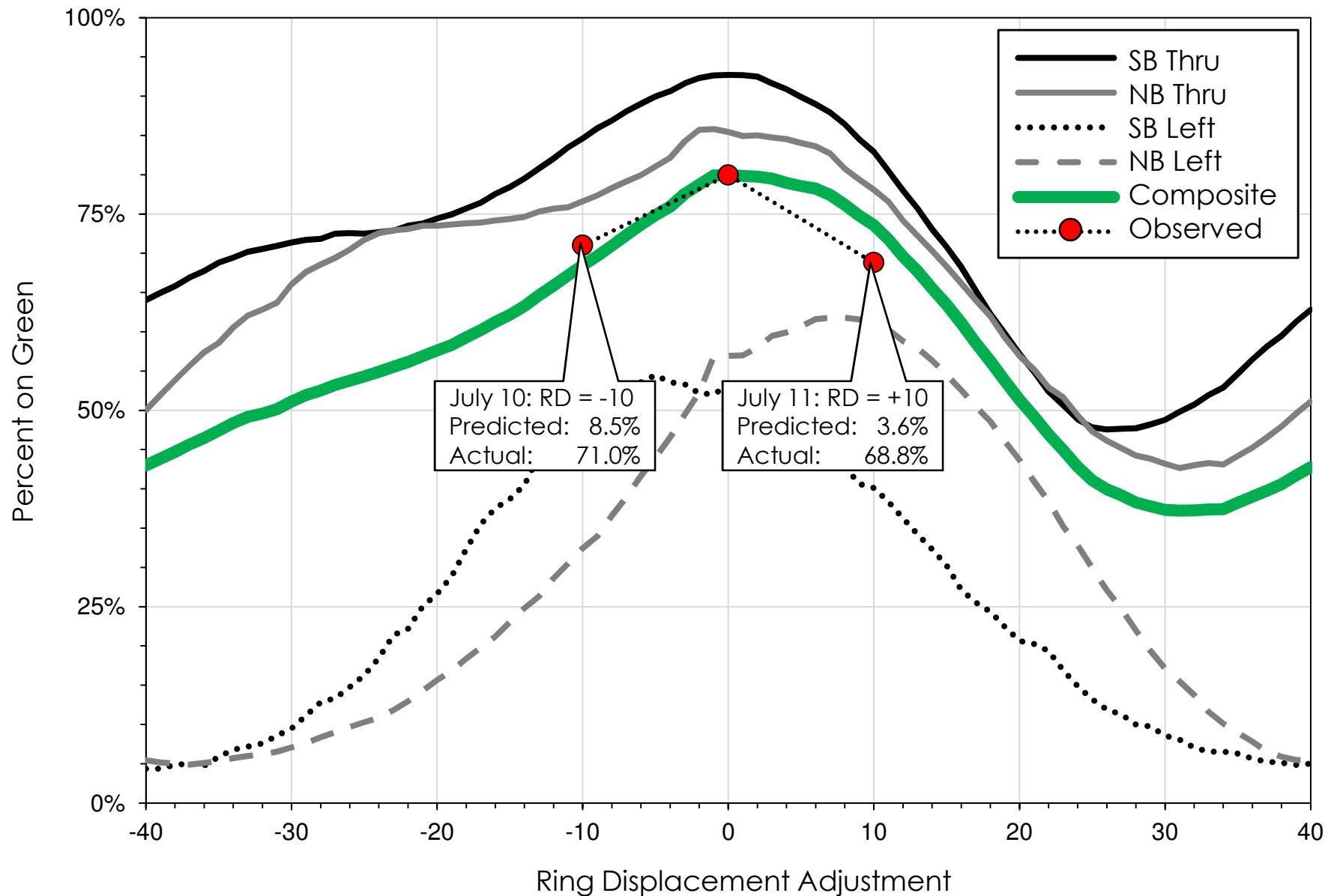
Composite Interchange Sweep

This is where all four movements are considered simultaneously.



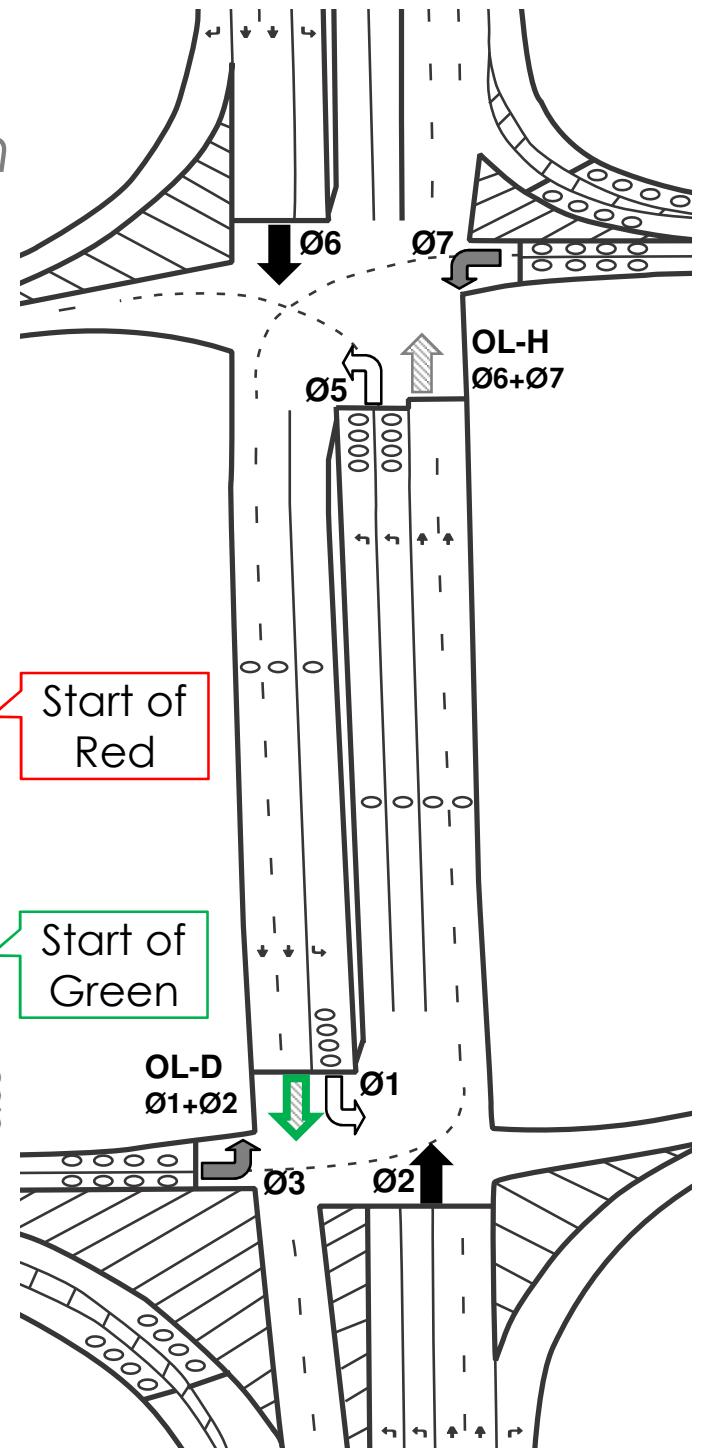
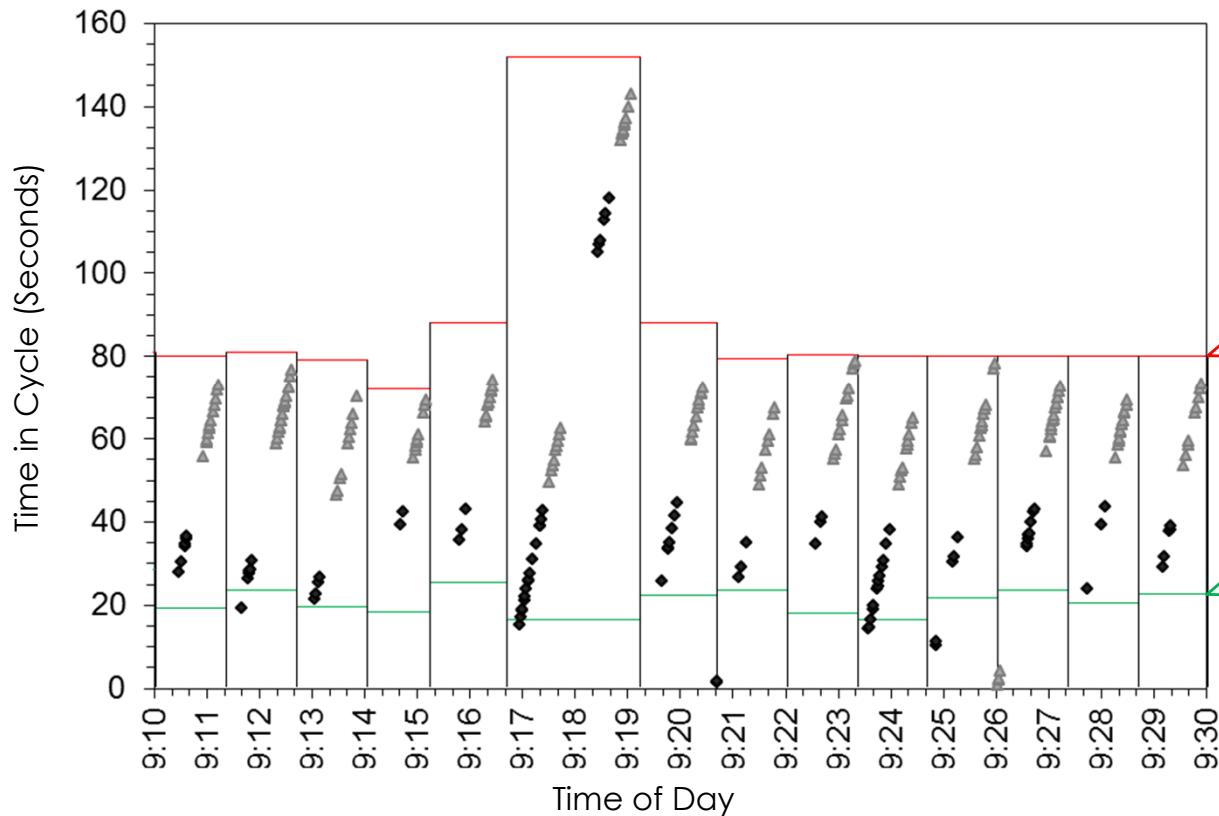
Field Evaluation

Adjust +/- 10 to see how it worked in the field



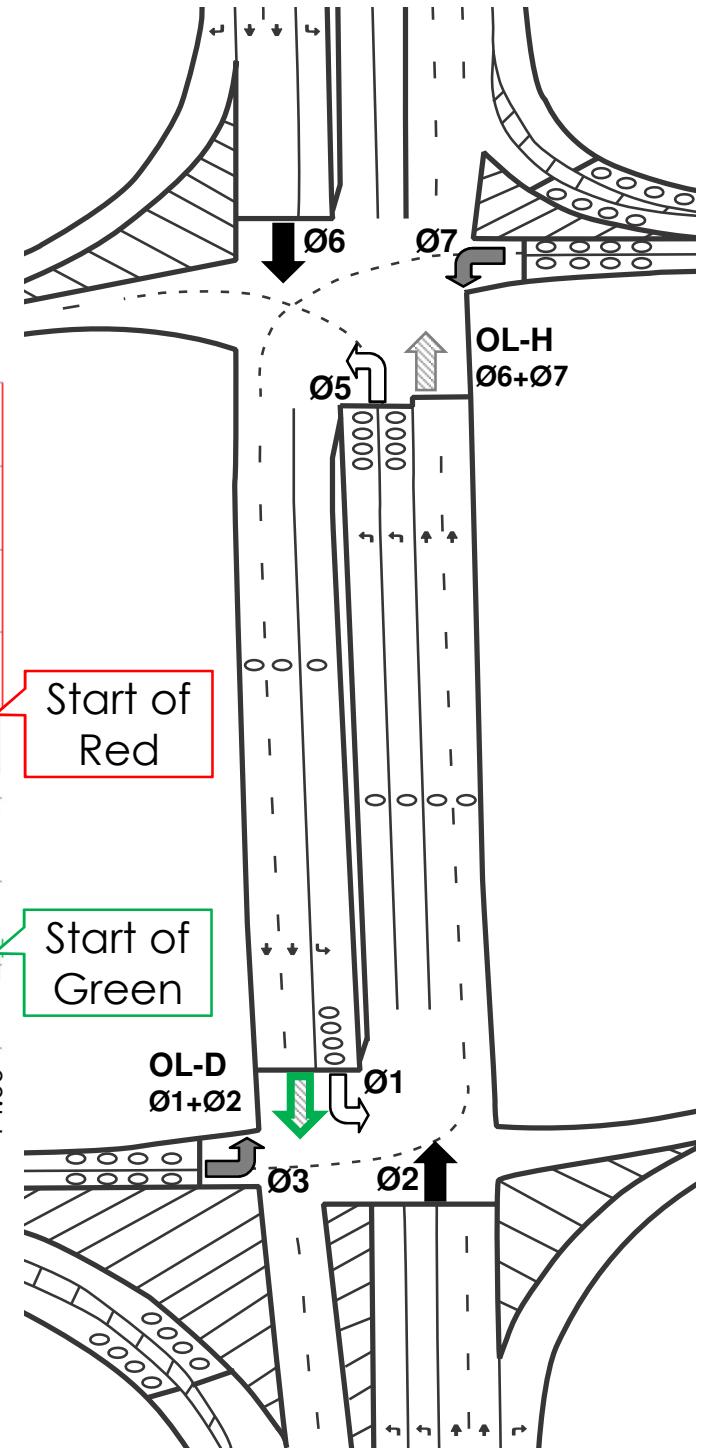
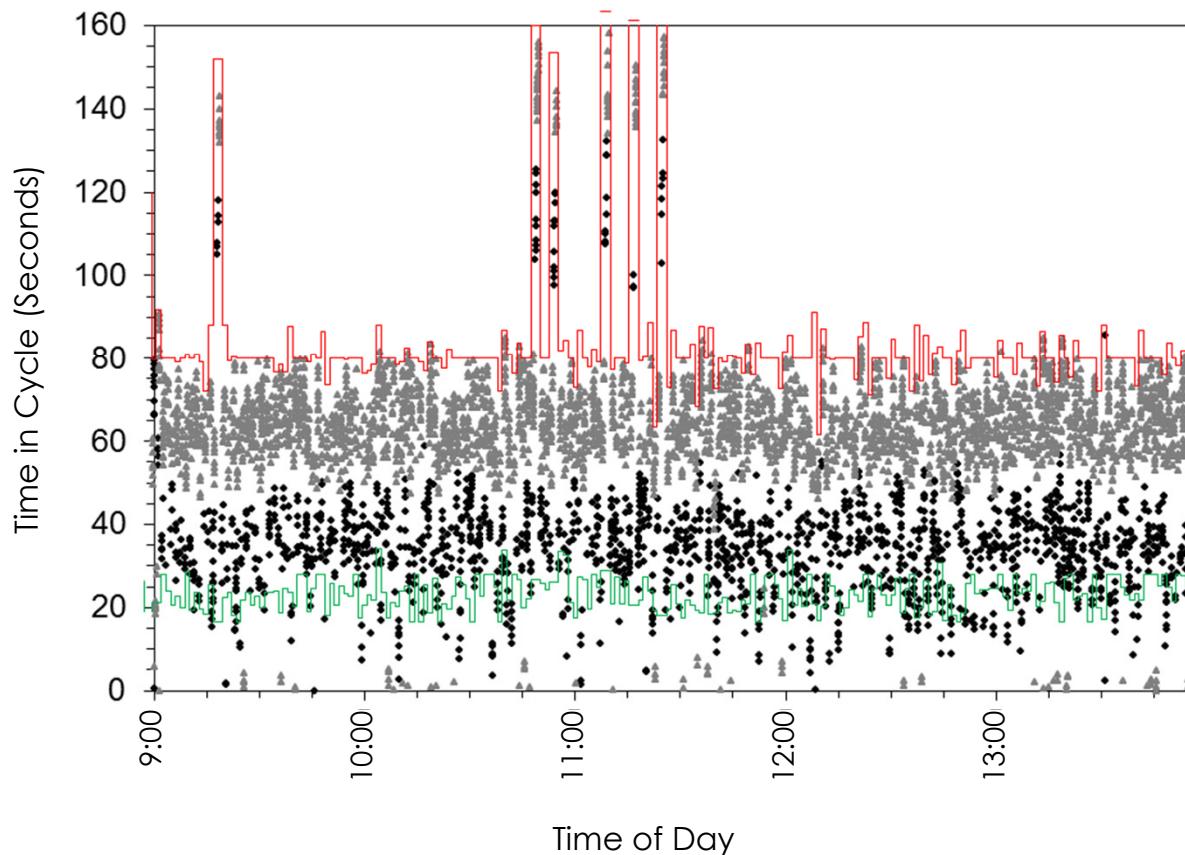
Purdue Coordination Diagram

Also Useful to Visualize Arrivals on Green



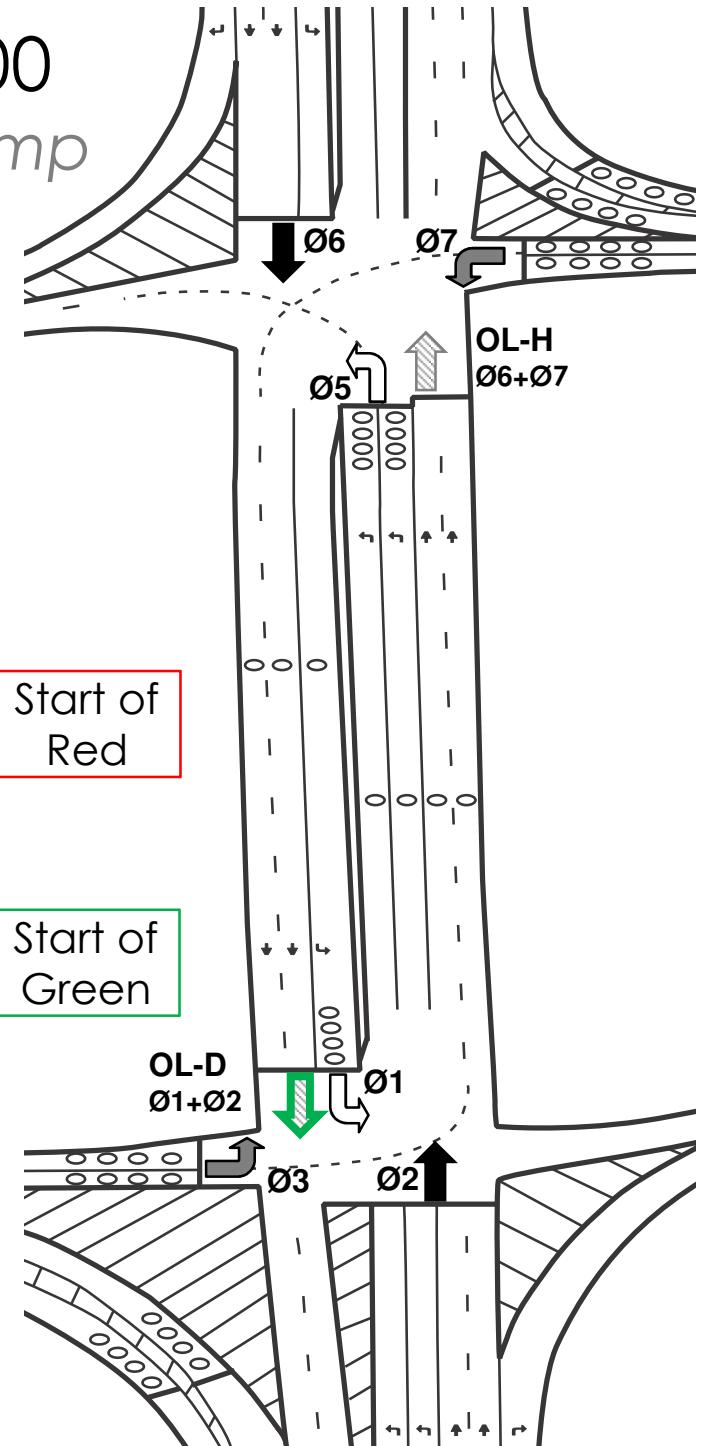
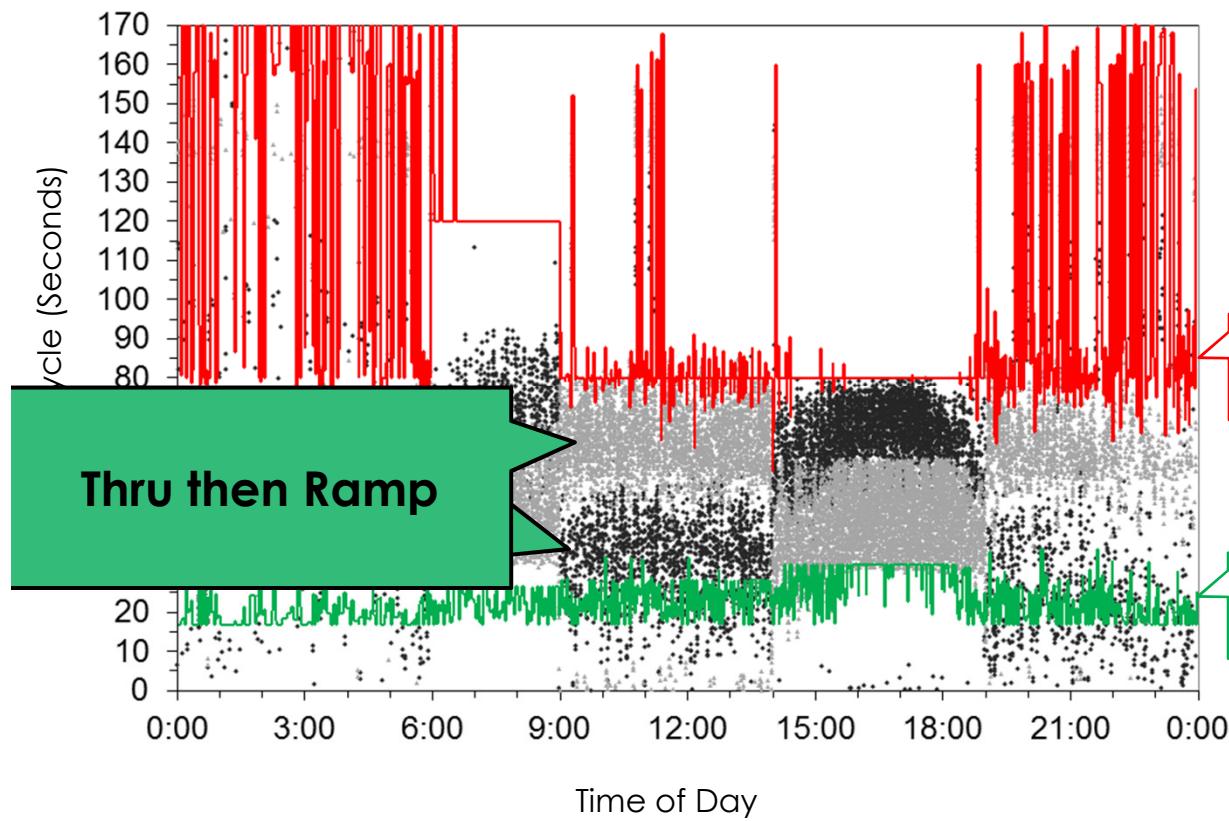
Purdue Coordination Diagram

Looking at an entire plan (0900-1400)



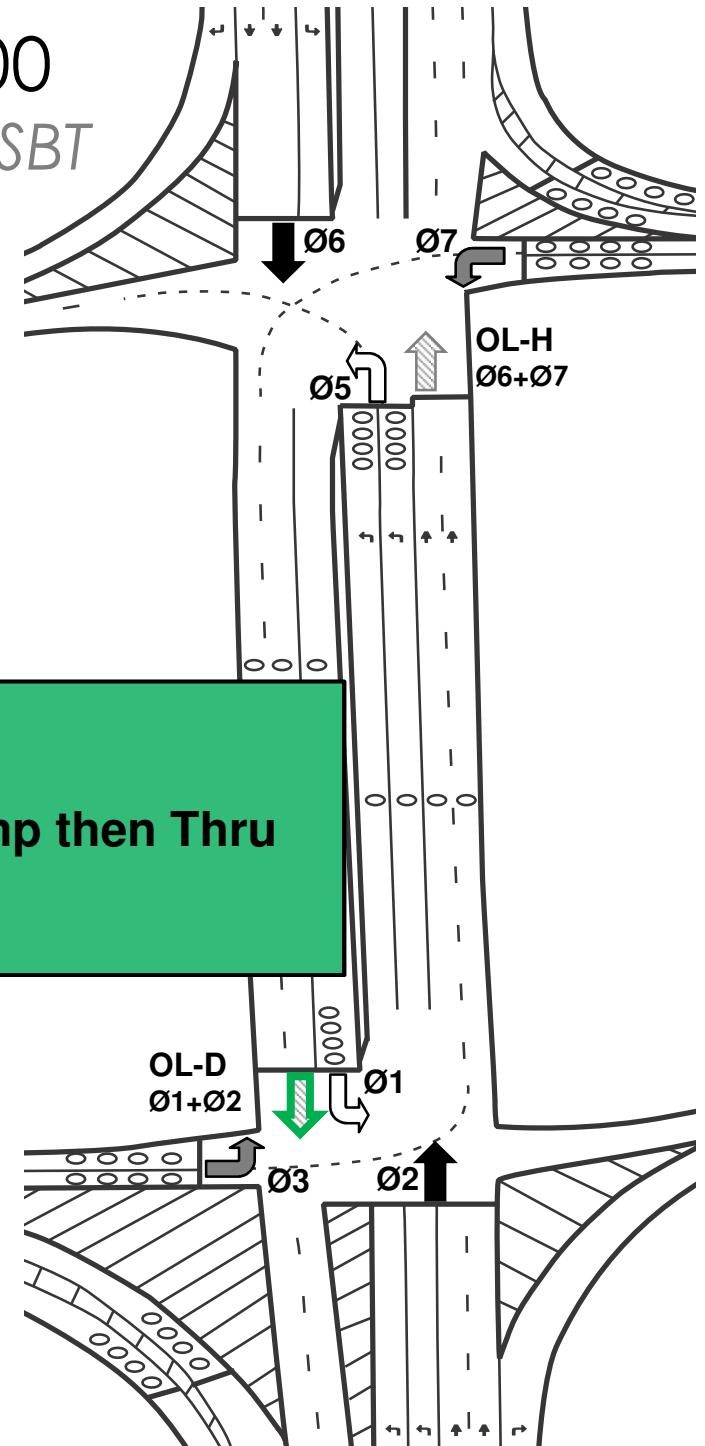
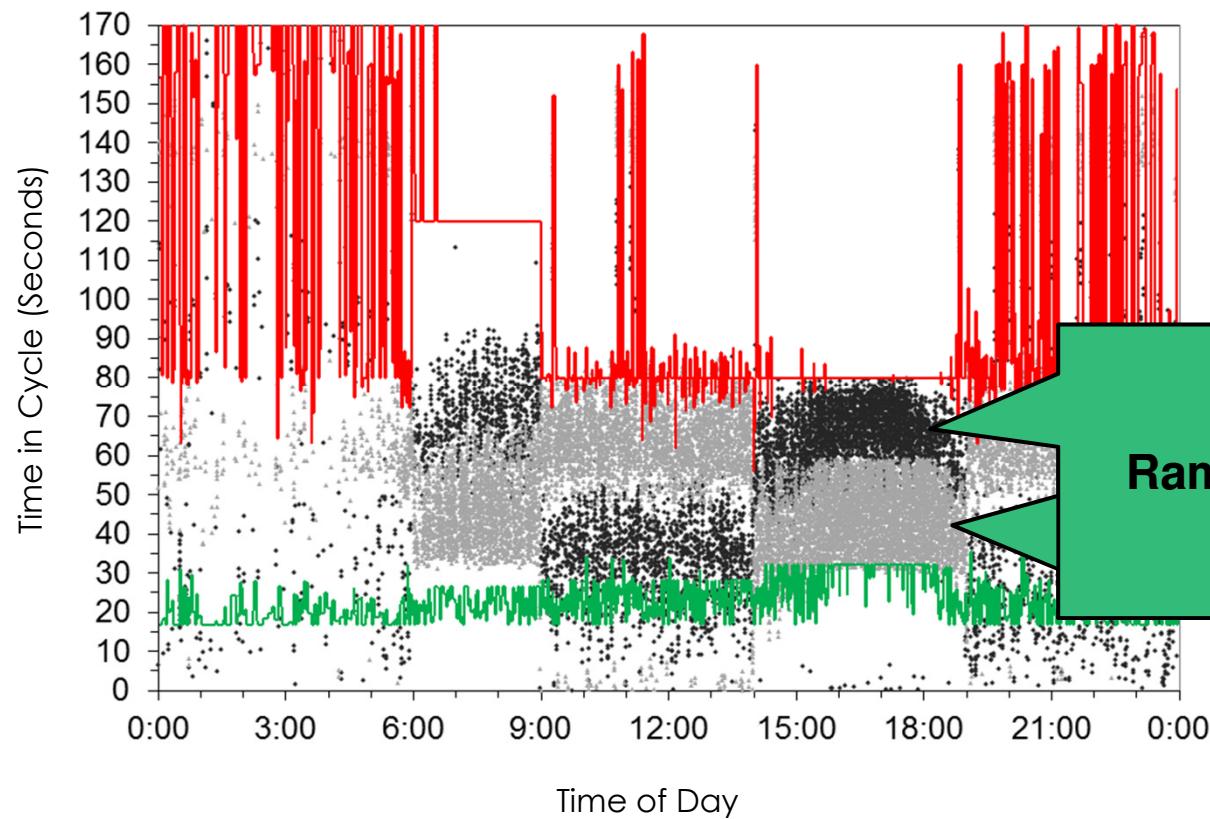
24HR PCD: Sequence for 0900-1400

First is Ø6 SBT, then Ø7 WBL from the ramp



24HR PCD: Sequence for 1400-1900

First is Ø7 WBL from the ramp, then Ø6 SBT



Conclusion: These Graphics are Useful!
Can they be included on newer generation traffic controllers?



Conclusion: These Graphics are Useful!
Can they be included on newer generation traffic controllers?

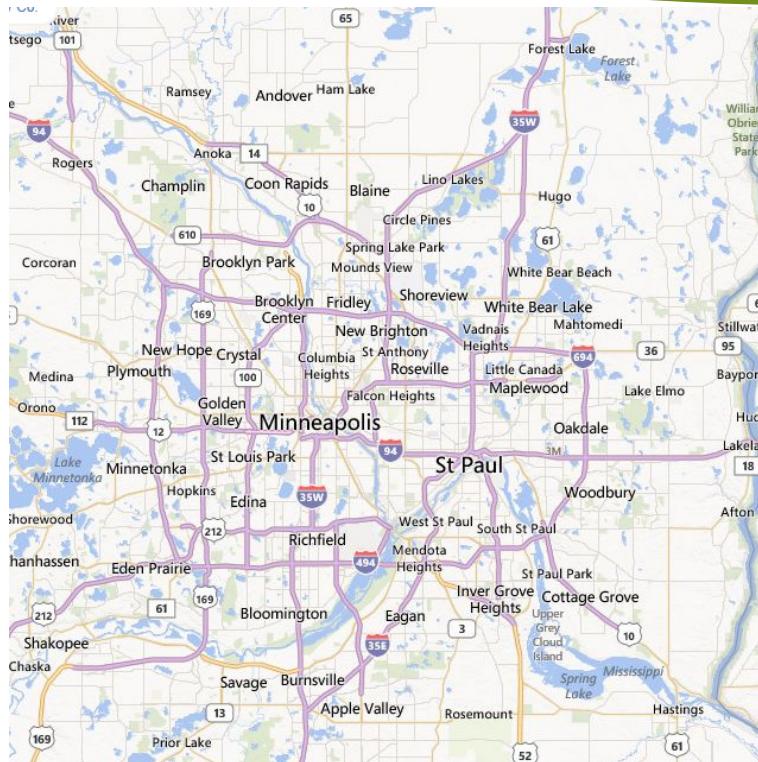


AUTOMATED TRAFFIC SIGNAL PERFORMANCE MEASURES CASE STUDIES: MnDOT



INSTITUTE OF TRANSPORTATION ENGINEERS WEBINAR PART 1 – MAY 7, 2014
PRESENTED BY STEVE MISGEN, MNDOT

MnDOT - Metro District Background



- ▶ Operates about 700 signals (Mpls/St. Paul Metro area)
 - ▶ 250 signal on i2 central system
 - ▶ 450 on ARIES dial-up
- ▶ Econolite ASC2/ASC2S or ASC3 controllers
- ▶ Signal Performance Measure
 - ▶ 83 on Smart Signal
 - ▶ 21 on Utah SPM

Smart Signal

- ▶ University of Minnesota
 - ▶ Henry Liu
- ▶ Minnesota Department of Transportation
- ▶ <http://dotapp7.dot.state.mn.us>
 - ▶ iMonitor – “Real-time” Level of Service
 - ▶ iMeasure – Data extraction tool

Smart Signal



iMonitor™ / iMeasure™

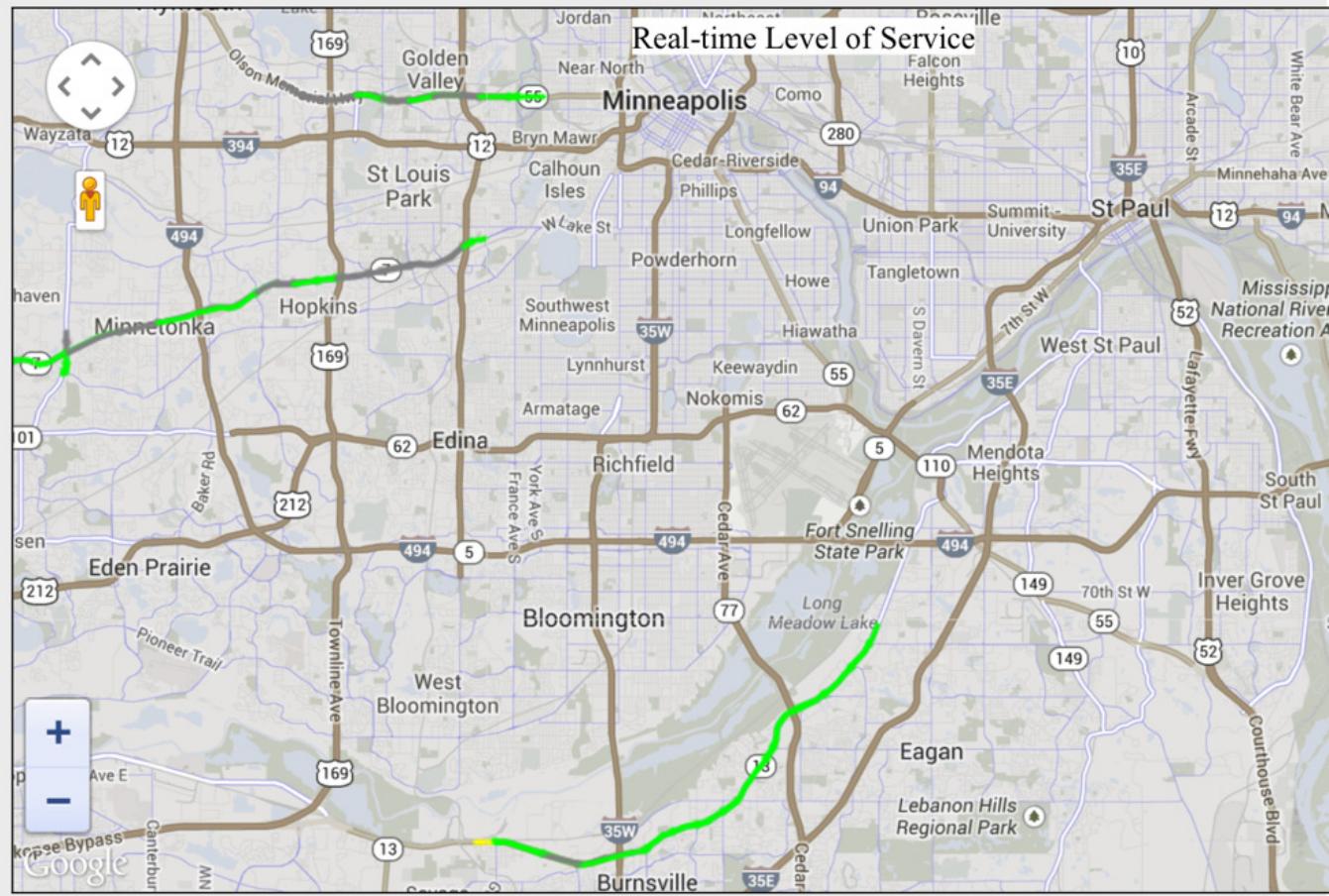
- System Overview
- System Check
- Site Access
- Help

LOS Legend:

- A&B
- C&D
- E
- F
- Real time data not available

Link Delay Legend:

- < 20 Sec./Veh.
- Between 20 and 55 Sec./Veh
- Between 55 and 80 Sec./Veh.
- > 80 Sec./Veh.
- Real time data not available



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Smart Signal

Performance Assessment

Optimization Preparation

Fine-tuning Analysis

Performance Comparison

Retiming Benefits

Periodic Report

Help

Volume Output

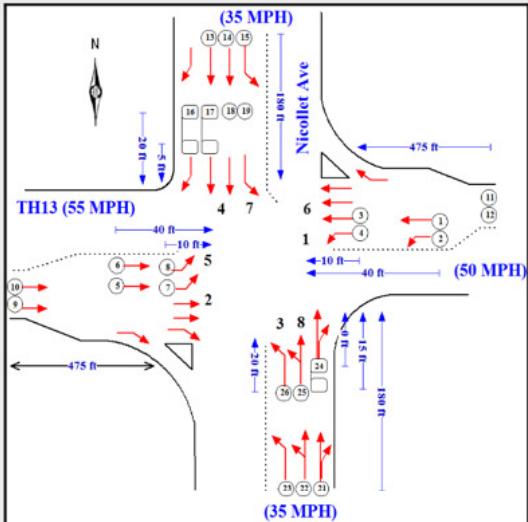
Intersection: TH13/Nicollet Approach Selection Mode: Normal Expert

Approaches (Group 1): Select Approaches (Group 2): Select

Start Date: 10/21/2013 End Date: 11/28/2013 Day of Week: Select Days

Start Time: 07:00:00 End Time: 18:00:00 Interval: 15 Minutes

Plot **Save Data**



15 Minutes Volumes
10/21/2013-11/28/2013 07:00:00-18:00:00 Group 1: EB Group 2: WB

15 Minutes Volumes

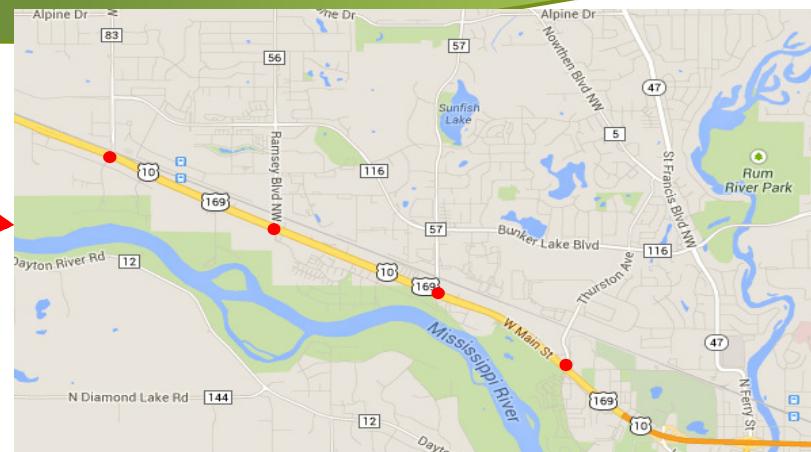
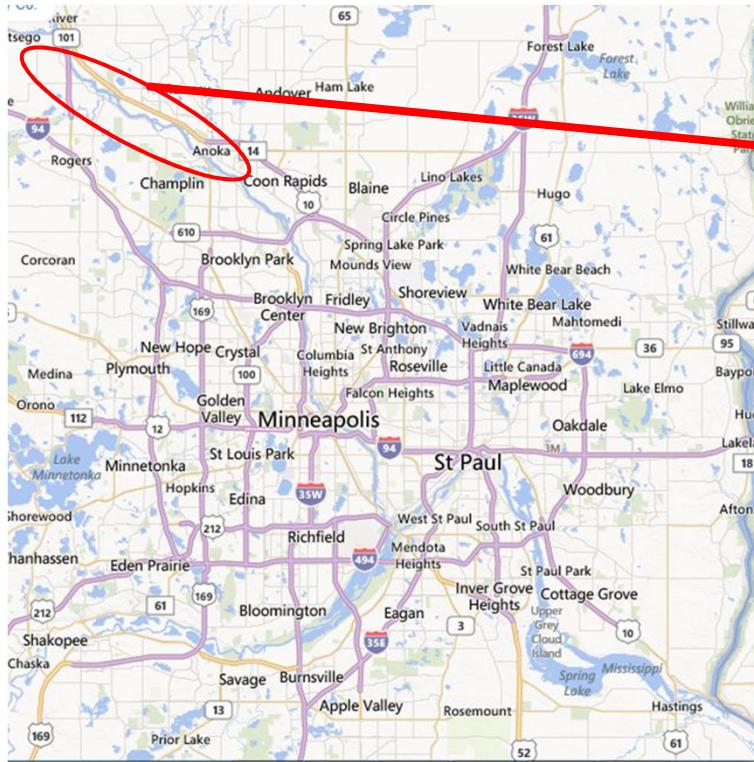
Time of Day

Group1 50th Percentile Group1 85th Percentile Group2 50th Percentile Group2 85th Percentile

Highcharts.com

The Project

Develop New Timing Using High Resolution Data collected from SmartSignal



- ▶ 4 fully-actuated signals
 - ▶ High speed 60-65 mph posted
 - ▶ 33,000-68,000 AADT
 - ▶ 7 TOD plans
 - ▶ Last retimed 2009

Signal Timing Development

Standard Method

- Data Collection
 - Manual Turning Movement Count – 12 hour
 - System Detectors
- Synchro – approximation of splits & cycle lengths
- Implementation & fine turning completed by time space diagram and field observations
- Before/After Comparison using Travel Time Studies

Improved Method

- Data Collection
 - Automated collection averaged over Sept-Oct for each movement (M-Th, F, S & S)
- Synchro - Time-space diagram for best two-way progression
- Implementation & fine turning completed by time-space diagram and field observations
- Smart Signal – monitor and make adjustments to insure efficiency
- Before/After Comparison using signal performance metrics

Volumes

September/October 2013 85th % Weekday Volumes - TH 10 at Thurston Avenue



Before/After Performance Comparison

Performance Comparison - Peak Hours (Total Intersection)												
TH 10 at Sunfish Blvd	Volume (# of vehicles)		Total Delay (Hours)		Number of Stops		Maximum Queue (Feet)		Saturation Level		% of Vehicles Arriving On Green	
	Total Intersection		Total Intersection		Total Intersection		Total Intersection		Total Intersection		Total Intersection	
Time of Day	Before ¹	After ²	Before ¹	After ²	Before ¹	After ²	Before ¹	After ²	Before ¹	After ²	Before ¹	After ²
AM Peak Hour 7:00 am to 8:00 am	3426	2906	30.15	21.9	2545	1484	613	121	0.74	0.54	0.7	0.84
Mid-Day Peak Hour 1:30 pm to 2:30 pm	2882	1982	14.42	11.27	1281	773	226	68	0.64	0.38	0.68	0.9
PM Peak Hour 4:30 pm to 5:30 pm	4082	2844	28.98	17.81	2352	1040	589	99	0.92	0.53	0.74	0.87
Total 5:00 am to 10:00 pm	46065	33607	256.41	177.01	21340	11301	261	58	0.63	0.34	0.6	0.9

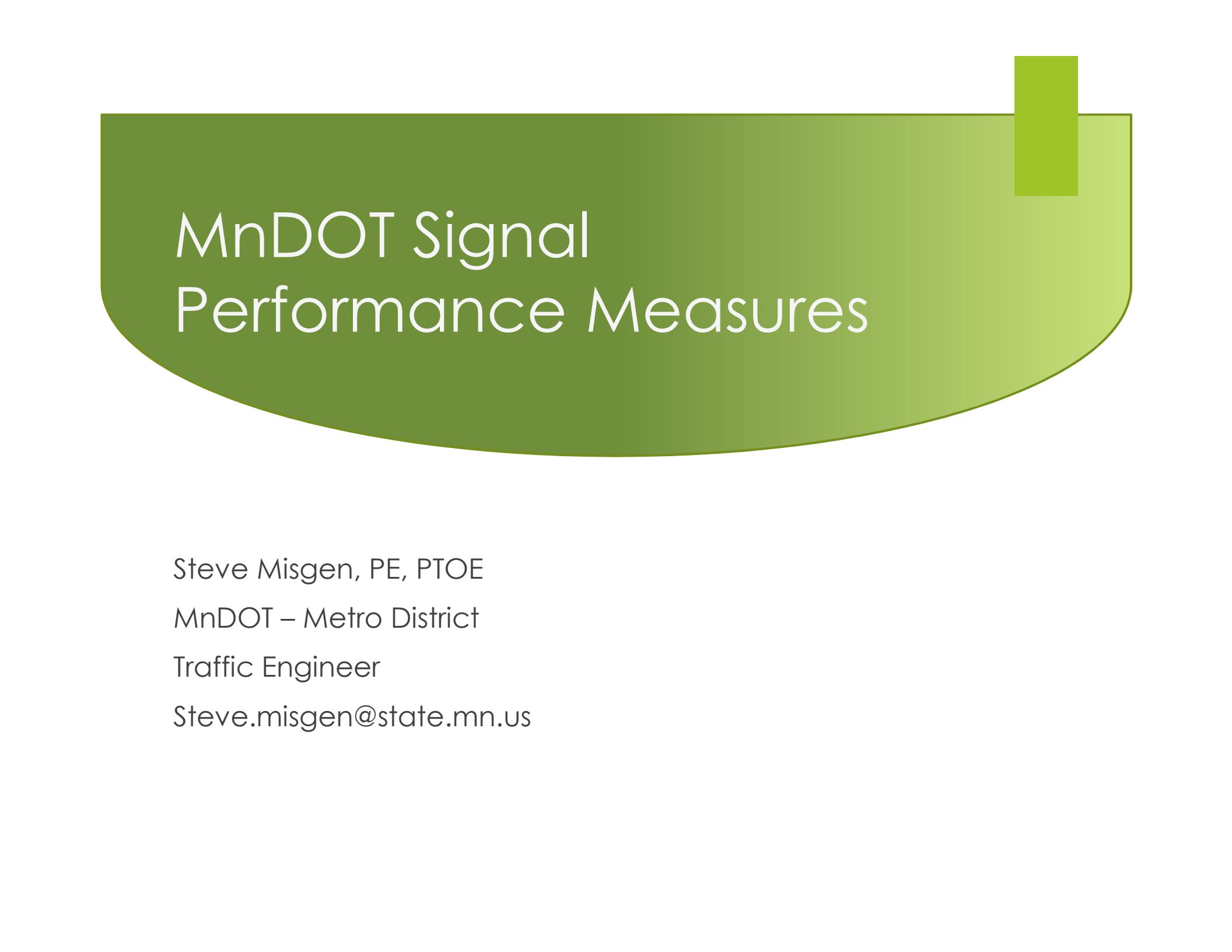
Future Plans

- ▶ Performance Index
 - ▶ based on volume, delay, number of stops, max queue length, saturation level & percent of vehicles arriving on Green
 - ▶ Calculate the PI for a given period on time (PM Peak) over a period of time (every Wednesday for the past year)
 - ▶ Track the change on performance over time
 - ▶ **When do you need to retime!**
- ▶ Time-space Diagram
 - ▶ Real-time TSD based on detector actuations
- ▶ Performance Metrics
 - ▶ Emissions – CO₂ fuel consumed

Future Plans

Performance Index Over Time





MnDOT Signal Performance Measures

Steve Misgen, PE, PTOE
MnDOT – Metro District
Traffic Engineer
Steve.misgen@state.mn.us

Find out more: <http://tig.transportation.org>



AASHTO TIG

- TIG Home
- About TIG
- Focus Technologies
- Executive Committee
- Feedback
- Additionally Selected Technologies
- TIG-Solicitation
- Lead States Team Guidance

TIG Home

AASHTO > AASHTO Technology Implementation Group > TIG Home

AASHTO's Technology Implementation Group — or TIG — scans the horizon for outstanding ad technology and invests time and money to accelerate their adoption by agencies nationwide. Each year, TIG selects a highly valuable, but largely unrecognized procedure, process, software that has been adopted by at least one agency, is market ready and is available for use by other. Guided by the vision of "a culture where rapid advancement and implementation of high payoff, expectation of the transportation community," TIG's objective is to share information with AAS agencies, and their industry partners to improve the Nation's transportation system.

Recently selected technologies with links to additional information are listed below. Also, you m and [Additionally Selected Technologies](#) categorized by AASHTO subcommittee interest area.

Lead States Team Focus Technologies

2013 Focus Technologies



- [Automated Traffic Signal Performance Measures](#)
- [UPlan Phase II](#)

Prior Four Years Focus Technologies

- [Embedded Data Collector](#)
- [Environmental Planning GIS Tools](#)

Additionally Selected Technologies

2013 ASTs

- [Double Crossover Dia](#)

Prior Four Years ASTs

- [Anonymous Wireless , Time Data Collection](#)
- [Curvature Extension F](#)

ITE Webinar Series on Automated Traffic Signal Performance Measures (SPMs)

- ▶ Achieve Your Agency's Objectives Using SPMs
 - April 9, 2014, 12:00 pm to 1:30 pm. Eastern
- ▶ SPM Case Studies
 - May 7, 2014, 12:00 pm to 1:30 pm. Eastern
- ▶ Critical Infrastructure Elements for SPMs
 - June 11, 2014, 12:00 pm to 1:30 pm. Eastern



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UDOT



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Thank you.
QUESTIONS?

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