Institution Oregon State University

Vehicle Properties				
Total Length (in)	118			
Diameter (in)	6.25			
Gross Lift Off Weigh (lb)	60			
Airframe Material(s)	Carbon Fiber/fiberglass			
Fin Material and Thickness (in)	Carbon Fiber 0.25			
Coupler Length(s)/Shoulder Length(s) (in)	15/6.5			

Motor Properties			
Motor Brand/Designation	AeroTech L2200		
Max/Average Thrust (lb)	700/495		
Total Impulse (lbf-s)	1147		
Mass Before/After Burn (lb)	10.46/4.92		
Liftoff Thrust (lb)	590		
Motor Retention Method	Bolted Retaining Ring		

Stability Analysis				
Center of Pressure (in. from nose)	87.8			
Center of Gravity (in. from nose)	66			
Static Stability Margin (on pad)	3.01			
Static Stability Margin (at rail exit)	3.07			
Thrust-to-Weight Ratio	8.25:1			
Rail Size/Type and Length (in)	1515 /180			
Rail Exit Velocity (ft/s)	92.2			

Ascent Analysis				
Maximum Velocity (ft/s)	553			
Maximum Mach Number	0.52			
Maximum Acceleration (ft/s^2)	353			
Target Apogee (ft)	4000			
Predicted Apogee (From Sim.) (ft)	4431			

Recovery System Properties - Overall		
Total Descent Time (s) 88.8		
Total Drift in 20 mph winds (ft)	1750	

Recovery System Properties - Energetics			
Ejection System Energetics (ex. Black Powder		Carbon bioxide and Black Powder	
Energetics Mass - Drogue	Primary	12g of CO2	
Chute (grams)	Backup	3.5g of Black Powder	
Energetics Mass - Main	Primary	23g of CO2	
Chute (grams)	Backup	6.5g of Black Powder	
Energetics Mass - Other	Primary	N/A	
(grams) - If Applicable	Backup	N/A	

Milestone	PDR
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Payload Deployment			
Location: Air or Ground (if applicable) Ground			
Altitude of Deployment (if applicable)	0 ft AGL		

Recovery System I	Properties -	Recovery Electronics	
Primary Altimeter Mak	e/Model	PerfectFlite Stratologger CF	
Secondary Altimeter Ma	ke/Model	TE MS5038 - Avionics	
Other Altimeters (if applicable)		TE MS5038 - BEAVS	
Rocket Locator (Make/Model)		ublox SAM-M8Q -	
Additional Locators (if applicable)		ublox SAM-M8Q -	
Transmitting Frequencies (al payload)	l - vehicle and	***Required by CDR*** (Complete on pages 3 and 4)	
Pad Stay Time (Launch Co	nfiguration)	10 hr	
Describe Redundancy Plan (batteries, switches, etc.)	The avionics bay will have additional batteries for twice the required time with backups in BEAVS.		

Recovery System Properties - Drogue Parachute				
Manufacturer/Model		Fruity chutes elliptical		
Size or Diameter (in or ft)		4ft		
Main Altin	neter Deployme	ent Setting	4000ft	
Backup Altimeter Deployment Setting		3950ft		
Velocity at Deployment (ft/s)		2.2	23ft/s	
Terr	Terminal Velocity (ft/s)		64.6ft/s	
•	ness Material, S 2 in. tubular Ny Kevlar strap)	Size, and Type lon or 1 in. flat	1in nylon flat shock cord	
Recove	ery Harness Len	gth (ft)	45ft	
Harness/Airframe Interfaces		Eye bolts		
Kinetic Energy	Section 1	Section 2	Section 3	Section 4
(Ft-lbs)	1343	1336	N/A	N/A

Recovery System Properties - Main Parachute				
Manufacturer/Model			ins uitra toroidai paraciidte fruity chutes	
Size o	Size or Diameter (in or ft)		12 ft	
Main Altimeter Deployment Setting (ft)		525		
Backup Altimeter Deployment Setting (ft)		!	500	
Velocity at Deployment (ft/s)			(53.6
Terminal Velocity (ft/s)			14	
Recovery Harness Material, Size, and Type (examples - 1/2 in. tubular Nylon or 1 in. flat Keylar strap)		1in nylon shock cord flat		
Recovery Harness Length (ft)			18	
Harness/Airframe Interfaces Eyeb			bolts and butterfly knot	
Kinetic Energy	Section 1	Section 2	Section 3	Section 4
(Ft-lbs) 63.1			N/A	N/A

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	Payload			
	Ov	erview		
Payload 1 (official payload)	The payload will be retained within the fore section of the airframe. Upon landing the payload & nose cone will eject from the airframe using a lead screw mechanism. Once ejected the payload wheels and tail will deploy and the rover electronics will be turned on. The payload will consist of a coaxial drivetrain, powered by two seperate motors. A ductile tail will be used to stabilize the rover. The rover system will be controlled remotly using a RF controller with a handshake frequency. The rover will then navigate to a collection site. Where a augar collection system will be deployed to collect a simulated lunar ice sample. Once the sample is collected it will be stored and transported 10 ft from the collection site.			
	Ov	erview		
Payload 2 (non-scored payload)				
	Test Plans, Status, a	nd Results		
Ejection Charge Tests				
Sub-scale Test Flights				
Vehicle Demon- stration Flights				
Payload Demon- stration Flights				
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Transmitter #1			
Location of transmitter:	Nose Cone		
Purpose of transmitter:	To track rocket altitude during flight		
Brand	HOPERF electronic	RF Output Power (mW)	100mW
Model	RFM95	Specific Frequency used by team (MHz)	915
Handshake or frequency hopping? (explain)	Will use a handshake protocol with acknowledgments		
Distance to closest e-match or altimeter (in)	61.33		
Description of shielding plan:	be surrounded by the ground plane, and will be isolated from the altimeter with several bulkheads which are slightly cond		

	Transmi	tter #2	
Location of transmitter:	Payload Bay		
Purpose of transmitter:	Ejection of Payload		
Brand	HOPERF electronic	RF Output Power (mW)	100mW
Model	RFM95	Specific Frequency used by team (MHz)	915
Handshake or frequency hopping? (explain)	Yes, to ensure that payload is not ejected prematurely. It will involve handshakes and acknowledgement.		
Distance to closest e-match or altimeter (in)	38.95		
Description of shielding plan:	It will be separated by a bulk head and will be surrounded by a ground plane.		

	Transmi	tter #3	
Location of transmitter:	Rover		
Purpose of transmitter:	Rover Control		
Brand	HOPERF electronic	RF Output Power (mW)	100mW
Model	RFM95	Specific Frequency used by team (MHz)	915
Handshake or frequency hopping? (explain)	Yes, it will use handshake to validate that the controls are correct.		
Distance to closest e-match or altimeter (in)	38.95		
Description of shielding plan: e p	e payload is ejected. Upon payload ejection it will be turned on and will not interfere wit		

Transmitter #4		
Location of transmitter:		
Purpose of transmitter:		
Brand	RF Output Power (mW)	
Model	Specific Frequency used by team (MHz)	
Handshake or frequency hopping? (explain)		
Distance to closest e-match or altimeter (in)		
Description of shielding plan:		

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Transmitter #5	
Location of transmitter:	
Purpose of transmitter:	

Brand	RF Output Power (mW)
Model	Specific Frequency used by team (MHz)
Handshake or frequency hopping? (explain)	- Fr
Distance to closest e-match or altimeter (in)	
Description of shielding plan:	
	Transmitter #6
Location of transmitter:	
Purpose of transmitter:	
Brand	RF Output Power (mW)
Model	Specific Frequency used by team (MHz)
Handshake or frequency hopping? (explain)	
Distance to closest e-match or altimeter (in)	
Description of shielding plan:	
	Additional Comments