

HYRO

JASON KLINDTWORTH | JOSH ASHER | LAYNE NOLLI

**CS461**

**Team 28**

*Fall 2016*

*Fall Term Progress Report*

Abstract

We are now in our second term of capstone and this paper documents the first half of that term. There have been fewer struggles this term but still many mysteries. This paper details our failures, hardships and success's. Overall we are were we need to be at and excited about launching this rocket up to 10,000 feet!

February 15, 2017

## I. OVERVIEW OF PURPOSE AND GOALS

OSU has for the past 2 years had seniors from MIME and ECE develop a hybrid rocket for their capstone projects. The first years didn't even get off the ground, but through their efforts last year's team was able to build a hybrid that went 5000 feet. They were able to build a system to collect a large amount of data from on-board sensors, but had no way to easily visualize it. That's why we were invited aboard. This is the first year a CS team has worked on the hybrid rocket team. Our goals are to provide visualization to their data along with providing remote controls (like filling the oxidizer tank) to allow the team to operate the rocket entirely from a safe distance. We have been working closely with our ECE counterparts in this second third of our capstone experience.

Last term we had completed our major design documents. This proved challenging on many levels. We had to not only get to know ourselves well, but learn to work well together. Then repeat that same process with a 15 member team. There were a lot of bumps in the road including communication, understanding, and learning. In the long run we all need to develop an entire hybrid rocket, launch it 10000 feet, and visualize the data from the onboard components.

This term we have begun our development of our project. Our goals at this point of the progress report are to get it to an alpha stage. For us that means getting the radio transceiver communication working, setting up the user interface with all of its components, and begin to give those components functionality. Then we want to solidify receiving data, visualizing and logging it. Graphics are not our biggest concern at the moment. We want to get our project as far along as possible so we can spend next term smoothing the data flow and looks out.

Another big goal for this term is to revise our original design documents. During the course of this progress report we all have taken the time to revise our sections. Not a whole lot of things have changed, but there were some major changes. These will be mentioned under the next section. The goal in the long run is to have a set of documentation that professionally describes our system and the road we took to get to the solution. Currently we have speeches and a rough draft of our poster to look forward to.

## II. WHERE WE ARE CURRENTLY

We have begun development of our user interface and its backend as well as starting work on the communication between the rocket at the ground computer. This communication is going to be done by radio transceivers called XBees. The user interface is at an alpha stage, but we are very comfortable in the amount of progress we have made on it. It has all the buttons that have been requested for the rocket commands. Including the call back functions for the buttons that will send data to the onboard rocket system. This does not yet send data to the XBee, but is one of our current coding problems. We have created classes for drawing the graphs and gauges on our interface. They look fairly ghetto right now, but Jason is going to work on graphics to make them look better. Right now they are drawn using the Tkinter canvas drawing functions. We were also successful in implanting the Matplotlib library and using it to draw graphs on the canvas widgets.

As far as the user interface backend is concerned we have all the thread and initialization functions necessary to start XBee communication and initialize the user interface. One of the next steps is to code all of the data buffers and log arrays into the program. When this is done we will code in the loading function that will load data into these arrays to display on the screen. We will have not done much work on the data processing yet, but we are close.

We received the XBees and a Beagle Bone Black to experiment with. On the traditional computer side we installed the XBee python library and were able to get the computer to talk to its XBee that was connected via USB. We did this by creating a python thread that initializes the serial port and XBee then loops with a callback function to receive transmission. This was successful, we will now code the send function. This was a very exciting accomplishment.

There were some major changes that came up this term so far. Mainly we found out that the ECE team will be covering collecting sensor data and controlling electronic components. They will interface with us on the Beagle Bone Black in the system and send us this info. We are responsible for the same communication of commands back to their program. This has saved us a lot of time and we feel we will have time to reach our stretch goal of 10000 feet.

The rocket currently has finally begun its development stage. A lot of components were not chosen until this week. This has left us and the ECE team really in the dark as far as design goes. Now the ECE team has finalized their stuff and is ready to communicate with us because the ME team has finally decided on the components and dimensions of their rocket. This is a very fun process to watch, especially test fires.

For the rest of the term we plan on getting our document signed and getting the system into full working beta. There are some unknowns still like the tank pressure, but we want to be far enough along that adding such a component will be easy. First though we will make sure all the currently selected requirements are met by the end of the term. We would like to spend next term refining our product.

## III. MAJOR PROBLEMS AND SOLUTIONS

## IV. WEEK BY WEEK RECAP

The following is a week by week recap from each team member up to week 5 of winter term.

### A. Week 1

1) *Josh Asher:* I am excited to be back from winter break. Looking forward to the major development portion of our project. Just remembered we all need to sign up for the AIAA, totally forgot about that. We were able to get a few things done over the break. Our development environment is set-up and working. We for the moment are trying out the Visual Studio python extension and it is working great so far. We were able to get a few things up on our GUI, this will be coming along faster now that we are back focused on school. Next week we plan to get the layout of the GUI finalized and work on the graphing utilities. I will be ordering a couple pieces we don't have so at some point we can get to work on the serial communication part of this project. Should be a great term!

2) *Jason Klindtworth:* We did not get a whole lot done over the break. We were hoping to get together a few times but it just did not work out with all of the traveling and icy conditions that ended up happening. We were able to independently get a bit worked on for our project however. We got a few working buttons and things up and working on a functional GUI. We will continue to tweak and change the layout until we find a design that we are both happy with, and will work for the project. Now that we are back in school and meeting regularly we should be able to ramp up the development progress in the next few weeks and are hoping to be most of the way done with the project by the end of this term.

3) *Layne Noll:* We didn't get any work opportunities over the break but once the start-of-term turmoil has settled I have full confidence in our team being able to get down to business on the project. Need to sign up for AIAA. Goals for the term are to be mostly done by the time spring rolls around to leave lots of room for last minute adjustments.

### B. Week 2

1) *Josh Asher:* This week we arranged meetings for both the TA and the rocket group meetings. So starting next week that should all be on schedule. We are planning on meeting on the weekends hopefully as a group. We think the initial part of our project including the GUI and the traditional computer side of things will go easy and be quick. We are kinda concerned about the progress of the ECE team, we haven't heard from them. During the rocket meeting next week we should hear from them. All our data we will be visualizing is coming from their setup so we are working the other direction towards that. Hopefully things are going well for them. I am purchasing a beagle bone for testing and later for fun so we can work on the USB and radio communication.

2) *Jason Klindtworth:* We are sort of in a waiting pattern at the moment. We are waiting for the ECE members of our group to lock down some of the hardware design so we know which direction we need to take the programming part of our project. Josh is hopefully going to get his hands on a beagle-bone micro-controller this week so we can start running some tests and see what we have as far as capabilities with the hardware. We also finalized our meeting times with our new TA and had our first meeting this week. We are still in the process of figuring out when our meeting times will be for the HyRo group as a whole, but hopefully those will start pretty soon as well.

3) *Layne Noll:* Set up meeting times with TA, Rocketry group meetings, and are looking to finalize a meet time for the CS branch of the Rocketry group still. Currently as a team we are waiting for the ECE team's current hardware status so we can set up some target goals and begin furthering the progress we have on the CS side of things.

### C. Week 3

1) *Josh Asher:* We had a weird week. No class and TA had to cancel on us. We did however have our first Hybrid meeting of the term and Nancy was actually there. Which was awesome. The ECE team is coming along and we should be meeting up with them in the project here in the next few weeks. We have a slack page for the entire rocket team. Everyone is very excited and so are we about this project. The GUI hasn't made it too much further, but we are meeting all together on Sunday to do some work on it. The beagle bone and radio transceivers should be in on Monday so we can start to work on the USB communication. Hopefully python is nice to us and that is rather easy. Once the GUI is prettier we will post some picture of it and the BBB.

2) *Jason Klindtworth:* Our TA canceled our weekly meeting this week at the last minute, so we did not have a chance to meet up. We did get our code posted to github (the start of it) and we did some layout and planning for the final design. We are planning on meeting up as a group at my house on Sunday so we can get some work done. We should be able to make good progress during that time. A lot of the work we are still waiting on the ECE crew to make final decisions about their portion of the design before we are able to move forward, but hopefully that will not take too much longer.

3) *Layne Noll:* No Class this week and we had a surprise cancellation from the TA as well. We were able to touch base with the ME/EE portions of our rocket design team during the first weekly meet up for this term however. Things seem to be going well on their end and we (the CS guys) are in a bit of a holding pattern until the ECE guys make a couple component decisions. Josh and Jason have made a little headway on the python GUI and I intend on tagging in for some hands-on work on that later this coming week.

#### D. Week4

1) *Josh Asher*: Everyone got a grip on the development environment this week. We are going to make some design changes as we have ran into better ideas while coding. These will be updated in the design dock. The BBB and the Xbee transceivers came in this week, but we haven't had time to play with them yet. This will be one of the major goals for next week. We need to make sure we establish and come up with good routines to talk back and forth with the Xbees. The GUI came on a little bit and is defiantly approaching and alpha stage. Our meeting with the TA went well. We are waiting on the approaching assignments with anticipation, but we have plenty of changes and progress to report on. We plan on working on the code more next week and having a meeting with the ECE team to try and nail out a protocol.

2) *Jason Klindtworth*: The group meeting on Sunday was very successful. We were able to get our development environment set up and working and also made quite a bit of progress on the layout of the UI. The graphs and buttons are going to need some additional work but so far they are looking good. We had class this week and got some more information about the upcoming assignments for the class and we are planning on getting together again this weekend to work on the progress report video and make more progress on the UI. We still cannot work on the backend of our program yet without further progress from the ECE team, but we will keep in touch with them and hopefully be able to get started on it soon.

3) *Layne Nolli*: This week we discussed design idea changes and got a good handle on what the cross disciplinary teams were up to. Josh picked up the hardware we are going to use for testing and development, so huge props to him. Development on alpha is getting going, we have a basic UI and placeholder data in place.

#### E. Week 5

1) *Josh Asher*: We have made significant progress this week on our code. We have successfully got the BBB connected to its XBee and the other XBee connected to a laptop. This was tricky at first, we had to find the correct python library to use and there was some issues when initially trying to setup the XBee's. We learned by using the Digi program XCTU we could modify the XBee's addresses and set their mode. At first we couldn't get the XBee's to talk and when we sent a message the whole program would crash. This is because we did not have the transceivers in API mode. This is the only mode our python library would function in! After that was figured out we did some test sends and receives. In our program we are now developing a thread that will run parallel to the main program that is in charge of sending and receiving message between the computer and beagle bone. When it receives a message it will place into a queue that will be processed by the main thread. We have got a deadline for our progress report and document revisions so we are setting up meetings to hammer these out. We are going to do our video on Sunday at Jason's. From here out we first plan to get our written assignments done then start coding the data structures and get data feeding into the gauges and graphs.

2) *Jason Klindtworth*: This week we started working on our revisions for the upcoming assignments. We also worked on finalizing our development environment and got to work on some code, we got the Xbee radio transceiver connected and talking with our software, which is a major step. We were pretty busy as a group this week and weren't able to get a whole lot done. But we are planning another meeting on Sunday to work on the video presentation and hammer out the detail of our revisions for the documents.

3) *Layne Nolli*: Learning about the hardware is going well. Josh got us caught up on the hardware he picked up for testing and we had a good opportunity during our group meeting to catch up on where the code is at and what needs to be worked on. A lot of other class work and midterms are falling due around this time so the group and the cross disciplinary groups have had their hands quite full. Going to be dealing with all of this paper revision and the presentation this week. Looking forward to making some more headway in the coming week on our code development.

## V. RETROSPECTIVE

Retrospective		
Positives	Deltas	Actions
We have an awesome client that is very easy to deal with. She is super nice and helpful not only on the project, but with resources to jobs.	Need to meet more on the weekends	We have began to meet at Jason's house and will continue to do this more often.
We were lucky enough to be guided by some of last year MIME students. They were very gracious and helped us immensely in understanding what we need to do.	Need to have better communication with our client Nancy Squires.	Next term Nancy should be able to attend our meetings and we will use this time to become more acquainted with her and her hopes for this project.
Our team members get a long very well. There has been no arguments yet and each assignment proved easy to collaborate on.	We need to get equipment and start coding	Over the winter break we plan on getting the needed supplies and meet to begin building our system
Our project is really cool. None of us knew what a hybrid rocket was! We are all very excited about launching this complicated amateur rocket	We need to tailor our software on board the rocket to the sensors the ECE chooses	We will maintain weekly communication with the ECE team and as they finalize the sensors we will adapt our generalization to the needs of those components
We have some of last years code to get ideas from	The rocket team hasn't fully formed and got to know each other	The ME students will be onboard next term and leading the meetings. We will keep close communication with them to form the bonds needed for the entire rocket team.
Our project does not seem to be extremely complicated and we believe we can meet some of our stretch goals.	We need to get an earlier start on assignments. We didn't wait to the last minute, but it would be nice to be further ahead so we can do more refining	We will start project earlier next term. This should be easier since we know each other better and have an idea of how to approach our issues.
We feel comfortable in LaTeX after much trial and error	We need to practice using git hub more. We had some issues using git hub as a team over fall term.	We are all going to watch some videos and do some practicing next term.
We have learned a lot about the software development process and what to expect in industry	We all need to get familiar with Python.	We will be starting our project over the break and getting acquainted with the language.