# OSURC Rover 2015 Electrical Box Connector Wiring

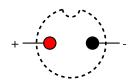
#### Nick Ames

Revision 3, 2015-03-17

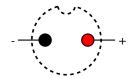
## 1 Connector Pinouts

## 1.1 Drive Motors, E-Stop, and Lights

## Jack, Solder Side



Pin #	Wire Color	Name	Description
1		-	Negative or Motor Black
2		+	Positive or Motor Red

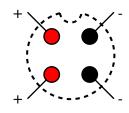


Cable, Solder Side

Figure 1: Drive Motors, E-Stop, and Lights

## 1.2 Main Power Input

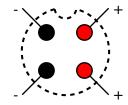
## Jack, Solder Side



Pin #	Wire Color	Name	Description
1		-	Gnd
2		-	Gnd
3		+	24V In
4		+	24V In

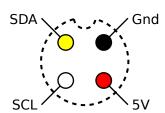
Figure 2: Gimbal Sensor

# Cable, Solder Side



## 1.3 Gimbal Sensor

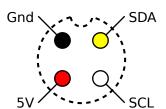
## Jack, Solder Side



Pin #	Wire Color	Name	Description
1		Gnd	Gnd
2		5V	5V
3		$\operatorname{SCL}$	I2C Clock
4		SDA	I2C Data

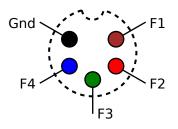
Figure 3: Gimbal Sensor

# Cable, Solder Side



#### 1.4 Arm Force Sensors

# Jack, Solder Side



#### Pin # Wire Color Description Name F1 Force Ch. 1 1 2 F2 Force Ch. 2 F3 Force Ch. 3 3 F4 Force Ch. 4 4 5 Gnd Gnd Note: Use 6-conductor cable.

## Cable, Solder Side

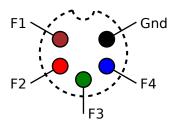
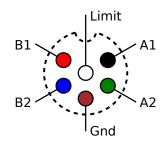


Figure 4: Arm Force Sensors

### 1.5 Arm Stepper Motors

## Jack, Solder Side



Pin #	Wire Color	Name	Description
1		A1	Coil A-1
2		A2	Coil A-2
3		Gnd	Gnd
4		B2	Coil B-2
5		B1	Coil B-1
6		Limit	Limit Switch
Note: The limit connection is to the NC pin.			
Match stepper wire colors to cable wire colors.			

Cable, Solder Side

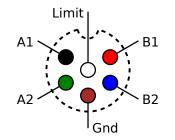
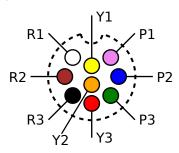


Figure 5: Arm Stepper Motors

#### 1.6 Gimbal Motors

# Jack, Solder Side



Pin #	Wire Color	Name	Description
1		P1	Pitch 1
2		P2	Pitch 2
3		P3	Pitch 3
4		Y3	Yaw 3
5		R3	Roll 3
6		R2	Roll 2
7		R1	Roll 1
8		Y2	Yaw 2
9		Y1	Yaw 1

Figure 6: Gimbal Motors

# Cable, Solder Side

