

$$f(w) = \frac{1}{2} w^T A w, \quad w \in \mathbb{R}^d, \quad A = \text{diag}(\lambda_1, \dots, \lambda_d) \succ 0$$



$$w^* = \underline{0} \in \mathbb{R}^d$$

$$\nabla_w f(w) = A w \Rightarrow w^{k+1} = w^k - \alpha A \cdot w^k$$

$$i \left\{ \begin{pmatrix} \lambda_1 \cdot w_1^k \\ \vdots \\ \lambda_d \cdot w_d^k \end{pmatrix} \right.$$

$$w_i^{k+1} = w_i^k - \alpha \cdot \lambda_i \cdot w_i^k$$

$$\uparrow = w_i^k (1 - \alpha \lambda_i)$$

$$w_i^k = w_i^{k-1} (1 - \alpha \lambda_i)$$

$$\downarrow = w_i^0 (1 - \alpha \lambda_i)^{k+1}$$

$$w_i^k \rightarrow w_i^* \quad \text{as } k \rightarrow \infty$$

$$w_i^k - w_i^* = w_i^* (1 - d\lambda_i)^k \leftarrow$$

$0 < |1 - d\lambda_i| < 1$

$$\Leftrightarrow d\lambda_i < 2$$

iff

$$d < \frac{2}{\lambda_d}$$

$$\Rightarrow w^k - w^* \rightarrow 0 \quad \text{as } k \rightarrow \infty$$

$$\begin{aligned} \text{rate}(d) &= \max_i |1 - d\lambda_i| \\ &= \max \{ |1 - d\lambda_1|, |1 - d\lambda_d| \} \end{aligned}$$

$$\min_d \max \{ |1 - d\lambda_1|, |1 - d\lambda_d| \}$$

$\stackrel{:=f_1}{\quad} \quad \quad \stackrel{:=f_2}{\quad}$

$$|1 - d\lambda_1| = |1 - d\lambda_d|$$

$$1 - d\lambda_1 = d\lambda_d - 1 \quad \checkmark$$

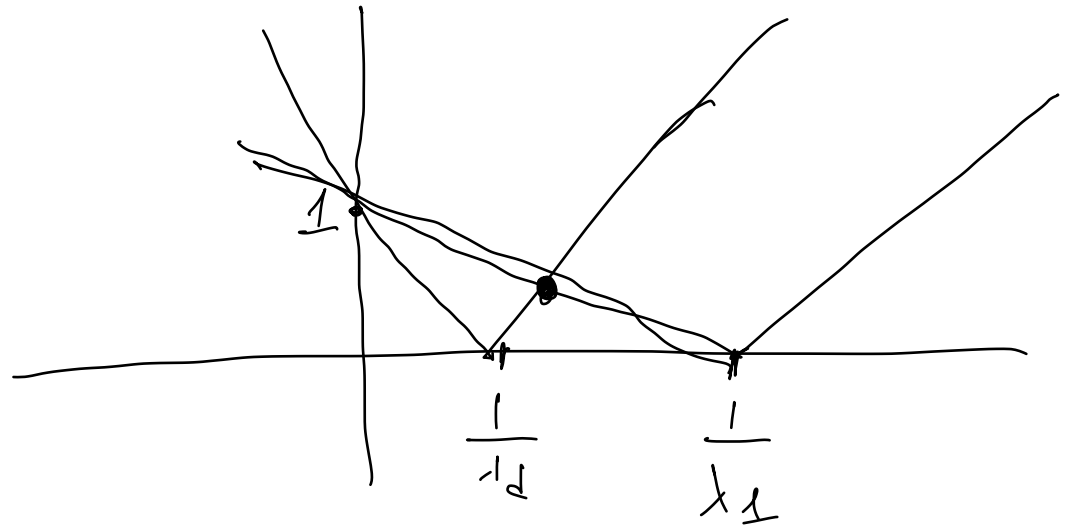
$$d^* = \frac{2}{\lambda_1 + \lambda_d}$$

learning rate d

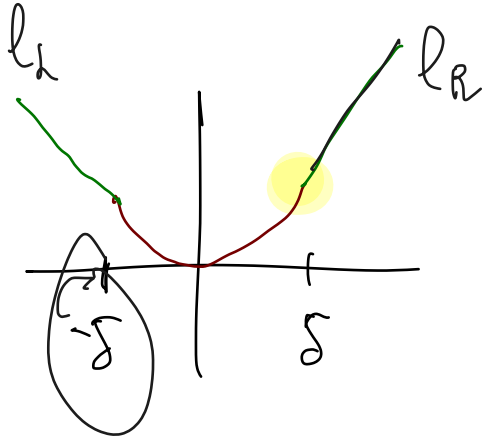
which achieves the faster rate

$$\text{rate}(d^*) = 1 - \underbrace{\frac{2}{\lambda_1 + \lambda_d}}_{d^*} \cdot \lambda_1 = \frac{\lambda_d - \lambda_1}{\lambda_d + \lambda_1} = \frac{\frac{\lambda_d}{\lambda_1} - 1}{\frac{\lambda_d}{\lambda_1} + 1}$$

$:= K$ condition number



$$\text{rate}(L^*) = \frac{k-1}{k+1}$$



$$l_{\text{huber}}(x) = \begin{cases} x^2 & \text{for } |x| \leq \delta \\ l_R & \text{for } x > \delta \leftarrow \\ l_L & \text{for } x < -\delta \end{cases}$$

Conditions to satisfy:

$$(1) l_R(x) = x^2 \text{ at } x = \delta$$

$$(3) l_R(x) = kx + c$$

$$(2) \left. \frac{d}{dx} l_R(x) \right|_{x=\delta} = \left. \frac{d}{dx} x^2 \right|_{x=\delta} = 2\delta$$

From ② $h = 2\delta \Rightarrow l_R(x) = 2\delta x + C$

From (i) $l_R(\delta) = \delta^2 \Rightarrow 2\delta^2 + C = \delta^2$
 $C = -\delta^2$

$\Rightarrow l_R(x) = 2\delta x - \delta^2$

$l_h(x) = l_R(x)$

$x = y - f(x)$

$l_{\text{huber}} = \begin{cases} x^2 & \text{for } |x| \leq \delta \\ 2\delta(|x|) - \delta^2 & \text{for } |x| > \delta \end{cases}$

$$l_{\text{huber}}^I(x) = \begin{cases} 2x & \text{if } |x| \leq \delta \\ 2\delta \operatorname{sgn}(x) & \text{else} \end{cases}$$

$$l_{\text{huber}}^{II}(x) = \begin{cases} 2 & \text{if } |x| \leq \delta \\ 0 & \text{else} \end{cases} \Rightarrow \text{convexity}$$