

Лабораторная работа №9

Задание 3

```
A = [0 1 0 0;  
-1 0 0 0;  
0 0 0 8;  
0 0 -8 0]
```

```
A = 4x4  
    0    1    0    0  
   -1    0    0    0  
    0    0    0    8  
    0    0   -8    0
```

```
B = [0; 7; 0; 6]
```

```
B = 4x1  
    0  
    7  
    0  
    6
```

```
C = [0 4 1 0]
```

```
C = 1x4  
    0    4    1    0
```

Определяем собственные числа

```
eig(A)
```

```
ans = 4x1 complex  
    0.0000 + 1.0000i  
    0.0000 - 1.0000i  
    0.0000 + 8.0000i  
    0.0000 - 8.0000i
```

Выберем различные значения желаемой степени устойчивости α

```
a_1 = 7
```

```
a_1 = 7
```

```
a_2 = 2
```

```
a_2 = 2
```

```
a_3 = 0.05
```

```
a_3 = 0.0500
```

Далее решаем неравенства Ляпунова

```
x_0 = [1; 1; 1; 1]
```

```
x_0 = 4x1  
    1  
    1  
    1
```

```
%m = 25

cvx_begin sdp
variable Q(4, 4)
variable Y(4, 1)
variable P(4, 4)
variable Y1(1, 4)
variable m
minimize m
Q > 0.00001*eye(4);
```

Warning: The use of strict inequalities in CVX is strongly discouraged,
because solvers treat them as non-strict inequalities. Please
consider using ">=" instead.

Warning: This linear matrix inequality appears to be unsymmetric. This is
very likely an error that will produce unexpected results. Please check
the LMI; and, if necessary, re-enter the model.

```
%P > 0.00001*eye(4);
A'*Q + Q*A + 2*a_2*Q + C'*Y'+Y*C <= 0;
```

Warning: This linear matrix inequality appears to be unsymmetric. This is
very likely an error that will produce unexpected results. Please check
the LMI; and, if necessary, re-enter the model.

```
%P*A' + A*P + 2*a_3*P + Y1'*B' + B*Y1 <= 0;
%[P x_0;
%   x_0' 1] > 0;
%[P Y1';
%   Y1 m] > 0;
cvx_end
```

Calling SDPT3 4.0: 41 variables, 6 equality constraints

```
-----

num. of constraints = 6
dim. of sdp var = 8, num. of sdp blk = 2
dim. of free var = 21 *** convert ublk to lblk
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM 1 0.000 1 0
it pstep dstep pinfeas dinfeas gap prim-obj dual-obj cputime
-----
0|0.000|0.000|8.8e+01|1.2e+02|7.6e+04| 1.151612e-09 0.000000e+00| 0:0:00| chol 1 1
1|0.902|0.826|8.7e+00|2.1e+01|3.0e+03|-3.605634e+00 1.063717e-03| 0:0:00| chol 1 1
2|1.000|0.699|2.1e-05|6.3e+00|3.8e+02|-1.029551e+01 8.912928e-04| 0:0:00| chol 1 1
3|1.000|0.530|5.7e-05|3.0e+00|1.2e+02|-4.001716e+01 4.047638e-04| 0:0:00| chol 1 1
4|1.000|0.055|1.7e-05|3.6e+00|3.4e+03|-1.078968e+04 3.819292e-04| 0:0:00| chol 1 1
5|1.000|0.215|1.9e-06|2.8e+00|5.3e+03|-1.964356e+05 2.857012e-04| 0:0:00| chol 1 1
6|1.000|0.022|1.4e-06|3.5e+00|1.0e+08|-3.361483e+08 2.794401e-04| 0:0:00| chol 1 1
7|1.000|0.001|2.7e-04|4.3e+00|3.8e+09|-6.236824e+09 2.758455e-04| 0:0:00| chol 1 1
8|1.000|0.086|1.3e-06|4.7e+00|3.4e+10|-4.426867e+10 2.576734e-04| 0:0:00| chol 1 1
9|1.000|0.186|9.4e-05|4.6e+00|1.8e+11|-2.362484e+11 2.054060e-04| 0:0:00| chol 1 1
10|1.000|0.303|4.0e-05|3.2e+00|2.8e+11|-1.316101e+12 1.460393e-04| 0:0:00| chol 1 1
11|1.000|0.158|3.1e-04|3.5e+00|1.4e+13|-4.409796e+13 1.218703e-04| 0:0:00| chol 2 2
```

```

12|1.000|0.111|3.2e-04|3.9e+00|3.6e+14|-7.582494e+14 1.070751e-04| 0:0:00| chol 2 2
13|1.000|0.091|3.3e-02|4.4e+00|4.7e+15|-7.377127e+15 9.945021e-05| 0:0:00| chol 2 2
stop: primal infeas has deteriorated too much, 2.1e+00
14|1.000|0.131|3.3e-02|4.4e+00|4.7e+15|-7.377127e+15 9.945021e-05| 0:0:00|
prim_inf,dual_inf,relgap = 3.31e-02, 4.38e+00, 6.43e-01
sqlp stop: dual problem is suspected of being infeasible
-----
number of iterations = 14
residual of dual infeasibility
certificate X = 1.68e-07
reldist to infeas. <= 3.29e-09
Total CPU time (secs) = 0.25
CPU time per iteration = 0.02
termination code = 2
DIMACS: 1.9e-06 0.0e+00 3.4e+00 0.0e+00 -1.0e+00 2.7e-02
-----

-----
Status: Unbounded
Optimal value (cvx_optval): -Inf

```

```
%m
```

И находим матрицу регулятора K:

```
%K = Y1*inv(P)
L = inv(Q)*Y
```

```

L = 4x1
    9.7763
   -4.4609
    0.4160
   -11.2644

```

Далее определим корни матрицы A+BK:

```
LC = eig(A+L*C)
```

```

LC = 4x1 complex
   -5.0941 + 1.7666i
   -5.0941 - 1.7666i
   -3.6197 + 8.8481i
   -3.6197 - 8.8481i

```

```
%BK = eig(A+B*K)
```