

Binary phase mask for extending depth-of-field

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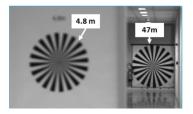
Designing the phase mask

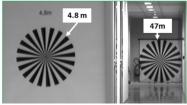
Obtained results

Introduction

Introduction

- Objective: Extend the depth of field.
- First Solution: Reduce the aperture of the system → This limits the amount of light reaching the sensor, affecting the image quality and brightness.
- Second Solution: Use a binary phase mask.
- Wiener filter: Enhance the quality of the final image.



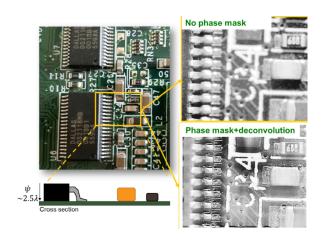




Expected result of the binary phase mask [1]

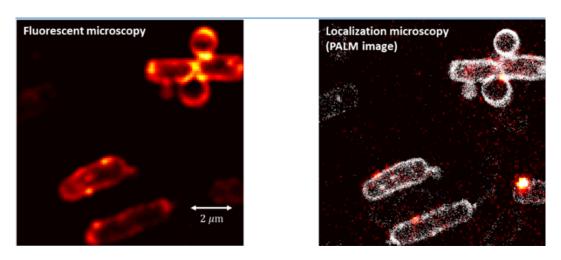
[1] https://www.lcf.institutoptique.fr/groupes-de-recherche/imagerie-etinformation/equipe-co-conception/co-design-optique/profondeur-de-champ.

Use cases



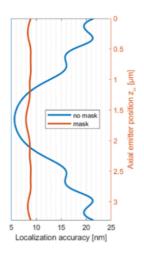
[2] https://www.institutoptique.fr/offres-emploi/these-conception-conjointe-demasques-de-phase-et-dalgorithmes-pour-la-microscopie-de?.

Use cases



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Physics Context

Physics Context

Defocus

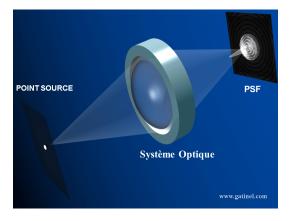
Defocus refers to the optical phenomenon where an image is blurred due to the lack of perfect convergence of light rays from a point source on the sensor plane. This is caused by deviations in focus. The defocus parameter ψ can be expressed as:

$$\psi = \frac{\pi R^2}{\lambda} \left(\frac{1}{f} - \frac{1}{d_0} - \frac{1}{d_i} \right)$$

where:

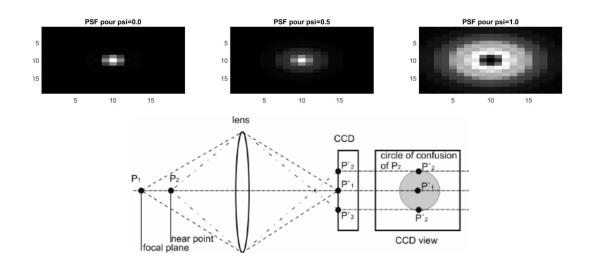
- f: Focal length of the lens.
- d_0 : Distance of the object from the lens.
- d_i : Distance of the image plane from the lens.
- R: Aperture radius.
- λ : Wavelength of the light.

PSF

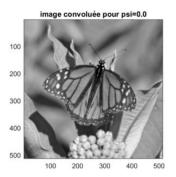


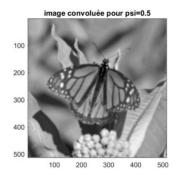
[3] https://www.gatinel.com/recherche-formation/acuite-visuelle-definition/psf

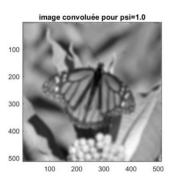
PSF



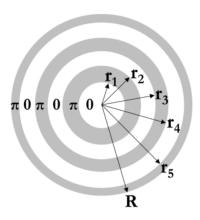
PSF





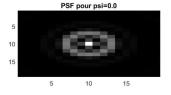


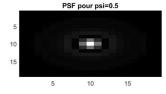
Binary phase mask

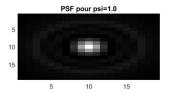


[1] https://www.lcf.institutoptique.fr/groupes-de-recherche/imagerie-et-information/equipe-co-conception/co-design-optique/profondeur-de-champ

Binary phase mask







Imaging model

Given a perfect scene O(r), the PSF of the system $h_{\psi}(r)$ and measurement noise n(r) the obtained scene is:

$$I_{\psi}(r) = \frac{h_{\psi}(r)}{r} * O(r) + n(r)$$

$$h_{\psi}(r) = \left| F\{P(r) \exp[i(\phi(r) + \psi r^2)] \} \right|^2$$

Defocus:
$$\psi = \frac{\pi R^2}{\lambda} \left(\frac{1}{f} - \frac{1}{d_o} - \frac{1}{d_i} \right)$$

Phase mask function: $\phi(r)$

Deconvolution

Our goal is to get an accurate estimator of the original scene:

$$\hat{O}_{\psi}(r) = d(r) * I_{\psi}(r)$$

where d(r) is a linear deconvolution filter.

How do we choose this filter?

Criteria

For a specific defocus ψ we define the mean squared error:

$$MSE_{\psi} = \langle |\hat{O}_{\psi}(r) - O(r)|^2 \rangle$$

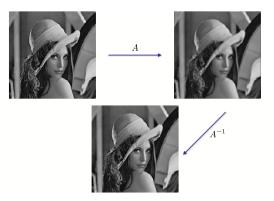
We want to design d(r) to minimize the MSE averaged over n_{MSE} defocus values:

$$MSE_{mean} = \frac{1}{n_{MSE}} \sum_{i=1}^{n_{MSE}} MSE_{\psi_i}$$

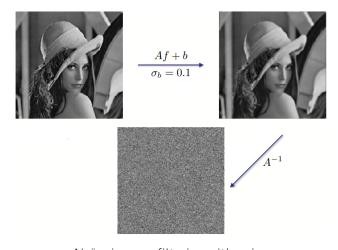
where $\psi_i \in [0, \psi_{\text{defoc max}}]$ are n_{MSE} uniformly distributed defocus values.

Context: Wiener filters

Why don't we just filter with the inverse of the PSF?



Naïve inverse filtering without noise



Naïve inverse filtering with noise

Wiener filter

Minimizing the MSE for a particular defocus value ψ :

$$\tilde{d}(\nu) = \frac{\tilde{h}_{\psi}^*(\nu)}{|\tilde{h}_{\psi}(\nu)|^2 + \frac{S_{nn}(\nu)}{S_{OO}(\nu)}}.$$

where $S_{nn}(\nu) = |\tilde{n}(\nu)|^2$, $S_{OO}(\nu) = |O(\nu)|^2$ (Power Spectral Densities)

Averaged Wiener filter

Ideal filter that minimizes the averaged MSE [4]:

$$\tilde{d}(\nu)_{\text{mean}} = \frac{\frac{1}{n_d} \sum_{i=1}^{n_d} \tilde{h}_{\psi_i}^*(\nu)}{\frac{1}{n_d} \sum_{i=1}^{n_d} |\tilde{h}_{\psi_i}(\nu)|^2 + \frac{S_{nn}(\nu)}{S_{OO}(\nu)}}.$$

where $\psi_i \in [0, \psi_{\text{defoc max}}], \quad S_{nn}(\nu) = |\tilde{n}(\nu)|^2, \quad S_{00}(\nu) = |O(\nu)|^2,$

[4] F. Diaz, F. Goudail, B. Loiseaux, and J.-P. Huignard, "In-crease in depth of field taking into account deconvolution by optimization of pupil mask," Opt. Lett. 34, 2970–2972 (2009).

How to assess the reconstructions?

Restored image quality (RIQ)

$$RIQ_{\psi}(dB) = 10 \log_{10} \left[\frac{\int S_{00}(\nu) d\nu}{MSE_{\psi}} \right]$$

$$RIQ_{\text{mean}}(\text{dB}) = 10 \log_{10} \left[\frac{\int S_{00}(\nu) \, d\nu}{MSE_{\text{mean}}} \right]$$

- 1. Choose an image which we consider the perfect undisturbed scene O(r)
- 2. Convolve this image by a simulated PSF $h_{\psi}(r)$ (defocus ψ + phase mask $\phi(r)$).
- 3. Add noise: $I_{\psi}(r) = h_{\psi}(r) * O(r) + n(r)$
- 4. Restore the original image with the Wiener Filter: $\hat{O}_{\psi}(r) = d(r) * I_{\psi}(r)$
- 5. Compute Mean Squared Error: $MSE_{\psi} = \langle |\hat{O}_{\psi}(r) O(r)|^2 \rangle$
- 6. Compute spectral power of the image: $S_{00}(\nu) = |O(\nu)|^2$
- 7. Compute Restored Image Quality criterion: $RIQ_{\psi}(\mathsf{dB}) = 10 \log_{10} \left[\frac{\int S_{00}(\nu) \, \mathrm{d}\nu}{MSE_{\psi}} \right]$

Optimal value for the radius r_1 of a single ring mask: Minimax approach

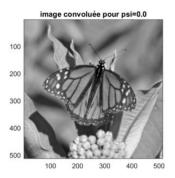
Algorithm 1 Optimization of Radius with RIQs

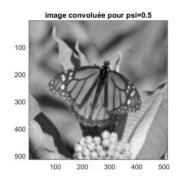
- 1: Initialization:
- 2: Define range of radius candidates rs
- 3: Define a range of defocus values psis
- 4: Initialize an empty array minRIQs
- 5: for each radius r in rs do
- 6: Initialize temporary array for RIQ values RIQs
- 7: for each defocus ψ in psis do
- 8: Simulate imaging model from a noiseless image
- 9: Compute reconstruction
- 10: Compute RIQ and store in RIQs
- 11: end for
- 12: For the current radius, store the minimum value of RIQs in minRIQs
- 13: end for
- 14: Output the radius corresponding to the highest RIQ in minRIQs

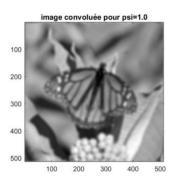
Designing a 3-ring mask: We do the same but with a (r_1, r_2) pair of values!

Obtained results

Original effect of defocus







Using 1-ring mask







Using 3-ring mask







