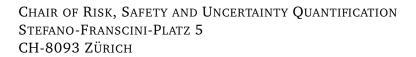


UQLAB USER MANUAL KRIGING (GAUSSIAN PROCESS MODELLING)

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Abstract

Kriging is a stochastic interpolation algorithm that has applications in various engineering and applied mathematics fields. UQLAB metamodelling tools provide an efficient, modular and easy to use Kriging module that allows one to obtain efficient Kriging predictors with minimal effort. For the experienced users there are numerous configuration options that can be easily set. This guide includes an extensive manual of the Kriging metamodelling module that is divided into three parts:

- A short introduction to the main concepts and techniques behind Kriging, with a selection of references to the relevant literature
- A detailed example-based guide, with explanation of most of the available options and methods
- ullet A comprehensive reference list of all the available functionalities of the module in UQLAB.

Keywords: UQLAB, Kriging, Gaussian process metamodelling

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Chapter 1

Theory

1.1 Kriging basics

Kriging (a.k.a. Gaussian process modelling) is a stochastic interpolation algorithm which assumes that the model output $\mathcal{M}(x)$ is a realization of a Gaussian process indexed by $x \in \mathcal{D}_X \subset \mathbb{R}^M$. A Kriging metamodel is described by the following equation (Santner et al., 2003):

$$\mathcal{M}^{K}(\boldsymbol{x}) = \boldsymbol{\beta}^{T} \boldsymbol{f}(\boldsymbol{x}) + \sigma^{2} Z(\boldsymbol{x}, \omega)$$
(1.1)

The first term in Eq. (1.1), $\beta^T f(x)$, is the mean value of the Gaussian process (a.k.a. trend) and it consists of the regression coefficients $\{\beta_j, j=1,\ldots,P\}$ and the basis functions $\{f_j, j=1,\ldots,P\}$. The second term in Eq. (1.1) consists of σ^2 , the (constant) variance of the Gaussian process and $Z(x,\omega)$, a zero mean, unit variance, stationary Gaussian process. The underlying probability space is represented by ω and is defined in terms of a correlation function R (a.k.a. correlation family) and its hyperparameters θ . The correlation function $R = R(x, x'; \theta)$ describes the correlation between two samples of the input space, e.g.x and x' and depends on the hyperparameters θ .

In the context of metamodelling, it is of interest to calculate a prediction $\mathcal{M}^K(x)$ for a new point x, given $\mathcal{X} = \{x_1, \ldots, x_n\}$, the experimental design and $y = \{y_1 = \mathcal{M}(x_1), \ldots, y_n = \mathcal{M}(x_n)\}^T$, the corresponding (noise-free) model responses. A Kriging metamodel (a.k.a. Kriging predictor) provides such predictions based on the Gaussian properties of the process.

The Gaussian assumption states that the vector formed by the true model responses, y and the prediction, $\hat{Y}(x)$, has a joint Gaussian distribution defined by:

where:

F is the information matrix of generic terms:

$$F_{ij} = f_i(\boldsymbol{x}_i), i = 1, \dots, N, j = 1, \dots, P$$

r(x) is the vector of cross-correlations between the prediction point x and each one of the observations whose terms read:

$$\mathbf{r}_i = R(\mathbf{x}, \mathbf{x}_i; \boldsymbol{\theta}), \ i = 1, \dots, N \tag{1.3}$$

R is the correlation matrix whose terms read:

$$R_{ij} = R(\boldsymbol{x}_i, \boldsymbol{x}_j; \boldsymbol{\theta}), \ i, j = 1, \dots, N$$
(1.4)

Consequently, the mean and variance of the Gaussian random variate $\hat{Y}(x)$ (a.k.a. mean and variance of the Kriging predictor) can be calculated (Santner et al., 2003; Dubourg, 2011):

$$\mu_{\hat{Y}}(\boldsymbol{x}) = \boldsymbol{f}(\boldsymbol{x})^T \boldsymbol{\beta} + \boldsymbol{r}(\boldsymbol{x})^T \boldsymbol{R}^{-1} (\boldsymbol{y} - \boldsymbol{F} \boldsymbol{\beta})$$
(1.5)

$$\sigma_{\hat{Y}}^{2}(x) = \sigma^{2} \left(1 - r^{T}(x)R^{-1}r(x) + u^{T}(x)(F^{T}R^{-1}F)^{-1}u(x) \right)$$
(1.6)

where:

$$\boldsymbol{\beta} = \left(\boldsymbol{F}^T \boldsymbol{R}^{-1} \boldsymbol{F} \right)^{-1} \boldsymbol{F}^T \boldsymbol{R}^{-1} \boldsymbol{y} \tag{1.7}$$

is the generalized least-squares estimate of the underlying regression problem and

$$\boldsymbol{u}(\boldsymbol{x}) = \boldsymbol{F}^T \boldsymbol{R}^{-1} \boldsymbol{r}(\boldsymbol{x}) - \boldsymbol{f}(\boldsymbol{x}) \tag{1.8}$$

Another useful corollary of the Gaussian assumption is that:

$$\hat{Y}(\boldsymbol{x}) \sim \mathcal{N}\left(\mu_{\hat{Y}}(\boldsymbol{x}), \sigma_{\hat{Y}}^2(\boldsymbol{x})\right)$$
 (1.9)

Thus:

$$\mathcal{P}\left[\hat{Y}(\boldsymbol{x}) \leq t\right] = \Phi\left(\frac{t - \mu_{\hat{Y}}(\boldsymbol{x})}{\sigma_{\hat{Y}}(\boldsymbol{x})}\right)$$
(1.10)

where $\Phi(\cdot)$ denotes the Gaussian cumulative density function. Note that this is the probability that $\hat{Y}(x)$ is smaller than t at a given x. This shall not be confused with a probability of failure computed in the framework of rare event simulation (see UQLAB User Manual – Structural Reliability). Based on Eq. (1.10) the confidence intervals on the predictor can be calculated by:

$$\hat{Y}(\boldsymbol{x}) \in \left[\mu_{\hat{Y}}(\boldsymbol{x}) - \Phi^{-1} \left(1 - \frac{\alpha}{2} \right) \sigma_{\hat{Y}}(\boldsymbol{x}) , \ \mu_{\hat{Y}}(\boldsymbol{x}) + \Phi^{-1} \left(1 - \frac{\alpha}{2} \right) \sigma_{\hat{Y}}(\boldsymbol{x}) \right]$$
(1.11)

with probability $1 - \alpha$.

In practice, in order to obtain a Kriging metamodel, the following steps are needed:

- Select the functional basis of the Kriging trend. This is further discussed in Section 1.2.
- Select the appropriate correlation function $R(x, x'; \theta)$. This is further discussed in Section 1.3.
- If the hyperparameters θ and the Gaussian process variance σ^2 are unknown (which is usually the case) get an estimate of those. This involves setting up an optimization problem (see Section 1.4) and solving it (see Section 1.5).

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• Using the optimal value of θ , the rest of the unknown Kriging parameters (σ^2, β) can be calculated.

Then predictions for new points can be made in terms of the mean and variance of $\hat{Y}(x)$, using Eqs. (1.5), (1.6).

A one-dimensional Kriging example is shown in Figure 1. Given a set of observations of some model, a Kriging predictor returns the mean and the variance of a Gaussian process that interpolates them. Using Eq. (1.11), the 95% confidence interval of the predictor is also calculated.

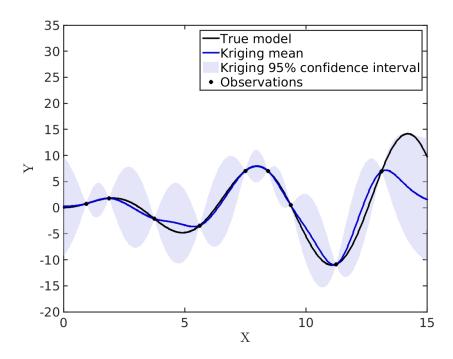


Figure 1: An example of a Kriging metamodel.

1.2 Trend types

The trend refers to the mean of the Kriging metamodel, that is the term $\beta^T f(x)$ in Eq. (1.1). Using a non-zero trend is optional but is however commonly preferred. Note that the mean of the Kriging predictor in Eq. (1.5) is not confined to be zero when the trend is zero. In the literature, a different naming is given to the Kriging metamodel depending on the type of trend that is used, (Dubourg, 2011), namely:

• *Simple Kriging*: The trend has a *known* constant value:

$$\boldsymbol{\beta}^T \boldsymbol{f}(\boldsymbol{x}) = \beta_0$$

Notice that no regression takes place in this case since the trend is known.

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• Ordinary Kriging: The trend has a constant yet unknown value:

$$\boldsymbol{\beta}^T \boldsymbol{f}(\boldsymbol{x}) = \beta_1 f_1(\boldsymbol{x}) = \beta_1$$

since $f_1(x) = 1$.

• *Universal Kriging*: This is the most general and flexible formulation. It assumes that the trend is a linear combination of prescribed functions, *e.g.* polynomials:

$$oldsymbol{eta}^T oldsymbol{f}(oldsymbol{x}) = \sum_{j=1}^P eta_j f_j(oldsymbol{x})$$

From the above it is clear that simple and ordinary Kriging are special cases of universal Kriging. In the current version of UQLAB, the basis functions can be either constants or polynomials or any other user-defined function.

1.2.1 Commonly used trends

The most commonly used trends are summarized in Table 1.

Table 1: Trend options combinations			
Trend	Formula		
constant (ordinary Kriging)	β_0		
linear	$\beta_0 + \sum_{i=1}^M \beta_i x_i$		
quadratic	$\beta_0 + \sum_{i=1}^{i-M} \beta_i x_i + \sum_{i=1}^{M} \sum_{j=1}^{M} \beta_{ij} x_i x_j$		

The multivariate polynomial trends that are given in Table 1 can be written in a more compact and general form as follows:

$$F(x) = \sum_{\alpha \in \mathcal{A}^{M,P}} \beta_{\alpha} f_{\alpha}(x), f_{\alpha}(x) = \prod_{i=1}^{M} x^{\alpha_i}$$
(1.12)

where $\alpha = \{\alpha_1, \dots, \alpha_M\}$ is a vector of indices and $\mathcal{A}^{M,P} = \{\alpha : |\alpha| \leq P\}$ denotes the set of indices that correspond to all polynomials in the M input variables up to degree P.

The Kriging module in UQLAB offers the possibility to use as a trend a multivariate polynomial of arbitrary degree P (as described in Eq. (1.12)) as well as different types of basis functions. For more information see Section 2.4.2 and Section 3.1.2 for a list of all the available options regarding the trend.

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1.3 Correlation functions

The correlation function (also called *kernel* or *covariance*¹ function in the literature) is a crucial ingredient for a Kriging predictor, since it contains the assumptions about the function we want to learn. Generally speaking, it describes the "similarity" between observations and new points, i.e. how similar such points are, depending on their distance. Close input points in that sense are then expected to have similar outputs y.

An arbitrary function of (x, x') is in general not a valid correlation function. The necessary conditions for a function R(x, x') to be a correlation function are:

- The correlation (or Gram) matrix whose elements are computed as $R_{ij} = R(x_i, x_j)$, $(x_i, x_j) \in \mathcal{X} \times \mathcal{X}$ is positive semi-definite (PSD) for any choice of number of samples N and experimental design \mathcal{X} .
- It is symmetric, i.e. $R(x, x') = R(x', x), \forall x', x \in \mathcal{D}_X$

In general it can be expressed in the form $R(x, x'; \theta)$ where θ is a vector that contains a set of parameters. Typically $\theta \in \mathbb{R}^M$ yet this is not necessarily true in the general case, since more than one element can correspond to each input dimension. In the current stage, it is assumed however that one element of θ is used per dimension for notational clarity.

1.3.1 Correlation function types

When the input dimension M is greater than 1 the following different types of correlation functions exist in the current version of UQLAB:

• *Ellipsoidal* correlation functions (Rasmussen and Williams, 2006). They are calculated as follows:

$$R(\boldsymbol{x}, \boldsymbol{x}'; \boldsymbol{\theta}) = R(h) , h = \sqrt{\sum_{i=1}^{M} \left(\frac{x_i - x_i'}{\theta_i}\right)^2}$$
 (1.13)

• Separable correlation functions (Sacks et al., 1989; Dubourg, 2011). They are calculated as

$$R(\boldsymbol{x}, \boldsymbol{x}'; \boldsymbol{\theta}) = \prod_{i=1}^{M} R(x_i, x_i', \theta_i)$$
 (1.14)

The function $R(\cdot)$ that appears on the right hand side of Eqs. (1.13), (1.14) corresponds to one-dimensional correlation functions also known as *correlation families*. The ones that are currently available in UQLAB can be found in Section 1.3.3.

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¹The covariance function corresponds to the correlation function multiplied by the variance of the Gaussian process σ^2 .

1.3.2 Isotropic correlation functions

The expressions of the different correlation functions that were given in Section 1.3.1 correspond to the *anisotropic* case. Generally speaking, a correlation function is called *isotropic* when it has the same behavior over all dimensions. In that sense, for each type of correlation function, the isotropy is defined as follows:

• Isotropic ellipsoidal correlation function:

$$R(\boldsymbol{x}, \boldsymbol{x}'; \theta) = R\left(\frac{1}{\theta}\sqrt{\sum_{i=1}^{M}(x_i - x_i')^2}\right), \ \theta \in \mathbb{R}$$
 (1.15)

• Isotropic separable correlation function:

$$R(\boldsymbol{x}, \boldsymbol{x}'; \theta) = \prod_{i=1}^{M} R(x_i, x_i'; \theta), \ \theta \in \mathbb{R}$$
(1.16)

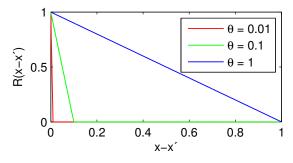
1.3.3 Correlation families

For each of the available correlation families, the function is plotted in Figures 2-6 together with a realization of a zero-mean, unit variance Gaussian process having this correlation function.

• Linear.

It is defined as:

$$R(h;\theta) = \max\left(0, 1 - \frac{|h|}{\theta}\right) \tag{1.17}$$



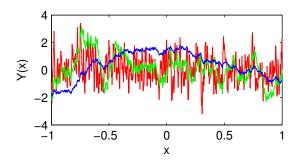


Figure 2: The linear correlation function and some sample paths of the corresponding zeromean unit-variance Gaussian process for various scale parameters.

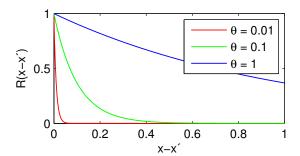
• Exponential.

It is defined by

$$R(h;\theta) = \exp\left(-\frac{|h|}{\theta}\right) \tag{1.18}$$

Its sample paths are C^0 , i.e. continuous but non-differentiable.

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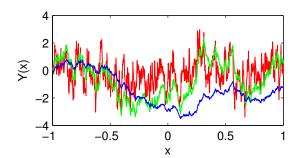
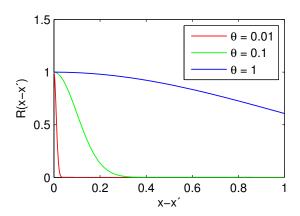


Figure 3: The exponential correlation function and some sample paths of the corresponding zero-mean unit-variance Gaussian process for various scale parameters.



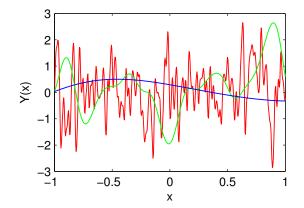


Figure 4: The Gaussian correlation function and some sample paths of the corresponding zero-mean unit-variance Gaussian process for various scale parameters.

• Gaussian (or squared exponential).

It is defined by

$$R(h;\theta) = \exp\left(-\sum_{i=1}^{M} \left(\frac{h}{\theta}\right)^{2}\right)$$
 (1.19)

Its sample paths are infinitely differentiable.

• Matérn.

The general form of the Matérn correlation function is given by

$$R(h; \theta, v) = \frac{1}{2^{v-1}\Gamma(v)} \left(2\sqrt{v}\frac{|h|}{\theta}\right)^{v} \mathcal{K}_{v}\left(2\sqrt{v}\frac{|h|}{\theta}\right)$$
(1.20)

where θ_i are the so-called scale parameters, $v \geq 1/2$ is the shape parameter, Γ is the Euler Gamma function and \mathcal{K}_v is the modified Bessel function of the second kind (also known as the Bessel function of the third kind). For more information see Abramovitz and Stegun (1965)).

An interesting feature of this family of correlation functions is that the sample paths of the corresponding Gaussian process are $\lceil v-1 \rceil$ times differentiable, where $\lceil \cdot \rceil$ denotes the ceiling function. For v=1/2 Matérn kernel coincides with the exponential

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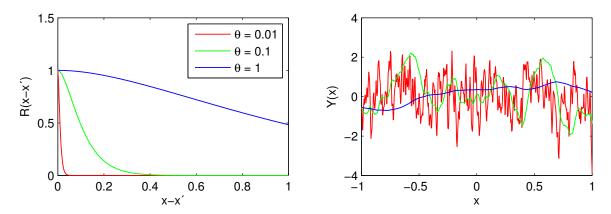


Figure 5: The Matérn 3/2 correlation function and some sample paths of the corresponding zero-mean unit-variance Gaussian process for various scale parameters.

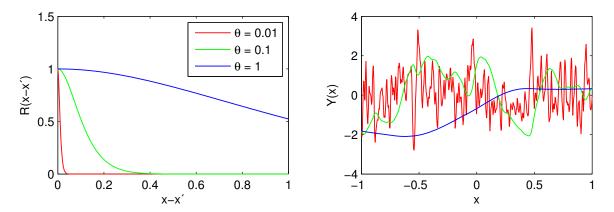


Figure 6: The Matérn 5/2 correlation function and some sample paths of the corresponding zero-mean unit-variance Gaussian process for various scale parameters.

correlation function which generates \mathcal{C}^0 sample paths. For $v \to \infty$ its tends towards the Gaussian correlation function which generates \mathcal{C}^∞ sample paths.

The Matérn functions can be calculated using simplified formulas when v=p+1/2 where p is a non-negative integer (Rasmussen and Williams, 2006). So far, the Matérn functions with v=3/2 and v=5/2 (abbreviated as Matérn-3/2 and Matérn-5/2 respectively) have been implemented. These types are the most commonly used. Their formulas are given next. For v=3/2:

$$R(h; \theta, v = 3/2) = \left(1 + \frac{\sqrt{3}|h|}{\theta}\right) \exp\left(-\frac{\sqrt{3}|h|}{\theta}\right)$$
 (1.21)

and for v = 5/2:

$$R(h; \theta, v = 5/2) = \left(1 + \frac{\sqrt{5}|h|}{\theta} + \frac{\sqrt{5}h^2}{2\theta^2}\right) \exp\left(-\frac{\sqrt{5}|h|}{\theta}\right)$$
(1.22)

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Note: When using one of the above correlation families to build an anisotropic ellipsoidal correlation function we treat them as $R = R(\overline{h})$ where $\overline{h} = \frac{|h|}{\theta}$.

1.4 Estimation methods

In order to obtain a Kriging metamodel as in Eq. (1.1), usually the hyperparameters θ are unknown and need to be estimated. This is achieved by solving an optimization problem that differs depending on the estimation method that is used. The estimation methods that are available in UQLAB are discussed in the following subsections.

1.4.1 Maximum Likelihood

The idea behind this method is to find the set of parameters β, σ^2, θ such that the likelihood of the observations $y = \{\mathcal{M}(x_1), \dots, \mathcal{M}(x_N)\}^T$ is maximal. Since y follows a multivariate Gaussian distribution (recall basic Kriging assumptions), the likelihood function $L(y \mid \beta, \sigma^2, \theta)$ reads as follows:

$$L(\boldsymbol{y} \mid \boldsymbol{\beta}, \sigma^2, \boldsymbol{\theta}) = \frac{\det(\boldsymbol{R})^{-1/2}}{(2\pi\sigma^2)^{N/2}} \exp\left[-\frac{1}{2\sigma^2}(\boldsymbol{y} - \boldsymbol{F}\boldsymbol{\beta})^T \boldsymbol{R}^{-1}(\boldsymbol{y} - \boldsymbol{F}\boldsymbol{\beta})\right]$$
(1.23)

By maximizing the quantity described in Eq. (1.23) one gets the following estimates of β and σ^2 that are known as the generalized least-squares estimates (for proof and more details refer to Dubourg (2011); Santner et al. (2003)):

$$\boldsymbol{\beta} = \boldsymbol{\beta}(\boldsymbol{\theta}) = \left(\boldsymbol{F}^T \boldsymbol{R}^{-1} \boldsymbol{F}\right)^{-1} \boldsymbol{F}^T \boldsymbol{R}^{-1} \boldsymbol{y}$$
 (1.24)

$$\sigma^{2} = \sigma^{2}(\boldsymbol{\theta}) = \frac{1}{N} (\boldsymbol{y} - \boldsymbol{F}\boldsymbol{\beta})^{T} \boldsymbol{R}^{-1} (\boldsymbol{y} - \boldsymbol{F}\boldsymbol{\beta})$$
(1.25)

However, they are dependent on the value of the hyperparameters θ which are calculated by solving the optimization problem:

$$\theta = \arg \min_{\mathcal{D}_{\theta}} \left(-\log L(\boldsymbol{y} \mid \boldsymbol{\beta}, \sigma^2, \boldsymbol{\theta}) \right)$$
 (1.26)

Based on equations (1.23), (1.25) the optimization problem in (1.26) can be written as follows:

$$\boldsymbol{\theta} = \arg\min_{\mathcal{D}_{\boldsymbol{\theta}}} \left(\frac{1}{2} \log(\det(\boldsymbol{R})) + \frac{N}{2} \log(2\pi\sigma^2) + \frac{N}{2} \right)$$
 (1.27)

1.4.2 Cross-Validation

The general principle of this method (also known as K-fold cross-validation) is to split the whole dataset of observations \mathcal{D} into K mutually exclusive and collectively exhaustive subsets

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 $\{\mathcal{D}_k, k=1,\ldots,K\}$ such that

$$\mathcal{D}_i \cap \mathcal{D}_j = \emptyset$$
, $\forall (i,j) \in \{1,\dots,K\}^2$ and $\bigcup_{k=1}^K \mathcal{D}_k = \mathcal{D}$ (1.28)

The k-th set of cross-validated predictions is obtained by fitting the model using all the subsets but the k-th one and predicting it on that specific k-th fold that was left apart. The leave-one-out cross-validation procedure corresponds to the special case that the number of classes is equal to the number of observations (K = N).

In this case the usual choice of objective function is (Santner et al., 2003; Bachoc, 2013):

$$\boldsymbol{\theta} = \arg \min_{\mathcal{D}_{\boldsymbol{\theta}}} \sum_{i=1}^{K} \left(\mathcal{M}(\boldsymbol{x}_i) - \mu_{\hat{Y},(-i)}(\boldsymbol{x}_i) \right)^2$$
 (1.29)

where $\mu_{\hat{Y},(-i)}(\boldsymbol{x}_i)$ is the mean Kriging predictor that was trained using all $\mathcal{X}, \boldsymbol{y}$ but $(\boldsymbol{x}_i, \boldsymbol{y}_i)$ then evaluated at this point \boldsymbol{x}_i . Notice that for the case of leave-one-out cross-validation, i is an index but in the general case i is a vector of indices.

The estimate of σ^2 is calculated using the following equation (Cressie, 1993; Bachoc, 2013):

$$\sigma^2 = \sigma^2(\boldsymbol{\theta}) = \frac{1}{K} \sum_{i=1}^K \frac{\left(\mathcal{M}(\boldsymbol{x}_i) - \mu_{\hat{Y},(-i)}(\boldsymbol{x}_i)\right)^2}{\sigma_{\hat{Y},(-i)}^2(\boldsymbol{x}_i)}$$
(1.30)

where $\sigma_{\hat{Y},(-i)}^2(x_i)$ denotes the variance of a Kriging predictor that was trained using all \mathcal{X}, y apart from x_i, y_i , evaluated at point x_i . When i is a set of indices then the division and the squared operations in Eq. (1.30) are performed element-wise.

1.5 Optimization methods

For solving the optimization problems described in (1.27) (maximum likelihood case) or (1.29) (cross-validation case) there are trade-offs for choosing some local (usually gradient-based) or global methods (usually evolutionary algorithms). On the one hand local methods tend to converge faster and require fewer objective function evaluations but on the other hand, the existence of flat regions and multiple local minimas, especially for increasing input dimension, can lead gradient methods to poor performance compared to global methods. There are also approaches that try to use features from both families (so-called hybrid methods).

An example of the objective function landscape for a one-dimensional problem is given, in Figure 7. The original model is $\mathcal{M}(x) = \left(1 + 25x^2\right)^{-1}$. The experimental design consists of 8 points as shown in Figure 7(a). The evaluation of the maximum likelihood and cross-validation criterion (to be minimized) as a function of θ is shown in Figures 7(b) and 7(c) respectively.

The optimization methods that are currently available will be briefly discussed next.

• Interior point with L-BFGS Hessian approximation

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An interior point gradient-based method is used that approximates the Hessian matrix using a Limited memory variant of the quasi-Newton Broyden-Fletcher-Goldfarb-Shanno method (Richard H. Byrd, Mary E. Hribar Y, 1999; Nocedal, 1980).

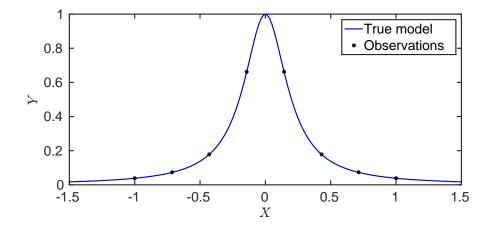
• Genetic Algorithm

This is a well-established global optimization method (Goldberg, 1989) that has been applied in many fields for the past decades. A hybrid approach can also be used, where the final solution of the genetic algorithm is used as a starting point of the gradient method that was previously mentioned.

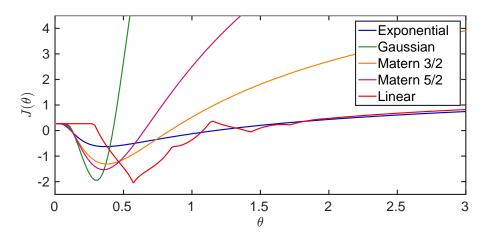
• Differential Evolution

This is another global, evolutionary optimization method (Storn and Price, 1997). An adaptive variant of this method is currently available, known as Self-adaptive Differential Evolution (SaDE) (Deng et al., 2013), as well as a hybrid variant of SaDE (HSaDE) where the optimal solution that is obtained is then refined using the L-BFGS method.

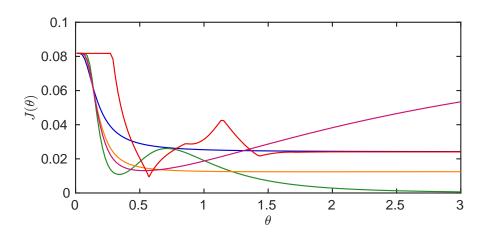
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(a) The Experimental Design, drawn from the Runge function.



(b) Maximum likelihood objective function landscape.



(c) Cross-validation objective function landscape.

Figure 7: A one-dimensional example of objective function landscapes with respect to the scale parameter θ using various correlation families.

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Chapter 2

Usage

In this section a reference problem will be set up to showcase how each of the Kriging options described in Section 1.1 can be used in UQLAB.

2.1 Reference problem

In the context of this manual Kriging is used for building a surrogate of some model given a set of observations and model responses. To this end, the following one-dimensional function is used as the true model:

$$\mathcal{M}(x) = x \sin(x) , x \sim \mathcal{U}(0, 15)$$
(2.1)

2.2 Problem set-up

The Kriging module creates a MODEL object that can be used exactly as any other. The basic options common to any Kriging metamodel read:

```
Metaopts.Type = 'uq_metamodel';
Metaopts.MetaType = 'Kriging';
```

Recalling (and slightly expanding) Eq. (1.1), a Kriging metamodel reads:

$$\mathcal{M}^{K}(\mathbf{x}) = \sum_{j=1}^{p} \beta_{j}(\boldsymbol{\theta}) f_{j}(\boldsymbol{x}) + \sigma^{2} Z(\boldsymbol{x}; \boldsymbol{R}(\boldsymbol{\theta}))$$
 (2.2)

where θ is obtained by solving an optimization problem:

$$\theta = \arg\min_{\boldsymbol{\theta} \in \mathcal{D}_a} J(\boldsymbol{\theta}) \tag{2.3}$$

In practice the objective function $J(\theta)$ is based on the choice of maximum likelihood or cross-validation estimation. Therefore, the main ingredients that need to be set up in order to obtain a Kriging metamodel are the following:

• An experimental design, \mathcal{X} , and the corresponding model responses, \mathbf{y} . If they are not available they can be generated by defining the 'true' model and a probabilistic input

vector. Note that this steps belongs to the general context of metamodelling, *i.e.* it is not specific to Kriging (see also UQLAB User Manual – Polynomial Chaos Expansions).

- A trend specification, *i.e.* selection of the type of basis functions $f_i(x)$, $j = 1, \ldots, p$.
- An appropriate correlation function $R(x, x'; \theta)$.
- A hyperparameter estimation method, *i.e.* the type of $J(\theta)$ in Eq. (2.3) and the way of estimating the Gaussian process variance $\sigma^2(\theta)$.
- A method to solve the optimization problem in Eq. (2.3).

Note that the minimal amount of information that need to be supplied by the user is the experimental design. The rest of the ingredients can either be selected and tuned by the user or just left to their default values.

2.3 Calculation of the Kriging metamodel

The minimal set of options needed in order to obtain a Kriging metamodel were discussed in Section 2.2. Below a minimal configuration example is given.

```
% start the UQLab framework
uqlab;
% Create X,Y
X = transpose(0 : 2 : 14);
Y = X.*sin(X);

% Create the Kriging metamodel
Metaopts.Type = 'uq_metamodel';
Metaopts.MetaType = 'Kriging';
Metaopts.ExpDesign.Sampling = 'user';
Metaopts.ExpDesign.X = X;
Metaopts.ExpDesign.Y = Y;
myKriging = uq_createModel(Metaopts);
```

Once the metamodel is created, a report of the Kriging results can be printed on screen by:

```
uq_print (myKriging);
%------ Kriging metamodel -----%
  Object Name: Model 1
  Input Dimension: 1

Experimental Design
   Sampling: User
   X size: [8x1]
   Y size: [8x1]

Trend
   Type: ordinary
   Degree: 0

Gaussian Process
```

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```
Corr. Type: ellipsoidal(anisotropic)
Corr. family: matern-3_2
sigma^2: 4.787983e+01
Estimation method: Cross-Validation

Hyperparameters
theta: [ 0.00100 ]
Optim. method: Hybrid Genetic Algorithm

Leave-one-out error: 4.3698313e-01

%-------%
```

It can be observed that the default values regarding the trend, correlation function, estimation and optimization method have been assigned. A visual representation of the metamodel can be obtained by:

```
uq_display(myKriging);
```

Note that uq_display for Kriging MODEL objects can only be used for one- and two- dimensional inputs. The figure produced by uq_display is shown in Figure 8.

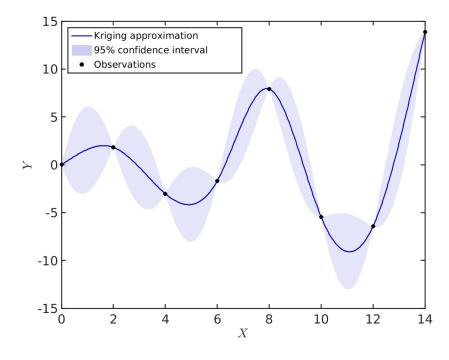


Figure 8: The output of $uq_display$ of a Kriging MODEL object having a one-dimensional input.

2.3.1 Accessing the results

The Kriging MODEL object myKriging that was created in Section 2.3 uses all the default configuration options (the were listed in the output of $uq_print(myKriging)$). We can

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directly access this object in order to obtain various results and information of the metamodel as will be discussed next.

Kriging parameters

The values of the basic parameters of the Kriging metamodel, namely θ , σ^2 , β are contained in the structure myKriging. Kriging:

Model evaluations

The experimental design and the corresponding model evaluations are stored in the myKriging. ExpDesign structure:

```
myKriging.ExpDesign
ans =
   Sampling: 'user'
   X: [8x1 double]
   Y: [8x1 double]
   NSamples: 8
   U: [8x1 double]
   time: 0.0131
```

The ExpDesign.Sampling field contains information about the generation of the sample of model evaluations. The ExpDesign.NSamples field contains the total number of full-model evaluations that were run during the calculation.

The remaining fields contain, respectively:

- ExpDesign.X: the experimental design \mathcal{X} .
- ExpDesign.Y: the full model evaluations, $y = \mathcal{M}(\mathcal{X})$.
- ExpDesign.U: the scaled experimental design. For each $x \in \mathcal{X}$, the rescaled components read:

$$u_i = \frac{x_i - \hat{\mu}_X}{\hat{\sigma}_X} \tag{2.4}$$

where the empirical mean $\hat{\mu}_X$ and standard deviation $\hat{\sigma}_X$ are calculated from the available samples \mathcal{X} (component by component).

• ExpDesign.time: the time elapsed (in seconds) in order to obtain the experimental design and the corresponding model evaluations.

A posteriori error estimates

The Leave-One-Error (LOO) of the metamodel is stored in myKriging. Error:

```
myKriging.Error
ans =
  LOO: 0.4642
```

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It is calculated as follows:

$$E_{LOO} = \frac{1}{N} \sum_{i=1}^{N} \left(\mathcal{M}(\boldsymbol{x}_i) - \mu_{\hat{Y},(-i)}(\boldsymbol{x}_i) \right)^2 / \text{Var}[Y]$$
 (2.5)

where $\mu_{\hat{Y},(-i)}(x_i)$ denotes the Kriging metamodel that is obtained by using all the points of the experimental design \mathcal{X} except x_i .

2.4 Set-up of the Kriging metamodel

In the following subsections the various configuration options of each of the ingredients of a Kriging metamodel are presented. These ingredients are summarized below:

- Metaopts.ExpDesign contains options regarding the generation or specification of the Experimental Design. The list of all available options can be found in Table 4 and the way to use each option is discussed in Section 2.4.1.
- Metaopts. Trend contains options regarding the term $\sum_{j=1}^{p} \beta_j(\boldsymbol{\theta}) f_j(\mathbf{x})$ in Eq. (2.2), see Section 1.1 for a theoretical introduction. The list of all available options can be found in Table 5 and the way to use each option is discussed in Section 2.4.2.
- Metaopts.Corr contains options regarding the correlation function that is used in order to obtain R in Eq. (2.2), see Section 1.3 for a theoretical introduction. The list of all available options can be found in Table 7 and the way to use each option is discussed in Section 2.4.3.
- Metaopts.EstimMethod refers to the method that is used for estimating the hyperparameters θ (maximum-likelihood or cross-validation). The choice of estimation method corresponds to different ways of calculating $\sigma^2(\theta)$ in Eq. (2.2) as well as $J(\theta)$ in Eq. (2.3). See Section 1.4 for a theoretical introduction of each estimation method.
- Metaopts.Optim contains options related to the method to be used for solving the optimization problem in Eq. (2.3), see Section 1.5 for a brief description of the available optimization methods. The list of all available options can be found in Table 9 and the way to use each option is discussed in Section 2.4.5.

2.4.1 Generation/Specification of the experimental design

2.4.1.1 Using already existing data

Depending on where the experimental design data is stored the following alternatives are offered:

• If data is stored in the MATLAB workspace, e.g. in the variables X, Y:

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```
Metaopts.ExpDesign.Sampling = 'user';
Metaopts.ExpDesign.X = X;
Metaopts.ExpDesign.Y = Y;
```

• If data is stored in a .mat file, e.g.mydata.mat:

```
Metaopts.ExpDesign.Sampling = 'data';
Metaopts.ExpDesign.DataFile = 'mydata.mat';
```

Note: The experimental design that is contained in mydata.mat must be saved with variable names X and Y respectively.

The input and output dimension of the problem M, N_{out} are automatically retrieved by the number of columns of x and y respectively.

2.4.1.2 Using INPUT and MODEL objects

First we have to create the probabilistic INPUT vector. For the reference problem in Eq. (2.1) this reads:

```
IOpts.Marginals.Type = 'Uniform';
IOpts.Marginals.Parameters = [0 15];
myInput = uq_createInput(Input);
```

The input and output dimension of the problem are automatically retrieved by the configuration of the INPUT object myInput and MODEL object myModel. For more information about the configuration options available of an INPUT and a MODEL object, please refer to the UQLAB User Manual – the INPUT module and the UQLAB User Manual – the MODEL module respectively.

Then we create a MODEL object as follows:

```
MOpts.mString = 'X.*sin(X)';
myModel = uq_createModel(MOpts);
```

Now we include the INPUT and MODEL objects to the Kriging metamodel configuration:

```
Metaopts.Input = myInput;
Metaopts.FullModel = myModel;
```

Finally, we need to define the size of the experimental design, e.g. for N=8 samples:

```
Metaopts.ExpDesign.NSamples = 8;
```

Note that, by default Monte Carlo sampling is used in order to obtain \mathcal{X} . However other sampling strategies can be selected through the option Metaopts. ExpDesign. Sampling, see Table 4 in Section 3.1.1 for a list of the available sampling strategies.

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2.4.2 Trend

2.4.2.1 Standard options

Some typical configuration options are the following:

- When considering a constant (*ordinary* Kriging), linear or quadratic trend the field Metaopts. Trend. Type must contain the appropriate string value, that is, 'ordinary', 'linear' and 'quadratic' respectively.
- For a polynomial trend of arbitrary degree we need to set

```
Metaopts.Trend.Type = 'polynomial';
Metaopts.Trend.Degree = q;
```

where q is an integer equal to the polynomial degree.

• For a constant trend with fixed value (*simple* Kriging) we need to set the following:

```
Metaopts.Trend.Type = 'simple';
Metaopts.Trend.CustomF = V;
```

where \vee is a real number.

A summary of the available trend options in UQLAB along with the corresponding formula and the additionally required options is given in Table 2.

Table 2: Trend options combinations			
Trend.Type	Formula	Trend.Degree	Trend.CustomF
'simple'	f(x) (no regression)	Not required	Required
'ordinary'	β_0	Not required	Not required
'linear'	$\beta_0 + \sum_{i=1}^M \beta_i x_i$	Not required	Not required
'quadratic'	$\beta_0 + \sum_{i=1}^M \beta_i x_i + \sum_{i=1}^M \sum_{j=1}^M \beta_{ij} x_i x_j$	Not required	Not required
'polynomial'	see Eq. (1.12)	Required	Not required
'custom'	$\sum_{i=1}^{P} \beta_i f_i(\boldsymbol{x})$	Not required	Required

In Figure 9 the mean and variance of various Kriging predictors having different trend configurations are plotted using the example script uq_Example_Kriging_03_TrendTypes.

Note: The field Metaopts.Trend.Type determines the trend type of a Kriging meta model. When no trend type has been defined by the user, the default Metaopts.Trend.Type = 'ordinary' is used (Ordinary Kriging).

2.4.2.2 Advanced options

• For a custom arbitrary trend, first we need to define it

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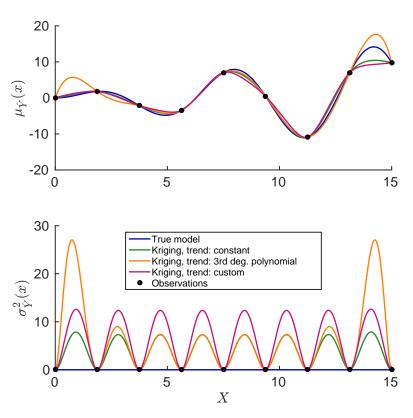


Figure 9: The output of the example scriptuq_Example_Kriging_03_TrendTypes. The mean and variance of various Kriging predictors is plotted, using different trend configurations.

```
Metaopts.Trend.Type = 'custom';
```

Then we can either define the trend as a string or a function handle. If for example the trend we want is $\sin(x)$ then

```
Metaopts.Trend.CustomF = 'sin';

or

Metaopts.Trend.CustomF = @sin;
```

The function can be any built-in MATLAB, UQLAB or user defined function (as long as it is contained in the MATLAB path). It is also possible to assign to Metaopts.Trend.CustomF a cell array of strings or function handles of arbitrary length.

In general the dimension of the information matrix F is $N \times P$. Depending on the selection of the trend type (Metaopts.Trend.Type) the value of P varies:

• When Metaopts.Trend.Type is one of 'ordinary', 'linear', 'quadratic', 'polynomial' then P equals to $1, M+1, \frac{M(M+1)}{2}$ respectively.

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- When Metaopts.Trend.Type='polynomial' then depending on the polynomial degree q, defined in Metaopts.Trend.Degree, then P equals to $\binom{M+q}{q}$.
- When Metaopts. Trend. Type is 'simple' then P equals to 1.
- When Metaopts.Trend.Type is 'custom':
 - If Metaopts. Trend. CustomF is a string or double then P equals to 1.
 - If Metaopts.Trend.CustomF is a cell array of strings or function handles then P equals the length of the cell array. In other words, each element of the array corresponds to a single column of F.

2.4.3 Correlation function

2.4.3.1 Standard options

The main ingredients for specifying the correlation function are:

• **Type:** The type of the autocorrelation function as described in Section 1.3.1. For example, in order to use a separable correlation function the following option is needed:

```
Metaopts.Corr.Type = 'separable';
```

If not specified otherwise by the user the correlation type is assumed to be 'ellipsoidal'.

- Family: The correlation function family is a 1-D function $R(\cdot)$. Its inputs depend on the type of correlation function.
 - For *ellipsoidal* correlation functions the correlation family is a function of the form R(h) where h>0 corresponds to the standardized Euclidean distance between \boldsymbol{x} and \boldsymbol{x}' (see Eq. (1.13)). Each coordinate difference between the rows of \boldsymbol{x} and \boldsymbol{x}' is standardized by a positive scalar θ .
 - For *separable* correlation functions the correlation family is a function of the form $R(x, x'; \theta)$ where θ is a positive scalar.

For using a built-in correlation family its name needs to be set, see Table 7 in Reference List (Section 3.1) for the name of each built-in correlation family and Section 1.3.3 for a brief description of each family. For example, in order to use the exponential family the following option is set:

```
Metaopts.Corr.Family = 'exponential';
```

Note: The default correlation family 'matern-3_2' is used if not specified otherwise by the user.

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• **Isotropic:** This is a Boolean flag (with true or false value) that specifies whether the correlation function is isotropic or not. By default the correlation function is considered anisotropic, unless the following option is set:

```
Metaopts.Corr.Isotropic = true;
```

In Figure 10 the mean and variance of various Kriging predictors having different correlation families are plotted using the example script uq_Example_Kriging_01_1D.

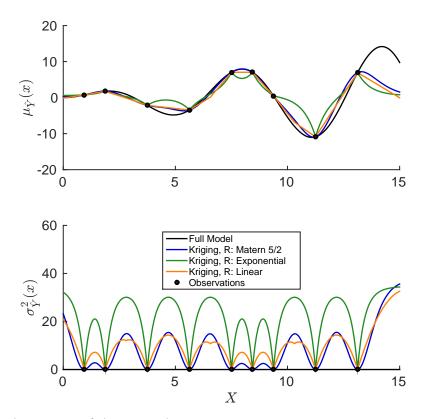


Figure 10: The output of the example script $uq_Example_Kriging_01_1D$. The mean and variance of various Kriging predictors is plotted, using different correlation families.

2.4.3.2 Advanced options

- **User-defined correlation family**: Apart from the already existing correlation families user-defined ones can be used. Depending on the type of correlation function that has been selected (separable or ellipsoidal) the user-defined correlation family is expected to accept different inputs.
 - **Separable case:** A user-defined correlation family is expected to be of the form $R(x, x'; \theta)$ where x, x' are scalars and θ a positive scalar. For example if the following correlation family needs to be used:

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$$R(x, x'; \theta) = \exp \left[-\left(\frac{x - x'}{\theta}\right)^{1.5} \right]$$

the following options should be provided:

```
Metaopts.Corr.Type = 'separable';
Metaopts.Corr.Family = @(x1,x2,th) exp(-((x1-x2)/th).^1.5);
```

Notice that for the separable case the user-defined correlation function can also be *non-stationary*.

Note: The user-defined correlation familiy is expected to be *vectorized*, *i.e.*it should be able to handle inputs $\times 1$ and $\times 2$ that are vectors either with the same or different length.

– Ellipsoidal case: A user-defined correlation family is expected to be of the form R(h) where h is a positive scalar. The value of h is calculated by UQLAB as in Eq. (1.13) and then sent to the user-defined function. For example if the following correlation family needs to be used:

$$R(h) = \exp\left(-h^{1.5}\right)$$

the following options should be provided:

```
Metaopts.Corr.Type = 'ellipsoidal';
Metaopts.Corr.Family = @(h) exp(-h.^1.5);
```

Note: The user-defined correlation familiy is expected to be *vectorized*, *i.e.*it should be able to handle inputs h that are vectors of arbitrary length.

• Adding a nugget: A *nugget* value can be set. This is a constant (or vector of constants) which is added to the diagonal of the *R* matrix. This can be accomplished by:

```
Metaopts.Corr.Nugget = 1e-2;
```

A different nugget value can be added to each diagonal element of R when the specified nugget is a vector of length equal to the size N of the experimental design.

- User-specified routine to calculate the correlation matrix (R): All the aforementioned options regarding the correlation function are handled by the function uq_Kriging_eval_R. If the user wants to use a fully custom correlation function in order to obtain the correlation matrix R the following rules need to be followed.
 - The function should return the correlation matrix $\mathbf R$ and accept x_1, x_2, θ and a structure of options like the following:

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```
function R = my_eval_R(x1,x2,theta, options)
...
```

- Inputs $\times 1$, $\times 2$ are matrices with arbitrary number of rows and M number of columns (where M is the input dimension).
- When the custom correlation function my_eval_R is called, e.g. during the creation or usage of a Kriging metamodel, the structure options will contain all options that were set inside Metaopts.Corr.
- The input theta of the function my_eval_R corresponds to the hyperparameters θ and it is expected to be a vector of arbitrary length. There is no limitation regarding its length but its dimension should be reflected in the choice of either initial value and/or optimization bounds(see Section 2.4.5 for more information about the optimization options).

It can be used for calculating the Kriging metamodel as well as within the Kriging predictor, as long as the following option has been set:

```
Metaopts.Corr.Handle = @my_eval_R;
```

2.4.4 Hyperparameters estimation methods

The hyperparameters estimation method affects the type of the objective function that is minimized in Eq. (2.3) as well as the way the (constant) Gaussian process variance σ^2 is calculated (for more information see Section 1.4).

Currently, the maximum likelihood and cross-validation methods are available for estimating the Kriging parameters and it suffices to select either 'ML' or 'CV' as the value of the field Metaopts. EstimMethod.

Note: If not specified otherwise by the user, the leave-one-out cross-validation method is used as the default.

A comparison of the resulting Kriging predictors using different estimation (and optimization) methods can be found in the example script uq_Example_Kriging_02_VariousMethods (see Figure 11).

2.4.4.1 Advanced Options

When the cross-validation method is used it is by default the leave-one-out approach. It can be set to be leave-K-out by setting:

```
Metaopts.CV.LeaveKOut = K;
```

where K is an integer that should be smaller than the size of the experimental design.

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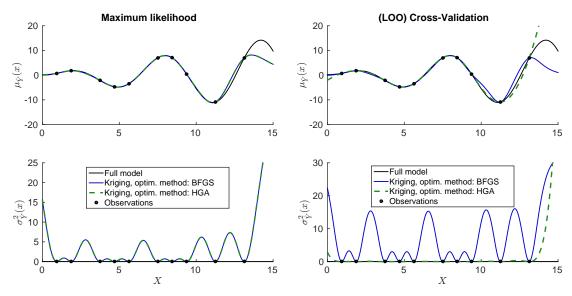


Figure 11: The output of the example script uq_Example_Kriging_02_VariousMethods. The mean and variance of various Kriging predictors is plotted, using different optimization methods. On the left hand side the maximum likelihood estimation method is used and on the right hand side the (LOO) cross validation method.

2.4.5 Hyperparameter optimization

Various configuration options are available regarding the method to solve the optimization problem in Eq. (2.3). The available optimization methods can be divided in two categories:

· Gradient-based methods

Currently the BFGS method is available. In order to use this method the following syntax is used:

```
Metaopts.Optim.Method = 'BFGS';
```

As in any gradient-based method, an initial value of the hyperparameters (here denoted as θ_0) is required. Note that the hyperparameters refer to the space \mathcal{U} as described by Eq. (2.4). By default, $\theta_0 = 1$ in each dimension. However, a different initial value can be selected, $e.g.\theta_0 = 0.5$ (in each dimension):

```
Metaopts.Optim.InitialValue = 0.5;
```

Different initial value per dimension can be selected by specifying an $M \times 1$ vector instead of a scalar.

· Global methods

Currently Genetic Algorithm (GA) and Self-adaptive Differential Evolution (SaDE) methods are available in UQLAB, as well as their hybrid counterparts (HGA and HSaDE respectively). In order to use one of these methods for solving the optimization of the hyperparameters, *e.g.* the Genetic Algorithm, one sets:

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```
Metaopts.Optim.Method = 'GA';
```

As in any global method the bounds of the optimization variable(s) needs to be set. Note that the hyperparameters refer to the space \mathcal{U} as described by Eq. (2.4). By default, the bounds (lower, upper) $[0.001, 10]^T$ are used. However, different bounds, $e.g.[0.01, 1]^T$ can be used as follows:

```
Metaopts.Optim.Bounds = [0.01; 1];
```

Additional options which are specific to each method may exist. For example, when using the Genetic Algorithm method one might need to set a different value of stall generations, *e.g.* 20. This can by accomplished by setting:

```
Metaopts.Optim.HGA.nStall = 20;
```

Moreover, regardless of the method, we can manually specify the following options:

• The number of iterations or generations (depending on the optimization method):

```
Metaopts.Optim.MaxIter = 100;
```

• The convergence tolerance:

```
Metaopts.Optim.Tol = 1e-5;
```

• The verbosity of the optimization process, *e.g.* showing only the final result:

```
Metaopts.Optim.Display = 'final';
```

For a list of all the available options for each method, please refer to Table 9 in Section 3.1.5.

```
Note: When no method has been defined by the user, the default Metaopts.Optim.Method = 'HGA' (Hybrid Genetic Algorithm) is used.
```

A comparison of the resulting Kriging predictors using different optimization (and estimation) methods can be found in the example script uq_Example_Kriging_02_VariousMethods (see Figure 11).

When no optimization of the hyperparameters is required because a prescribed value theta_user is to be used, the following syntax shall be used:

```
Metaopts.Optim.Method = 'none';
Metaopts.Optim.InitialValue = theta_user;
```

2.5 Kriging metamodels of vector-valued models

All the examples presented so far in this chapter dealt with scalar-valued models. In case the model (or the experimental design, if manually specified) produces multi-component

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outputs, UQLAB performs an independent Kriging metamodel for each output component on the shared experimental design. No additional configuration is needed to enable this behaviour. A Kriging example with multi-component outputs can be found in the UQLAB example script uq_Example_Kriging_04_MultipleOutputs.

2.5.1 Accessing the results

Running a Kriging calculation on a multi-component output model will result in a multi-component output structure. As an example, a model with 9 outputs will produce the following output structure:

```
myKriging.Kriging
ans =
1x9 struct array with fields:
beta
sigmaSQ
theta
```

Each element of the Kriging structure is functionally identical to its scalar counterpart in Section 2.3.1. Similarly, the myKriging. Error structure becomes a multi-element structure:

```
myKriging.Error
ans =
1x9 struct array with fields:
LOO
```

2.6 Using a Kriging predictor as a model

Regardless of the configuration options that were used in order to derive the Kriging metamodel Eqs. (1.5)-(1.6) can be used to predict new points. Indeed, after a Kriging MODEL object is created in UQLAB, it can be used just like an ordinary model (for details, see the UQLAB User Manual – the MODEL module).

Consider the example in Section 2.3. After obtaining a Kriging metamodel using any set of configuration options described in Section 2.4, one can evaluate the mean of the Kriging predictor on point x=1 as follows:

```
x = 1;
% Evaluate the mean of the Kriging predictor on point x
YmuKG = uq_evalModel(x)
YmuKG =
0.8782
```

The variance of the predictor can be also evaluated by using a two-component output:

```
% Evaluate the mean and variance of the Kriging predictor on point x
[YmuKG, YvarKG] = uq_evalModel(x)
YmuKG =
0.8782
YvarKG =
53.5691
```

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As most functions within UQLAB, model evaluations are vecorized, *i.e.* evaluating multiple points at a time is much faster than repeatedly evaluating one point at a time:

```
x = transpose(0:0.1:15);
% Evaluate the mean and variance of the Kriging predictor on points x
[YmuKG, YvarKG] = uq_evalModel(x);
```

2.7 Manually specifying a Kriging predictor (predictor-only mode)

It is possible to use the Kriging module in UQLAB to build custom Kriging-based models to be used as predictors as in Section 2.6. This allows, *e.g.* to import a metamodel calculated with another software into the UQLAB framework, or even to create one *ad-hoc* model. In the following, we exemplify how to create a custom Kriging metamodel that is similar to the one that was obtained in Section 2.3.

```
% Create the experimental design and calculate the response of the model
X = transpose(0 : 2 : 15);
Y = X.*sin(X);
% Create a custom Kriging object
Metaopts.Type = 'uq_metamodel';
Metaopts.MetaType = 'Kriging';
Metaopts.ExpDesign.Sampling = 'User';
Metaopts.ExpDesign.X = X;
Metaopts.ExpDesign.Y = Y;
% Select ordinary Kriging
Metaopts.Kriging.Trend.Type = 'ordinary';
% Set the values of beta, sigma^2 and theta
Metaopts.Kriging.beta = 69.84 ;
Metaopts.Kriging.sigmaSQ = 2.566e5;
Metaopts.Kriging.theta = 9.999;
% Select ellipsoidal, Matern-3/2 correlation function
Metaopts.Kriging.Corr.Type = 'ellipsoidal';
Metaopts.Kriging.Corr.Family = 'matern-3_2';
% Create the metamodel
myCustomKriging = uq_createModel(Metaopts);
% Evaluate the metamodel on some new points
Xnew = transpose(1 : 2 : 13);
Ynew = uq_evalModel(Xnew);
```

In case the metamodel has more than one output, it is sufficient to specify the same information for each output coordinate by adding an index i to the Metaopts.Kriging(i) structure.

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Chapter 3

Reference List

How to read the reference list

Structures play an important role throughout the UQLAB syntax. They offer a natural way to group configuration options and output quantities semantically. Due to the complexity of the algorithms implemented, it is not uncommon to employ nested structures to fine-tune inputs/outputs. Throughout this reference guide, we adopt a table-based description of the configuration structures.

The simplest case is given when a field of the structure is a simple value/array of values:

Tab	Table X: Input		
•	.Name	String	A description of the field is put here

which corresponds to the following syntax

```
Input.Name = 'My Input';
```

The columns correspond to name, data type and a brief description of each field. At the beginning of each row a symbol is given to inform as to whether the corresponding field is mandatory, optional, mutually exclusive, etc. The comprehensive list of symbols is given in the following table:

Mandatory
 Optional
 ⊕ Mandatory, mutually exclusive (only one of the fields can be set)
 ⊞ Optional, mutually exclusive (one of them can be set, if at least one of the group is set, otherwise none is necessary)

When one of the fields of a structure is a nested structure, we provide a link to a table that describes the available options, as in the case of the Options field in the following example:

Table X: Input

•	.Name	String	Description
	.Options	Table Y	Description of the Options structure

Tab	Table Y: Input.Options		
•	.Field1	String	Description of Field1
	.Field2	Double	Description of Field2

In some cases an option value gives the possibility to define further options related to that value. The general syntax would be

```
Input.Option1 = 'VALUE1';
Input.VALUE1.Val1Opt1 = ...;
Input.VALUE1.Val1Opt2 = ...;
```

This is illustrated as follows:

Tab	Table X: Input			
•	.Option1	String	Short description	
		'VALUE1'	Description of 'VALUE1'	
		'VALUE2'	Description of 'VALUE2'	
⊞	.VALUE1	Table Y	Options for 'VALUE1'	
\Box	.VALUE2	Table Z	Options for 'VALUE2'	

Tab	Table Y: Input.VALUE1		
	.Val10pt1	String	Description
	.Val10pt2	Double	Description

Tab	Table Z: Input.VALUE2		
	.Val20pt1	String	Description
	.Val20pt2	Double	Description

Note: In the sequel, double/doubles mean a real number represented in double precision (resp. a set of such real numbers).

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3.1 Create a Kriging metamodel

Syntax

```
myKriging = uq_createModel(Metaopts)
```

Input

The struct variable Metaopts contains the configuration information for a Kriging metamodel. The detailed list of options available is reported in Table 3.

Tal	Table 3: Metaopts			
•	.Type	'uq_metamodel'	Select the metamodelling tool	
•	.MetaType	'Kriging'	Select Kriging	
	.Name	String	Unique identifier for the metamodel	
	.ExpDesign	Table 4	Experimental Design options (Section 2.4.1)	
	.Input	String	The name of the INPUT object that describes the inputs of the metamodel	
		INPUT object	The INPUT object that describes the inputs of the metamodel	
	.FullModel	String	The name of the MODEL object that is used to calculate the model responses	
		MODEL object	The MODEL object that is used to calculate the model responses	
	.Trend	Table 5	Trend-related options (Section 2.4.2)	
	.Corr	Table 7	Correlation function options (Section 2.4.3)	
	.EstimMethod	String	Hyperparameters estimation method (Section 2.4.4)	
		'CV' (default)	Cross-Validation estimation	
		'ML'	Maximum-Likelihood estimation	
	.CV	Table 8	Options relevant to the Cross-Validation estimation method. It is only taken into account if the selected method is Cross-Validation	
	.Optim	Table 9	Hyperparameter optimization-related options (Section 2.4.5)	

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.Kriging	Table 14	Field used for specifying the parameters of a custom Kriging metamodel (Section 2.7)
.KeepCache	logical default: 1	When set to 0 some cached matrices are removed after the metamodel has been created. By keeping the cached matrices the speed of the Kriging predictor may be increased for some problems.

3.1.1 Experimental design options

Tal	Table 4: Metaopts.ExpDesign			
•	.Sampling	String	Sampling type	
		'MC' (default)	Monte Carlo sampling	
		'LHS'	Latin Hypercube sampling	
		'Sobol'	Sobol sequence sampling	
		'Halton'	Halton sequence sampling	
		'Data'	Obtain samples directly from an external .mat file (defined in ExpDesign.DataFile)	
		'User'	User defined experimental design. (defined in ExpDesign.X, ExpDesign.Y)	
	.DataFile	String	A string containing the name of the mat file that contains the Experimental Design. It is only taken into account (and is necessary) when ExpDesign.Sampling = 'Data'.	
	.NSamples	Integer	The number of samples to draw	
	.X	$N \times M$ Double	User defined model input X (only applies when ExpDesign.Sampling = 'user')	
	. У	$N \times O$ Double	User defined model response Y (only applies when ExpDesign.Sampling = user)	

3.1.2 Trend options

Ta	Table 5: Metaopts.Trend				
	.CustomF	Double	constant trend in simple Kriging		
		String	The function name that returns $f(x)$		

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	Cell containing strings	The respective names of functions $f_i(\boldsymbol{x}), i=1,\ldots,P$ such that each function returns the i 'th column of \boldsymbol{F}
	Cell containing handles	The respective handles of functions $f_i(\boldsymbol{x}), i=1,\ldots,P$ such that each function returns the i 'th column of \boldsymbol{F}
.Degree	Double default: 3	The polynomial degree. Only applies when Metaopts.Trend.Trend = 'polynomial'
.Type	String	The type of trend
	'simple'	Simple Kriging: a given mean is used as a trend. No regression takes place. The mean should be given in Metaopts.Trend.CustomF
	'ordinary' (default)	Ordinary Kriging: the mean is an unknown constant
	'linear'	The trend is a linear polynomial
	'quadratic'	The trend is a quadratic polynomial
	'polynomial'	The trend is a polynomial of arbitrary degree, defined in Metaopts.Trend.Degree
	'custom'	The number of samples to draw
.PolyTypes	$1 \times M$ Cell containing Strings	The type of polynomials that are used
.TruncOptions	Table 6	Polynomial basis truncation options

Tal	Table 6: Metaopts.Trend.TruncOptions			
	.qNorm	Double default: 1	Hyperbolic truncation scheme (see the UQLAB User Manual – Polynomial Chaos Expansions)	
	.MaxInteraction	Integer	Limit basis terms to up to MaxInteraction variables. See the UQLAB User Manual – Polynomial Chaos Expansions for more information	
	.Custom	Double	User-defined basis	

3.1.3 Correlation-function options

Tal	Table 7: Metaopts.Corr			
	.Type	String	The correlation function type	
		'Ellipsoidal' (default)	Ellipsoidal correlation function	

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	'Separable'	Separable correlation function
.Family	String or function handle	The correlation family, that is the elementary 1-D function that is used by the correlation function. For a description of each family refer to Section 1.3.3
	'Exponential'	Exponential correlation function.
	'Gaussian'	Gaussian correlation function
	'Linear'	Linear correlation function
	'Matern-3_2' (default)	Matérn-3/2 correlation function
	'Matern-5_2	Matérn-5/2 correlation function
	function handle	The user defined correlation family function handle
.Isotropic	boolean (default:false)	Determines whether the correlation function is isotropic or anisotropic
.Nugget	Double (default: 0)	If scalar, adds this quantity to the diagonal elements of the correlation matrix R If vector, adds each element to the corresponding diagonal element of R
.Handle	function handle default: @uq_Kriging_eval_R	The handle of the function that is used to calculate the correlation matrix R (see Advanced options in Section 2.4.3)

3.1.4 Estimation method options

Tal	Table 8: Metaopts.CV		
	.LeaveKOut	Integer default: 1	 The number of elements in i, in Eq. (1.29). It can be any integer between 1 and N (the number of samples). The default value is 1 (known as Leave-One-Out Cross-Validation)

3.1.5 Hyperparameter optimization options

Tal	Table 9: Metaopts.Optim		
	.InitialValue	$M \times 1$ or 1×1 Double default: 0.5	 A vector containing the initial estimate of the correlation parameters If M > 1 and a scalar is selected the same value is assumed for all dimensions

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.Bounds	$2 \times M$ or 2×1 Double default: [4 ; 1e-3]	 A matrix containing the bounds of admissible values of the correlation parameters, in the form [lower_bound; upper_bound]. If a single value is assigned for each bound the same value is used for all the elements of the vector θ (in case of M > 1)
.Display	String	Determines the verbosity of the optimization process
	'none'	Nothing will be printed to the command window
	'iter' (defaul	t) The state of the optimization process will be printed after each iteration
	'final'	Only the final result of the optimization process will be printed
.MaxIter	Integer default: 10	The maximum number of iterations or generations
.Method	String	Optimization method (Section 2.4.5)
	'none'	No optimization. The value Metaopts.Optim.InitialValue is used
	'LBFGS'	Gradient based optimization (L-BFGS) using MATLAB's built-in fmincon function
	'GA'	Genetic Algorithm optimization using MATLAB's built-in ga function
	'HGA' (defaul	t) Hybrid Genetic Algorithm optimization using MATLAB's built-in ga and fmincon functions
	'HSaDE'	(BETA) Hybrid Self-adaptive Differential Evolution optimization method
.BFGS	Table 12	Options relevant to the LBFGS optimization method
.GA	Table 10	Options relevant to the GA optimization method
.HGA	Table 11	Options relevant to the HGA optimization method
.HSADE	Table 13	Options relevant to the HSADE optimization method
.Tol	Double default:1e-3	Optimization Convergence tolerance

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Note: The convergence tolerance defined under Metaopts.Optim.Tol may slightly differ depending on the optimization method. For MATLAB built-in optimization methods check the definition of the option 'TolFun' of the respective method

Tal	Table 10: Metaopts.Optim.GA		
	.nPop	positive integer default: using Eq. (3.1)	The population size of each generation
	.nStall	positive integer default: 2	The maximum number of stall generations

Tal	Table 11: Metaopts.Optim.HGA		
	.nPop	positive integer default: using Eq. (3.1)	The population size of each generation
	.nStall	positive integer default: 2	The maximum number of stall generations
	.nLM	integer (≥ 1) default: 5	The limited memory size of LBFGS method that is executed starting from the optimal value that was obtained after the Genetic Algorithm optimization

Ta	Table 12: Metaopts.Optim.BFGS		
	.nLM	integer (≥ 1) default: 5	The limited memory size of LBFGS method

Tal	Table 13: Metaopts.Optim.HSADE		
	.nPop	positive integer default: using Eq. (3.1)	The population size of each generation
	.nStall	positive integer default: 2	The maximum number of stall generations
	.nLM	integer (≥ 1) default: 5	The limited memory size of LBFGS method that is executed starting from the optimal value that was obtained after the HSADE optimization

When an evolutionary optimization method is used and no population size has been set by the user, the following empirical formula is used to determine the default population size n_{pop} :

$$n_{pop} = \min(20, \text{floor}(4 + 3 \log M))$$
 (3.1)

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3.1.6 Custom Kriging options

When a user-defined Kriging metamodel is to be created, the Metaopts.Kriging field must be set with the following parameters (notice that all are *mandatory* in this case):

Tal	Table 14: Metaopts.Kriging		
•	.Trend	Table 5	The Trend definition
•	.beta	Double	The values of the regression coefficients β in Eq. (2.2)
•	.sigmaSQ	Double	The value of σ^2 in Eq. (2.2)
•	.theta	Double	The value of θ in Eq. (2.2)
•	.Corr	Table 7	The correlation function definition See note below

Note: In the current version of UQLAB not all the options regarding the correlation function (as reported in Table 7) are available for custom Kriging. Only the following are supported:

```
Type: mandatoryFamily: mandatory
```

- .Isotropic: optional. By default anisotropic correlation function is assumed.

If the metamodel has more than one outputs then Metaopts.Kriging is expected to be a structure array with length equal to the number of outputs and the parameters in Table 14 defined for each Metaopts.Kriging(index) (where index ranges from 1 to the total number of outputs).

```
Note: For Custom Kriging the fields Metaopts.ExpDesign.X and Metaopts.ExpDesign.Y are also required (see Table 4).
```

For a usage example of custom Kriging, see Section 2.7.

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Output

Table 15: myKriging = uq_createInput()		
.Name	String	The name of the Kriging metamodel
.Kriging	Table 17	Kriging results
.Internal	Table 19	Internal fields
.Error	Table 18	Error metrics of the metamodelling result
.Options	Table 3	The options that were defined in Metaopts variable
.ExpDesign	Table 16	Experimental Design related values

Table 16: myKriging.ExpDesign		
.NSamples	Double	The number of samples
.Sampling	String	The sampling method
.X	$N \times M$ Double	The experimental design values
.U	$N \times M$ Double	 The experimental design values in the auxiliary space If no scaling is selected then .U = .X
.Y	$N \times O$ Double	The output Y that corresponds to the input X

Table 17: myKriging.Kriging		
.beta	$p \times 1$ Double	The value of $\beta(\theta)$ in Eq. (2.2)
.sigmaSQ	Double	The value of $\sigma^2(\boldsymbol{\theta})$ in Eq. (2.2)
.theta	M imes 1 Double	The value of θ in Eq. (2.2)

Note: In general the fields myKriging.Kriging and myKriging.Error are structure arrays with length equal to the number of outputs of the metamodel.

Table 18: myKriging.Error		
.LOO	Double	The Leave-One-Out error, calculated using Eq. (2.5)

The Leave-one-out error is calculated using Eq. (2.5).

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3.1.7 Internal fields (advanced)

Note: The internal fields of the Kriging module are not intended to be accessed or changed at most typical usage scenarios of the module. Also note that some internal fields are not documented here.

Table 19: myKriging.Internal		
.Runtime	Structure	Variables that are used during the calculation of the kriging metamodel
.Error	Table 21	Internal fields related to the metamodelling error
.Kriging	Table 20	Internal fields with data related to the Kriging metamodel

Table 20: myKriging.Internal.Kriging		
.Trend	Table 22	Internal fields related to the trend
.GP	Table 23	Internal fields related to the Gaussian process
.Optim	Table 24	Internal fields related to the Optimization of the hyperparameters
.Cached	Structure	Internal fields related to cached variables

Note: In general the fields <code>myKriging.Internal.Kriging</code> and <code>myKriging.Internal.Error</code> are structure arrays with length equal to the number of outputs of the metamodel. Therefore in order to access the parameters that correspond to the respective output one should use for example <code>myKriging.Internal.Kriging(k).field</code> where $k=1,...,N_{\text{out}}$.

Table 21: myKriging.Internal.Error		
.LOOmean	$N \times 1$ Double	The numerator in Eq. (1.30)
.LOOsd	$N \times 1$ Double	The denominator in Eq. (1.30) (excluding K)
.varY	Double	The variance of the output Y. One can multiply this quantity with the relative LOO error in myKriging.Error.LOO to get the absolute value of the LOO error

Table 22: myKriging.Internal.Kriging.Trend		
.F	N imes p Double	The trend's basis function evaluated on the experimental design (see Eq. (2.2))
.beta	$p \times 1$ Double	The value of $\beta(\theta)$ in Eq. (2.2)

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Table 23: myKriging.Internal.Kriging.GP		
.R	$N \times N$ Double	The correlation matrix value
.sigmaSQ	Double	The value of $\sigma^2(\boldsymbol{\theta})$ in Eq. (2.2)

Table 24: myKriging.Internal.Kriging.Optim		
.Theta	Double	The optimum value of $ heta$ that was obtained
.ObjFun	Double	The objective function value when $oldsymbol{ heta}$ is optimum
.InitialObjFun	Double	The value of the objective function using the initial estimate of $ heta$
.nEval	Double	The number of objective function evaluations that took place during the optimization
.nIter	Double	 The number of iterations (or generations) that took place during the optimization For hybrid methods only the number of generations is taken into account

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3.2 Kriging predictor

Syntax

```
Y_mu = uq_evalModel(X, myKriging)
[Y_mu, Y_sigma2] = uq_evalModel(...)
```

Description

Y_mu = uq_evalModel(X, myKriging) returns the mean of the Kriging predictor ($N \times N_{\text{out}}$ Double) on the points X ($N \times M$ Double) using the Kriging metamodel MyKriging.

[Y_mu, Y_sigma2] = uq_evalModel(...) additionally returns the variance of the Kriging predictor ($N \times N_{\text{out}}$ Double).

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3.3 Printing/visualizing a Kriging metamodel

UQLAB offers two commands to conveniently print reports containing contextually relevant information for a given object.

3.3.1 Printing the results: uq_print

Syntax

```
uq_print (myKriging);
uq_print (myKriging,outidx);
uq_print (myKriging,outidx, option1, option2, ...);
```

Description

uq_print (myKriging) prints a report of the configuration options and results of the Kriging metamodel object myKriging. If the model has multiple outputs, only the results for the first output variable are printed.

uq_print (myAnalysis, outidx) prints a report of the configuration options and results of the Kriging metamodel object myKriging for the output variables specified in the array outidx.

uq_print (myKriging, outidx, option1, option2, ...) prints a report only of the configuration options or results that are specified via the options option1, option2, ...etc, of the Kriging metamodel object myKriging for the output variables specified in the array outidx. See Table Table 25 for the available options.

Table 25: uq_print options	
'beta'	Prints out the regression coefficients $oldsymbol{eta}$.
'theta'	Prints out the final hyperparameters θ value(either the optimal value or the user-specified value if the user manually specified it).
'F'	Prints out the information matrix F .
'R'	Prints out the correlation matrix $oldsymbol{R}$.

Examples:

uq_print (myKriging, [1 3]) will print the Kriging metamodelling results for output variables 1 and 3.

uq_print (myKriging, 3, 'theta', 'R') will only print the hyperparameters θ and correlation matrix \mathbf{R} values for output variable 3.

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3.3.2 Graphically display the results: uq_display

Syntax

```
uq_display(myKriging);
uq_display(myKriging, outidx);
uq_display(myKriging, outidx, 'R');
```

Description

- uq_display (myKriging) create a visualization of the results of the Kriging metamodel in object myKriging, if possible. If the model has multiple outputs, only the results for the first output variable are visualized.
- uq_display(myKriging, outidx) create a visualization of the results of the Kriging metamodel in object myKriging for the output variables specified in the array outidx.
- uq_display(myKriging, outidx, 'R') create a visualization of the correlation matrix R in object myKriging for the output variables specified in the array outidx.

Note: For visualizing the Kriging metamodelling results using uq_display the input should be either 1- or 2-dimensional. However uq_display(myKriging, outidx, 'R') can be used for arbitrary input dimension.

Examples:

uq_display (myKriging, [1 3]) will display the Kriging metamodelling results for output variables 1 and 3.

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