Quasi-random sampling for multivariate distributions via generative neural networks

Marius Hofert (with Avinash Prasad and Mu Zhu)

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1 Classical copula modeling

■ General goal: Modeling a df H or $X \sim H$ with continuous margins F_1, \ldots, F_d (for possibly high-dimensional, computational applications).

■ Examples:

- ▶ Static: X models a joint loss in a risk management context; e.g., $\mu = \mathbb{P}(X > x)$ or $\mathrm{ES}_{\alpha}(S) = \mathbb{E}(S \,|\, S > F_S^{-1}(\alpha))$ for $S = X_1 + \cdots + X_d$.
- ▶ Dynamic: X models joint innovations of an ARMA-GARCH process or increments of dependent geometric Brownian motions

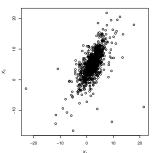
Sklar's Theorem:

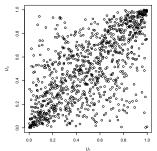
- ▶ Analytical: $H(x) = C(F_1(x_1), ..., F_d(x_d))$ for a copula C, a distribution function with U(0,1) margins.
- Stochastic: $X = (F_1^{-1}(U_1), \dots, F_d^{-1}(U_d)) \sim H$ (quantile transformation) and $U = (F_1(X_1), \dots, F_d(X_d)) \sim C$ (probability transf.).
- Why: Useful under asymmetric information (margins known, dependence unknown) or from a computational point of view (e.g., estimation).

- Statistics: Instead of X, we now have $X = (X_1^\top, \dots, X_n^\top)^\top \in \mathbb{R}^{n \times d}$.
 - 1) Given X, compute the *pseudo-observations* $U=(\boldsymbol{U}_1^\top,\dots,\boldsymbol{U}_n^\top)^\top\in\mathbb{R}^{n\times d}$ with

$$U_{ij} = \hat{F}_{n,j}(X_{ij}) = \frac{1}{n+1} \sum_{k=1}^{n} \mathbb{1}_{\{X_{kj} \le X_{ij}\}} = \frac{R_{ij}}{n+1},$$

where $R_{ij} = \operatorname{rank}(X_{ij})$ among the component sample X_{1j}, \ldots, X_{nj} .





- 2) Based on U, one needs to fit, test and select an adequate copula C.
- 3) Simulate $U_1, \ldots, U_{n_{\sf gen}}$ from the fitted C and estimate, for example:

• $F_S^{-1}(u)$ where $S = X_1 + \dots + X_d = F_1^{-1}(U_1) + \dots + F_d^{-1}(U_d)$

Examples (QRM):

- Value-at-risk $VaR_{\alpha}(S) = F_S^{-1}(\alpha)$ of the total loss S
- Expected shortfall $\mathrm{ES}_{\alpha}(S) = \mathbb{E}(S \mid S > F_S^{-1}(\alpha))$
- Expectations $\mu = \mathbb{E}(\Psi_0(\boldsymbol{X})) = \mathbb{E}(\Psi(\boldsymbol{U}))$ where $\Psi(\boldsymbol{u})$ is given by $\Psi_0(F_1^{-1}(u_1), \dots, F_d^{-1}(u_d))$ and so $\mu \approx \frac{1}{n_{\mathsf{gen}}} \sum_{i=1}^{n_{\mathsf{gen}}} \Psi(\boldsymbol{U}_i)$.

Examples (MC):

- With $\Psi(u) = \mathbb{1}_{\{u_1 > u, \dots, u_d > u\}}$ we obtain that

$$\mu = \mathbb{E}(\Psi(\boldsymbol{U})) = \mathbb{P}(U_1 > u, \dots, U_d > u),$$

so exceedance probabilities, e.g., the probability of a flood over multiple dikes or joint losses in a stock portfolio.

- With $\Psi(\boldsymbol{u}) = \max\{(F_1^{-1}(u_1) + \dots + F_d^{-1}(u_d))/d - K, 0\}$ we obtain that $\mu = \mathbb{E}(\Psi(\boldsymbol{U}))$ is the expected payoff of a European basket call option.

Problems (with this classical modeling approach):

- 1) Step 2) above: Finding an adequate copula model C for the pseudo-observations, especially in more than two dimensions.
- 2) Large variance $var(\frac{1}{n_{\rm gen}}\sum_{i=1}^{n_{\rm gen}}\Psi(U_i))$ of the Monte Carlo estimator under rare-event simulation.

Ideas:

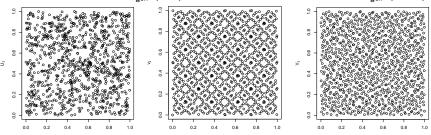
- 1) Use (specific) neural networks (NNs) (⇒ flexible dependence).
- 2) Use quasi-random sampling for such NNs (\Rightarrow variance reduction).

Outline:

- ▶ We first address 2), under dependence.
- ► We then study how NNs can be random number generators (RNGs) from copulas, so 1).
- We then address how NNs can be quasi-RNGs (QRNGs).
- For simplicity, we focus on the case where $F_1 = \cdots = F_d$ are U(0,1) in what follows (except for an ES_α example).

2 Quasi-random numbers for copulas

- If $C=\Pi$ (independence), pseudo-random numbers (PRNs) can be replaced by quasi-random numbers (QRNs) to reduce the variance.
- $\begin{array}{l} \blacksquare \quad \text{QRN sequences are low-discrepancy sequences } P_n = \{ \boldsymbol{v}_i \}_{i=1}^n \text{ (middle)} \\ \text{with } D^*(P_n) = \sup_{\boldsymbol{z} \in (0,1]^d} \left| \frac{\#\{i: \ \boldsymbol{v}_i \in [\boldsymbol{0}, \boldsymbol{z})\}}{n} \lambda([\boldsymbol{0}, \boldsymbol{z})) \right| \in O(n^{-1} \log^d n). \end{array}$
- **Example:** $U_1, \ldots, U_{n_{\sf gen}}$ (left), randomized Sobol' $V_1, \ldots, V_{n_{\sf gen}}$ (right):



■ The *RQMC estimator* $\frac{1}{n_{\rm gen}} \sum_{i=1}^{n_{\rm gen}} \Psi(V_i)$ is unbiased, fast and its variance can be estimated (from repeated randomizations).

- Question: How can we obtain QRNs from a general copula C?
- Idea: Could define $D_C^*(P_n) = \sup_{z \in (0,1]^d} \left| \frac{\#\{i : v_i \in [0,z)\}}{n} \mathbb{P}(U \in [0,z)) \right|$, but this does not lead to a construction principle. However, one can transform $V_1, \ldots, V_{n_{\mathrm{gen}}}$ to samples from C; see Cambou et al. (2017).
- Inverse Rosenblatt transform \mathcal{R}^{-1} : Bijection to transform $U' \sim \mathrm{U}(0,1)^d$ to $U \sim C$ (known as *conditional distribution method (CDM)* for sampling, a generalization of the inversion method to d > 1):

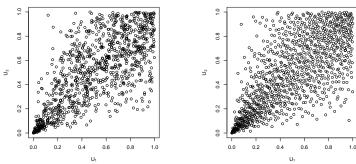
$$\begin{split} &U_1 = U_1', \\ &U_2 = C_{2|1}^{-1}(U_2' \,|\, U_1), \quad \text{(compare with } X_2 = F_2^{-1}(U_2') \sim F_2 \text{)} \\ &U_j = C_{j|1,\dots,j-1}^{-1}(U_j' \,|\, U_1,\dots,U_{j-1}), \quad j \in \{2,\dots,d\}. \end{split}$$

Formula for the implementation (which needs to be inverted!):

$$C_{j|1,\dots,j-1}(u_j \mid u_1,\dots,u_{j-1}) = \frac{D_{j-1,\dots,1} C_{1,\dots,j}(u_1,\dots,u_j)}{D_{j-1,\dots,1} C_{1,\dots,j-1}(u_1,\dots,u_{j-1})}.$$

 \Rightarrow Known analytically tractable $C_{j|1,\dots,j-1}^{-1}$: Normal, t, Clayton.

Example: 1000 PRNs (left) and QRNs (right) from a Clayton copula.



- **Disclaimer:** Even if not visible, there may be a variance reduction effect.
- For large j, evaluating $C_{j|1,\dots,j-1}^{-1}$ is time-consuming even for normal, t, Clayton.
- For Gumbel copulas, $C_{j|1,...,j-1}^{-1}$ is not tractable.
- See Cambou et al. (2017) for a different approach, but conceptually (first component \Rightarrow frailty) and numerically challenging (α -stable qf).

3 PRNs for copulas via GMMNs

■ Idea: To address Problem 1), we consider

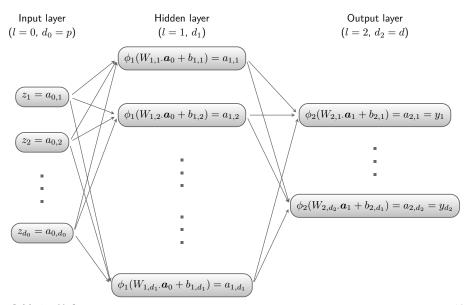
$$\mathbb{E}(\Psi(oldsymbol{U})) pprox rac{1}{n_{ extsf{gen}}} \sum_{i=1}^{n_{ extsf{gen}}} \Psi(oldsymbol{U}_i), \tag{1}$$

$$U_i = f_{\hat{\theta}}(F_Z^{-1}(U_i')), \quad i = 1, \dots, n_{\text{gen}},$$
 (2)

where

- $lackbox{m U}_1',\ldots,m U'_{n_{\sf gen}}\stackrel{\scriptscriptstyle \sf ind.}{\sim} \mathrm{U}(0,1)^p$ (later: $m V_1,\ldots,m V_{n_{\sf gen}}$; randomized Sobol');
- $F_{\mathbf{Z}}^{-1}(\mathbf{u}) = (F_{Z_1}^{-1}(u_1), \dots, F_{Z_p}^{-1}(u_p))$ maps to a *prior distribution* (Φ) ;
- $f_{\hat{\theta}}$ is a trained generative neural network f_{θ} (GMMNs).
- Training of f_{θ} learns a map from pseudo-random numbers from Z (here: $N_p(\mathbf{0}, I_p)$) to pseudo-random numbers from $U \sim C$.
- This is similar to \mathcal{R}^{-1} , but computationally simpler to evaluate.
- Errors:
 - 1) Monte Carlo error (1) (can be made arbitrarily small by the SLLN)
 - 2) Neural network (NN) "bottleneck" (2) (small if NN trained correctly)

3.1 What are NNs?



- Hyperparameters (fixed before training):
 - The ϕ_l 's are the activation functions (e.g., ReLU $\phi_l(x) = \max\{0, x\}$, sigmoid $\phi_l(x) = 1/(1 + e^{-x})$).
 - ▶ Number of layers, number of neurons per layer, number of epochs in training and batch size (more later).

Parameter vector:

 $\theta = (W_1, \dots, W_{L+1}, \boldsymbol{b}_1, \dots, \boldsymbol{b}_{L+1})$ consists of weight matrices and biases (initialized randomly and with zeros, resp.).

- $m{\theta}$ is fitted (or: the NN is *trained*) by stochastic gradient descent based on a *cost function* E(U,Y) computed between (a subset of)
 - lacktriangle the training data $U=(m{U}_1^ op,\dots,m{U}_{n_{\mathrm{trn}}}^ op)^ op$ from C (= target) and
 - the outputs $Y = f_{\theta}(Z)$ of the NN from the prior sample $Z = (Z_1^{\top}, \dots, Z_{n_{\text{tm}}}^{\top})^{\top}$.
- Often E is taken as the scaled MSE $E(U,Y) = \frac{1}{2n_{\rm trn}} \sum_{i=1}^{n_{\rm trn}} \| \boldsymbol{u}_i \boldsymbol{y}_i \|_2^2$ \Rightarrow Fails to learn the map from Z to U properly.

3.2 What are GMMNs?

• Generative moment matching networks (GMMNs) use as E(U,Y) the sample maximum mean discrepancy $\mathrm{MMD}(U,Y)$

$$\sqrt{\frac{1}{n_{\mathsf{trn}}^2} \sum_{i_1=1}^{n_{\mathsf{trn}}} \sum_{i_2=1}^{n_{\mathsf{trn}}} (K(\boldsymbol{U}_{i_1}, \boldsymbol{U}_{i_2}) - 2K(\boldsymbol{U}_{i_1}, \boldsymbol{Y}_{i_2}) + K(\boldsymbol{Y}_{i_1}, \boldsymbol{Y}_{i_2}))}$$

where K is a mixture of Gaussian kernels of different bandwidths. After experimentation, we chose

$$K(\boldsymbol{u}, \boldsymbol{y}) = \sum_{i=1}^{6} e^{-\frac{\|\boldsymbol{u} - \boldsymbol{y}\|_{2}^{2}}{2\sigma_{i}^{2}}} \quad \boldsymbol{\sigma} = (0.001, 0.01, 0.15, 0.25, 0.50, 0.75).$$

- Intuitively, MMD takes into account all pairs of observations between U_{i_1} and Y_{i_2} (desirable, but costly \Rightarrow mini-batch optimization).
- For the population version, one can show that $\mathrm{MMD}(\boldsymbol{U},\boldsymbol{Y})=0$ if and only if $\boldsymbol{U} \stackrel{\text{d}}{=} \boldsymbol{Y}$.

3.3 How are GMMNs trained?

- Training algorithm (mini-batch optimization):
 - 1) Initialize θ (weights W_1, W_2 : uniform entries; biases b_1, b_2 : 0)
 - 2) Partition the $(n_{\rm trn},d)$ -data matrix U and prior $(n_{\rm trn},d)$ -matrix Z into batches ($\approx n_{\rm trn}/n_{\rm bat}$ blocks of $n_{\rm bat}$ (batch size) rows each).
 - 3) For each batch, update θ by a stochastic gradient step (Adam).
 - 4) After $\approx n_{\rm trn}/n_{\rm bat}$ gradient steps, U and Z are exhausted and one epoch is completed. Shuffle their rows and go to Step 2).
 - 5) Training finishes after n_{epo} epochs.
- Setup in our experiments:
 - ▶ p = d (inspired from \mathbb{R}^{-1} in the CDM);
 - ▶ single hidden layer (*universal approximation theorem*: given suitable activation functions, single hidden layer NNs with $d_1 < \infty$ can approximate any continuous function on a compact subset of \mathbb{R}^d);

• $d_1 = 300$ neurons in the hidden layer;

- ϕ_1 to be ReLU (fast) and ϕ_2 to be sigmoid (maps to (0,1));
- batch size $n_{\rm bat}=5000$ (trade-off: large enough for "bottleneck" error to be small; small enough to not be memory-prohibitive);
- number of epochs $n_{\text{epo}} = 300$; and
- $n_{\rm trn} = 60\,000$ pseudo-samples from C (available for all models).

3.4 How can GMMNs generate QRNs from C?

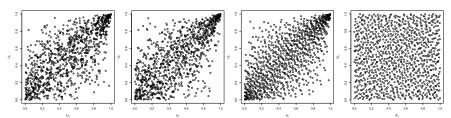
Algorithm 3.1 (GMMN quasi-random sampling)

- 1) Compute the RQMC points $V_1, \ldots, V_{n_{\sf gen}}$ (e.g., randomized Sobol').
- 2) Compute the prior samples $\mathbf{Z}_i = F_{\mathbf{Z}}^{-1}(\mathbf{V}_i)$, $i = 1, \dots, n_{\text{gen}}$.
- 3) Return the pseudo-observations of $m{Y}_i = f_{\hat{m{ heta}}}(m{Z}_i)$, $i=1,\ldots,n_{\sf gen}$.

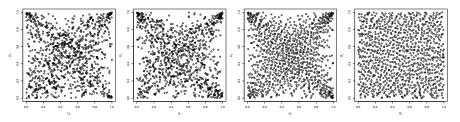
GMMNs are fast to evaluate and sufficiently smooth to preserve low discrepancy. If all the mixed partial derivatives of $h=\Psi\circ f_{\hat{\boldsymbol{\theta}}}\circ F_Z^{-1}$ exist a.e. and are continuous, then under Owen-type scrambling, $\mathrm{var}\big(\frac{1}{n_{\mathrm{gen}}}\sum_{i=1}^{n_{\mathrm{gen}}}h(\boldsymbol{V}_i)\big)=O(n_{\mathrm{gen}}^{-3}(\log n_{\mathrm{gen}})^{p-1}).$

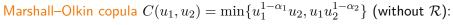
3.5 Do GMMNs generate samples from *C* well?

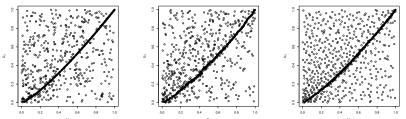
Gumbel PRNs, GMMN PRNs, GMMN QRNs, R-transformed GMMN QRNs:



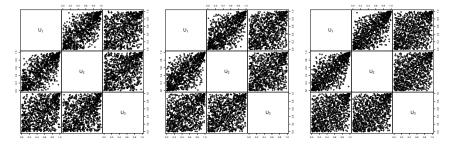
Gumbel-rotated t_4 mixture:







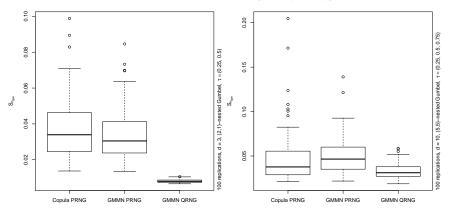
Nested Gumbel copula $C(u) = C_0(C_1(u_1, u_2), u_3) \ (\tau \in \{0.25, 0.5\})$:



One can consider box plots of realization of the Cramér-von Mises statistic

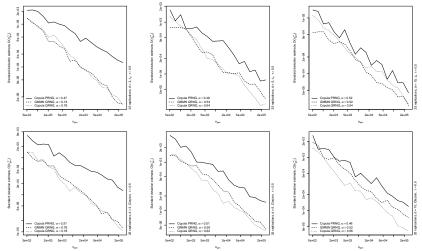
$$S_{n_{\mathrm{gen}}} = \int_{[0.1]^d} n_{\mathrm{gen}} (C_{n_{\mathrm{gen}}}(\boldsymbol{u}) - C(\boldsymbol{u}))^2 \, \mathrm{d}C_{n_{\mathrm{gen}}}(\boldsymbol{u}),$$

where $C_{n_{\rm gen}}$ is the *empirical copula* (ecdf of the pseudo-obs.) of $n_{\rm gen}=1000$ PRNs, GMMN PRNs and GMMN QRNs ($d \in \{3,10\}$):

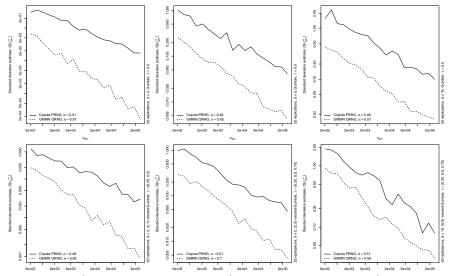


3.6 Variance-reduction effect?

Sample standard deviation of the estimator of $\mathbb{P}(U>0.99)$ computed from PRNs, GMMN QRNs and QRNs:



Sample standard deviation of the estimator of $\mathbb{E}(S \mid S > F_S^{-1}(0.99))$ (N(0,1) margins) computed from PRNs and GMMN QRNs (no QRNs):



Summary

- We can learn a QRNG from any joint model based on a PRNG for C.
- If generated from a known C, this is easy. If only a sample is available, $n_{\rm trn}$ needs to be sufficiently large (depending on the application).
- Gain: Universality (all models), computability (robustness, run time), especially useful for real data (where the true model is unknown).
- Challenges:
 - 1) Kendall's tau near 1;
 - 2) training needs a GPU server (evaluation "needs" TensorFlow);
 - 3) joint tail behavior;
 - 4) $d \gg 10$.
- Open problem: For $d\gg 10$, must training be improved (as distributions become harder to learn) or do RQMC point sets generally deteriorate? (GMMNs are still smooth). One could try (t,m,s)-nets other than Sobol' (but no related R package or standalone C code available).

Outlook: Application to time series

- Copula–GARCH model: $X_{t,j} = \mu_{t,j} + \sigma_{t,j} Z_{t,j}$, $j = 1, \ldots, d$, and $Z_t = (Z_{t,1}, \ldots, Z_{t,d}) \stackrel{\text{ind.}}{\sim} H$ with copula C.
- GMMN-GARCH model: $X_{t,j} = \mu_{t,j} + \sigma_{t,j} Z_{t,j}$, $j = 1, \ldots, d$, and $Z_t = (Z_{t,1}, \ldots, Z_{t,d}) \stackrel{\text{ind.}}{\sim} H$ with GMMN for C.
- Goal: Improving empirical predictive distributions (here: 1-step ahead).
- Applications:
 - 1) **ZCB yield curves** (term structure of interest rates)
 - ▶ US (d = 30 annual times to maturity) and CA (d = 120 quarterly times to maturity) ZCB yield curves (training: 1995–2015)
 - lacktriangle Marginal deARMA–GARCHing \Rightarrow standardized residuals $(\hat{m{Z}}_t)_t$
 - ▶ PCA \Rightarrow d = 3 (US data) and d = 4 (CA data) account for $\geq 95\%$ of the total variance
 - ▶ **Performance** evaluation on 1y (CA) and 1/2y (US) test data:

- Dependence: $\mathrm{AMMD} = \frac{1}{100} \sum_{i=1}^{100} \mathrm{MMD}(U^{(i)}, \hat{U}; K_{\mathsf{tst}})$, where $U^{(i)}$ is the ith matrix of generated data and \hat{U} are the pseudo-observations of the test data.
- Better one-day ahead empirical predictive distributions:

$$AVS^{1/4} = \frac{1}{T - \tau} \sum_{t=\tau+1}^{T} \sum_{j_1=1}^{d} \sum_{j_2=1}^{d} \left(|X_{t,j_1} - X_{t,j_2}|^{1/4} - \frac{1}{1000} \sum_{i=1}^{1000} |\hat{X}_{t,j_1}^{(i)} - \hat{X}_{t,j_2}^{(i)}|^{1/4} \right)^2$$

For both datasets, the GMMN–GARCH models better matched the cross-sectional dependence on the test datasets.

2) Exchange rates w.r.t. USD and w.r.t. GBP

- ► CAD, GBP, EUR, CHF, JPY w.r.t. USD and of CAD, USD, EUR, CHF, JPY, CNY w.r.t. GBP (training: 2000–2015; test: 2015)
- ▶ AMMD and $AVS^{1/4}$ as before.
- $\blacktriangleright \text{ VEAR}_{\alpha} = \left| \alpha \frac{1}{T \tau} \sum_{t=\tau+1}^{T} \mathbb{1}_{\left\{ S_{t} < \widehat{\mathsf{VaR}}_{\alpha}(\hat{S}_{t}) \right\}} \right| \text{ (VaR ex. abs. err.)}$
- For both datasets, the GMMN–GARCH models produced better daily $VaR_{0.05}(S_t)$ forecasts.

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