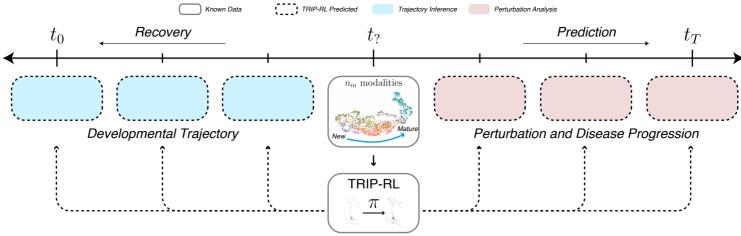
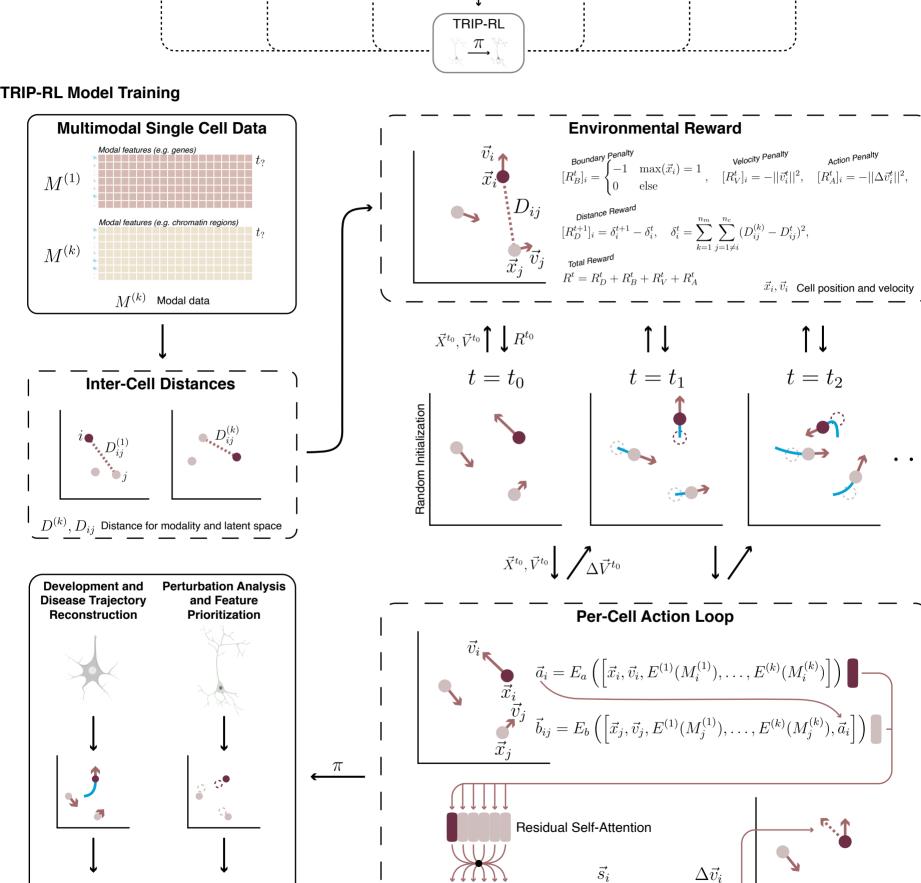
Flowchart





 $ec{a}_i, ec{b}_{ij}$ Cell and neighbor embeddings

 $ec{s}_i, \Delta ec{v}_i$ State and action vectors

 π Trained policy

 $E^{(k)}$ Encoder for modality k

 E_a, E_b, E_s Cell, neighbor, and state encoders