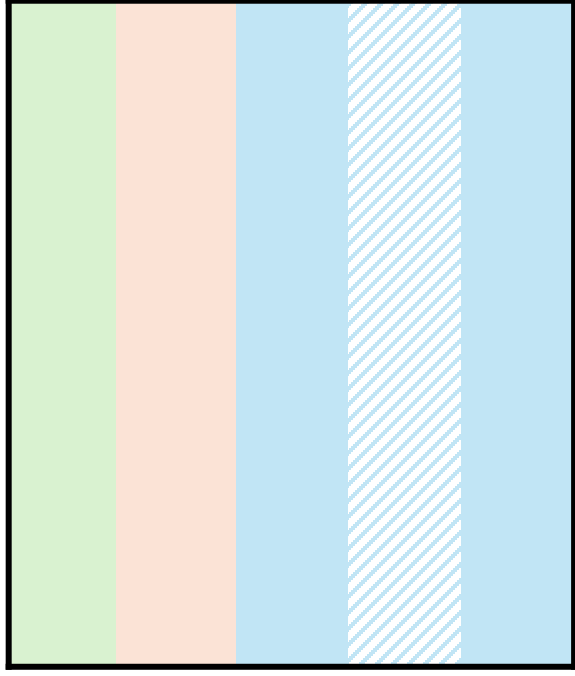


Cells



*Position*

*Velocity*

*Modality 1*

*Modality 2*

*Modality n*