

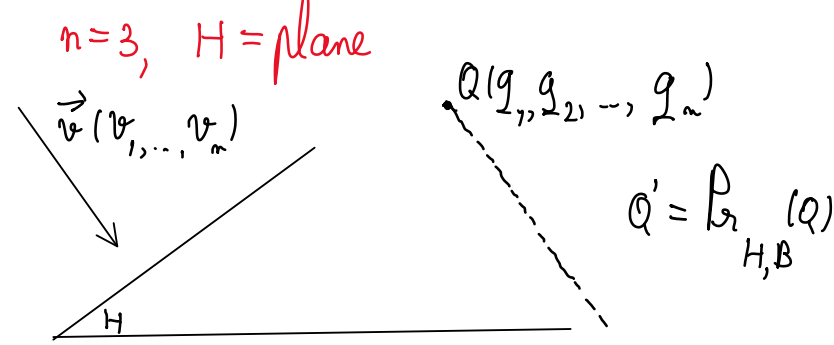
# Seminar 8

24.04.2023

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## Projections and reflections onto a hyperplane

**Def:** In an  $n$ -dimensional euclidean space  $E$  a hyperplane is a set of the form  $H = \{ (x_1, x_2, \dots, x_n) \mid a_1 x_1 + a_2 x_2 + \dots + a_n x_n + a_{n+1} = 0 \}$   
For  $n=2$ ,  $H = \text{line}$   
 $n=3$ ,  $H = \text{plane}$



$$Q' = Q \cap H$$

$$l = Q + t \vec{v} : \begin{cases} x_1 = q_1 + t v_1 \\ x_2 = q_2 + t v_2 \\ \vdots \\ x_n = q_n + t v_n \end{cases}$$

$$Q' : \begin{cases} x_1 = q_1 + t v_1 \\ x_2 = q_2 + t v_2 \\ \vdots \\ a_1 x_1 + a_2 x_2 + \dots + a_n x_n + a_{n+1} = 0 \end{cases}$$

$$Q' : \begin{cases} \text{---} || \text{---} \\ a_1(q_1 + t v_1) + a_2(q_2 + t v_2) + \dots + a_n q_n + a_{n+1} = 0 \end{cases}$$

$$t(a_1 v_1 + \dots + a_n v_n) + a_1 q_1 + a_2 q_2 + \dots + a_n q_n + a_{n+1} = 0$$

$$t = - \frac{a_1 q_1 + \dots + a_n q_n + a_{n+1}}{a_1 v_1 + \dots + a_n v_n}$$

$$Q' = \begin{cases} x_1 = q_1 - \frac{a_1 q_1 + \dots + a_n q_n + a_{n+1}}{a_1 v_1 + \dots + a_n v_n} \cdot v_1 \\ \vdots \\ x_n = q_n - \frac{a_1 q_1 + \dots + a_n q_n + a_{n+1}}{a_1 v_1 + \dots + a_n v_n} \cdot v_n \end{cases}$$

$$P(x_1, \dots, x_n), P'(x'_1, \dots, x'_n), P' = P_{H, \vec{v}}(P)$$

$$[P']_R = [P]_R - \frac{a_1 x_1 + \dots + a_n x_n + a_{n+1}}{a_1 v_1 + \dots + a_n v_n} \cdot [\vec{v}]_R \quad (*)$$

## Tensor product:

$$\vec{v}(v_1, v_2, \dots, v_n), \vec{w}(w_1, w_2, \dots, w_n) \in V^n$$

$$\vec{v} \otimes \vec{w} = \vec{v} \cdot \vec{w}$$

$$\vec{v} \otimes \vec{w} = \begin{pmatrix} v_1 w_1 + v_1 w_2 + \dots + v_1 w_n \\ v_2 w_1 + v_2 w_2 + \dots + v_2 w_n \\ \vdots \\ v_n w_1 + v_n w_2 + \dots + v_n w_n \end{pmatrix}$$

$$A, B \in M_{n,m}(\mathbb{R}), A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1m} \\ \vdots & \vdots & & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nm} \end{pmatrix}$$

$$A \otimes B = \begin{pmatrix} a_{11} B & a_{12} B & \dots & a_{1m} B \\ \vdots & \vdots & & \vdots \\ a_{n1} B & a_{n2} B & \dots & a_{nm} B \end{pmatrix}$$

$$\left( \begin{array}{c|c} 1 & 2 \\ \hline 3 & 4 \end{array} \right) \otimes \left( \begin{array}{c|c} 0 & -1 \\ \hline 1 & 1 \end{array} \right) = \begin{pmatrix} 0 & -1 & 0 & -2 \\ 1 & 1 & 2 & 2 \\ 0 & -3 & 0 & -4 \\ 3 & 3 & 4 & 4 \end{pmatrix}$$

$$e(x_1, x_2, \dots, x_n) = a_1 x_1 + a_2 x_2 + \dots + a_n x_n + a_{n+1}$$

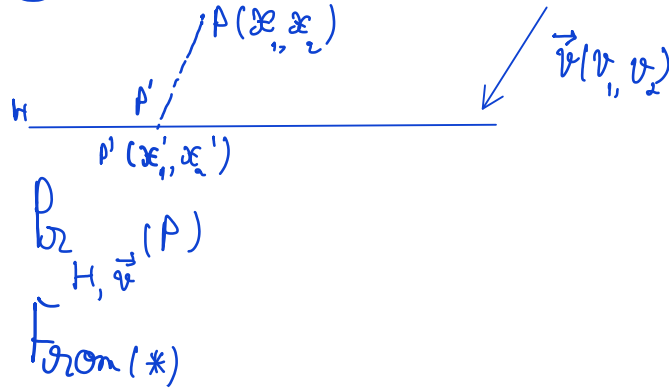
$$H: e(x_1, \dots, x_n) = 0$$

$$(\lim e)(x_1, x_2, \dots, x_n) = a_1 x_1 + \dots + a_n x_n$$

$$[P']_R = [P]$$

$$[P']_R = \frac{1}{\lim e(\vec{v})} \cdot \underbrace{(\vec{a} \cdot \vec{v}) \cdot I_n - \vec{v} \otimes \vec{a}}_{n \times n} \cdot [P]_R - \frac{a_{n+1}}{\lim e(\vec{v})} \cdot [\vec{v}]_R$$

2D



$$\begin{pmatrix} x'_1 \\ x'_2 \end{pmatrix} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} - \frac{a_1 x_1 + a_2 x_2 + a_3}{a_1 v_1 + a_2 v_2} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \Leftrightarrow$$

$$\Leftrightarrow \begin{pmatrix} x'_1 \\ x'_2 \end{pmatrix} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} - \frac{a_1 x_1 + a_2 x_2 + a_3}{\lim e(v)} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \Leftrightarrow$$

$$\Leftrightarrow \begin{pmatrix} x'_1 \\ x'_2 \end{pmatrix} = \frac{1}{\lim e v} \left( \vec{a} \cdot \vec{v} \cdot \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} - a_1 x_1 + a_2 x_2 \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \right) - \frac{a_3}{\lim e(v)} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \Leftrightarrow$$

$$\Leftrightarrow \begin{pmatrix} x'_1 \\ x'_2 \end{pmatrix} = \frac{1}{\lim e v} \left( \vec{a} \cdot \vec{v} - (a_1 \ a_2) \cdot \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} + (a_1 \ a_2) \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \right) - \frac{a_3}{\lim e(v)} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \Leftrightarrow$$

$$\Leftrightarrow \begin{pmatrix} x'_1 \\ x'_2 \end{pmatrix} = \frac{1}{\lim e v} \left( (\vec{a} \cdot \vec{v}) \cdot I_2 - \vec{v} \otimes \vec{a} \right) \cdot [P]_R - \frac{a_{n+1}}{\lim e(\vec{v})} [\vec{v}]_R$$

$$b) \vec{v}(2, 1, 1) \in V^3$$

$$a(1, 3, 2, 2) \in E^3$$

a) Give the matrix form to the parallel proj:  $z=0$

along the line  $Q + \langle v \rangle$

$$e(x, y, z) = z$$

$$\lim e(x, y, z) = z$$

$$\vec{a} = (0, 0, 1)$$

$$\vec{v} = (2, 1, 1)$$

$$[P]_{H, \vec{v}} = \frac{1}{1} \left( (1 \cdot I_3 - \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} \cdot (0 \ 0 \ 1)) \cdot [P] \right)$$

$$= \left( \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} - \begin{pmatrix} 0 & 0 & 2 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} \right) \cdot [P] =$$

$$= \begin{pmatrix} 1 & 0 & -2 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{pmatrix} [P]$$

$$\text{Ref}(P) = 2 \cdot [P]_{H, \vec{v}} \cdot [P] = 2 \cdot \begin{pmatrix} 1 & 0 & -2 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{pmatrix} [P] = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} [P] = \begin{pmatrix} 1 & 0 & -4 \\ 0 & 1 & -2 \\ 0 & 0 & -1 \end{pmatrix} [P]$$