```
> with(Student[LinearAlgebra]): with(LinearAlgebra): with(linalg):
> A := Matrix([[0, -2, 0], [1, -2, 0], [0, 0, -2]])
                                                     A := \left| \begin{array}{ccc} 0 & 2 & 0 \\ 1 & -2 & 0 \\ 0 & 0 & -2 \end{array} \right|
                                                                                                                                          (1)
> det(A)
                                                                                                                                          (2)
> inverse(A)
                                                     \begin{bmatrix} -\frac{1}{2} & 0 & 0 \\ 0 & 0 & -\frac{1}{2} \end{bmatrix}
                                                                                                                                          (3)
> Determinant(A);
                                                                 -4
                                                                                                                                          (4)

    CharacteristicPolynomial(A,r);
                                                     r^3 + 4r^2 + 6r + 4
                                                                                                                                          (5)
-2
-1 - I
-1 + I
                                                                                                                                          (6)
> lam,P:=Eigenvectors(A);
                                      lam, P := \begin{bmatrix} -1+I \\ -1-I \\ -2 \end{bmatrix}, \begin{bmatrix} 1+I & 1-I & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}
                                                                                                                                          (7)
> lam
                                                       \begin{vmatrix} -1+I\\-1-I\\-2 \end{vmatrix}
                                                                                                                                          (8)

\begin{bmatrix}
1 + I & 1 - I & 0 \\
1 & 1 & 0 \\
0 & 0 & 1
\end{bmatrix}

                                                                                                                                          (9)
                                                          uI := \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}
                                                                                                                                        (10)
```

```
lam1:=-2
                                                                        lam1 := -2
                                                                                                                                                                      (11)
> u2:=<1 + I, 1, 0>
                                                                    u2 := \begin{bmatrix} 1+I\\1\\0 \end{bmatrix}
                                                                                                                                                                      (12)
                                                                     lam2 := -1 + I
                                                                                                                                                                      (13)
> u3:=<1 - I, 1, 0>
                                                                    u3 := \begin{bmatrix} 1 - I \\ 1 \\ 0 \end{bmatrix}
                                                                                                                                                                      (14)
                                                                     lam3 := -1 - I
                                                                                                                                                                      (15)
                                                                                                                                                                      (16)
                                                                             \left[\begin{array}{c} 0 \\ 0 \\ 0 \end{array}\right]
                                                                                                                                                                      (17)
                                                                             \left[\begin{array}{c} 0 \\ 0 \\ 0 \end{array}\right]
                                                                                                                                                                      (18)
> P:=<u1|u2|u3>
                                                            P := \left[ \begin{array}{cccc} 0 & 1 + \mathbf{I} & 1 - \mathbf{I} \\ 0 & 1 & 1 \\ 1 & 0 & 0 \end{array} \right]
                                                                                                                                                                      (19)
> J:=DiagonalMatrix([lam1,lam2,lam3])
                                                         J := \begin{bmatrix} -2 & 0 & 0 \\ 0 & -1 + I & 0 \\ 0 & 0 & -1 - I \end{bmatrix}
                                                                                                                                                                      (20)
> A=P.J.P^(-1)
                                                                                                                                                                      (21)
```

```
\begin{vmatrix} 0 & -2 & 0 \\ 1 & -2 & 0 \\ 0 & 0 & -2 \end{vmatrix} = \begin{vmatrix} 0 & -2 & 0 \\ 1 & -2 & 0 \\ 0 & 0 & -2 \end{vmatrix}
                                                                                                       (21)
 > MatrixExponential(t*J)
                      e^{-2t} 0 0
0 e^{-t}\cos(t) + Ie^{-t}\sin(t) 0
0 0 e^{-t}\cos(t) - Ie^{-t}\sin(t)
                                                                                                       (22)
> E:=MatrixExponential(t*A)
                          e^{-t}\sin(t) + e^{-t}\cos(t)  -2 e^{-t}\sin(t) 0
                   E := \begin{vmatrix} e^{-t}\sin(t) & e^{-t}\cos(t) - e^{-t}\sin(t) & 0 \\ 0 & 0 & e^{-2t} \end{vmatrix}
                                                                                                       (23)
> Map(limit, E, t=infinity)
                                                                                                       (24)
=
> limit(E[1,1],t=infinity)
                                                  0
                                                                                                       (25)
> limit(E[1,2],t=infinity)
                                                  0
                                                                                                       (26)
> limit(E[1,3],t=infinity)
                                                  0
                                                                                                       (27)
\rightarrow limit(E[2, 1], t = infinity)
                                                  0
                                                                                                       (28)
> limit(E[2, 2], t = infinity)
                                                  0
                                                                                                       (29)
> limit(E[2, 3], t = infinity)
                                                  0
                                                                                                       (30)
> limit(E[3, 1], t = infinity)
                                                  0
                                                                                                       (31)
\vdash limit(E[3, 2], t = infinity)
                                                  0
                                                                                                       (32)
> limit(E[3,3], t = infinity)
                                                  0
                                                                                                       (33)
```

```
P := \begin{bmatrix} -1 & 0 & 0 & 3 \\ 0 & 5 & 2 & 1 \\ 2 & 0 & 0 & 0 \\ -3 & 1 & -2 & -1 \end{bmatrix}
                                                                                                                                         (34)
 > det(P)
                                                                                                                                         (35)
 > J:=DiagonalMatrix([2,2,-1,0])
                                                    J \coloneqq \left| \begin{array}{cccc} 2 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right|
                                                                                                                                         (36)
                                                \begin{bmatrix} 0 & 0 & -1 & 0 \\ \frac{1}{3} & \frac{3}{2} & \frac{47}{12} & \frac{5}{2} \\ 0 & 0 & 2 & 0 \\ -\frac{1}{3} & \frac{1}{2} & -\frac{47}{12} & -\frac{1}{2} \end{bmatrix}
                                                                                                                                         (37)
 > solve(1-x^2=0,x)
                                                                                                                                         (38)
> phim2:=rhs(dsolve({diff(x(t),t)=1-x(t)^2,x(0)=-2},x(t)))
                                             phim2 := tanh(t - arctanh(2))
                                                                                                                                         (39)
> convert(convert(phim2,exp),exp)
                                                                                                                                         (40)
> eval(phim2,t=0)
                                                                                                                                         (41)
 > solm2:=unapply((exp(2*t)+3)/(exp(2*t)-3),t)
                                                    solm2 := t \rightarrow \frac{e^{2t} + 3}{e^{2t} + 3}
                                                                                                                                         (42)
simplify(diff(solm2(t),t)-1+solm2(t)^2)
                                                                                                                                         (43)
> solm2(0)
                                                                 -2
                                                                                                                                         (44)
> solve(3*cosh(t)^2-4,t)
                                                                                                                                         (45)
```





