

RINDLER METRIC

Written by Daniel Volinski at danielvolinski@yahoo.es

```
(%i2) info:build_info()$info@version;
```

(%o2)

5.38.1

```
(%i2) reset()$kill(all)$
```

```
(%i1) derivabbrev:true$
```

```
(%i2) ratprint:false$
```

```
(%i3) fpprintprec:5$
```

```
(%i4) if get('draw','version')=false then load(draw)$
```

```
(%i5) wxplot_size:[1024,768]$
```

```
(%i6) if get('optvar','version')=false then load(optvar)$
```

```
(%i7) if get('rkf45','version')=false then load(rkf45)$
```

```
(%i8) declare(trigsimp,evfun)$
```

```
(%i9) declare(s,mainvar)$
```

1 Settings

(%i10) ct_coords:[ξ, τ]

(%i11) dim:length(ct_coords)

Line element

(%i12) ldisplay(ds²=line_element: $\xi^2 \text{del}(\tau)^2 - \text{del}(\xi)^2$)

$$ds^2 = \xi^2 \text{del}(\tau)^2 - \text{del}(\xi)^2 \quad (\%t12)$$

Covariant Metric Tensor

(%i16) lg:zeromatrix(dim,dim)
 for i thru dim do
 lg[i,i]:coeff(expand(line_element),del(ct_coords[i])²)
 for j thru dim do
 for k thru dim do
 if j≠k then lg[j,k]: $\frac{1}{2}$ *coeff(coeff(line_element,del(ct_coords[j])),del(ct_coords[k]))
 ldisplay(lg)

$$lg = \begin{pmatrix} -1 & 0 \\ 0 & \xi^2 \end{pmatrix} \quad (\%t16)$$

2 Using optvar

(%i17) depends(ct_coords,s)\$

Lagrangian

(%i18) params:[m=1]\$

(%i19) ldisplay(L:½*m*diff(ct_coords,s).lg.transpose(diff(ct_coords,s)))\$

$$L = \frac{m \left(\xi^2 (\tau_s)^2 - (\xi_s)^2 \right)}{2} \quad (\%t19)$$

Momentum Conjugate

(%i20) ldisplay(P_ξ:ev(diff(L,'diff(ξ,s))))\$

$$P_\xi = -m (\xi_s) \quad (\%t20)$$

(%i21) linsolve(p_ξ=P_ξ,diff(ξ,s)),factor;

$$\left[\xi_s = -\frac{p_\xi}{m} \right] \quad (\%o21)$$

(%i22) ldisplay(P_τ:ev(diff(L,'diff(τ,s))))\$

$$P_\tau = m \xi^2 (\tau_s) \quad (\%t22)$$

(%i23) linsolve(p_τ=P_τ,diff(τ,s)),factor;

$$\left[\tau_s = \frac{p_\tau}{m \xi^2} \right] \quad (\%o23)$$

Generalized Forces

(%i24) ldisplay(F_ξ:diff(L,ξ))\$

$$F_\xi = m \xi (\tau_s)^2 \quad (\%t24)$$

(%i25) ldisplay(F_τ:diff(L,τ))\$

$$F_\tau = 0 \quad (\%t25)$$

Euler-Lagrange Equations

```
(%i26) aa:el(L,ct_coords,s)$
(%i30) bb:ev(aa,eval,diff)$
(%i32) bb[1]:subst([k[0]=-E],-bb[1])$
      bb[4]:subst([k[2]=Lambda],bb[4])$
(%i36) bb[1]:rhs(bb[1])=lhs(bb[1])$
      bb[2]:lhs(bb[2])-rhs(bb[2])=0$
      bb[3]:lhs(bb[3])-rhs(bb[3])=0$
      bb[4]:rhs(bb[4])=lhs(bb[4])$
```

Conservation Laws

```
(%i37) map(ldisp,part(bb,[1,4]))$
```

$$E = -\frac{m \left(\xi^2 (\tau_s)^2 - (\xi_s)^2 \right)}{2} + m \xi^2 (\tau_s)^2 - m (\xi_s)^2 \quad (\%t37)$$

$$\Lambda = m \xi^2 (\tau_s) \quad (\%t38)$$

Express the Energy in terms of the Angular Momentum

```
(%i39) linsolve(eliminate(part(bb,[1,4]),[diff(tau,s)]),E),expand;
```

$$\left[E = \frac{\Lambda^2}{2m \xi^2} - \frac{m (\xi_s)^2}{2} \right] \quad (\%o39)$$

Equations of Motion

```
(%i40) map(ldisp,part(bb,[2,3]))$
```

$$-m \xi (\tau_s)^2 - m (\xi_{ss}) = 0 \quad (\%t40)$$

$$m \xi^2 (\tau_{ss}) + 2m \xi (\xi_s) (\tau_s) = 0 \quad (\%t41)$$

Solve for second derivative of coordinates

```
(%i42) linsol:linsolve(part(bb,[2,3]),diff(ct_coords,s,2))$
```

```
(%i43) map(ldisp,linsol)$
```

$$\xi_{ss} = -\xi (\tau_s)^2 \quad (\%t43)$$

$$\tau_{ss} = -\frac{2 (\xi_s) (\tau_s)}{\xi} \quad (\%t44)$$

Check Conservation of Energy

```
(%i45) subst(linsol,diff(rhs(bb[1]),s));
```

$$0 \quad (\%o45)$$

Check Conservation of Angular momentum

```
(%i46) subst(linsol,diff(rhs(bb[4]),s));
```

$$0 \quad (\%o46)$$

Legendre Transformation

```
(%i47) Legendre:linsolve([p_x=P_x,p_tau=P_tau],[diff(xi,s),diff(tau,s)])$
```

```
(%i48) map(ldisp,Legendre)$
```

$$\xi_s = -\frac{p_\xi}{m} \quad (\%t48)$$

$$\tau_s = \frac{p_\tau}{m \xi^2} \quad (\%t49)$$

Hamiltonian

```
(%i50) ldisplay(H:radcan(subst(Legendre,p_x*'diff(xi,s)+p_tau*'diff(tau,s)-L)))$
```

$$H = -\frac{p_\xi^2 \xi^2 - p_\tau^2}{2m \xi^2} \quad (\%t50)$$

```
(%i51) ldisplay(H:ev(p_x*'diff(xi,s)+p_tau*'diff(tau,s)-L,Legendre,radcan))$
```

$$H = -\frac{p_\xi^2 \xi^2 - p_\tau^2}{2m \xi^2} \quad (\%t51)$$

Equations of Motion

```
(%i52) Hq:makelist(Hq[i],i,1,2*dim)$
```

```
(%i56) Hq[1]:'diff(xi,s)=diff(H,p_x)$
      Hq[2]:'diff(tau,s)=diff(H,p_tau)$
      Hq[3]:'diff(p_x,s)=-diff(H,xi)$
      Hq[4]:'diff(p_tau,s)=-diff(H,tau)$
```

```
(%i57) map(ldisp,radcan(Hq))$
```

$$\xi_s = -\frac{p_\xi}{m} \quad (\%t57)$$

$$\tau_s = \frac{p_\tau}{m \xi^2} \quad (\%t58)$$

$$p_{\xi s} = \frac{p_\tau^2}{m \xi^3} \quad (\%t59)$$

$$p_{\tau s} = 0 \quad (\%t60)$$

Check Conservation of Energy

```
(%i61) depends([p_x,p_tau],s)$
```

```
(%i62) subst(Hq,diff(H,s)),fullratsimp;
```

$$0 \quad (\%o62)$$

Reduce Order

```
(%i64) cv_coords:[Ξ,T]$  
      depends(cv_coords,s)$
```

```
(%i66) gradev(ξ,s,Ξ)$  
      gradev(τ,s,T)$
```

Euler-Lagrange Equations

```
(%i67) aa:el(L,ct_coords,s)$  
(%i71) bb:ev(aa,eval,diff)$  
(%i73) bb[1]:subst([k[0]=-E],-bb[1])$  
      bb[4]:subst([k[2]=Λ],bb[4])$  
(%i77) bb[1]:rhs(bb[1])=lhs(bb[1])$  
      bb[2]:lhs(bb[2])-rhs(bb[2])=0$  
      bb[3]:lhs(bb[3])-rhs(bb[3])=0$  
      bb[4]:rhs(bb[4])=lhs(bb[4])$
```

Conservation Laws

```
(%i78) map(ldisp,part(bb,[1,4]))$
```

$$E = -\frac{m(T^2\xi^2 - \Xi^2)}{2} + mT^2\xi^2 - m\Xi^2 \quad (\%t78)$$

$$\Lambda = mT\xi^2 \quad (\%t79)$$

Equations of Motion

```
(%i80) map(ldisp,part(bb,[2,3]))$
```

$$-mT^2\xi - m(\Xi_s) = 0 \quad (\%t80)$$

$$m(T_s)\xi^2 + 2m\Xi T\xi = 0 \quad (\%t81)$$

Solve for second derivative of coordinates

```
(%i82) linsol:linsolve(part(bb,[2,3]),diff(ct_coords,s,2))$
```

```
(%i83) map(ldisp,linsol)$
```

$$\Xi_s = -T^2\xi \quad (\%t83)$$

$$T_s = -\frac{2\Xi T}{\xi} \quad (\%t84)$$

Numerical solution (Lagrangian)

(%i85) kill(labels)\$

(%i8) funcs:append(ct_coords,cv_coords)\$ldisplay(funcs)\$
initial:[8,10,0.01,-0.02]\$ldisplay(initial)\$
odes:append(cv_coords,map('rhs,linsol))\$ldisplay(odes)\$
interval:[s,0,50]\$ldisplay(interval)\$

$$funcs = [\xi, \tau, \Xi, T] \quad (\%t2)$$

$$initial = [8, 10, 0.01, -0.02] \quad (\%t4)$$

$$odes = \left[\Xi, T, -T^2\xi, -\frac{2\Xi T}{\xi} \right] \quad (\%t6)$$

$$interval = [s, 0, 50] \quad (\%t8)$$

(%i9) P:map("=",funcs,initial);

$$[\xi = 8, \tau = 10, \Xi = 0.01, T = -0.02] \quad (P)$$

(%i10) lgP:lg,P,params;

$$\begin{pmatrix} -1 & 0 \\ 0 & 64 \end{pmatrix} \quad (lgP)$$

(%i11) gVV:diff(ct_coords).lgP.transpose(diff(ct_coords));

$$64T^2 \text{del}(s)^2 - \Xi^2 \text{del}(s)^2 \quad (gVV)$$

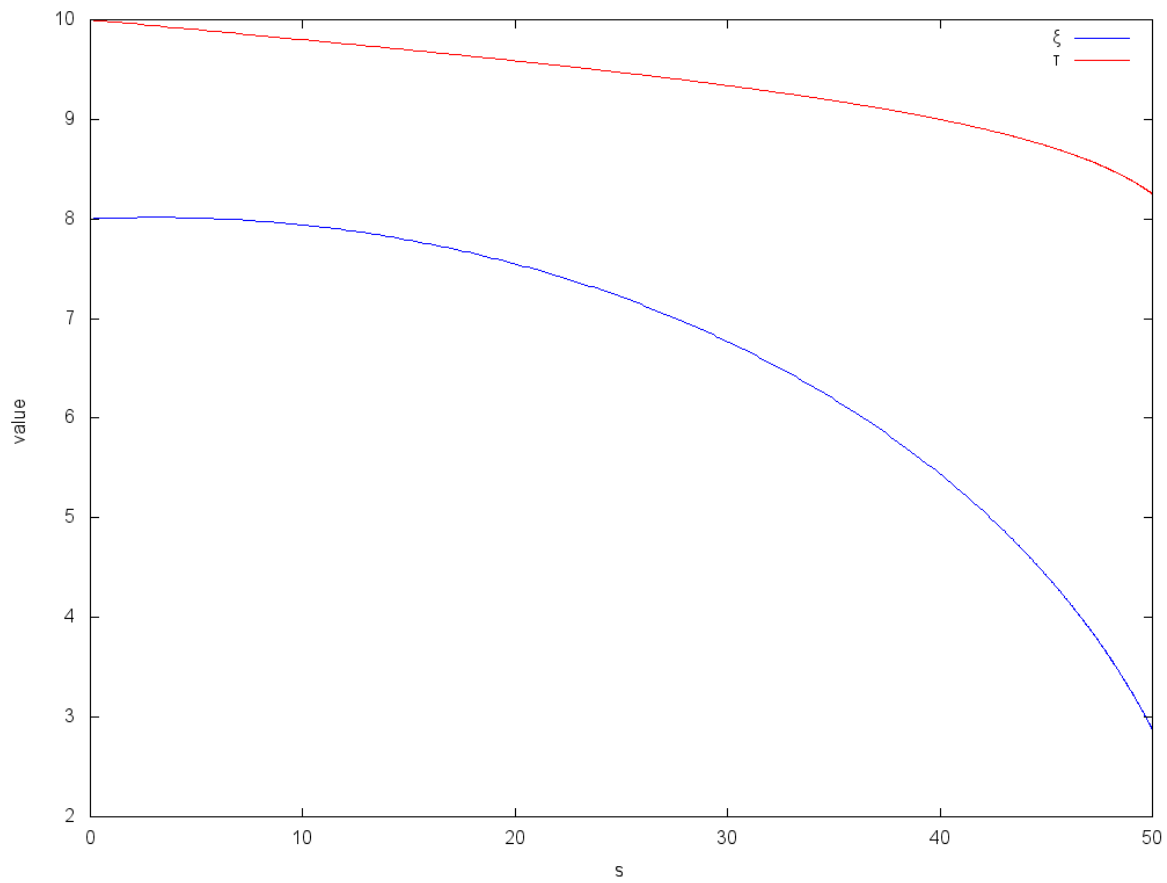
(%i12) gVVP:gVV,P,params;

$$0.0255 \text{del}(s)^2 \quad (gVVP)$$

(%i13) rksol:rkf45(odes,funcs,initial,interval, absolute_tolerance=1E-12,report=true),params\$

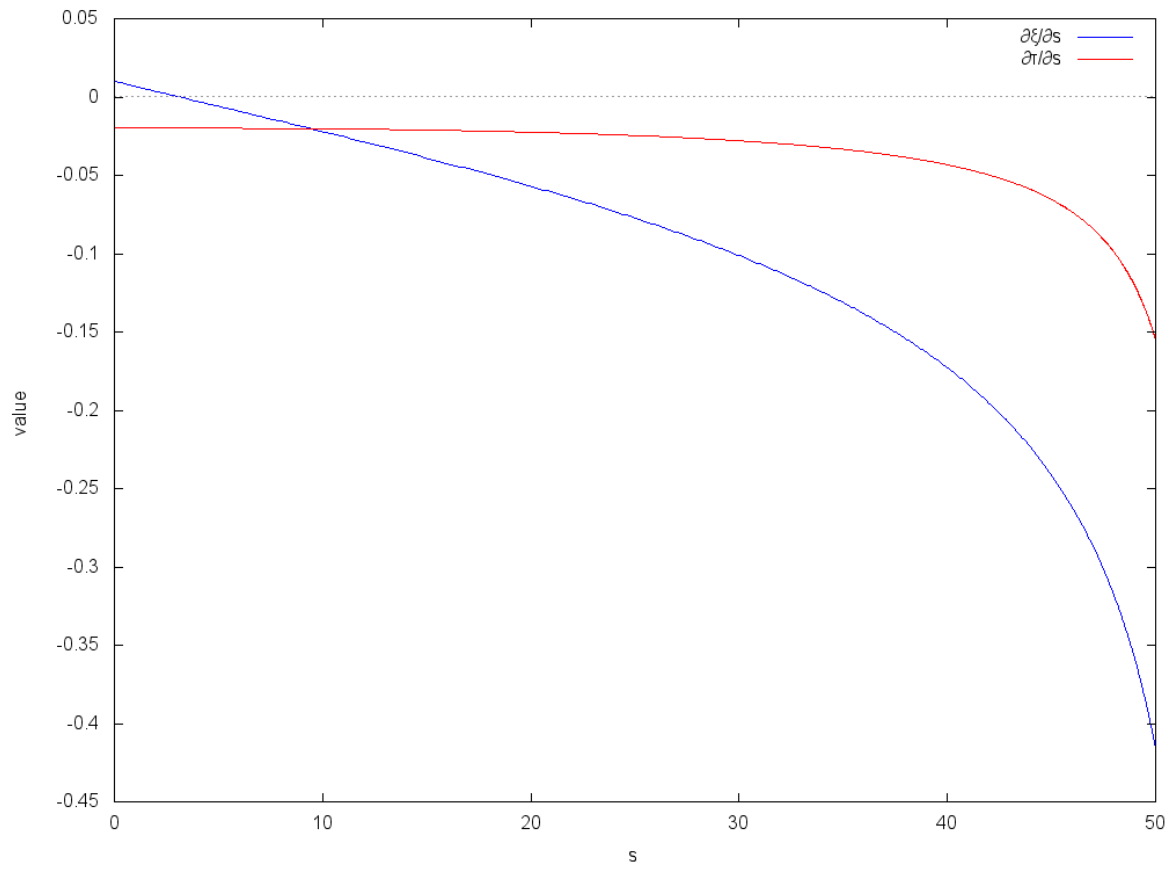
Info: rkf45:
Integration points selected:563
Total number of iterations:563
Bad steps corrected:1
Minimum estimated error:5.047210⁻¹⁴
Maximum estimated error:5.884210⁻¹³
Minimum integration step taken:0.0077667
Maximum integration step taken:0.36342

```
(%i14) wxplot2d([[discrete,map(lambda([u],part(u,[1,2])),rksol)], [discrete,map(lambda([u],part(u,[1,3]
[style,[lines,1]], [xlabel,"s"], [ylabel,"value"], [legend," $\xi$ ", " $\tau$ "], [gnuplot_preamble,"set
key top right"])]$
```



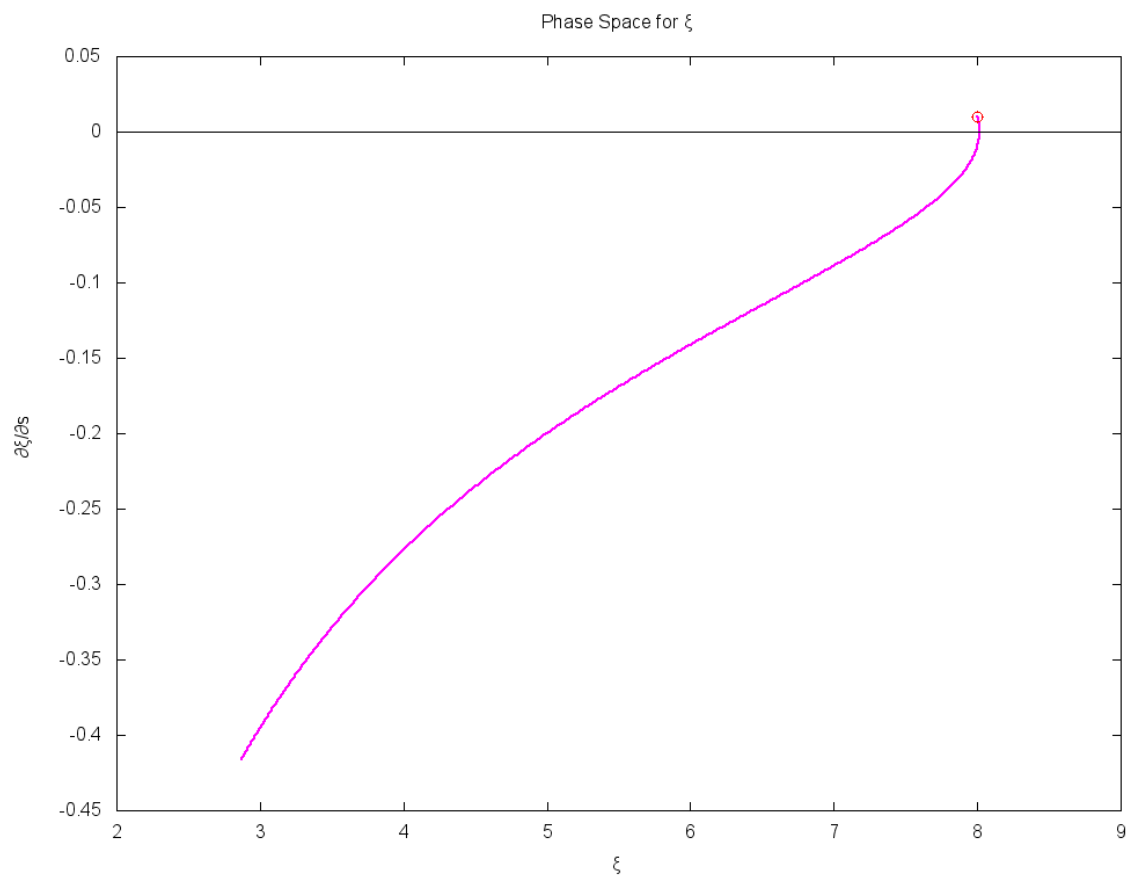
(%t14)


```
(%i15) wxplot2d([[discrete,map(lambda([u],part(u,[1,4])),rksol)], [discrete,map(lambda([u],part(u,[1,5]
[style,[lines,1]], [xlabel,"s"], [ylabel,"value"], [legend," $\partial\xi/\partial s$ "," $\partial\tau/\partial s$ "],
[gnuplot_preamble,"set key top right"])]$
```



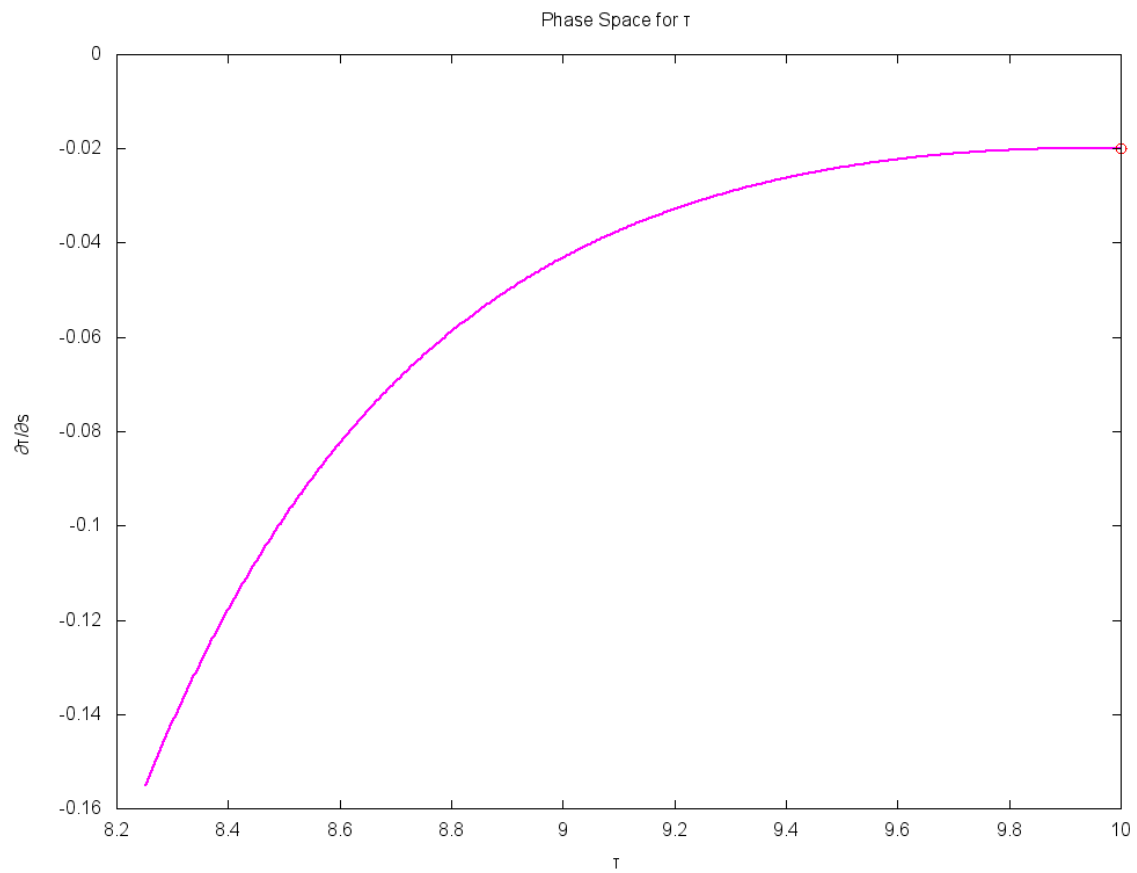
(%t15)

```
(%i16) wxplot2d([[discrete,map(lambda([u],part(u,[2,4])),rksol)], [discrete,[part(initial,[1,3])]]], [ax
[title,"Phase Space for  $\xi$ "],[point_type,circle], [style,[lines,2],[points,3]],[color,magenta,red]
[xlabel," $\xi$ "],[ylabel," $\partial\xi/\partial s$ "],[legend,false]]$
```



(%t16)

```
(%i17) wxplot2d([[discrete,map(lambda([u],part(u,[3,5])),rksol)], [discrete,[part(initial,[2,4])]]], [ax
[title,"Phase Space for  $\tau$ "],[point_type,circle], [style,[lines,2],[points,3]],[color,magenta,red]
[xlabel," $\tau$ "],[ylabel," $\partial\tau/\partial s$ "],[legend,false])$
```



(%t17)

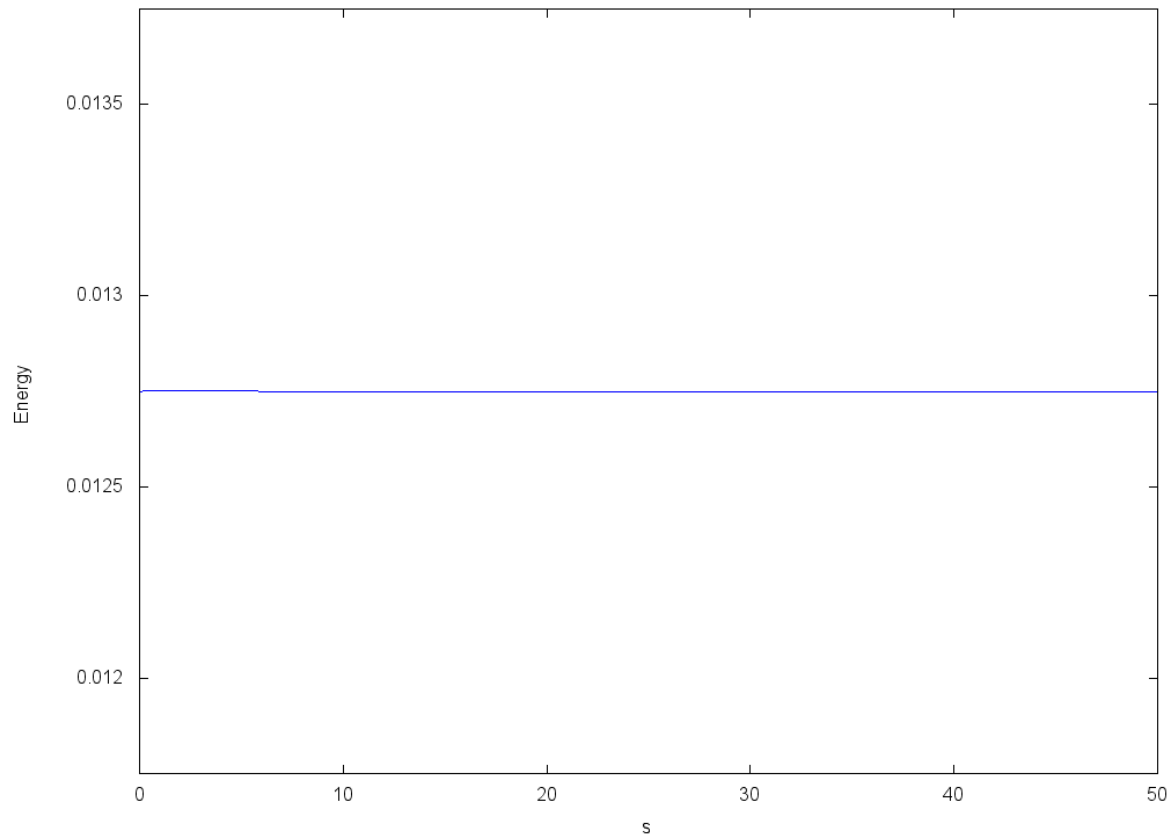
Check Conservation of Energy using the Numerical Data

```
(%i18) W:rhs(bb[1]),P,params,numer,eval;
```

0.01275

(W)

```
(%i19) wxplot2d([discrete,makelist([first(rkline), ev(rhs(bb[1]),map("=",funcs,rest(rkline)))],rkline,rkline,1,50),[xlabel,"s"],[ylabel,"Energy"],[y,W-0.001,W+0.001]),params$
```



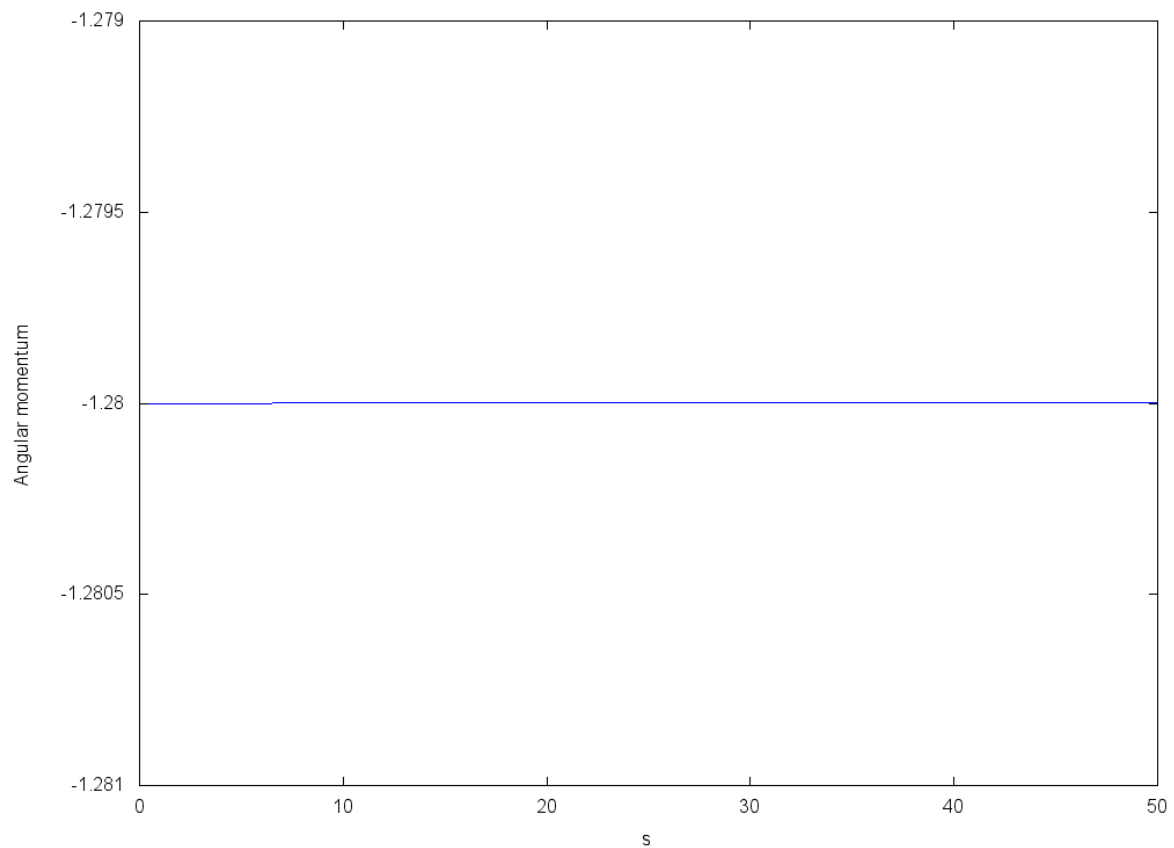
(%t19)

Check Conservation of Angular momentum using the Numerical Data

```
(%i20) W:rhs(bb[4]),P,params,numer,eval;
```

$$-1.28 \quad (W)$$

```
(%i21) wxplot2d([discrete,makelist([first(rkline), ev(rhs(bb[4]),map("=",funcs,rest(rkline)))],rkline,r
[xlabel,"s"],[ylabel,"Angular momentum"],[y,W-0.001,W+0.001]),params$
```



(%t21)

Numerical solution (Hamiltonian)

(%i22) kill(labels)\$

Calculate the initial values

(%i1) initialH:initial;

$[8, 10, 0.01, -0.02]$

(initialH)

(%i3) initialH[3]:P_ξ,['diff(ξ,s)=diff(ξ,s)],P,params,numer\$
initialH[4]:P_τ,['diff(τ,s)=diff(τ,s)],P,params,numer\$

(%i9) funcs:[ξ,τ,p_ξ,p_τ]\$ldisplay(funcs)\$
ldisplay(initialH)\$
odes:map('rhs,radcan(Hq))\$ldisplay(odes)\$
ldisplay(interval)\$

$funcs = [\xi, \tau, p_\xi, p_\tau]$ (%t5)

$initialH = [8, 10, -0.01, -1.28]$ (%t6)

$odes = \left[-\frac{p_\xi}{m}, \frac{p_\tau}{m\xi^2}, \frac{p_\tau^2}{m\xi^3}, 0 \right]$ (%t8)

$interval = [s, 0, 50]$ (%t9)

(%i10) rksol:rkf45(odes,funcs,initialH,interval, absolute_tolerance=1E-12,report=true),params\$

Info: rkf45:

Integration points selected:443

Total number of iterations:443

Bad steps corrected:1

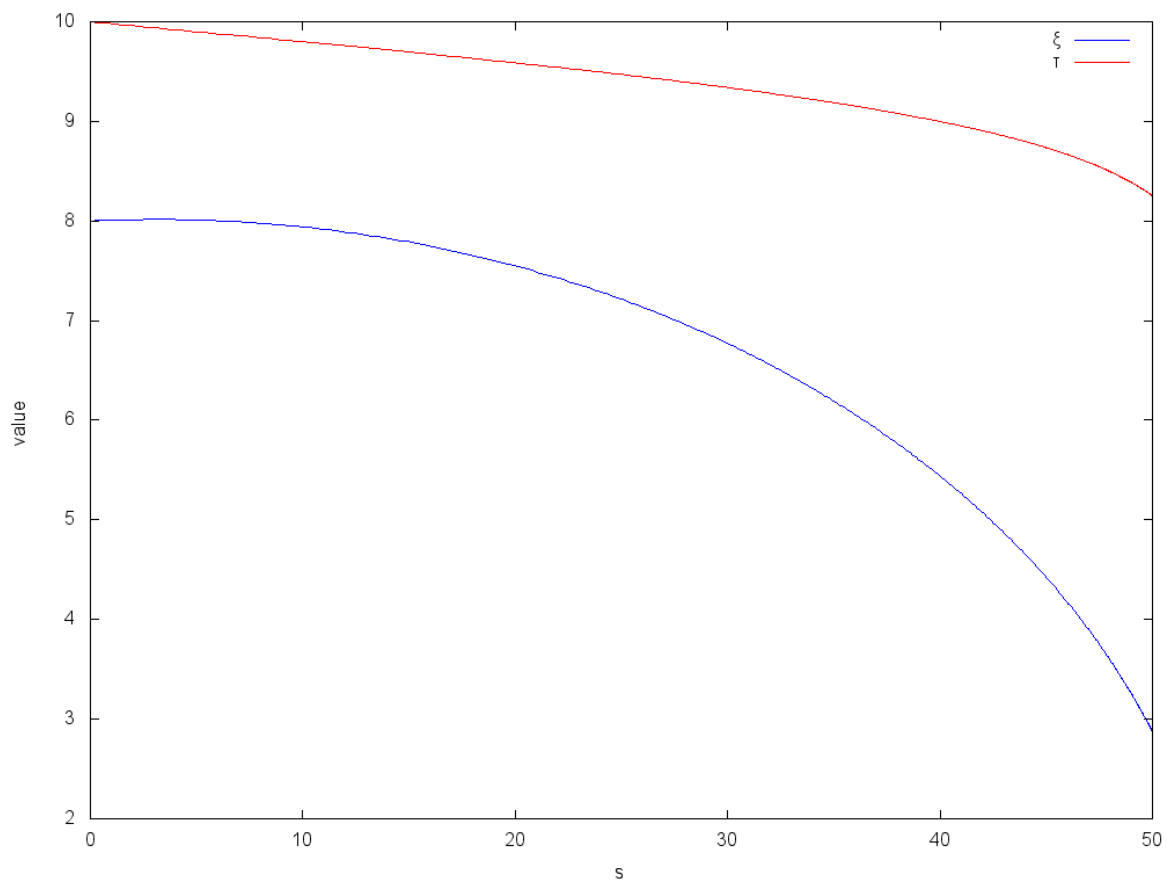
Minimum estimated error: 3.728710^{-18}

Maximum estimated error: 5.611510^{-13}

Minimum integration step taken: 5.679110^{-5}

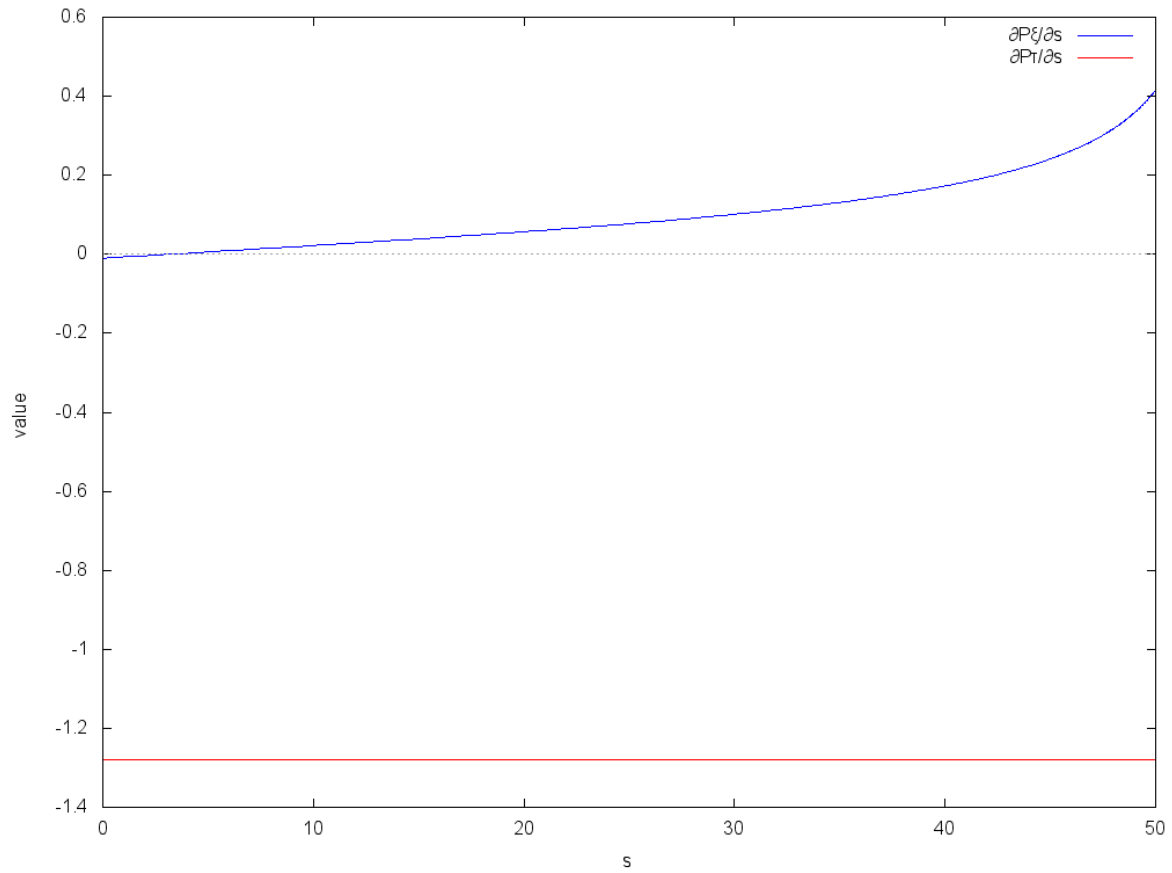
Maximum integration step taken:0.38395

```
(%i11) wxplot2d([[discrete,map(lambda([u],part(u,[1,2])),rksol)], [discrete,map(lambda([u],part(u,[1,3]
[style,[lines,1]], [xlabel,"s"], [ylabel,"value"], [legend," $\xi$ ", " $\tau$ "], [gnuplot_preamble,"set
key top right"])]$
```



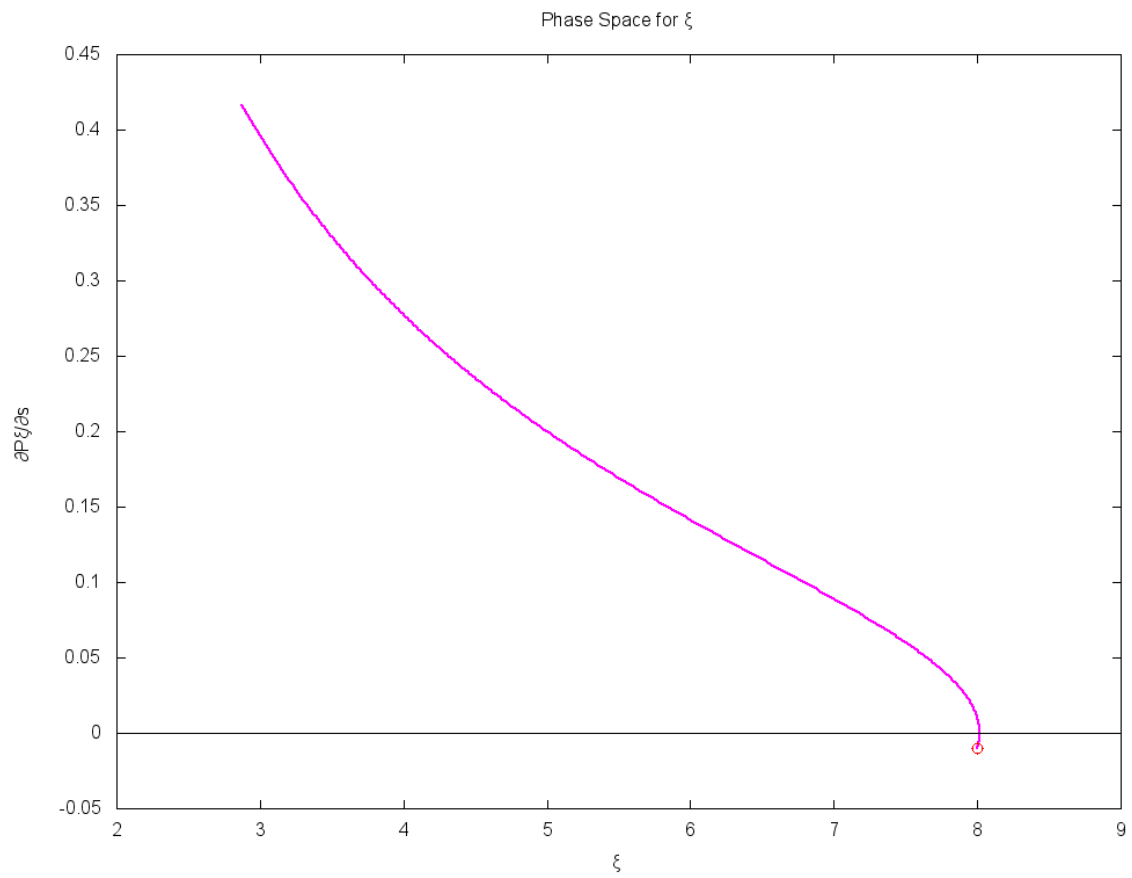
(%t11)

```
(%i12) wxplot2d([[discrete,map(lambda([u],part(u,[1,4])),rksol)], [discrete,map(lambda([u],part(u,[1,5]
[style,[lines,1]], [xlabel,"s"], [ylabel,"value"], [legend," $\partial P_\xi/\partial s$ ", " $\partial P_\tau/\partial s$ "],
[gnuplot_preamble,"set key top right"])]$
```



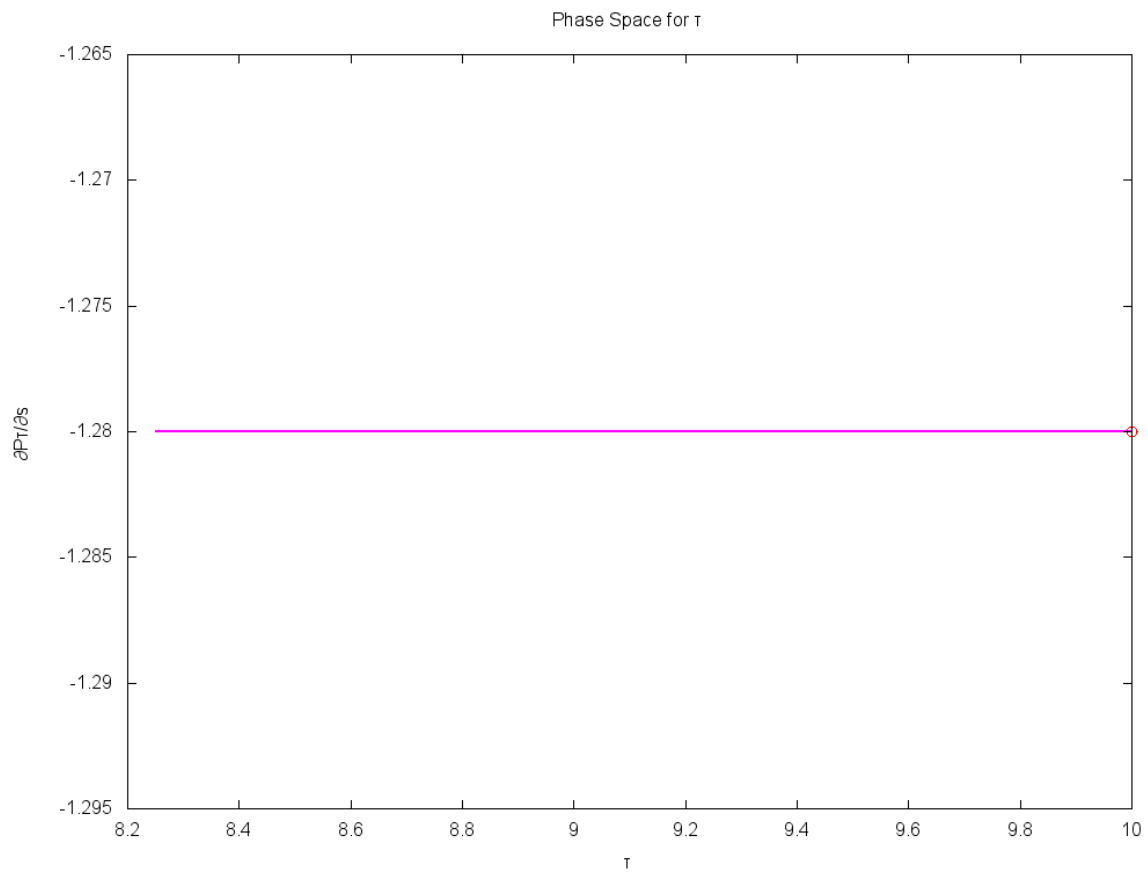
(%t12)


```
(%i13) wxplot2d([[discrete,map(lambda([u],part(u,[2,4])),rksol)], [discrete,[part(initial,[1,3])]]], [ax
[title,"Phase Space for  $\xi$ "],[point_type,circle], [style,[lines,2],[points,3]],[color,magenta,red]
[xlabel," $\xi$ "],[ylabel," $\partial P\xi/\partial s$ "],[legend,false])$
```



(%t13)

```
(%i14) wxplot2d([[discrete,map(lambda([u],part(u,[3,5])),rksol)], [discrete,[part(initial,[2,4])]]], [ax
[title,"Phase Space for  $\tau$ "],[point_type,circle], [style,[lines,2],[points,3]],[color,magenta,red]
[xlabel," $\tau$ "],[ylabel," $\partial P/\partial s$ "],[legend,false])$
```



(%t14)

Check Conservation of Energy using the Numerical Data

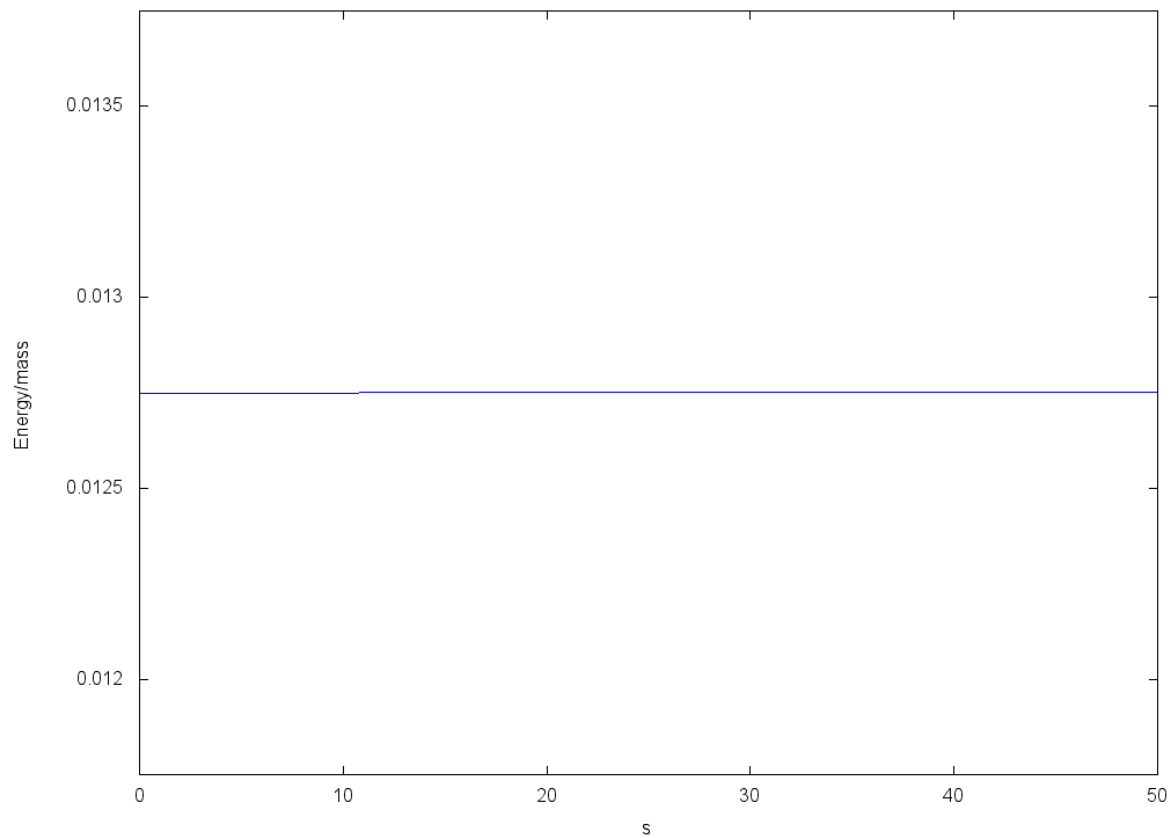
```
(%i15) P:map("=",funcs,initialH)$
```

```
(%i16) Y:H,P,params,numeric;
```

0.01275

(Y)

```
(%i17) wxplot2d([discrete,makelist([first(rkline), ev(H,map("=",funcs,rest(rkline))))],rkline,rksol)],  
[xlabel,"s"],[ylabel,"Energy/mass"],[y,Y-0.001,Y+0.001]),params$
```



(%t17)

3 Using ctensor

```
(%i18) kill(labels)$
(%i1)  if get('itensor','version')=false then load(itensor)$
(%i2)  imetric(g)$
(%i3)  if get('ctensor','version')=false then load(ctensor)$
(%i4)  dim:length(ct_coords)$
(%i10) ctrgsimp:true$
      ratchristof:true$
      ratriemann:true$
      rateinstein:true$
      ratweyl:true$
      ratfac:true$
(%i11) cmetric()$
```

Covariant Metric tensor

```
(%i12) ishow(g([μ,ν],[ ])=lg)$
```

$$g_{\mu\nu} = \begin{pmatrix} -1 & 0 \\ 0 & \xi^2 \end{pmatrix} \quad (\%t12)$$

Contravariant Metric tensor

```
(%i13) ishow(g([ ],[μ,ν])=ug)$
```

$$g^{\mu\nu} = \begin{pmatrix} -1 & 0 \\ 0 & \frac{1}{\xi^2} \end{pmatrix} \quad (\%t13)$$

Christoffel Symbol of the first kind

```
(%i15) christof(false)$
      for i thru dim do for j:i thru dim do for k thru dim do
      if lcs[i,j,k]≠0 then
      ishow(Γ([ct_coords[i],ct_coords[j],ct_coords[k]],[ ])=lcs[i,j,k])$
```

$$\Gamma_{\xi\tau\tau} = \xi \quad (\%t15)$$

$$\Gamma_{\tau\tau\xi} = -\xi \quad (\%t15)$$

Christoffel Symbol of the second kind

```
(%i17) christof(false)$
      for i thru dim do for j:i thru dim do for k thru dim do
      if mcs[i,j,k]≠0 then
      ishow(Γ([ct_coords[i],ct_coords[j]], [ct_coords[k]])=mcs[i,j,k])$
```

$$\Gamma_{\xi\tau}^{\tau} = \frac{1}{\xi} \quad (\%t17)$$

$$I_{\tau\tau}^{\xi} = \xi \quad (\%t17)$$

Riemann Tensor

```
(%i20) riemann(true)$
      lriemann(false)$
      uriemann(false)$
```

This spacetime is flat

Ricci Tensor

```
(%i22) ricci(true)$
      uricci(false)$
```

THIS SPACETIME IS EMPTY AND/OR FLAT

Scalar curvature

```
(%i23) scurvature();
```

$$0 \quad (\%o23)$$

Kretschmann invariant

```
(%i24) rinvariant();
```

$$0 \quad (\%o24)$$

Einstein Tensor

```
(%i26) einstein(true)$
      leinstein(false)$
```

THIS SPACETIME IS EMPTY AND/OR FLAT

Weyl Conformal tensor

```
(%i27) weyl(true)$
```

ALL 2 DIMENSIONAL SPACETIMES ARE CONFORMALLY FLAT

Geodesics

```
(%i28) cgeodesic(true)$
```

$$geod_1 = T^2\xi + \Xi_s \quad (\%t28)$$

$$geod_2 = \frac{(T_s)\xi + 2\Xi T}{\xi} \quad (\%t29)$$

Solve for second derivative of coordinates

```
(%i30) linsol:linsolve(listarray(geod),diff(ct_coords,s,2))$
```

```
(%i31) map(ldisp,linsol)$
```

$$\Xi_s = -T^2\xi \quad (\%t31)$$

$$T_s = -\frac{2\Xi T}{\xi} \quad (\%t32)$$