

# SHAIKOT DIFFERENTIAL FORMS

Based on Shaikot Jahan Shuvo Playlist: [Differential Forms](#)

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```
(%i2) info:build_info()$info@version;
```

(%o2)

5.38.1

```
(%i2) reset()$kill(all)$
```

```
(%i1) derivabbrev:true$
```

```
(%i2) load(linearalgebra)$
```

```
(%i3) load(draw)$
```

```
(%i4) wxplot_size:[1024,768]$
```

```
(%i5) load(drawdf)$
```

```
(%i6) if get('vect','version')=false then load(vect)$
```

```
(%i7) norm(u):=block(trigsimp(radcan( $\sqrt{(u.u)}$ )))$
```

```
(%i8) normalize(v):=block(v/norm(v))$
```

```
(%i9) if get('cartan','version')=false then load(cartan)$
```

```
(%i10) declare(trigsimp,evfun)$
```

**Define the space**

```
(%i11) r:[x,y,z]$
```

```
(%i12) scalefactors(r)$
```

```
(%i13) sf;
```

$[1, 1, 1]$

(%o13)

```
(%i14) sfprod;
```

1

(%o14)

```
(%i15) init_cartan(r)$
```

```
(%i16) cartan_coords;
```

$[x, y, z]$

(%o16)

```
(%i17) cartan_basis;
```

$[dx, dy, dz]$

(%o17)

(%i18) `cartan_dim;`

3

(%o18)

(%i19) `extdim;`

3

(%o19)

# 1 Introduction to Differential forms

```
(%i21) A:[2,3]$
      B:[1,-1]$
```

```
(%i22) A.B;
```

-1

(%o22)

Vector  $\vec{u}$

```
(%i23) kill(a,b,c)$
```

```
(%i24) u:[a,b,c]$
```

Scalar field  $f$

```
(%i25) depends(f,r)$
```

$\nabla f$

```
(%i26) gradf:ev(express(grad(f)),diff);
```

$[f_x, f_y, f_z]$

(gradf)

$u \cdot \nabla f$

```
(%i27) u.gradf;
```

$c(f_z) + b(f_y) + a(f_x)$

(%o27)

Define the space

```
(%i28) r:[x,y]$
```

```
(%i29) scalefactors(r)$
```

```
(%i30) init_cartan(r)$
```

Vector  $\vec{u}$

```
(%i31) u:['cos(pi/6)','sin(pi/6)]$
```

Scalar field  $f$

```
(%i32) ldisplay(f:y^2-3*x*y+x^3)$
```

$f = y^2 - 3xy + x^3$

(%t32)

$\nabla f$

```
(%i33) gradf:ev(express(grad(f)),diff);
```

$[3x^2 - 3y, 2y - 3x]$

(gradf)

## Potential

(%i34) potential(gradf);

$$y^2 - 3xy + x^3 \quad (\%o34)$$

$u \cdot \nabla f$

(%i35) u.gradf,ratsimp;

$$-\frac{\left(3^{\frac{3}{2}} - 2\right)y - 3^{\frac{3}{2}}x^2 + 3x}{2} \quad (\%o35)$$

Lie derivative

$\mathcal{L}_u f$

(%i36) lie.diff(u,f),ratsimp;

$$-\frac{\left(3^{\frac{3}{2}} - 2\right)y - 3^{\frac{3}{2}}x^2 + 3x}{2} \quad (\%o36)$$

## Check

(%i37) is(%th(1)=%th(2));

true (%o37)

$df(u)$

(%i38) u|ext\_diff(f),ratsimp;

$$-\frac{\left(3^{\frac{3}{2}} - 2\right)y - 3^{\frac{3}{2}}x^2 + 3x}{2} \quad (\%o38)$$

## Check

(%i39) is(%th(1)=%th(3));

true (%o39)

## Standard basis

(%i41) e\_1:[1,0]\$  
e\_2:[0,1]\$

$df(e_1)$

(%i42) e\_1|ext\_diff(f);

$$3x^2 - 3y \quad (\%o42)$$

$df(e_2)$

(%i43) e\_2|ext\_diff(f);

$$2y - 3x \quad (\%o43)$$

## 2 Differential 1-forms

```
(%i44) kill(labels,x,y,z,alpha,v)$
```

Define the space

```
(%i1) r:[x,y,z]$
```

```
(%i2) scalefactors(r)$
```

```
(%i3) init_cartan(r)$
```

$\alpha \in \mathcal{A}^1(\mathbb{R}^3), \quad \alpha = 2 \, dx - 3 \, dy + 5 \, dz$

```
(%i4) ldisplay(alpha:2*dx-3*dy+5*dz)$
```

$$\alpha = 5 \, dz - 3 \, dy + 2 \, dx \quad (\%t4)$$

Vector  $\vec{v}$

```
(%i5) v:[-1,3,-4]$
```

$v[\alpha] = \alpha(v)$

```
(%i6) v|alpha;
```

$$-31 \quad (\%o6)$$

### 3 Wedge product

```
(%i7) kill(labels,x_1,x_2,x_3)$
```

Define the space

```
(%i1) r:[x_1,x_2,x_3]$
```

```
(%i2) init_cartan(r)$
```

Vectors  $\vec{v}, \vec{w}$

```
(%i4) v:[1,2,3]$
```

```
w:[4,5,6]$
```

$\alpha \in \mathcal{A}^2(\mathbb{R}^3), \quad \alpha = dx_1 \wedge dx_2$

```
(%i5) ldisplay(alpha:dx_1~dx_2)$
```

$$\alpha = dx_1 dx_2 \quad (\%t5)$$

$\alpha(v, w)$

```
(%i6) w|(v|alpha);
```

$$-3 \quad (\%o6)$$

$\alpha(w, v)$

```
(%i7) v|(w|alpha);
```

$$3 \quad (\%o7)$$

## 4 Exterior derivative

```
(%i8) kill(labels,x,y,f,g)$
```

Define the space

```
(%i1) r:[x,y]$
```

```
(%i2) init_cartan(r)$
```

Scalar fields  $f, g$

```
(%i3) depends([f,g],r)$
```

$df \wedge dg$

```
(%i4) edit(ext_diff(f)~ext_diff(g));
```

$$((f_x) (g_y) - (f_y) (g_x)) \, dx \, dy \quad (\%o4)$$

```
(%i5) determinant(jacobian([f,g],r));
```

$$(f_x) (g_y) - (f_y) (g_x) \quad (\%o5)$$

Define the space

```
(%i6) r:[x,y,z]$
```

```
(%i7) init_cartan(r)$
```

Scalar field  $f$

```
(%i8) ldisplay(f:x^3*y^2*z^4)$
```

$$f = x^3 y^2 z^4 \quad (\%t8)$$

$$\alpha \in \mathcal{A}^1(\mathbb{R}^3), \quad \alpha = df$$

```
(%i9) ldisplay(alpha:edit(ext_diff(f)))$
```

$$\alpha = 4x^3 y^2 z^3 \, dz + 2x^3 y z^4 \, dy + 3x^2 y^2 z^4 \, dx \quad (\%t9)$$

$d(df)$

```
(%i10) edit(ext_diff(alpha));
```

$$0 \quad (\%o10)$$

```
(%i11) kill(x,y,z,alpha,beta,gamma)$
```

```
(%i12) depends([alpha,beta],r)$
```

Define the space

(%i13) r:[x,y,z]\$

(%i14) init\_cartan(r)\$

$\gamma \in \mathcal{A}^1(\mathbb{R}^3), \quad \gamma = d(\alpha \wedge \beta)$

(%i15) ldisplay( $\gamma$ :edit(ext\_diff( $\alpha \sim \beta$ ))))\$

$$\gamma = dz (\alpha (\beta_z) + (\alpha_z) \beta) + dy (\alpha (\beta_y) + (\alpha_y) \beta) + dx (\alpha (\beta_x) + (\alpha_x) \beta) \quad (\%t15)$$

$\gamma \in \mathcal{A}^1(\mathbb{R}^3), \quad \gamma = d\alpha \wedge \beta + \alpha \wedge d\beta$

(%i16) ldisplay( $\gamma$ :edit(ext\_diff( $\alpha \sim \beta + \alpha \sim \text{ext\_diff}(\beta)$ ))))\$

$$\gamma = dz (\alpha (\beta_z) + (\alpha_z) \beta) + dy (\alpha (\beta_y) + (\alpha_y) \beta) + dx (\alpha (\beta_x) + (\alpha_x) \beta) \quad (\%t16)$$

Define the space

(%i17) r:[x,y]\$

(%i18) init\_cartan(r)\$

$\gamma \in \mathcal{A}^1(\mathbb{R}^2), \quad \gamma = d(\alpha \wedge \beta)$

(%i19) ldisplay( $\gamma$ :edit(ext\_diff( $\alpha \sim \beta$ ))))\$

$$\gamma = dy (\alpha (\beta_y) + (\alpha_y) \beta) + dx (\alpha (\beta_x) + (\alpha_x) \beta) \quad (\%t19)$$

$\gamma \in \mathcal{A}^1(\mathbb{R}^2), \quad \gamma = d\alpha \wedge \beta + \alpha \wedge d\beta$

(%i20) ldisplay( $\gamma$ :edit(ext\_diff( $\alpha \sim \beta + \alpha \sim \text{ext\_diff}(\beta)$ ))))\$

$$\gamma = dy (\alpha (\beta_y) + (\alpha_y) \beta) + dx (\alpha (\beta_x) + (\alpha_x) \beta) \quad (\%t20)$$



## 5 Push forward of vectors

```
(%i21) kill(labels,x,y,u,v,a,b,f,phi,omega)$
```

Define the space

```
(%i1)  z:[x,y]$
```

```
(%i2)  init_cartan(z)$
```

Change of coordinates  $\varphi$

```
(%i3)  ldisplay(phi:[x+y,x-y])$
```

$$\varphi = [y + x, x - y] \quad (\%t3)$$

Inverse change of coordinates  $i\varphi$

```
(%i4)  xi:[u,v]$
```

```
(%i5)  ldisplay(iphi:map('rhs,linsolve(map("=",xi,phi),z)))$
```

$$i\varphi = \left[ \frac{v+u}{2}, \frac{u-v}{2} \right] \quad (\%t5)$$

Vector  $\vec{w}$

```
(%i6)  w:[a,b]$
```

Vector field  $\vec{f}$

```
(%i7)  f:[f_1,f_2]$
```

```
(%i8)  depends(f,z)$
```

$df$

```
(%i9)  ext_diff(f);
```

$$[(f_{1y}) dy + (f_{1x}) dx, (f_{2y}) dy + (f_{2x}) dx] \quad (\%o9)$$

$df(\vec{w})$

```
(%i10) w|ext_diff(f);
```

$$[b (f_{1y}) + a (f_{1x}), b (f_{2y}) + a (f_{2x})] \quad (\%o10)$$

Jacobian

```
(%i11) J:jacobian(f,z);
```

$$\begin{pmatrix} f_{1x} & f_{1y} \\ f_{2x} & f_{2y} \end{pmatrix} \quad (J)$$

$$J \cdot \vec{w}$$

```
(%i12) list_matrix_entries(J.w);
```

$$[b(f_{1y}) + a(f_{1x}), b(f_{2y}) + a(f_{2x})] \quad (\%o12)$$

**Vector**  $\vec{v}_1 = (1, 3)^T$

```
(%i13) ldisplay(v_1:[1,3])$
```

$$v_1 = [1, 3] \quad (\%t13)$$

**Jacobian of**  $\varphi$

```
(%i14) J:jacobian(phi,zeta);
```

$$\begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \quad (\text{J})$$

```
(%i15) ldisplay(w_1:list_matrix_entries(J.v_1))$
```

$$w_1 = [4, -2] \quad (\%t15)$$

$$\omega \in \mathcal{A}^2(\mathbb{R}^2), \quad \omega = dx \wedge dy$$

```
(%i16) ldisplay(omega:dx~dy)$
```

$$\omega = dx \, dy \quad (\%t16)$$

**Pullback**  $i\varphi^*\omega \in \mathcal{A}^2(\mathbb{R}^2)$

```
(%i17) ldisplay(Pb:diff(iphi,v)|(diff(iphi,u)|ev(omega,map("=",zeta,iphi))))$
```

$$Pb = -\frac{1}{2} \quad (\%t17)$$

**Define the new space**

```
(%i18) init_cartan(xi)$
```

$$\psi \in \mathcal{A}^2(\mathbb{R}^2), \quad \psi = i\varphi^*\omega \, du \wedge dv$$

```
(%i19) ldisplay(psi:Pb*(du~dv))$
```

$$\psi = -\frac{du \, dv}{2} \quad (\%t19)$$

$$\omega \in \mathcal{A}^2(\mathbb{R}^2), \quad \omega = du \wedge dv$$

```
(%i20) ldisplay(omega:du~dv)$
```

$$\omega = du \, dv \quad (\%t20)$$

**Pullback**  $\varphi^*\omega \in \mathcal{A}^2(\mathbb{R}^2)$

```
(%i21) ldisplay(Pb:diff(φ,y)|(diff(φ,x)|ev(ω,map("=",ξ,φ))))$
```

$$Pb = -2 \quad (\%t21)$$

**Define the old space**

```
(%i22) init_cartan(ζ)$
```

$$\psi \in \mathcal{A}^2(\mathbb{R}^2), \quad \psi = \varphi^*\omega \, dx \wedge dy$$

```
(%i23) ldisplay(ψ:Pb*(dx~dy))$
```

$$\psi = -2dx \, dy \quad (\%t23)$$

$$\omega \in \mathcal{A}^2(\mathbb{R}^2), \quad \omega = dx \wedge dy$$

```
(%i24) ldisplay(ω:dx~dy)$
```

$$\omega = dx \, dy \quad (\%t24)$$

**Standard basis**

```
(%i26) e_1:[1,0]$
```

```
      e_2:[0,1]$
```

$$(dx \wedge dy)(\vec{e}_1, \vec{e}_2)$$

```
(%i27) e_2|(e_1|ω);
```

$$1 \quad (\%o27)$$

$$P = J \cdot \vec{e}_1$$

```
(%i28) P:list_matrix_entries(J.e_1);
```

$$[1, 1] \quad (P)$$

$$Q = J \cdot \vec{e}_2$$

```
(%i29) Q:list_matrix_entries(J.e_2);
```

$$[1, -1] \quad (Q)$$

**Define the new space**

```
(%i30) init_cartan(ξ)$
```

$$\psi \in \mathcal{A}^2(\mathbb{R}^2), \quad \psi = du \wedge dv$$

```
(%i31) ldisplay(ψ:du~dv)$
```

$$\psi = du \, dv \quad (\%t31)$$

```
(%i32) Q|(P|ψ);
```

$$-2 \quad (\%o32)$$

## 6 Pullback of Differential forms

```
(%i33) kill(labels)$
```

## 7 Integration of forms

```
(%i1) kill(labels,x,y,u,v,f)$
```

Define the space

```
(%i1) ζ:[x,y]$
```

```
(%i2) init_cartan(ζ)$
```

Scalar field  $f(x, y)$

```
(%i3) f(x,y):=x$
```

```
(%i4) I:'integrate('integrate(f(x,y),x,y+2,0),y,-2,0)$
```

```
(%i5) ldisplay(I=ev(I,integrate))$
```

$$\int_{-2}^0 \int_{y+2}^0 x \, dx \, dy = -\frac{4}{3} \quad (\%t5)$$

Change of coordinates  $\varphi : \mathbb{R}^2 \rightarrow \mathbb{R}^2$

```
(%i6) ldisplay(φ:[x+y,x-y])$
```

$$\varphi = [y + x, x - y] \quad (\%t6)$$

Inverse change of coordinates  $i\varphi : \mathbb{R}^2 \rightarrow \mathbb{R}^2$

```
(%i7) ξ:[u,v]$
```

```
(%i8) ldisplay(iφ:map('rhs,linsolve(map("=",ξ,φ),ζ)))$
```

$$i\varphi = \left[ \frac{v+u}{2}, \frac{u-v}{2} \right] \quad (\%t8)$$

$\omega \in \mathcal{A}^2(\mathbb{R}^2)$ ,  $\omega = f(x, y) \, dx \wedge dy$

```
(%i9) ldisplay(ω:f(x,y)*(dx~dy))$
```

$$\omega = x \, dx \, dy \quad (\%t9)$$

Pullback  $i\varphi^* \omega \in \mathcal{A}^2(\mathbb{R}^2)$

```
(%i10) ldisplay(Pb:diff(iφ,v)|(diff(iφ,u)|ev(ω,map("=",ζ,iφ))))$
```

$$Pb = -\frac{v}{4} - \frac{u}{4} \quad (\%t10)$$

```
(%i11) I:'integrate('integrate(Pb,u,-v,v),v,0,2)$
```

```
(%i12) ldisplay(I=ev(I,integrate))$
```

$$\int_0^2 \int_{-v}^v -\frac{v}{4} - \frac{u}{4} \, du \, dv = -\frac{4}{3} \quad (\%t12)$$

$$\omega \in \mathcal{A}^2(\mathbb{R}^2), \quad \omega = y^2 dx + x dy$$

(%i13) `ldisplay( $\omega$ :y2*dx+x*dy)`

$$\omega = x dy + y^2 dx \quad (\%t13)$$

**Parametrization**  $i\varphi : \mathbb{R}^2 \rightarrow \mathbb{R}$

(%i14) `ldisplay( $i\varphi$ : [5*t-5, 5*t-3])`

$$i\varphi = [5t - 5, 5t - 3] \quad (\%t14)$$

$$T^* \varphi^{-1}$$

(%i15) `ldisplay( $i\varphi$ \':diff( $i\varphi$ ,t))`

$$i\varphi' = [5, 5] \quad (\%t15)$$

**Pullback**  $i\varphi^* \omega \in \mathcal{A}^1(\mathbb{R}^2)$

(%i16) `ldisplay( $Pb$ : $i\varphi$ \' | ev( $\omega$ ,map("=", $\zeta$ , $i\varphi$ )))`

$$Pb = 125t^2 - 125t + 20 \quad (\%t16)$$

(%i17) `I: 'integrate( $Pb$ ,t,0,1)`

(%i18) `ldisplay( $I$ =ev( $I$ ,integrate))`

$$\int_0^1 125t^2 - 125t + 20 dt = -\frac{5}{6} \quad (\%t18)$$

**Define the space**

(%i19)  `$\zeta$ : [x,y,z]`

(%i20) `init_cartan( $\zeta$ )`

$$\omega \in \mathcal{A}^2(\mathbb{R}^3), \quad \omega = z^2 dx \wedge dy$$

(%i21) `ldisplay( $\omega$ :z2*(dx~dy))`

$$\omega = z^2 dx dy \quad (\%t21)$$

**Parametrization**  $i\varphi : \mathbb{R}^3 \rightarrow \mathbb{R}^2$

(%i22) `kill(r,θ,ξ)`

(%i23)  `$\xi$ : [r,θ]`

(%i24) `ldisplay( $i\varphi$ : [r*cos(θ), r*sin(θ), sqrt(1-r2)])`

$$i\varphi = [r \cos(\theta), r \sin(\theta), \sqrt{1 - r^2}] \quad (\%t24)$$

$$T^*\varphi^{-1}$$

(%i25) J:jacobian(iφ,ξ);

$$\begin{pmatrix} \cos(\theta) & -r \sin(\theta) \\ \sin(\theta) & r \cos(\theta) \\ -\frac{r}{\sqrt{1-r^2}} & 0 \end{pmatrix} \quad (\text{J})$$

**Pullback**  $i\varphi^*\omega \in \mathcal{A}^2(\mathbb{R}^3)$

(%i26) ldisplay(Pb:trigsimp(diff(iφ,θ)|(diff(iφ,r)|ev(ω,map("=",ζ,iφ))))\$

$$Pb = r - r^3 \quad (\%t26)$$

(%i27) I:'integrate('integrate(Pb,r,0,1),θ,0,2\*π)\$

(%i28) ldisplay(I=ev(I,integrate))\$

$$2\pi \int_0^1 r - r^3 \, dr = \frac{\pi}{2} \quad (\%t28)$$