## PENDULUM

```
(%i2) info:build_info()$info@version;
                                                                                                               (\%o2)
5.38.1
(%i2) reset()$kill(all)$
(%i1) derivabbrev:true$
(%i2) ratprint:false$
(%i3) fpprintprec:5$
(%i4) if get('draw,'version)=false then load(draw)$
(%i5) wxplot_size:[1024,768]$
(%i6) if get('rkf45, 'version)=false then load(rkf45)$
(%i7) declare(trigsimp,evfun)$
(%i8) declare(t,mainvar)$
(%i9) orderless(g,A,\omega)$
(%i10) declare([g,A,\omega],constant)$
(\%i11) assume(g>0,A>0,\omega>0)$
(\%i12) params: [g=9.8,A=0.1,\omega=0.1]$
(\%i13) \tau:10$
(%i14) DE: 'diff(\theta,t,2)=A*cos(\theta)*\omega^2*cos(t*\omega)-g*sin(\theta);
                                      \theta_{tt} = A \omega^2 \cos(\theta) \cos(\omega t) - q \sin(\theta)
                                                                                                                (DE)
Small angles approximation
(%i16) C\theta:ratdisrep(taylor(\cos(\theta), \theta, 0, 1))$
         S\theta:ratdisrep(taylor(sin(\theta),\theta,0,1))$
(%i17) subst([\cos(\theta) = C\theta, \sin(\theta) = S\theta],DE);
                                             \theta_{tt} = A \omega^2 \cos(\omega t) - q\theta
                                                                                                              (\%o17)
(\%i18) ode2(\%, \theta, t);
                            \theta = -\frac{A\omega^2 \cos(\omega t)}{\omega^2 - a} + \%k1 \sin(\sqrt{g}t) + \%k2 \cos(\sqrt{g}t)
                                                                                                              (\%o18)
```

## Reduce order

(%i19) depends  $(\Theta,t)$ \$

(%i20) gradef( $\theta$ ,t, $\Theta$ )\$

(%i21) DE:ev(DE,diff,eval);

$$\Theta_t = A \omega^2 \cos(\theta) \cos(\omega t) - g \sin(\theta) \tag{DE}$$

(%i29) funcs:  $[\theta,\Theta]$  \$1display(funcs)\$

initial:  $[\pi/7,1]$  \$\text{ldisplay(initial)} \$\text{odes: } [\text{\$\text{\$\text{\$O\$}}, \text{\$rhs}(DE)]\$} \$\text{ldisplay(odes)}\$\$ interval:  $[t,0,\tau]$  \$\text{ldisplay(interval)}\$

$$funcs = [\theta, \Theta] \tag{\%t23}$$

$$initial = \left[\frac{\pi}{7}, 1\right] \tag{\%t25}$$

$$odes = [\Theta, A\omega^2 \cos(\theta) \cos(\omega t) - g\sin(\theta)]$$
 (%t27)

$$interval = [t, 0, 10] \tag{\%t29}$$

(%i30) rksol:rkf45(odes,funcs,initial,interval, absolute\_tolerance=1E-8,report=true),params\$

Info: rkf45:

 $Integration\ points\ selected: 893$ 

Total number of iterations:893

 $Bad\,steps\,corrected{:}1$ 

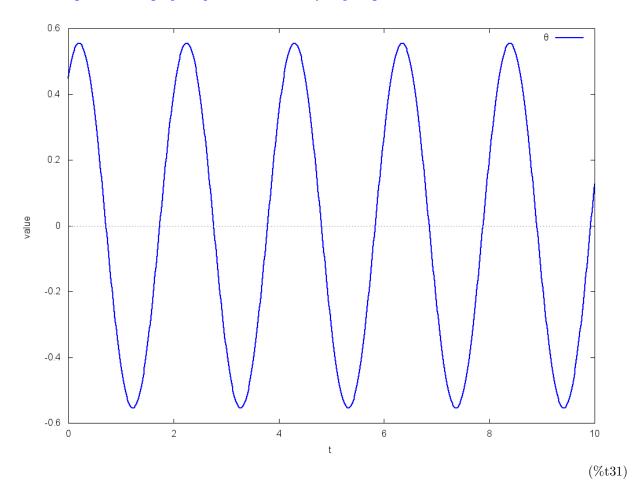
Minimum estimated error:  $3.90510^{-9}$ 

Maximum estimated error: 5.473610<sup>-9</sup>

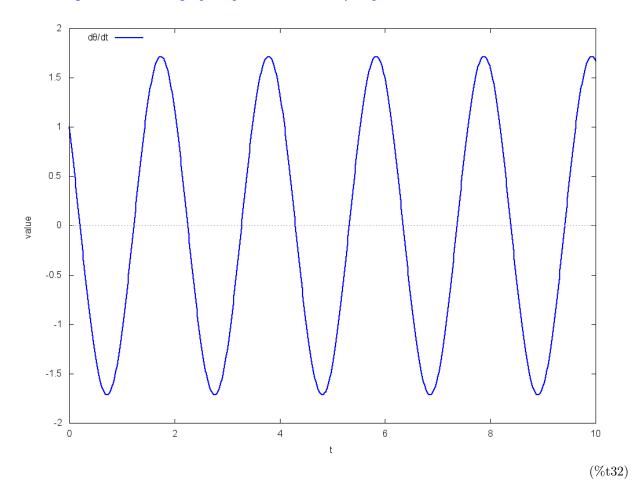
Minimum integration step taken: 0.010169

Maximum integration step taken: 0.01287

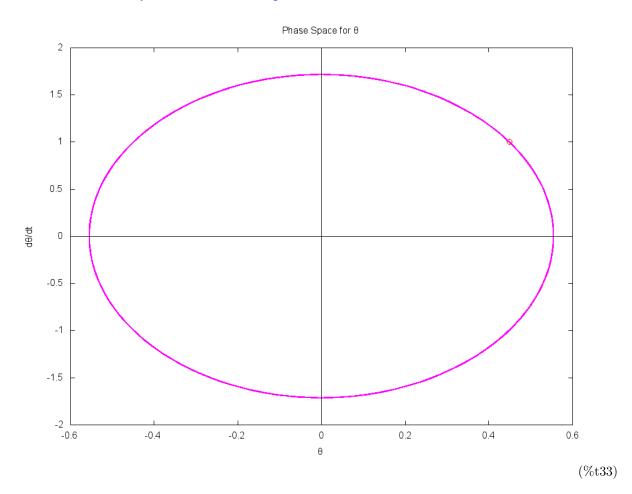
(%i31) wxplot2d([discrete,map(lambda([u],part(u,[1,2])),rksol)], [style,[lines,2]],[xlabel,"t"],[ylabel [legend," $\theta$ "],[gnuplot\_preamble,"set key top right"])\$



 $\begin{tabular}{ll} \begin{tabular}{ll} (\%i32) & $$ wxplot2d([discrete,map(lambda([u],part(u,[1,3])),rksol)], [style,[lines,2]],[xlabel,"t"],[ylabel [legend,"d$$$ d$$/dt"],[gnuplot_preamble,"set key top left"])$ \end{tabular}$ 



(%i33) wxplot2d([[discrete,map(lambda([u],part(u,[2,3])),rksol)], [discrete,[part(initial,[1,2])]]],[ax [title,"Phase Space for  $\theta$ "],[point\_type,circle], [style,[lines,2],[points,3]],[color,magenta,red] [xlabel," $\theta$ "],[ylabel,"d $\theta$ /dt"],[legend,false])\$



```
(%i34) kill(labels)$
(%i1) wxanimate_framerate:60$
(%i2) wxanimate_autoplay:false$
(%i3) rksol:rk(odes,funcs,initial,[t,0,\tau,0.1]),params$
(%i4) set_draw_defaults(proportional_axes = xy, delay = 1, xtics = 1, ytics = 1, xrange = [-1,1], yrange = [-1,0])$
Create animated GIF file

(%i5) draw(terminal = 'animated_gif, file_name = "Pendulum", makelist(gr2d( color = red, point_type = filled_circle, point_size = 2, points_joined = true, line_width = 2, key = sconcat("t=",float(t)/10," s"), points([[0.0,0.0], [sin(rksol[t][2]),-cos(rksol[t][2])])), t,1,length(rksol))),params$
(%i6) time(%);
```

```
(%i7) wxanimate_framerate:30$
(%i9) print("Click the figure to start animation") with_slider_draw(t,makelist(i,i,1,length(rksol)),
       color = red, point_type = filled_circle, point_size = 2, points_joined = true,
       line_width = 2, key = sconcat("t=",float(t)/10," s"), points([[0.0,0.0],
       [sin(rksol[t][2]),-cos(rksol[t][2])])),params$
Click the figure to start animation
```

(%t9)

(%o10)

[0.265]

(%i10) time(%);

```
(%i12) print("Click the figure to start animation")$ wxanimate_draw( t,length(rksol),
    color = red, point_type = filled_circle, point_size = 2, points_joined = true,
    line_width = 2, key = sconcat("t=",float(t)/10," s"), points([[0.0,0.0],
        [sin(rksol[t][2]),-cos(rksol[t][2])])),params$
```

Click the figure to start animation

(%t12) (%t13) time(%);

[0.203] (%o13)