https://github.com/t-o-k/Maxima-bezier/rational bezier surface 3d.wxmx

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- (%i1) kill(all)\$
- (%i1) load("draw")\$
- (%i2) load("bezier")\$
- (%i3) tau: 2*%pi\$
- (%i4) angle: tau/4;
- (angle) $\frac{\pi}{2}$
- (%i5) w: matrix([1.0, cos(angle/2), 1.0]);

(W)
$$\left(1.0 \ \frac{1}{\sqrt{2}} \ 1.0\right)$$

(%i6) weights: transpose(w).w;

(weights)
$$\begin{vmatrix} 1.0 & \frac{1.0}{\sqrt{2}} & 1.0 \\ \frac{1.0}{\sqrt{2}} & \frac{1}{2} & \frac{1.0}{\sqrt{2}} \\ 1.0 & \frac{1.0}{\sqrt{2}} & 1.0 \end{vmatrix}$$

The 9 points; $\langle x, y, z \rangle$ in the control grid:

This will create a surface that is 1/8 of the surface of a torus with major radius 2 and minor radius 1.

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(%i7) points_x:
          matrix(
            [3, 5, 5],
            [3, 5, 5],
            [3, 4, 4]
         )
       $
(%i8) points y:
          matrix(
            [2, 2, 4],
            [2, 2, 4],
            [ 3, 3, 4 ]
          )
       $
(%i9) points_z:
          matrix(
            [1, 1, 1],
            [2, 2, 2],
            [2, 2, 2]
       $
(%i10) define(f x(u, v), rational bezier function 2a(points x, weights, u, v));
(%010) f_x(u,v) := (4.0 u^2 v^2 + 4.0 \sqrt{2} (1-u) u v^2 + 3.0 (1-u)^2 v^2 +
       5.0\sqrt{2}u^{2}(1-v)v+10(1-u)u(1-v)v+3.0\sqrt{2}(1-u)^{2}(1-v)
       v+5.0 u^{2} (1-v)^{2}+5.0 \sqrt{2} (1-u) u (1-v)^{2}+3.0 (1-u)^{2} (1-v)^{2}
       )/(1.0 u^2 v^2 + 1.0 \sqrt{2} (1-u) u v^2 + 1.0 (1-u)^2 v^2 + 1.0 \sqrt{2} u^2
       (1-v)v+2(1-u)u(1-v)v+1.0\sqrt{2}(1-u)^{2}(1-v)v+1.0u^{2}
       (1-v)^2+1.0\sqrt{2}(1-u)u(1-v)^2+1.0(1-u)^2(1-v)^2
(%i11) define(f y(u, v), rational bezier function 2a(points y, weights, u, v));
(%011) f_v(u,v) := (4.0 u^2 v^2 + 3.0 \sqrt{2} (1-u) u v^2 + 3.0 (1-u)^2 v^2 +
       4.0\sqrt{2}u^{2}(1-v)v+4(1-u)u(1-v)v+2.0\sqrt{2}(1-u)^{2}(1-v)v
       +4.0 u^{2} (1-v)^{2} +2.0 \sqrt{2} (1-u) u (1-v)^{2} +2.0 (1-u)^{2} (1-v)^{2}
       /(1.0 u^2 v^2 + 1.0 \sqrt{2} (1-u) u v^2 + 1.0 (1-u)^2 v^2 + 1.0 \sqrt{2} u^2
       (1-v)v+2(1-u)u(1-v)v+1.0\sqrt{2}(1-u)^{2}(1-v)v+1.0u^{2}
       (1-v)^2+1.0\sqrt{2}(1-u)u(1-v)^2+1.0(1-u)^2(1-v)^2
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(%i12) define(f_z(u, v), rational_bezier_function_2a(points_z, weights, u, v));
(%012) f_z(u,v) := (2.0 u^2 v^2 + 2.0 \sqrt{2} (1-u) u v^2 + 2.0 (1-u)^2 v^2 +
         2.0\sqrt{2}u^{2}(1-v)v+4(1-u)u(1-v)v+2.0\sqrt{2}(1-u)^{2}(1-v)v
+1.0u^{2}(1-v)^{2}+1.0\sqrt{2}(1-u)u(1-v)^{2}+1.0(1-u)^{2}(1-v)^{2})
         /(1.0 u^2 v^2 + 1.0 \sqrt{2} (1-u) u v^2 + 1.0 (1-u)^2 v^2 + 1.0 \sqrt{2} u^2
         (1-v)v+2(1-u)u(1-v)v+1.0\sqrt{2}(1-u)^2(1-v)v+1.0u^2
(1-v)^2+1.0\sqrt{2}(1-u)u(1-v)^2+1.0(1-u)^2(1-v)^2
(%i13) wxplot3d(
            [f_x(u, v), f_y(u, v), f_z(u, v)],
            [ u, 0, 1 ],
            [v, 0, 1],
            same xyz
         );
                                              Parametric function
(%t13)
```