1.1 Introduction to package qm

The qm package was written by Eric Majzoub, University of Missouri (email: majzoube-at-umsystem.edu). EM thanks Maxima developers Robert Dodier and Barton Willis for their contributions that have improved the package considerably. Please report any errors or unexpected behavior by submitting an issue on the Github page for this project (https://github.com/QMeqGR/qm-maxima).

The purpose of this package is to provide computational tools for solving quantum mechanics problems in a finite-dimensional Hilbert space. It was written with students in mind as well as practitioners, and is appropriate for upper-level undergraduate quantum mechanics at the level of Townsend's *A Modern Introduction to Quantum Mechanics* and above. The package is loaded with: load(qm); If you use wxMaxima then issue load("wx.lisp"); after loading the qm package. This will allow pretty printing of the kets and bras similar to what you see in this manual.

1.1.1 Basic capabilities

The qm package provides functions and standard definitions to solve quantum mechanics problems in a finite dimensional Hilbert space. For example, one can calculate the outcome of Stern-Gerlach experiments using built-in definitions of the Sx, Sy, and Sz operators for arbitrary spin, e.g. s={1/2, 1, 3/2, ...}. For spin-1/2 the standard basis kets in the x, y, and z-basis are defined in the package as {xp,xm}, {yp,ym}, and {zp,zm}, respectively.

Brief list of some capabilities:

- Create kets and bras in a matrix representation with arbitrary but finite dimension.
- Create general ket vectors with arbitrary but finite dimension.
- Given an operator and a state ket, perform standard computations of expectation values, variance, etc.
- For time-independent Hamiltonians one can construct the time evolution operator and study, for example, magnetic resonance.
- Create kets and bras in the angular momentum $|j,m\rangle$ representation.
- Create tensor products of states to represent multi-particle systems.
- Compute Clebsch-Gordan coefficients by stepping up and down the ladder of states constructed using tensor products of $|j,m\rangle$ kets.
- Construct Bell states and compute quantities of interest for entangled systems such as density matrices.
- Perform partial traces over density matrices to compute reduced density matrices.

Let us begin with a trivial example involving spin-1/2 particles. This will illustrate how kets and bras in a matrix representation are defined within the qm package. A bra vector in the z-basis may be written as

$$$$

The bra <psi| will be represented in Maxima by the row vector [a b], where the basis vectors are

$$\langle z+| = [1 \ 0]$$

and

```
\langle z - | = [0 1].
```

This bra vector can be created with the mbra command

```
mbra([a,b])
```

or taking the quantum mechanical dagger of the corresponding ket. In a Maxima session this looks like the following. The basis kets {zp,zm} are transformed into bras using the dagger function.

1.1.2 Types of kets and bras

There are two types of kets and bras available in the qm package, the first type is given by a matrix representation, as returned by the functions mbra and mket. mkets are column vectors and mbras are row vectors, and their components are entered as Maxima lists in the mbra and mket functions. The second type of bra or ket is abstract; there is no matrix representation. Abstract bras and kets are entered using the bra and ket functions, while also using Maxima lists for the elements. These general kets are displayed in Dirac notation. Abstract bras and kets are used for both the (j,m) representation of states and also for tensor products. For example, a tensor product of two ket vectors |a> and |b> is input as ket([a,b]) and displayed as

```
|a,b> (general ket)
```

Note that abstract kets and bras are assumed to be orthonormal. These general bras and kets may be used to build arbitrarily large tensor product states.

The following examples illustrate some of the basic capabilities of the qm package. Here both abstract, and concrete (matrix representation) kets are shown. The last example shows how to construct an entangled Bell pair.

```
(%i1) ket([a,b])+ket([c,d]);
                                   |c, d\rangle + |a, b\rangle
(%o1)
(%i2) mket([a,b]);
                                         [a]
(\%02)
                                         [ b ]
(%i3) mbra([a,b]);
                                       [a b]
(%i4) bell:(1/sqrt(2))*(ket([u,d])-ket([d,u]));
                                   |u, d> - |d, u>
(\%04)
                                        sqrt(2)
(%i5) dagger(bell);
                                   <u, d| - <d, u|
(\%05)
                                        sqrt(2)
```

Note that ket([a,b]) is treated as tensor product of states a and b as shown below.

```
(%i1) braket(bra([a1,b1]),ket([a2,b2]));
(%o1) kron_delta(a1, a2) kron_delta(b1, b2)
```

Constants that multiply kets and bras must be declared complex by the user in order for the dagger function to properly conjugate such constants. The example below illustrates this behavior.

The following shows how to declare a ket with both real and complex components in the matrix representation.

1.1.3 Special ket types

Some kets are difficult to work with using either the matrix representation or the general ket representation. These include tensor products of (j,m) kets used in the addition of angular momentum computations. For this reason there are a set of tpkets and associated tpXX functions defined in section (j,m)-kets and bras.

1.1.4 Types of spin operators

When working with kets and bras in the matrix representation, use the spin operators Sxx. When working with abstract kets and bras in the (j,m) representation use the operators Jxx. The family of Sxx operators are represented as matrices in Maxima, while the family of Jxx operators are rule based or function based.

1.2 Functions and Variables for qm

hbar [Variable]

Planck's constant divided by 2*%pi. hbar is not given a floating point value, but is declared to be a real number greater than zero. If the system variable display2d_unicode is true then hbar will be displayed as its Unicode character.

 $ket ([k_1,k_2,...])$

[Function]

ket creates a general state ket, or tensor product, with symbols k_i representing the states. The state kets k_i are assumed to be orthonormal.

ketp (abstract ket)

[Function]

ketp is a predicate function for abstract kets. It returns true for abstract kets and false for anything else.

bra $([b_1,b_2,\ldots])$

[Function]

bra creates a general state bra, or tensor product, with symbols b_i representing the states. The state bras b_i are assumed to be orthonormal.

brap (abstract bra)

[Function]

brap is a predicate function for abstract bras. It returns true for abstract bras and false for anything else.

 $mket ([c_1,c_2,\ldots])$

[Function]

mket creates a *column* vector of arbitrary finite dimension. The entries c_i can be any Maxima expression. The user must declare any relevant constants to be complex. For a matrix representation the elements must be entered as a list in [...] square brackets.

mketp (ket) [Function]

mketp is a predicate function that checks if its input is an mket, in which case it returns true, else it returns false. mketp only returns true for the matrix representation of a ket.

mbra $([c_1, c_2, ...])$

[Function]

mbra creates a row vector of arbitrary finite dimension. The entries c_i can be any Maxima expression. The user must declare any relevant constants to be complex. For a matrix representation the elements must be entered as a list in [...] square brackets.

mbrap (bra) [Function]

mbrap is a predicate function that checks if its input is an mbra, in which case it returns true, else it returns false. mbrap only returns true for the matrix representation of a bra.

Two additional functions are provided to create kets and bras in the matrix representation. These functions conveniently attempt to automatically declare constants as complex. For example, if a list entry is a*sin(x)+b*cos(x) then only a and b will be declared complex and not x.

```
autoket ([a_1, a_2, \ldots])
```

[Function]

autoket takes a list $[a_1, a_2, ...]$ and returns a ket with the coefficients a_i declared complex. Simple expressions such as a*sin(x)+b*cos(x) are allowed and will declare only the coefficients as complex.

```
(%i1) autoket([a*sin(x),b*sin(x)]);
                                         [ a sin(x) ]
     (%01)
                                         [ b \sin(x) ]
     (%i2) facts();
            [kind(hbar, real), hbar > 0, kind(a, complex), kind(b, complex)]
     (%02)
autobra ([a_1, a_2, \ldots])
                                                                        [Function]
     autobra takes a list [a1, a2, ...] and returns a bra with the coefficients ai declare-
     d complex. Simple expressions such as a*sin(x)+b*cos(x) are allowed and will
     declare only the coefficients as complex.
     (%i1) autobra([a,b]);
                                           [a b]
     (%o1)
     (%i2) facts();
            [kind(hbar, real), hbar > 0, kind(a, complex), kind(b, complex)]
     (%o2)
     (\%i1) autobra([a*sin(x),b]);
                                       [a sin(x) b]
     (%o1)
     (%i2) facts();
             [kind(hbar, real), hbar > 0, kind(a, complex), kind(b, complex)]
dagger (vector)
                                                                        [Function]
     dagger is the quantum mechanical dagger function and returns the conjugate
     transpose of its input. Arbitrary constants must be declare-d complex for dagger
     to produce the conjugate.
     (%i1) dagger(mbra([%i,2]));
                                           Γ - %i ]
                                           [
     (%o1)
braket (psi,phi)
                                                                        [Function]
     Given a bra psi and ket phi, braket returns the quantum mechanical bracket
     <psi|phi>. Note, braket(b,k) is equivalent to b . k where . is the Maxima non-
     commutative dot operator.
     (%i1) declare([a,b,c],complex);
     (%01)
                                             done
     (%i2) braket(mbra([a,b,c]),mket([a,b,c]));
                                               2
     (%02)
                                         c + b + a
     (%i3) braket(dagger(mket([a,b,c])),mket([a,b,c]));
                     c conjugate(c) + b conjugate(b) + a conjugate(a)
     (%03)
     (%i4) braket(bra([a1,b1,c1]),ket([a2,b2,c2]));
     (\%04)
                 kron_delta(a1, a2) kron_delta(b1, b2) kron_delta(c1, c2)
norm (psi)
     Given a ket or bra psi, norm returns the square root of the quantum mechanical
```

bracket <psi|psi>. The vector psi must always be a ket, otherwise the function

will return false.

```
(%i1) declare([a,b,c],complex);
     (%o1)
                                            done
     (%i2) norm(mket([a,b,c]));
     (%o2)
                 sqrt(c conjugate(c) + b conjugate(b) + a conjugate(a))
magsqr (c)
                                                                      [Function]
     magsqr returns conjugate(c)*c, the magnitude squared of a complex number.
     (%i1) declare([a,b,c,d],complex);
     (%o1)
                                            done
     (%i2) A:braket(mbra([a,b]),mket([c,d]));
     (\%02)
                                         bd+ac
     (%i3) P:magsqr(A);
     (%o3) (b d + a c) (conjugate(b) conjugate(d) + conjugate(a) conjugate(c))
```

1.2.1 Spin-1/2 state kets and associated operators

Spin-1/2 particles are characterized by a simple 2-dimensional Hilbert space of states. It is spanned by two vectors. In the z-basis these vectors are {zp,zm}, and the basis kets in the z-basis are {xp,xm} and {yp,ym} respectively.

zp	Return the $ z+\rangle$ ket in the z-basis.		[Function]
zm	Return the $ z-\rangle$ ket in the z-basis.		[Function]
хр	Return the $ x+\rangle$ ket in the z-basis.		[Function]
xm	Return the $ x-\rangle$ ket in the z-basis.		[Function]
ур	Return the $ y+\rangle$ ket in the z-basis.		[Function]
уm	Return the $ y-\rangle$ ket in the z-basis.		[Function]
	(%i1) zp;	[1]	
	(%o1)	[]	
	(%i2) zm;		
	(%02)	[0] [] [1]	

Switching bases is done in the following example where a z-basis ket is constructed and the x-basis ket is computed.

1.2.2 Pauli matrices and Sz, Sx, Sy operators

sigmax
Returns the Pauli x matrix.

sigmay
Returns the Pauli y matrix.

sigmaz
Function
Returns the Pauli z matrix.

Sx
Returns the spin-1/2 Sx matrix.

[Function]
Returns the spin-1/2 Sy matrix.

Sz Returns the spin-1/2 Sz matrix. [Function]

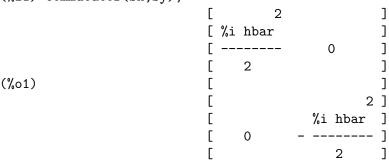
(%i1) sigmay;

(%i2) Sy;

commutator (X,Y) [Function]

Given two operators X and Y, return the commutator X . Y – Y . X.

(%i1) commutator(Sx,Sy);



anticommutator (X,Y)

[Function]

Given two operators X and Y, return the commutator X. Y + Y. X.

(%i1)
$$(1/2)*$$
anticommutator(sigmax, sigmax);

1.2.3 SX, SY, SZ operators for any spin

SX (s) [Function]

SX(s) for spin s returns the matrix representation of the spin operator Sx. Shortcuts for spin-1/2 are Sx,Sy,Sz, and for spin-1 are Sx1,Sy1,Sz1.

SY(s) for spin s returns the matrix representation of the spin operator Sy. Shortcuts

SY(s) for spin s returns the matrix representation of the spin operator Sy. Shortcuts for spin-1/2 are Sx,Sy,Sz, and for spin-1 are Sx1,Sy1,Sz1.

SZ(s) [Function] SZ(s) for spin s returns the matrix representation of the spin operator Sz. Shortcuts for spin-1/2 are Sx,Sy,Sz, and for spin-1 are Sx1,Sy1,Sz1.

Example: (%i1) SY(1/2); %i hbar] 2] (%o1)] [%i hbar]] 0 2 (%i2) SX(1); hbar 0 0] sqrt(2)] hbar hbar (%o2) 0 sqrt(2)] sqrt(2)] hbar] 0] sqrt(2)

1.2.4 Basis set transformations

Given a matrix representation of an operator in terms of mkets one may transform from one mket basis to another.

basis_set_p (B) [Function]

The predicate function $basis_set_p$ takes as an argument a basis set $[b_1, b_2, ...]$ enclosed in square brackets, where each b_i is true for the predicate function mketp.

 $mtrans (B_1, B_2)$ [Function]

The function mtrans returns the matrix of inner products of the two bases B_1 and B_2 . The bases must be of the same dimension.

 $op_trans (A,B_1,B_2)$ [Function]

The function op_trans returns the matrix representation of operator A in basis B_2 . The operator A must be given in the basis B_1 .

1.2.5 Expectation value and variance

expect (0,psi) [Function]

Computes the quantum mechanical expectation value of the operator O in state psi, <psi|O|psi>.

qm_variance (0,psi)

[Function]

Computes the quantum mechanical variance of the operator O in state psi, $\ensuremath{\mbox{sqrt}}(\ensuremath{\mbox{spsi}}|0^2|\ensuremath{\mbox{psi}}> - \ensuremath{\mbox{spi}}|0|\ensuremath{\mbox{psi}}>^2).$

1.2.6 Angular momentum and ladder operators in the matrix representation

SP (s) [Function] SP is the raising ladder operator S_{+} for spin s.

SM (s) [Function] SM is the raising ladder operator S_{-} for spin s.

Examples of the ladder operators:

(%i1) SP(1);] [0 sqrt(2) hbar 0] [0 (%o1) sqrt(2) hbar] [0 0 0] (%i2) SM(1); 0 0 0] (%02) [sqrt(2) hbar 0] sqrt(2) hbar 0] 0

1.2.7 Rotation operators

RX (s,t) [Function]

RX(s) for spin s returns the matrix representation of the rotation operator Rx for rotation through angle t.

RY (s,t) [Function]

RY(s) for spin s returns the matrix representation of the rotation operator Ry for rotation through angle t.

RZ (s,t) [Function]

RZ(s) for spin s returns the matrix representation of the rotation operator Rz for rotation through angle t.

(%i1) RY(1,t);

Proviso: assuming 4*t # 0

	$[\cos(t) + 1]$	sin(t)	1 - cos(t)]
	[]
	[2	sqrt(2)	2]
	[]
	[sin(t)		sin(t)]
(%o1)	[cos(t)]
	[sqrt(2)		sqrt(2)]
	[-]
	[1 - cos(t)]	sin(t)	cos(t) + 1]
	[]
	[2	sqrt(2)	2]

1.2.8 Time-evolution operator

U (H,t) [Function]

U(H,t) is the time evolution operator for Hamiltonian H. It is defined as the matrix exponential matrixexp(-%i*H*t/hbar).

(%i1) U(w*Sy,t);

Proviso: assuming 64*t*w # 0

1.3 Angular momentum representation of kets and bras

1.3.1 Matrix representation of (j,m)-kets and bras

The matrix representation of kets and bras in the qm package are represented in the z-basis. To create a matrix representation of of a ket or bra in the (j,m)-basis one uses the spin_mket and spin_mbra functions.

$$spin_mket (s, m_s, [1,2])$$

[Function]

spin_mket returns a ket in the z-basis for spin s and z-projection ms, for axis 1=X or 2=Y.

$spin_mbra (s, m_s, [1,2])$

[Function]

[Function]

[Function]

spin_mbra returns a bra in the z-basis for spin s and z-projection m_s, for axis 1=X or 2=Y.

(%i1) spin_mbra(3/2,1/2,2);

1.3.2 Angular momentum (j,m)-kets and bras

To create kets and bras in the $|i,m\rangle$ representation you use the abstract ket and bras functions with j,m as arguments, as in ket([j,m]) and bra([j,m]).

(%i1) bra([3/2,1/2]);

(%02)

Some convenience functions for making the kets are the following:

jmtop (j)

(%i1) jmtop(3/2);

(%i1) jmbot(3/2);

jmtop creates a (j,m)-ket with m=j.

jmbot (j)

jmbot creates a (j,m)-ket with m=-j.

jmket (j,m) [Function] jmket creates a (j,m)-ket.

$$(\%i1)$$
 jmket $(3/2,1/2)$;

```
jmketp (jmket)
     jmketp checks to see that the ket has an m-value that is in the set \{-j,-j+1,\ldots,+j\}.
     (%i1) jmketp(ket([j,m]));
     (%o1)
                                              false
     (\%i2) jmketp(ket([3/2,1/2]));
     (%o2)
                                              true
jmbrap (jmbra)
                                                                          [Function]
     jmbrap checks to see that the bra has an m-value that is in the set {-j,-j+1,...,+j}.
jmcheck (j,m)
                                                                           [Function]
     jmcheck checks to see that m is one of \{-j, \ldots, +j\}.
     (%i1) jmcheck(3/2,1/2);
     (%o1)
                                              true
Jp (jmket)
                                                                           [Function]
     Jp is the J<sub>+</sub> operator. It takes a jmket jmket(j,m) and returns sqrt(j*(j+1)-
     m*(m+1))*hbar*jmket(j,m+1).
Jm (jmket)
                                                                           [Function]
     Jm is the J- operator. It takes a jmket jmket(j,m) and returns sqrt(j*(j+1)-m*(m-
     1))*hbar*jmket(j,m-1).
Jsqr (jmket)
                                                                           [Function]
     Jsqr is the J^2 operator.
                                   It takes a jmket jmket(j,m) and returns
     j*(j+1)*hbar^2*jmket(j,m).
Jz (jmket)
                                                                           [Function]
     Jz is the J<sub>z</sub> operator. It takes a jmket jmket(j,m) and returns m*hbar*jmket(j,m).
  These functions are illustrated below.
     (%i1) k:ket([j,m]);
     (%o1)
                                             |j, m>
     (%i2) Jp(k);
     (\%02)
                         hbar |j, m + 1\rangle sqrt(j (j + 1) - m (m + 1))
     (%i3) Jm(k);
     (\%03)
                         (%i4) Jsqr(k);
                                    hbar j (j + 1) |j, m>
     (\%04)
     (%i5) Jz(k);
                                          hbar | j, m > m
     (\%05)
```

1.3.3 Addition of angular momentum in the (j,m)-representation

Addition of angular momentum calculations can be performed in the (j,m)-representation using the function definitions below. The internal representation of kets and bras for this purpose is the following. Given kets $|j1,m1\rangle$ and $|j2,m2\rangle$ a tensor product of (j,m)-kets is instantiated as:

and the corresponding bra is instantiated as:

where the factor of 1 is the multiplicative factor of the tensor product. We call this the *common factor* (cf) of the tensor product. The general form of a tensor product in the (j,m) representation is:

Using the function definitions below one must be careful to avoid errors produced by Maxima's automatic list arithmetic. For example, do not use (J1z+J2z), and instead use the defined function Jtz. Similarly for any of the operators that are added together, one should always use the total Jtxx defined function.

tpket (jmket1,jmket2)

[Function]

tpket instantiates a tensor product of two (j,m)-kets.

tpbra (jmbra1,jmbra2)

[Function]

tpbra instantiates a tensor product of two (j,m)-bras.

tpbraket (tpbra,tpket)

[Function]

tpbraket returns the bracket of a tpbra and a tpket.

```
(%i1) k:tpket(jmtop(1),jmbot(1));
```

(%i2) K:Jtsqr(k);

(%i3) B:tpdagger(k);

(%i4) tpbraket(B,K);

2 2 hbar

(%o4)

 $\mathtt{tpcfset}\ (\mathtt{cf}, tpket)$

[Function]

tpcfset manually sets the common factor cf of a tpket.

tpscmult (a, tpket)

[Function]

tpscmult multiplies the tensor product's common factor by a.

(%i1)
$$k1:tpket(ket([1/2,1/2]),ket([1/2,-1/2]));$$

(%i2) tpscmult(c,k1);

tpadd (tpket,tpket)

[Function]

tpadd adds two tpkets. This function is necessary to avoid trouble with Maxima's automatic list arithmetic.

(%i1)
$$k1:tpket(ket([1/2,1/2]),ket([1/2,-1/2]));$$

(%i2) k2:tpket(ket([1/2,-1/2]),ket([1/2,1/2]));

(%i3) tpadd(k1,k2);

tpdagger (tpket or tpbra)

[Function]

tpdagger takes the quantum mechanical dagger of a tpket or tpbra.

(%i1)
$$k1:tpket(ket([1/2,1/2]),ket([1/2,-1/2]));$$

(%i2) tpdagger(k1);

J1z (tpket)

[Function]

J1z returns the tensor product of a tpket with Jz acting on the first ket.

J2z (tpket) [Function]

J2z returns the tensor product of a tpket with Jz acting on the second ket.

```
J1p2m (tpket)
                                                                           [Function]
     J1p2m returns (J_{1+}J_{2-}) for the tpket.
     (\%i1) k:tpket(ket([3/2,1/2]),ket([1/2,1/2]));
                                                3 1
                                                        1 1
     (%o1)
                                   [tpket, 1, |-, ->, |-, ->]
      (%i2) b:tpdagger(k);
                                                3 1
                                                        1 1
      (\%02)
                                   [tpbra, 1, <-, -|, <-, -|]
      (\%i3) J1p2m(k);
                           [tpket, sqrt(3) hbar , |-, ->, |-, - ->]
      (\%03)
      (\%i4) J1m2p(k);
                                                 0
      (\%04)
J1m2p (tpket)
                                                                           [Function]
     J1m2p returns (J_{1-}J_{2+}) for the tpket.
J1zJ2z (tpket)
                                                                           [Function]
     J1zJ2z returns (J_{1z}J_{2z}) for the tpket.
                                                                           [Function]
Jtsqr (tpket)
     Jtsqr returns (J_1^2+J_2^2+J_{1+}J_{2-}+J_{1-}J_{2+}+J_{1z}J_{2z}) for the tpket.
     (%i1) k:tpket(ket([3/2,-1/2]),ket([1/2,1/2]));
                                 [tpket, 1, |-, -->, |-, ->]
      (%o1)
      (%i2) B:tpdagger(k);
                                               3 1 1 1
                                 [tpbra, 1, <-, - -|, <-, -|]
      (\%02)
      (%i3) K2:Jtsqr(k);
                                                                          3 1
                                3 1 1 1
     (%o3) [tpket, 4 hbar , |-, - ->, |-, ->] + [tpket, 2 hbar , |-, ->, |-,
                                     2 2 2
     (%i4) tpbraket(B,K2);
                                                     2
     (\%04)
                                              4 hbar
get_j (q)
                                                                           [Function]
     get_j is a convenience function that computes j from j(j+1)=q where q is a rational
     number. This function is useful after using the function Jtsqr.
     (%i1) get_j(15/4);
                                               j = -
      (%o1)
```

1.3.4 Example computations

For the first example, let us see how to determine the total spin state $|j,m\rangle$ of the two-particle state $|1/2,1/2;1,1\rangle$.

(%i2) Jtsqr(k);

(%i3) get_j(15/4);

This is an eigenket of Jtsqr, thus $|3/2,3/2\rangle = |1/2,1/2;1,1\rangle$, and it is also the top state. One can now apply the lowering operator to find the other states: $|3/2,1/2\rangle$, $|3/2,-1/2\rangle$, and $|3/2,-3/2\rangle$.

(%i1) k:tpket(jmtop(1/2),jmtop(1));

(%i2) k2:Jtm(k);

(%i3) k3:Jtm(k2);

(%i4) k4:Jtm(k3);

In the example below we calculate the Clebsch-Gordan coefficients of the two-particle state with two spin-1/2 particles. We begin by defining the top rung of the ladder and stepping down. To calculate the coefficients one first creates the tensor product top state, and computes the values for the total angular momentum |J,M>. At the top of the ladder M=J. For the first step down the ladder one computes Jm |J,M>, which must be equal to Jtm |j1,m1;j2,m2>. This gives first set of coefficients and one continues down the ladder to compute the rest of them.

```
(%i1) top:tpket(jmtop(1/2),jmtop(1/2));
                                            1 1
                                    1 1
                         [tpket, 1, |-, ->, |-, ->]
(%o1)
                                    2 2
                                            2 2
(%i2) Jtsqr(top);
                                   2
                                       1 1
                                              1 1
                      [tpket, 2 hbar , |-, ->, |-, ->]
(\%02)
                                       2 2
                                               2 2
(%i3) get_j(2);
(%o3)
                                   j = 1
(%i4) Jtz(top);
                                      1 1
                        [tpket, hbar, |-, ->, |-, ->]
(\%04)
                                      2 2
(%i5) JMtop:ket([1,1]);
(\%05)
                                  |1, 1>
(%i6) mid:Jtm(top);
                     1 1 1
                                 1
       [tpket, hbar, |-, ->, |-, -->] + [tpket, hbar, |-, -->, |-, ->]
                     2 2
                                 2
                            2
(%i7) Jm(JMtop);
(\%07)
                             sqrt(2) |1, 0> hbar
(%i8) mid:tpscmult(1/(sqrt(2)*hbar),mid);
                      1 1
                              1
                                                    1
                                                           1
                                  1
(%08) [tpket, -----, |-, ->, |-, - ->] + [tpket, -----, |-, - ->, |-,
             sqrt(2) 2 2 2
                                   2
                                                 sqrt(2)
(%i9) bot:Jtm(mid);
                  [tpket, sqrt(2) hbar, |-, - ->, |-, - ->]
(\%09)
(%i10) Jm(ket([1,0]));
                            sqrt(2) |1, - 1> hbar
(%i11) bot:tpscmult(1/(sqrt(2)*hbar),bot);
                       [tpket, 1, |-, -->, |-, -->]
(%o11)
                                2 2 2 2
```

1.4 General tensor products

Tensor products are represented as lists in the qm package. The ket tensor product |z+,z+> can be represented as ket([u,d]), for example, and the bra tensor product <a,b| is represented as bra([a,b]) for states a and b. For a tensor product where the identity is one of the elements of the product, substitute the string Id in the ket or bra at the desired location. See the examples below for the use of the identity in tensor products.

Examples below show how to create abstract tensor products that contain the identity element Id and how to take the bracket of these tensor products.

In the next example we construct the state function for an entangled Bell pair, construct the density matrix, and then trace over the first particle to obtain the density submatrix for particle 2.

```
(%i1) bell:(1/sqrt(2))*(ket([u,d])-ket([d,u]));
                                 |u, d> - |d, u>
(%o1)
                                 _____
                                      sqrt(2)
(%i2) rho:bell . dagger(bell);
      \label{eq:continuous} |u,\ d>\ .\ \langle u,\ d|\ -\ |u,\ d>\ .\ \langle d,\ u|\ -\ |d,\ u>\ .\ \langle u,\ d|\ +\ |d,\ u>\ .\ \langle d,\ u|\ \blacksquare
(%o2) ------
                                          2
(%i3) assume(not equal(u,d));
(\%03)
                                 [notequal(u, d)]
(\%i4) trace1:bra([u,Id]) . rho . ket([u,Id])+bra([d,Id]) . rho . ket([d,Id]);
                        |-, u> . <-, u| |-, d> . <-, d|
(\%04)
                                                  2
```

One can also construct the density matrix using the function matrep.

matrep (A,B) [Function]

Given an abstract representation of an operator, e.g. $A = |a\rangle$. $\langle b| + |b\rangle$. $\langle a|$, the function matrep takes the operator A and basis set B and constructs the matrix representation of A. NOTE: if there are symbolic constants as coefficients in the abstract representation they must be declared as scalar for the simplification rules to work properly with the non-commutative "." operator.

```
(%i1) bell:(1/sqrt(2))*(ket([1,0])-ket([0,1]));
                                  |1, 0> - |0, 1>
(%o1)
                                       sqrt(2)
(%i2) rho:bell . dagger(bell);
      |1, 0\rangle . <1, 0|-|1, 0\rangle . <0, 1|-|0, 1\rangle . <1, 0|+|0, 1\rangle . <0, 1|\blacksquare
(%02) -----
                                           2
(%i3) B: [ket([1,1]), ket([1,0]), ket([0,1]), ket([0,0])];
(\%03)
                         [|1, 1\rangle, |1, 0\rangle, |0, 1\rangle, |0, 0\rangle]
(%i4) matrep(rho,B);
                                                 0 ]
                                ]
                                ]
                                [ 0
                                                0 ]
                                2
                                                   ]
(\%04)
                                ]
                                ]
                                            1
                                [ 0
                                                0 ]
                                2
                                            2
                                                   ]
                                ]
                                [ 0
                                                0 ]
                                       0
(%i5) declare([a,b],scalar);
(\%05)
                                        done
(%i6) 0:a*ket([1]) . bra([0])+b*ket([0]) . bra([1]);
                           (|0> . <1|) b + (|1> . <0|) a
(\%06)
(%i7) B:[ket([1]),ket([0])];
(\%07)
                                     [|1>, |0>]
(%i8) matrep(0,B);
                                      [0 a]
(%08)
                                      [b 0]
```

1.4.1 Abstract basis set generator

```
basis_set (n,[l_1,l_2,\ldots])
```

[Function]

The function basis_set takes two arguments, n is the number of particles, and the second argument is a list of labels of the particle states. Currently this function accepts up to four particles (n=1,2,3,4). The number of elements in the basis set is mⁿ, where m is the number of states per particle, so a 4-particle system with four states will have 256 basis kets.

1.4.2 Example calculation of matrix elements

Let us see how to compute the matrix elements of the operator (J1z-J1z) in the z-basis for two spin-1/2 particles. First, we define the four basis kets of the form $|j_1,m_1;j_2,m_2\rangle$. Next we define the Hamiltonian and then use the function matrep.

```
(%i1) b1:tpket(ket([1/2,1/2]),ket([1/2,1/2]));
                                        1 1
                                                1 1
(%o1)
                           [tpket, 1, |-, ->, |-, ->]
(%i2) b2:tpket(ket([1/2,1/2]),ket([1/2,-1/2]));
                                       1 1
                          [tpket, 1, |-, ->, |-, - ->]
(\%02)
(%i3) b3:tpket(ket([1/2,-1/2]),ket([1/2,1/2]));
                                            1
                                                 1
                          [tpket, 1, |-, - ->, |-, ->]
(\%03)
(\%i4) b4:tpket(ket([1/2,-1/2]),ket([1/2,-1/2]));
                         [tpket, 1, |-, - ->, |-, - ->]
(\%04)
(%i5) B: [b1,b2,b3,b4];
                            1 1
(%o5) [[tpket, 1, |-, ->, |-, ->], [tpket, 1, |-, ->, |-, - ->],
                   2 2
                   [tpket, 1, |-, -->, |-, ->], [tpket, 1, |-, -
                                    2
                                          2 2
(%i6) H:omega*(J1z-J2z);
(\%06)
                                (J1z - J2z) omega
(%i7) declare(omega, scalar);
(\%07)
                                       done
(%i8) matrep(H,B);
                       [ 0
                                0
                                              0
                                                       0 ]
                       Γ
                       [ 0
                                              0
                                                       0 ]
                           hbar omega
(%08)
                       Γ
                                                          1
                       [ 0
                                                       0 ]
                                0
                                         - hbar omega
                                                       0 ]
                       [ 0
                                0
                                              0
```

1.4.3 Matrix trace functions

qm_mtrace (matrix) [Function]

The function qm_mtrace is the usual matrix trace; it takes a square matrix and returns the sum of the diagonal components.

qm_atrace (A,B) [Function]

The function qm_atrace takes an abstract operator A and a basis B and attempts to compute the matrix representation using the matrep function. If successful it will return the matrix trace the resulting matrix.

```
(%i1) B:[ket([1]),ket([0])];
                                [|1>, |0>]
(%o1)
(%i2) declare(c,scalar);
(\%02)
                                   done
(%i3) A:c*ket([1]) . bra([1]);
(\%03)
                               (|1> . <1|) c
(%i4) matrep(A,B);
                                 [c 0]
(\%04)
                                 [00]
(%i5) qm_atrace(A,B);
(\%05)
(\%i6) bell:(1/sqrt(2))*(ket([1,0])-ket([0,1]));
                              |1, 0> - |0, 1>
(\%06)
                                  sqrt(2)
(%i7) rho:bell . dagger(bell);
     |1, 0\rangle . <1, 0|-|1, 0\rangle . <0, 1|-|0, 1\rangle . <1, 0|+|0, 1\rangle . <0, 1|\blacksquare
(%o7) -------
(%i8) trace1:bra([1,Id]) . rho . ket([1,Id])+bra([0,Id]) . rho . ket([0,Id]);
                      |-, 1> . <-, 1| |-, 0> . <-, 0|
                      ----- + ------
(%08)
(%i9) B:[ket([Id,1]),ket([Id,0])];
(\%09)
                            [|Id, 1>, |Id, 0>]
(%i10) matrep(trace1,B);
                                 [ 0 ]
                                 [ 2
(%o10)
                                 1 ]
                                 [0 -]
                                      2 ]
```

1.5 Quantum harmonic oscillator

The qm package can perform simple quantum harmonic oscillator calculations involving the ladder operators a⁺ and a⁻. These are referred to in the package as ap and am respectively. For computations with arbitrary states to work you must declare the harmonic oscillator state, say n, to be both scalar and integer, as shown in the examples below.

ap ap is the raising operator a⁺ for quantum harmonic oscillator states. [Function]

am

a is the lowering operator a for quantum harmonic oscillator states.

A common problem is to compute the 1st order change in energy of a state due to a perturbation of the harmonic potential, say an additional factor $V(x) = x^2 + g*x^4$ for small g. This example is performed below, ignoring any physical constants in the problem.

Another package that handles quantum mechanical operators is operator_algebra written by Barton Willis.

1.6 Pre-defined quantities

There are some pre-defined quantities in the file predef.mac that may be convenient for the user. These include Bell states, and some basis sets that are tedious to input. The predef.mac file is not loaded automatically. To make the definitions available issue load(predef);

Appendix A Function and Variable index

A	Jtm
am 25 anticommutator 9 ap 25 autobra 6 autoket 5	Jtp 17 Jtsqr 18 Jtz 17 Jz 14
В	K
basis_set 22 basis_set_p 10 bra 4 braket 6 brap 4	ket
214	${f M}$
\mathbf{C}	magsqr7
commutator9	matrep
D	mket
dagger6	mketp
\mathbf{E}	
expect	N
\mathbf{G}	norm6
get_j	O
J	op_trans
J1m	
J1m2p	
J1p	\mathbf{Q}
J1p2m 18 J1sqr 17	qm_atrace24
J1z	qm_mtrace
J1zJ2z18	qm_variance11
J2m	
J2p	
J2sqr	R
J2z	16
Jm	RX
jmbot 13 jmbrap 14	RY
jmcheck	RZ
jmket	
jmketp	
jmtop	
Jp	

S	tpket
sigmax8	tpscmult
sigmay 8	
sigmaz8	\mathbf{U}
SM	-
spin_mbra	U
spin_mket 13 SP 11	
Sx	\mathbf{X}
SX 9	 xm7
Sy 8	xp
SY 9	Ap
Sz 9	
SZ9	\mathbf{Y}
	ym
T	ур
tpadd	
tpbra	\mathbf{Z}
tpbraket	Z
tpcfset	zm
tpdagger 16	zp
hbar	