## 1.1 Introduction to package qm

Package version: 0.5

The qm package provides functions and standard definitions to solve quantum mechanics problems in a finite dimensional Hilbert space. For example, one can calculate the outcome of Stern-Gerlach experiments using the built-in definition of the Sx, Sy, and Sz operators for arbitrary spin, e.g.  $s=\{1/2, 1, 3/2, \ldots\}$ . For spin-1/2 the standard basis states in the x, y, and z-basis are available as  $\{xp,xm\}$ ,  $\{yp,ym\}$ , and  $\{zp,zm\}$ . One can create general ket vectors with arbitrary but finite dimension and perform standard computations such as expectation value, variance, etc. The angular momentum  $|j,m\rangle$  representation of kets is also available. It is also possible to create tensor product states for multiparticle systems and to perform calculations on those systems.

The qm package was written by Eric Majzoub, University of Missouri. (Email: majzoube-at-umsystem.edu) The package is loaded with: load(qm);

## 1.2 Functions and Variables for qm

hbar

Planck's constant divided by 2\*%pi. hbar is not given a floating point value, but is declared to be a real number greater than zero.

```
\text{ket } (c_1, c_2, \dots) [Function]
```

ket creates a column vector of arbitrary finite dimension. The entries  $c_i$  can be any Maxima expression. The user must declare any relevant constants to be complex.

bra creates a row vector of arbitrary finite dimension. The entries  $c_i$  can be any Maxima expression. The user must declare any relevant constants to be complex.

ketp (vector) [Function]

ketp is a predicate function that checks if its input is a ket, in which case it returns true, else it returns false.

```
brap (vector)
                                                                           [Function]
     brap is a predicate function that checks if its input is a bra, in which case it returns
     true, else it returns false.
     (%i4) b:bra(a,b);
     (\%04)
                                             [a b]
      (%i5) brap(b);
     (%o5)
                                               true
dag (vector)
                                                                           [Function]
     dag is the quantum mechanical dagger function and returns the conjugate transpose
     of its input.
     (%i4) dag(bra(%i,2));
                                             [ - %i ]
      (\%04)
                                             ]
braket (psi,phi)
                                                                           [Function]
     Given two kets psi and phi, braket returns the quantum mechanical bracket
     <psi|phi>. The vector psi may be input as either a ket or bra. If it is a ket it will
     be turned into a bra with the dag function before the inner product is taken. The
     vector phi must always be a ket.
     (%i4) declare([a,b,c],complex);
     (\%04)
                                               done
     (%i5) braket(ket(a,b,c),ket(a,b,c));
     (%05)
                      c conjugate(c) + b conjugate(b) + a conjugate(a)
norm (psi)
     Given a ket or bra psi, norm returns the square root of the quantum mechanical
     bracket <psi|psi>. The vector psi must always be a ket, otherwise the function
     will return false.
     (%i4) declare([a,b,c],complex);
     (\%04)
                                               done
     (%i5) norm(ket(a,b,c));
     (\%05)
                   sqrt(c conjugate(c) + b conjugate(b) + a conjugate(a))
magsqr (c)
                                                                           [Function]
     magsqr returns conjugate(c)*c, the magnitude squared of a complex number.
     (%i4) declare([a,b,c,c],complex);
      (\%04)
                                               done
     (%i5) A:braket(ket(a,b),ket(c,d));
      (\%05)
                                conjugate(b) d + conjugate(a) c
      (%i6) P:magsqr(A);
```

(b d + a conjugate(c)) (conjugate(b) d + conjugate(a) c)

(%06)

## 1.2.1 Spin-1/2 state kets and associated operators

Spin-1/2 particles are characterized by a simple 2-dimensional Hilbert space of states. It is spanned by two vectors. In the z-basis these vectors are {zp,zm}, and the basis kets in the z-basis are {xp,xm} and {yp,ym} respectively.

zp	Return the $ z+\rangle$ ket in the z-basis.		[Function]
zm	Return the $ z-\rangle$ ket in the z-basis.		[Function]
хр	Return the $ x+\rangle$ ket in the z-basis.		[Function]
xm	Return the $ x-\rangle$ ket in the z-basis.		[Function]
ур	Return the $ y+\rangle$ ket in the z-basis.		[Function]
уm	Return the $ y\rangle$ ket in the z-basis.		[Function]
	(%i4) zp;		
	(%o4)	[ 1 ] [ ] [ 0 ]	
	(%i5) zm;		
	(%o5)	[ O ] [ ] [ 1 ]	
	(%i4) yp;	г 4 1	
	(%o4)	[ 1 ] [ ] [ sqrt(2) ] [	
	(%i5) ym;	[ 1 ]	
	(%o5)	[ ] [ sqrt(2) ] [ %i ] [ ] [ sqrt(2) ]	

Switching bases is done in the following example where a z-basis ket is constructed and the x-basis ket is computed.

#### 1.2.2 Pauli matrices and Sz, Sx, Sy operators

[Function]

Returns the Pauli x matrix.

sigmay [Function]

Returns the Pauli y matrix.

sigmaz [Function]

Returns the Pauli z matrix.

[Function]

Returns the spin-1/2 Sx matrix.

Sy Returns the spin-1/2 Sy matrix. [Function]

Sz [Function]

Returns the spin-1/2 Sz matrix.

(%i4) sigmay;

(%i5) Sy;

commutator (X,Y)

[Function]

Given two operators X and Y, return the commutator X . Y - Y . X.

(%i4) commutator(Sx,Sy);

2 [ %i hbar 0 2 ] (%04)] 2] %i hbar 0 Г 2 ]

#### 1.2.3 SX, SY, SZ operators for any spin

- SX (s) [Function] SX(s) for spin s returns the matrix representation of the spin operator Sx. Shortcuts for spin-1/2 are Sx,Sy,Sz, and for spin-1 are Sx1,Sy1,Sz1.
- SY(s) [Function] SY(s) for spin s returns the matrix representation of the spin operator Sy. Shortcuts for spin-1/2 are Sx,Sy,Sz, and for spin-1 are Sx1,Sy1,Sz1.
- SZ(s) [Function] SZ(s) for spin s returns the matrix representation of the spin operator Sz. Shortcuts for spin-1/2 are Sx,Sy,Sz, and for spin-1 are Sx1,Sy1,Sz1.

Example:

(%i4) SY(1/2);

(%i5) SX(1);

	[		hbar		]
	]	0		0	]
	]		sqrt(2)		]
	]				]
	]	hbar		hbar	]
(%o5)	]		0		]
	]	sqrt(2)		sqrt(2)	]
	]				]
	]		hbar		]
	]	0		0	]
	]		sqrt(2)		]

#### 1.2.4 Expectation value and variance

# 

#### 1.2.5 Angular momentum representation of kets and bras

To create kets and bras in the  $|j,m\rangle$  representation you can use the following functions.

jm\_ketp (jmket) [Function] jm\_ketp checks to see that the ket has the 'jmket' marker.

jm\_brap (jmbra) [Function] jm\_brap checks to see that the bra has the 'jmbra' marker.

 $jm\_check\ (j,m)$  [Function]  $jm\_check\ checks\ to\ see\ that\ m\ is\ one\ of\ \{-j,\ \ldots,\ +j\}.$ 

jm\_braket (jmbra,jmket)
 jm\_braket takes the inner product of the jm-kets.
[Function]

(%i4) K:jm\_ket(zp,zm); [[1]] [ [ [[0]] (%04)[jmket, [ [[0]] [ [ ] ] [[1]] (%i5) B:jm\_bra(zp,zm); [[1] [ 0 ] ] [jmbra, [ [ (%o5) ] [ [ 0 ] [1] (%i6) jm\_braket(B,K); (%06) 1

#### 1.2.6 Angular momentum and ladder operators

SP (s) [Function] SP is the raising ladder operator  $S_{+}$  for spin s.

SM (s) [Function]

SM is the raising ladder operator  $S_{-}$  for spin s.

Examples of the ladder operators:

# 1.3 Rotation operators

RX (s,t) [Function]

 $\mathtt{RX}(\mathtt{s})$  for spin  $\mathtt{s}$  returns the matrix representation of the rotation operator  $\mathtt{Rx}$  for rotation through angle  $\mathtt{t}$ .

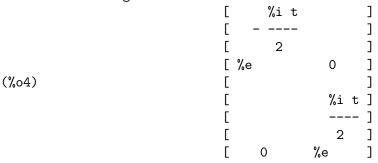
RY (s,t) [Function]
RY(s) for spin s returns the matrix representation of the rotation operator Ry for rotation through angle t.

RZ (s,t) [Function]

RZ(s) for spin s returns the matrix representation of the rotation operator Rz for rotation through angle t.

(%i4) RZ(1/2,t);

Proviso: assuming 64\*t # 0



# 1.4 Time-evolution operator

UU (H,t) [Function]

UU(H,t) is the time evolution operator for Hamiltonian H. It is defined as the matrix exponential matrixexp(-%i\*H\*t/hbar).

(%i4) UU(w\*Sy,t);

Proviso: assuming 64\*t\*w # 0

[ tw tw]
[ 
$$\cos(---) - \sin(---)$$
 ]
[ 2 2 ]
(%04)
[ tw tw]
[  $\sin(---) \cos(---)$  ]
[ 2 2 ]

# 1.5 Tensor products

Tensor products are represented as lists in Maxima. The ket tensor product |z+,z+> is represented as [tpket,zp,zp], and the bra tensor product <a,b| is represented as [tpbra,a,b] for kets a and b. The list labels tpket and tpbra ensure calculations are performed with the correct kind of objects.

$$ketprod (k_1, k_2, ...)$$
 [Function]

ketprod produces a tensor product of kets  $k_i$ . All of the elements must pass the ketp predicate test to be accepted.

braprod produces a tensor product of bras  $b_i$ . All of the elements must pass the brap predicate test to be accepted.

braketprod (B,K) [Function]

braketprod takes the inner product of the tensor products B and K. The tensor products must be of the same length (number of kets must equal the number of bras).

Examples below show how to create tensor products and take the bracket of tensor products.

```
(%i4) ketprod(zp,zm);
                                     [1] [0]
                            [tpket, [[ ], [ ]]]
(%o4)
                                     [0][1]
(%i5) ketprod('zp,'zm);
                           all elements must be kets
(%05)
                                     done
(%i4) kill(a,b,c,d);
(\%04)
                                     done
(%i5) declare([a,b,c,d],complex);
(\%05)
                                     done
(%i6) braprod(bra(a,b),bra(c,d));
(\%06)
                         [tpbra, [[ a b ], [ c d ]]]
(%i7) braprod(dag(zp),bra(c,d));
                         [tpbra, [[ 1 0 ], [ c d ]]]
(\%07)
(%i4) zpb:dag(zp);
(%o4)
                                   [10]
(%i5) zmb:dag(zm);
                                   [01]
(\%05)
(%i6) K:ketprod('zp,'zm);
                           all elements must be kets
(\%06)
                                     done
(%i7) B:braprod(zpb,zmb);
(%07)
                         [tpbra, [[ 1 0 ], [ 0 1 ]]]
(%i8) B:braprod('zpb,'zmb);
                           all elements must be bras
(%08)
                                     done
(%i9) braketprod(K,B);
(\%09)
                                     false
(%i10) braketprod(B,K);
(%o10)
                                     false
```

# Appendix A Function and Variable index

В	$\mathbf{Q}$
bra	qm_variance
braketprod         8           brap         2	R
braprod	
biapiou	RX
	RY 7
$\mathbf{C}$	RZ 8
commutator	S
D	sigmax
dag 2	sigmay4
uag	sigmaz4
	SM
$\mathbf{E}$	Sx
expect6	SX
expection	Sy
	SY
$\mathbf{J}$	Sz 4
jm_bra6	SZ 5
jm_braket 6	
jm_brap 6	U
jm_check 6	
jm_ket6	UU 8
jm_ketp 6	
	$\mathbf{X}$
K	xm
ket	xp 3
ketp 1	
ketprod 8	<b>3</b> 7
_	$\mathbf{Y}$
M	ym 3
	ур 3
magsqr	
	${f Z}$
N	zm
norm	zp
1101m	-F

Appendix A: Function and Variable index	
hbar1	