1.1 Introduction to package qm

The qm package provides functions and standard definitions to solve quantum mechanics problems in a finite dimensional Hilbert space. For example, one can calculate the outcome of Stern-Gerlach experiments using the built-in definition of the Sx, Sy, and Sz operators for arbitrary spin, e.g. $s=\{1/2, 1, 3/2, \ldots\}$. For spin-1/2 the standard basis states in the x, y, and z-basis are available as $\{xp,xm\}$, $\{yp,ym\}$, and $\{zp,zm\}$. One can create general ket vectors with arbitrary but finite dimension and perform standard computations such as expectation value, variance, etc. The angular momentum $|j,m\rangle$ representation of kets is also available. It is also possible to create tensor product states for multiparticle systems and to perform calculations on those systems.

The qm package was written by Eric Majzoub, University of Missouri. (Email: majzoube-at-umsystem.edu) The package is loaded with: load(qm);

1.2 Functions and Variables for qm

hbar

Planck's constant divided by 2*%pi. hbar is not given a floating point value, but is declared to be a real number greater than zero.

 $\text{ket }([c_1,c_2,\ldots])$ [Function]

ket creates a *column* vector of arbitrary finite dimension. The entries c_i can be any Maxima expression. The user must declare any relevant constants to be complex. For a matrix representation the elements must be entered as a list in [...] square brackets. If no list is entered the ket is represented as a general ket, ket(a) will return |a>.

```
(%i4) kill(a);
(\%04)
                                        done
(%i5) ket(a);
(\%05)
                                         la>
(%i6) declare([c1,c2],complex);
(\%06)
                                        done
(%i7) ket([c1,c2]);
                                       [ c1 ]
(\%07)
                                            1
                                       [ c2 ]
(%i8) facts();
(%08) [kind(hbar, real), hbar > 0, kind(c1, complex), kind(c2, complex)]
```

bra $([c_1, c_2, \ldots])$ [Function]

bra creates a *column* vector of arbitrary finite dimension. The entries c_i can be any Maxima expression. The user must declare any relevant constants to be complex. For a matrix representation the elements must be entered as a list in [...] square bracbras. If no list is entered the bra is represented as a general bra, bra(a) will return a.

[Function]

```
(%i4) kill(c1,c2);
      (\%04)
                                                done
      (%i5) bra(c1,c2);
      (\%05)
                                              <c1, c2|
      (%i6) bra([c1,c2]);
                                             [ c1 c2 ]
      (\%06)
      (%i7) facts();
      (\%07)
                                   [kind(hbar, real), hbar > 0]
ketp (vector)
                                                                             [Function]
     ketp is a predicate function that checks if its input is a ket, in which case it returns
     true, else it returns false. ketp only returns true for the matrix representation of
     a ket.
      (%i4) kill(a,b,k);
      (\%04)
                                                done
      (%i5) k:ket(a,b);
      (%o5)
                                               |a, b>
      (%i6) ketp(k);
      (\%06)
                                                false
      (%i7) k:ket([a,b]);
                                                [ a ]
      (\%07)
                                                Γ
                                                     1
                                                [ b ]
      (%i8) ketp(k);
      (%08)
                                                true
brap (vector)
                                                                             [Function]
     brap is a predicate function that checks if its input is a bra, in which case it returns
     true, else it returns false. brap only returns true for the matrix representation of
     a bra.
      (%i4) b:bra([a,b]);
                                              [a b]
      (\%04)
      (%i5) brap(b);
     (%05)
                                                true
dagger (vector)
                                                                             [Function]
     dagger is the quantum mechanical dagger function and returns the conjugate
     transpose of its input.
      (%i4) dagger(bra([%i,2]));
                                              [ - %i ]
                                              (\%04)
                                                      ]
                                              [ 2
                                                      1
```

Given two kets psi and phi, braket returns the quantum mechanical bracket <psi|phi>. The vector psi may be input as either a ket or bra. If it is a ket it will be turned into a bra with the dagger function before the inner product is taken.

The vector phi must always be a ket.

braket (psi,phi)

```
(%i4) declare([a,b,c],complex);
     (\%04)
                                             done
     (%i5) braket(ket([a,b,c]),ket([a,b,c]));
     (%o5)
                     c conjugate(c) + b conjugate(b) + a conjugate(a)
norm (psi)
                                                                        [Function]
     Given a ket or bra psi, norm returns the square root of the quantum mechanical
     bracket <psi|psi>. The vector psi must always be a ket, otherwise the function
     will return false.
     (%i4) declare([a,b,c],complex);
     (\%04)
                                             done
     (%i5) norm(ket([a,b,c]));
     (\%05)
                  sqrt(c conjugate(c) + b conjugate(b) + a conjugate(a))
     (%i6) norm(ket(a,b,c));
     (\%06)
                             sqrt(braket(|a, b, c>, |a, b, c>))
magsqr (c)
                                                                        [Function]
     magsqr returns conjugate(c)*c, the magnitude squared of a complex number.
     (%i4) declare([a,b,c,d],complex);
     (\%04)
                                             done
     (%i5) A:braket(ket([a,b]),ket([c,d]));
     (\%05)
                               conjugate(b) d + conjugate(a) c
     (%i6) P:magsqr(A);
     (%06) (conjugate(b) d + conjugate(a) c) (b conjugate(d) + a conjugate(c))
1.2.1 Spin-1/2 state kets and associated operators
Spin-1/2 particles are characterized by a simple 2-dimensional Hilbert space of states. It is
```

Spin-1/2 particles are characterized by a simple 2-dimensional Hilbert space of states. It is spanned by two vectors. In the z-basis these vectors are {zp,zm}, and the basis kets in the z-basis are {xp,xm} and {yp,ym} respectively.

zp [Function] Return the $|z+\rangle$ ket in the z-basis. [Function] zmReturn the $|z-\rangle$ ket in the z-basis. [Function] хp Return the $|x+\rangle$ ket in the z-basis. xm[Function] Return the $|x-\rangle$ ket in the z-basis. [Function] ур Return the $|y+\rangle$ ket in the z-basis. ym [Function]

Return the $|y-\rangle$ ket in the z-basis.

(%i4)	zp;	[1]
(%o4)		[0]
(%i5)	zm;	
(%o5)		[0] [] [1]
(%i4)	yp;	
(%o4) (%i5)	ym;	[1] [] [sqrt(2)] [%i] [] [sqrt(2)]
	•	[1] [] [sqrt(2)]
(%o5)		[sqrt(2)] [
(%i4)	<pre>braket(xp,zp);</pre>	
(%o4)		1 sqrt(2)

Switching bases is done in the following example where a z-basis ket is constructed and the x-basis ket is computed.

1.2.2 Pauli matrices and Sz, Sx, Sy operators

sigmax [Function]

Returns the Pauli x matrix.

sigmay

[Function]

Returns the Pauli y matrix.

sigmaz

[Function]

Returns the Pauli z matrix.

Sx

[Function]

Returns the spin-1/2 Sx matrix.

Sy

[Function]

Returns the spin-1/2 Sy matrix.

Sz

[Function]

Returns the spin-1/2 Sz matrix.

(%i4) sigmay;

(%i5) Sy;

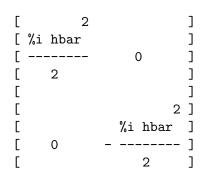
[%i hbar]
[0]
[2]
[]
[%i hba	r]
[- 0]
[2]

commutator (X,Y)

[Function]

Given two operators X and Y, return the commutator X . Y - Y . X.

(%i4) commutator(Sx,Sy);



1.2.3 SX, SY, SZ operators for any spin

SX (s)

[Function]

SX(s) for spin s returns the matrix representation of the spin operator Sx. Shortcuts for spin-1/2 are Sx,Sy,Sz, and for spin-1 are Sx1,Sy1,Sz1.

SY(s)

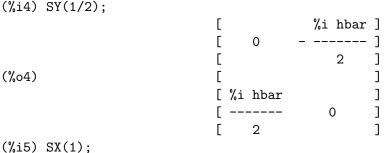
[Function]

SY(s) for spin s returns the matrix representation of the spin operator Sy. Shortcuts for spin-1/2 are Sx,Sy,Sz, and for spin-1 are Sx1,Sy1,Sz1.

SZ (s) [Function]

SZ(s) for spin s returns the matrix representation of the spin operator Sz. Shortcuts for spin-1/2 are Sx,Sy,Sz, and for spin-1 are Sx1,Sy1,Sz1.

Example:



0 0 sqrt(2)]] hbar (%05)0 sqrt(2)] sgrt(2)]] hbar] 0 _____ 0] sqrt(2)

1.2.4 Expectation value and variance

expect (0,psi) [Function]

Computes the quantum mechanical expectation value of the operator O in state psi, <psi|O|psi>.

qm_variance (0,psi)

[Function]

Computes the quantum mechanical variance of the operator O in state psi, $\ensuremath{\mathsf{sqrt}}(\ensuremath{\mathsf{sqrt}})^2|\ensuremath{\mathsf{psi}}> - \ensuremath{\mathsf{sqrt}})$.

1.2.5 Angular momentum representation of kets and bras

To create kets and bras in the $|j,m\rangle$ representation you can use the following functions.

 jm_ket creates the ket $|j,m\rangle$ for total spin j and z-component m.

```
jm_bra (j,m)
                                                                            [Function]
     jm_bra creates the bra \langle j,m| for total spin j and z-component m.
     (%i4) jm_bra(3/2,1/2);
                                                  [3 1]
                                         [jmbra, [ - - ]]
     (\%04)
                                                       2]
                                                                            [Function]
jm_ketp (jmket)
     jm_ketp checks to see that the ket has the 'jmket' marker.
                                                                            [Function]
     jm_brap checks to see that the bra has the 'jmbra' marker.
jm_check (j,m)
                                                                            [Function]
     jm\_check checks to see that m is one of \{-j, \ldots, +j\}.
jm_braket (jmbra, jmket)
                                                                            [Function]
     jm_braket takes the inner product of the jm-kets.
     (%i4) K:jm_ket(j1,m1);
                                        [jmket, [ j1 m1 ]]
     (\%04)
     (%i5) B:jm_bra(j2,m2);
     (%05)
                                        [jmbra, [ j2 m2 ]]
     (%i6) jm_braket(B,K);
                                                  0
     (\%06)
     (%i7) B:jm_bra(j1,m1);
                                        [jmbra, [ j1 m1 ]]
     (\%07)
     (%i8) jm_braket(B,K);
     (%08)
1.2.6 Angular momentum and ladder operators
SP (s)
                                                                            [Function]
     SP is the raising ladder operator S_+ for spin s.
SM (s)
                                                                            [Function]
     SM is the raising ladder operator S_{-} for spin s.
  Examples of the ladder operators:
     (%i4) SP(1);
                                                                    ]
                               [ 0
                                     sqrt(2) hbar
                                                           0
                                ]
                               [ 0
     (\%04)
                                                     sqrt(2) hbar ]
                                [ 0
                                           0
                                                           0
                                                                    ]
     (%i5) SM(1);
                                0
                                                       0
                                                                 0 ]
                                                                    ]
                               [ sqrt(2) hbar
                                                                 0 ]
     (%05)
                               sqrt(2) hbar 0 ]
                                       0
```

1.3 Rotation operators

RX (s,t) [Function]

RX(s) for spin s returns the matrix representation of the rotation operator Rx for rotation through angle t.

RY (s,t) [Function]

RY(s) for spin s returns the matrix representation of the rotation operator Ry for rotation through angle t.

RZ (s,t) [Function]

RZ(s) for spin s returns the matrix representation of the rotation operator Rz for rotation through angle t.

(%i4) RZ(1/2,t);

Proviso: assuming 64*t # 0

%i t] 2 Γ [%e (%04)] %i t] ----] 2 1] 0 %e

1.4 Time-evolution operator

UU (H,t) [Function]

UU(H,t) is the time evolution operator for Hamiltonian H. It is defined as the matrix exponential matrixexp(-%i*H*t/hbar).

(%i4) UU(w*Sy,t);

Proviso: assuming 64*t*w # 0

[tw tw]
[cos(---) - sin(---)]
[2 2]
(%04)
[tw tw]
[sin(---) cos(---)]

1.5 Tensor products

Tensor products are represented as lists in Maxima. The ket tensor product |z+,z+> is represented as [tpket,zp,zp], and the bra tensor product <a,b| is represented as [tpbra,a,b] for kets a and b. The list labels tpket and tpbra ensure calculations are performed with the correct kind of objects.

 $ketprod (k_1, k_2, ...)$

[Function]

ketprod produces a tensor product of kets k_i . All of the elements must pass the ketp predicate test to be accepted.

braprod (b_1, b_2, \ldots)

[Function]

braprod produces a tensor product of bras b_i. All of the elements must pass the brap predicate test to be accepted.

braketprod (B,K)

[Function]

braketprod takes the inner product of the tensor products B and K. The tensor products must be of the same length (number of kets must equal the number of bras).

Examples below show how to create tensor products and take the bracket of tensor products.

```
(%i4) ketprod(zp,zm);
                                     [1] [0]
(\%04)
                            [tpket, [[ ], [ ]]]
                                     [0][1]
(%i5) ketprod('zp,'zm);
                          all elements must be kets
(\%05)
                                     done
(%i4) kill(a,b,c,d);
(\%04)
                                     done
(%i5) declare([a,b,c,d],complex);
(\%05)
                                     done
(%i6) braprod(bra([a,b]),bra([c,d]));
(\%06)
                         [tpbra, [[ a b ], [ c d ]]]
(%i7) braprod(dagger(zp),bra([c,d]));
(\%07)
                         [tpbra, [[ 1 0 ], [ c d ]]]
(%i4) K:ketprod(zp,zm);
                                     [1] [0]
                                       ],[]]]
(\%04)
                            [tpket, [[
                                     [0][1]
(%i5) zpb:dagger(zp);
(\%05)
                                   [10]
(%i6) zmb:dagger(zm);
                                   [01]
(\%06)
(%i7) B:braprod(zpb,zmb);
(\%07)
                         [tpbra, [[ 1 0 ], [ 0 1 ]]]
(%i8) braketprod(K,B);
(%08)
                                     false
(%i9) braketprod(B,K);
(\%09)
                                       1
```

Appendix A Function and Variable index

В	Q
bra	qm_variance
brap	R x8
\mathbf{C}	RY
commutator	\mathbf{S}
D dagger	sigmax 4 sigmay 5 sigmaz 5 SM 7
${f E}$	SP
expect6	SX
J	SY 5 Sz 5
jm_bra 7 jm_braket 7 jm_brap 7	SZ 6
jm_check 7 jm_ket 6 jm_ketp 7	U ww8
K	\mathbf{X}
ket 1 ketp 2	xm
ketprod	\mathbf{Y}
${f M}$ magsqr 3	ут
N	Z
norm	zp

Appendix A: Function and Variable index	
hbar1	