## 1.1 Introduction to package qm

The `qm` package was written by Eric Majzoub, University of Missouri. Email: majzoube-at-umsystem.edu

The `qm` package provides functions and standard definitions to solve quantum mechanics problems in a finite dimensional Hilbert space. For example, one can calculate the outcome of Stern-Gerlach experiments using the built-in definition of the Sx, Sy, and Sz operators for arbitrary spin, e.g. `s={1/2, 1, 3/2, ...}`. For spin-1/2 the standard basis states in the $x$, $y$, and $z$-basis are available as `{xp,xm}`, `{yp,ym}`, and `{zp,zm}`. One can create general ket vectors with arbitrary but finite dimension and perform standard computations such as expectation value, variance, etc. The angular momentum $|j,m>$ representation of kets is also available. It is also possible to create tensor product states for multiparticle systems and to perform calculations on those systems.

Kets and bras are represented by column and row vectors, respectively. For spin-1/2 particles, for example, the bra vector

`<psi| = a <z+| + b <z-|`

is represented by the row vector `[a b]`, where the basis vectors are

`<z+| = [1 0]`

and

`<z-| = [0 1].`

Generally, if one wishes to do purely symbolic calculations, then input of basic kets, (j,m)-kets, and so forth should be done without lists. If one wishes to do numerical computations using the kets then enter the arguments as a list. See the following examples.

```
(%i1) ket(a,b)+ket(c,d);
(%o1)                              |c, d> + |a, b>
(%i2) ket([a,b])+ket([c,d]);
                                        [ c + a ]
(%o2)                                   [       ]
                                        [ d + b ]
(%i1) ketprod('zp,'zm)+ketprod('zm,'zp);
(%o1)                     ketprod(zp, zm) + ketprod(zm, zp)
(%i2) ketprod([zp,zm]);
                                          [ 1 ]   [ 0 ]
(%o2)                         [tpket, [[     ],  [     ]]]
                                          [ 0 ]   [ 1 ]
(%i1) declare([a,b],complex);
(%o1)                                  done
(%i2) psi:a*ket(1)+b*ket(2);
(%o2)                              |2> b + |1> a
(%i3) psidag:dagger(psi);
(%o3)                     <2| conjugate(b) + <1| conjugate(a)
(%i4) psidag . psi;
(%o4)                       b conjugate(b) + a conjugate(a)
```

```
(%i1) declare([c1,c2],complex,r,real);
(%o1)                                  done
(%i2) k:ket([c1,c2,r]);
                                    [ c1 ]
                                    [    ]
(%o2)                               [ c2 ]
                                    [    ]
                                    [ r  ]
(%i3) b:dagger(k);
(%o3)                  [ conjugate(c1)  conjugate(c2)  r ]
(%i4) b . k;
                     2
(%o4)               r  + c2 conjugate(c2) + c1 conjugate(c1)
```

The package is loaded with: `load(qm);`

## 1.2 Functions and Variables for qm

**hbar**                                                                    [Variable]

Planck's constant divided by `2*%pi`. `hbar` is not given a floating point value, but is declared to be a real number greater than zero.

**ket** ($[c_1,c_2,\ldots]$)                                                [Function]

`ket` creates a *column* vector of arbitrary finite dimension. The entries $c_i$ can be any Maxima expression. The user must `declare` any relevant constants to be complex. For a matrix representation the elements must be entered as a list in `[...]` square brackets. If no list is entered the ket is represented as a general ket, `ket(a)` will return `|a>`.

```
(%i1) kill(a);
(%o1)                                  done
(%i2) ket(a);
(%o2)                                   |a>
(%i3) declare([c1,c2],complex);
(%o3)                                  done
(%i4) ket([c1,c2]);
                                    [ c1 ]
(%o4)                               [    ]
                                    [ c2 ]
(%i5) facts();
(%o5) [kind(hbar, real), hbar > 0, kind(c1, complex), kind(c2, complex)]
```

**bra** ($[c_1,c_2,\ldots]$)                                                [Function]

`bra` creates a *row* vector of arbitrary finite dimension. The entries $c_i$ can be any Maxima expression. The user must `declare` any relevant constants to be complex. For a matrix representation the elements must be entered as a list in `[...]` square bracbras. If no list is entered the bra is represented as a general bra, `bra(a)` will return `<a|`.

```
(%i1) kill(c1,c2);
(%o1)                              done
(%i2) bra(c1,c2);
(%o2)                            <c1, c2|
(%i3) bra([c1,c2]);
(%o3)                           [ c1   c2 ]
(%i4) facts();
(%o4)                  [kind(hbar, real), hbar > 0]
```

**ketp** (*vector*)                                                          [Function]

ketp is a predicate function that checks if its input is a ket, in which case it returns true, else it returns false. ketp only returns true for the matrix representation of a ket.

```
(%i1) kill(a,b,k);
(%o1)                              done
(%i2) k:ket(a,b);
(%o2)                             |a, b>
(%i3) ketp(k);
(%o3)                             false
(%i4) k:ket([a,b]);
                                  [ a ]
(%o4)                             [   ]
                                  [ b ]
(%i5) ketp(k);
(%o5)                             true
```

**brap** (*vector*)                                                          [Function]

brap is a predicate function that checks if its input is a bra, in which case it returns true, else it returns false. brap only returns true for the matrix representation of a bra.

```
(%i1) b:bra([a,b]);
(%o1)                           [ a   b ]
(%i2) brap(b);
(%o2)                             true
```

**dagger** (*vector*)                                                        [Function]

dagger is the quantum mechanical *dagger* function and returns the conjugate transpose of its input.

```
(%i1) dagger(bra([%i,2]));
                                  [ - %i ]
(%o1)                             [      ]
                                  [  2   ]
```

**braket** (psi,phi)                                                         [Function]

Given two kets psi and phi, braket returns the quantum mechanical bracket <psi|phi>. The vector psi may be input as either a ket or bra. If it is a ket it will be turned into a bra with the dagger function before the inner product is taken. The vector phi must always be a ket.

```
(%i1) declare([a,b,c],complex);
(%o1)                              done
(%i2) braket(ket([a,b,c]),ket([a,b,c]));
(%o2)          c conjugate(c) + b conjugate(b) + a conjugate(a)
```

**norm (psi)** [Function]

Given a `ket` or `bra psi`, `norm` returns the square root of the quantum mechanical
bracket `<psi|psi>`. The vector `psi` must always be a `ket`, otherwise the function
will return `false`.

```
(%i1) declare([a,b,c],complex);
(%o1)                              done
(%i2) norm(ket([a,b,c]));
(%o2)        sqrt(c conjugate(c) + b conjugate(b) + a conjugate(a))
(%i3) norm(ket(a,b,c));
(%o3)                          norm(|a, b, c>)
```

**magsqr (c)** [Function]

`magsqr` returns `conjugate(c)*c`, the magnitude squared of a complex number.

```
(%i1) declare([a,b,c,d],complex);
(%o1)                              done
(%i2) A:braket(ket([a,b]),ket([c,d]));
(%o2)                  conjugate(b) d + conjugate(a) c
(%i3) P:magsqr(A);
(%o3) (conjugate(b) d + conjugate(a) c) (b conjugate(d) + a conjugate(c))
```

### 1.2.1 Handling general kets and bras

General kets and bras are, as discussed, created without using a list when giving the arguments. The following examples show how general kets and bras can be manipulated.

```
(%i1) ket(a)+ket(b);
(%o1)                              |b> + |a>
(%i2) braket(bra(a),ket(b));
(%o2)                          kron_delta(a, b)
(%i3) braket(bra(a)+bra(c),ket(b));
(%o3)                  kron_delta(b, c) + kron_delta(a, b)
```

### 1.2.2 Spin-1/2 state kets and associated operators

Spin-1/2 particles are characterized by a simple 2-dimensional Hilbert space of states. It is spanned by two vectors. In the $z$-basis these vectors are {zp,zm}, and the basis kets in the $z$-basis are {xp,xm} and {yp,ym} respectively.

**zp** [Function]

Return the $|z+>$ ket in the $z$-basis.

**zm** [Function]

Return the $|z->$ ket in the $z$-basis.

**xp** [Function]

Return the $|x+>$ ket in the $z$-basis.

xm                                                                          [Function]
      Return the |x-> ket in the *z*-basis.

yp                                                                          [Function]
      Return the |y+> ket in the *z*-basis.

ym                                                                          [Function]
      Return the |y-> ket in the *z*-basis.

```
(%i1) zp;
                                        [ 1 ]
(%o1)                                   [   ]
                                        [ 0 ]
(%i2) zm;
                                        [ 0 ]
(%o2)                                   [   ]
                                        [ 1 ]
(%i1) yp;
                                   [    1    ]
                                   [ ------- ]
                                   [ sqrt(2) ]
(%o1)                              [         ]
                                   [   %i    ]
                                   [ ------- ]
                                   [ sqrt(2) ]
(%i2) ym;
                                   [     1     ]
                                   [  -------  ]
                                   [  sqrt(2)  ]
(%o2)                              [           ]
                                   [     %i    ]
                                   [ - ------- ]
                                   [   sqrt(2) ]
(%i1) braket(xp,zp);
                                        1
(%o1)                                 -------
                                      sqrt(2)
```

Switching bases is done in the following example where a *z*-basis ket is constructed and the *x*-basis ket is computed.

```
(%i1) declare([a,b],complex);
(%o1)                                    done
(%i2) psi:ket([a,b]);
                                        [ a ]
(%o2)                                   [   ]
                                        [ b ]
(%i3) psi_x:'xp*braket(xp,psi)+'xm*braket(xm,psi);
                    b        a                  a        b
(%o3)          (------- + -------) xp + (------- - -------) xm
               sqrt(2)   sqrt(2)         sqrt(2)   sqrt(2)
```

## 1.2.3 Pauli matrices and Sz, Sx, Sy operators

**sigmax**                                                    [Function]
Returns the Pauli x matrix.

**sigmay**                                                    [Function]
Returns the Pauli *y* matrix.

**sigmaz**                                                    [Function]
Returns the Pauli *z* matrix.

**Sx**                                                        [Function]
Returns the spin-1/2 *Sx* matrix.

**Sy**                                                        [Function]
Returns the spin-1/2 *Sy* matrix.

**Sz**                                                        [Function]
Returns the spin-1/2 *Sz* matrix.

```
(%i1) sigmay;
                                    [ 0    - %i ]
(%o1)                               [          ]
                                    [ %i    0   ]
(%i2) Sy;
                            [              %i hbar ]
                            [    0      - ------- ]
                            [              2       ]
(%o2)                       [                      ]
                            [ %i hbar              ]
                            [ -------       0      ]
                            [    2                 ]
```

**commutator (X,Y)**                                          [Function]
Given two operators X and Y, return the commutator X . Y - Y . X.

```
(%i1) commutator(Sx,Sy);
                            [          2             ]
                            [ %i hbar               ]
                            [ --------       0       ]
                            [    2                   ]
(%o1)                       [                        ]
                            [                     2  ]
                            [              %i hbar   ]
                            [      0     - --------  ]
                            [                 2      ]
```

### 1.2.4 SX, SY, SZ operators for any spin

SX (s)                                                                  [Function]
  SX(s) for spin s returns the matrix representation of the spin operator Sx. Shortcuts
  for spin-1/2 are Sx,Sy,Sz, and for spin-1 are Sx1,Sy1,Sz1.

SY (s)                                                                  [Function]
  SY(s) for spin s returns the matrix representation of the spin operator Sy. Shortcuts
  for spin-1/2 are Sx,Sy,Sz, and for spin-1 are Sx1,Sy1,Sz1.

SZ (s)                                                                  [Function]
  SZ(s) for spin s returns the matrix representation of the spin operator Sz. Shortcuts
  for spin-1/2 are Sx,Sy,Sz, and for spin-1 are Sx1,Sy1,Sz1.

  Example:

```
(%i1) SY(1/2);
                            [              %i hbar ]
                            [     0      - ------- ]
                            [                 2    ]
(%o1)                       [                      ]
                            [ %i hbar              ]
                            [ -------        0     ]
                            [    2                 ]
(%i2) SX(1);
                     [              hbar              ]
                     [     0      -------       0     ]
                     [            sqrt(2)             ]
                     [                               ]
                     [  hbar                   hbar  ]
(%o2)                [ -------        0      ------- ]
                     [ sqrt(2)                sqrt(2) ]
                     [                               ]
                     [              hbar              ]
                     [     0      -------       0     ]
                     [            sqrt(2)             ]
```

### 1.2.5 Expectation value and variance

**expect (O,psi)** [Function]

Computes the quantum mechanical expectation value of the operator `O` in state `psi`, `<psi|O|psi>`.

```
(%i1) ev(expect(Sy,xp+ym),ratsimp);
(%o1)                              - hbar
```

**qm_variance (O,psi)** [Function]

Computes the quantum mechanical variance of the operator `O` in state `psi`, `sqrt(<psi|O`$^2$`|psi> - <psi|O|psi>`$^2$`)`.

```
(%i1) ev(qm_variance(Sy,xp+ym),ratsimp);
                                  %i hbar
(%o1)                             -------
                                     2
```

### 1.2.6 Angular momentum representation of kets and bras

To create kets and bras in the |*j,m*> representation you can use the following functions.

**jm_ket (j,m)** [Function]

`jm_ket` creates the ket |*j,m*> for total spin *j* and *z*-component *m*.

**jm_bra (j,m)** [Function]

`jm_bra` creates the bra <*j,m*| for total spin *j* and *z*-component *m*.

```
(%i1) jm_bra(3/2,1/2);
                                   3   1
(%o1)                       jm_bra(-,  -)
                                   2   2
(%i2) jm_bra([3/2,1/2]);
                                  [ 3   1 ]
(%o2)                     [jmbra, [ -   - ]]
                                  [ 2   2 ]
```

**jm_ketp (*jmket*)** [Function]

`jm_ketp` checks to see that the ket has the 'jmket' marker.

```
(%i1) jm_ketp(jm_ket(j,m));
(%o1)                           false
(%i2) jm_ketp(jm_ket([j,m]));
(%o2)                           true
```

**jm_brap (*jmbra*)** [Function]

`jm_brap` checks to see that the bra has the 'jmbra' marker.

**jm_check (j,m)** [Function]

`jm_check` checks to see that *m* is one of {-j, ..., +j}.

```
(%i1) jm_check(3/2,1/2);
(%o1)                           true
```

`jm_braket` (*jmbra,jmket*)                                                    [Function]

jm_braket takes the inner product of the jm-kets.

```
(%i1) K:jm_ket(j1,m1);
(%o1)                              jm_ket(j1, m1)
(%i2) B:jm_bra(j2,m2);
(%o2)                              jm_bra(j2, m2)
(%i3) jm_braket(B,K);
(%o3)                   kron_delta(j1, j2) kron_delta(m1, m2)
(%i4) B:jm_bra(j1,m1);
(%o4)                              jm_bra(j1, m1)
(%i5) jm_braket(B,K);
(%o5)                                   1
(%i6) K:jm_ket([j1,m1]);
(%o6)                             [jmket, [ j1   m1 ]]
(%i7) B:jm_bra([j2,m2]);
(%o7)                             [jmbra, [ j2   m2 ]]
(%i8) jm_braket(B,K);
(%o8)                                   0
(%i9) jm_braket(jm_bra(j1,m1)+jm_bra(j3,m3),jm_ket(j2,m2));
(%o9) kron_delta(j2, j3) kron_delta(m2, m3)
                                    + kron_delta(j1, j2) kron_delta(m1, m2)
```

`JP` (*jmket*)                                                                [Function]

JP is the $J_+$ operator. It takes a jmket jm_ket(j,m) and returns sqrt(j*(j+1)-m*(m+1))*hbar*jm_ket(j,m+1).

`JM` (*jmket*)                                                                [Function]

JM is the $J_-$ operator. It takes a jmket jm_ket(j,m) and returns sqrt(j*(j+1)-m*(m-1))*hbar*jm_ket(j,m-1).

`Jsqr` (*jmket*)                                                              [Function]

Jsqr is the $J^2$ operator. It takes a jmket jm_ket(j,m) and returns (j*(j+1)*hbar$^2$*jm_ket(j,m).

`Jz` (*jmket*)                                                                [Function]

Jz is the $J_z$ operator. It takes a jmket jm_ket(j,m) and returns m*hbar*jm_ket(j,m).

These functions are illustrated below.

```
(%i1) k:jm_ket([j,m]);
(%o1)                           [jmket, [ j   m ]]
(%i2) JP(k);
(%o2)           hbar jm_ket(j, m + 1) sqrt(j (j + 1) - m (m + 1))
(%i3) JM(k);
(%o3)           hbar jm_ket(j, m - 1) sqrt(j (j + 1) - (m - 1) m)
(%i4) Jsqr(k);
                                  2
(%o4)                   hbar  j (j + 1) jm_ket(j, m)
(%i5) Jz(k);
(%o5)                     hbar jm_ket(j, m) m
```

### 1.2.7 Angular momentum and ladder operators

SP (s)                                                              [Function]
   SP is the raising ladder operator $S_+$ for spin s.

SM (s)                                                              [Function]
   SM is the raising ladder operator $S_-$ for spin s.

   Examples of the ladder operators:

```
(%i1) SP(1);
                      [ 0  sqrt(2) hbar       0        ]
                      [                                ]
(%o1)                 [ 0       0        sqrt(2) hbar  ]
                      [                                ]
                      [ 0       0             0        ]
(%i2) SM(1);
                      [      0            0         0 ]
                      [                              ]
(%o2)                 [ sqrt(2) hbar      0         0 ]
                      [                              ]
                      [      0       sqrt(2) hbar   0 ]
```

## 1.3 Rotation operators

RX (s,t)                                                           [Function]
   RX(s) for spin s returns the matrix representation of the rotation operator Rx for
   rotation through angle t.

RY (s,t)                                                           [Function]
   RY(s) for spin s returns the matrix representation of the rotation operator Ry for
   rotation through angle t.

RZ (s,t)                                                           [Function]
   RZ(s) for spin s returns the matrix representation of the rotation operator Rz for
   rotation through angle t.

```
(%i1) RZ(1/2,t);
Proviso: assuming 64*t # 0
                                [      %i t          ]
                                [    - ----          ]
                                [       2            ]
                                [ %e            0    ]
(%o1)                           [                    ]
                                [             %i t   ]
                                [             ----   ]
                                [              2     ]
                                [    0       %e      ]
```

## 1.4 Time-evolution operator

UU (H,t)                                                              [Function]
   UU(H,t) is the time evolution operator for Hamiltonian H. It is defined as the matrix
   exponential matrixexp(-%i*H*t/hbar).

```
(%i1) UU(w*Sy,t);
Proviso: assuming 64*t*w # 0
                                [      t w          t w  ]
                                [ cos(---)   - sin(---)  ]
                                [      2            2    ]
(%o1)                           [                        ]
                                [      t w          t w  ]
                                [ sin(---)    cos(---)   ]
                                [      2            2    ]
```

## 1.5 Tensor products

Tensor products are represented as lists in Maxima. The ket tensor product |z+,z+>
is represented as [tpket,zp,zp], and the bra tensor product <a,b| is represented as
[tpbra,a,b] for kets a and b. The list labels tpket and tpbra ensure calculations are
performed with the correct kind of objects.

ketprod (k$_1$, k$_2$, ...)                                            [Function]
   ketprod produces a tensor product of kets k$_i$. All of the elements must pass the ketp
   predicate test to be accepted.

braprod (b$_1$, b$_2$, ...)                                            [Function]
   braprod produces a tensor product of bras b$_i$. All of the elements must pass the brap
   predicate test to be accepted.

braketprod (B,K)                                                      [Function]
   braketprod takes the inner product of the tensor products B and K. The tensor
   products must be of the same length (number of kets must equal the number of bras).

   Examples below show how to create tensor products and take the bracket of tensor
products.

```
(%i1) ketprod(zp,zm);
                                    [ 1 ]   [ 0 ]
(%o1)                       ketprod([   ], [   ])
                                    [ 0 ]   [ 1 ]
(%i2) ketprod('zp,'zm);
(%o2)                          ketprod(zp, zm)
(%i1) kill(a,b,c,d);
(%o1)                              done
(%i2) declare([a,b,c,d],complex);
(%o2)                              done
(%i3) braprod(bra([a,b]),bra([c,d]));
(%o3)                       braprod([ a  b ], [ c  d ])
(%i4) braprod(dagger(zp),bra([c,d]));
(%o4)                       braprod([ 1  0 ], [ c  d ])
(%i1) K:ketprod(zp,zm);
                                    [ 1 ]   [ 0 ]
(%o1)                       ketprod([   ], [   ])
                                    [ 0 ]   [ 1 ]
(%i2) zpb:dagger(zp);
(%o2)                             [ 1  0 ]
(%i3) zmb:dagger(zm);
(%o3)                             [ 0  1 ]
(%i4) B:braprod(zpb,zmb);
(%o4)                       braprod([ 1  0 ], [ 0  1 ])
(%i5) braketprod(K,B);
(%o5)                              false
(%i6) braketprod(B,K);
(%o6)                              false
```

# Appendix A  Function and Variable index