

# II.2 Energy Models for Sensor Networks

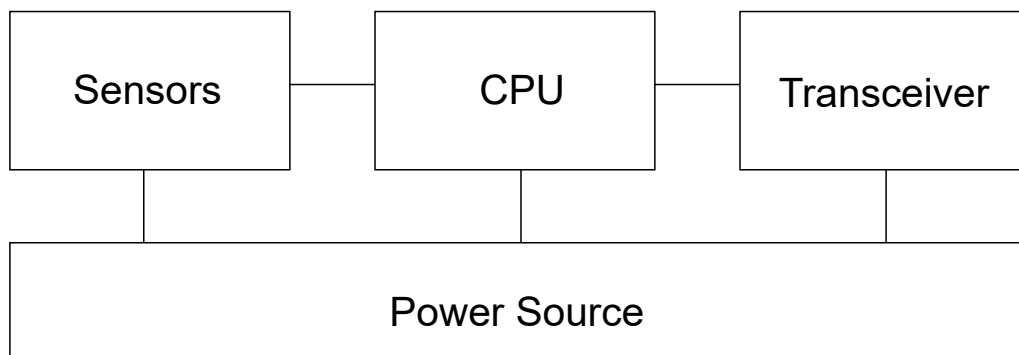
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EE5132/EE5024 IoT Sensor Networks  
CK Tham, ECE NUS

## Basic Architecture



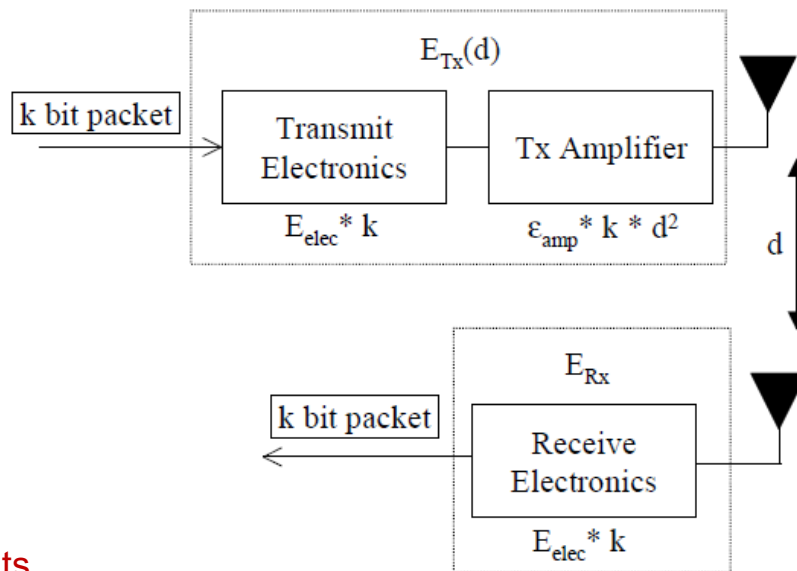
# Sources of Energy Consumption

- Radio
  - Transceiver electronics
- Processing
  - Dynamic Voltage Scaling (DVS)
    - Reduction of frequency allows the processor to run at a lower voltage
    - Supply voltage  $V$
    - Switching Energy consumed  $\propto V^2$
    - Leakage Energy
      - due to leakage current (happens even when no work is done)
      - exponential relationship with supply voltage
  - Hence, reducing  $V$  reduces energy consumption
  - However, this increases latency
- Switching between active, idle and sleep modes
- Storage

## Simple Radio Model

[Heinzelman00]

- Different assumptions about the radio characteristics, including energy dissipation in the transmit and receive modes, will change the advantages of different protocols.
- Consider a simple model where the radio dissipates  $E_{elec} = 50$  nJ/bit to run the transmitter or receiver circuitry, and  $\epsilon_{amp} = 100$  pJ/bit/m<sup>2</sup> for the transmit amplifier to achieve an acceptable SNR  $E_b/N_0$ .
- *Note:* This model may be overly optimistic.



$k$  = no. of bits

$$E_{Tx}(k, d) = E_{Tx-elec}(k) + E_{Tx-amp}(k, d)$$

$$E_{Tx}(k, d) = E_{elec} * k + \epsilon_{amp} * k * d^2$$

energy loss due to channel txn

$$E_{Rx}(k) = E_{Rx-elec}(k)$$

$$E_{Rx}(k) = E_{elec} * k$$

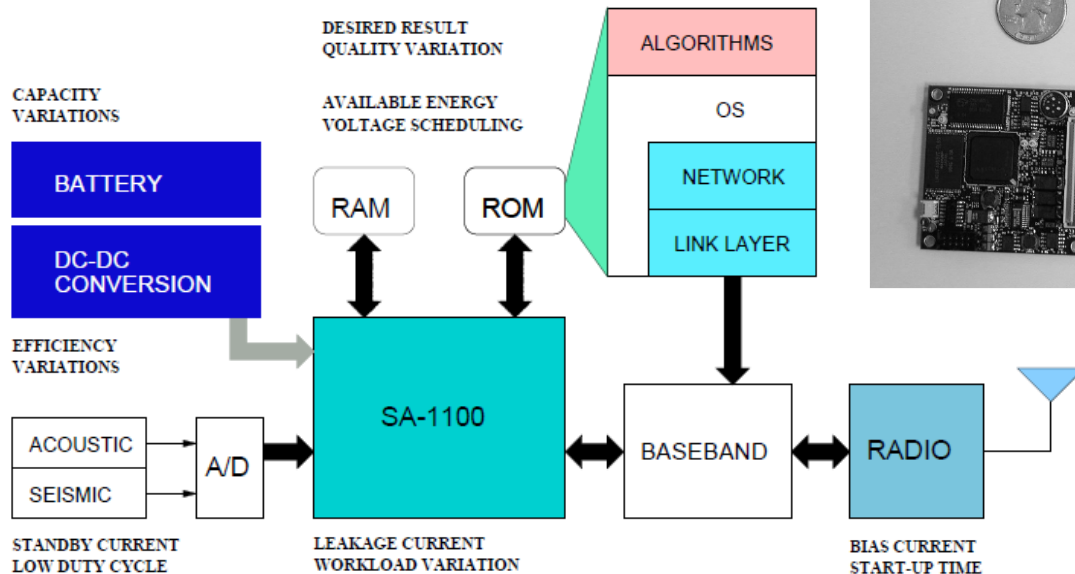
Operation	Energy Dissipated
Transmitter Electronics ( $E_{Tx-elec}$ ) Receiver Electronics ( $E_{Rx-elec}$ ) ( $E_{Tx-elec} = E_{Rx-elec} = E_{elec}$ )	50 nJ/bit
Transmit Amplifier ( $\epsilon_{amp}$ )	100 pJ/bit/m <sup>2</sup>

## Points to Note

- For these parameter values:
  - receiving a message is not a low cost operation
  - protocols should thus try to minimize not only the transmit distances but also the number of transmit and receive operations for each message

# $\mu$ AMPS Wireless Sensor Node

[Shih01]



# $\mu$ AMPS Wireless Sensor Node

- $\mu$ AMPS (micro-Adaptive Multi-domain Power-aware Sensors)
- Wish to scale the energy consumption of the entire system in order to maximize system lifetime and reduce global energy consumption
  - all layers of the system, including the algorithms, operating system and network protocols can adapt to minimize energy usage
- StrongARM SA 1110 microprocessor
  - clock speed can vary from 59 to 206 MHz, i.e. energy consumption can be varied

# More Detailed Radio Model

[Shih01]

- Average power consumption of the radio

$$P_{radio} = N_{tx} [P_{tx} (T_{on-tx} + T_{st}) + P_{out} T_{on-tx}] + N_{rx} [P_{rx} (T_{on-rx} + T_{st})]$$

$N_{tx/rx}$  is the average number of times per second that the transmitter/receiver is used

$P_{tx/rx}$  is the power consumption of the transmitter/receiver

$P_{out}$  is the output transmit power (power amplifier)

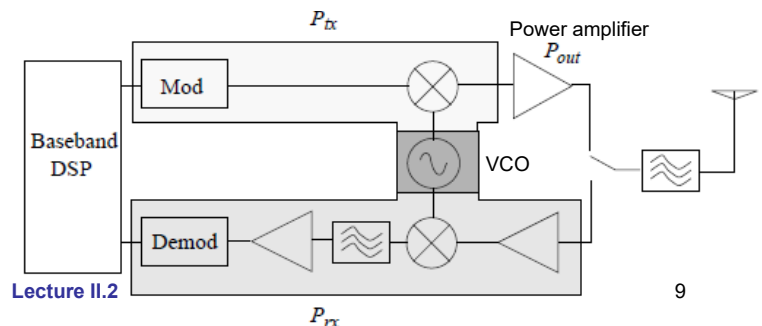
$T_{on-tx/rx}$  is the transmit/receive on-time (actual data transmission/reception time)

$= L/R$ , where  $L$  is the packet size in bits and  $R$  is the data rate in bits per second

$T_{st}$  is the startup time of the transceiver

The power amplifier is on only when communications occur.

$P_{rx}$  is 2 to 3 times higher than  $P_{tx}$  as the receiver circuitry is more complex, e.g.  $\approx 180$  mW



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## Start Up Energy

- Common energy saving strategy: shut off radio when not in use
- Is this always good?
- No!
- Start up time: for phase-locked loop (PLL) of transceiver to be locked to desired carrier frequency using voltage controlled oscillator (VCO)
- Start up energy quite high
- Moral: Good only if packet size large enough

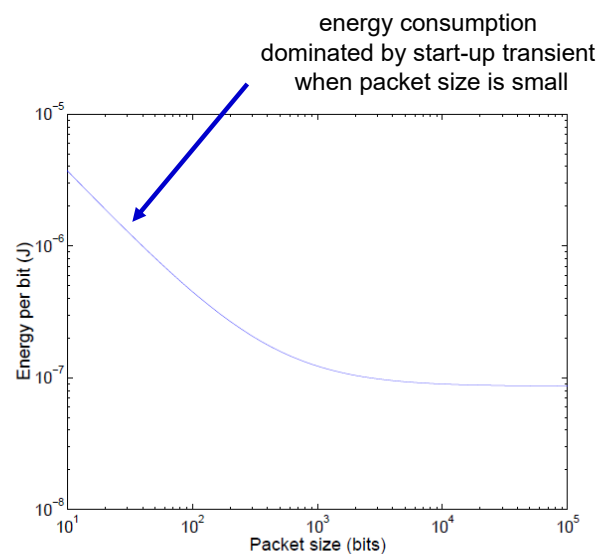


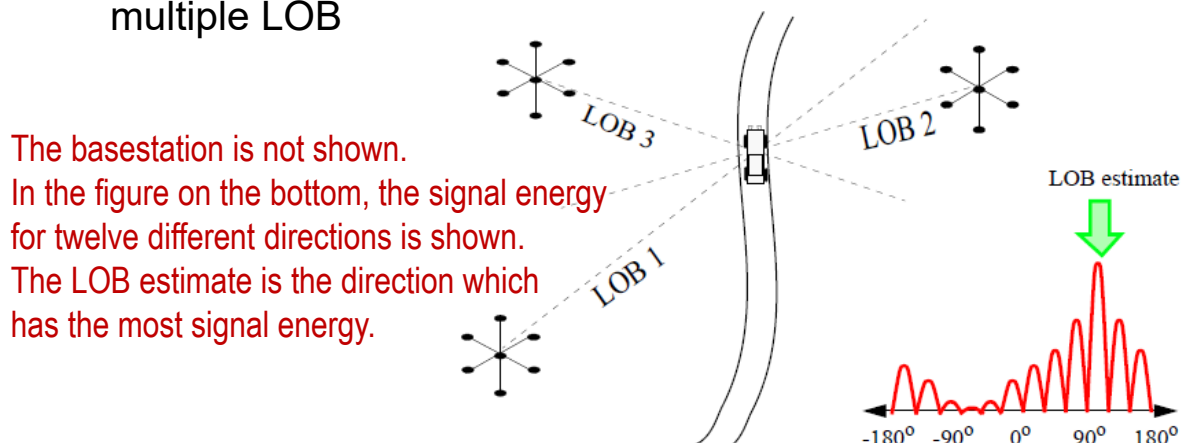
Figure 5: Effect of startup transient where  $R = 1$  Mbps,  $T_{st} \approx 450 \mu s$ ,  $P_{tx} = 81$  mW, and  $P_{out} = 0$  dBm.

# Energy for Communication

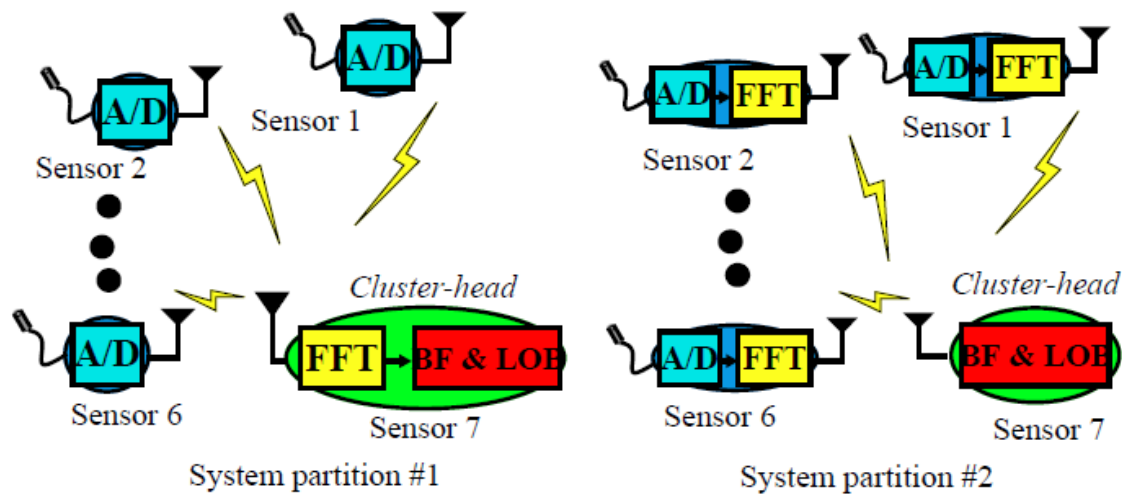
- Other factors
  - Link layer: coding
  - Modulation scheme
  - refer to [Shih01] for details
- Effects of MAC, routing and transport protocols will be studied in greater detail in subsequent lectures

## Vehicle Tracking Application

- Objective: find the location of the vehicle using acoustic sensing
- Assume clustered sensor nodes
- Entities: node, clusterhead, base station
- Each node sends data to clusterhead which computes the LOB (line of bearing) through signal processing (Fast Fourier Transform)
- Basestation (sink) determines location from intersection point of multiple LOB



# Computation Partitioning



Beamforming (BF): sum outputs of filtered sensor outputs

# Computation Partitioning

Note: Reducing processor frequency allows it to run at a lower voltage.

**Latency limit: 20 ms**

- All computation is done on the clusterhead
- FFT & BF at cluster head:  $f=206$  MHz at 1.44 V
- Energy = 6.2mJ
- Latency = 19.2ms

System Partition 1

- 1024 pt FFT at each sensor at 0.85 V and 74 MHz
- BF at cluster head at 1.17 V and 162 MHz
- Energy = 3.4mJ
- Latency = 18.4ms

System Partition 2

# Node-Level Power Mode Scheduling

- A power mode scheduling algorithm manages the active and sleep modes of the underlying device in order to increase node lifetime
  - wasted energy due to leakage can be reduced since if a device is completely turned off, no leakage energy is dissipated

## Node Operating Modes

- System power model like ACPI  
Advanced Configuration & Power Interface

**Table 1: Useful sleep states for the sensor node.**

State	SA-1110	Sensor, A/D	Radio
Active ( $s_0$ )	active	sense	tx/rx
Ready ( $s_1$ )	idle	sense	rx
Monitor ( $s_2$ )	sleep	sense	rx
Observe ( $s_3$ )	sleep	sense	off
Deep Sleep ( $s_4$ )	sleep	off	off

- ↓ 1. Increasing latency to sleep/wake  
2. Decreasing power consumption



# State Transitions

$t_i$  = time between end of processing of previous event and arrival of next event  
hierarchy of sleep states

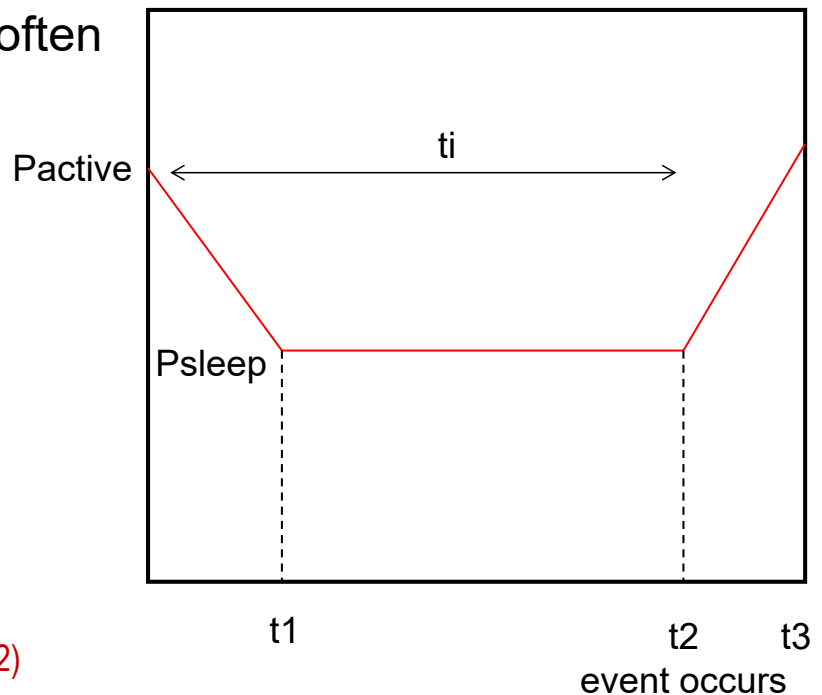
- Should not switch between states very often

- Eact->sleep =  $(P_{active} + P_{sleep}) * t_1 / 2$
- Esleep =  $P_{sleep} * (t_2 - t_1)$
- Esleep->act =  $(P_{active} + P_{sleep}) * (t_3 - t_2) / 2$

- Therefore, sleep if  $P_{active} * t_i > E_{act \rightarrow sleep} + E_{sleep} + E_{sleep \rightarrow active}$

- One other drawback: latency!

Latency is  $(t_3 - t_2)$



# State Transitions

$t_i$  = time between end of processing of previous event and arrival of next event

Energy saving  $E_s$  due to transitioning:

$$E_{s,k} = P_0 t_i - \left[ \frac{P_0 + P_k}{2} \right] (\tau_{d,k} + \tau_{u,k}) - P_k (t_i - \tau_{d,k})$$

$$= (P_0 - P_k) t_i - \left[ \frac{P_0 - P_k}{2} \right] \tau_{d,k} - \left[ \frac{P_0 + P_k}{2} \right] \tau_{u,k}$$

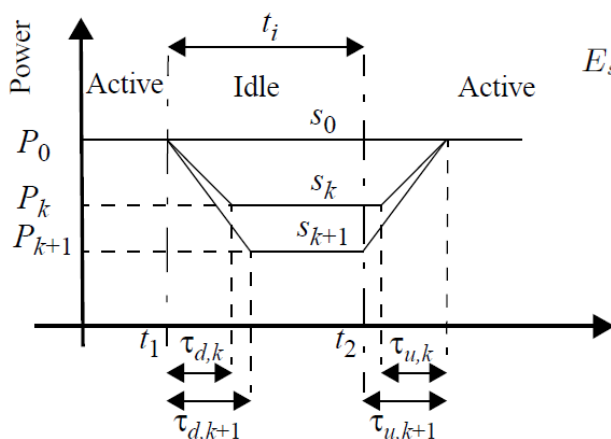


Figure 11: State transition latency and power.

Nett energy saving if  $t_i > T_{th,k}$

Transition is only justified when

$$E_{s,k} > 0$$

Transition time threshold

$$T_{th,k} = \frac{1}{2} \left[ \tau_{d,k} + \left( \frac{P_0 + P_k}{P_0 - P_k} \right) \tau_{u,k} \right]$$

# State Transitions

- Implications
  - the longer the delay overhead of the transition  $s_0 \rightarrow s_k$ , the longer the transition time threshold
  - the greater the difference between  $P_0$  and  $P_k$ , the shorter the threshold

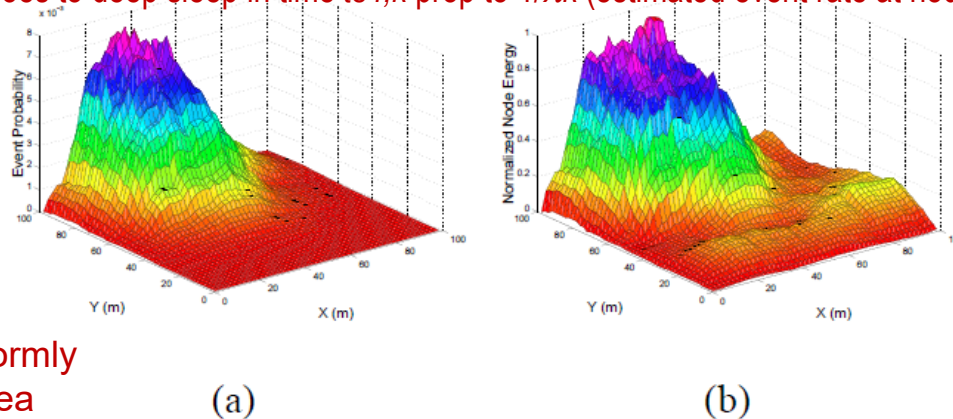
**Table 2: Sleep state power, latency and thresholds.**

State	$P_k$ (mW)	$\tau_k$ (ms)	$T_{th,k}$ (ms)
Active	1040	-	-
Ready	400	5	8
Monitor	270	15	20
Look	200	20	25
Sleep	10	50	50

Note: may miss events in deep sleep

## State Transitions – Energy Consumption

- Performance of **adaptive** probabilistic sleep state transition scheme in event processing task
  - Adapts to event arrival statistics
  - Node  $k$  goes to deep sleep in time  $ts_{4,k}$  prop to  $1/\lambda_k$  (estimated event rate at node  $k$ )



1,000 nodes  
Distributed uniformly  
100mX100m area

**Figure 12: (a) Spatial distribution of events (b) Spatial energy consumption of nodes.**

High event probability  $\rightarrow$  High energy consumption

# Summary

- We have not discussed energy consumption arising from physical layer communications operations such as coding and modulation
  - refer to [Shih01] for details
- We will consider energy consumption at MAC, routing and transport layers in subsequent lectures

# References

- [Heinzelman00] W. Heinzelman, A. Chandrakasan, and H. Balakrishnan. Energy-Efficient Communication Protocol for Wireless Microsensor Networks. In *The 33rd Hawaiian International Conference on Systems Sciences (HICSS)*, Maui, HA, January 2000.
- [Shih01] Eugene Shih, Seong-Hwan Cho, Nathan Ickes, Rex Min, Amit Sinha, Alice Wang, and Anantha Chandrakasan. “Physical Layer Driven Protocol and Algorithm Design for Energy-Efficient Wireless Sensor Networks”, *Proceedings of the Seventh Annual ACM Conference on Mobile Computing and Networking*, Rome, Italy, July 2001.