

```

#include <OneWire.h>

#include <DallasTemperature.h>

#include "thingProperties.h"

// Data wire is plugged into digital pin 2 on the Arduino

#define ONE_WIRE_BUS 8

// Setup a oneWire instance to communicate with any OneWire device

OneWire oneWire(ONE_WIRE_BUS);

// Pass oneWire reference to DallasTemperature library

DallasTemperature sensors(&oneWire);

#define SensorPin A0 //pH meter Analog output to Arduino Analog Input 0

#define Offset 0.00 //deviation compensate

#define LED 13

#define samplingInterval 20

#define printInterval 800

#define ArrayLenth 40 //times of collection

int pHArray[ArrayLenth]; //Store the average value of the sensor feedback

int pHArrayIndex = 0;

void setup(void)

{

    sensors.begin(); // Start up the library

    pinMode(LED, OUTPUT);

    Serial.begin(9600);

    Serial.println("pH meter experiment!"); //Test the serial monitor

```

```

// Defined in thingProperties.h

initProperties();


// Connect to Arduino IoT Cloud

ArduinoCloud.begin(ArduinoIoTPreferredConnection);

setDebugMessageLevel(2);

ArduinoCloud.printDebugInfo();
}


void loop(void)
{

    ArduinoCloud.update();

    // Send the command to get temperatures

    sensors.requestTemperatures();


    //print the temperature in Celsius

    Serial.print("Temperature: ");

    Serial.print(sensors.getTempCByIndex(0));

    Serial.print((char)176);//shows degrees character

    Serial.print("C | ");

    temp = sensors.getTempCByIndex(0);

    //pH

    static unsigned long samplingTime = millis();

    static unsigned long printTime = millis();

    static float pHValue, voltage;

    if (millis() - samplingTime > samplingInterval) {

```

```

    pHArray[pHArrayIndex++] = analogRead(SensorPin);

    if (pHArrayIndex == ArrayLenth) pHArrayIndex = 0;

    voltage = avergearray(pHArray, ArrayLenth) * 5.0 / 1024;

    pHValue = 3.5 * voltage + Offset;

    samplingTime = millis();

}

if (millis() - printTime > printInterval) //Every 800 milliseconds, print a numerical, convert
the state of the LED indicator
{
    Serial.print("Voltage:");

    Serial.print(voltage, 2);

    Serial.print("  pH value: ");

    Serial.println(pHValue, 2);

    digitalWrite(LED, digitalRead(LED) ^ 1);

    printTime = millis();
}

pH= pHValue;
}

double avergearray(int* arr, int number) {

    int i;

    int max, min;

    double avg;

    long amount = 0;

    if (number <= 0) {

        Serial.println("Error number for the array to avraging!/n");

        return 0;

    }

    if (number < 5) { //less than 5, calculated directly statistics

```

```

for (i = 0; i < number; i++) {

    amount += arr[i];

}

avg = amount / number;

return avg;

} else {

    if (arr[0] < arr[1]) {

        min = arr[0];

        max = arr[1];

    } else {

        min = arr[1];

        max = arr[0];

    }

    for (i = 2; i < number; i++) {

        if (arr[i] < min) {

            amount += min; //arr<min

            min = arr[i];

        } else {

            if (arr[i] > max) {

                amount += max; //arr>max

                max = arr[i];

            } else {

                amount += arr[i]; //min<=arr<=max

            }

        } //if

    } //for

    avg = (double)amount / (number - 2);

```

```
} //if

return avg;

}

/*

Since PH is READ_WRITE variable, onPHChange() is

executed every time a new value is received from IoT Cloud.

*/

void onPHChange() {

    // Add your code here to act upon PH change

}

/*

Since Temp is READ_WRITE variable, onTempChange() is

executed every time a new value is received from IoT Cloud.

*/

void onTempChange() {

    // Add your code here to act upon Temp change

}
```