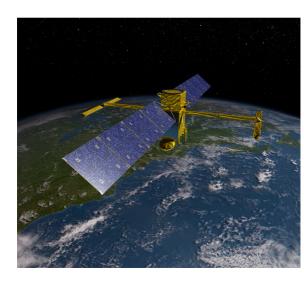
"Wave-Turbulence Interactions in the Oceans"

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(V) Channel modes and Kelvin waves





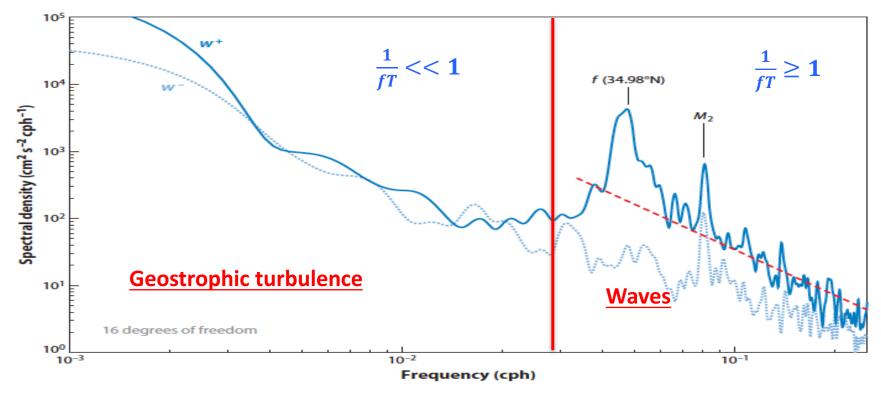


Figure 1

Rotary velocity spectrum at 261-m depth from current-meter data from the WHOI699 mooring gathered during the WESTPAC1 experiment (mooring at 6,149-m depth.) The solid blue line (w^+) is clockwise motion, and the dashed blue line (w^-) is counterclockwise motion; the differences between these emphasize the downward energy propagation that often dominates the near-inertial band. The dashed red line is the line $E_0N\omega^{-p}$ with N=2.0 cycles per hour (cph), $E_0=0.096$ cm² s⁻² cph⁻², and p=2.25, which is quantitatively similar to levels in the Cartesian spectra presented by Fu (1981) for station 5 of the Polygon Mid-Ocean Experiment (POLYMODE) II array.

A frequency spectrum displays different properties between fast and slow motions

SHALLOW WATER MODEL

$$\frac{\partial u}{\partial t} - fv = -g \frac{\partial \eta}{\partial x}$$
$$\frac{\partial v}{\partial t} + fu = -g \frac{\partial \eta}{\partial y}$$
$$\frac{\partial \eta}{\partial t} + H \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) = 0$$

Wave equation:
$$\frac{\partial}{\partial t} \left[\frac{\partial^2 \eta}{\partial t^2} + + f^2 \eta - c_o^2 \Delta \eta \right] = 0 \text{ with } c_o^2 = gH$$

Using:

$$\begin{pmatrix} \eta \\ u \\ v \end{pmatrix} = \Re \begin{pmatrix} A \\ U \\ V \end{pmatrix} e^{i(k_x x + k_y y - \omega t)}$$

leads to:

$$\omega^2 = f^2 + c_o^2 [k_x^2 + k_y^2]$$

with $c_0^2 = gH$ and $R = \sqrt{gH}/f$ R is a Rossby radius

Two limits for the Poincaré waves:

Short wave limit:

$$(k_x^2 + k_y^2) \gg f^2/gH=1/R^2$$
: gravity waves solutions: $\omega \sim \pm \sqrt{gH(k_x^2 + k_y^2)}$

=> Length scale of the wave disturbance is not large enough to feel the Earth rotation

Long wave limit:

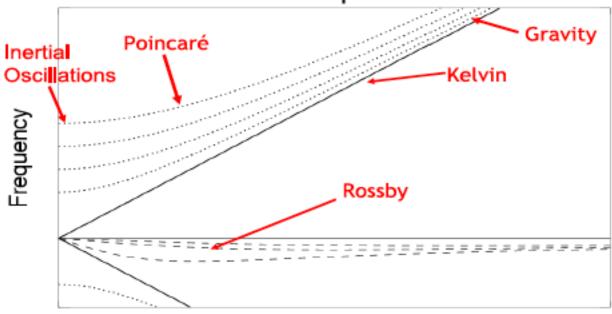
$$(k_x^2 + k_y^2) \ll f^2/gH = 1/R^2$$
: inertial oscillation solutions: $\omega \sim \pm f$

⇒ Length scale of the wave disturbance is large such that rotation effects dominate gravity effects.

The criterium is R/L.

The **Rossby radius of deformation** is the horizontal length scale over which the height field adjusts during approach to the geostrophic equilibrium (or the GW frequency approaches f).

Shallow water dispersion relations

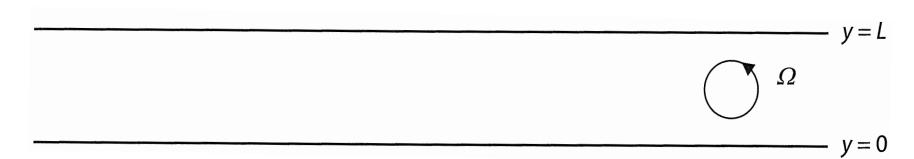


Wavenumber k

Figure 2: Dispersion relations for a rotating shallow water system. The Poincaré wave solutions are produced in the presence of a height perturbation in a rotating shallow water system. The Kelvin waves require the presence of a boundary (or the equator) and the Rossby waves require the presence of a gradient in potential vorticity.

CHANNEL MODES (J. Pedlosky 2003)

Let us consider a channel of width L:



The equation of motion for the wave is (from SW equations):

$$\nabla^2 \eta - \frac{1}{c_o^2} \frac{\partial^2 \eta}{\partial t^2} - \frac{f^2}{c_o^2} \eta = 0, \quad \text{with } c_o = \sqrt{gH}$$

With the y-component of the velocity, v, given by:

$$\frac{\partial^2 v}{\partial t^2} + f^2 v = -g \frac{\partial^2 \eta}{\partial t \partial y} + g f \frac{\partial \eta}{\partial x}$$

v must vanish at the boundaries (y=0,L)

CHANNEL MODES

We can look for solutions of the form: $\eta = \bar{\eta}(y)e^{i(kx-\omega t)}$ $\bar{\eta}$ (y) satisfies the ordinary differential equation:

$$\frac{\mathrm{d}^2 \overline{\eta}}{\mathrm{d}y^2} + \left\{ \frac{\omega^2 - f^2}{c_0^2} - k^2 \right\} \overline{\eta} = 0$$

With the boundary conditions (at y=0,L):

$$\frac{\mathrm{d}\overline{\eta}}{\mathrm{d}\nu} + k \frac{f}{\omega} \overline{\eta} = 0$$

Let us define ℓ such that:

$$\ell^2 = \frac{\omega^2 - f^2}{c_0^2} - k^2$$

Solution becomes:

$$\overline{\eta}(y) = A\sin\ell y + B\cos\ell y$$

With the boundary conditions: $A\ell + B\frac{kf}{\omega} = 0$ at y=0,

and
$$A\ell\cos\ell L - B\ell\sin\ell L + \frac{kf}{\omega}\{A\sin\ell L + B\cos\ell L\} = 0$$
 at y=L

Combining these two BCs leads to (used later to get I):

$$\sin \ell L \left[\omega^2 \ell^2 + k^2 f^2\right] = \sin \ell L \left[\omega^2 \left(\frac{\omega^2 - f^2}{c_0^2}\right) - k^2 \omega^2 + k^2 f^2\right]$$
$$= \sin \ell L \left[\frac{\omega^2}{c_0^2} - k^2\right] \left(\omega^2 - f^2\right) = 0$$

CHANNEL MODES

$$\sin \ell L \left[\frac{\omega^2}{c_0^2} - k^2 \right] \left(\omega^2 - f^2 \right) = 0$$

Solutions for ω (for any ℓ):

- 1. $\omega = \pm f$: limit for long wavelengths: why this solution for any ℓ ?
- 2. $\omega = \pm kc_0$: limit for short gravity waves (y-independent): why this solution for any ℓ ?
- 3. $\sin \ell L = 0$: solutions are $\ell L = n\pi$, n=1,2,3,...

Let us consider the third solution ...

Using:
$$\ell^2 = \frac{\omega^2 - f^2}{c_0^2} - k^2$$

Leads to the dispersion relation:
$$\omega_n^2 = f^2 + c_0^2 \left[k^2 + n^2 \pi^2 / L^2 \right]$$

This is exactly the dispersion relation for Poincaré waves except that the wavenumber ℓ is quantized in multiple of $\frac{\pi}{L}$: $\ell L = n\pi$, n = 1,2,3...

Using $\overline{\eta}(y) = A \sin \ell y + B \cos \ell y$ and the relation between A and B (from the BCs), the solution for η is :

$$\eta = \eta_0 \left[\cos(n\pi y/L) - \frac{kfL}{\omega n\pi} \sin(n\pi y/L) \right] \cos(kx - \omega t)$$

and solutions for u and v are:

$$u = \frac{\eta_0}{D} \left[\frac{c_0^2}{(\omega/k)} \cos(n\pi y/L) - \frac{fL}{n\pi} \sin(n\pi y/L) \right] \cos(kx - \omega t)$$

$$v = \frac{-\eta_0}{D} \frac{\left[f^2 + c_0^2 n^2 \pi^2 / L^2 \right]}{\omega n\pi / L} \sin(n\pi y/L) \sin(kx - \omega t)$$

CHANNEL MODES

$$\sin \ell L \left[\frac{\omega^2}{c_0^2} - k^2 \right] \left(\omega^2 - f^2 \right) = 0$$

Solutions for ω (for any ℓ):

- 1. $\omega = \pm f$: limit for long wavelengths: why this solution for any ℓ ?
- 2. $\omega = \pm kc_0$: limit for short gravity waves (y-independent): why this solution for $\ell \neq 0$?
- 3. $\sin \ell L = 0$: solutions are $\ell L = n\pi$, n=1,2,3,...

Let us consider now the second solution ...

THE KELVIN MODE

Second solution is: $\omega = \pm kc_0$

This is the dispersion relation for y-independent, nonrotating, short surface waves. But our fluid is rotating and therefore no solution independent of y is a possible solution (see the BCs for η at y=0,L).

Using again:
$$\ell^2 = \frac{\omega^2 - f^2}{c_0^2} - k^2$$

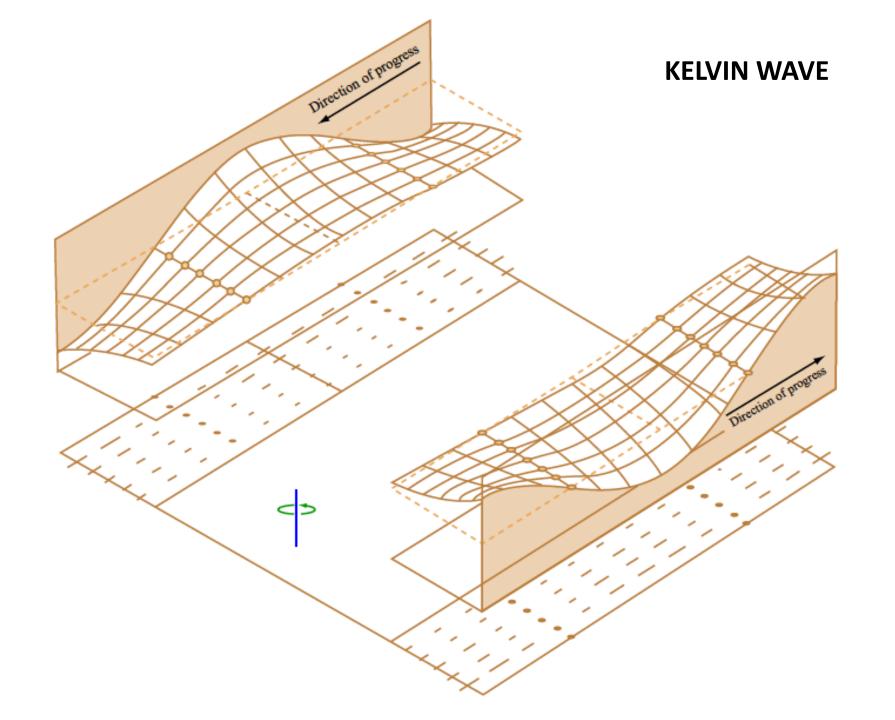
we have for this case since $\omega = \pm kc_0$ we have: $\ell = \pm if/c_0$

So the cross-channel wavenumber is purely imaginary. Let us look for the solution corresponding to the positive imaginary root.

Using again: $\overline{\eta}(y) = A \sin \ell y + B \cos \ell y$, and the relation between A and B from the BCs (and writing the sine and cosine in their exponential form, we get:

$$\overline{\eta}(y) = \eta_0 \left\{ e^{-fy/c_0} \left[1 + \omega/kc_0 \right] - e^{fy/c_0} \left[1 - \omega/kc_0 \right] \right\}$$

This solution consists of two parts ...



THE KELVIN MODE

Let us consider the wave propagating to the right:

$$\eta = \eta_0 e^{-fy/c_0} \cos(kx - \omega t)$$

This solution would also be valid if only a single wall were present (channel semi-infinite in the +y-direction). Let us calculate v and u. Using the previous relations, we get for v: $v(f^2 - \alpha^2) = \sigma f n - \sigma n$

$$v(f^2 - \omega^2) = gf\eta_x - g\eta_{yt}$$

$$= -gfk\sin(kx - kc_0t) + g\frac{f}{c_0}kc_0\sin(kx - kc_0t)$$

$$= 0!$$

So the cross channel velocity is identically zero for all y-values.

$$u(f^{2} - \omega^{2}) = -gf\eta_{y} - g\eta_{xt}$$

$$= g\frac{f^{2}}{c_{0}}\eta - gk^{2}c_{0}\eta$$

$$= \frac{g}{c_{0}}(f^{2} - k^{2}c_{0}^{2})\eta = \frac{g}{c_{0}}(f^{2} - \omega^{2})\eta$$

THIS LEADS TO:

$$u(f^{2} - \omega^{2}) = -gf\eta_{y} - g\eta_{xt}$$

$$= g\frac{f^{2}}{c_{0}}\eta - gk^{2}c_{0}\eta$$

$$= \frac{g}{c_{0}}(f^{2} - k^{2}c_{0}^{2})\eta = \frac{g}{c_{0}}(f^{2} - \omega^{2})\eta$$

$$u = -\frac{g}{f} \frac{\partial \eta}{\partial y}$$

GEOSTROPHIC BALANCE IN THE Y-DIRECTION!

THE RESULTING EQUATIONS ARE:

$$fu = -g\eta_y$$

$$u_t = -g\eta_x$$

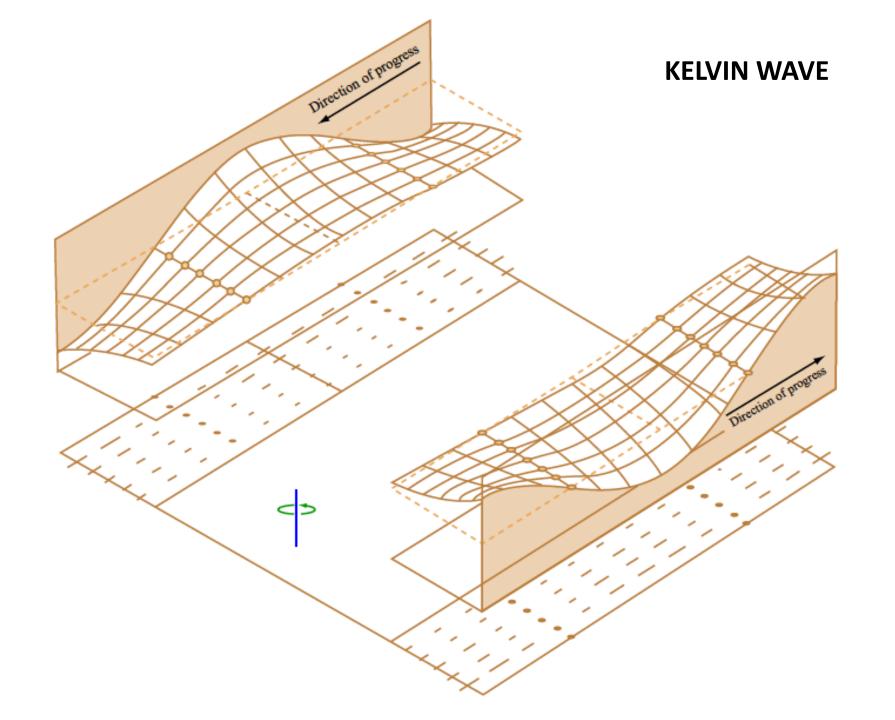
$$\eta_t = -Hu_x$$

$$\eta_{tt} = c_0^2 \eta_{xx}$$

$$\eta_{yy} - \frac{f^2}{c_o^2} \eta = 0$$

- GRAVITY WAVE EQUATION (Y-INDEPENDENT) AS IN THE NON-ROTATING CASE
- GEOTROPHIC BALANCE IN THE Y-DIRECTION

THIS GW MODE MAINTAINS ITS CHARACTER OF HAVING V=0. IT DOES SO BY INTRODUCING A SLOPING FREE SURFACE ELEVATION THAT BALANCES THE CORIOLIS ACCELERATION OF U.



SSH FROM M₂ BAROTROPIC TIDES (Richman et al. 2012)

SSH FROM M₂ IS BASIN-SCALE! IT BEHAVES AS KELVIN WAVES (6000 KM) PROPAGATING CYCLONICALLY AROUND A BASIN WITH A PERIOD OF ~12 H (see next class).. USING $\eta=\eta_o$. $\sin\alpha$ WITH $\alpha=k_xx+k_yy-\omega t$ THE PHASE. THIS FIGURE SHOWS:

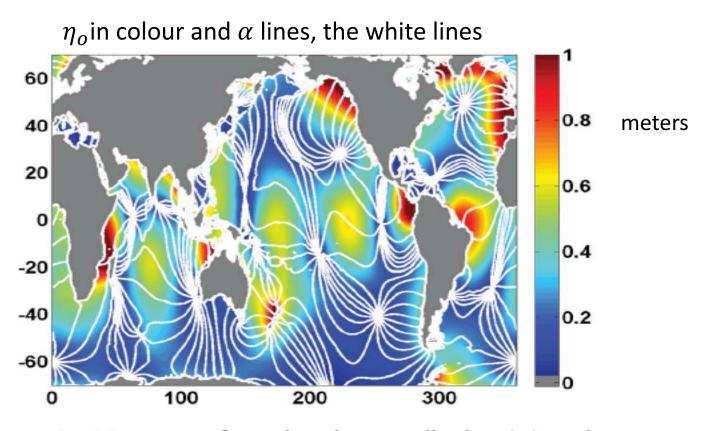


Figure 1. M₂ sea surface elevation amplitudes (m) and phase for (a) HYCOM and (b) TPXO7.2 [Egbert et al., 1994], a highly accurate altimetry-constrained model of the barotropic tides. White lines indicate phase, drawn 20° apart.