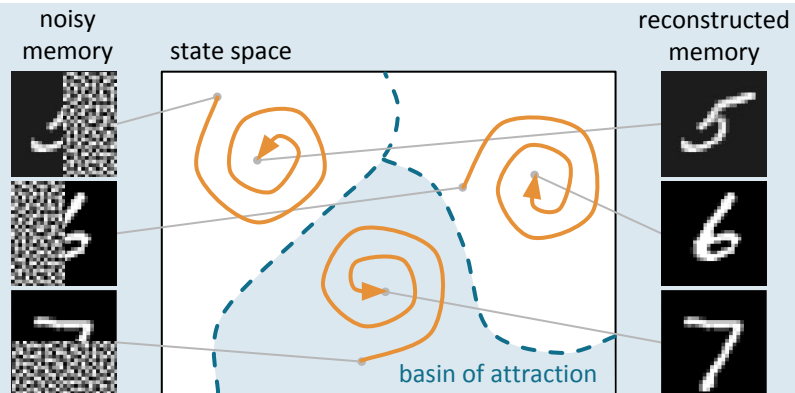


Goal - Modelling auto-associative memory

We model memory with a discrete dynamical system

$$\mathbf{x}^{(k+1)} = f(\mathbf{x}^{(k)}),$$

whose stable equilibria are the memories to store. This way, as the state evolves, it gradually converges to a memory, and thereby reconstructs it.



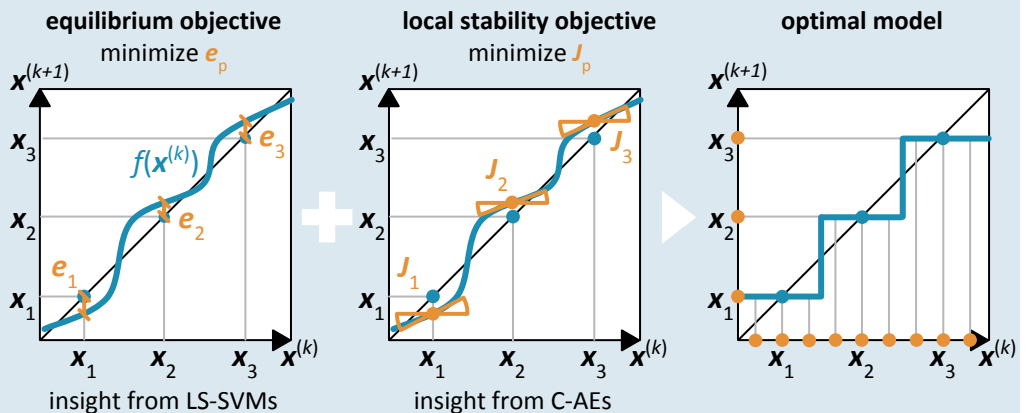
Proposed solution - Combining LS-SVMs¹ and C-AEs² into C-LS-SVMs

¹Least Squares SVMs
²Contractive autoencoders

We describe the dynamical system by the update equation

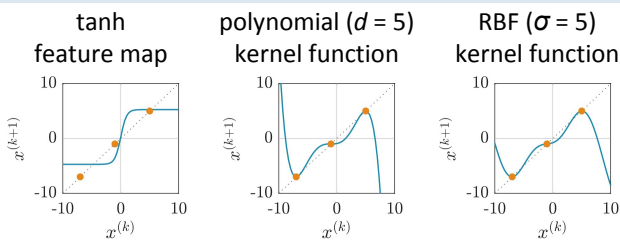
$$\mathbf{x}^{(k+1)} = f(\mathbf{x}^{(k)}) = \mathbf{W}^T \boldsymbol{\varphi}(\mathbf{x}^{(k)}) + \mathbf{b}.$$

The parameters \mathbf{W} and \mathbf{b} result from a convex optimization problem that balances an **equilibrium objective**, and a **local stability objective**.



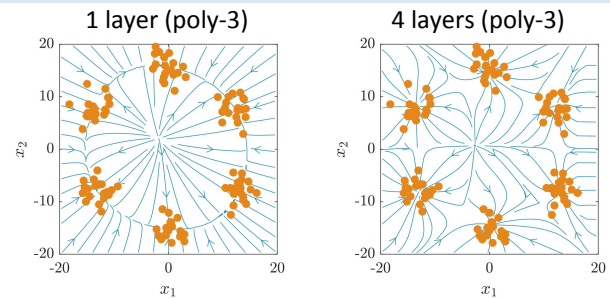
Results

Shallow C-LS-SVMs



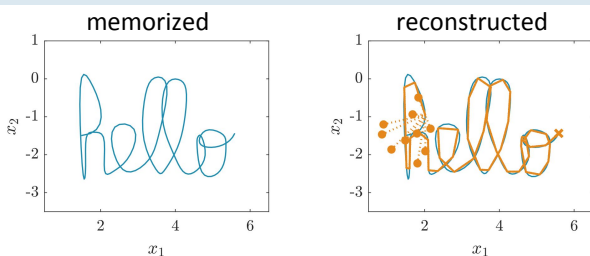
A C-LS-SVM can use a wide range of feature maps $\boldsymbol{\varphi}(\mathbf{x})$, either defined explicitly, such as the tanh feature map, or defined implicitly by a positive definite kernel function.

Deep C-LS-SVMs



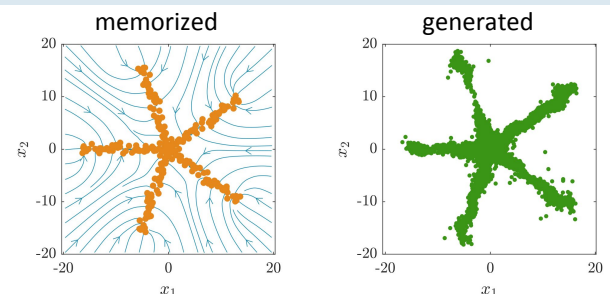
Deep C-LS-SVMs more accurately store the memories (•).

C-LS-SVMs that memorize movements



The C-LS-SVM reconstructs the memorized movement well from noisy initial conditions (•) up to the end (×).

Generative C-LS-SVMs



The generated points precisely populate the data manifold.