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# **Code Assignment 1**

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```
In [51]: # setup functions↔
In [ ]: # define X, Y, Z, N, n_x, m_y↔
```

#### **Gradient Descent**

```
In [53]: # define gradient_decent()↔
Out[53]: gradient_decent (generic function with 1 method)
```

Off course, the choice of the stepsize=2.0 is optimized for this concrete example!

```
In [54]: (residual, rides, avg_price, iter, t, p) = gradient_decent(stepsize=2.0)
     @show (residual, rides, avg_price, iter, t);
     (residual, rides, avg_price, iter, t) = (6.6792805490928935e-6, 30.1967103814 92267, 6144.210478599871, 24, 0.033948589)
```

### **Newton Descent**

```
In [55]: # define newton_decent()+
Out[55]: newton_decent (generic function with 1 method)
In [56]: (residual, rides, avg_price, iter, t, p) = newton_decent(stepsize = .2)
     @show (residual, rides, avg_price, iter, t);
     (residual, rides, avg_price, iter, t) = (1.4383251444418475e-5, 30.1967092773 2457, 6144.147609907126, 51, 66.096929758)
```

### **Coordinate Decent**

```
In [57]: # define coordinate_decent()↔
Out[57]: coordinate_decent (generic function with 1 method)
```

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```
In [47]: (residual, rides, avg_price, iter, t, p) = coordinate_decent()
    @show (residual, rides, avg_price, iter, t);

    (residual, rides, avg_price, iter, t) = (6.6075340955011415e-6, 30.1967096406 16426, 6144.168840475095, 27, 62.665376635)
```

## **Subsidizer Supply**

The coordinate descent method is inefficient, when faced with the subsidized supply function.