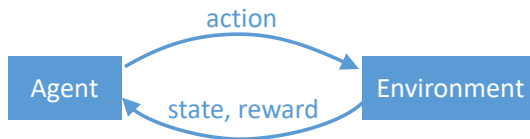
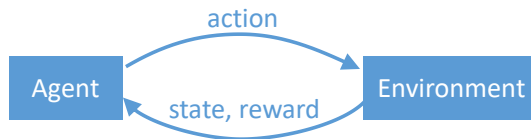


Motivation — Sequential Decision Making



Markov Decision Processes

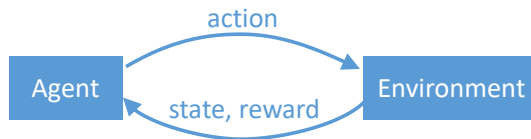
Motivation — Sequential Decision Making



Markov Decision Processes

1. Observe state $s \in S$;

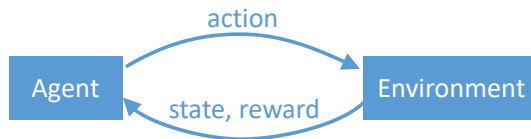
Motivation — Sequential Decision Making



Markov Decision Processes

1. Observe state $s \in S$;
2. Pick a **discrete** action $a \in A$;

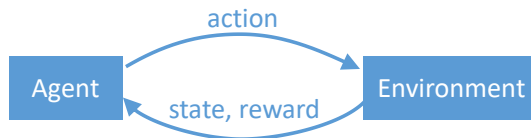
Motivation — Sequential Decision Making



Markov Decision Processes

1. Observe state $s \in S$;
2. Pick a discrete action $a \in A$;
3. Transition to a next state $s' \sim \mathbb{P}(s'|s, a)$;

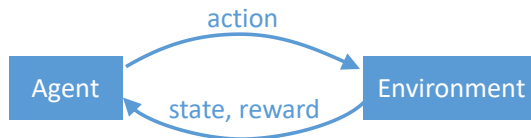
Motivation — Sequential Decision Making



Markov Decision Processes

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Motivation — Sequential Decision Making



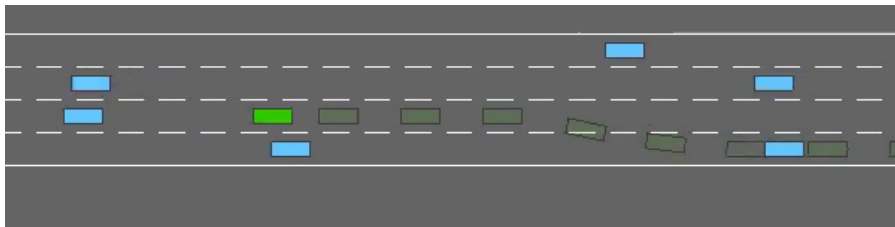
Markov Decision Processes

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Objective: maximise $V = \mathbb{E}[\sum_{t=0}^{\infty} \gamma^t r_t]$

Motivation — Example

The highway-env environment 



We want to handle stochasticity.

Motivation — How to solve MDPs?

Online *Planning*

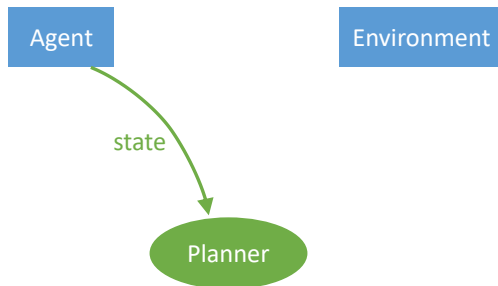
- ▶ we have access to a generative model:
 - ↳ yields samples of $s', r \sim \mathbb{P}(s', r|s, a)$ when queried



Motivation — How to solve MDPs?

Online *Planning*

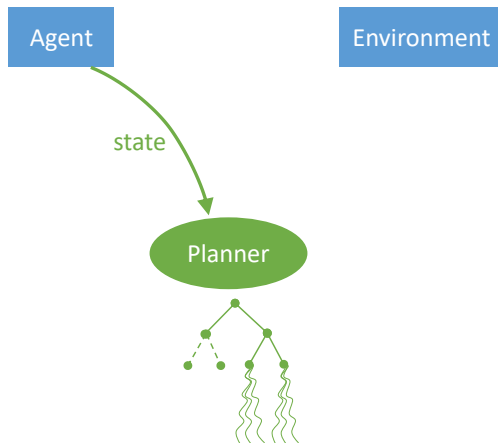
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Motivation — How to solve MDPs?

Online *Planning*

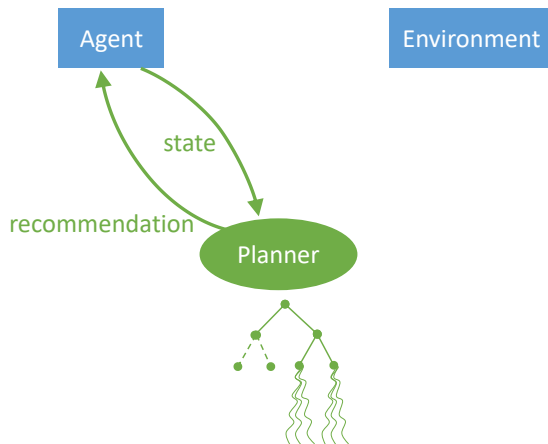
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Motivation — How to solve MDPs?

Online *Planning*

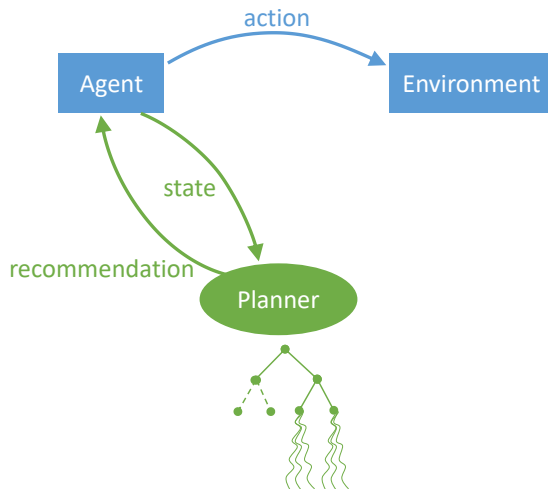
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Motivation — How to solve MDPs?

Online *Planning*

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Motivation — How to solve MDPs?

Online *Planning*

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