

# **Week 7**

**Mathematics and Computational Methods  
for Complex Systems, 2023-2024**

**Dhruva Venkita Raman**

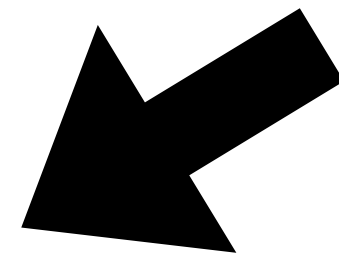
# Outline of today

## Differential quantities

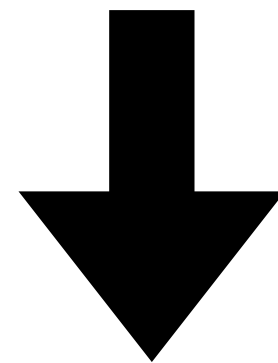
What are they?

Operations and algebra

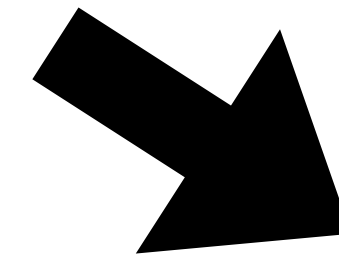
How do we compute them?



**Differential  
equations**

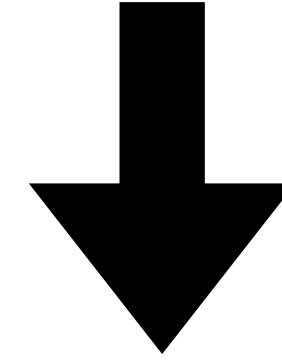


**Optimisation**

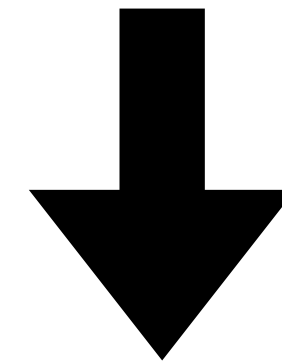


**Machine learning**

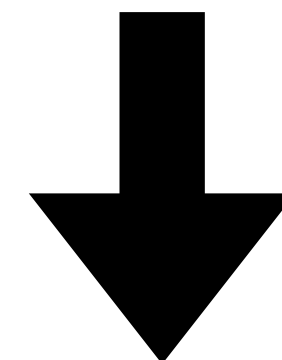
# Course structure



**Dynamical  
systems**



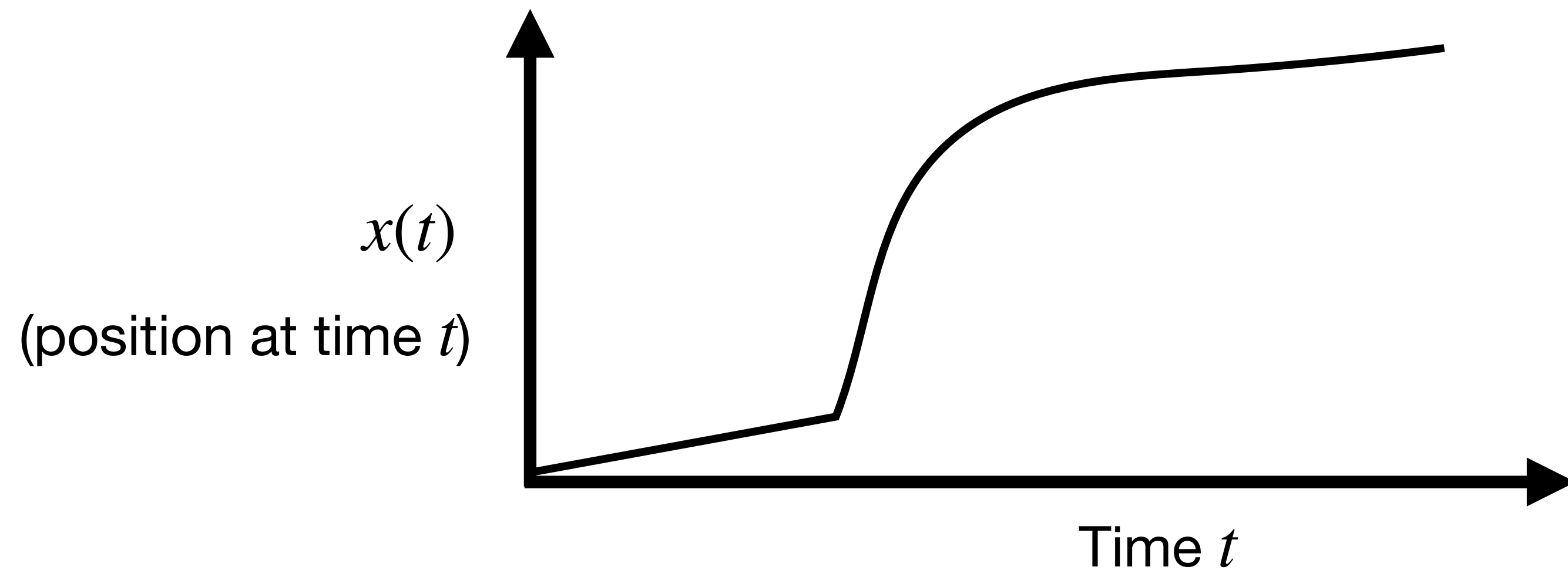
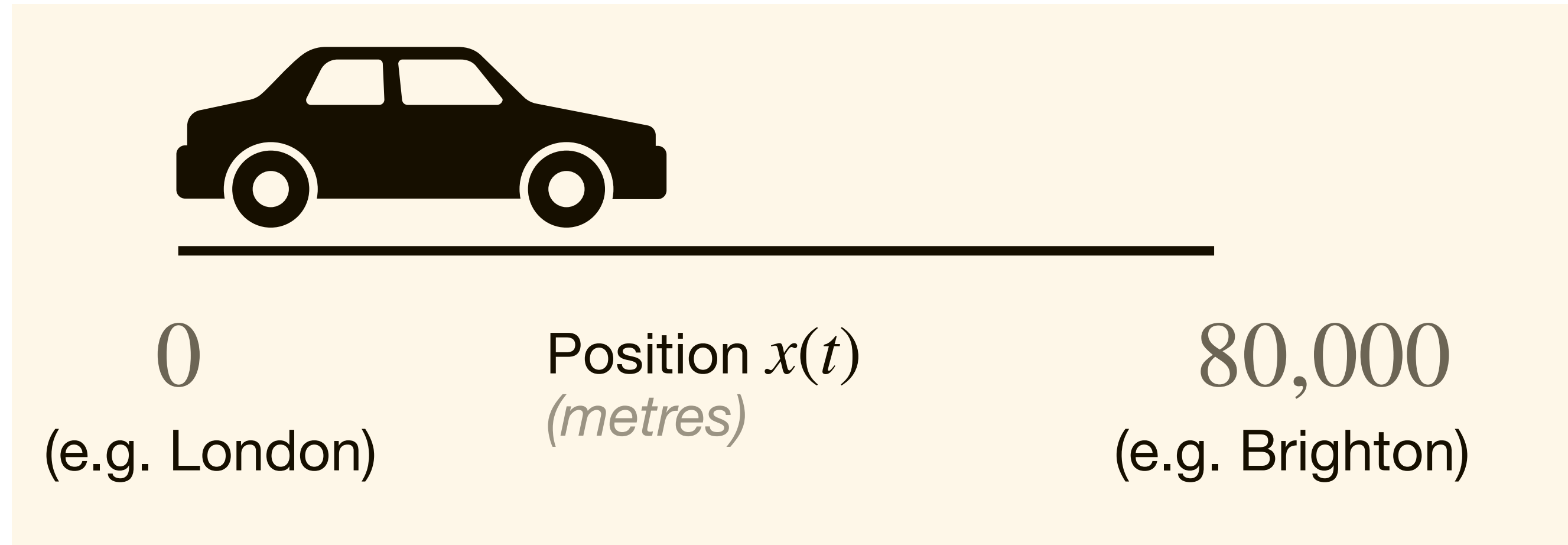
**Optimisation**



**Complexity**

# Mid module feedback

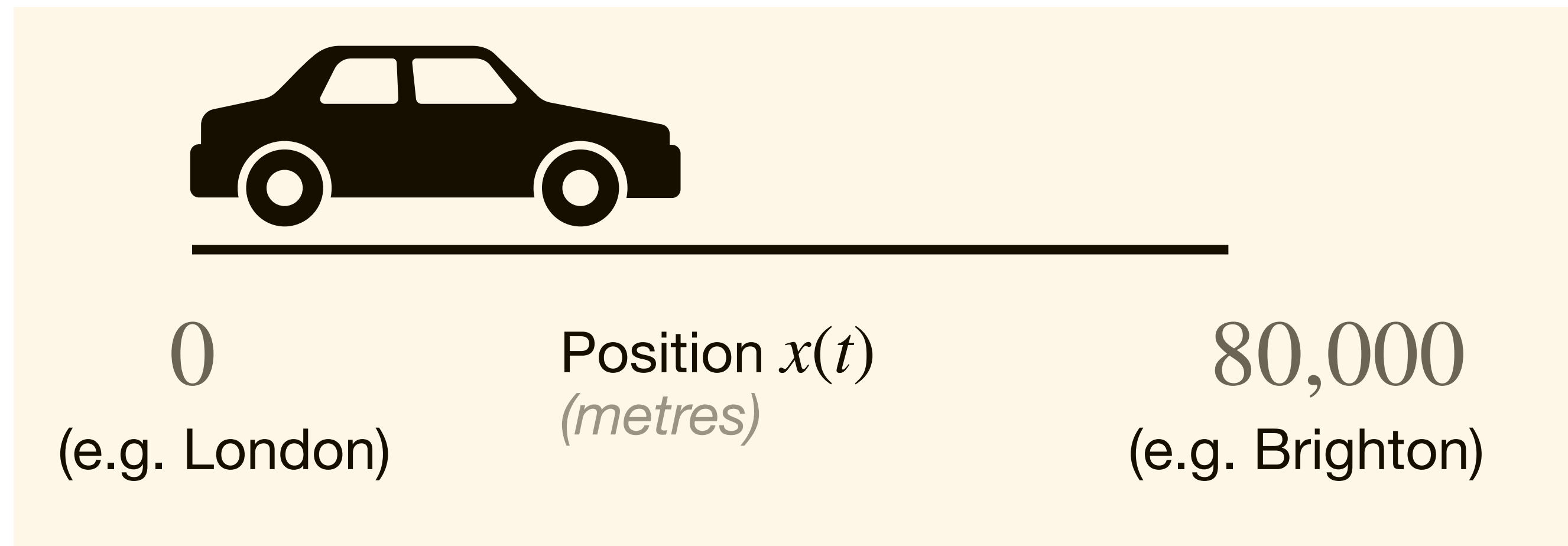
# Position of car as a function of time



# Velocity of car as a function of time

*What does this even mean?*

N.B. Velocity has a direction, so can be negative  
Speed is the magnitude of velocity

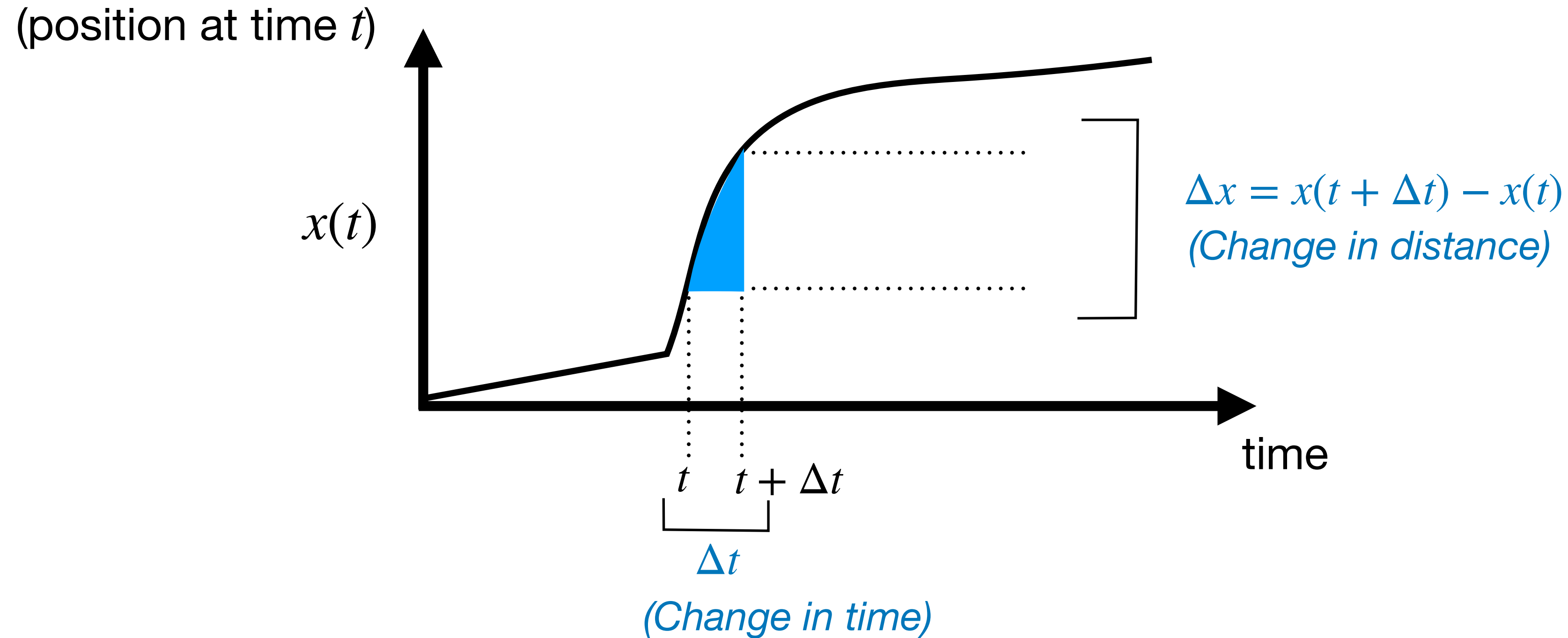


**Differential  
quantity:**

Velocity requires comparison of  
position at **two** points in time!

# Average speed over a time interval

N.B.  $\Delta$  often represents '*change in*'

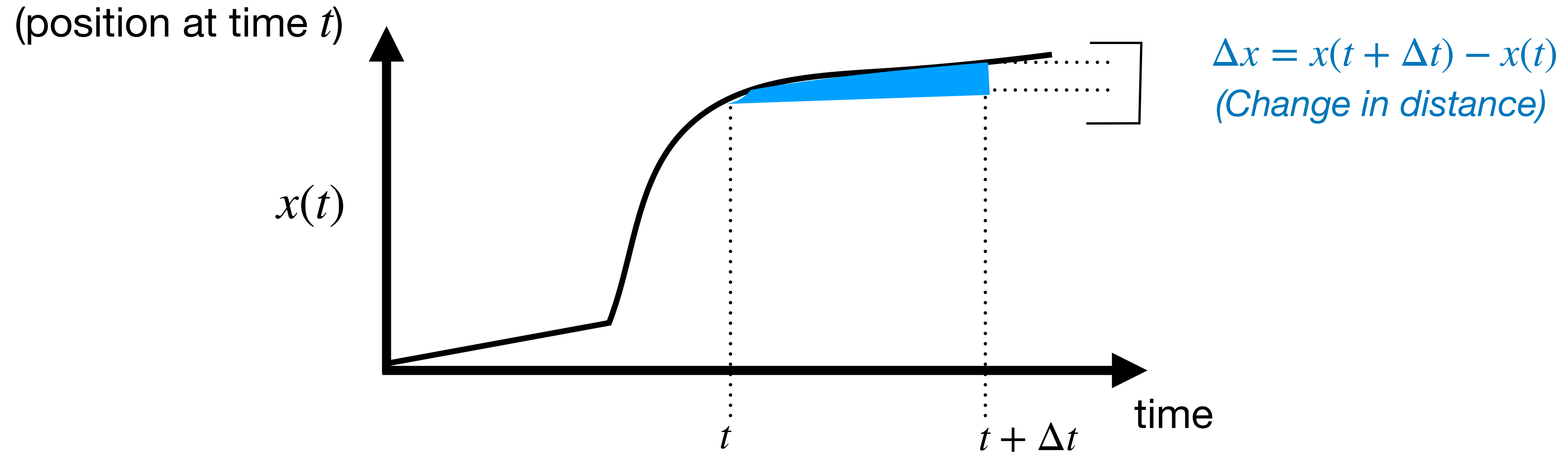


Average velocity between  
times  $t$  and  $t + \Delta t$  :

$$\frac{x(t + \Delta t) - x(t)}{\Delta t}$$

# Average speed over a time interval

N.B.  $\Delta$  often represents 'change in'

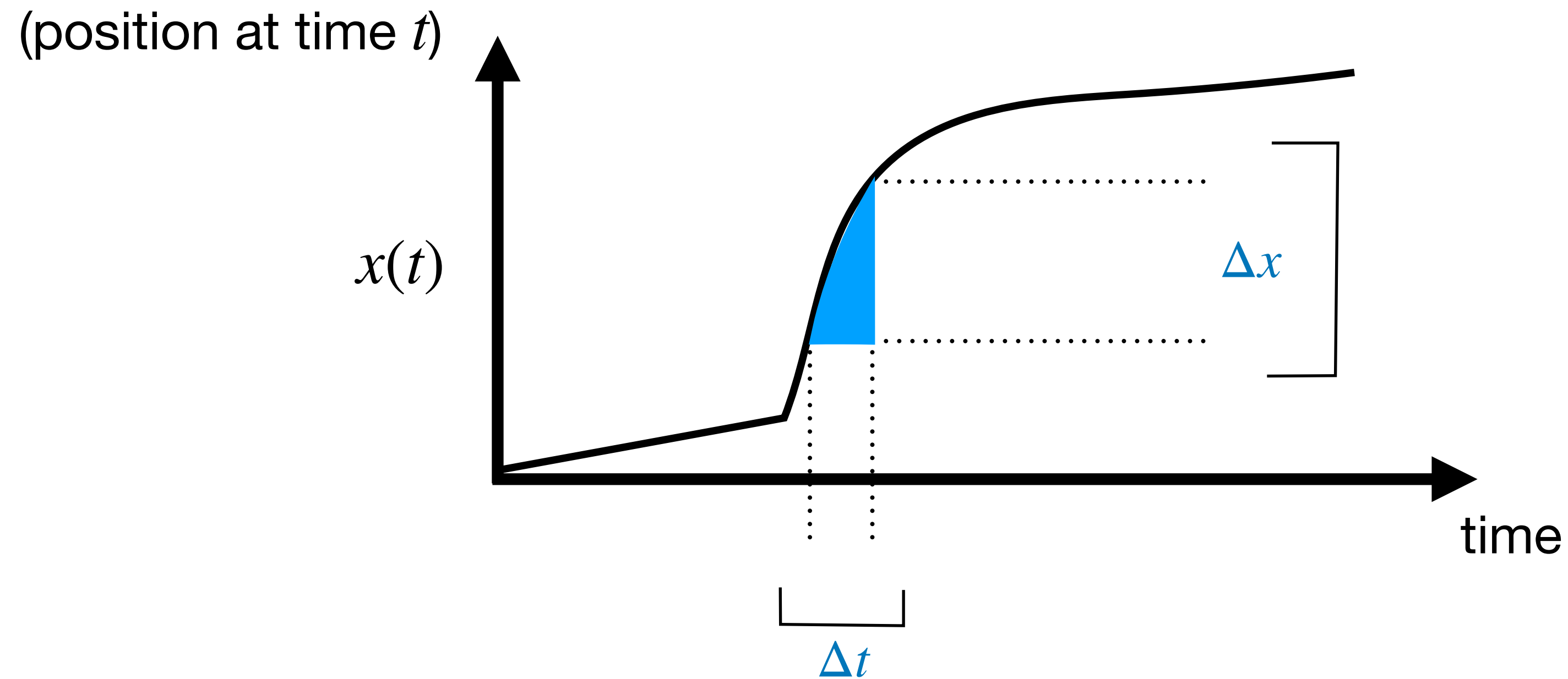


Average velocity between  
times  $t$  and  $t + \Delta t$  :

$$\frac{x(t + \Delta t) - x(t)}{\Delta t}$$



# Velocity at a point in time



Velocity at time  $t$  :

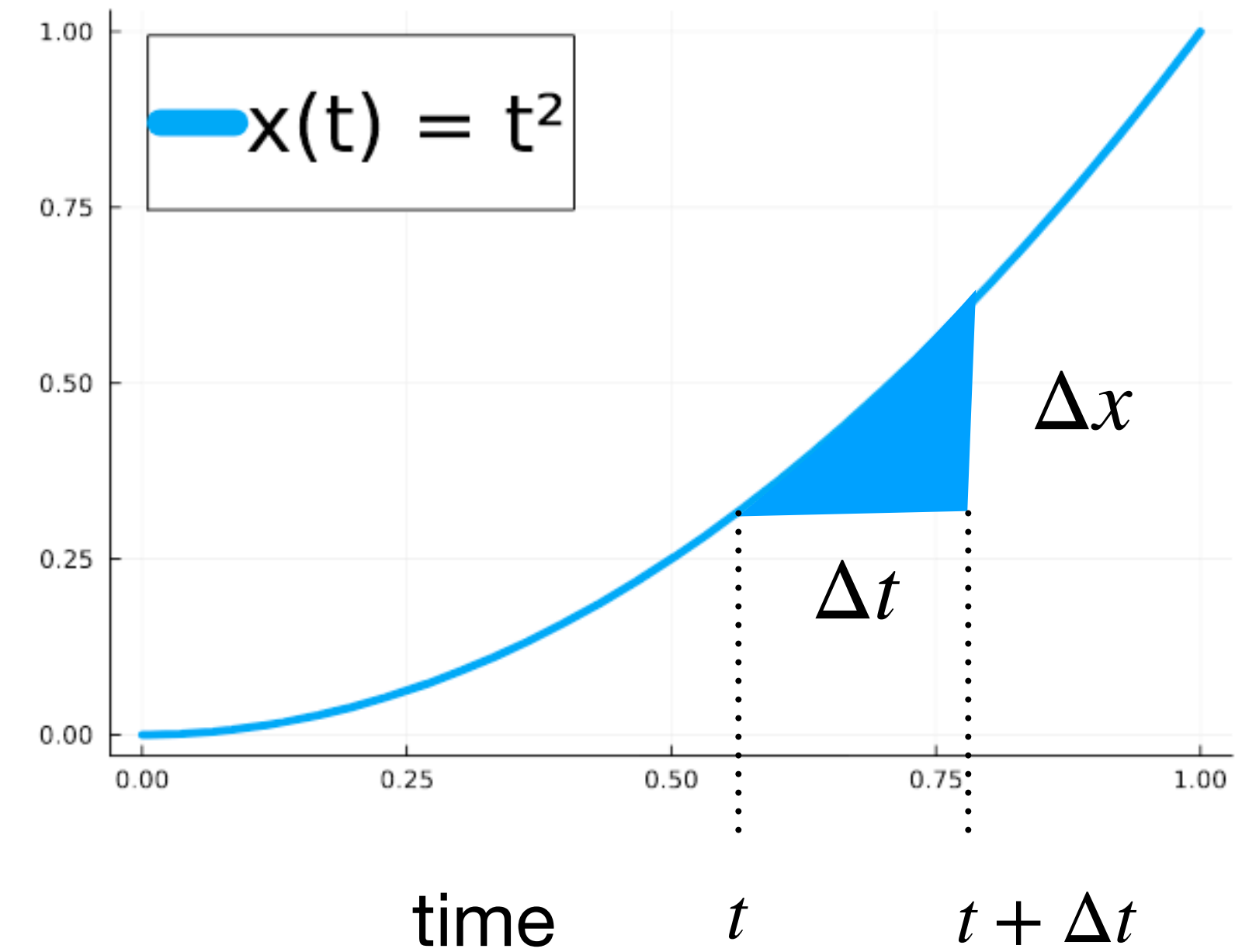
$$\lim_{\Delta t \rightarrow 0} \frac{\Delta x}{\Delta t}$$

$$\left( = \lim_{\Delta t \rightarrow 0} \frac{x(t + \Delta t) - x(t)}{\Delta t} \right)$$

# An example

Suppose  $x(t) = t^2$

$x(t)$



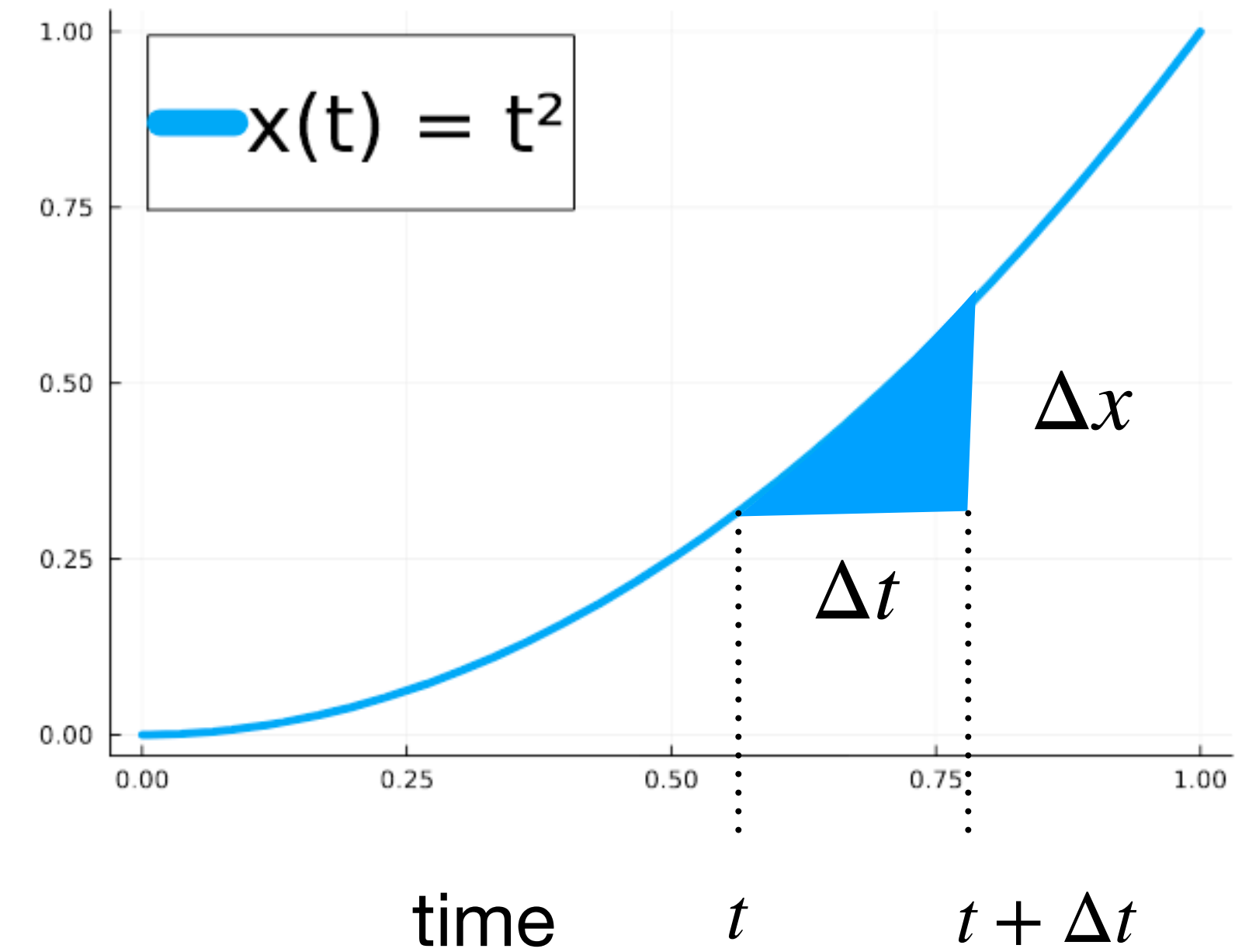
Velocity at time  $t$  :  $\lim_{\Delta t \rightarrow 0} \frac{\Delta x}{\Delta t}$

# An example

Suppose  $x(t) = t^2$

Then 
$$\frac{x(t + \Delta t) - x(t)}{\Delta t} = \frac{(t + \Delta t)^2 - t^2}{\Delta t}$$

$x(t)$



Velocity at time  $t$  : 
$$\lim_{\Delta t \rightarrow 0} \frac{\Delta x}{\Delta t}$$

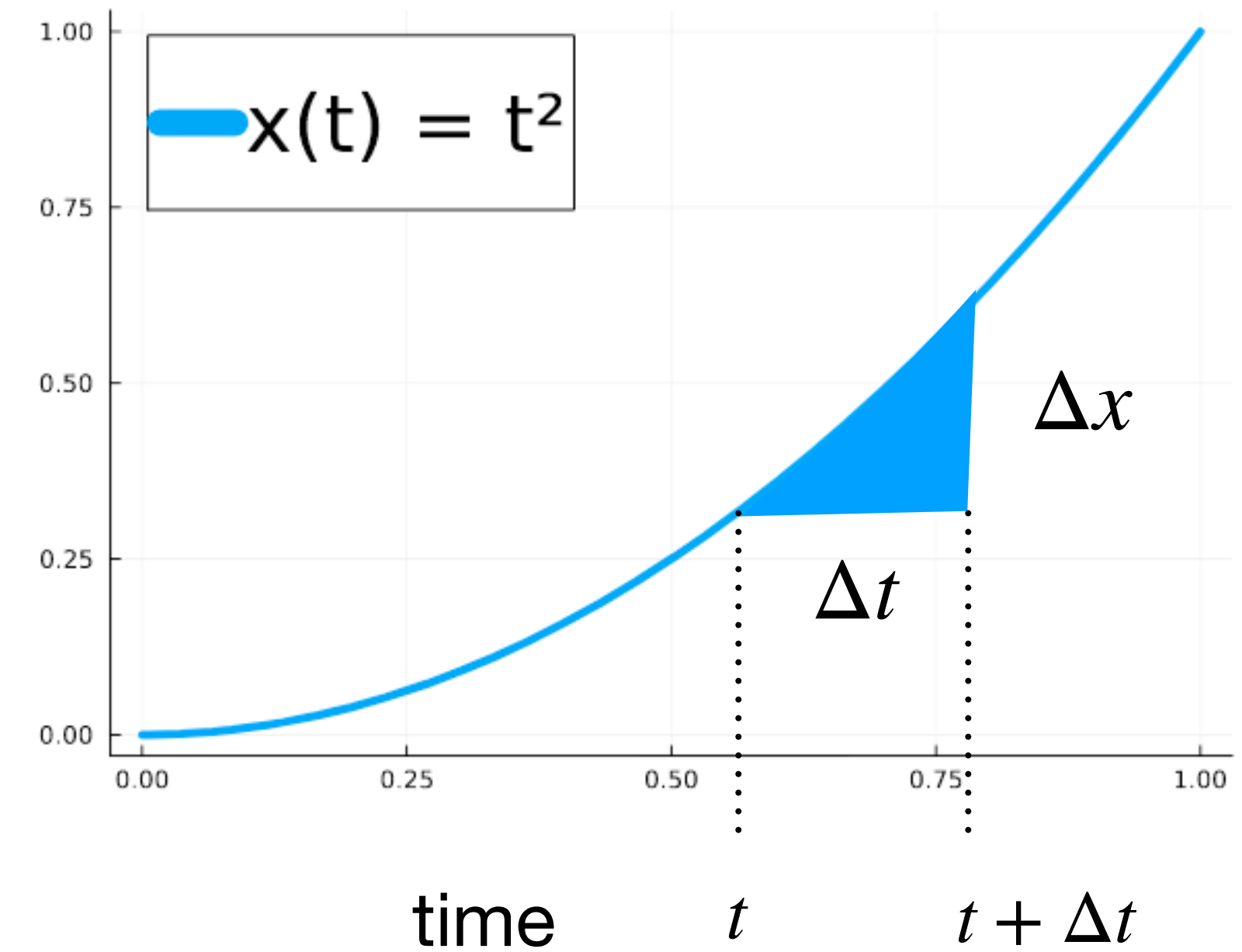
# An example

Suppose  $x(t) = t^2$

Then 
$$\frac{x(t + \Delta t) - x(t)}{\Delta t} = \frac{(t + \Delta t)^2 - t^2}{\Delta t}$$

$$= \frac{t^2 + 2t\Delta t + (\Delta t)^2 - t^2}{\Delta t}$$

$x(t)$



Velocity at time  $t$  : 
$$\lim_{\Delta t \rightarrow 0} \frac{\Delta x}{\Delta t}$$

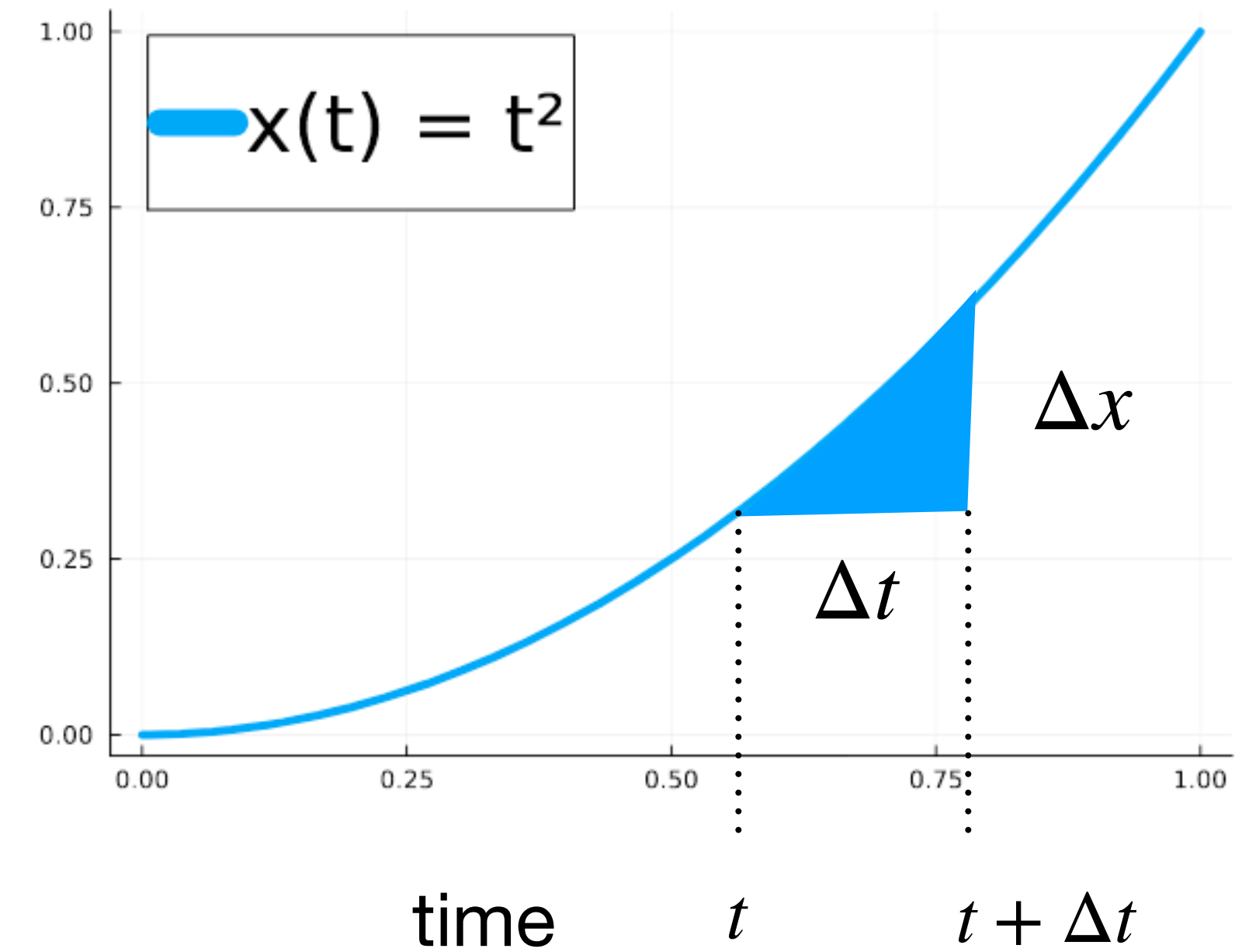
# An example

Suppose  $x(t) = t^2$

Then

$$\frac{x(t + \Delta t) - x(t)}{\Delta t} = \frac{(t + \Delta t)^2 - t^2}{\Delta t}$$
$$= \frac{t^2 + 2t\Delta t + (\Delta t)^2 - t^2}{\Delta t}$$
$$= 2t + \Delta t$$
$$= 2t \quad (\text{As } \Delta t \rightarrow 0)$$

$x(t)$



Velocity at time  $t$  :  $\lim_{\Delta t \rightarrow 0} \frac{\Delta x}{\Delta t}$

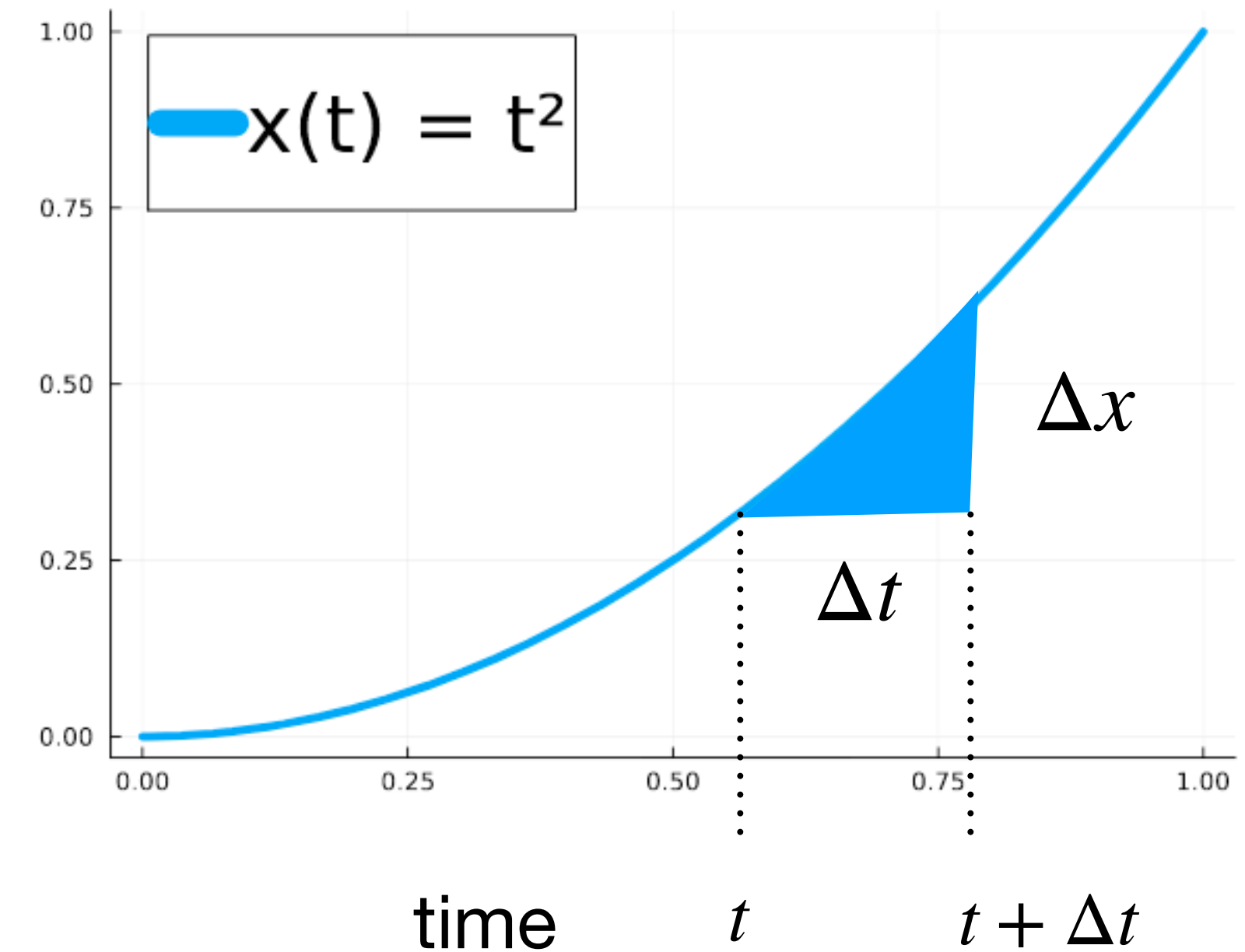
# An example

Suppose  $x(t) = t^2$

Then

$$\frac{x(t + \Delta t) - x(t)}{\Delta t} = \frac{(t + \Delta t)^2 - t^2}{\Delta t}$$
$$= \frac{t^2 + 2t\Delta t + (\Delta t)^2 - t^2}{\Delta t}$$
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$x(t)$

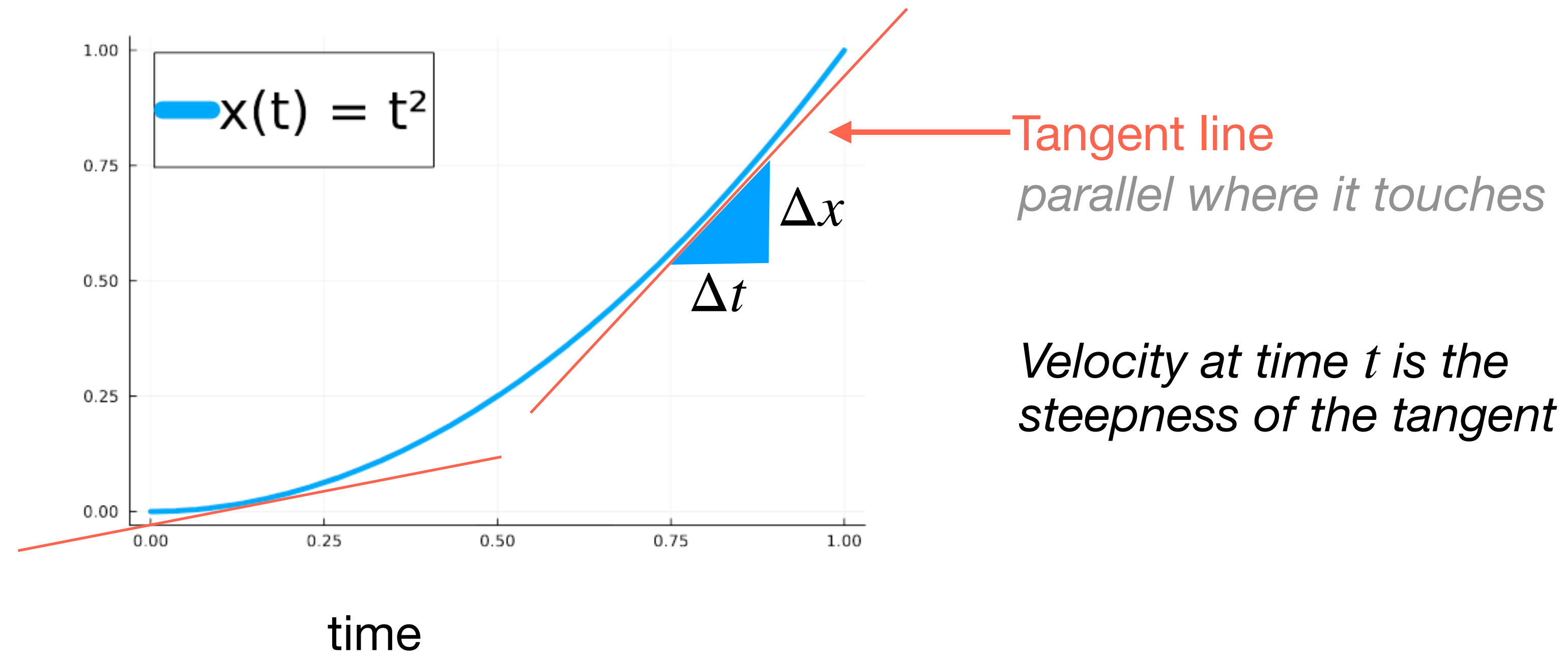


Velocity at time  $t$  :  $\lim_{\Delta t \rightarrow 0} \frac{\Delta x}{\Delta t}$

## Exercise

Did we assume  $\Delta t$  is positive?

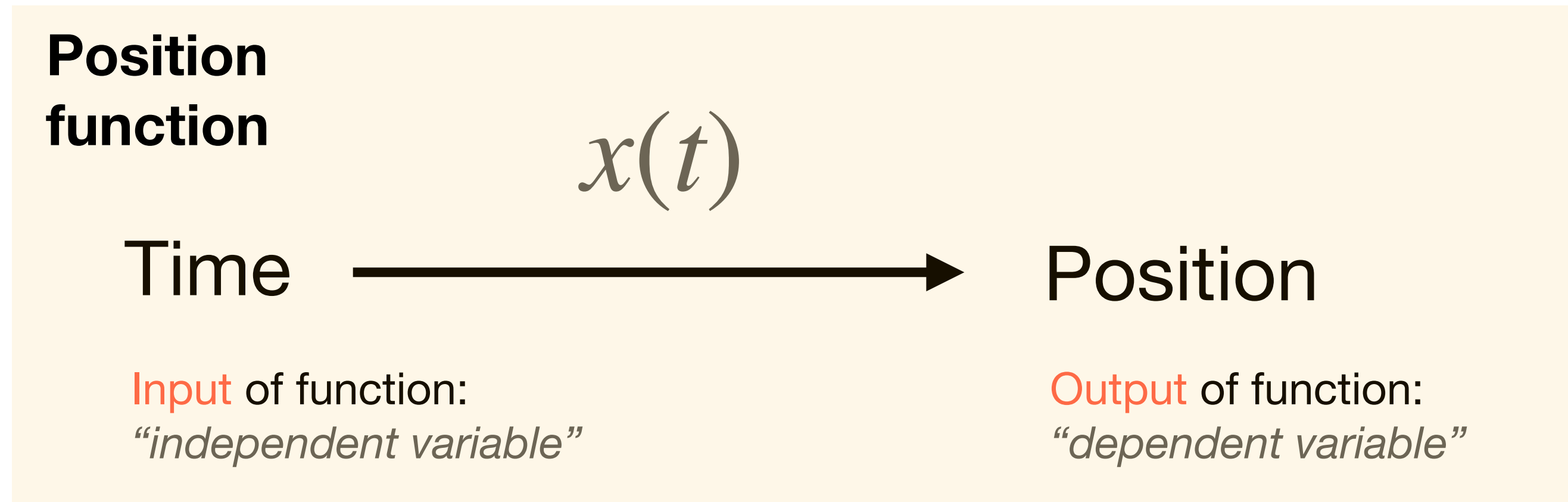
# Tangents



$$\text{Velocity at time } t : \lim_{\Delta t \rightarrow 0} \frac{\Delta x}{\Delta t}$$

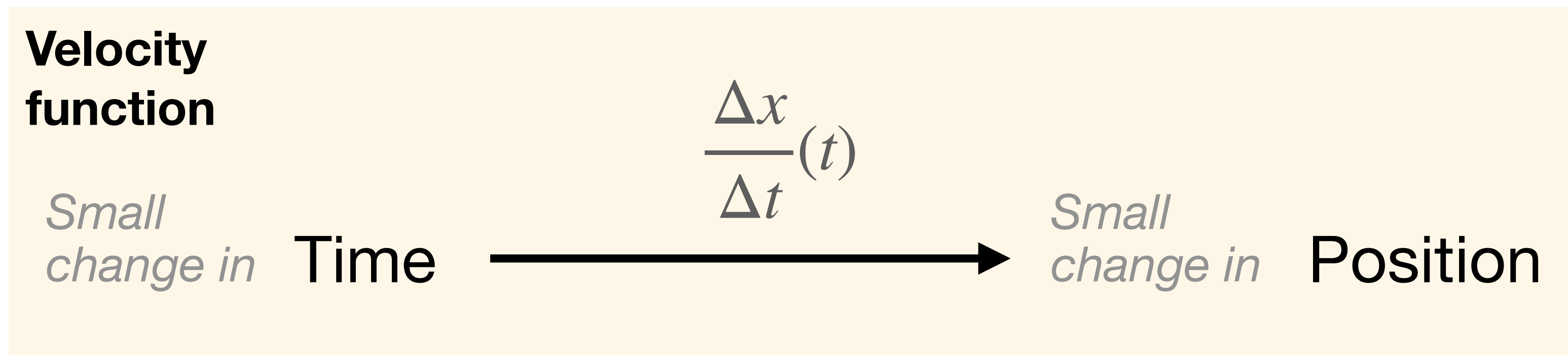
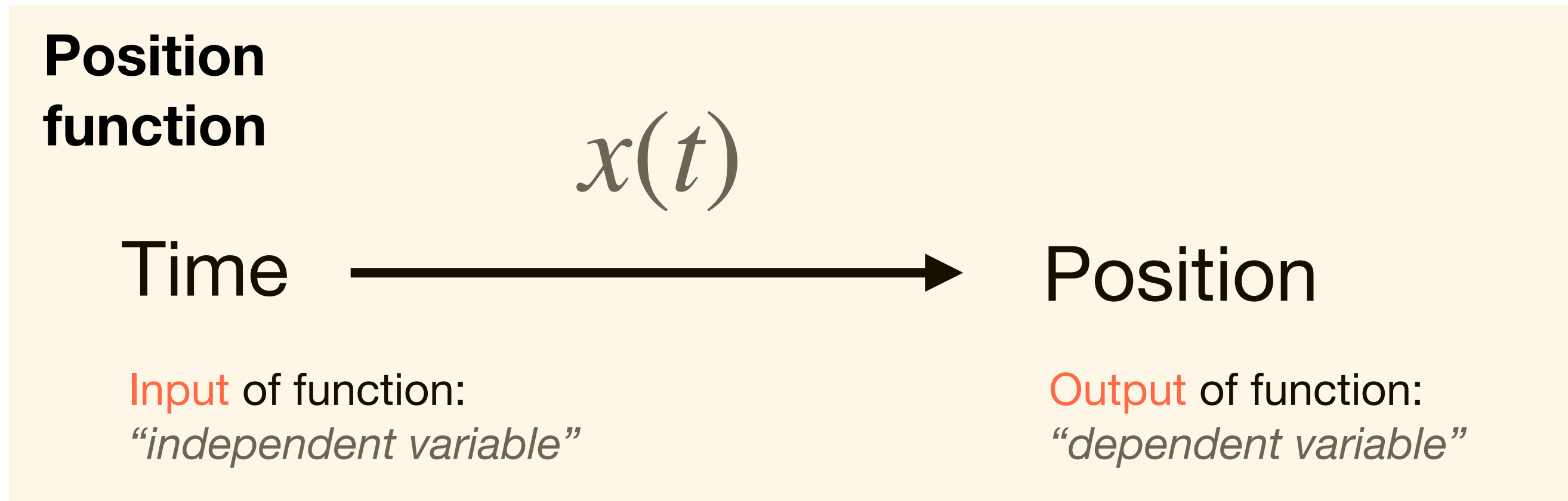
*(i.e. as triangle width goes to zero)*

# Velocity is a differential quantity





# Velocity is a differential quantity



# Velocity is a differential quantity

*“Velocity is the rate of change of  
position with respect to time”*

Independent variable  $x(t)$



A black arrow points from the text 'Independent variable  $x(t)$ ' to the word 'position' in the italicized definition above.

Dependent variable  $t$



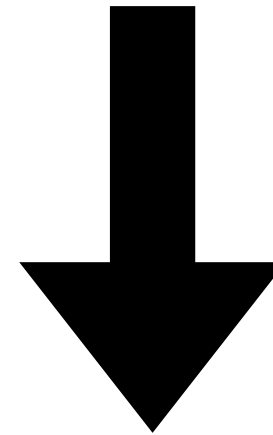
A black arrow points from the text 'Dependent variable  $t$ ' to the word 'time' in the italicized definition above.

# Velocity is a differential quantity

*“Velocity is the rate of change of  
position with respect to time”*

Independent variable  $x(t)$

Dependent variable  $t$



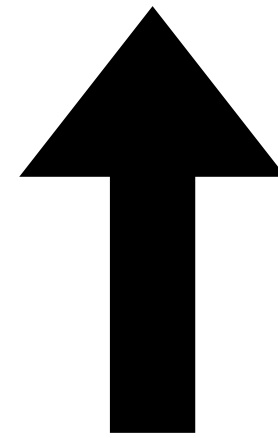
*“Velocity is the **derivative** of  
position with respect to time”*

# Velocity is a differential quantity

Notation: the differential

$dr$  : Infinitesimal change in variable  $r$

Velocity is  $\frac{dx(t)}{dt}$



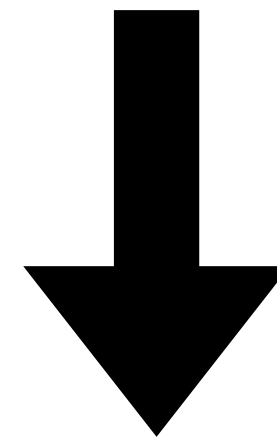
*“Velocity is the derivative of  
position with respect to time”*

# Velocity is a differential quantity

**Notation: the differential**

$dr$  : Infinitesimal change in variable  $r$

$$\frac{dx(t)}{dt}$$

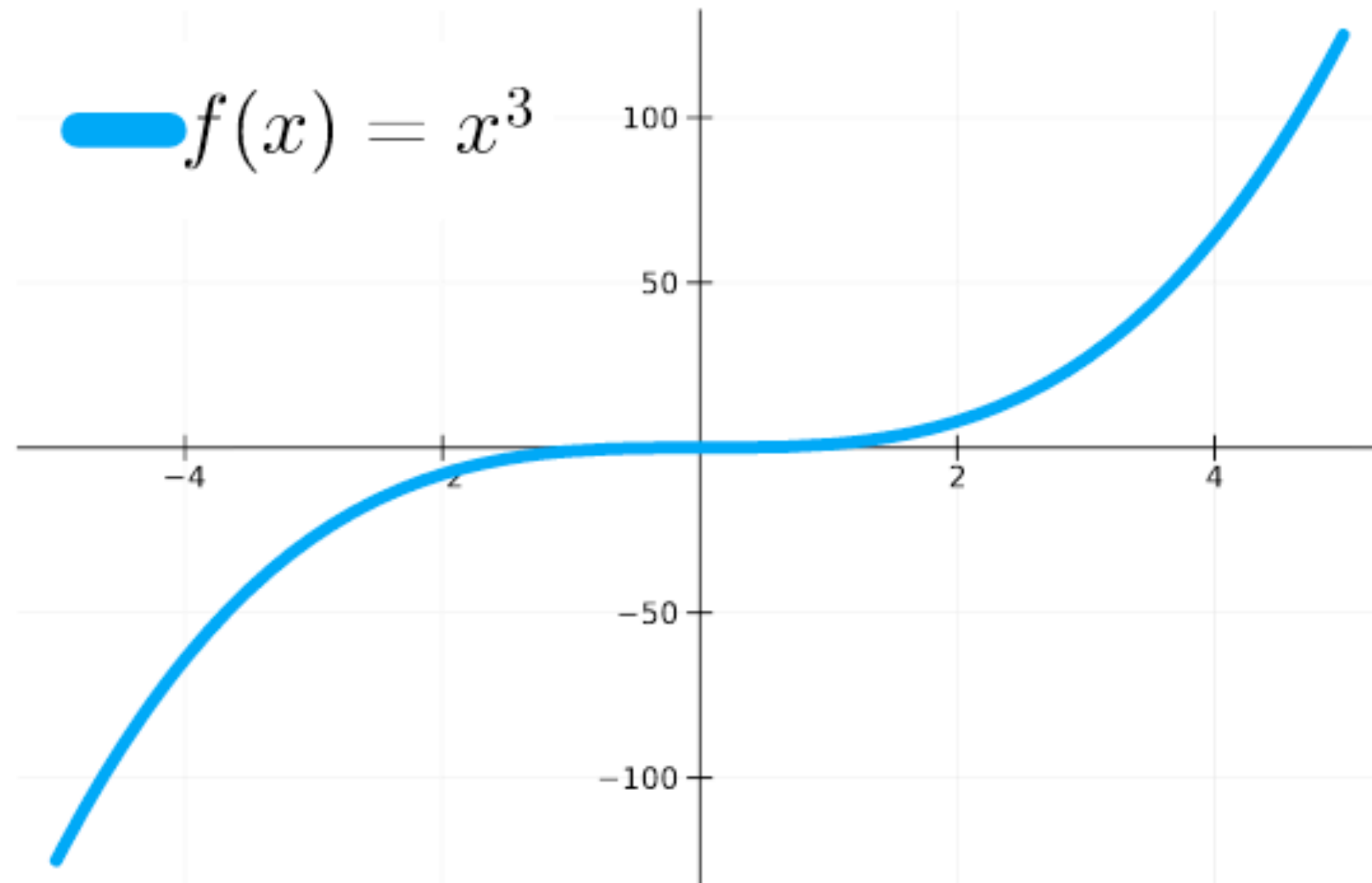


**Tip: read from the bottom**

Infinitesimal change in denominator =>  
How much change in numerator?

*If  $t$  changed infinitesimally, how much  
would  $x(t)$  (infinitesimally) change?*

# Lots of\* functions have derivatives

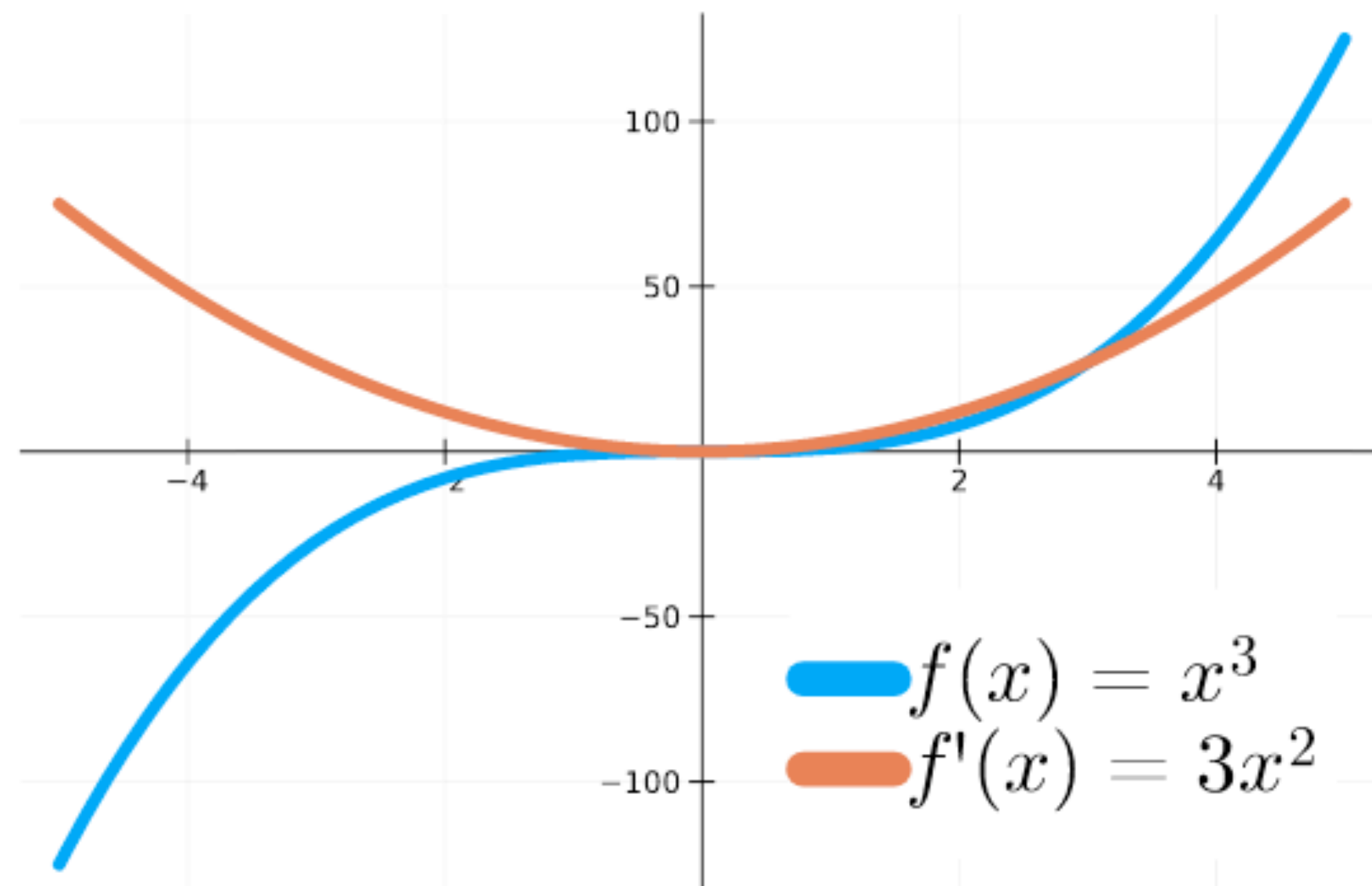


*Mathematical notation  
for derivative?*

*Sketch the derivative  
from intuition*

*\*Terms and conditions apply*

# Lots of\* functions have derivatives



**Common notations:**

$$\frac{df(x)}{dx}$$

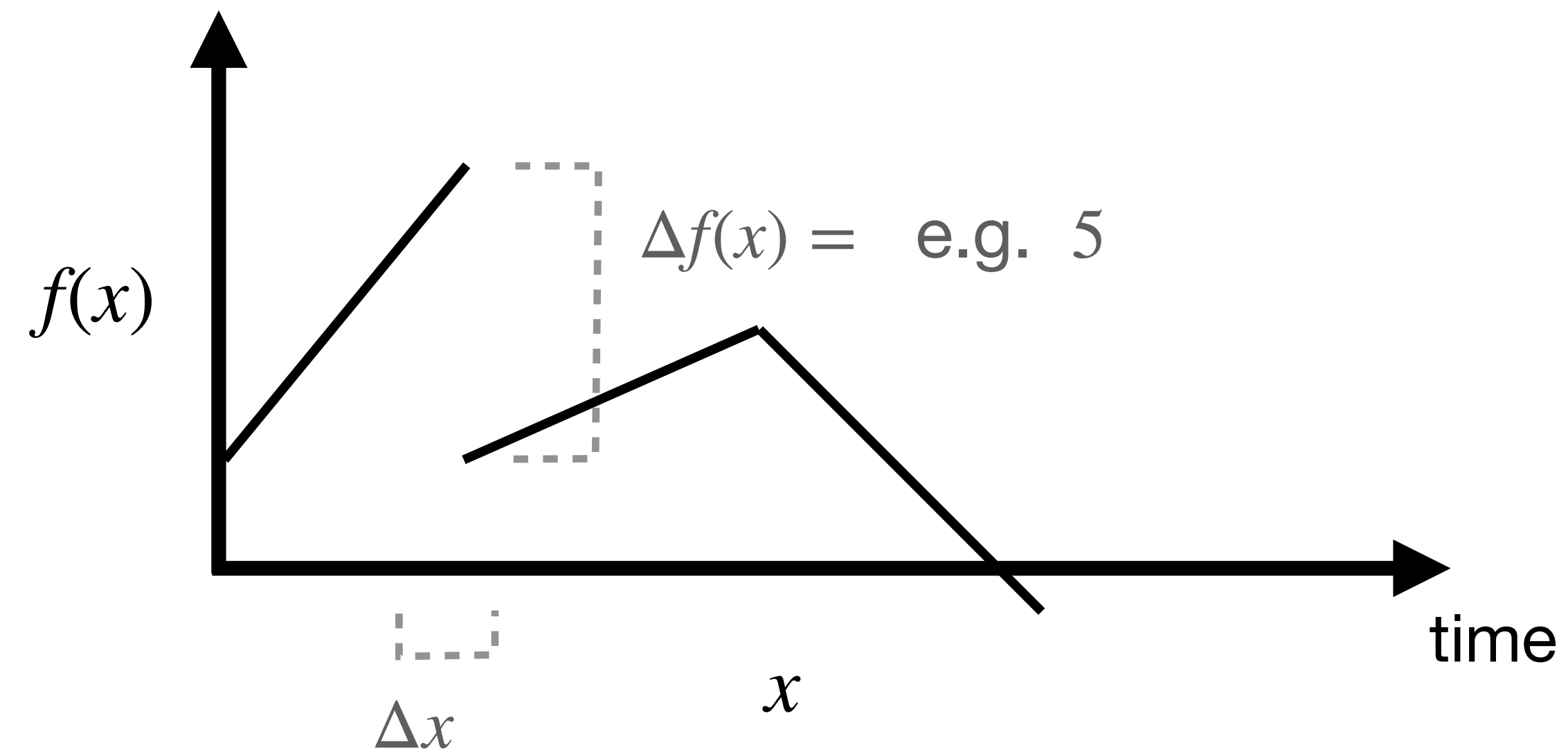
$$\frac{df}{dx}(x)$$

$$f'(x)$$

$$\dot{f}(x)$$

*\*Terms and conditions apply*

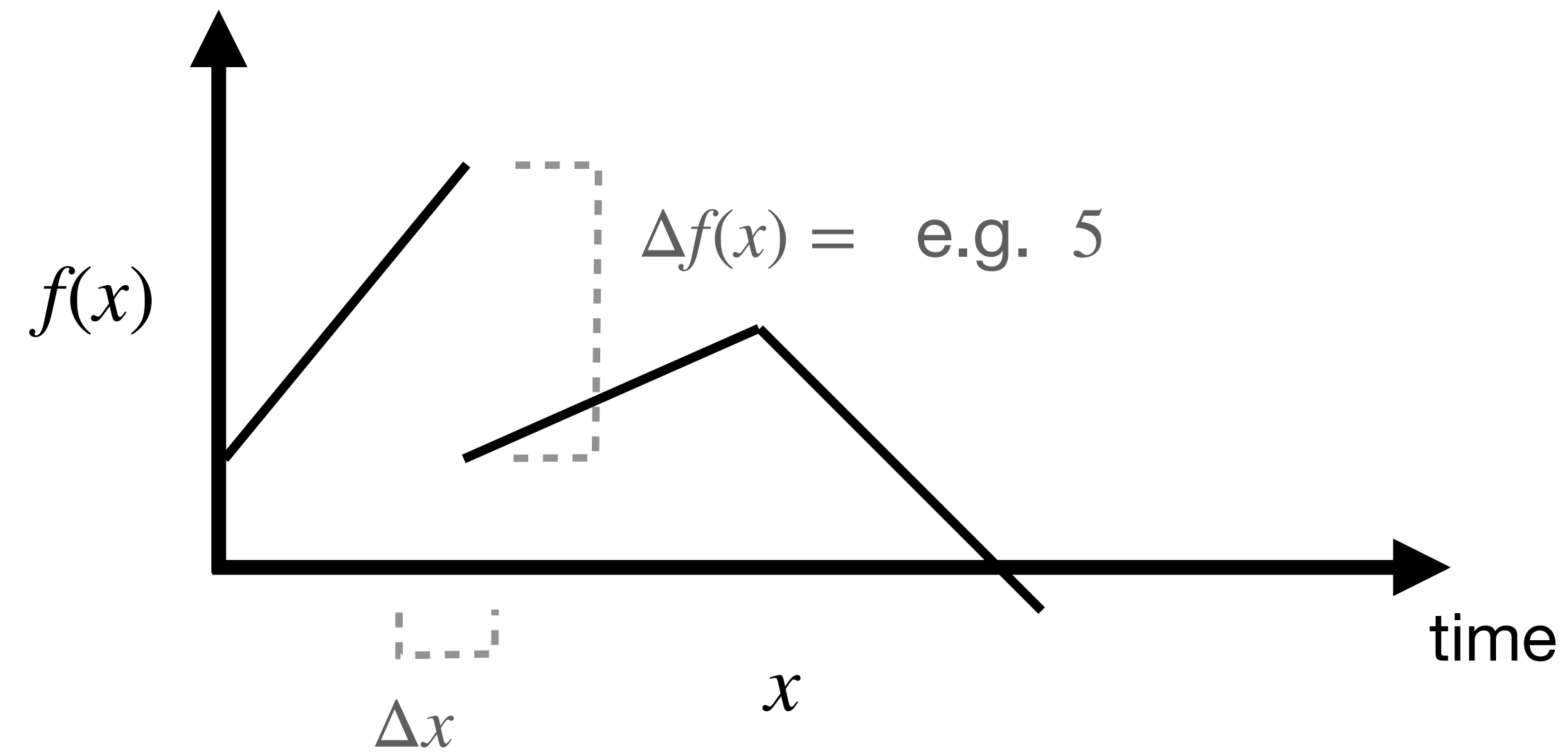
Derivatives are **undefined** at corners and jumps



$$\lim_{\Delta x \rightarrow 0} \frac{\Delta f(x)}{\Delta x} ?$$



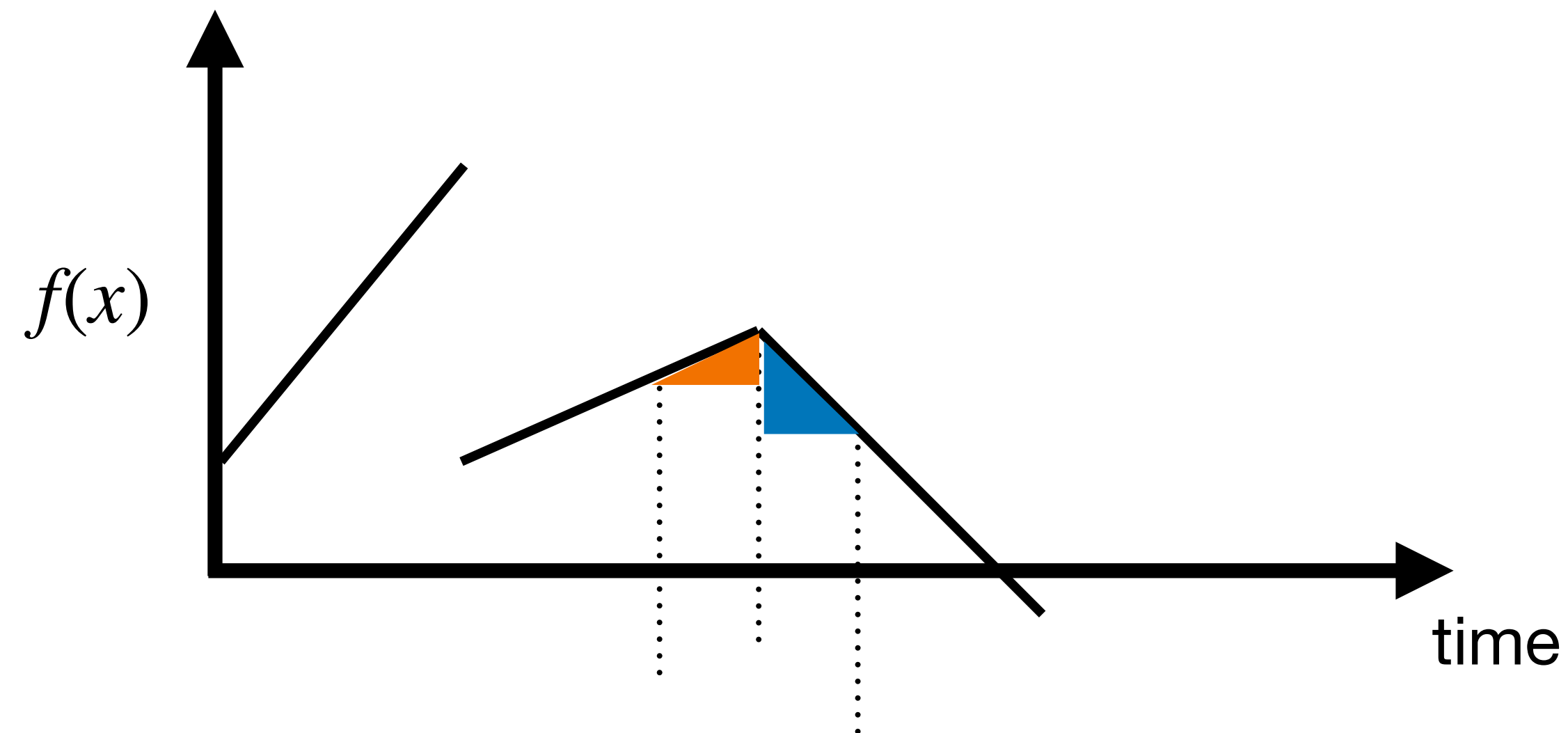
Derivatives are **undefined** at corners and jumps



$$\lim_{\Delta x \rightarrow 0} \frac{\Delta f(x)}{\Delta x} = \lim_{\Delta x \rightarrow 0} \frac{5}{\Delta x}$$



# Derivatives are **undefined** at sharp corners and jumps

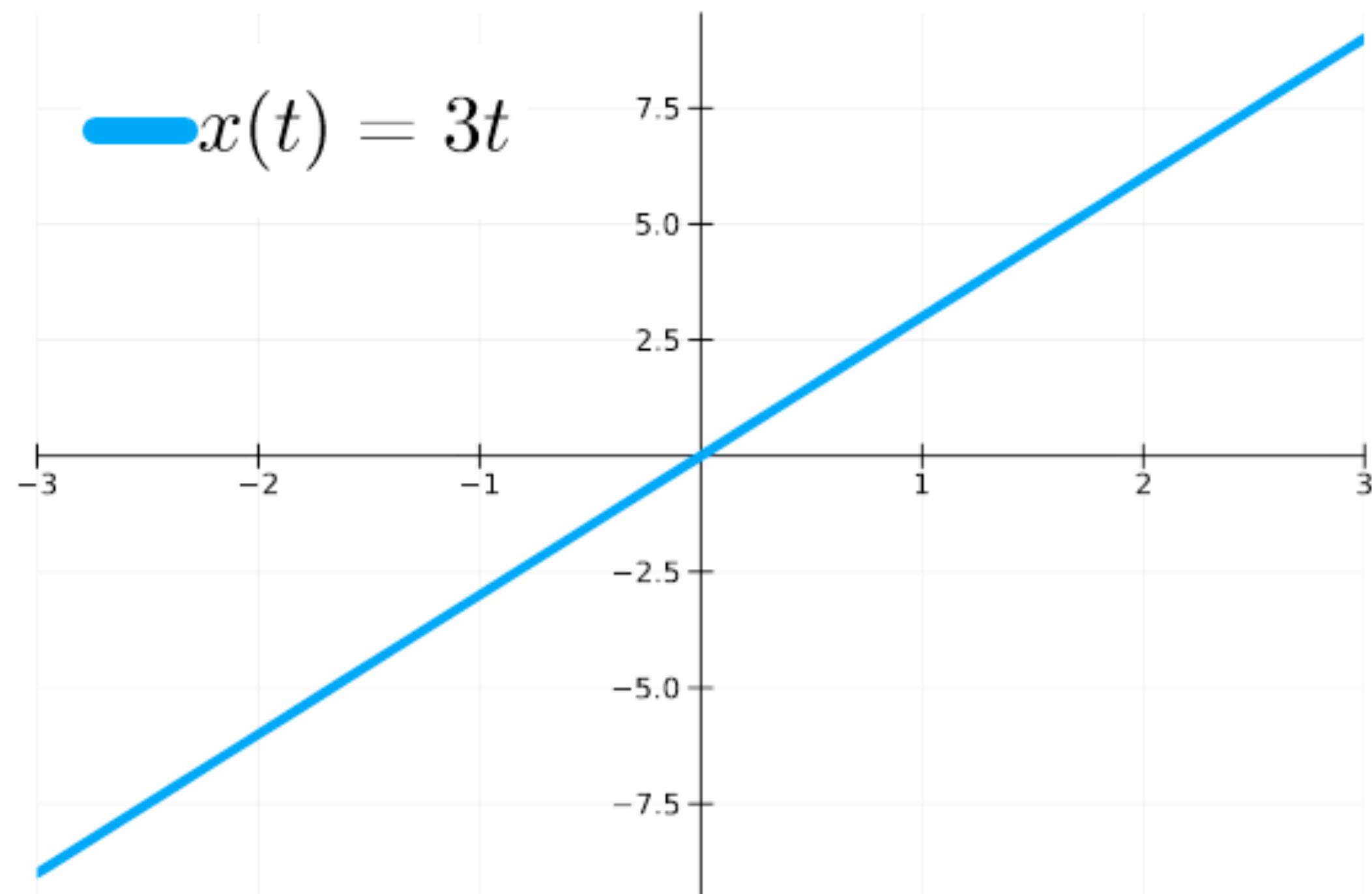


$$\lim_{\Delta x \rightarrow 0, \Delta x < 0} \frac{\Delta f(x)}{\Delta x} \neq \lim_{\Delta x \rightarrow 0, \Delta x > 0} \frac{\Delta f(x)}{\Delta x}$$

$$\lim_{\Delta x \rightarrow 0} \frac{\Delta f(x)}{\Delta x} :$$

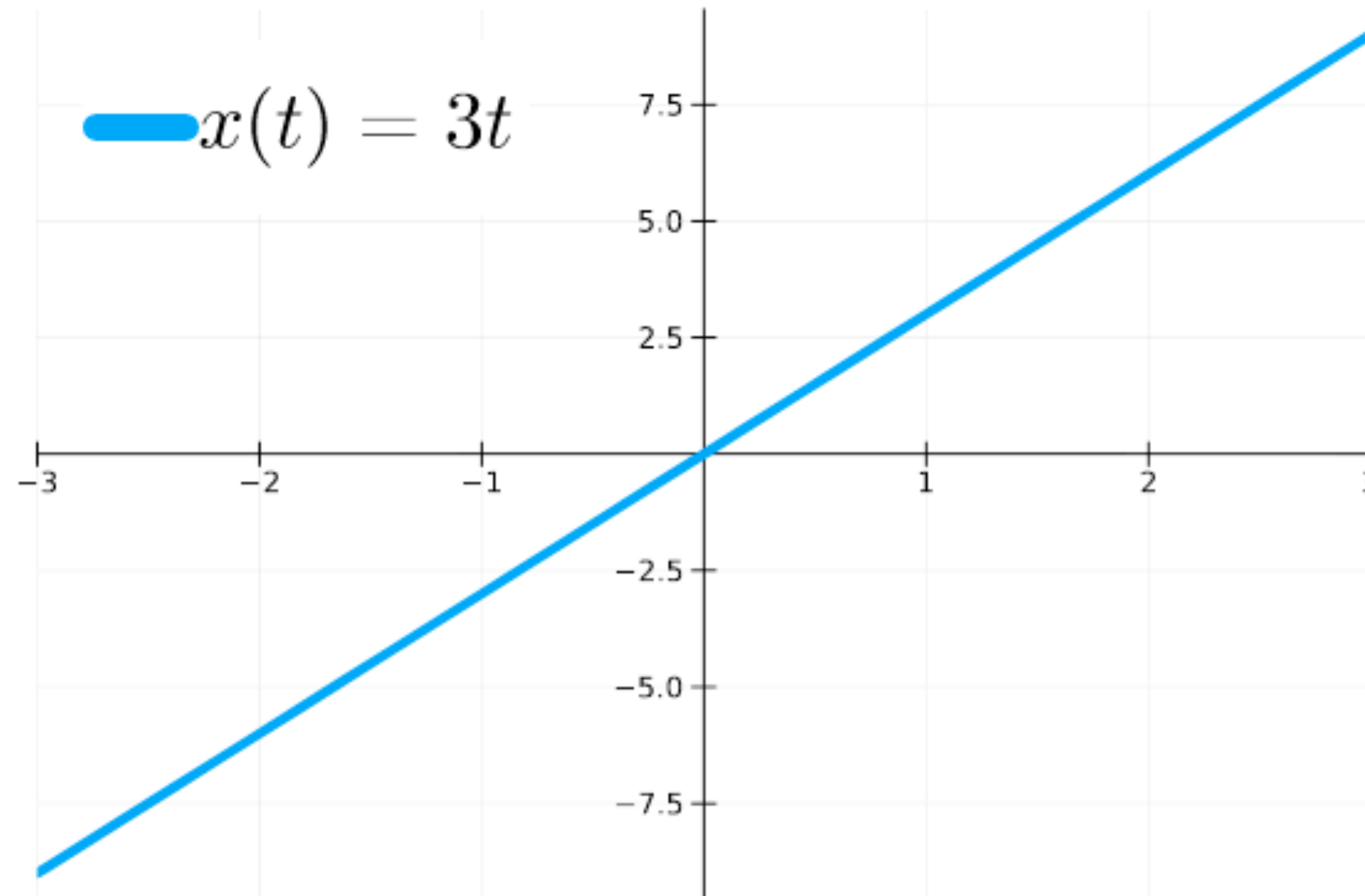
*$\Delta x$  can be negative or positive.  
Limit should be the same!*

# Derivative?



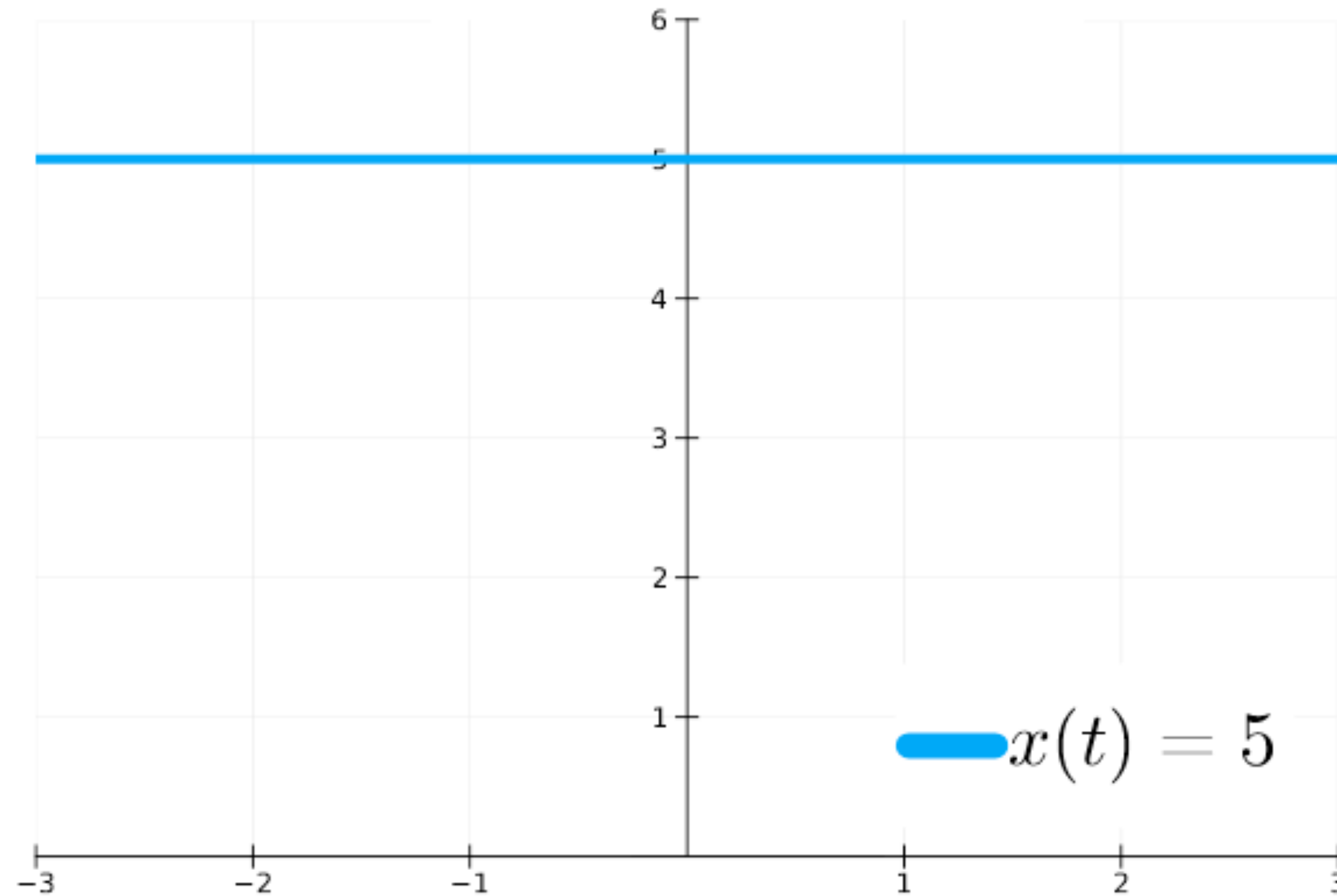
# Derivative?

*Linear functions have  
**constant** derivatives*

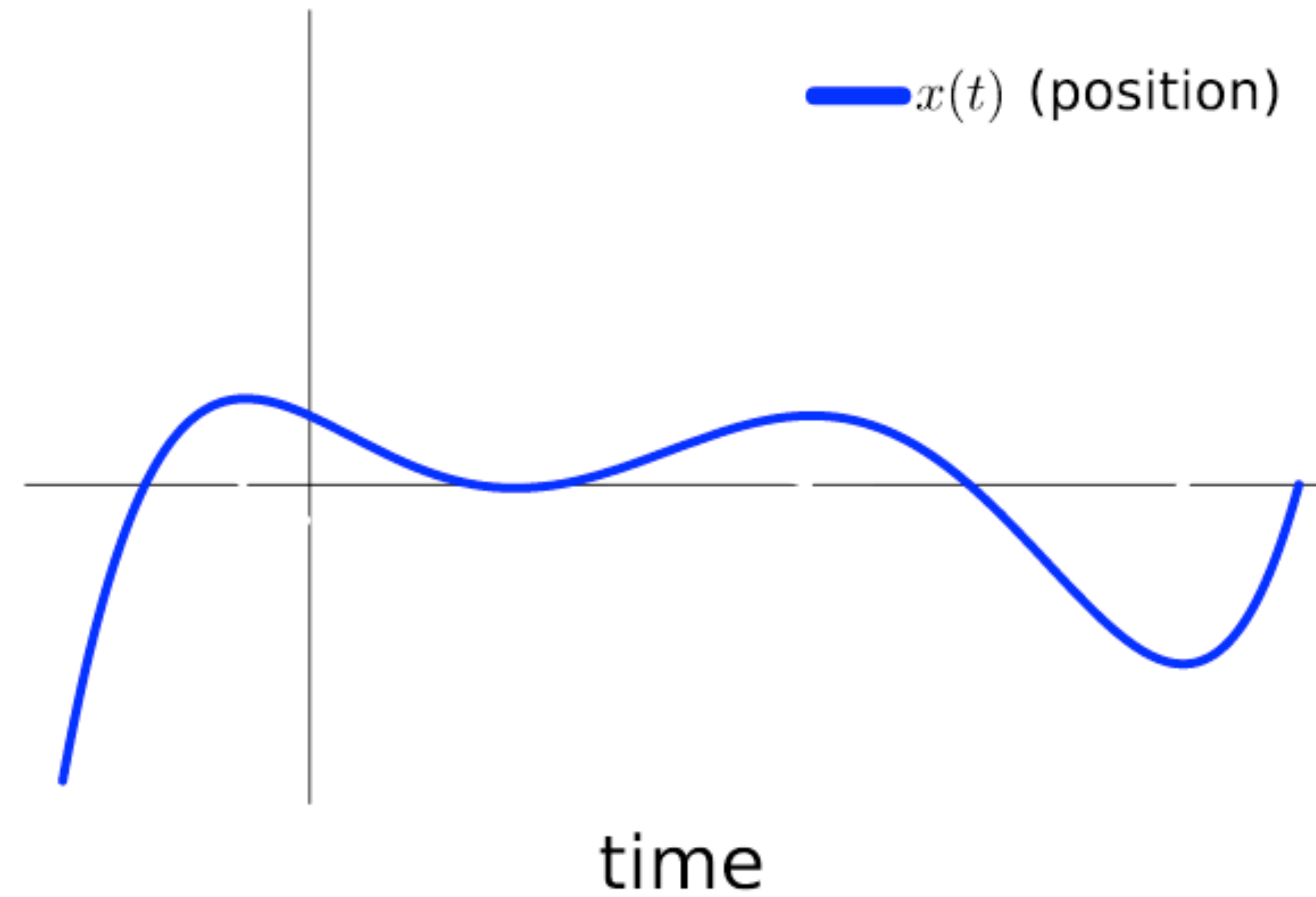


# Derivative?

*Constant functions  
have **zero** derivatives*

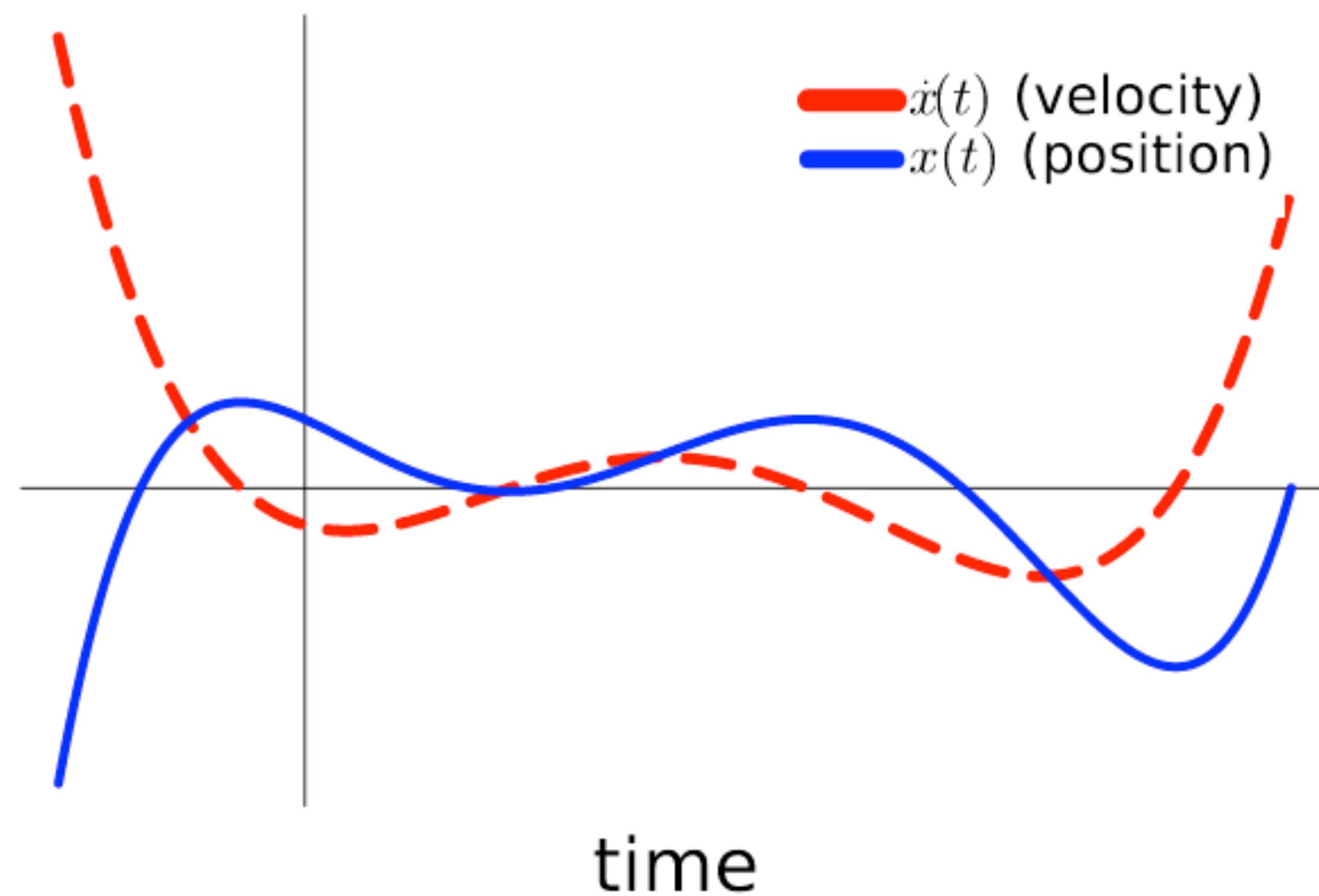


# Acceleration



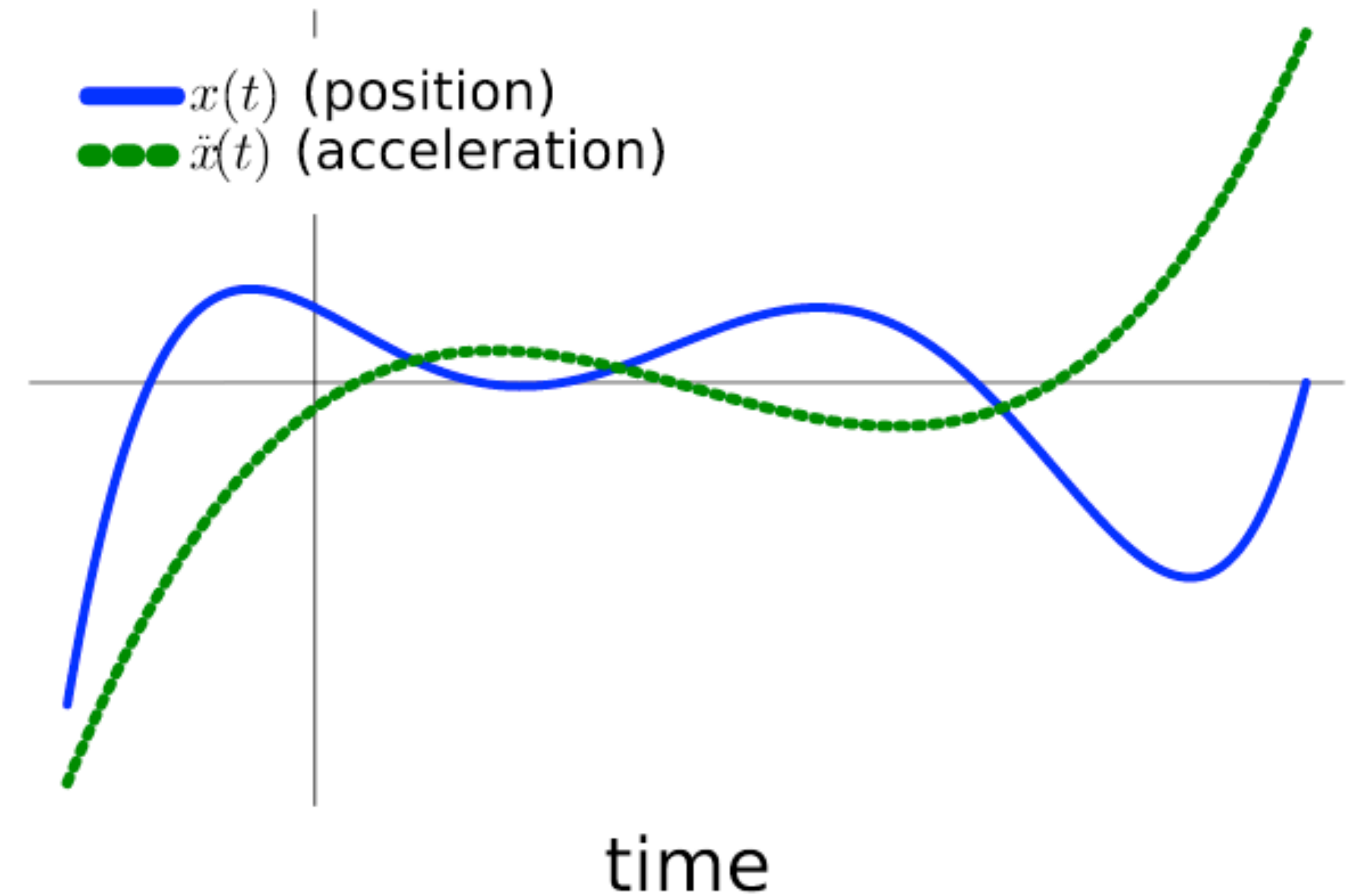
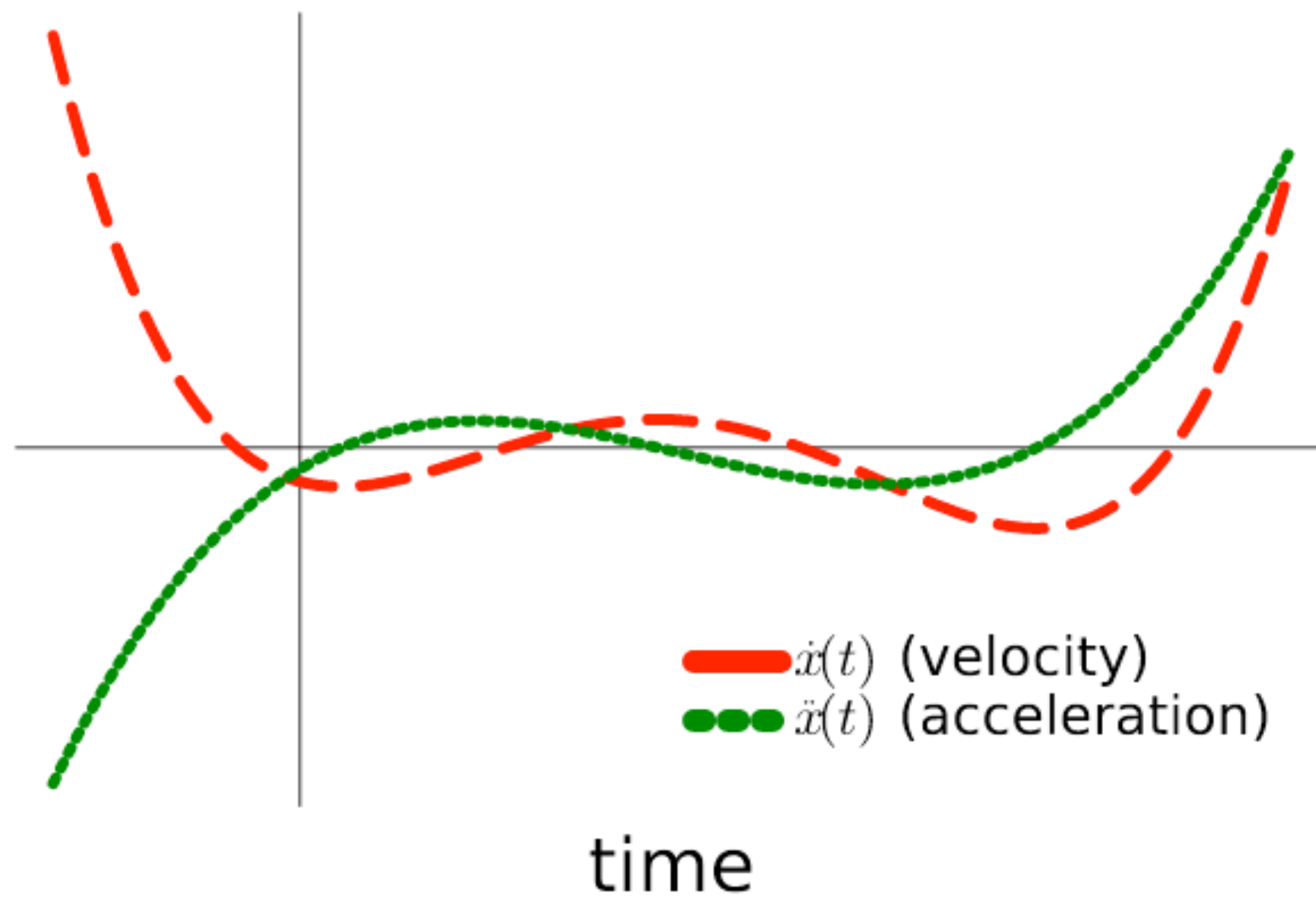
Geometrical analogue?

# Acceleration



Geometrical analogue?

# Acceleration



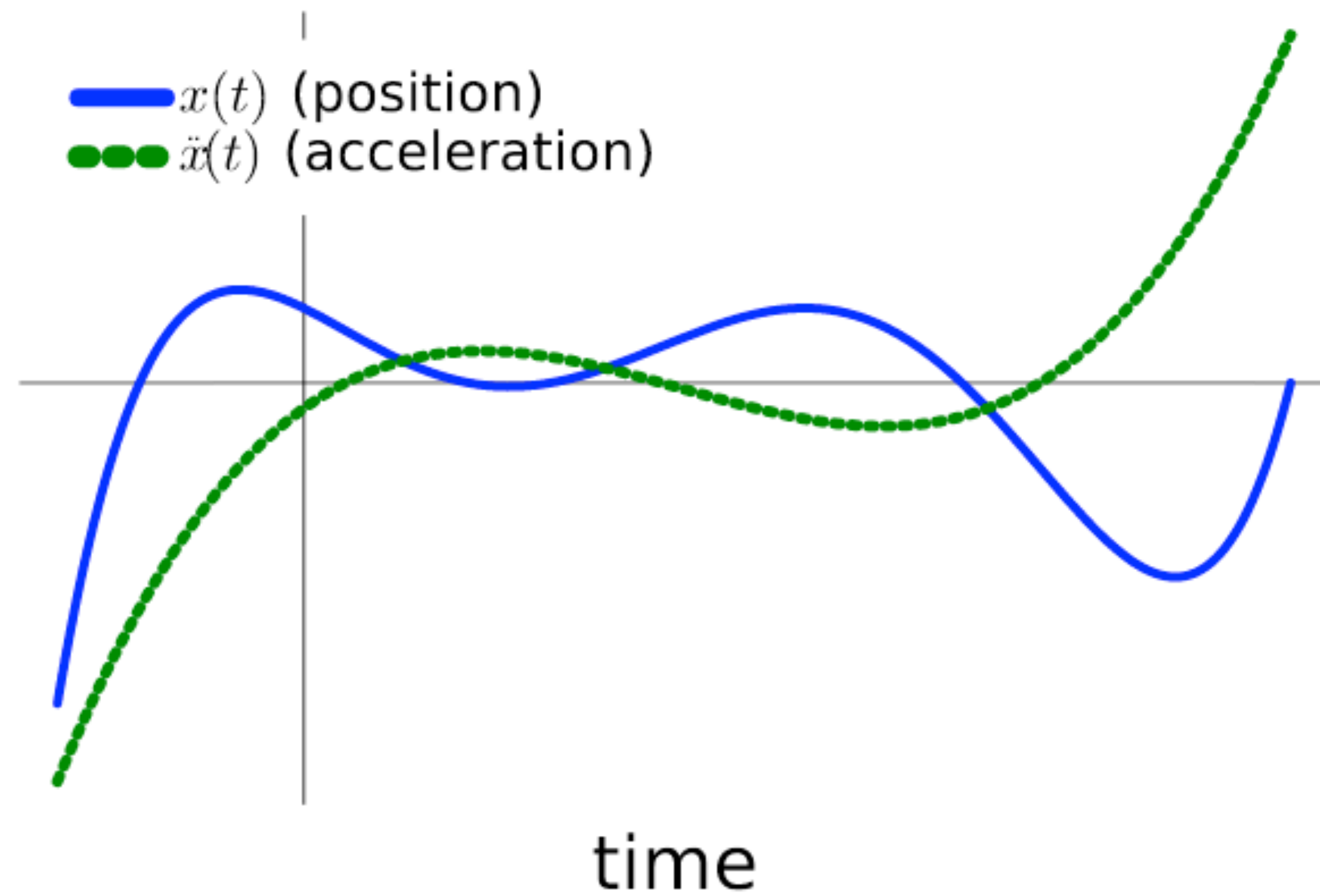
Geometrical analogue:

Derivative of velocity (= steepness)

Double derivative of position (= curviness)



# Acceleration is a differential quantity of a differential quantity



**Common notations:**

$$\frac{d^2f(x)}{dx^2}$$

$$\frac{d^2f}{dx^2}(x)$$

$$f''(x)$$

$$\ddot{f}(x)$$

Geometrical analogue:

Derivative of velocity (= steepness)

**Double** derivative of position (= curviness)

# Higher-order derivatives

**Common notations:**

$$\frac{d^n f(x)}{dx^n}$$

$$\frac{d^n f}{dx^n}(x)$$

(Fourth order)



$$f''''(x)$$

$$\overset{\cdot\cdot}{\underset{\cdot\cdot}{f}}(x)$$

# A bog-standard function

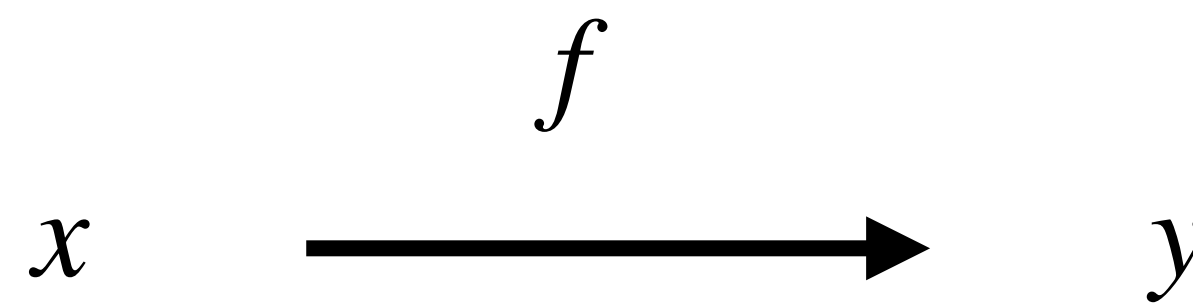
*Mapping between values*

$$f : \mathbb{R} \rightarrow \mathbb{R}$$

$$y = f(x)$$

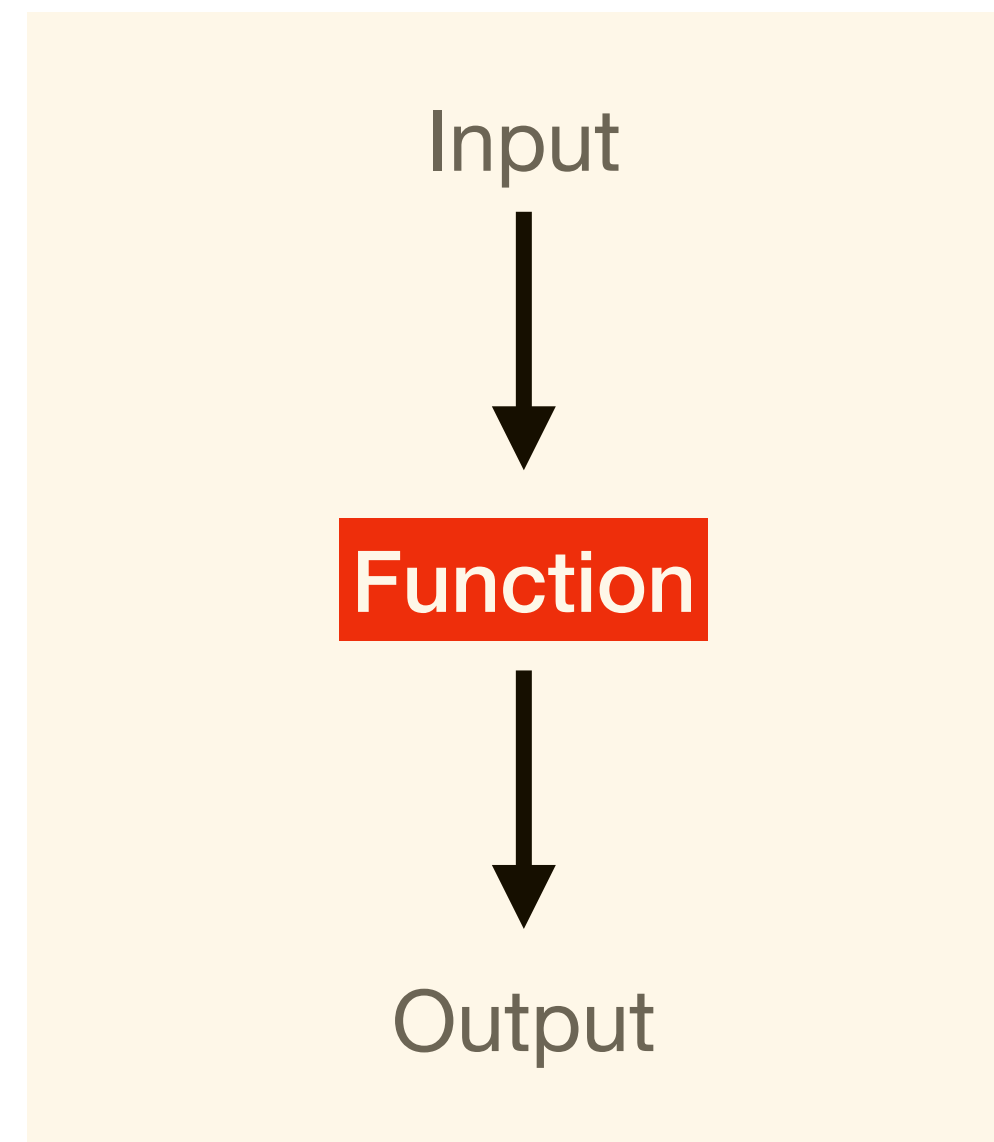
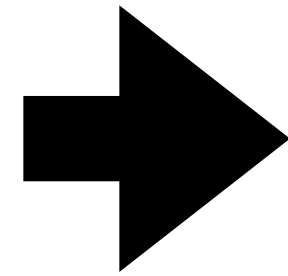
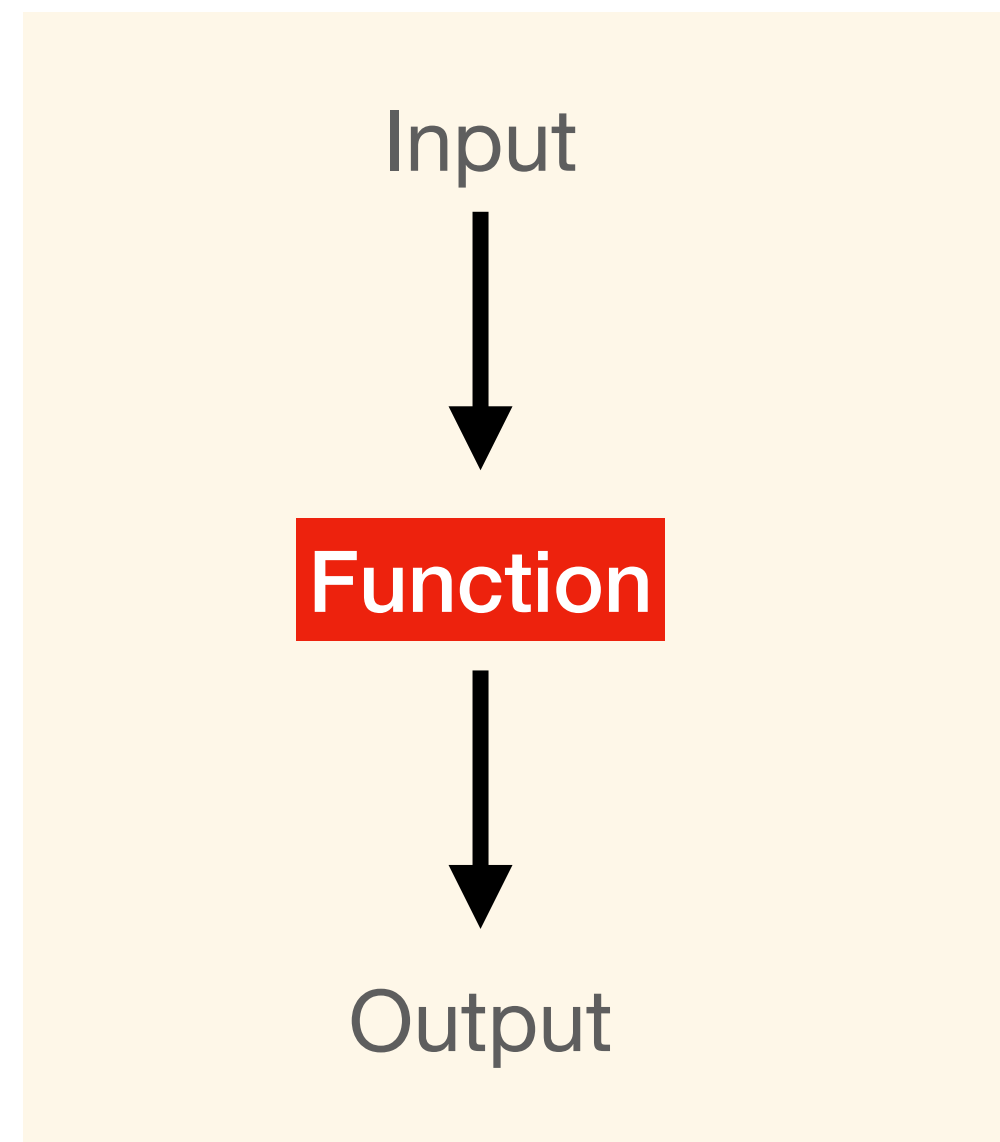
$y$  is the output .  
 $f$  is the mapping

*They are **not**  
the same*

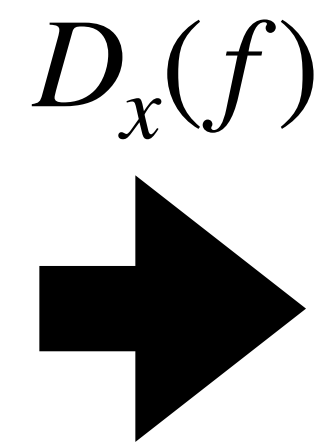


# Differentiation is an **operator**

*Mapping between functions*



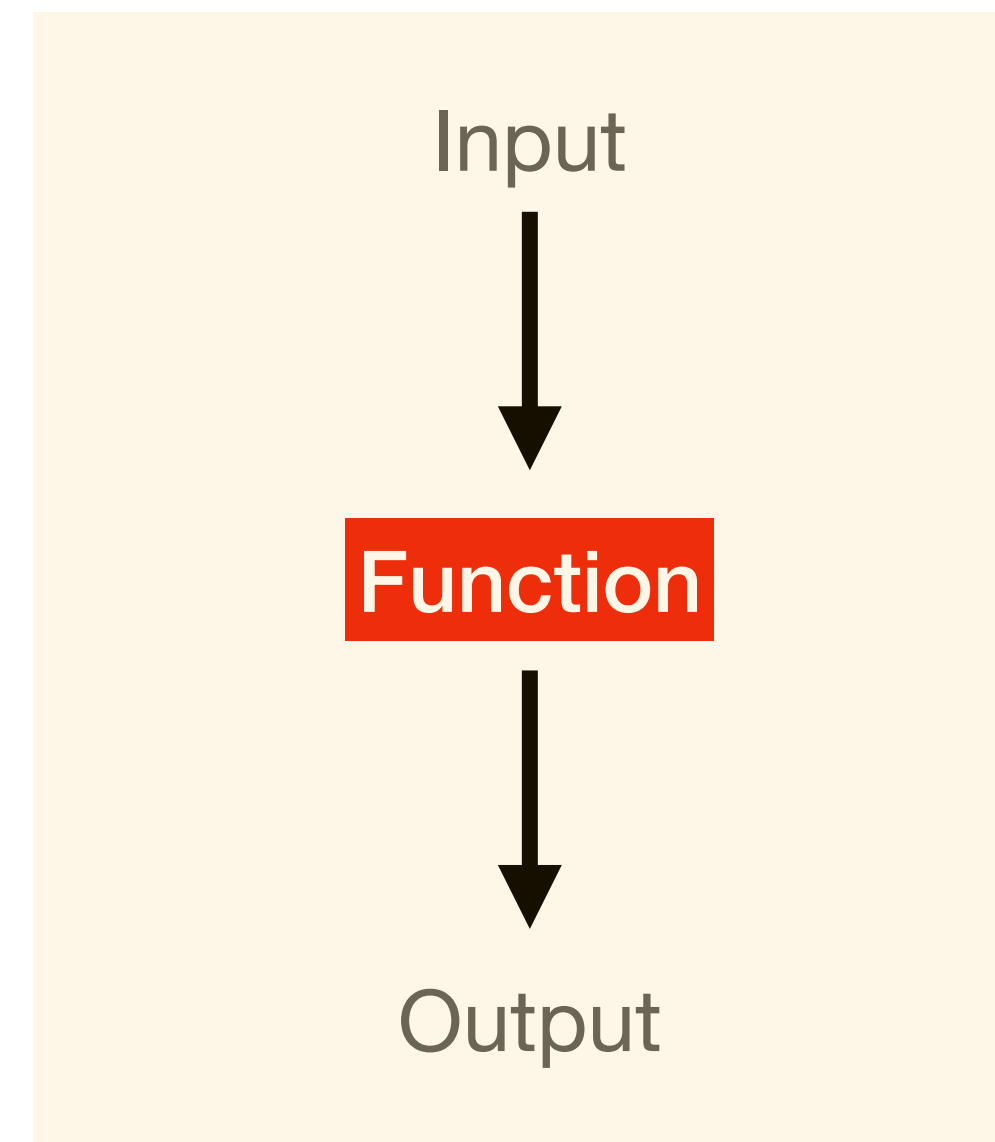
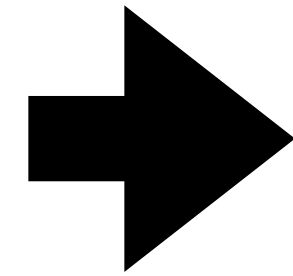
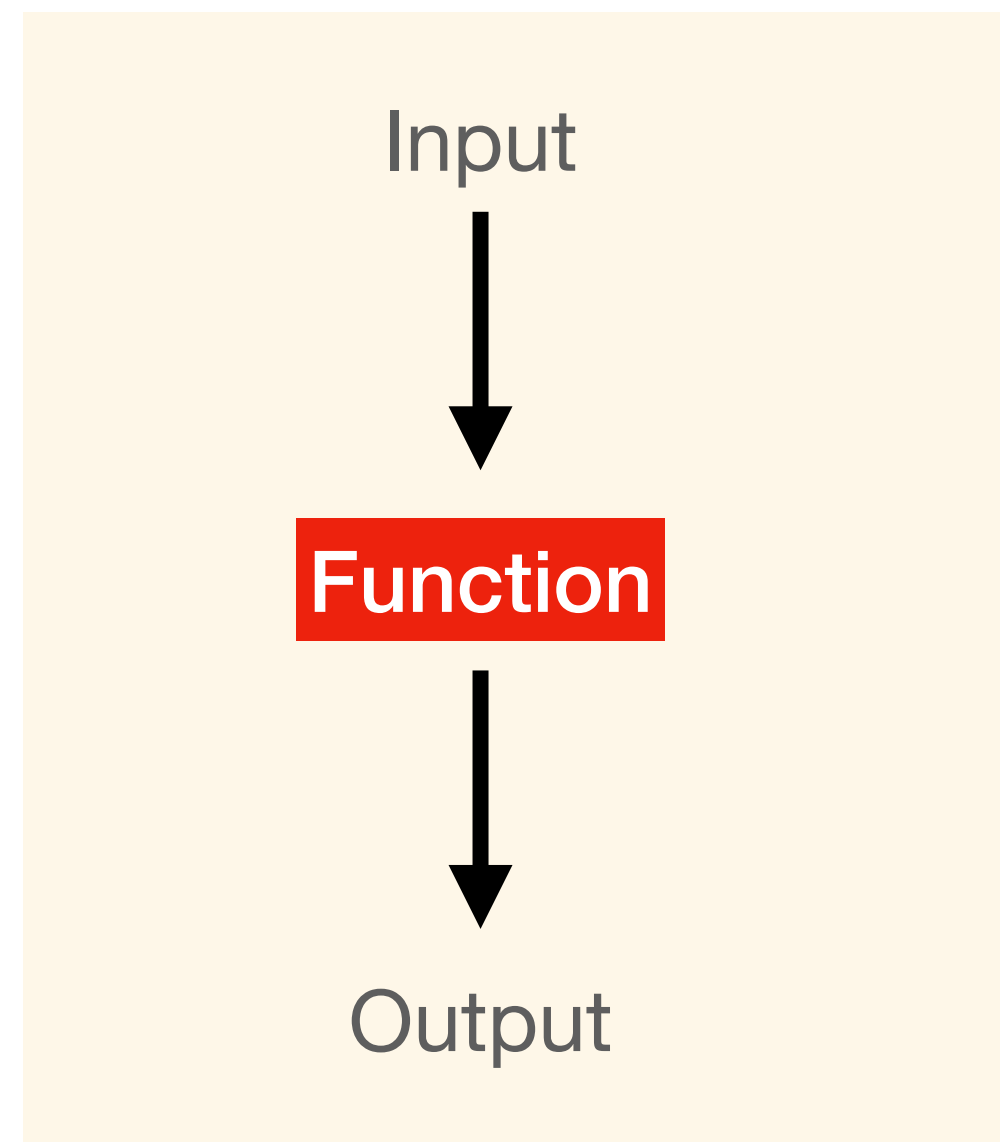
$f(x)$



$\frac{df}{dx}(x)$

# Differentiation is an **operator**

*Mapping between functions*



$\frac{df}{dx}(x)$  is the output .

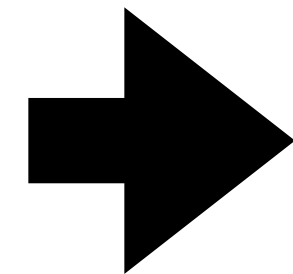
$D_x$  is the mapping

$f$  is the input

*They are **not** the same*

$f(x)$

$D_x(f)$



$\frac{df}{dx}(x)$

# Differentiation is an **operator**

*Mapping between functions*

$$D_x(f)(x) = \frac{df}{dx}(x) \quad (= \text{value at } x)$$

**Common notations:**

$D_x(f)$  : differential operator  
with respect to  $x$

$$f(x) \quad \xrightarrow{D_x(f)}$$



$$\frac{df}{dx}(x) \quad \xrightarrow{D_x \circ D_x(f)} \quad \frac{d^2f}{dx^2}(x)$$

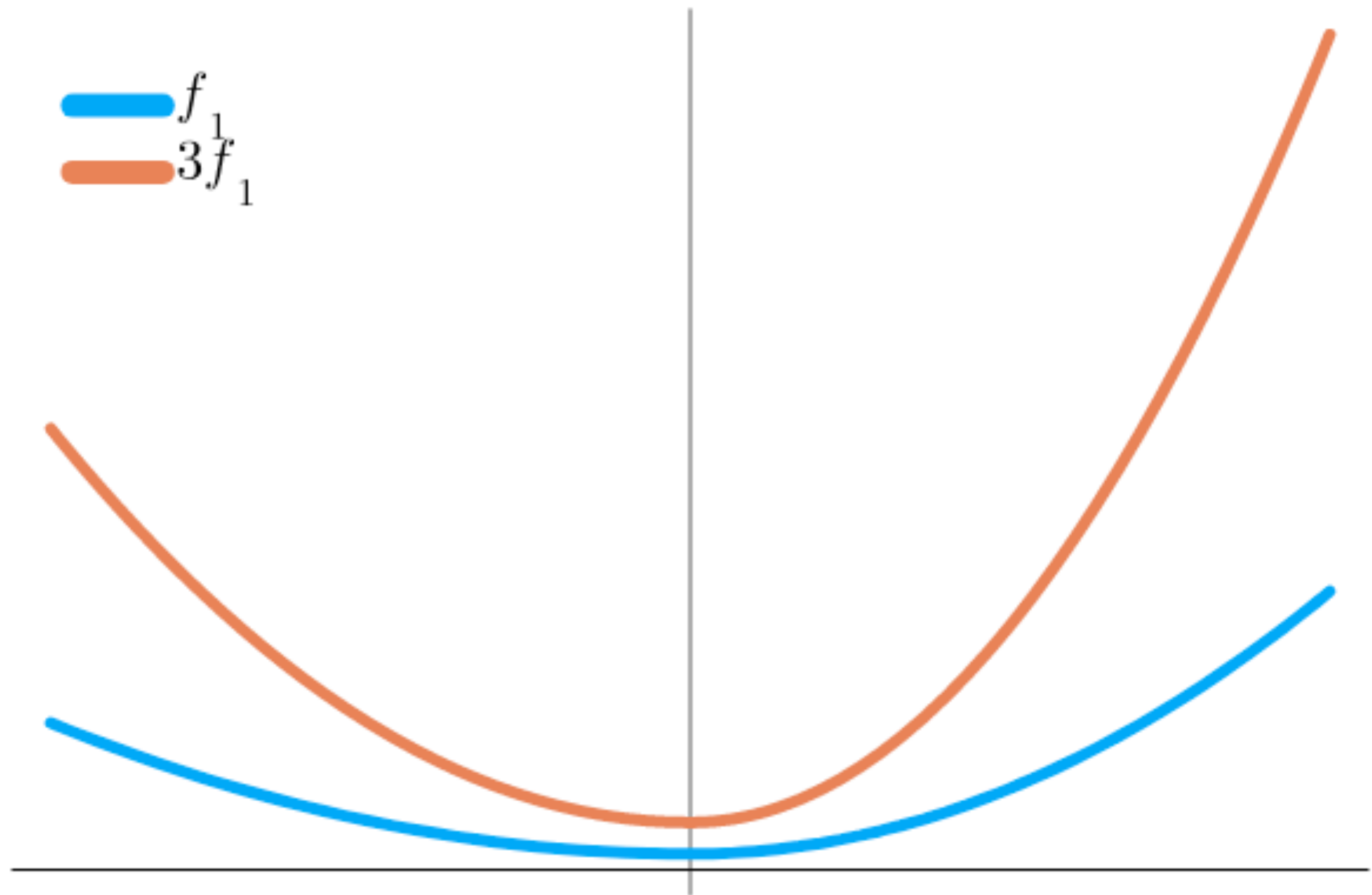
# Differentiation is a **linear** operator

$$kD_x(f) = D_x(kf)$$

Where  $k \in \mathbb{R}$  and  
 $f$  is a function

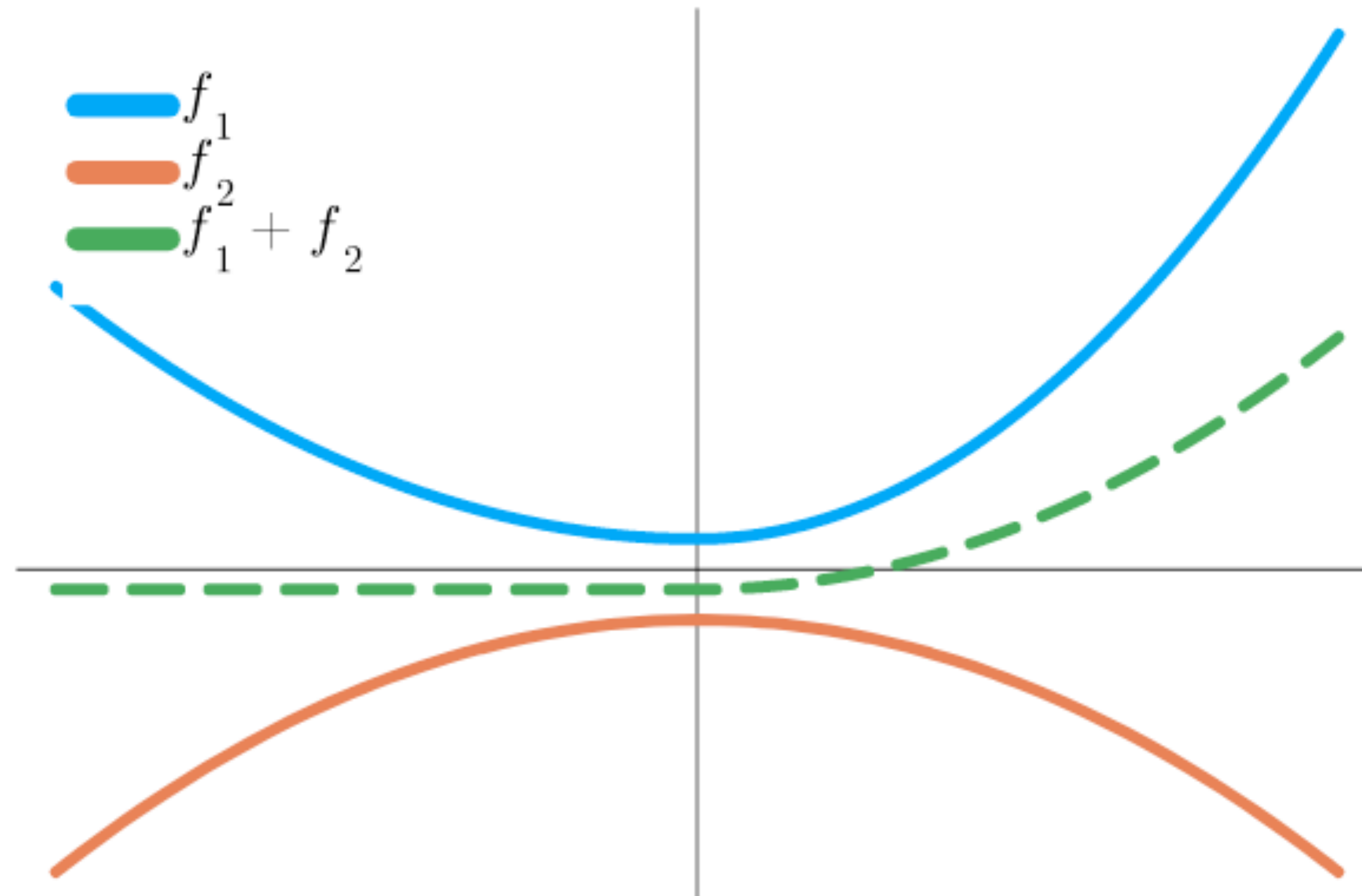
$$k = 3$$

  $f_1$   
  $3f_1$



Differentiation is a  
**linear** operator

$$D_x(f_1) + D_x(f_2) = D_x(f_1 + f_2)$$





# Differentiation is a **linear** operator

Overall:

$$D_x \left( \sum_{i=1}^n a_i f_i \right) = \sum_{i=1}^n a_i D_x(f_i)$$

*for any  $a_i \in \mathbb{R}$ ,  $n \in \mathbb{N}$*

# Differentiation is a **linear** operator

$$f(x) = x^2 + 3x - 4$$

$$f = f_1 + 3f_2 - 4f_3$$

$$f_1(x) = x^2$$

$$f_2(x) = x$$

$$f_3(x) = 1$$

# Differentiation is a **linear** operator

$$f(x) = x^2 + 3x - 4$$

$$f = f_1 + 3f_2 - 4f_3$$

$$f_1(x) = x^2$$

$$f_2(x) = x$$

$$f_3(x) = 1$$

$$D_x(f) = \frac{df(x)}{dx} = D_x(f_1) + 3D_x(f_2) - 4D_x(f_3)$$

# Standard derivatives

Function	Derivative
$y = x^n$	$y' = nx^{n-1}$
$y = \sin(x)$	$y' = \cos(x)$
$y = \cos(x)$	$y' = -\sin(x)$
$y = \ln(x)$	$y' = 1/x$
$y = e^x$	$y' = e^x$

# Standard derivatives

Function	Derivative
$y = x^n$	$y' = nx^{n-1}$
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$y = \ln(x)$	$y' = 1/x$
$y = e^x$	$y' = e^x$

$f(x) = 2x^3 + 3x^4 + 5 \ln(x)$

$\frac{df}{dx}(x) = ?$

# Standard derivatives

Function	Derivative
$y = x^n$	$y' = nx^{n-1}$
$y = \sin(x)$	$y' = \cos(x)$
$y = \cos(x)$	$y' = -\sin(x)$
$y = \ln(x)$	$y' = 1/x$
$y = e^x$	$y' = e^x$

$$f(x) = 2x^3 + 3x^4 + 5 \ln(x)$$

$$\frac{df}{dx}(x) = 2 * (3x^2) + 3 * (4x^3) + \frac{5}{x}$$

$$= 6x^2 + 12x^3 + \frac{5}{x}$$

# Computing derivatives

Drag to move cell

```
• begin
•   using Symbolics ✓
•   @variables t # independent variable
•   D_t = Differential(t)
•   y = t^2 + 4sin(t) + log(t)
• end
```

$$\frac{d}{dt} (\log(t) + 4 \sin(t) + t^2)$$

```
• D_t(y)
```

$$2t + \frac{1}{t} + 4 \cos(t)$$

```
• expand_derivatives(D_t(y))
```

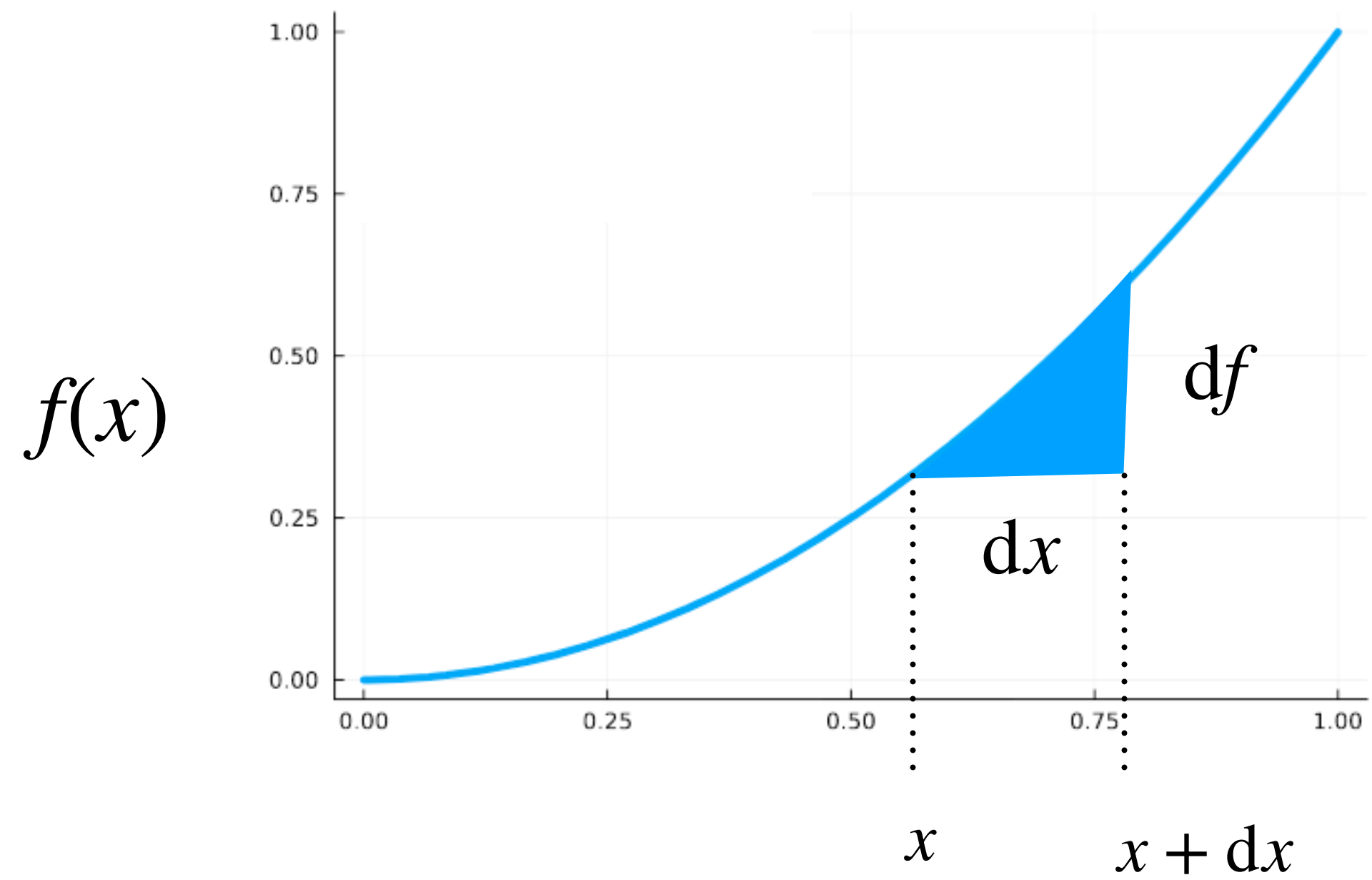
## Alternatives

SymPy in Python  
Wolfram alpha online

Not ChatGPT

# Product and chain rules

Differentiate product and  
composition of functions



$$df = \left( \frac{df}{dx} \right) dx$$

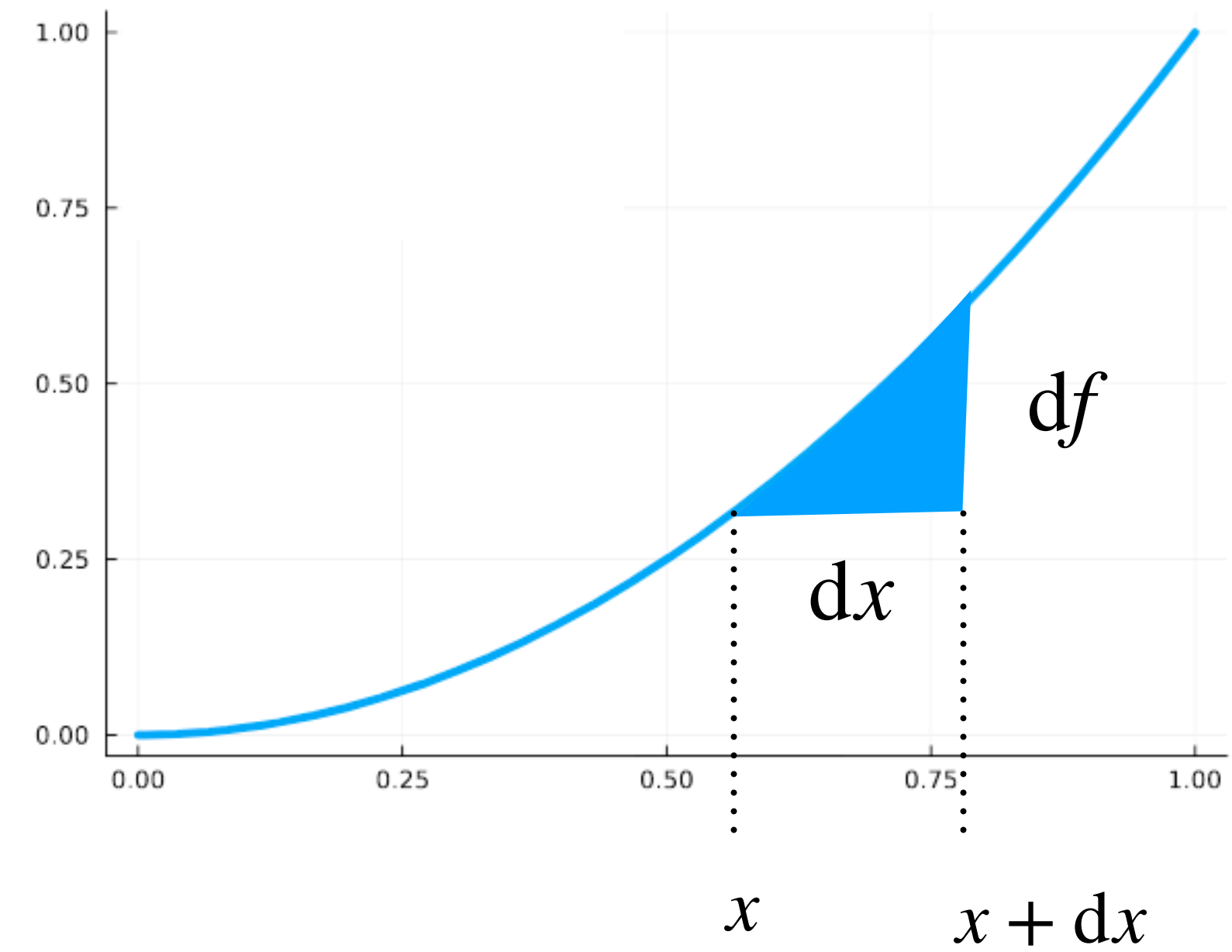


# Product rule

$$f(x) = g(x)h(x)$$

$$\frac{df}{dx}(x) ?$$

$f(x)$



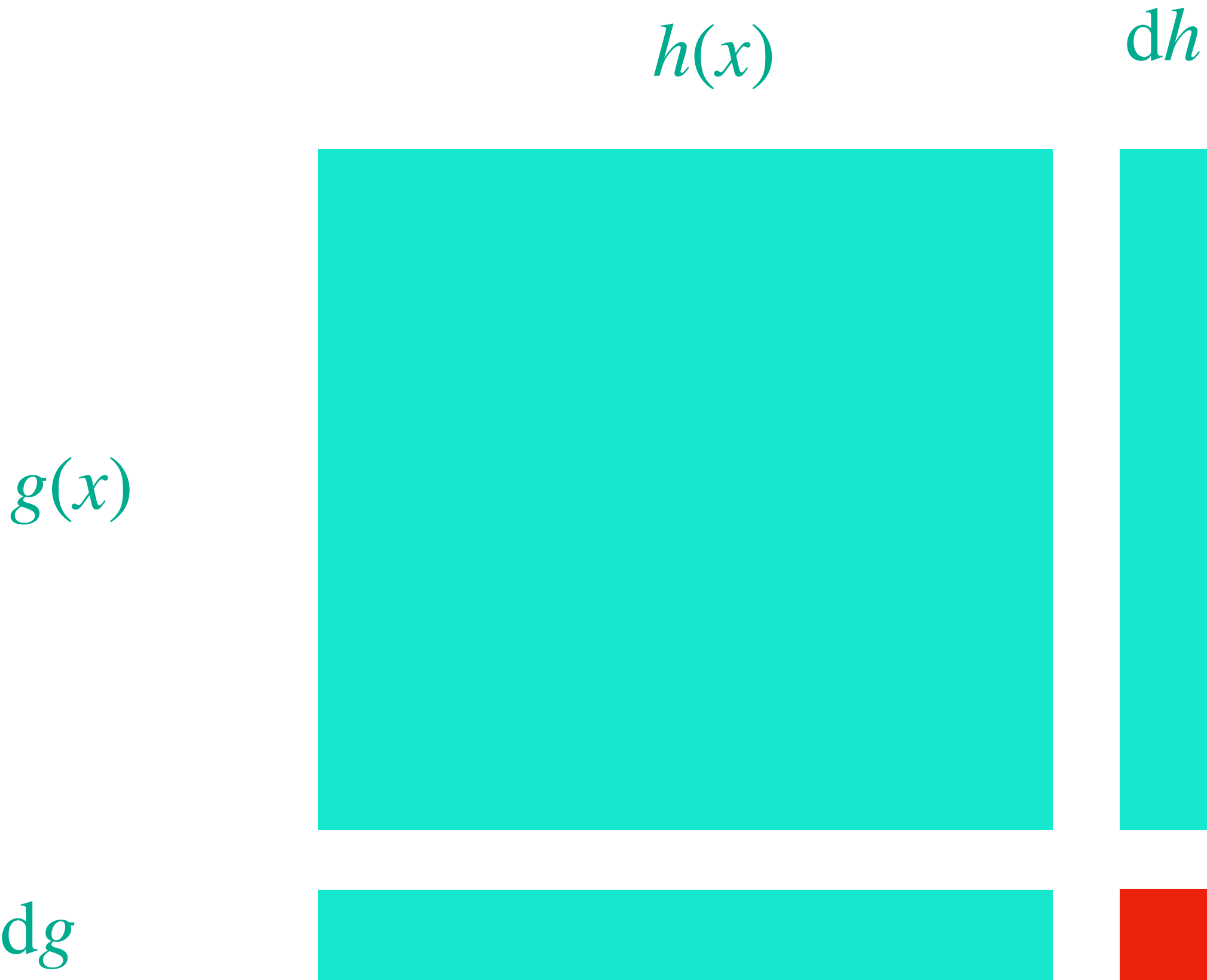
$$df = \left( \frac{df}{dx} \right) dx$$

Product rule

$$f(x) = g(x)h(x)$$

$$\frac{df}{dx}(x) ?$$

$$x \rightarrow x + dx$$
$$f(x) \rightarrow f(x) + df$$



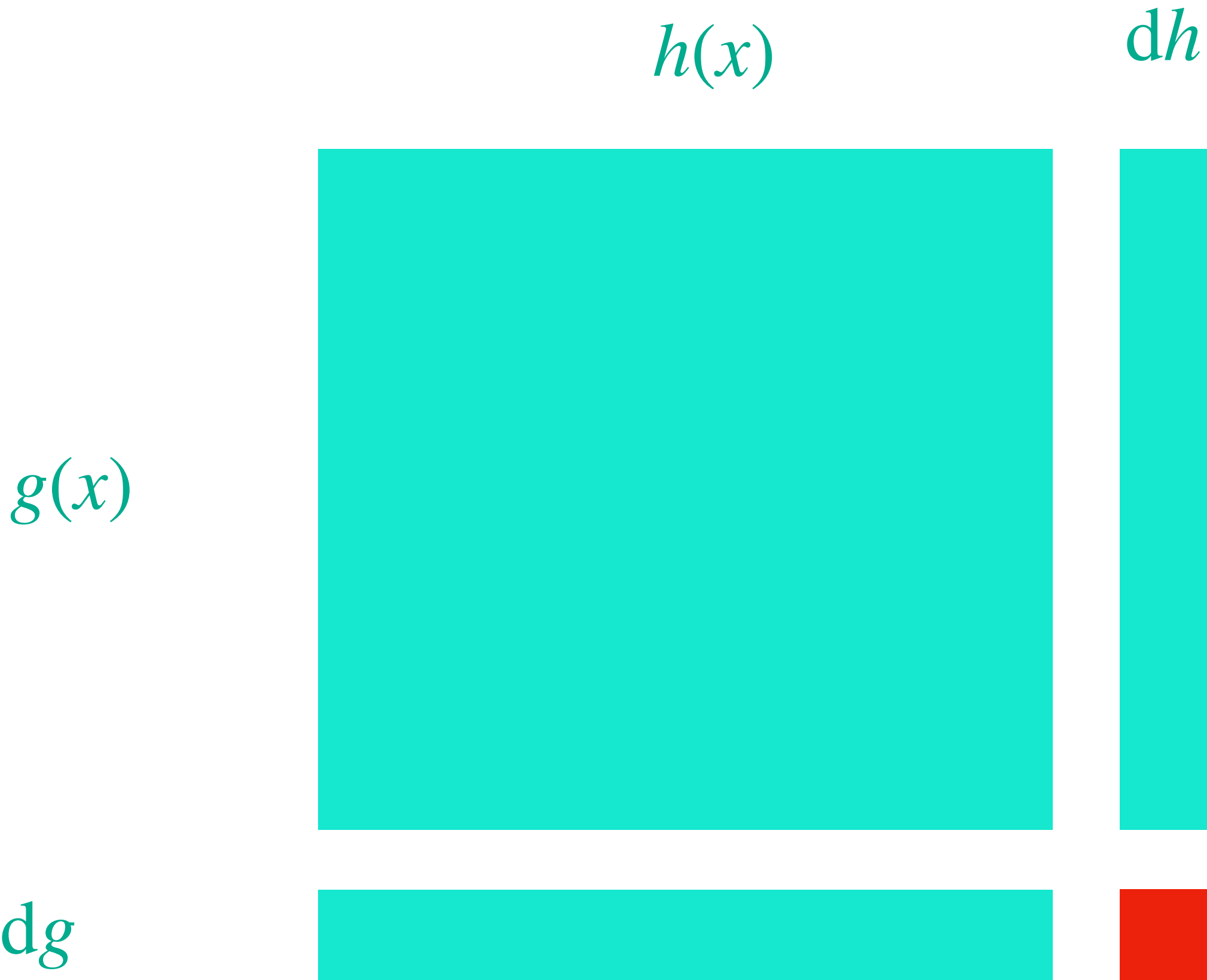
# Product rule

$$f(x) = g(x)h(x)$$

$$\frac{df}{dx}(x) ?$$

$$df = h(x)dg + g(x)dh + dgdh$$

$$x \rightarrow x + dx$$
$$f(x) \rightarrow f(x) + df$$



# Product rule

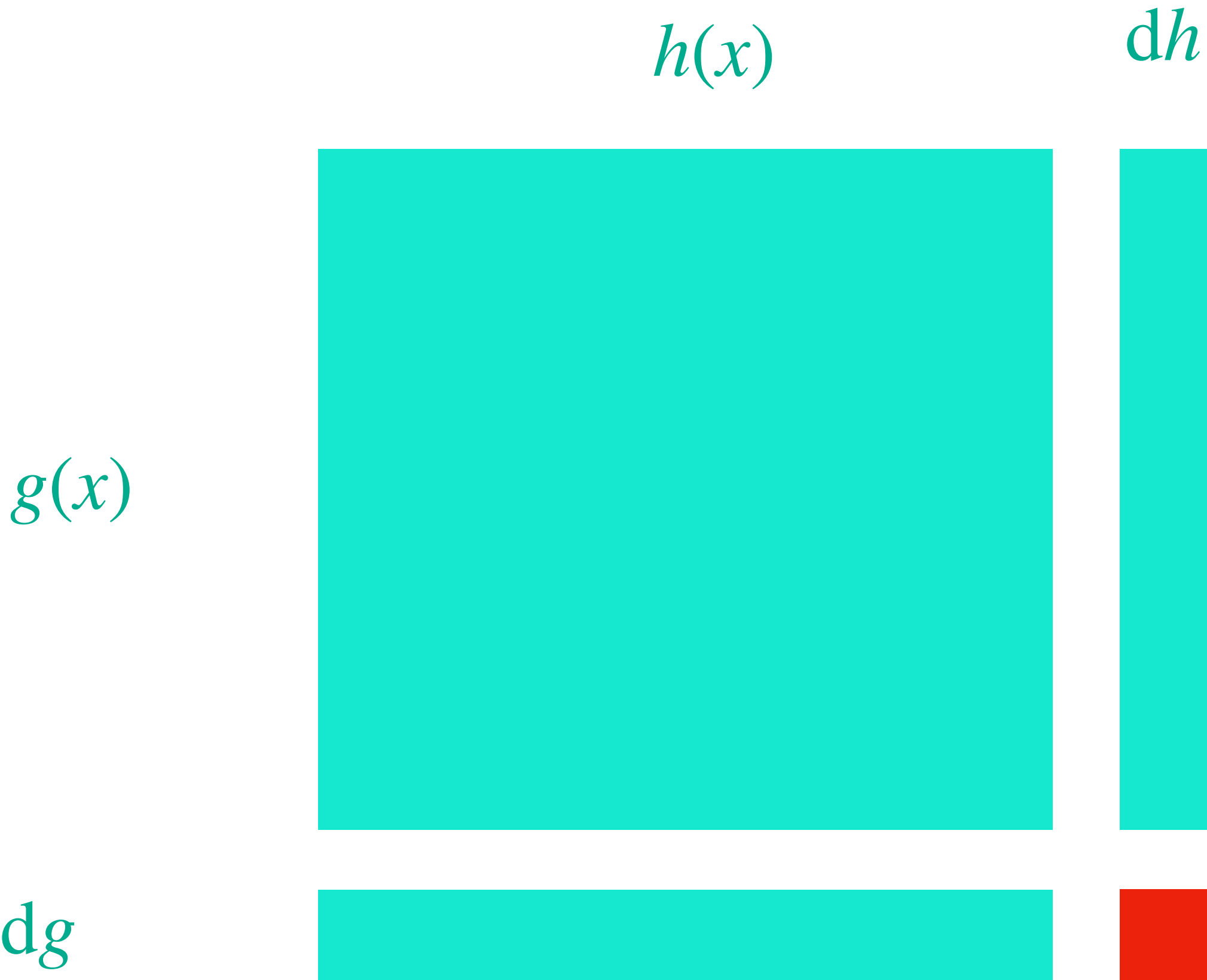
$$f(x) = g(x)h(x)$$

$$\frac{df}{dx}(x) ?$$

$$df = h(x)dg + g(x)dh + dgdh$$

$$\frac{df}{dx} = h(x)\frac{dg}{dx} + g(x)\frac{dh}{dx} + \cancel{\frac{dgdh}{dx}} \quad 0$$

$$x \rightarrow x + dx$$
$$f(x) \rightarrow f(x) + df$$



# Product rule

$$\frac{\cancel{dg}dh}{dx} \quad ?$$

$$\frac{df}{dx} = h(x)\frac{dg}{dx} + g(x)\frac{dh}{dx} + \frac{dgdh}{dx}$$

There must be some  $k \in \mathbb{R}$   
such that:

$$|dg| \leq k |dx|$$

$$|dh| \leq k |dx|$$

*e.g. twice the max steepness of  
 $g(x)$  and  $h(x)$*

# Product rule

$$\left| \frac{dg dh}{dx} \right| \leq \left| \frac{k^2 dx^2}{dx} \right| = k |dx|$$
$$= 0 \text{ as } dx \rightarrow 0$$

$$\frac{df}{dx} = h(x) \frac{dg}{dx} + g(x) \frac{dh}{dx} + \frac{dg dh}{dx}$$

There must be some  $k \in \mathbb{R}$   
such that:

$$|dg| \leq k |dx|$$

$$|dh| \leq k |dx|$$

*e.g. twice the max steepness of  
 $g(x)$  and  $h(x)$*

# Product rule

$$D_x(fg) = gD_x(f) + fD_x(g)$$

$$\frac{df}{dx} = h(x)\frac{dg}{dx} + g(x)\frac{dh}{dx} + \frac{dgdh}{dx}$$

# Product rule

## Example

$$f(x) = x^3 \cos(x)$$

$$D_x(fg) = gD_x(f) + fD_x(g)$$

$$f(x) = g(x)h(x)$$

$$g(x) = x^3$$

$$h(x) = \cos(x)$$



# Product rule

## Example

$$f(x) = x^3 \cos(x)$$

$$D_x(fg) = gD_x(f) + fD_x(g)$$

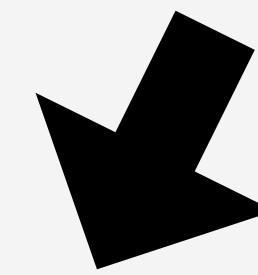
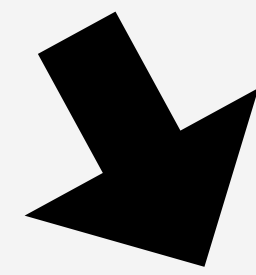
$$f(x) = g(x)h(x)$$

$$g(x) = x^3$$

$$dg = 3x^2 dx$$

$$h(x) = \cos(x)$$

$$dh = -\sin(x) dx$$



$$df = \cos(x)(3x^2 dx) - x^3(\sin(x) dx)$$

# Chain rule

$$\cancel{f(x) = g(x)h(x)} \quad (\textit{Product rule})$$

$$f(x) = g \circ h(x) \quad (\textit{Chain rule})$$

$$g(x) = x^2$$

$$h(x) = \sin(x)$$

$$g \circ h?$$

$$h \circ g?$$

$$gh?$$

$$hg?$$

# Chain rule

~~$f(x) = g(x)h(x)$~~     *(Product rule)*

$f(x) = g \circ h(x)$     *(Chain rule)*

$g(x) = x^2$   
 $h(x) = \sin(x)$

$g \circ h?$	$h \circ g?$	$gh?$	$hg?$
$[\sin(x)]^2$	$\sin(x^2)$	$x^2 \sin(x)$	$x^2 \sin(x)$

# Chain rule

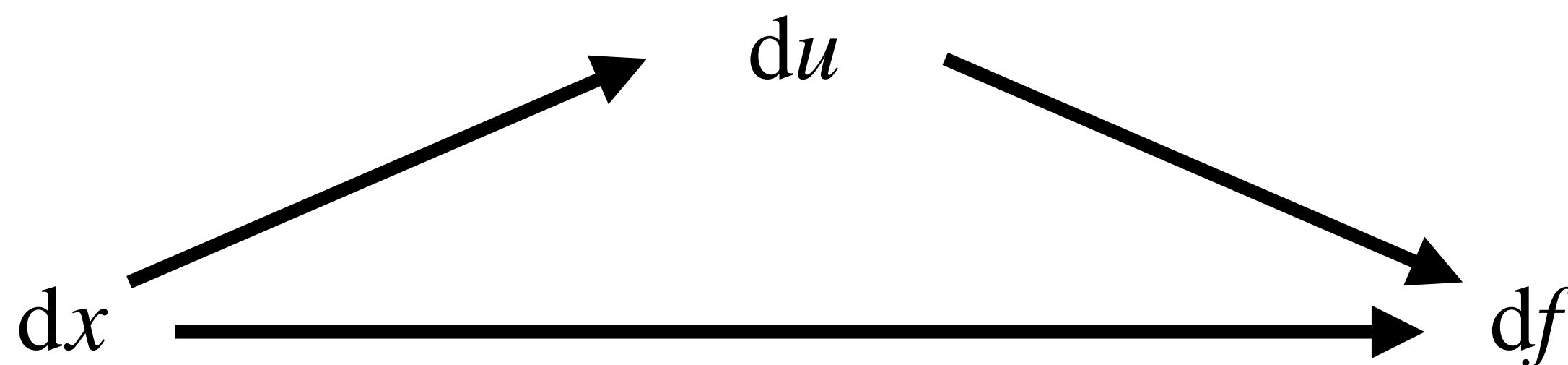
$$f(x) = g \circ h(x)$$

**Step 1: Rewrite**

$$f(x) = g(u)$$

$$u = h(x)$$

$$D_x(g \circ h) ?$$



# Chain rule

$$f(x) = g \circ h(x)$$

**Step 1: Rewrite**

$$f(x) = g(u)$$

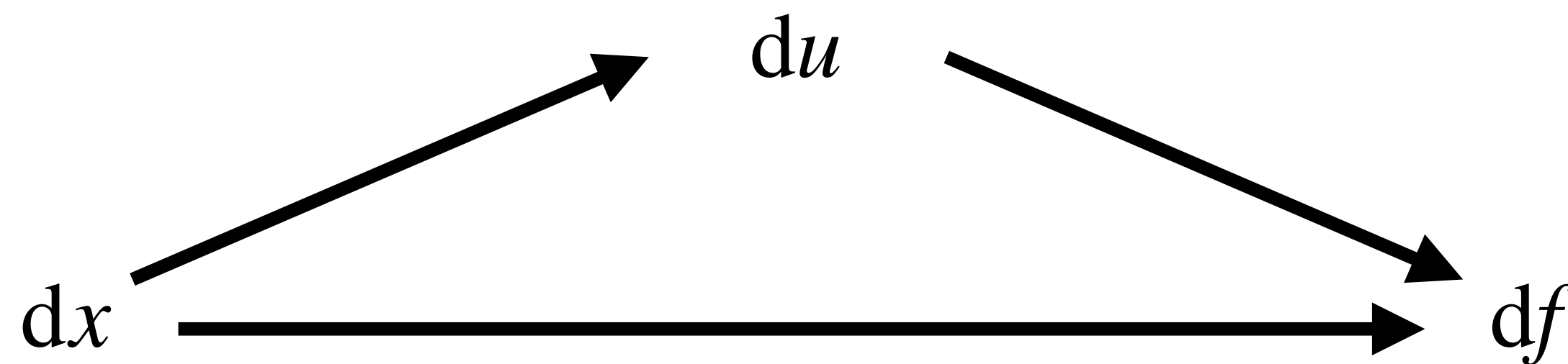
$$u = h(x)$$

**Step 2:**

**Individual derivatives**

$$du = \frac{dh(x)}{dx} dx$$

$$df = \frac{dg(u)}{du} du$$



# Chain rule

$$f(x) = g \circ h(x)$$

**Step 1: Rewrite**

$$f(x) = g(u)$$

$$u = h(x)$$

**Step 2:**

**Individual derivatives**

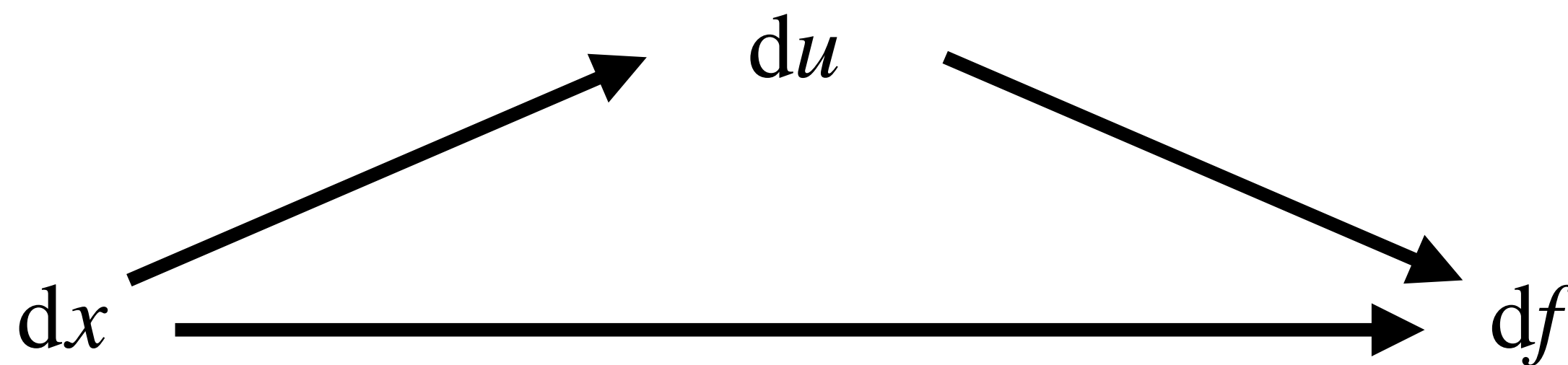
$$du = \frac{dh(x)}{dx} dx$$

$$df = \frac{dg(u)}{du} du$$

**Step 3:**

**Put together**

$$df = \frac{dg(u)}{du} \frac{dh(x)}{dx} dx$$



# Chain rule

$$f(x) = g \circ h(x)$$

## Example

$$f(x) = \cos(x^3)$$

# Chain rule

$$f(x) = g \circ h(x)$$

## Example

$$f(x) = \cos(x^3)$$

## Step 1: break into pieces

$$g(u) = \cos(u)$$

$$u = h(x) = x^3$$



# Chain rule

$$f(x) = g \circ h(x)$$

## Example

$$f(x) = \cos(x^3)$$

## Step 1: break into pieces

$$g(u) = \cos(u)$$

$$u = h(x) = x^3$$

## Step 2: calculate derivatives

$$dg(u) = -\sin(u)du$$

$$du = 3x^2dx$$

# Chain rule

$$f(x) = g \circ h(x)$$

## Example

$$f(x) = \cos(x^3)$$

### Step 1: break into pieces

$$g(u) = \cos(u)$$

$$u = h(x) = x^3$$

### Step 2: calculate derivatives

$$dg(u) = -\sin(u)du$$

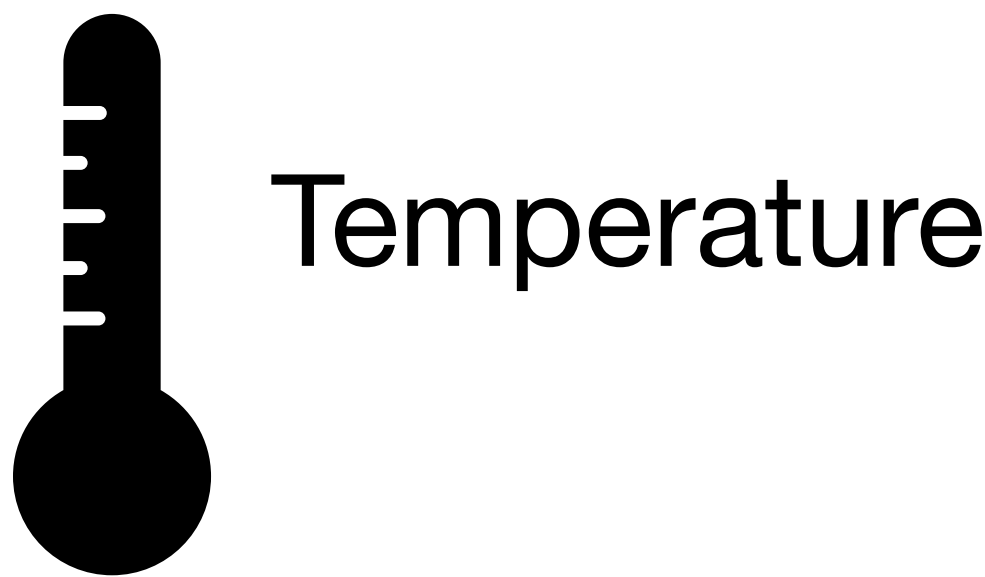
$$du = 3x^2dx$$

### Step 3: Put together

$$df(x) = -\sin(x^3)3x^2dx$$

# Multidimensional derivatives

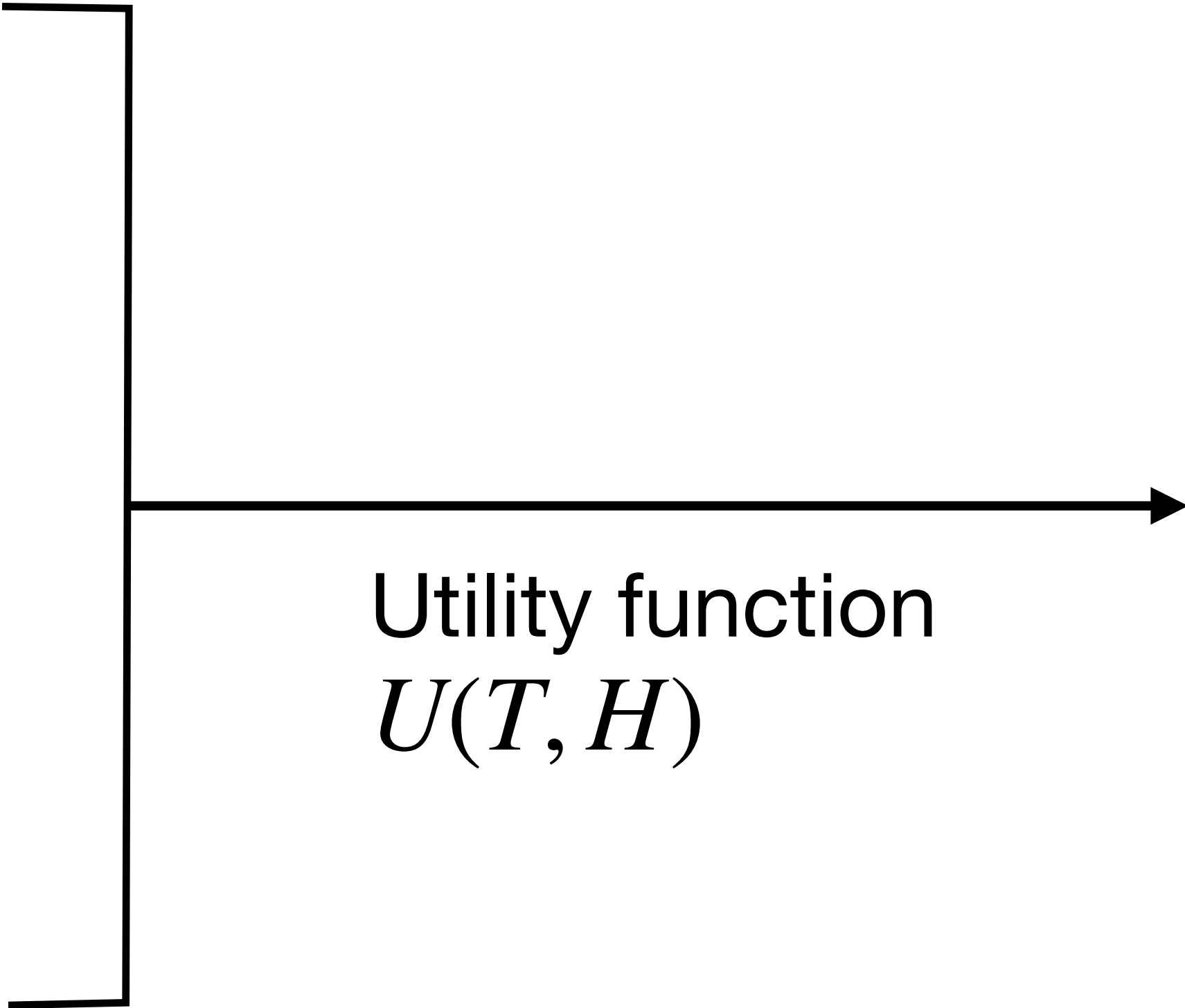
$$U : \mathbb{R}^2 \rightarrow \mathbb{R}^{225}$$



Temperature



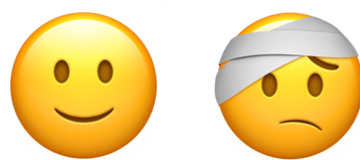
Humidity



## Question

Dimensionality of derivative?

“Utility” x 225



# Multidimensional derivatives

$$U : \mathbb{R}^2 \rightarrow \mathbb{R}^{225}$$

$$x = (T, H)$$

$$\frac{dU}{dx} = \begin{bmatrix} \frac{dU_1}{dx_1} & \frac{dU_1}{dx_2} \\ \frac{dU_2}{dx_1} & \frac{dU_2}{dx_2} \\ \vdots & \vdots \\ \frac{dU_n}{dx_1} & \frac{dU_n}{dx_2} \end{bmatrix}$$

# Multidimensional derivatives

$$f: \mathbb{R}^m \rightarrow \mathbb{R}^n$$

## Question

Dimensionality of derivative?

# Multidimensional derivatives

$$f: \mathbb{R}^m \rightarrow \mathbb{R}^n$$

## Question

Dimensionality of derivative?

The **Jacobian** matrix

$m$  columns

$$\frac{df}{dx} = \begin{bmatrix} \frac{df_1}{dx_1} & \frac{df_1}{dx_2} & \cdots & \frac{df_1}{dx_m} \\ \frac{df_2}{dx_1} & \frac{df_2}{dx_2} & \cdots & \frac{df_2}{dx_m} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{df_n}{dx_1} & \frac{df_n}{dx_2} & \cdots & \frac{df_n}{dx_m} \end{bmatrix} \quad n \text{ rows}$$

# Multidimensional derivatives

$$f : \mathbb{R}^m \rightarrow \mathbb{R}^n$$

## Question

Dimensionality of derivative?

## The **Jacobian** matrix

$m$  columns

$$\frac{df}{dx} = \begin{bmatrix} \frac{df_1}{dx_1} & \frac{df_1}{dx_2}, \dots, \frac{df_1}{dx_m} \\ \frac{df_2}{dx_1} & \frac{df_2}{dx_2}, \dots, \frac{df_2}{dx_m} \\ \vdots & \vdots \\ \frac{df_n}{dx_1} & \frac{df_n}{dx_2}, \dots, \frac{df_n}{dx_m} \end{bmatrix}$$

$n$  rows

## Notation

$$D_x(f) : \mathbb{R}^m \rightarrow \mathbb{R}^{m \times n}$$

$$J_x(f) : \mathbb{R}^m \rightarrow \mathbb{R}^{m \times n}$$

$$\nabla(f) : \mathbb{R}^m \rightarrow \mathbb{R}^{m \times n}$$

# Practice

$$f(x) = [x_1^2 + 4x_3, 5x_2 + 6x_1^3]$$

$$f: \mathbb{R}^n \rightarrow \mathbb{R}^2$$

Function	Derivative
$y = x^n$	$y' = nx^{n-1}$
$y = \sin(x)$	$y' = \cos(x)$
$y = \cos(x)$	$y' = -\sin(x)$
$y = \ln(x)$	$y' = 1/x$
$y = e^x$	$y' = e^x$



Practice

$$f(x) = [x_1^2 + 4x_3, 5x_2 + 6x_1^3]$$

$$f: \mathbb{R}^n \rightarrow \mathbb{R}^2$$

$$D_x(f) : \mathbb{R}^n \rightarrow \mathbb{R}^{n \times 2}$$

$$\begin{bmatrix} \bullet & \bullet \\ \bullet & \bullet \\ 0 & 0 \\ \vdots & \vdots \\ 0 & 0 \end{bmatrix}$$

Function	Derivative
$y = x^n$	$y' = nx^{n-1}$
$y = \sin(x)$	$y' = \cos(x)$
$y = \cos(x)$	$y' = -\sin(x)$
$y = \ln(x)$	$y' = 1/x$
$y = e^x$	$y' = e^x$

# Finite difference approximation

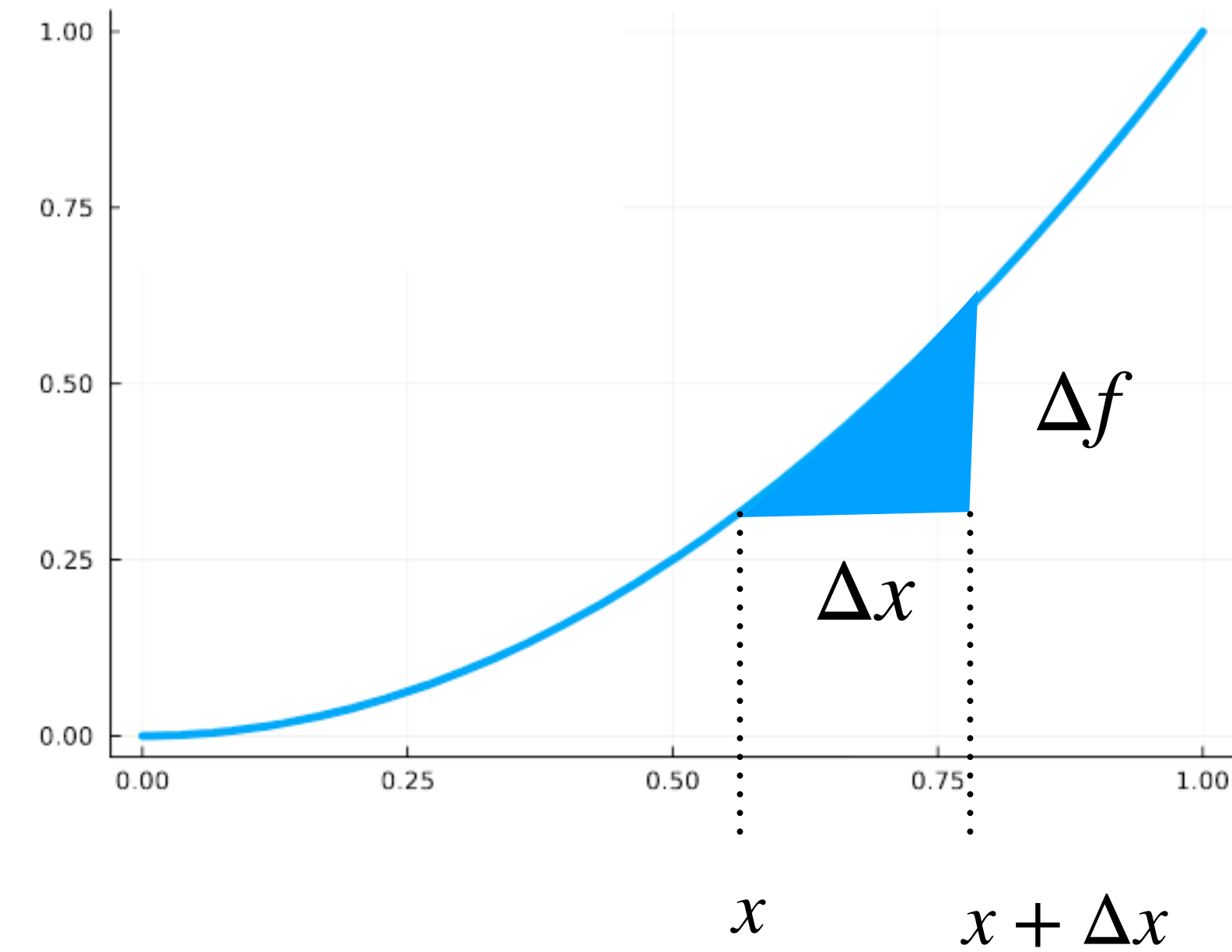
## *Scalar functions*

$$\frac{df}{dx} = \lim_{\Delta x \rightarrow 0} \frac{f(x + \Delta x) - f(x)}{\Delta x}$$

$$\frac{df}{dx} \approx \frac{f(x + \Delta x) - f(x)}{\Delta x}$$

*(Small  $\Delta x$ )*

$f(x)$



Don't know derivative? Approximate!

# Finite differences

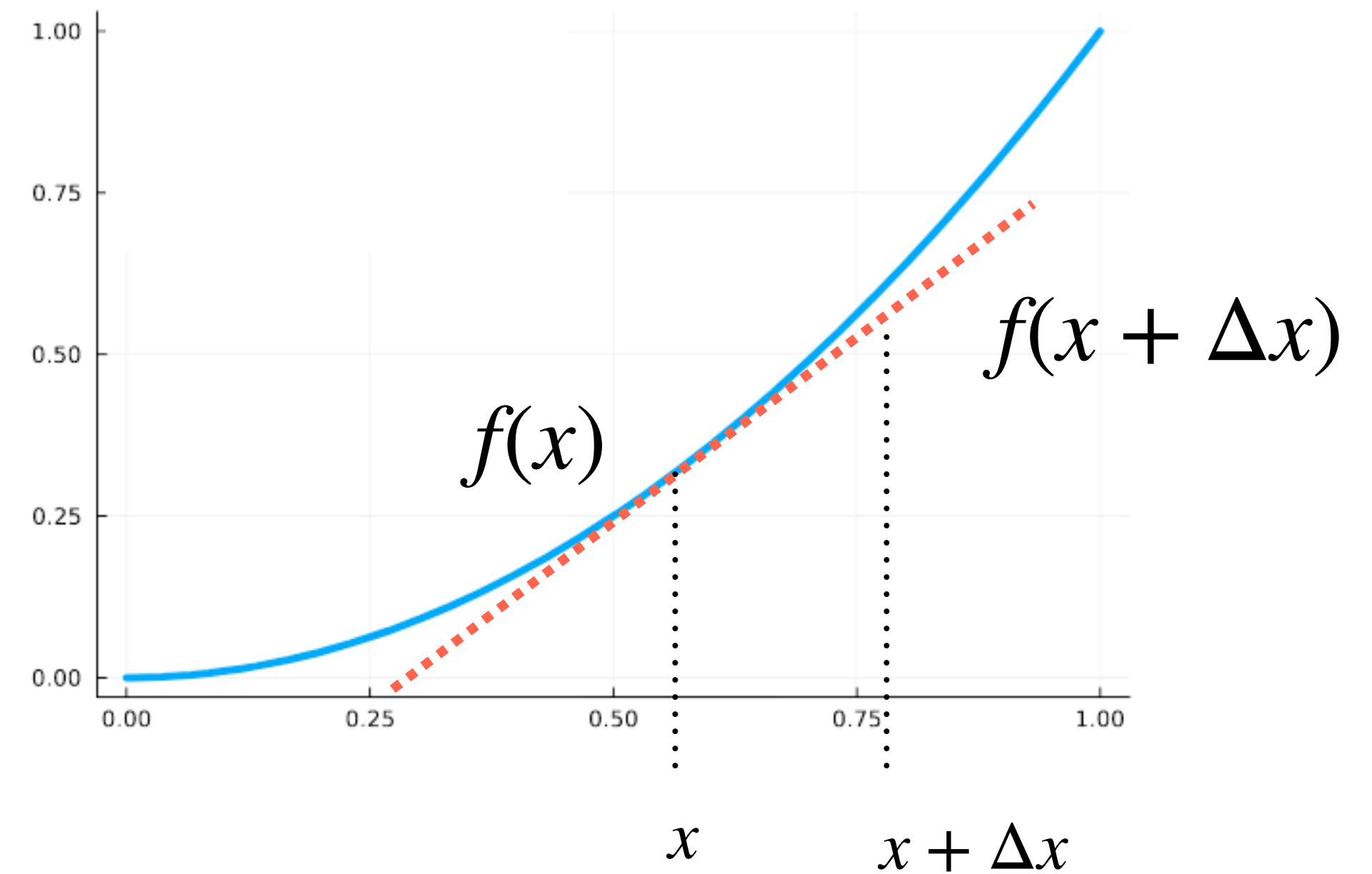
## *Scalar functions*

$$\frac{df}{dx} = \lim_{\Delta x \rightarrow 0} \frac{f(x + \Delta x) - f(x)}{\Delta x}$$

$$\frac{df}{dx} \approx \frac{f(x + \Delta x) - f(x)}{\Delta x}$$

*(Small  $\Delta x$ )*

Don't know function value? Approximate!



### Extrapolation

$$f(x + \Delta x) \approx \frac{df}{dx} \Delta x$$

Approximate this ← Know these

# Finite differences

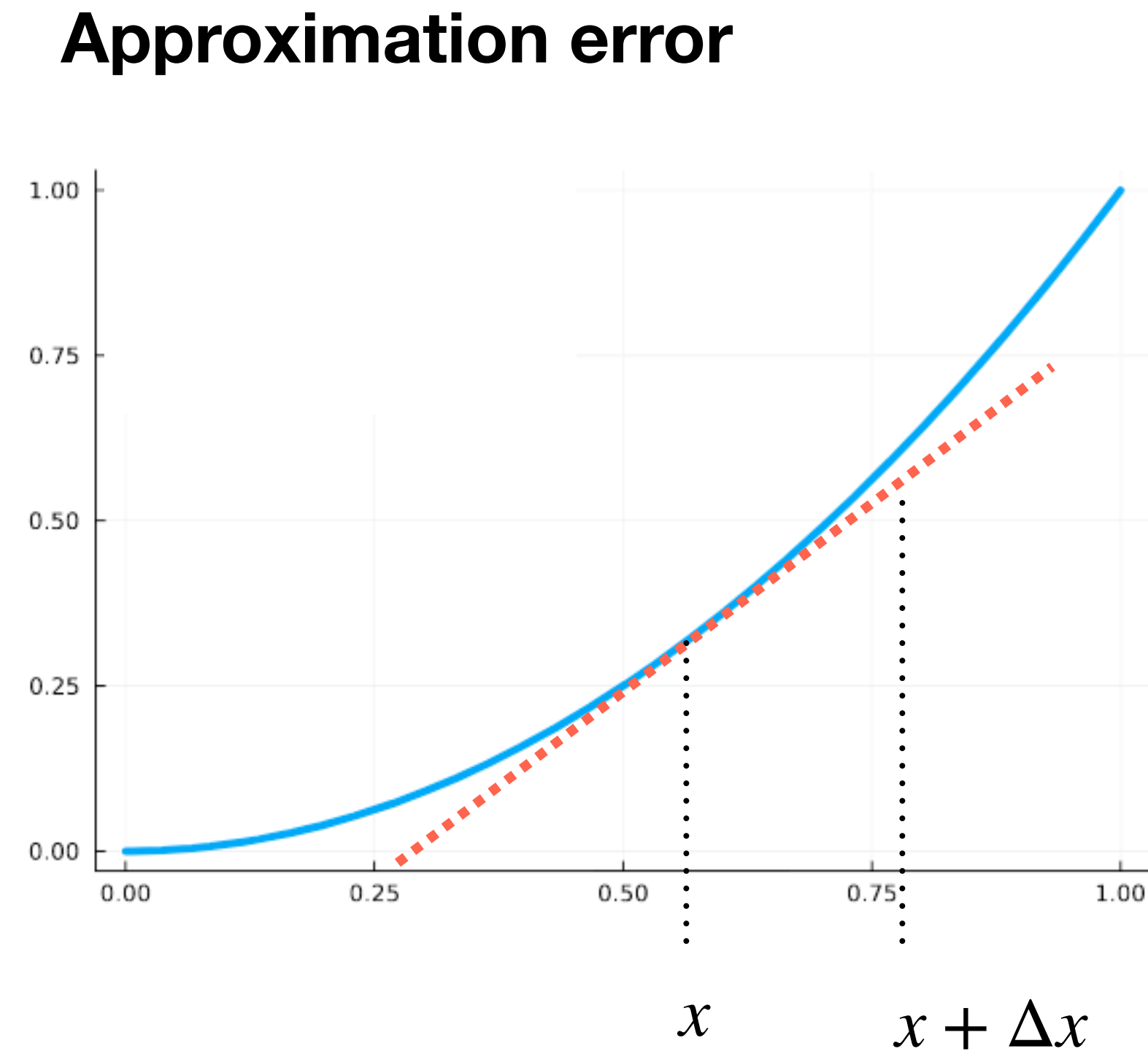
## *Approximation error*

$$\frac{df}{dx} = \lim_{\Delta x \rightarrow 0} \frac{f(x + \Delta x) - f(x)}{\Delta x}$$

$$\frac{df}{dx} \approx \frac{f(x + \Delta x) - f(x)}{\Delta x}$$

*(Small  $\Delta x$ )*

$f(x)$



### Issues

How small?

How accurate?

Numerical error:  $\frac{\text{small}}{\text{small}}$

# Multidimensional finite differences

$$f : \mathbb{R}^m \rightarrow \mathbb{R}^n$$

$$x = [x_1, x_2, \dots, x_n]$$

$$\frac{df_i}{dx_j} \approx \frac{f_i(x + \Delta x_j) - f_i(x)}{\|\Delta x_j\|_2}$$

$$\Delta x_j = [0, 0, \dots, \Delta, 0]$$

↑  
Entry  $j$

$m$  columns

$$\frac{df}{dx} = \begin{bmatrix} \frac{df_1}{dx_1} & \frac{df_1}{dx_2}, \dots, \frac{df_1}{dx_m} \\ \frac{df_2}{dx_1} & \frac{df_2}{dx_2}, \dots, \frac{df_2}{dx_m} \\ \vdots & \vdots \\ \frac{df_n}{dx_1} & \frac{df_n}{dx_2}, \dots, \frac{df_n}{dx_m} \end{bmatrix}$$

$n$  rows

Must take  $n \times m$  finite differences

# Example

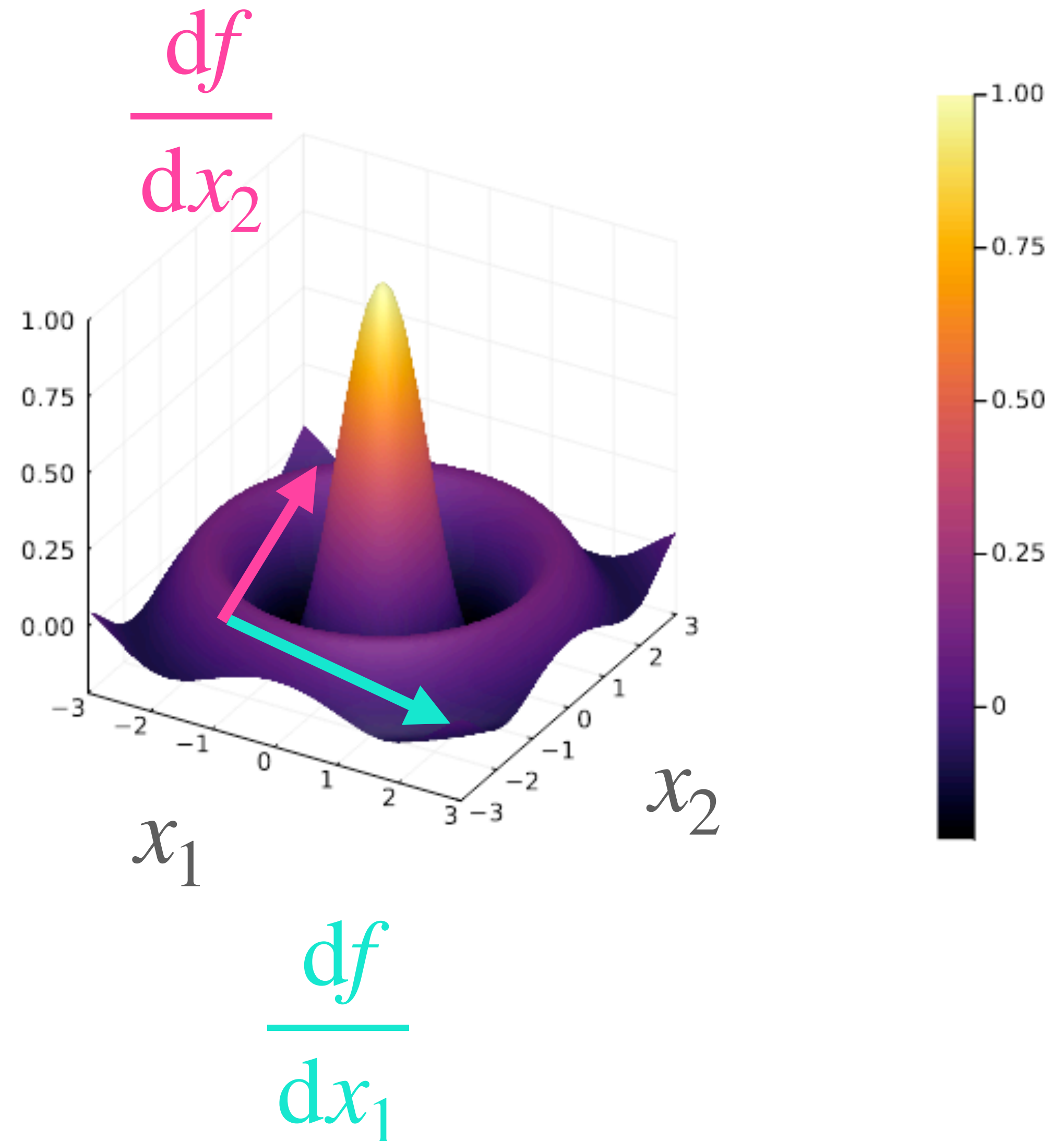
$$f: \mathbb{R}^2 \rightarrow \mathbb{R}$$

$$\frac{df_i}{dx_j} \approx \frac{f_i(x + \Delta x_j) - f_i(x)}{\|\Delta x_j\|_2}$$

$$\Delta x_1 = 0.01[1,0]$$

$$\Delta x_2 = 0.01[0,1]$$

$f(x_1, x_2)$



# Example

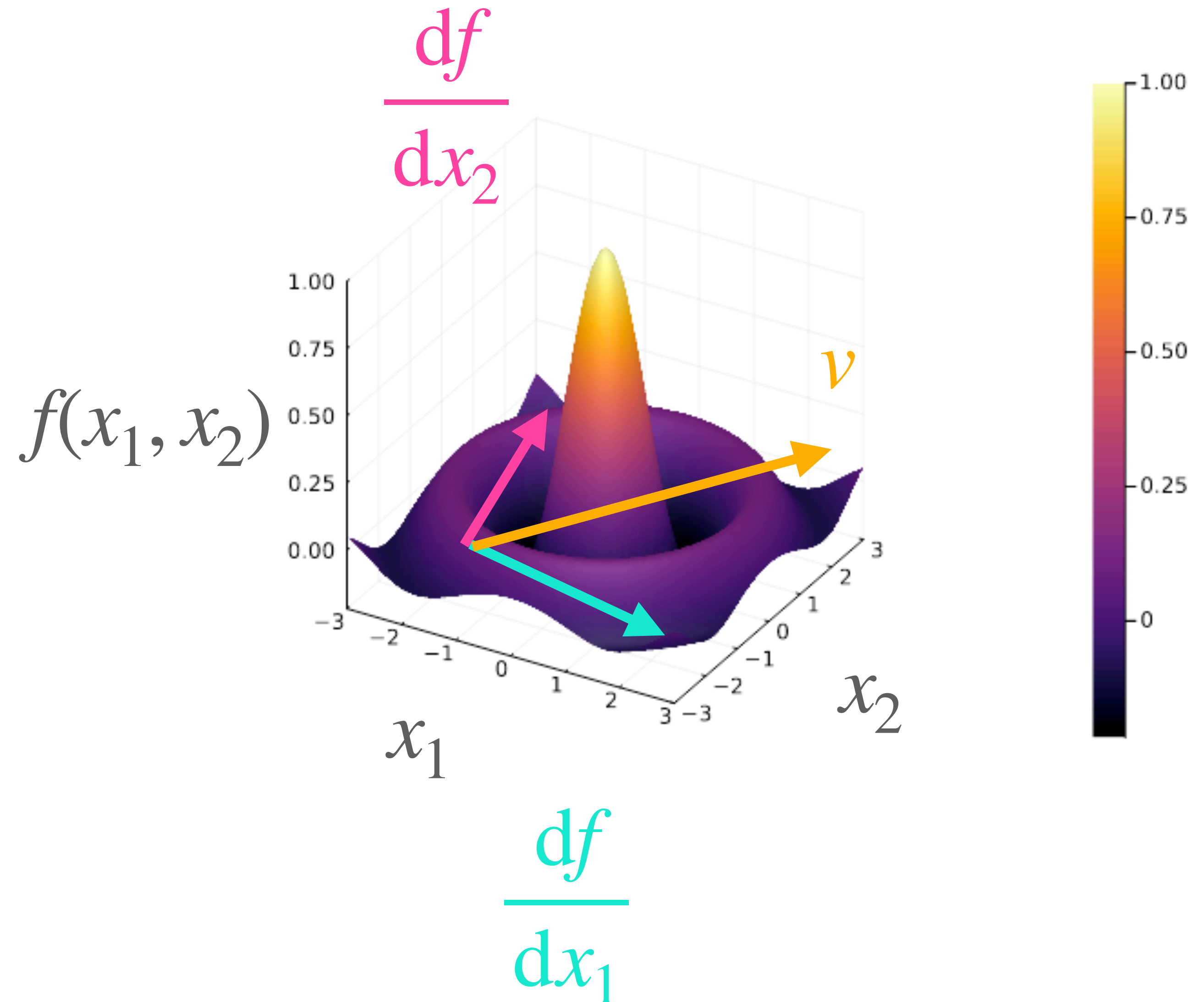
$$f: \mathbb{R}^2 \rightarrow \mathbb{R}$$

$$\frac{df_i}{dx_j} \approx \frac{f_i(x + \Delta x_j) - f_i(x)}{\|\Delta x_j\|_2}$$

$$\Delta x_1 = 0.01[1,0]$$

$$\Delta x_2 = 0.01[0,1]$$

$$v = 3\Delta x_1 + 2\Delta x_2$$
$$f(x + v)?$$



# Example

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}$$

$$\frac{df_i}{dx_j} \approx \frac{f_i(x + \Delta x_j) - f_i(x)}{\|\Delta x_j\|_2}$$

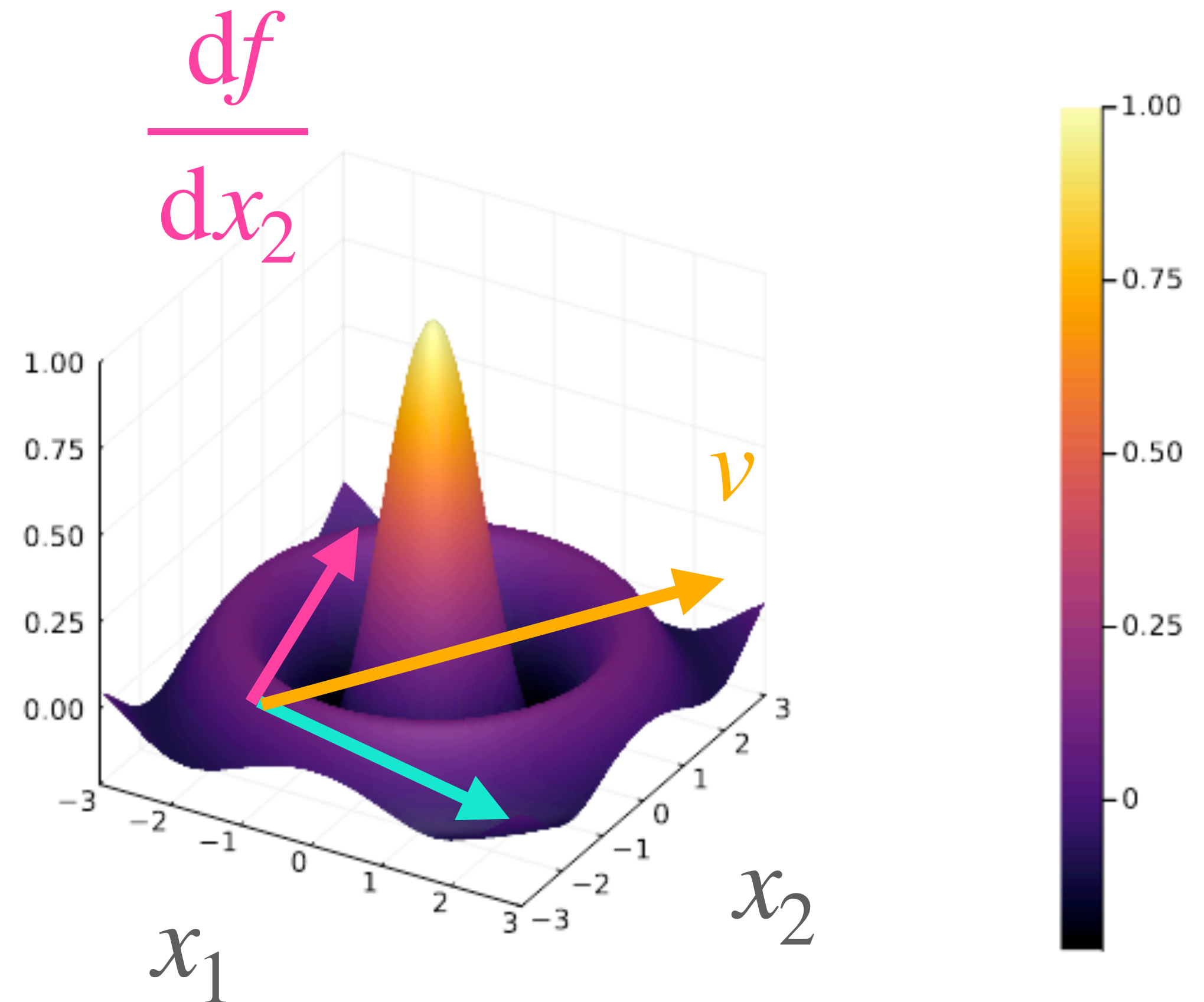
$$\Delta x_1 = 0.01[1, 0]$$

$$\Delta x_2 = 0.01[0, 1]$$

$$v = 3\Delta x_1 + 2\Delta x_2$$

$$f(x + v) = f(x) + 3\frac{df}{dx_1}\Delta x_1 + 2\frac{df}{dx_2}\Delta x_2$$

$f(x_1, x_2)$





# Directional derivatives (more to come)

$$f: \mathbb{R}^n \rightarrow \mathbb{R}$$

$$f(x + v)?$$

$$v = [v_1, v_2, \dots, v_n]$$

$$\frac{df}{dx} = [\bullet \quad \bullet \quad \dots \quad \bullet]$$

$$f(x + v) \approx f(x) + \sum_{i=1}^n v_i \frac{df}{dx_i}$$

# Directional derivatives (more to come)

$$f: \mathbb{R}^n \rightarrow \mathbb{R}$$

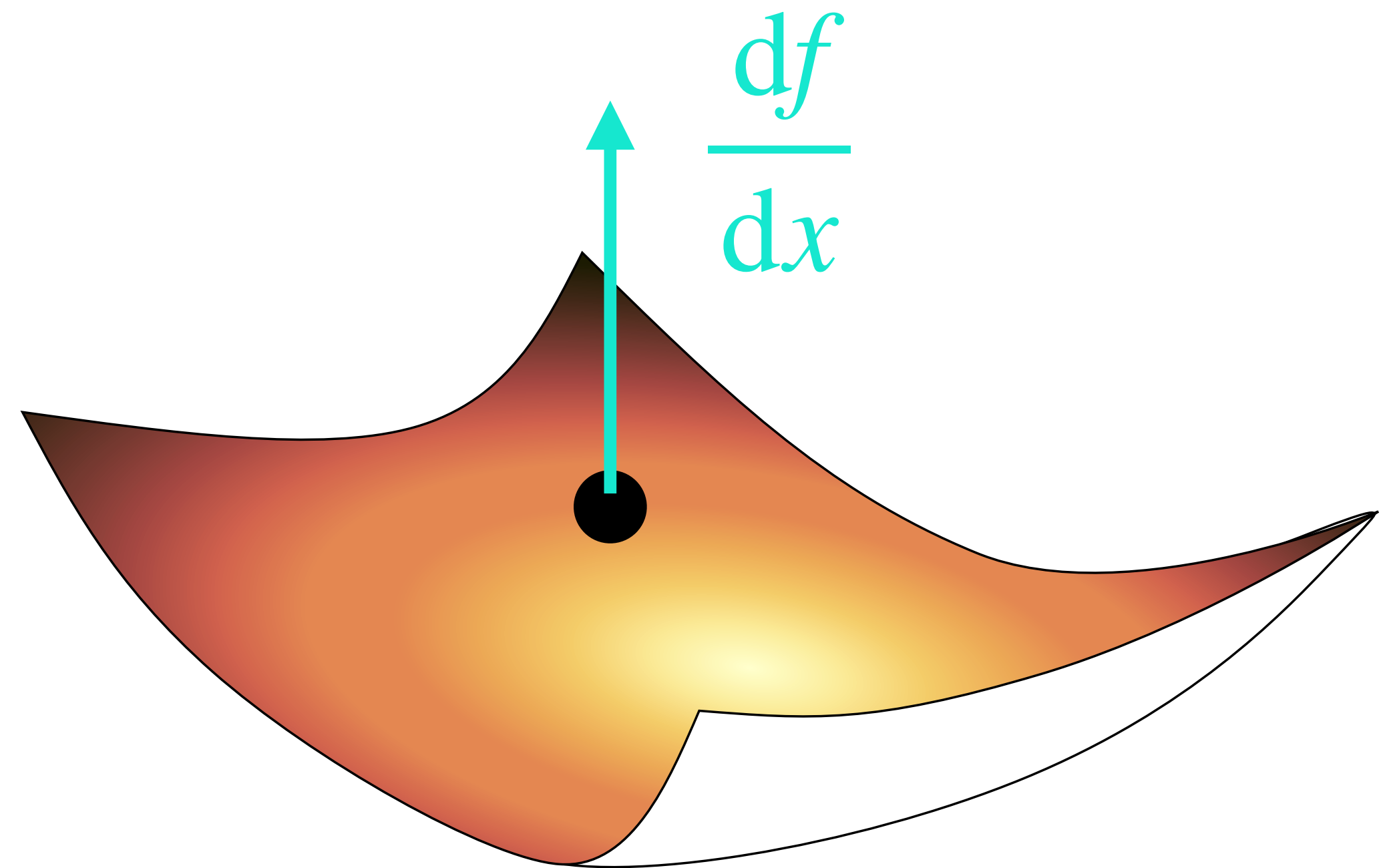
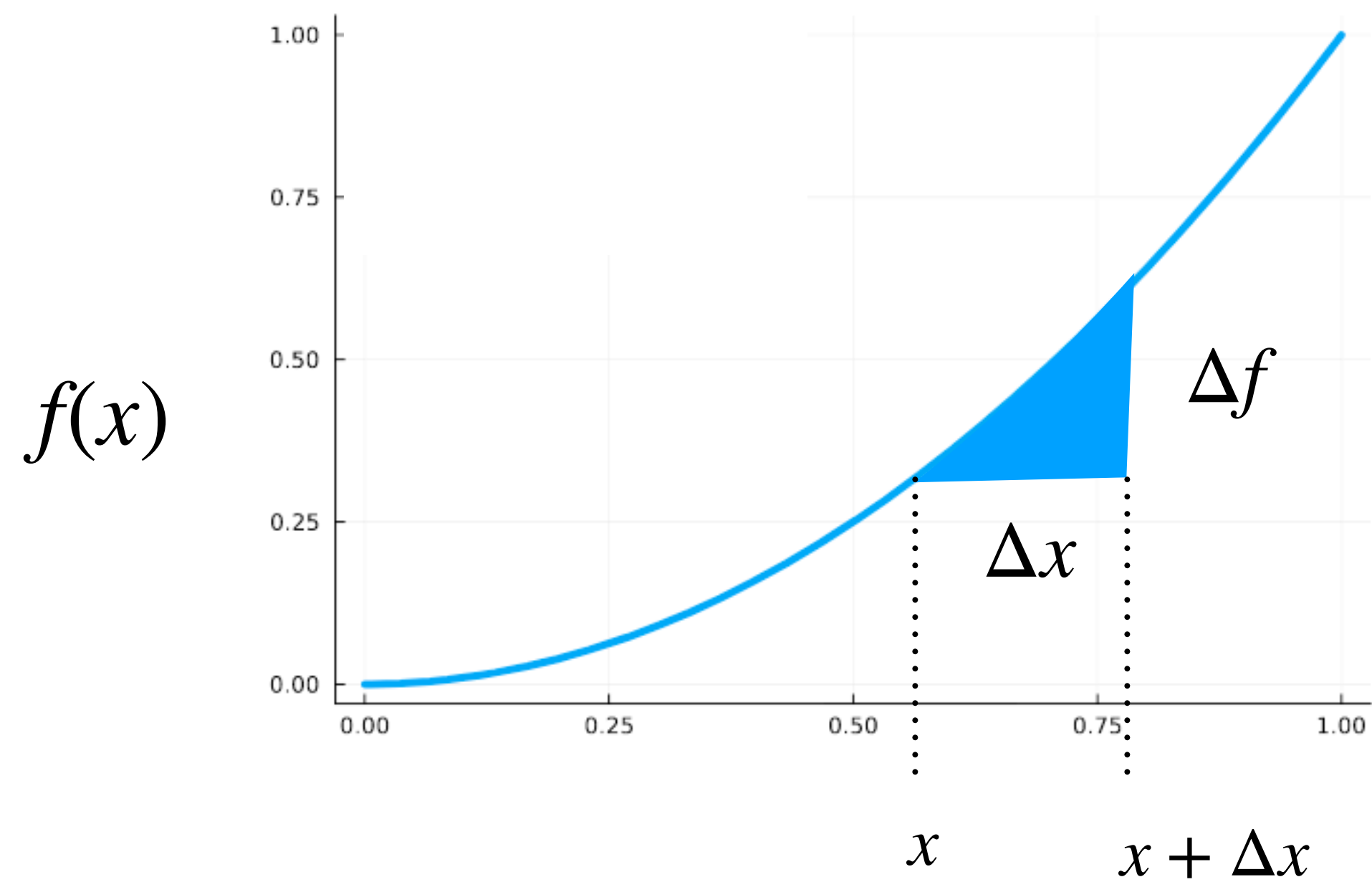
$$v = [v_1, v_2, \dots, v_n]$$

$$\frac{df}{dx} = [\bullet \quad \bullet \quad \dots \quad \bullet]$$

$$f(x + v) \approx f(x) + v^T \frac{df}{dx}$$

Dot product!

# Visualising the multidimensional derivative



$$f(x + v) \approx f(x) + v^T \frac{df}{dx}$$
$$v = \frac{df}{dx} ?$$