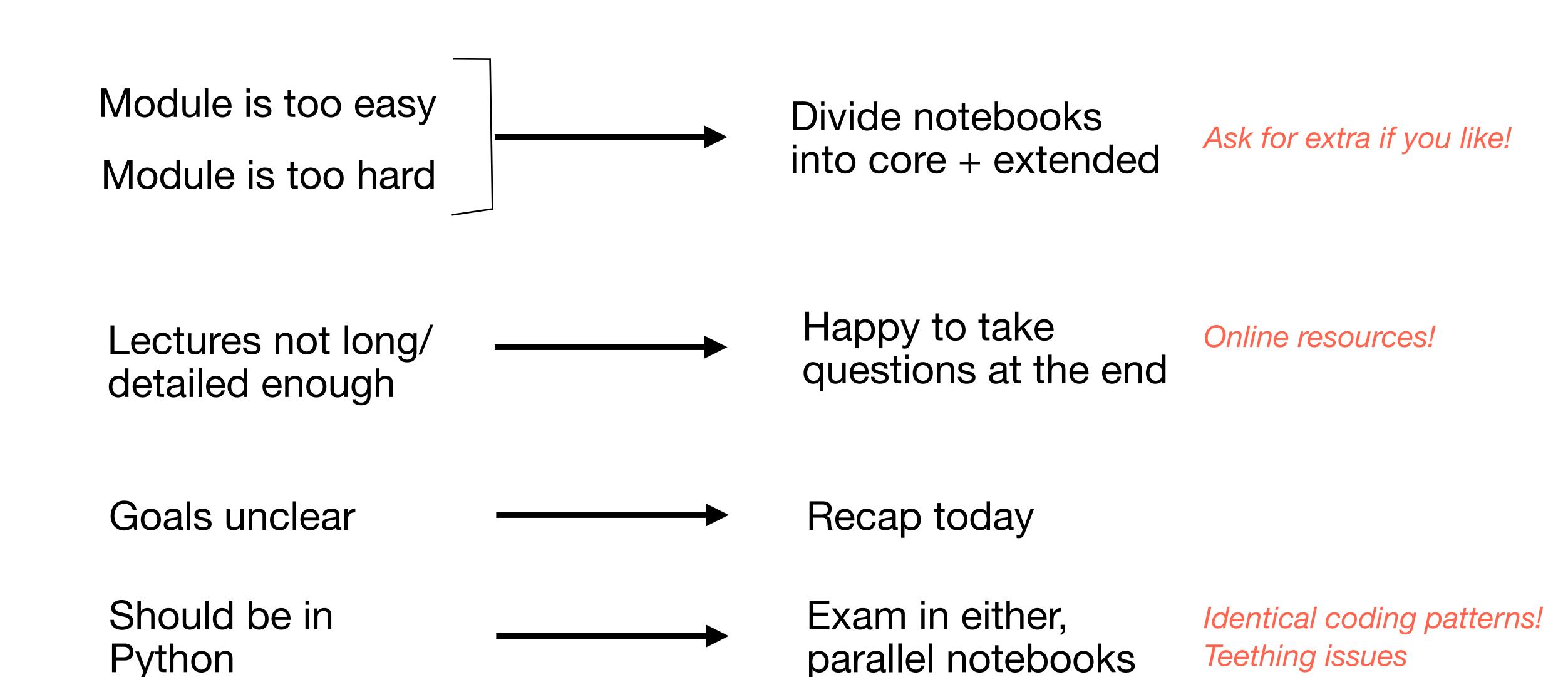
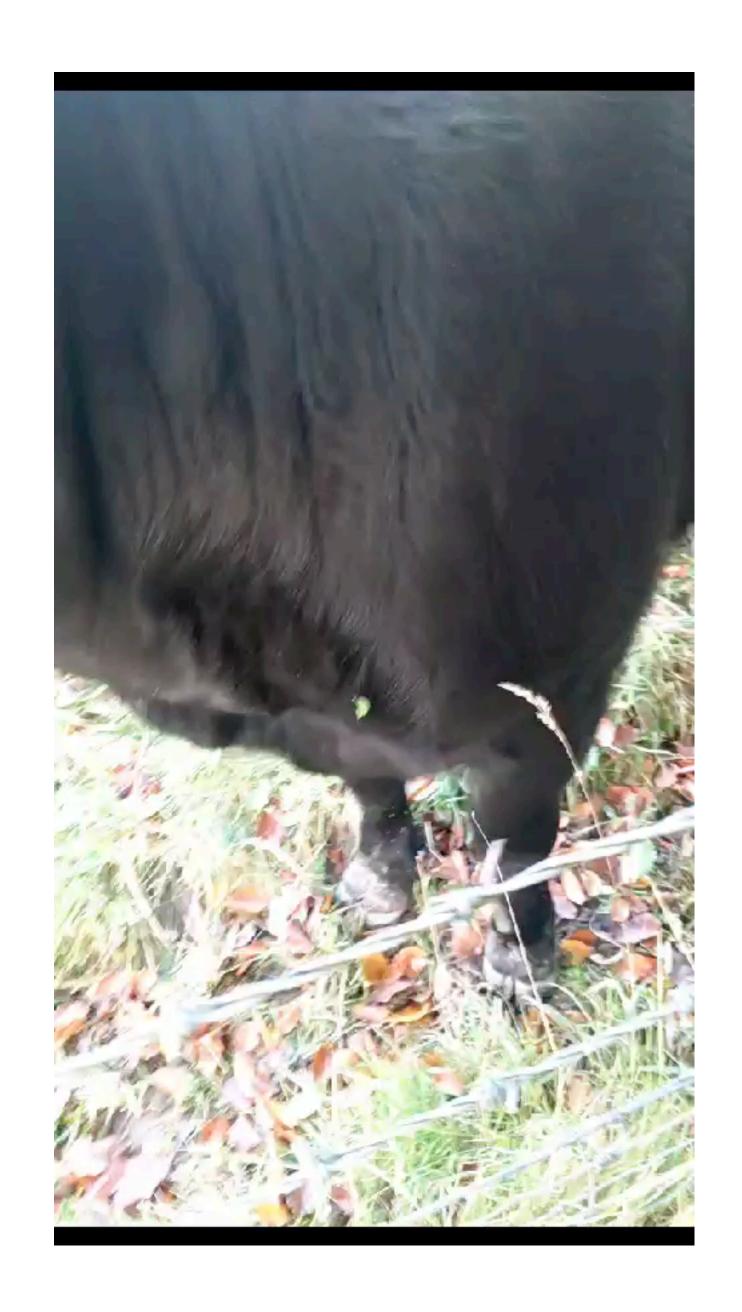
# Week 8

Mathematics and Computational Methods for Complex Systems, 2023-2024

## Mid module feedback

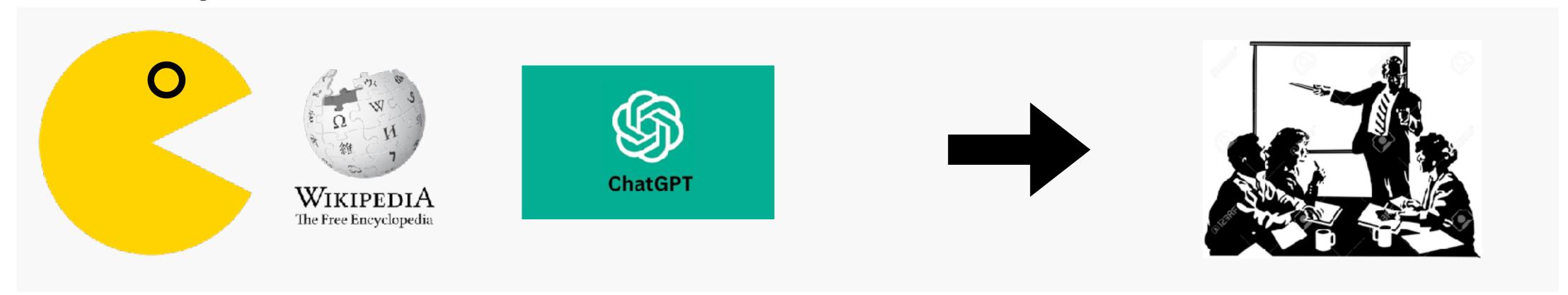


# Reminder on course goals



# Reminder on course goals

### 21st century life



How to learn/communicate/use/think with mathematical concepts



Learn maths all of it!



## Exam

Take home in December
Give back in January

Preparation?

Practice doing maths, not rote-learning

# **Dynamical systems**

Learning dynamical systems requires experimentation

Play lots with the code!

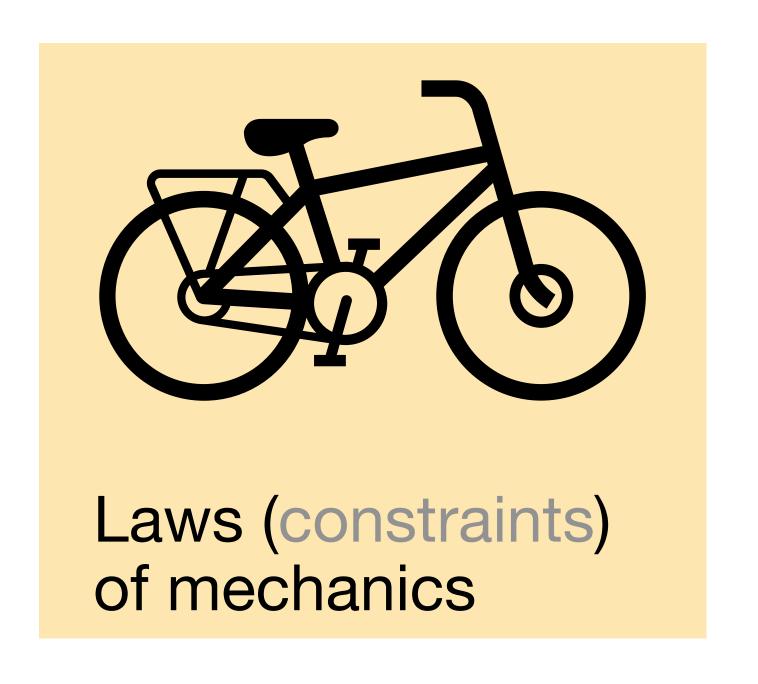
# **Goal today**

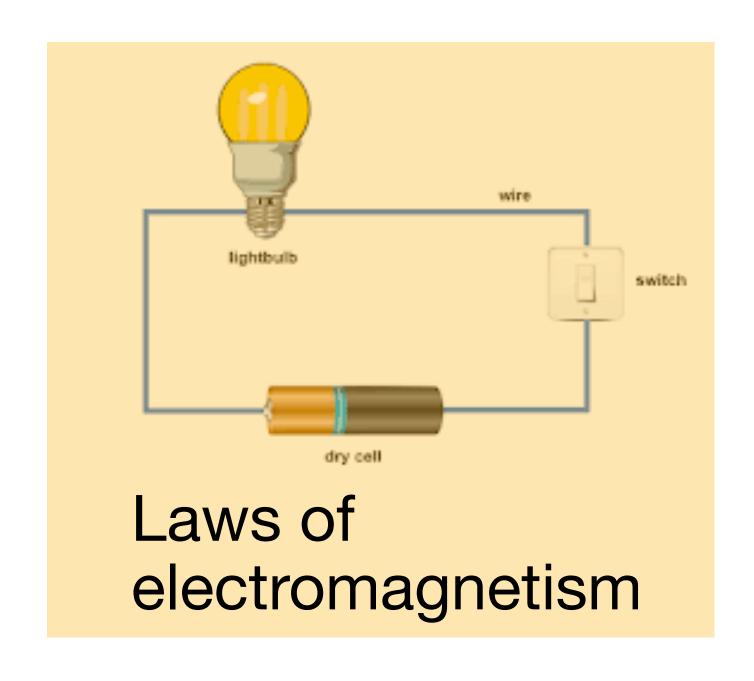
Model a pandemic!

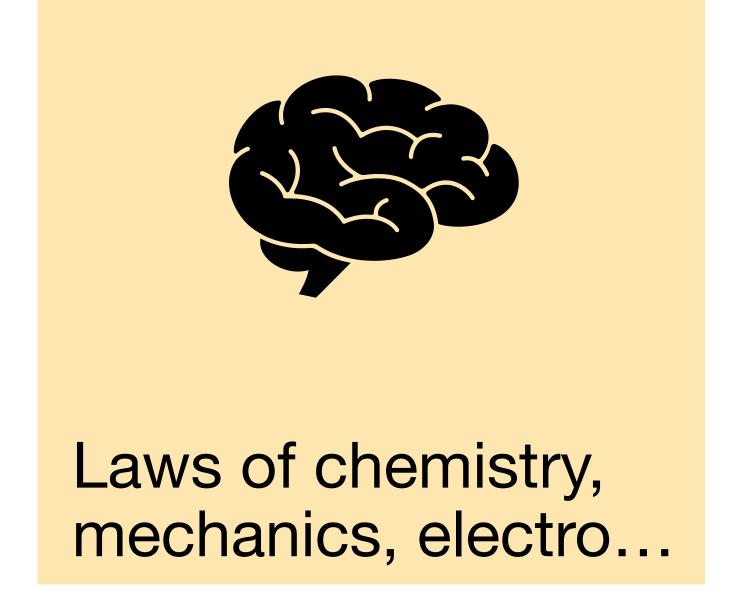
## What is a dynamical system

(Intuition)

Something that changes in time in a constrained way (so everything)







# What do we want to do with dynamical systems?







We need mathematical models of these systems

# How do we model dynamical systems?

Markov process

Markov process

Stochastic differential equation

Partial differential equation

Reaction rate network

In this course

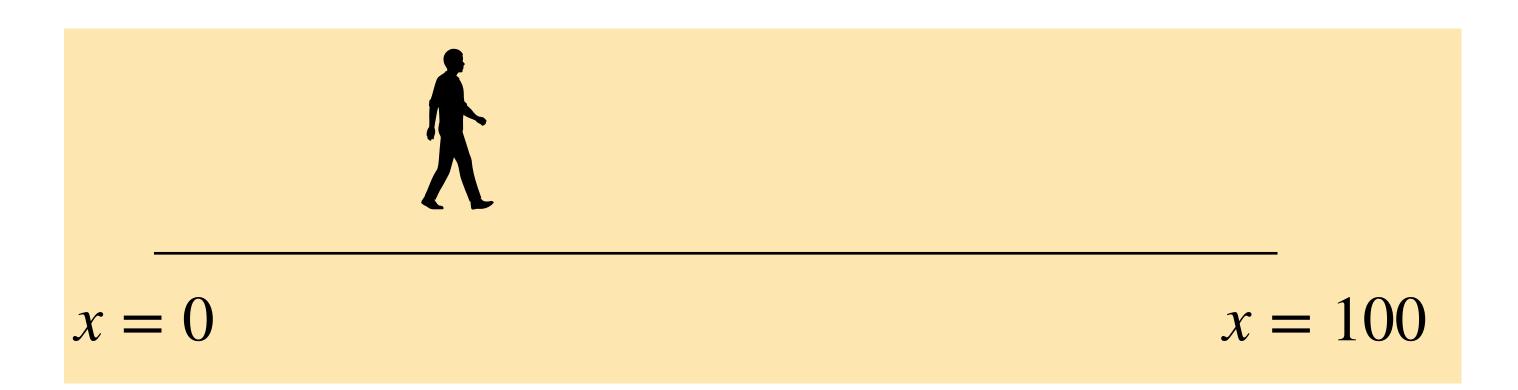
(Ordinary) differential equations

(Difference equations)

ODE

# Recap

Suppose I am walking with velocity 4m/s



What is x(t), my position as a function of time?

# Recap

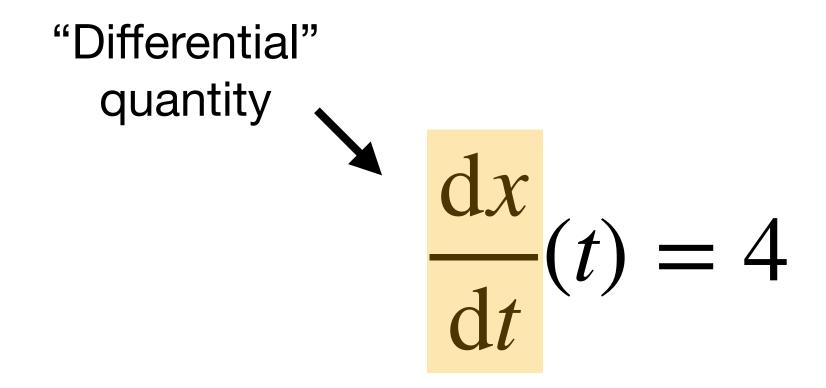
Velocity is rate of change of position with respect to time:

$$\frac{\mathrm{d}x}{\mathrm{d}t}(t)$$

Maths problem: need to solve

$$\frac{\mathrm{d}x}{\mathrm{d}t}(t) = 4$$

# This is a differential equation



Equations that include differential quantities (i.e. derivatives)

# What are we trying to do

Information on differential quantity over all time

$$\frac{\mathrm{d}x}{\mathrm{d}t}(t) = 4$$

"Solution"

Information on quantity itself over all time

$$x(t) = ?$$

# Solution terminology

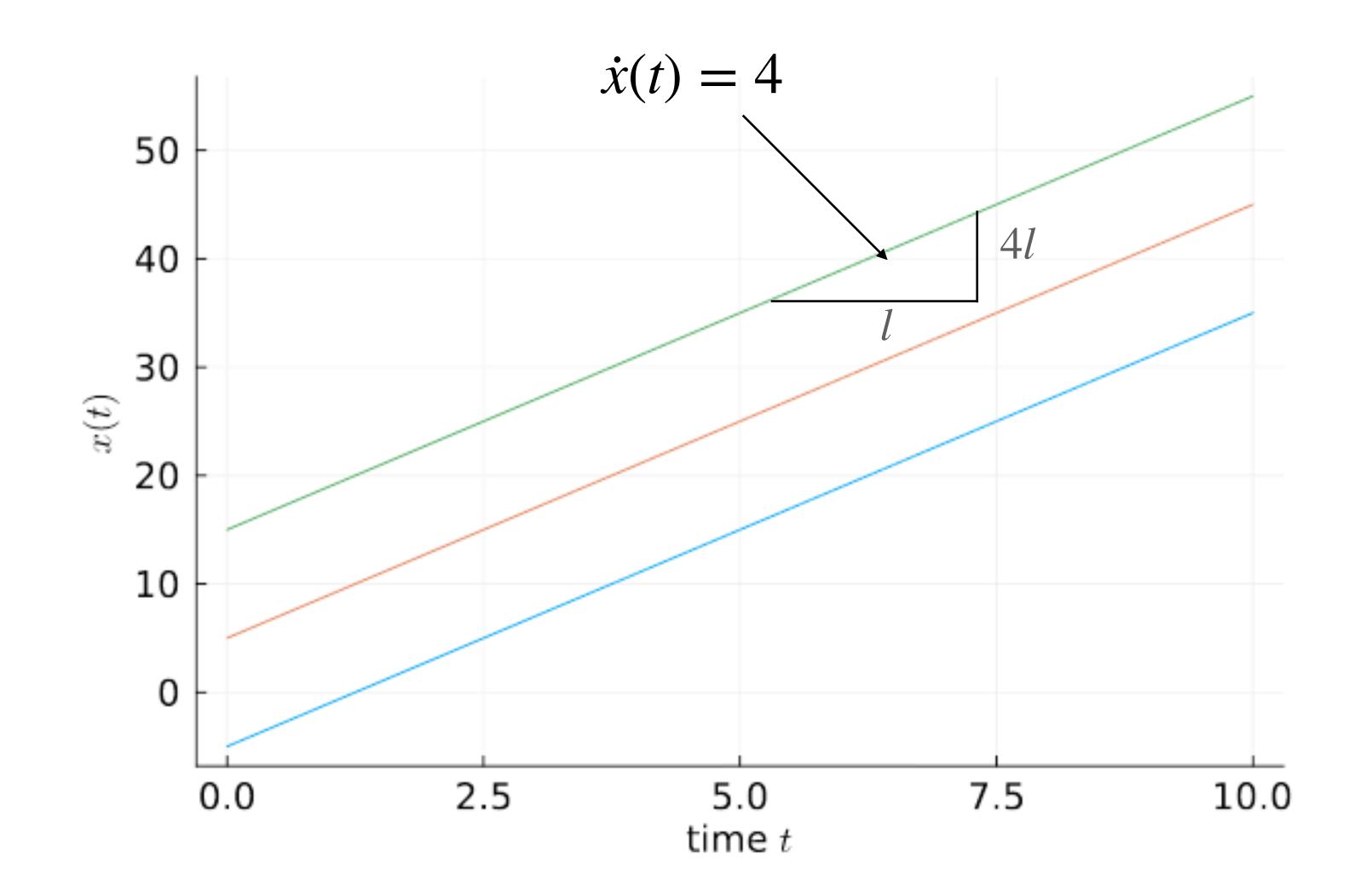
### **General solution**

$$x(t) = 4t + C$$
Constant of integration

### **Particular solution**

$$x(t) = 4t + 15$$

"Integrating the differential equation"



# Initial conditions allow us to pick a particular solution

#### **General solution**

$$x(t) = 4t + C$$

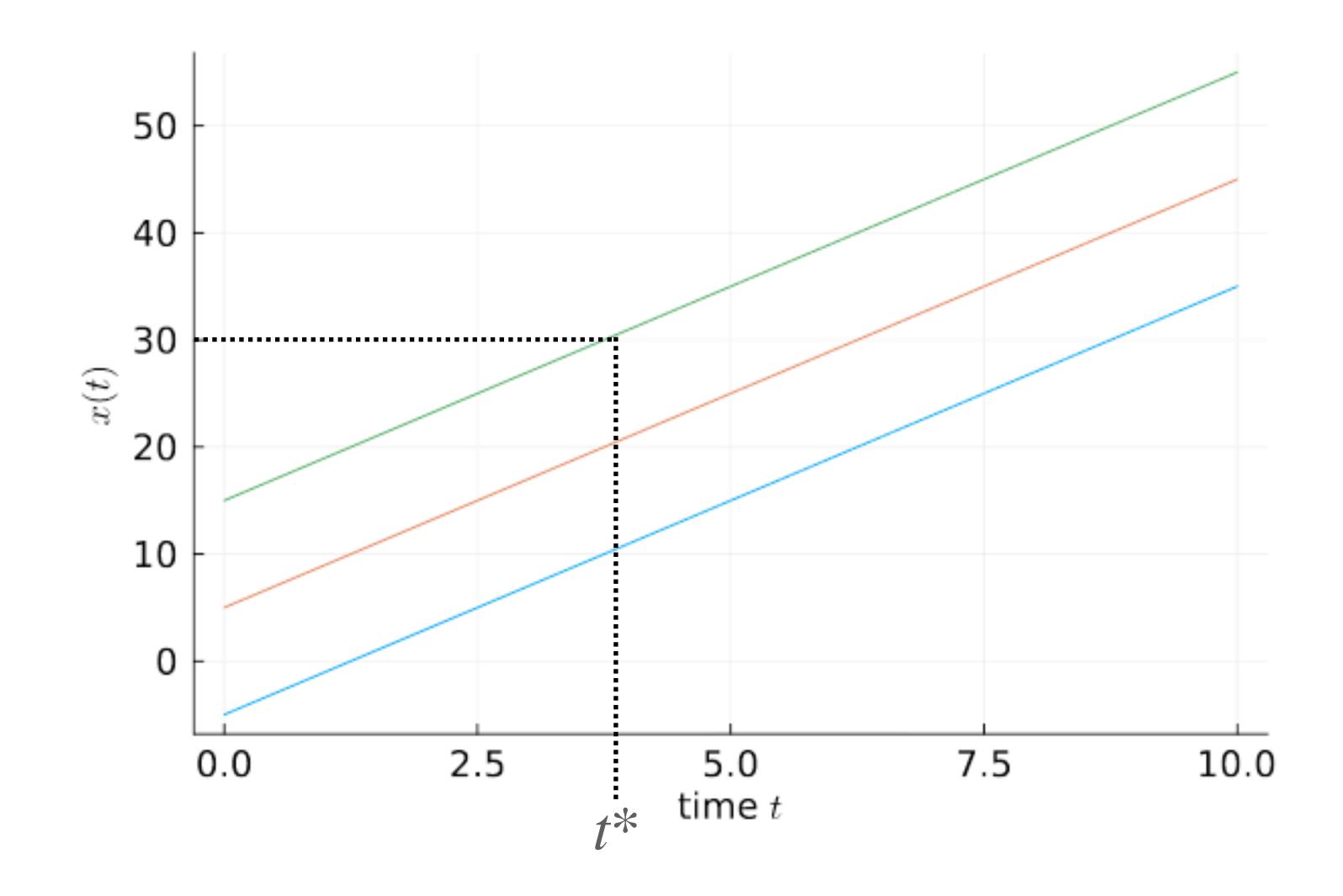
#### Particular solution

$$x(t) = 4t + 15$$

### **Initial conditions**

$$x(t^*) = 40$$

(Usually  $t^* = 0$ )



# What it means to solve a Differential Equation

### How something changes

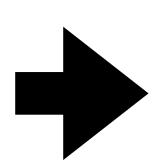
Suppose I am walking with velocity 4m/s



What something is at

some time

Initial position is 2m



What something is

over all time

What is my position as a function of t?

# What it means to solve a Differential Equation

#### How something changes

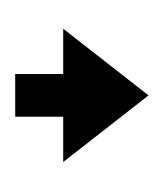
Suppose I am walking with velocity 4m/s



What something is at

some time

Initial position is 2m



### What something is

over all time

What is my position as a function of t?

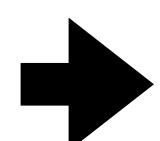
### **Differential equation**

$$\dot{x}(t) = 4$$



"Initial Condition"

$$x(0) = 15$$



#### **Solution:**

**function** of time

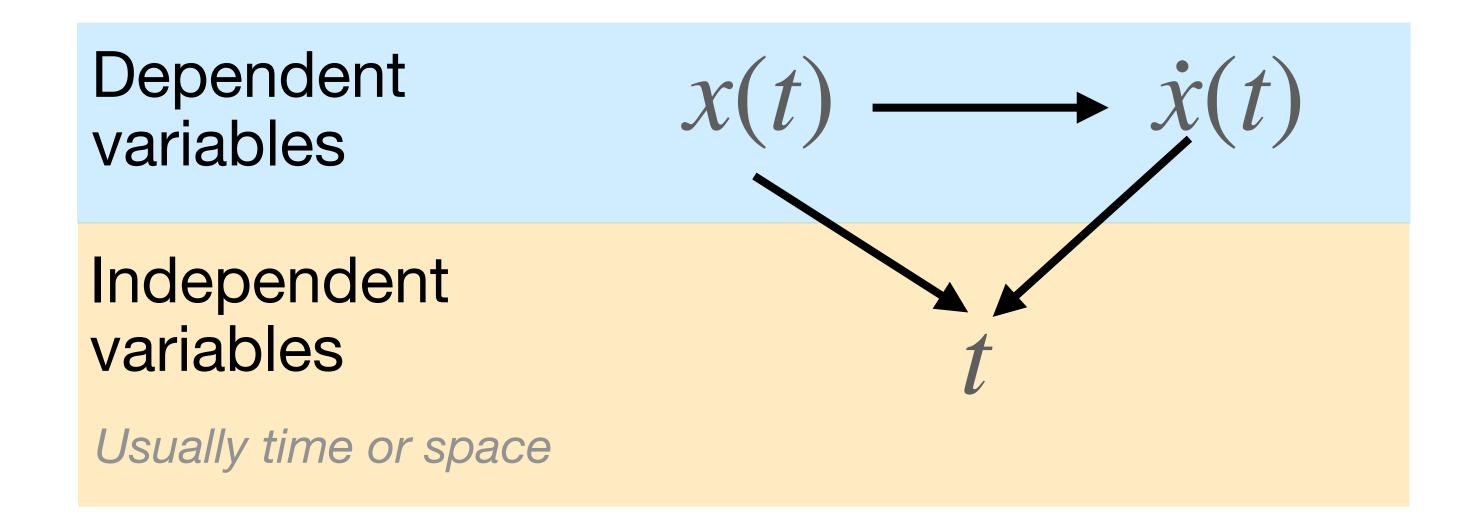
$$x(t) = 4t + 15$$

Also called an initial value problem

## Classification of variables

$$\dot{x}(t) = 4$$

### Variable dependencies



- Denominators in the derivatives

# Sketch this differential equation

$$\dot{x}(t) = x(t)$$

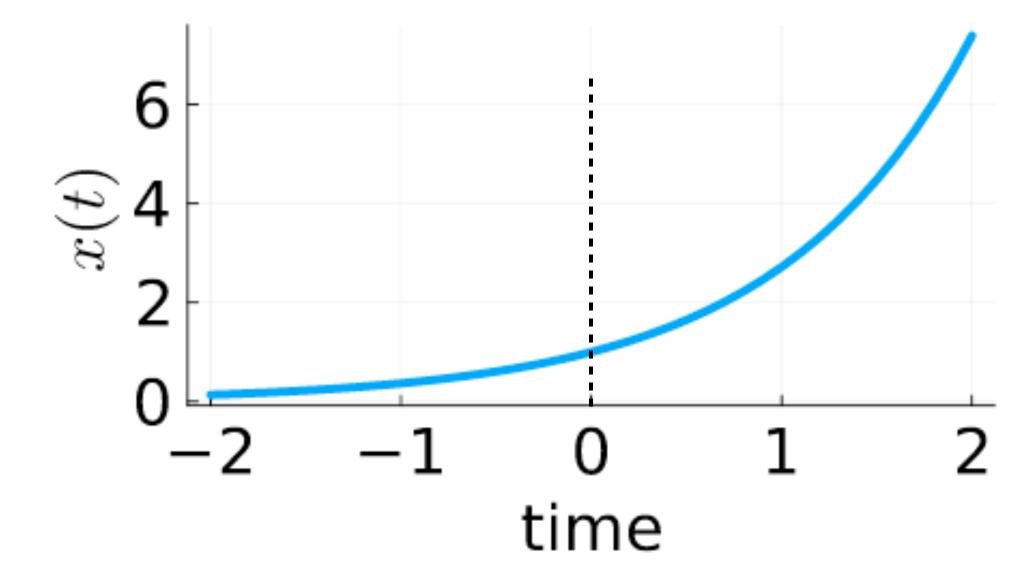
$$x(0) = 1$$

# Option 0: educated guesswork

# Important skill!

$$\dot{x}(t) = x(t)$$

$$x(0) = 1$$



Derivative starts positive, so function is increasing at zero

If function increases then derivative increases

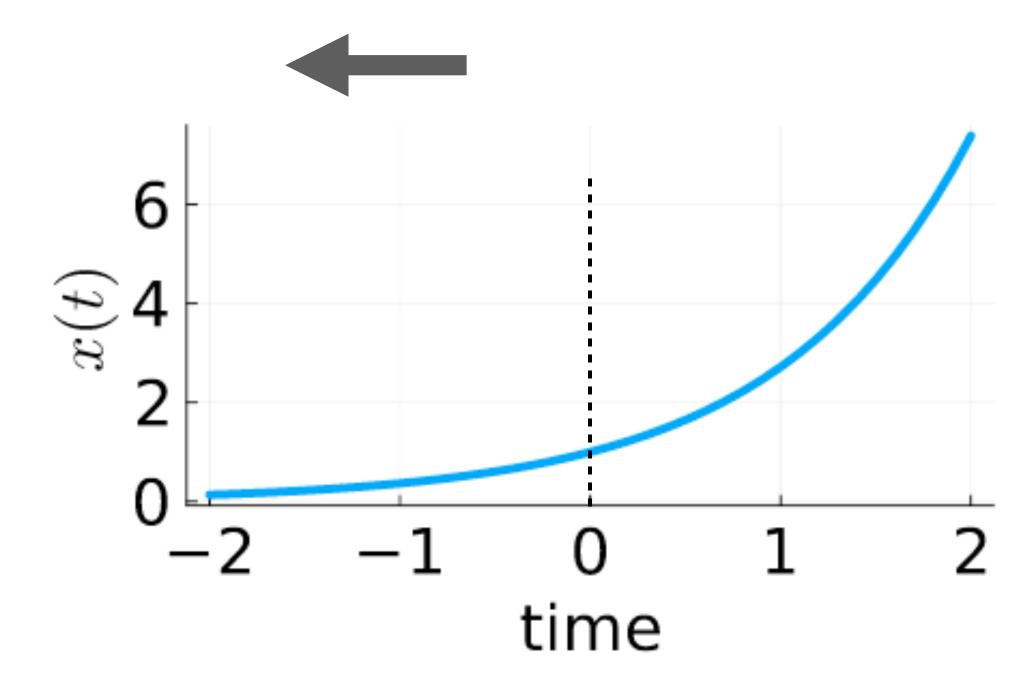
Positive feedback: function accelerates

# Option 0: educated guesswork

# Important skill!

$$\dot{x}(t) = x(t) \qquad x(0) = 1$$

$$\frac{\mathrm{d}x}{\mathrm{d}(-t)} = -\frac{\mathrm{d}x}{\mathrm{d}(t)} \quad \text{(chain rule)}$$



Derivative starts positive, so function is increasing at zero

If function increases then derivative increases

Positive feedback: function accelerates

# Sketch the same differential equation

...with different initial conditions

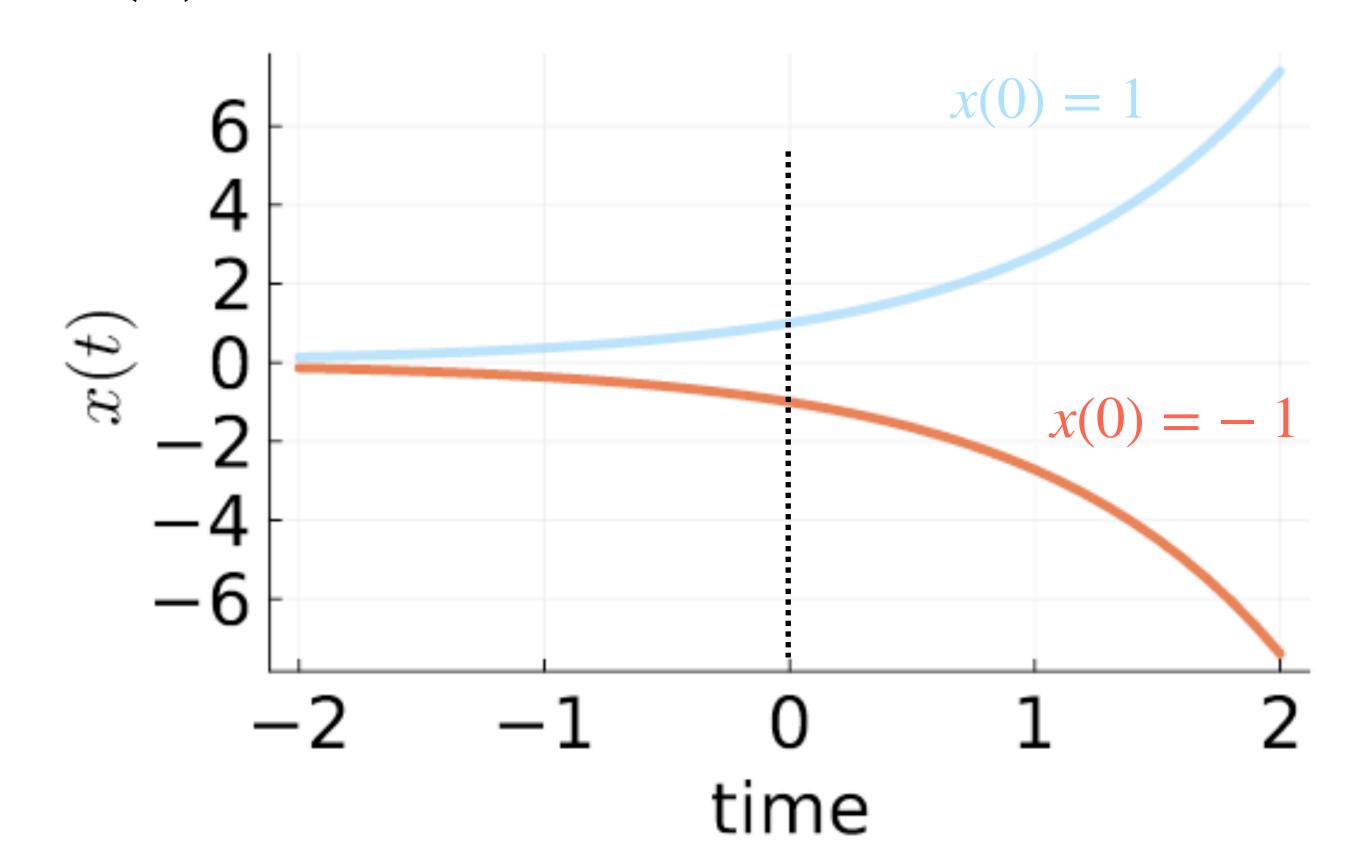
$$\dot{x}(t) = x(t)$$

$$x(0) = -1$$

# Small differences in initial conditions can have a big effect

$$\dot{x}(t) = x(t)$$

$$x(0) = -1$$



Derivative starts negative, so function is decreasing at zero

If function decreases then derivative decreases

Positive feedback: function accelerates

# Option 1: analytical solution

# Usually impossible

$$\frac{\mathrm{d}x}{\mathrm{d}t} = x(t)$$

$$x(0) = 1$$

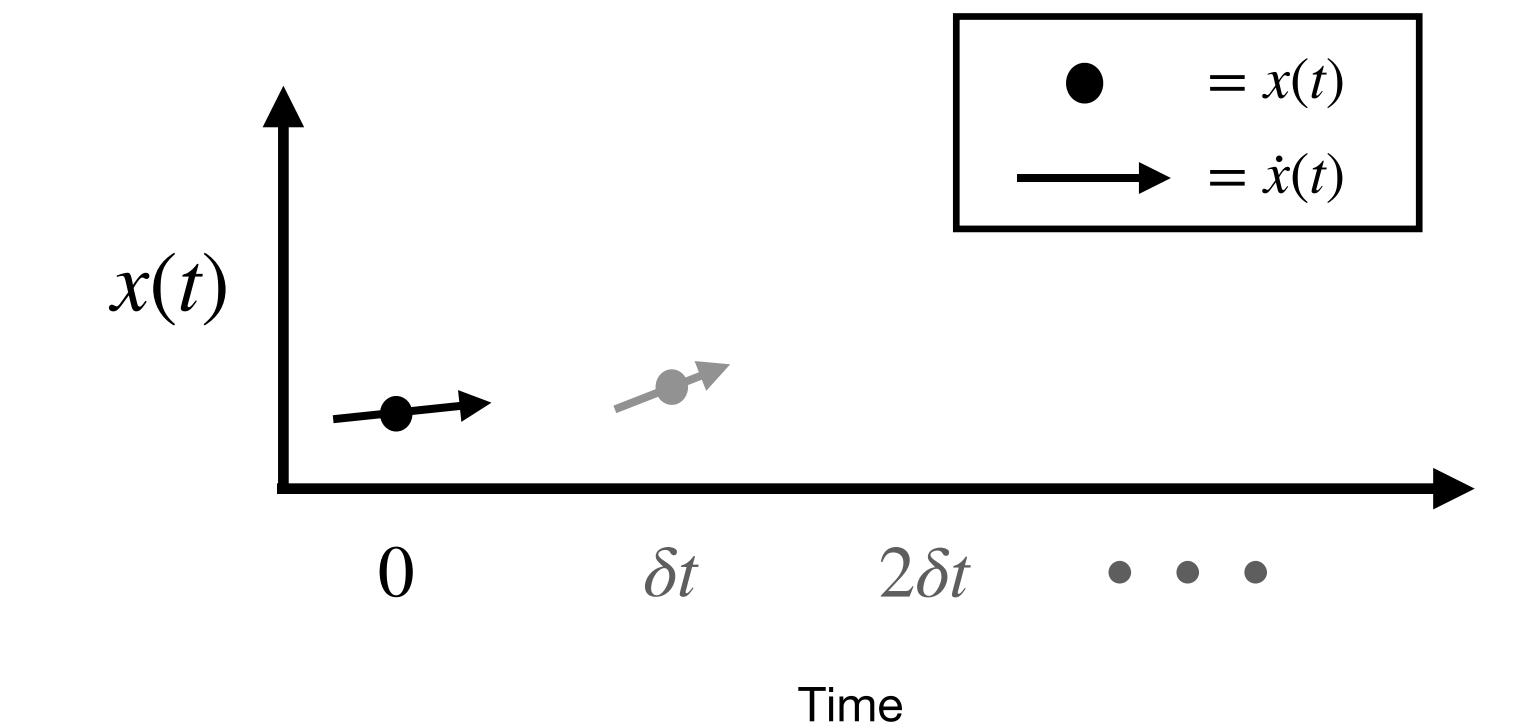
$$\Rightarrow \frac{1}{x(t)} dx = 1 dt$$

Constant of integration

$$\Rightarrow \ln(x(t)) = t + C$$

$$\Rightarrow x(t) = x(0)\exp(t)$$
$$(x(0) = \exp(C))$$

Predict  $x(t + \delta t)$  from x(t) and  $\dot{x}(t)$ 



Predict  $x(t + \delta t)$  from x(t) and  $\dot{x}(t)$ 

(Finite-difference approximation of derivative)

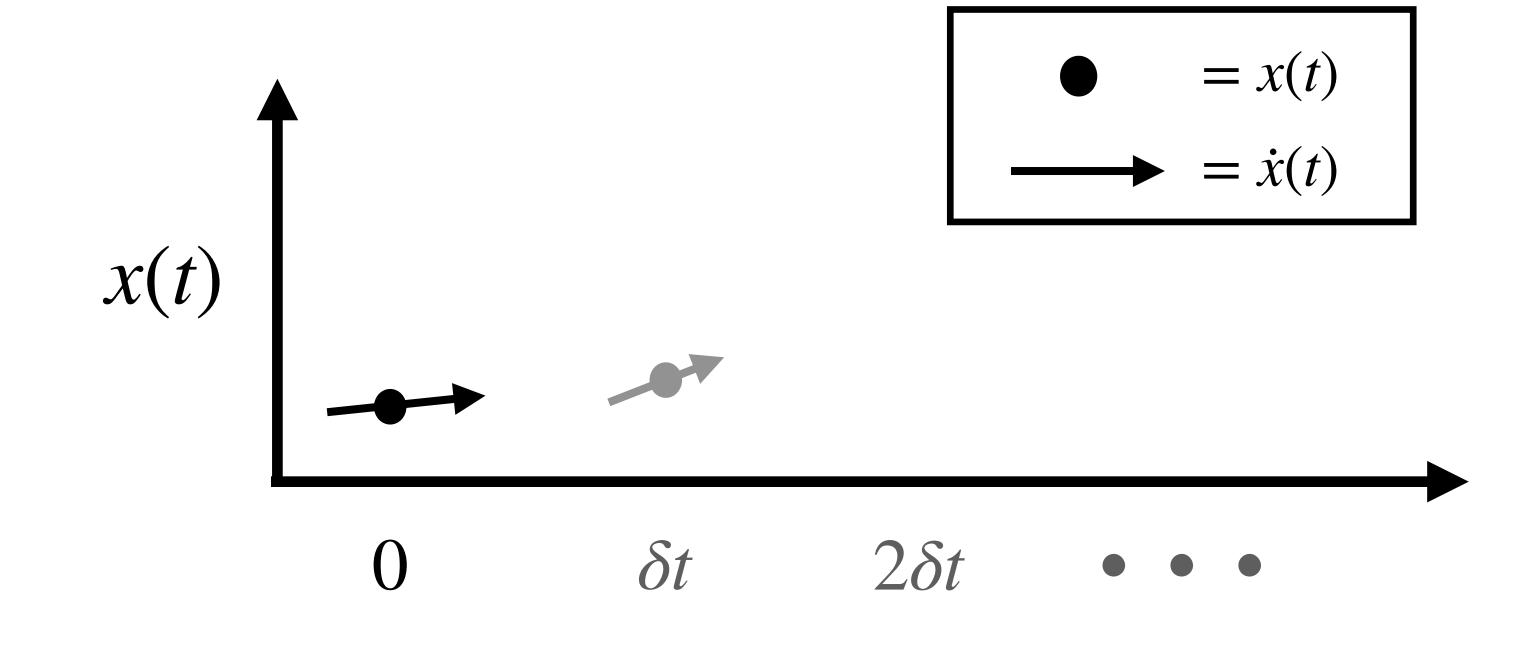
1. 
$$\dot{x}(t) \approx \frac{x(t + \delta t) - x(t)}{\delta t}$$

(Rearrange)

2. 
$$x(t + \delta t) \approx x(t) + (\delta t)\dot{x}(t)$$
Predict Know Know

Predict  $x(t + \delta t)$  from x(t) and  $\dot{x}(t)$ 

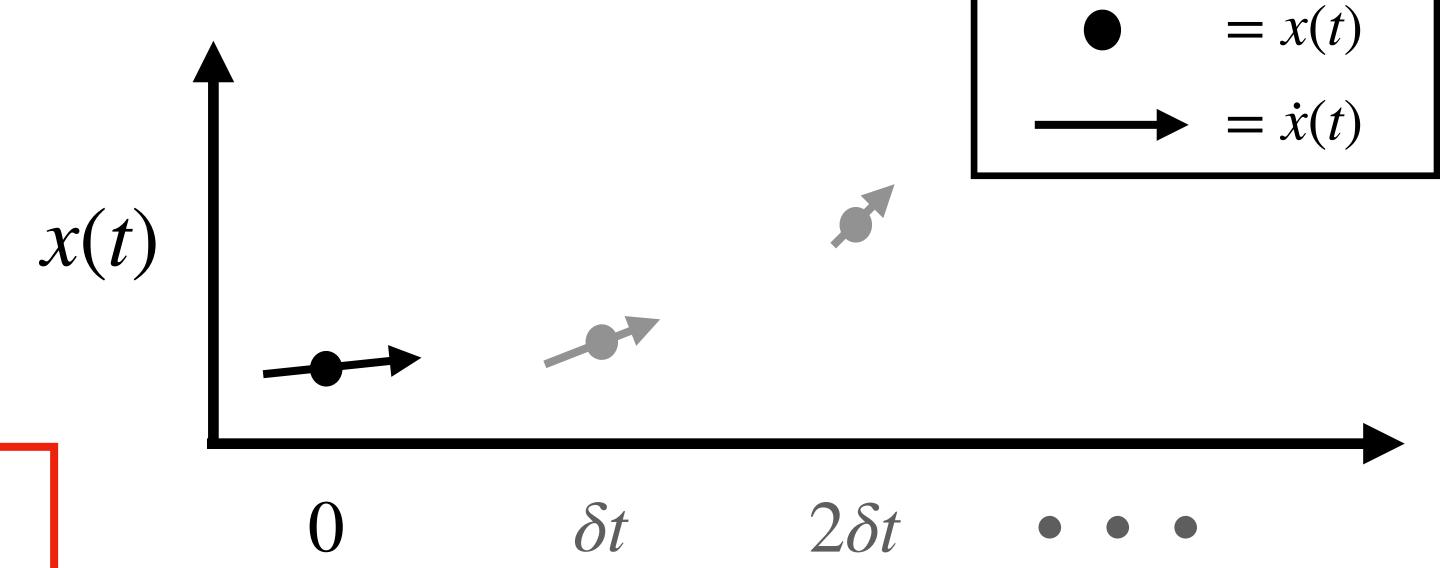
Predict Know Know 
$$x(0 + \delta t) \approx x(0) + (\delta t)\dot{x}(0)$$
  $\dot{x}(\delta t) = x(\delta t)$ 



Time

Predict  $x(t + \delta t)$  from x(t) and  $\dot{x}(t)$ 

$$x(2\delta t) \approx x(\delta t) + [\delta t]\dot{x}(\delta t)$$
$$\dot{x}(2\delta t) = x(2\delta t)$$



Iterate for  $x(t+2\delta t), x(t+3\delta t), \dots$ 

Time

# General form of first order Ordinary Differential Equations (ODE)

$$\dot{x}(t) = f(x(t), t) - \text{Arbitrary function } f$$

$$\dot{x}(0) = x_0$$

## Examples

**Is** first order

$$\dot{x}(t) = [x(t)]^2 + 2tx(t)$$

Isn't first order

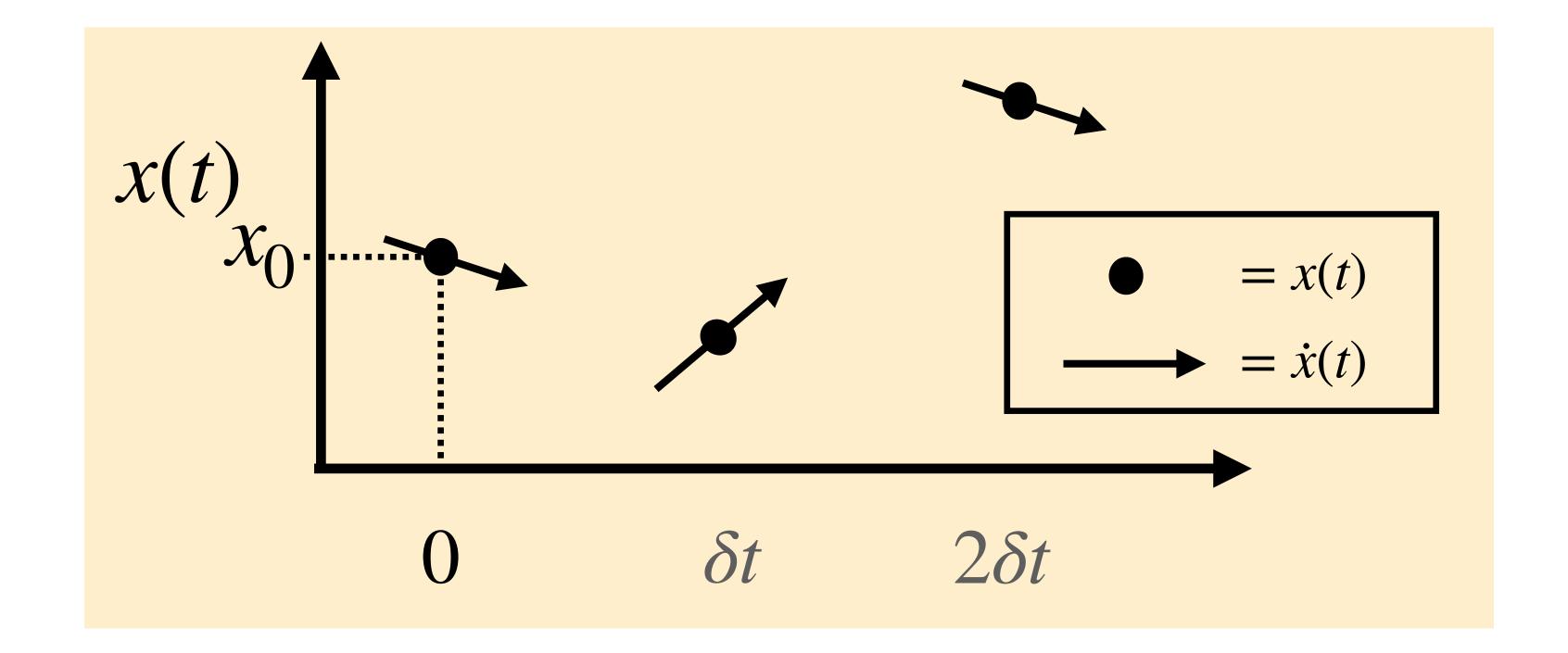
$$\ddot{x}(t) = -x(t)$$

Second order (double derivative)

# Forward Euler algorithm for numerically solving first-order ODEs

$$\dot{x}(t) = f(x(t), t)$$

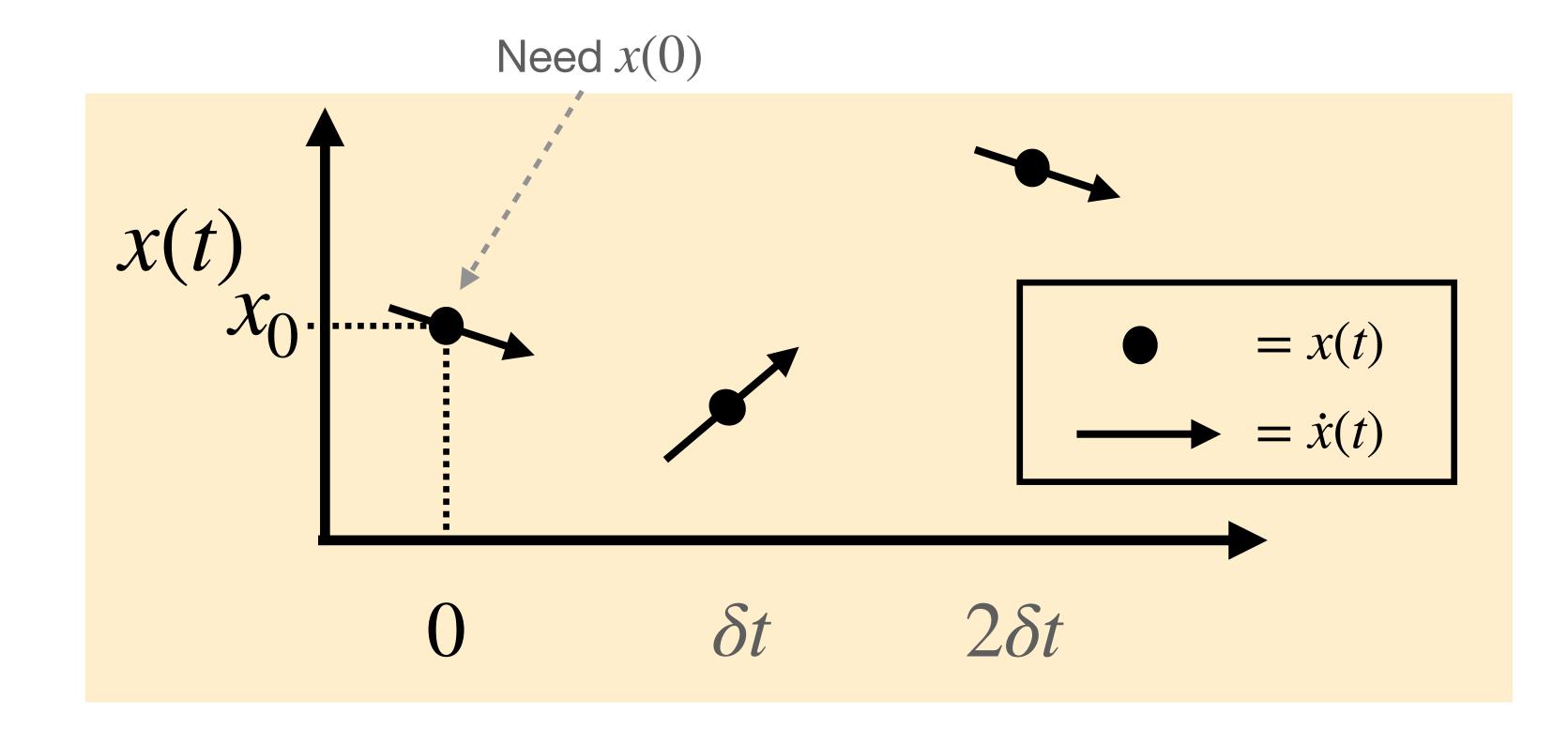
$$\dot{x}(0) = x_0$$



# Forward Euler algorithm for numerically solving first-order ODEs

$$\dot{x}(t) = f(x(t), t)$$

$$\dot{x}(0) = x_0$$



(Julia code in notebook)

for t in δt\*np.arange(1,n):

$$x(t + \delta t) = x(t) + \delta t^* f(x(t))$$

$$= \dot{x}(t)$$

# **Terminology**

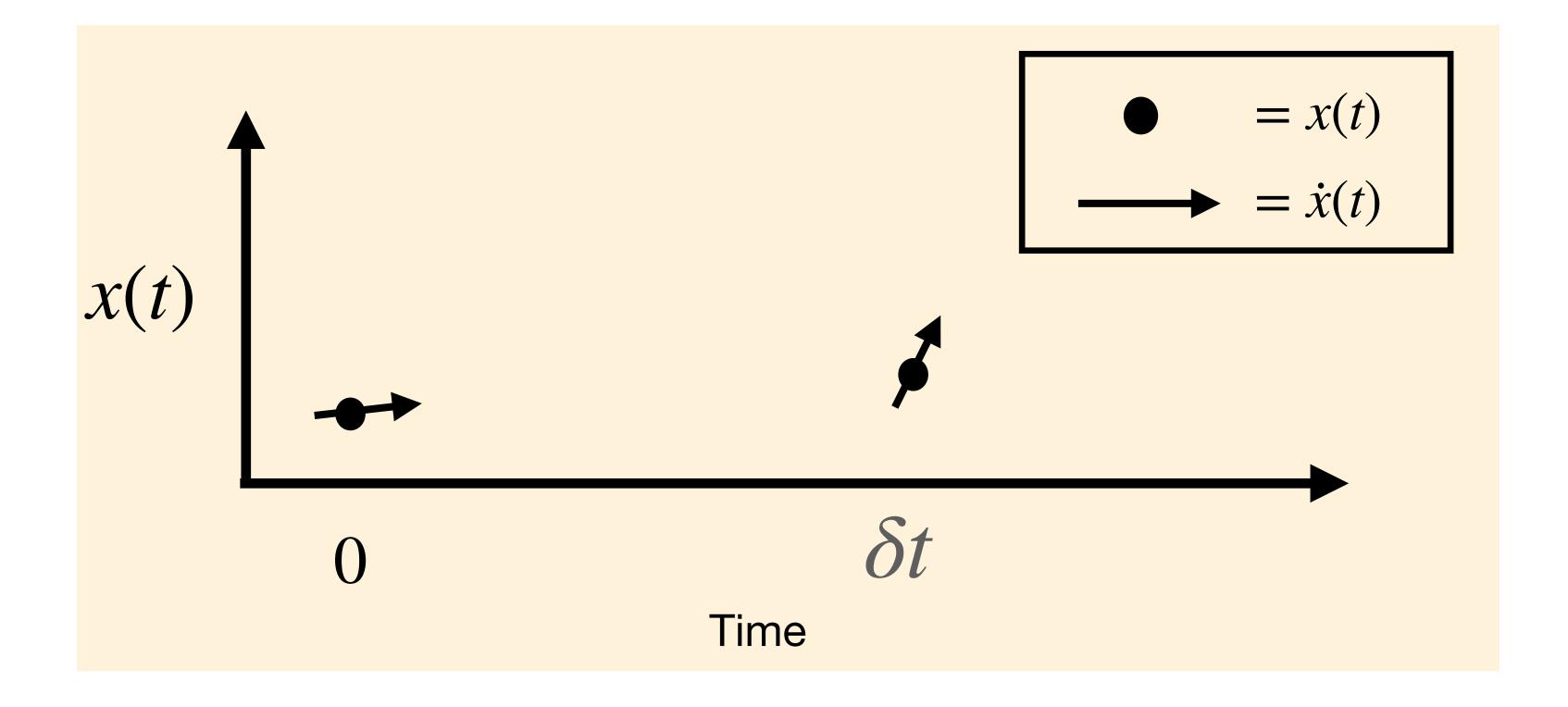
Forward Euler is a "numerical ODE solver"

The simplest but not the best!...

# **Evaluating numerical solvers**

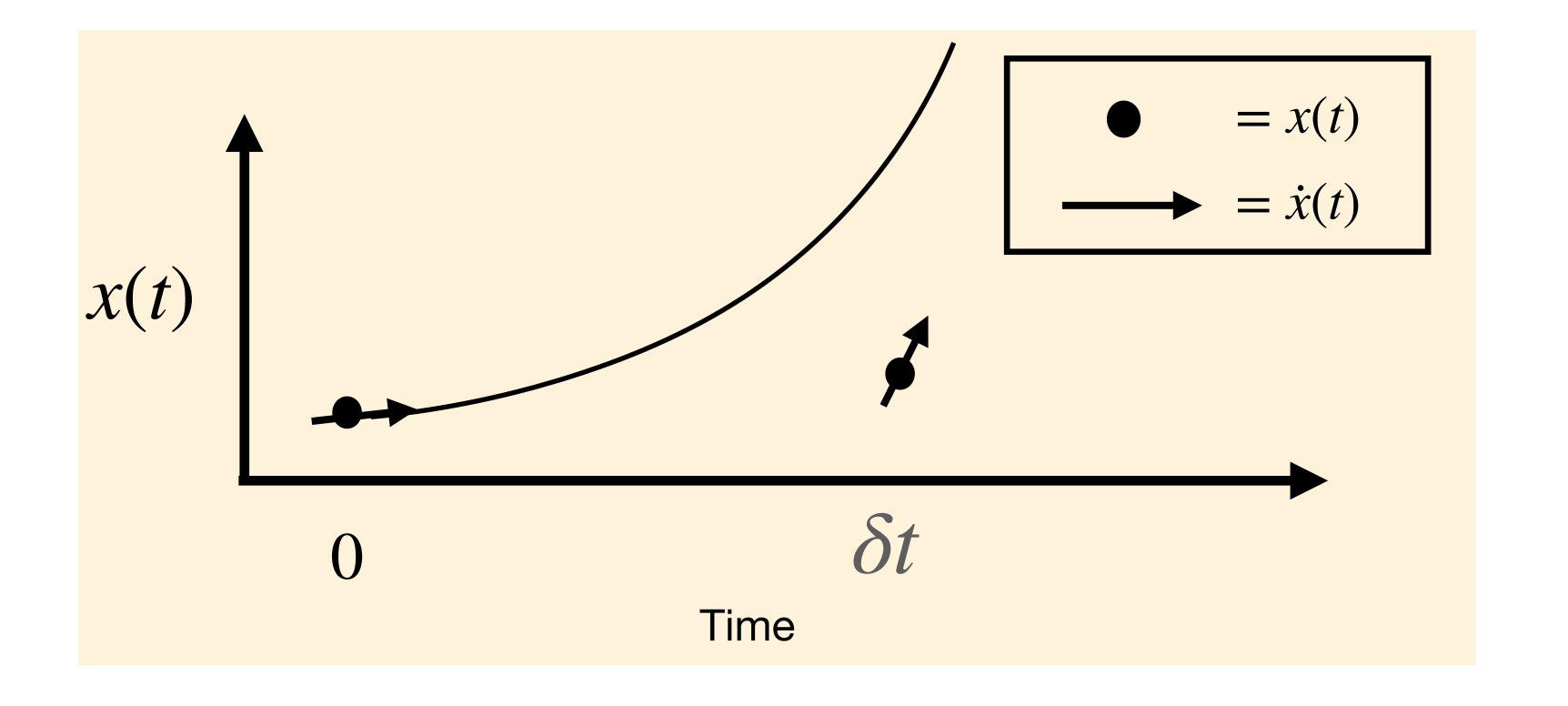
Sources of approximation error?

Is  $x(\delta t)$  an over or under-estimate in this example?



# **Evaluating numerical solvers**

# Numerical approximation was an over-estimate



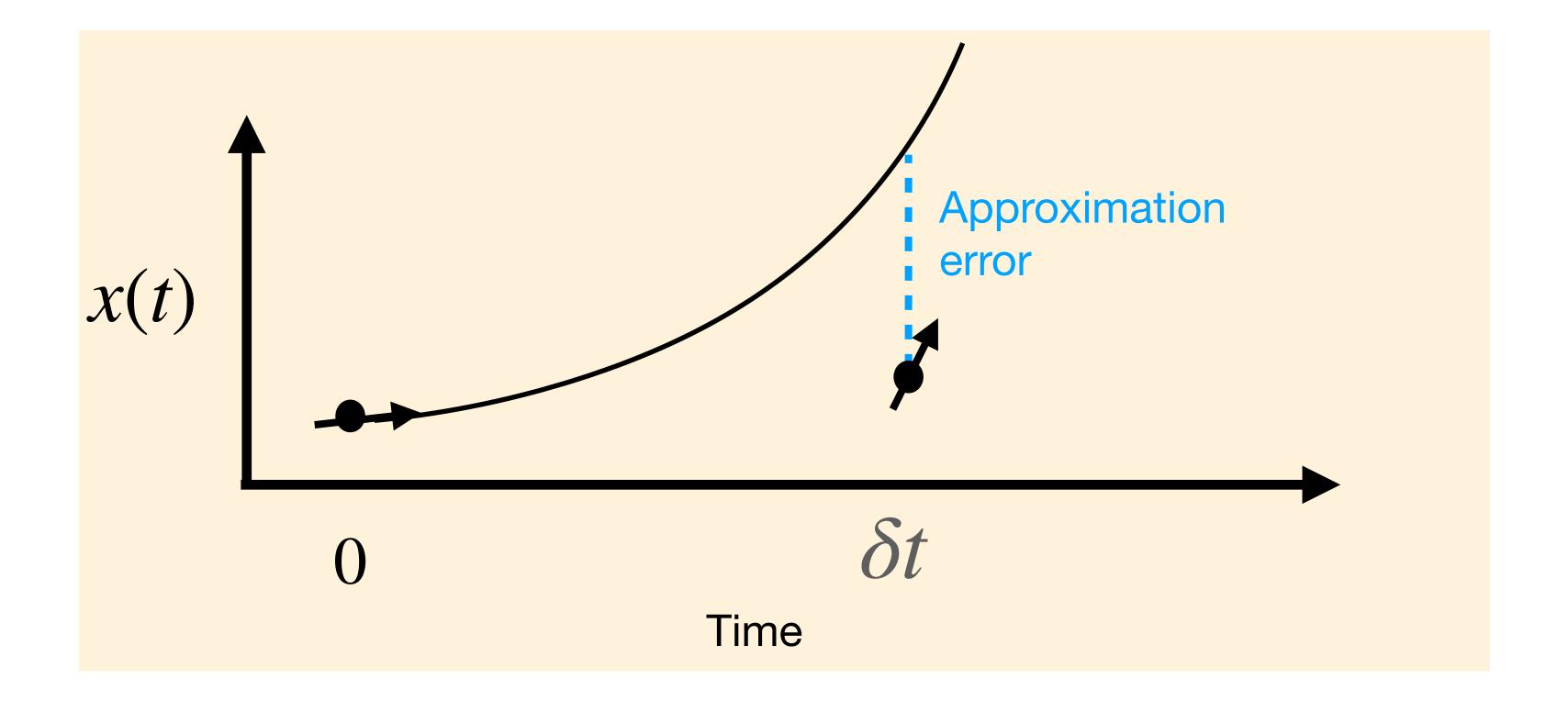
Derivative increases over interval

Function increases faster than  $\dot{x}(0)$  suggests

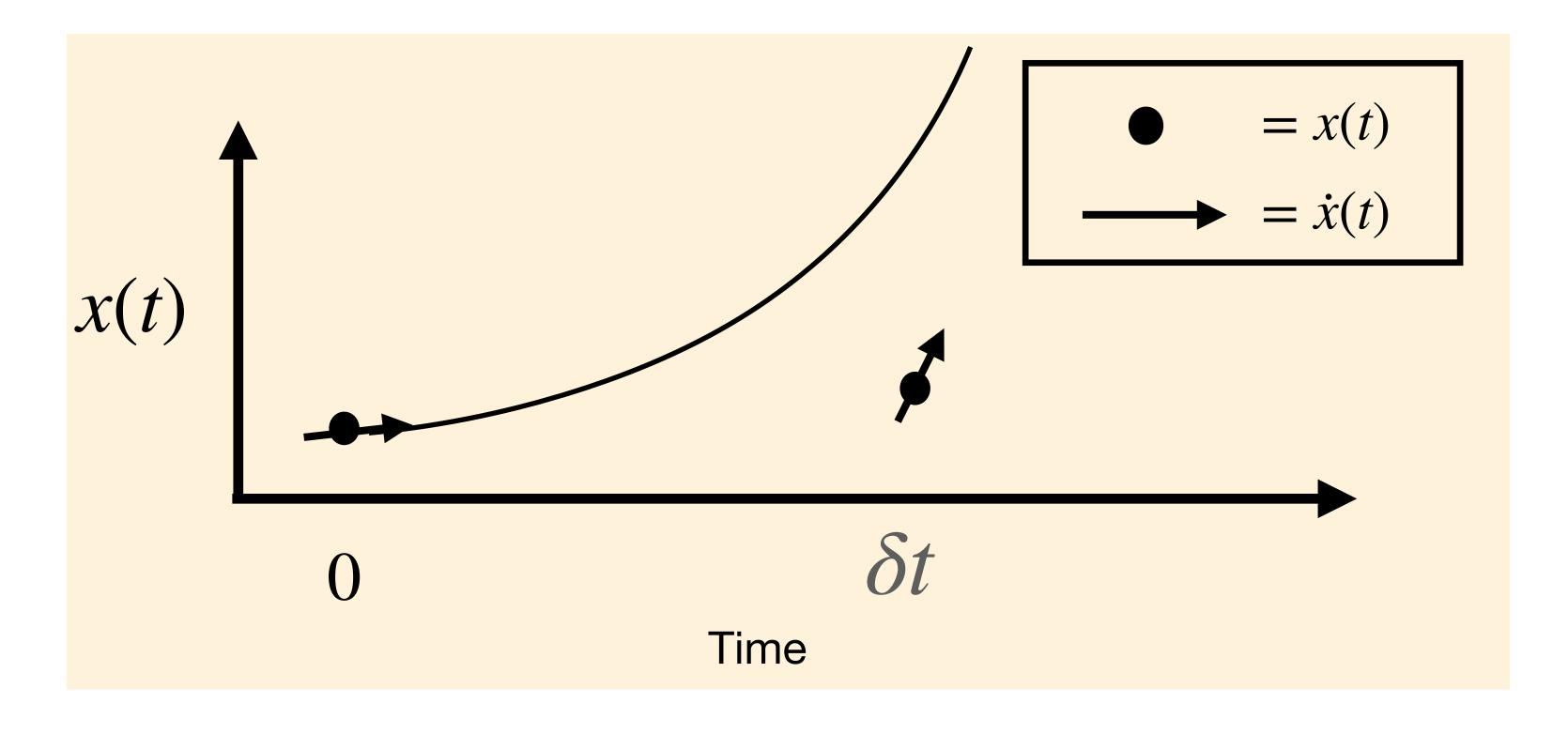
Diagnostic:  $\dot{x}(\delta t) > \dot{x}(0)$ 

# **Evaluating numerical solvers**

What could decrease approximation error?



What could decrease approximation error?



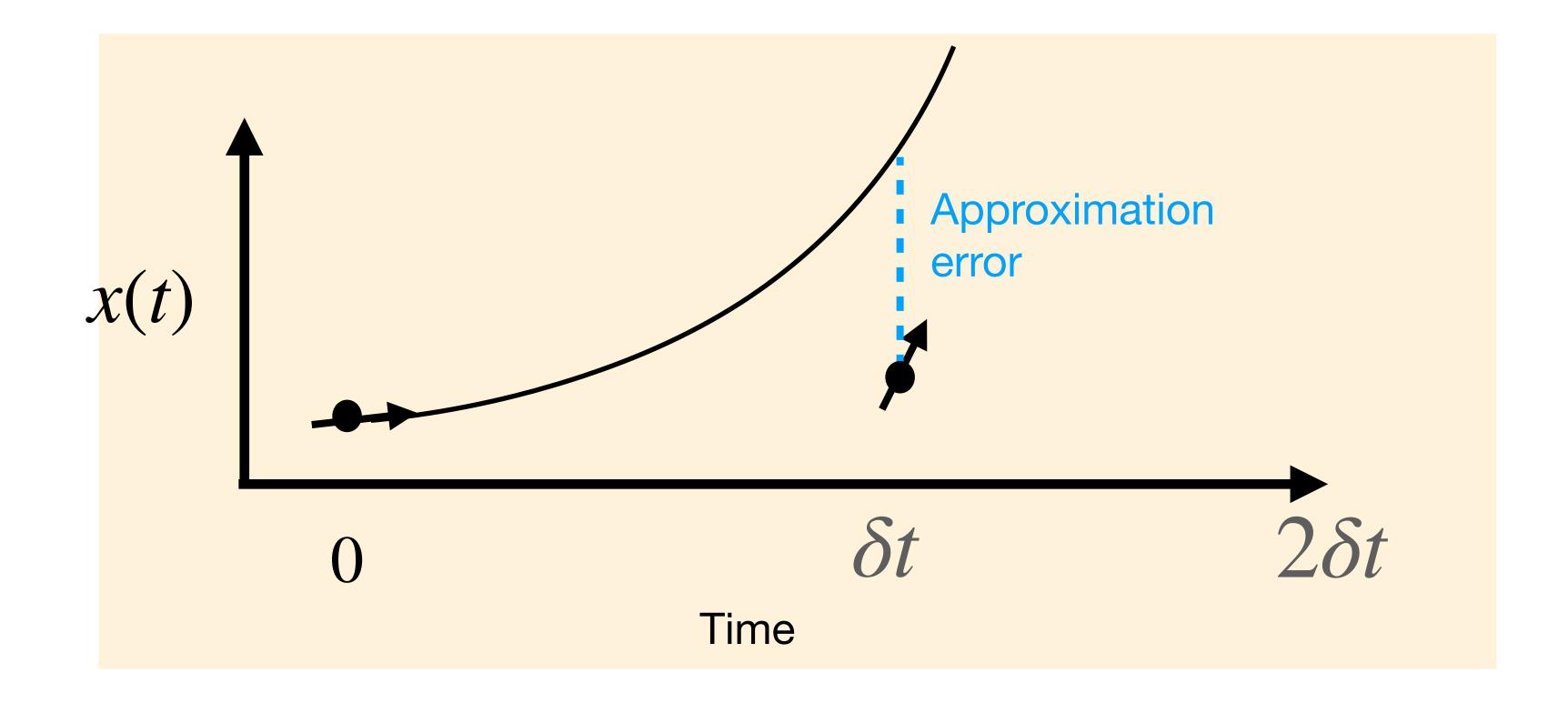
Clever

Change in a direction that interpolates  $\dot{x}(0)$  and  $\dot{x}(\delta t)$ 

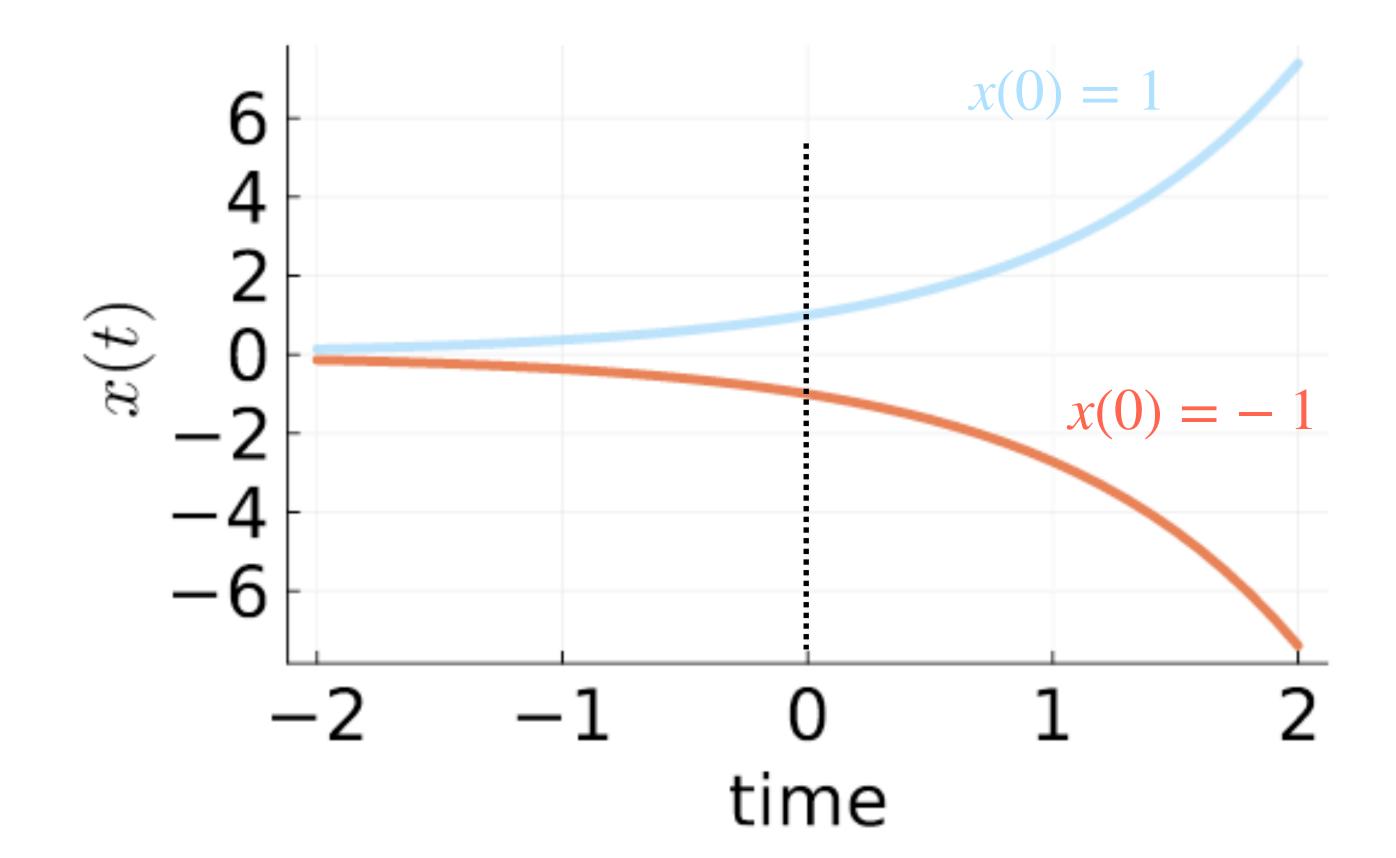
**Brute force** 

Decrease  $\delta t$ 

Will approximation error compound over time?



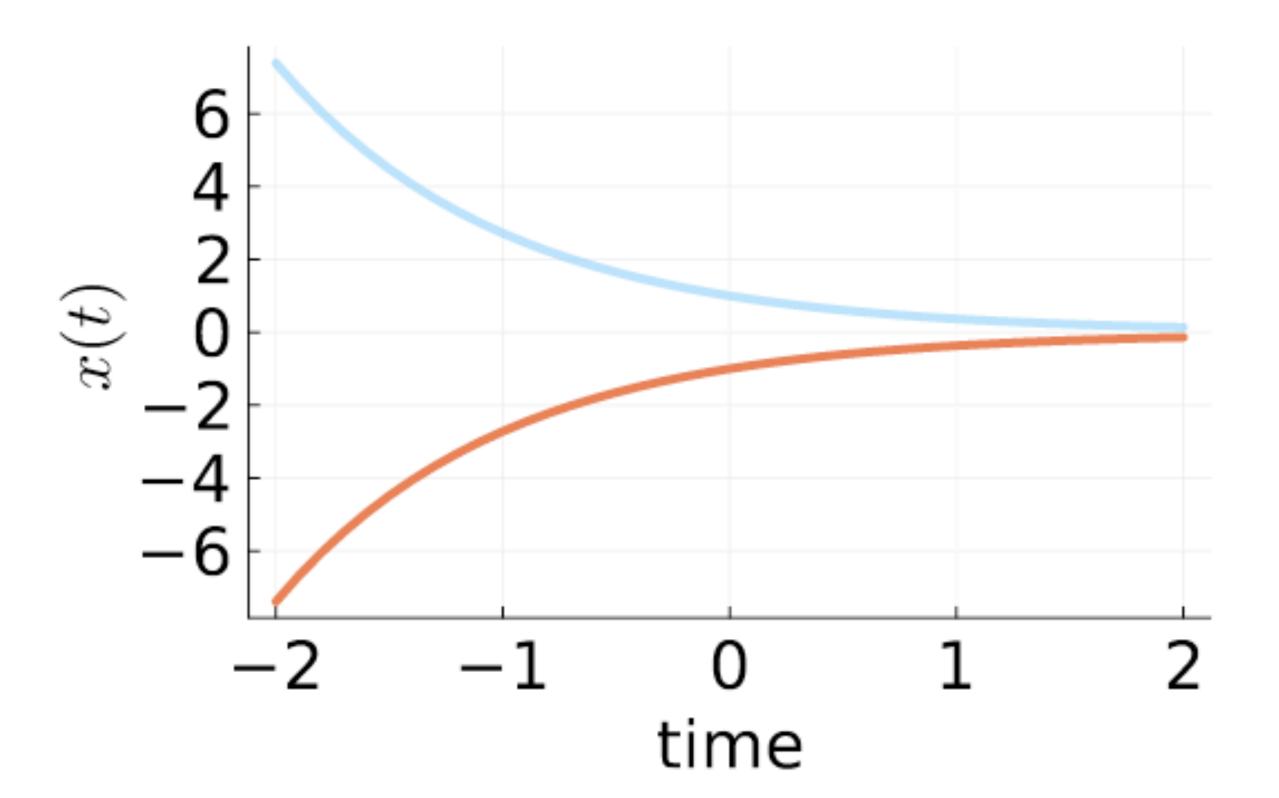
$$\dot{x}(t) = x(t)$$



Will approximation error compound over time here?

Possibly! Small differences in true solution increase over time

$$\dot{x}(t) = -x(t)$$



Will approximation error compound over time here?

Less likely for this ODE?

When does approximation error compound over time?

Depends upon ODE, solving algorithm, initial conditions....

Mathematical analysis is hard. Difficult to explain intuition in lecture

Interactive seminar question instead

#### A good numerical solver should have....

Heuristics for stepsize  $\delta t$  that balance accuracy (small  $\delta t$ ) with speed (large  $\delta t$ )

Small approximation error by cleverly interpolating information on  $\dot{x}(t)$  over time steps

Warnings in situations where approximation error compounds

Numerical analysis is an entire field of mathematics

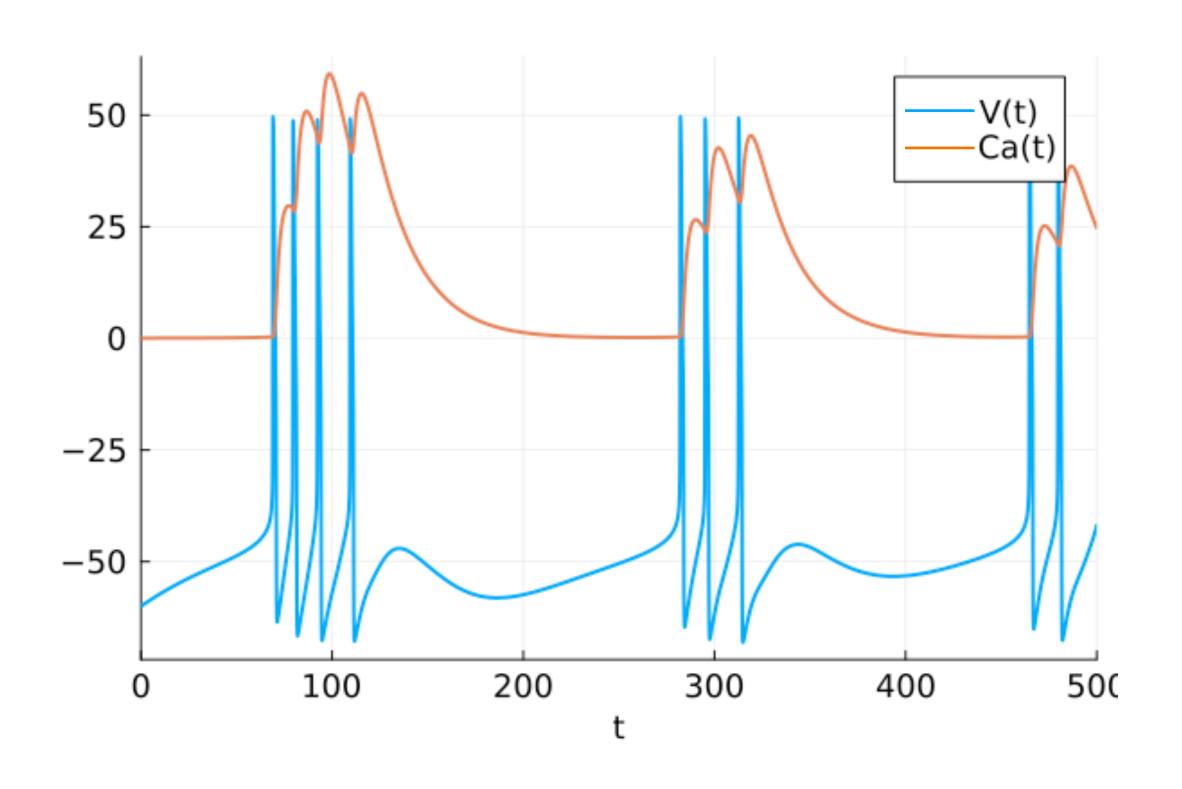
#### Stiff ODE example

Optimal  $\delta t$  changes drastically over time

Too big? Nonsense solution!

Specialised stiff ODE solvers exist

## Voltage and calcium concentration in a bursting neuron model



No precise definition for stiffness

#### Solving first-order ODE in Python/Julia

scipy.integrate.solve\_ivp

using OrdinaryDiffEq
solve(o::ODEProblem)

Choice of numerical solvers. Picking the right one is an art!

(Scipy ones are slow, outdated and error-prone)

(Diffeqpy is a Julia port that does better)

#### **Summary thus far**

Gained some intuition on how ODEs behave

Gained some intuition on numerical solvers, and when they do badly

Haven't discussed how/why to model real life processes with ODEs!....

# Modelling (badly) a discrete stochastic dynamical system

N students. Every day, some of you get COVID...

Probability of infection per student on a given day:  $\sim \mathrm{Bern}(\lambda)$  (e.g.  $\lambda = 0.1$ )

 $S_i$ : number of healthy students on day i

## Expected value of healthy students on a given day is easy to calculate

$$S_0 = N$$

$$\mathbb{E}[S_1] = (1 - \lambda)N$$

$$\mathbb{E}[S_2] = (1 - \lambda)^2 N$$

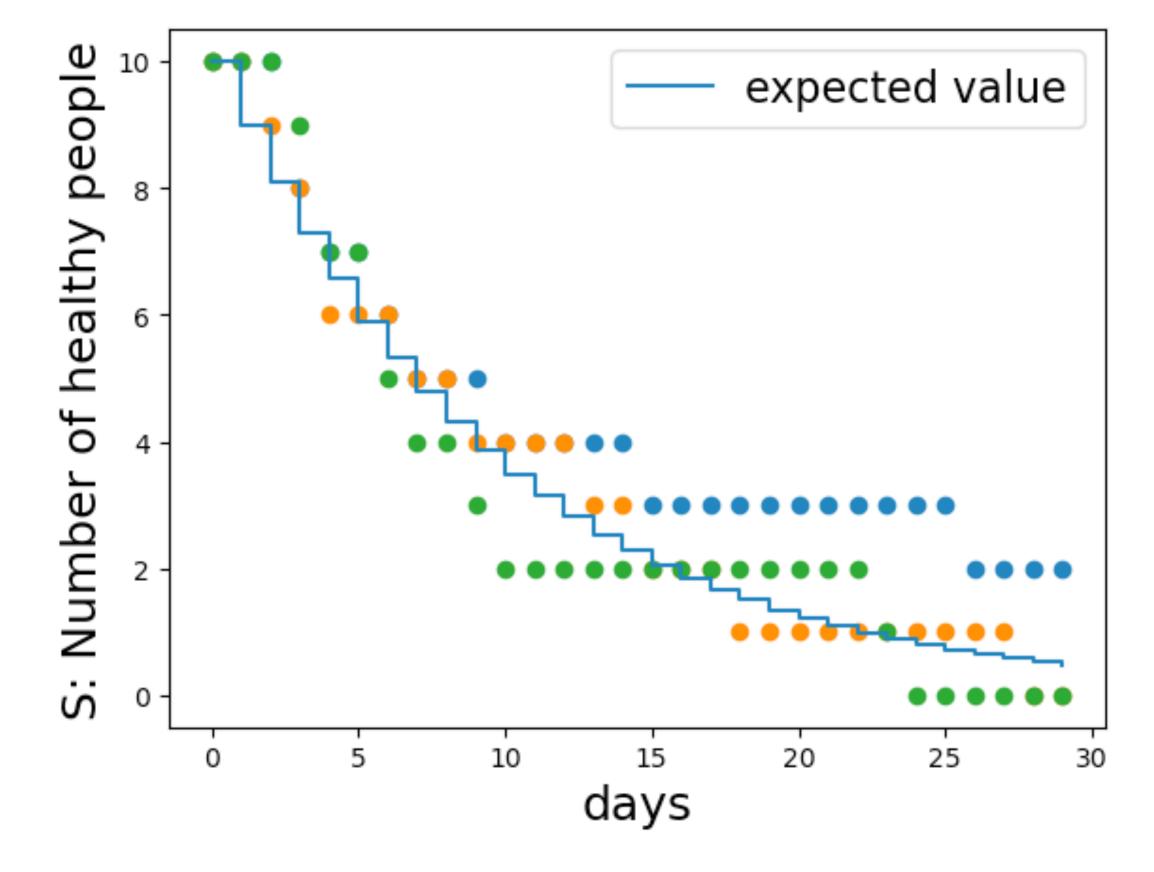
$$\vdots$$

$$\mathbb{E}[S_k] = (1 - \lambda)^k N$$

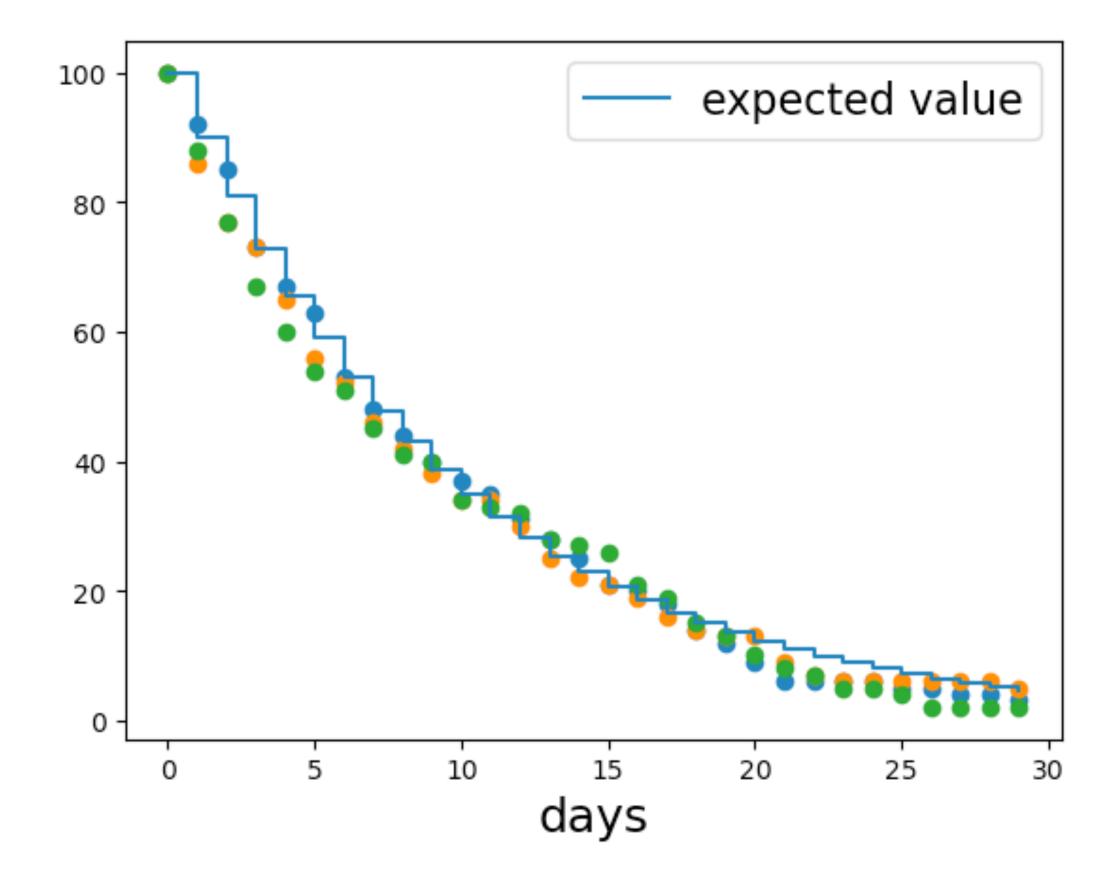
...but the variance is hard! Depends on previous days

#### If you can't calculate, simulate!

$$N=10$$
, repeats = 4



N=100, repeats = 4



More students means less variance. Why?

#### What's wrong with our model?

Doesn't model many factors like recovery, changing immunity, etc.

- We'll get there!

Hard to analyse mathematically due to stochasticity

Infections don't actually occur on the stroke of midnight!

#### We're going to approximate our model

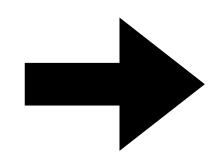
#### Discrete time

t = 1 day, 2 days, ...

Measure number of healthy people

Hard to analyse

Infections are stochastic



#### **Continuous time ODE**

Measure all timepoints

Measure expected number of healthy people

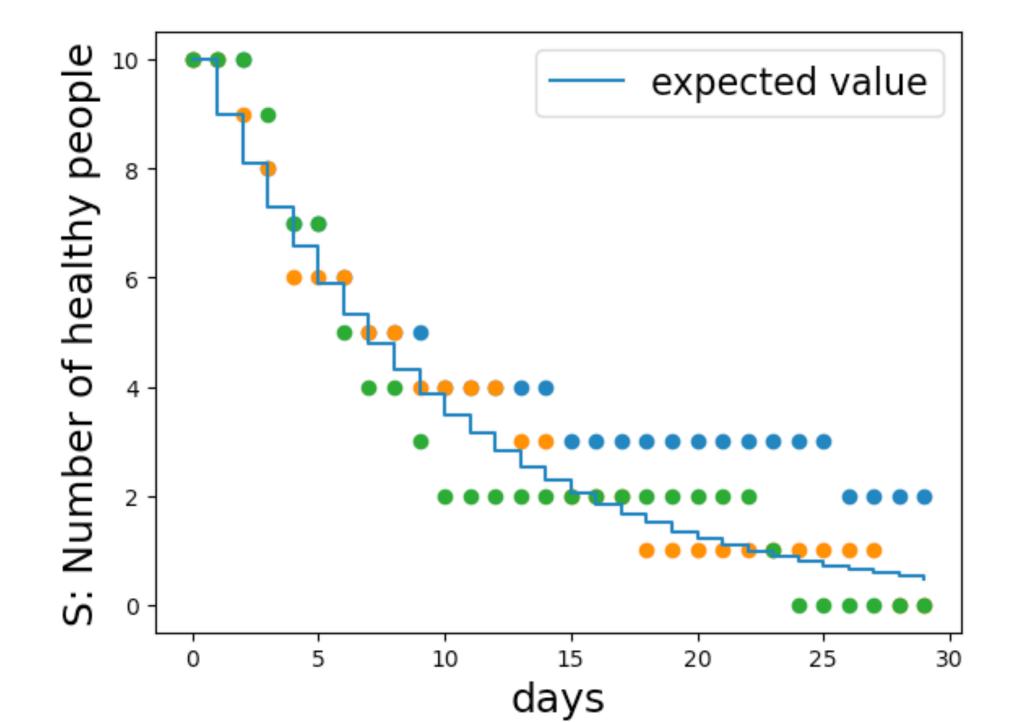
Easier to analyse

Only reasonable when stochasticity is low

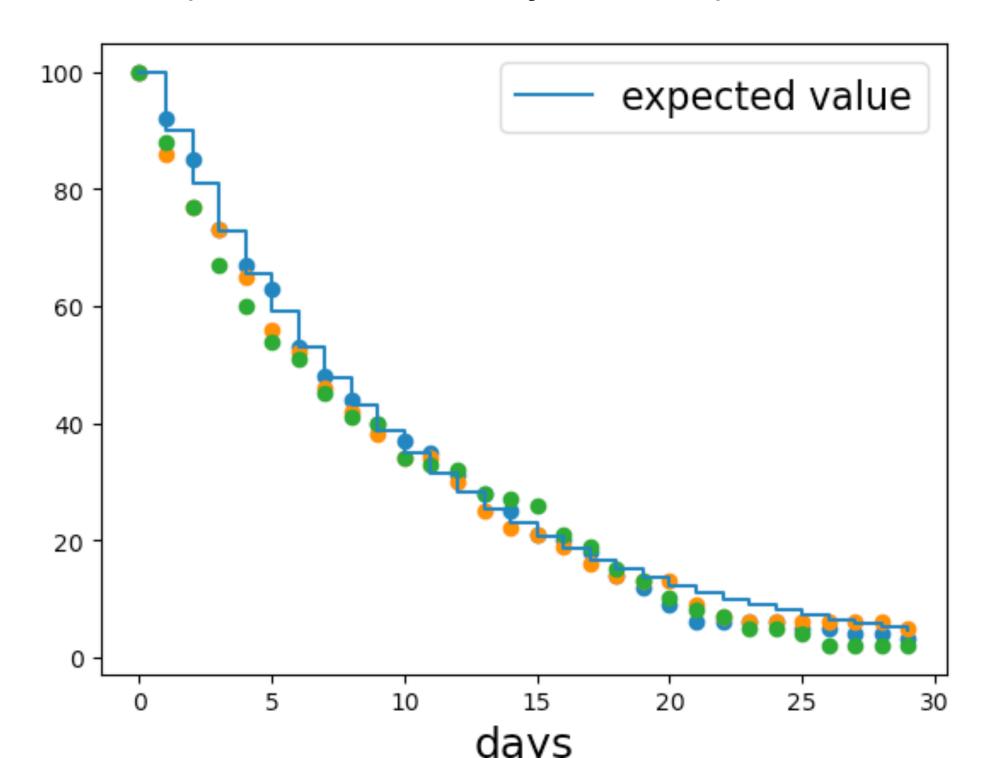
### This is called a mean field approximation

It's how many ODE models are derived

Less valid (high stochasticity N=10)



**Valid** (low stochasticity, N=100)



### Why are we only counting each day?

Infections can happen at any time. Why not measure twice a day?

#### **Current**

$$S_{t+1} - S_t \sim -B(S_t, 1 - \lambda)$$

#### Measure twice a day

$$S_{t+\frac{1}{2}} - S_t \sim -B\left(S_t, \frac{1-\lambda}{2}\right)$$

### Why are we only counting each day?

Infections can happen at any time. Why not measure at a timestep  $\delta t$ ?

#### Current

$$S_{t+1} - S_t \sim -B(S_t, 1 - \lambda)$$

#### Measure twice a day

$$S_{t+\frac{1}{2}} - S_t \sim -B\left(S_t, \frac{1-\lambda}{2}\right)$$

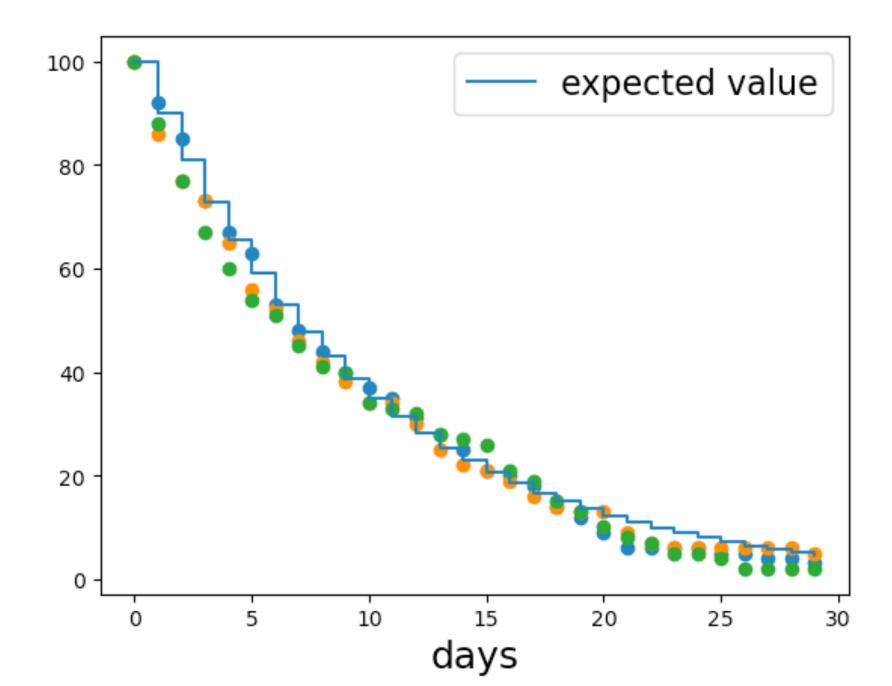
#### Measure every $\delta t$

$$S_{t+\delta t} - S_t \sim -B\left(S_t, \delta t(1-\lambda)\right)$$

#### Hidden assumption

Expected number of infections is linear in time, for small time steps < 1 day

## Clearly not true on longer timescales:



#### **Questions for audience:**

What's the source of the nonlinearity?

Why is short-timescale linearity reasonable?

### Mean field equation for infection rate

Expected value of binomial:

$$\mathbb{E}[S_{t+\delta t} - S_t] = -S_t \delta t (1 - \lambda)$$

Rearranging and removing expectations for clarity:

$$\frac{S_{t+\delta t} - S_t}{\delta t} = -pS_t \qquad p = (1 - \lambda)$$

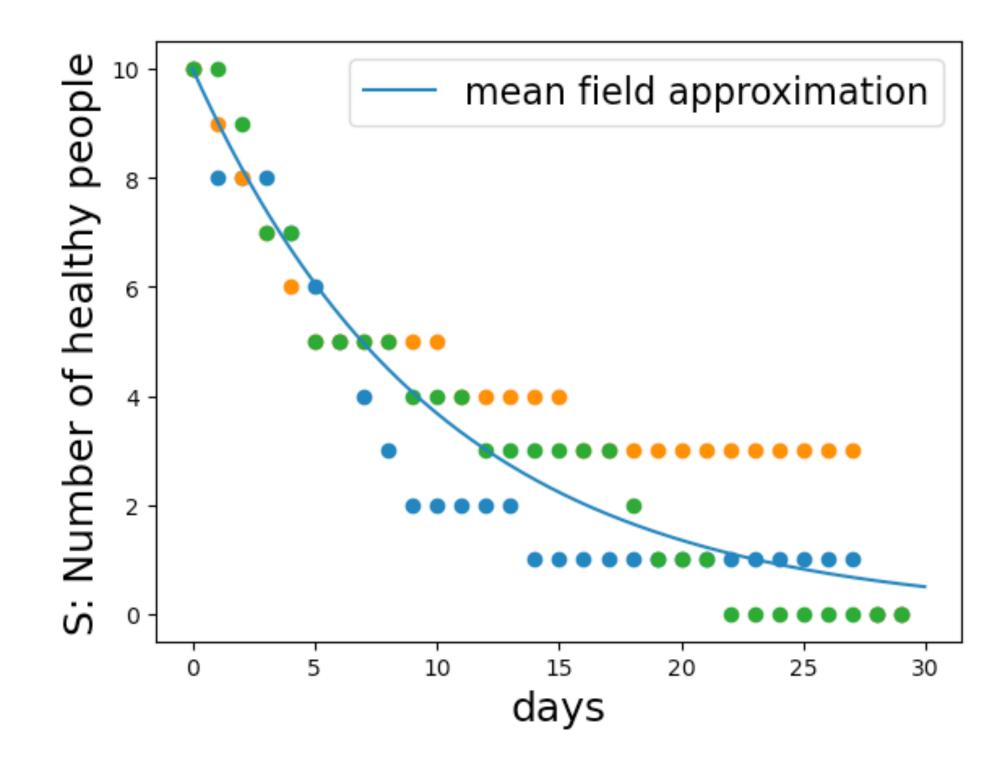
Limit as  $\delta t \rightarrow 0$ 

$$\dot{S}(t) = -pS(t)$$

#### What have we done?

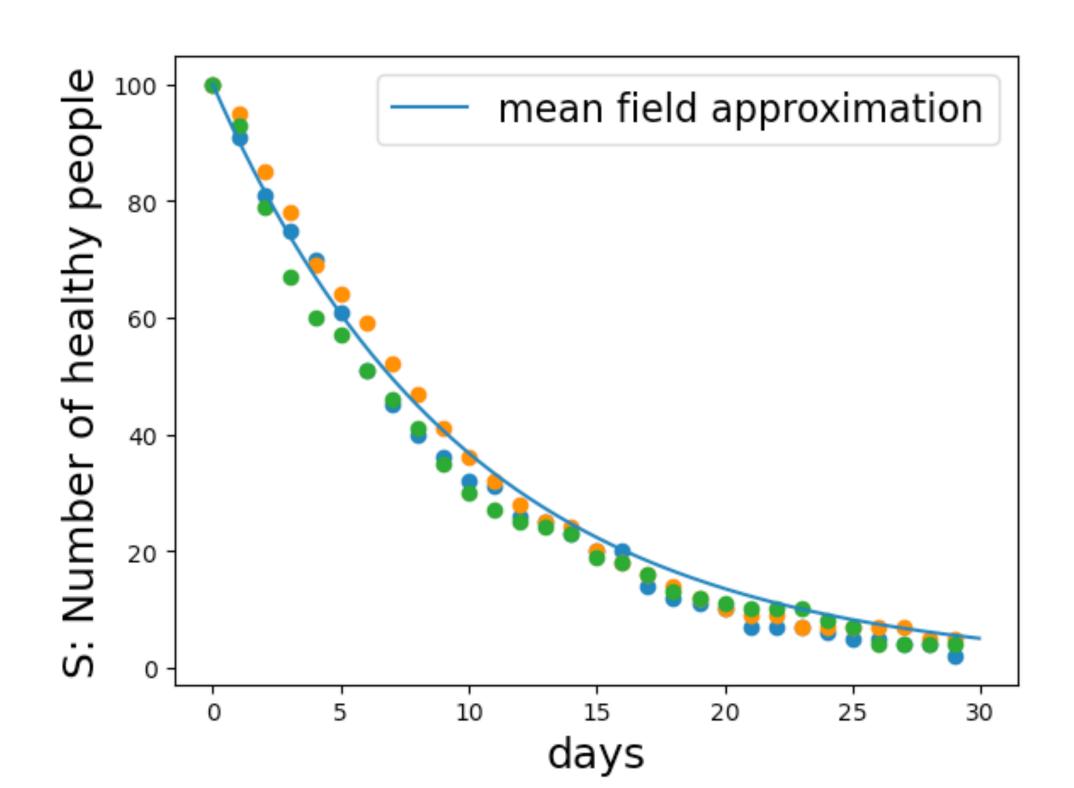
Rewritten what we expect a stochastic process to do as an ODE

$$N = 10$$



$$\dot{S}(t) = -pS(t)$$

$$N = 100$$



#### Analytical solution is easy in this case

$$\dot{S}(t) = -pS(t)$$

$$S(0) = N$$

$$S(t) = N \exp(-pt)$$

Solve for yourself. Use previous analytical solution to help

#### Interpreting our (bad) model

$$\dot{S}(t) = -pS(t)$$

$$S(0) = N$$

What are the units of p?

(Units on each side of equation should be equal)

#### Interpreting our (bad) model

$$\frac{\mathrm{d}S}{\mathrm{d}t}(t) = -pS(t)$$

$$\frac{\text{Number}}{\text{time}} = \text{Units of p} \times \text{Number}$$

Units of 
$$p$$
 are  $\frac{1}{\text{time}}$ 

p is a rate (the intrinsic infection rate)

### What's wrong with our model?

Doesn't model many factors like recovery, changing immunity, etc.

Hard to analyse mathematically due to stochasticity

- Sorted!

Infections don't occur on the stroke of midnight!

- Sorted!

#### **Systems of ODEs**

Single state represented as number (e.g. number of healthy students)  $\dot{x}(t) = f(x(t), t)$ 

ODEs useful for analysing dynamic interactions between quantities

#### SI Model

Mean dynamics of healthy students (from before)

$$\dot{S}(t) = -pS(t)$$

$$S(0) = N$$

Dynamics of infected students?

$$\dot{I}(t) = ???$$
 $I(0) = 0$ 

#### SI Model

Total students doesn't change (no deaths)

$$\forall t: S(t) + I(t) = N$$

Differentiating in time:

$$\dot{S}(t) + \dot{I}(t) = 0$$

$$\Rightarrow \dot{I}(t) = -\dot{S}(t)$$

#### SI Model

New model:

$$\begin{bmatrix} \dot{S}(t) \\ \dot{I}(t) \end{bmatrix} = \begin{bmatrix} -p & 0 \\ p & 0 \end{bmatrix} \begin{bmatrix} S(t) \\ I(t) \end{bmatrix}$$

$$\dot{x}(t) = Ax(t)$$

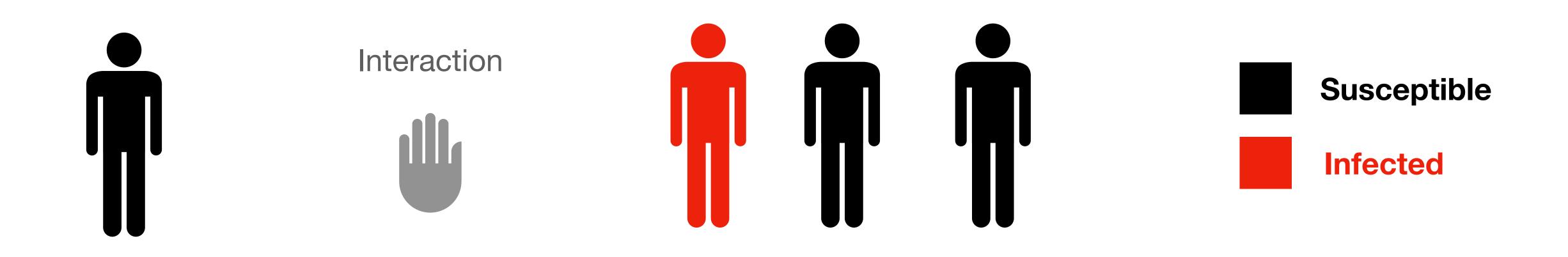
$$\begin{bmatrix} S(0) \\ I(0) \end{bmatrix} = \begin{bmatrix} N \\ 0 \end{bmatrix}$$

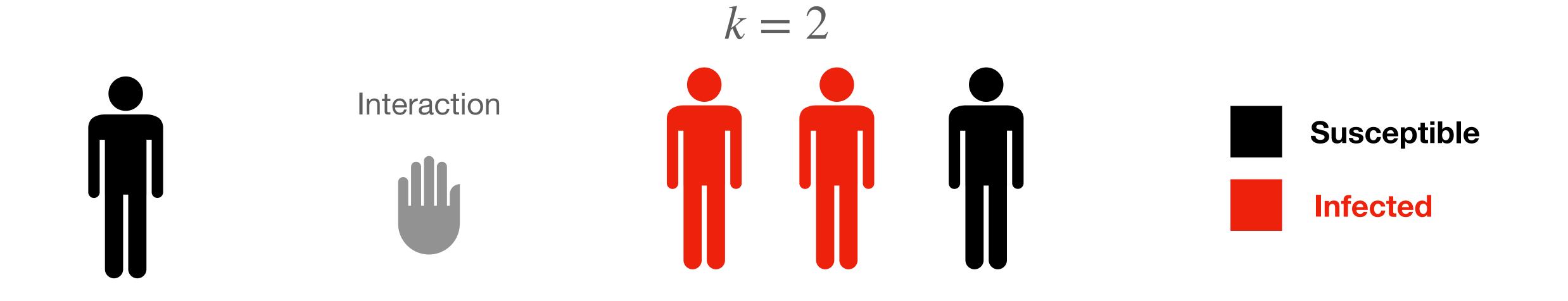
$$x(0) = \begin{bmatrix} S(0) \\ I(0) \end{bmatrix}$$

...still a linear first-order ODE!

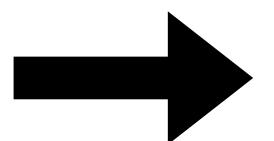
Overall rate of infection should depend on number of susceptibles and number of infected

But how?

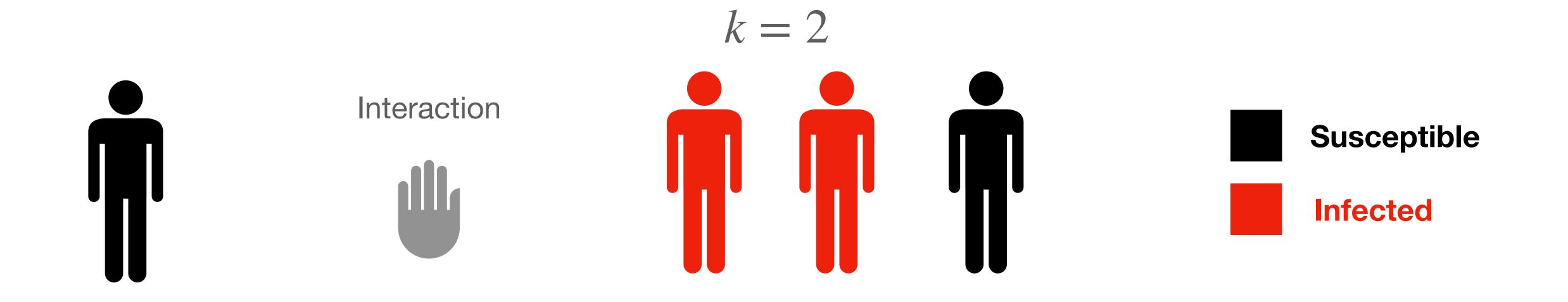




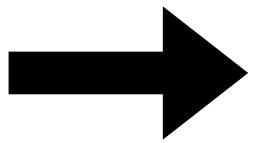
Increase proportion of infected individuals by factor of k



Increase infection rate by factor of k

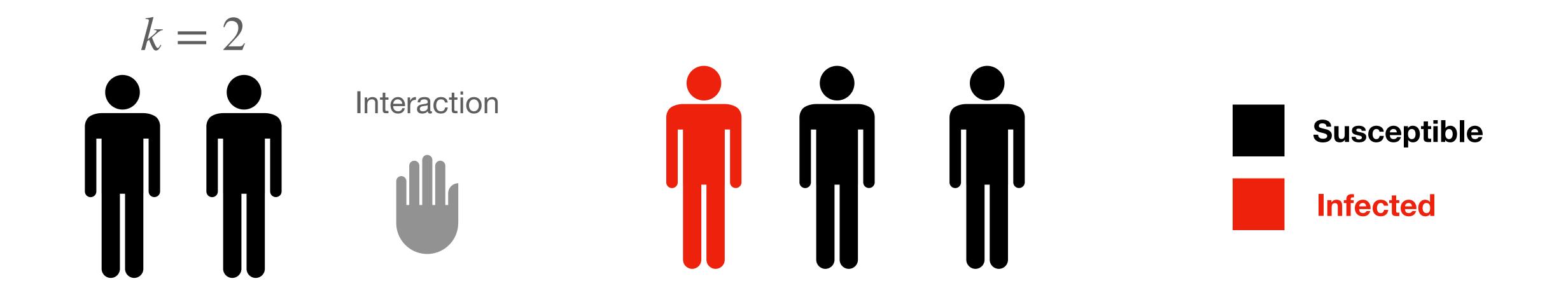


Increase proportion of infected individuals by factor of k

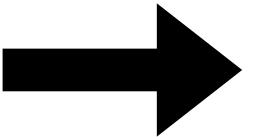


Increase infection rate by factor of k

$$\dot{S}(t) \propto -p \frac{I(t)}{N}$$



Increase susceptible individuals by factor of k



Increase infection rate by factor of k

$$\dot{S}(t) \propto -\frac{pS(t)I(t)}{N}$$

#### Note

Could have  $\tilde{p} = \frac{p}{N}$ , but nice to have population-independent measure of infectivity

### Improved SI Model

$$\dot{S}(t) = -p \frac{S(t)I(t)}{N}$$

$$\dot{I}(t) = p \frac{S(t)I(t)}{N}$$

$$\begin{bmatrix} S(0) \\ I(0) \end{bmatrix} = \begin{bmatrix} N \\ 0 \end{bmatrix}$$

Now it's nonlinear:(

Every infectious person eventually recovers (no deaths)

Same type of stochastic process as infection

Same mean field approximation

## The standard SIR model

$$\dot{S}(t) = -p \frac{S(t)I(t)}{N}$$

$$\dot{I}(t) = p \frac{S(t)I(t)}{N} - \gamma I(t)$$

$$\dot{R}(t) = \gamma I(t)$$

p: infection rate  $\gamma$ : recovery rate

$$\dot{S}(t) + \dot{I}(t) + \dot{R}(t)?$$

## The standard SIR model

$$\dot{S}(t) = -p \frac{S(t)I(t)}{N}$$

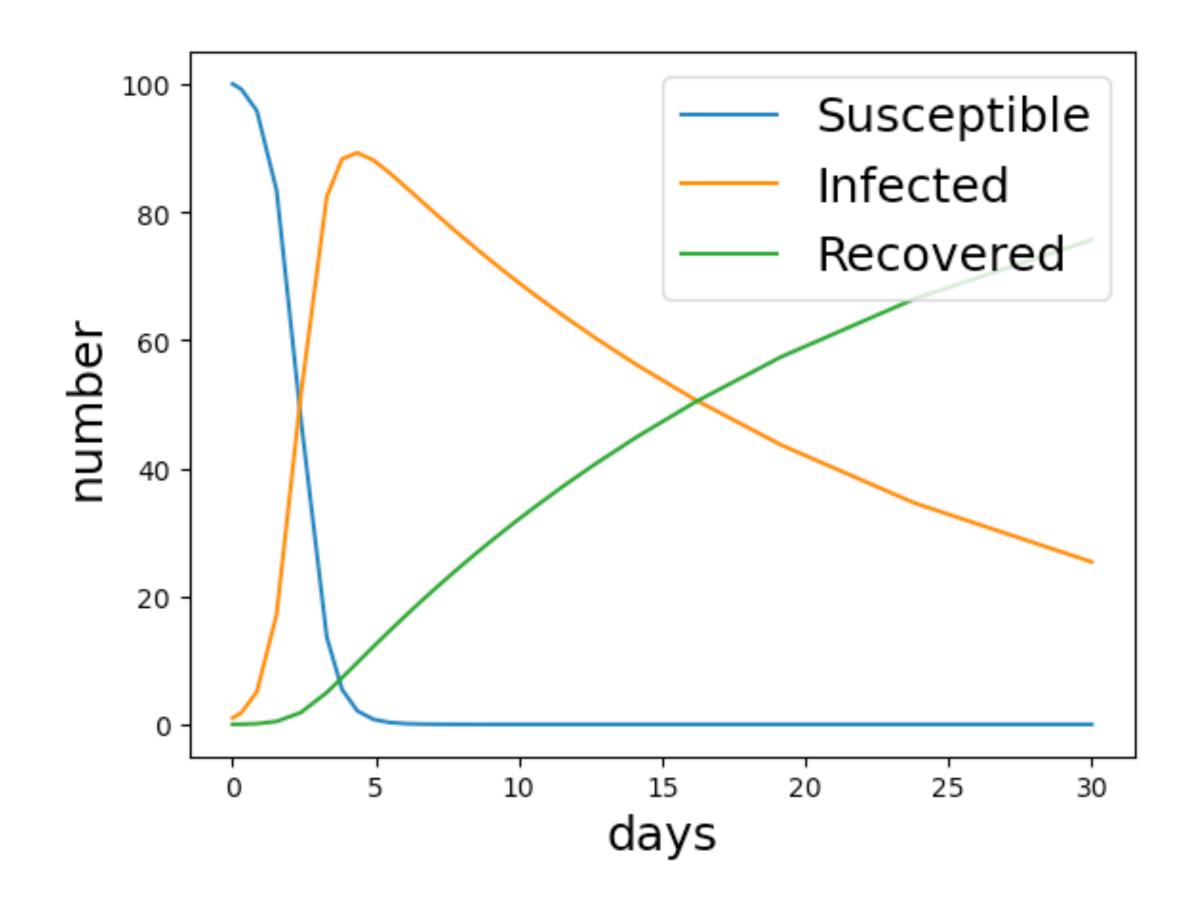
$$\dot{I}(t) = p \frac{S(t)I(t)}{N} - \gamma I(t)$$

$$\dot{R}(t) = \gamma I(t)$$

$$x(t) = \begin{bmatrix} S \\ I \\ R \end{bmatrix} \qquad \dot{x}(t) = f(x(t), t)$$

p: infection rate  $\gamma$ : recovery rate

## Plotting the SIR model



$$\dot{S}(t) = -p \frac{S(t)I(t)}{N}$$

$$\dot{I}(t) = p \frac{S(t)I(t)}{N} - \gamma I(t)$$

$$\dot{R}(t) = \gamma I(t)$$

Experienced modeller can intuit shape of graph from equations, without simulating

## Analysis

Dynamics depend upon parameters

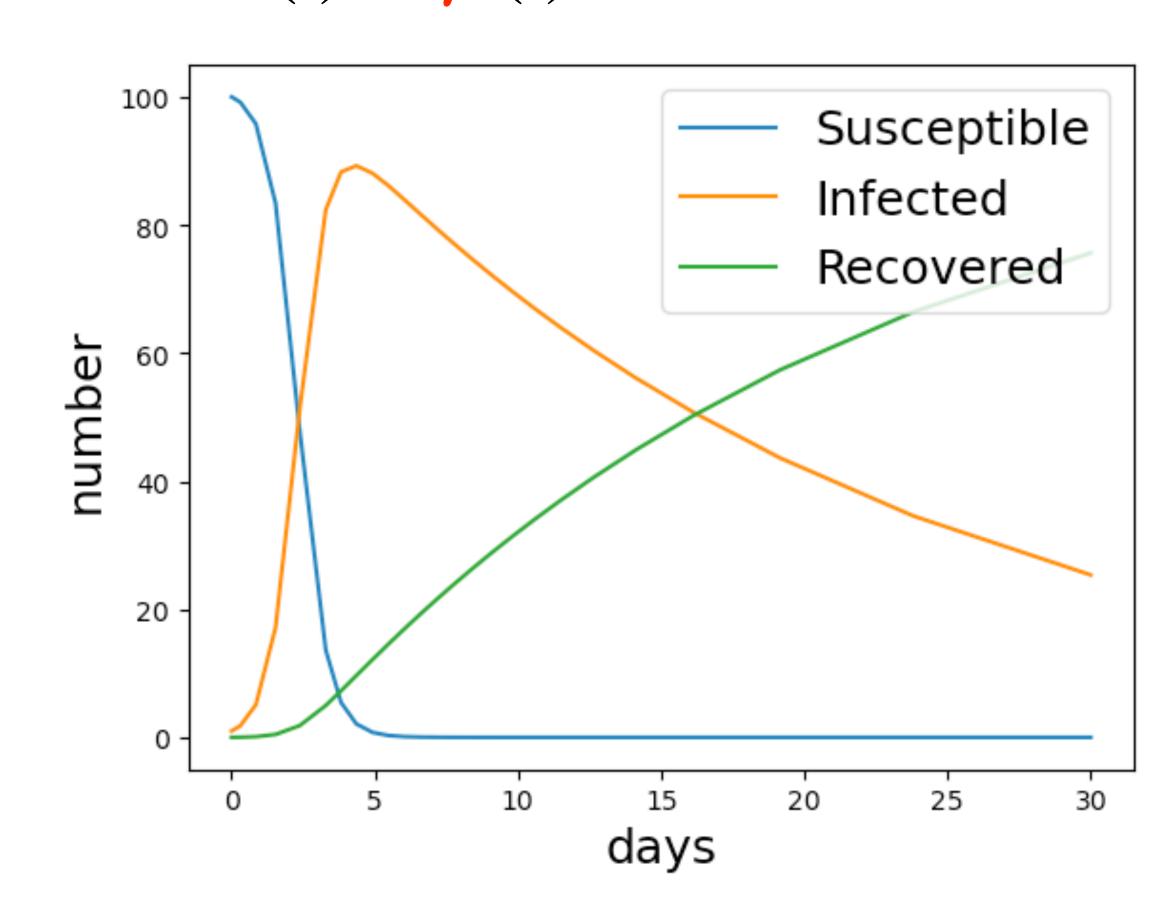
What combination of parameters could avoid a pandemic?

Need expected infections to always be decreasing

$$\dot{S}(t) = -\frac{p}{N} S(t) I(t)$$

$$\dot{I}(t) = \frac{p}{N} S(t) I(t) - \gamma I(t)$$

$$\dot{R}(t) = \gamma I(t)$$



## Analysis

Dynamics depend upon parameters

$$\dot{S}(t) = -\frac{p}{N}S(t)I(t)$$

$$\dot{I}(t) = \frac{p}{N}S(t)I(t) - \gamma I(t)$$

$$\dot{R}(t) = \gamma I(t)$$

What combination of parameters could avoid a pandemic?

Need expected infections to always be decreasing

$$\dot{I}(0) < 0 \qquad \Rightarrow \frac{p}{N} N - \gamma < 0$$
$$\Rightarrow \frac{p}{\gamma} < 1$$

## The basic reproduction number

$$R_0 = \frac{p}{\gamma}$$

 $R_0 < 1$ : a single infected person in the population will infect less than one person, on average

## Question for the audience

$$R_0 = \frac{p}{\gamma}$$

How would you model vaccination? Social distancing?

Can you comment on herd immunity in the context of this model?

## Herd immunity

$$R_0 = \frac{p}{\gamma}$$

How would you model vaccination? Social distancing?

Can you comment on herd immunity in the context of this model?

Could add extra state for the vaccinated. Or just decrease p

Vaccination/distancing need only decrease infectivity until  $R_0 < 1$ .

## Fixed points of the SIR model

$$\dot{S}(t) = -p \frac{S(t)I(t)}{N}$$

$$\dot{I}(t) = \left(p \frac{S(t)}{N} - \gamma\right)I(t)$$

$$\dot{R}(t) = \gamma I(t)$$

p: infection rate  $\gamma$ : recovery rate

For what values of S, I, R are there no dynamics?

## Steady state analysis of SIR model

$$\dot{S}(t) = -p \frac{S(t)I(t)}{N}$$

$$\dot{I}(t) = \left(p \frac{S(t)}{N} - \gamma\right)I(t)$$

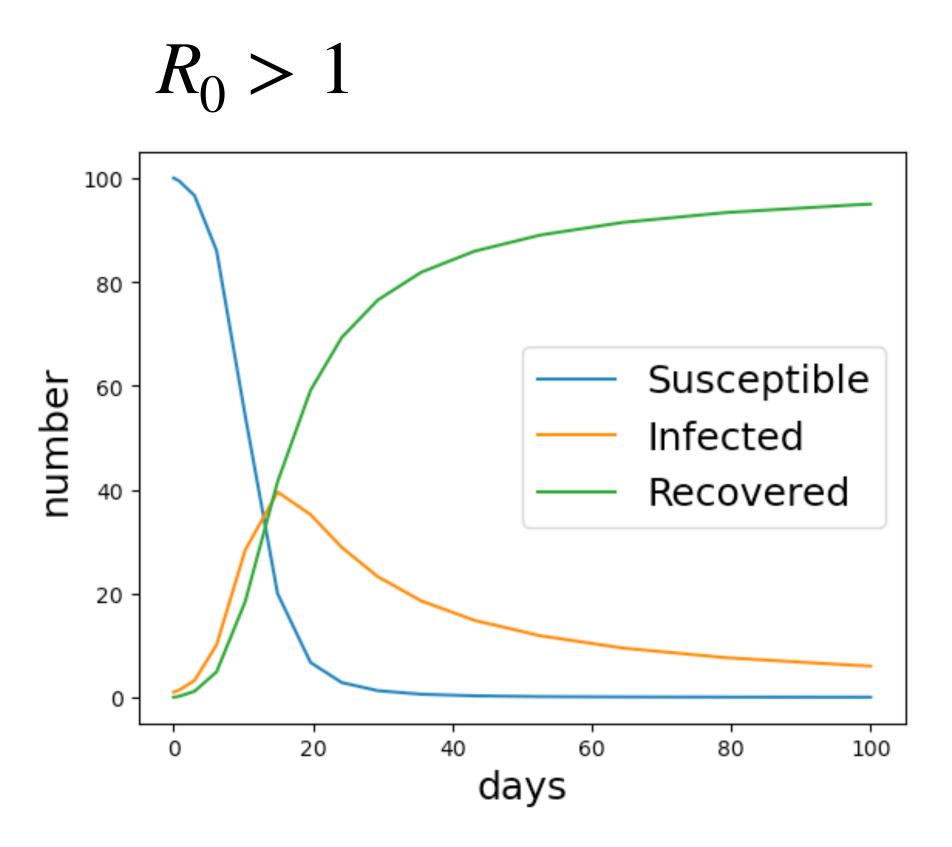
$$\dot{R}(t) = \gamma I(t)$$

Fixed point: I(t) = 0. S(t), R(t) can be anything!

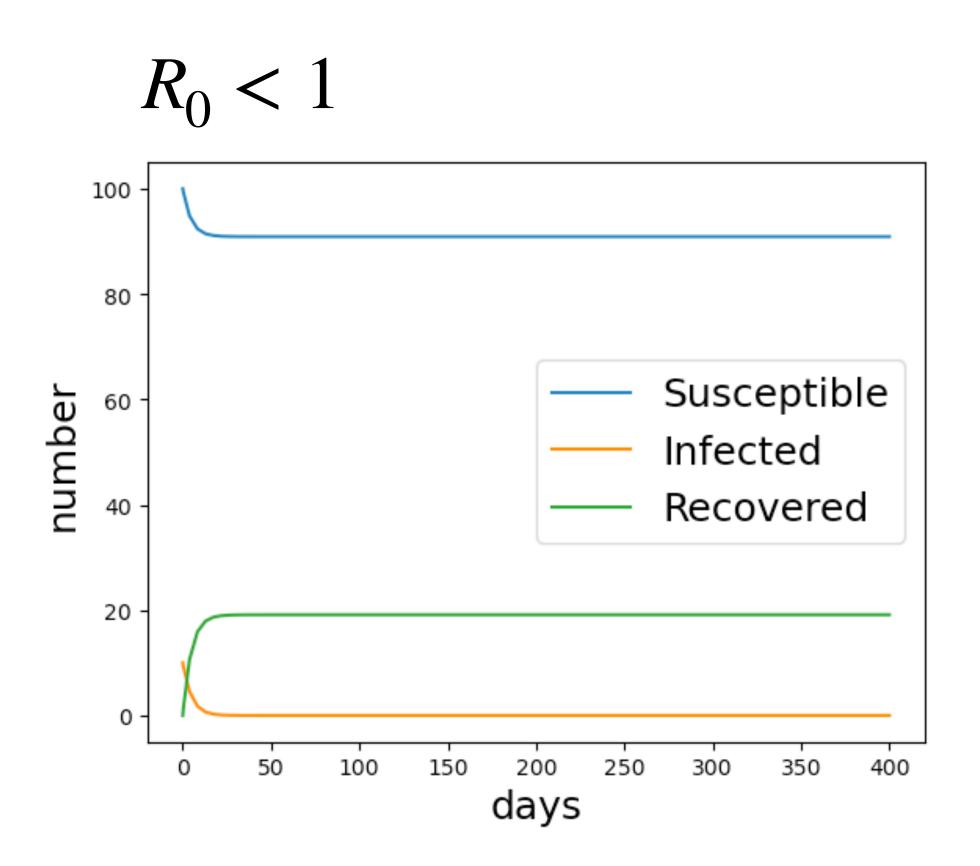
But not all fixed points are created equal!...

## Deviation from a fixed point

add a single infection...



Unstable: infections increase away from the fixed point. Pandemic!

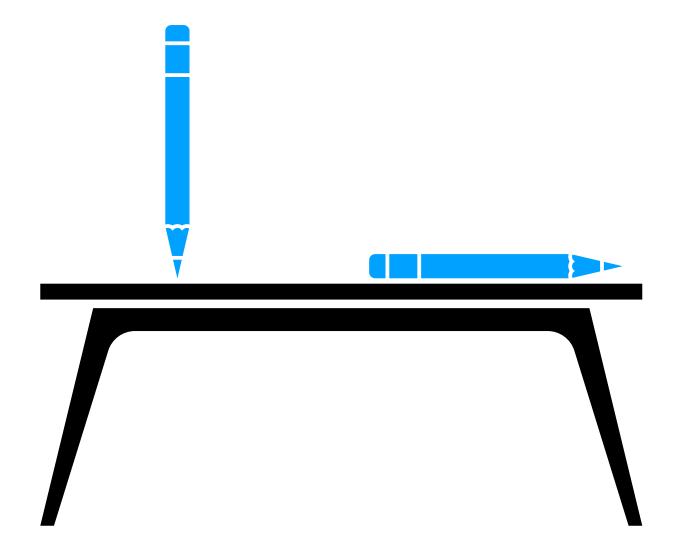


Stable: infections decrease back to the fixed point

## Fixed points for general ODE

$$\dot{x}(t) = f(x(t), t)$$

$$\dot{x}(0) = x_0$$



### **Fixed points:**

$$\{x^*: f(x^*, t) = 0\}$$

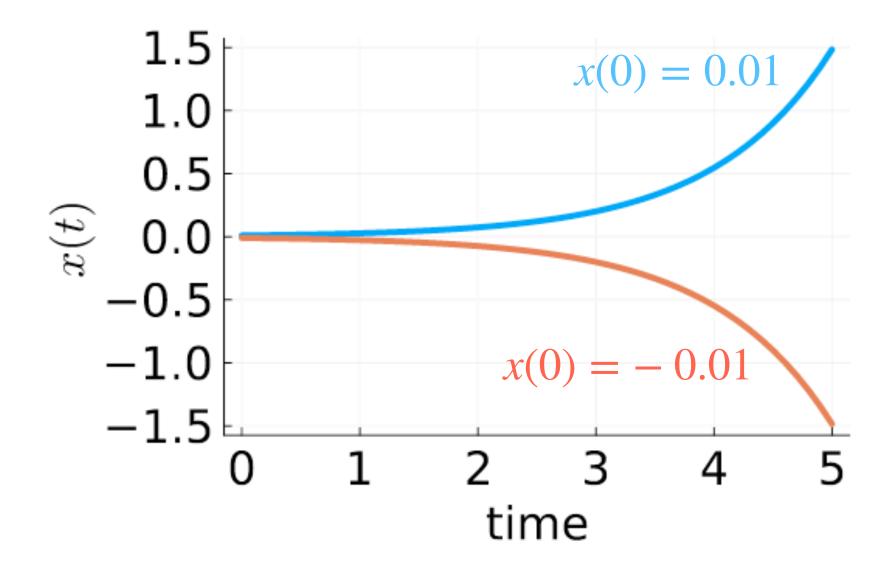
Definition of stability?

Can we infer from equations without simulating?

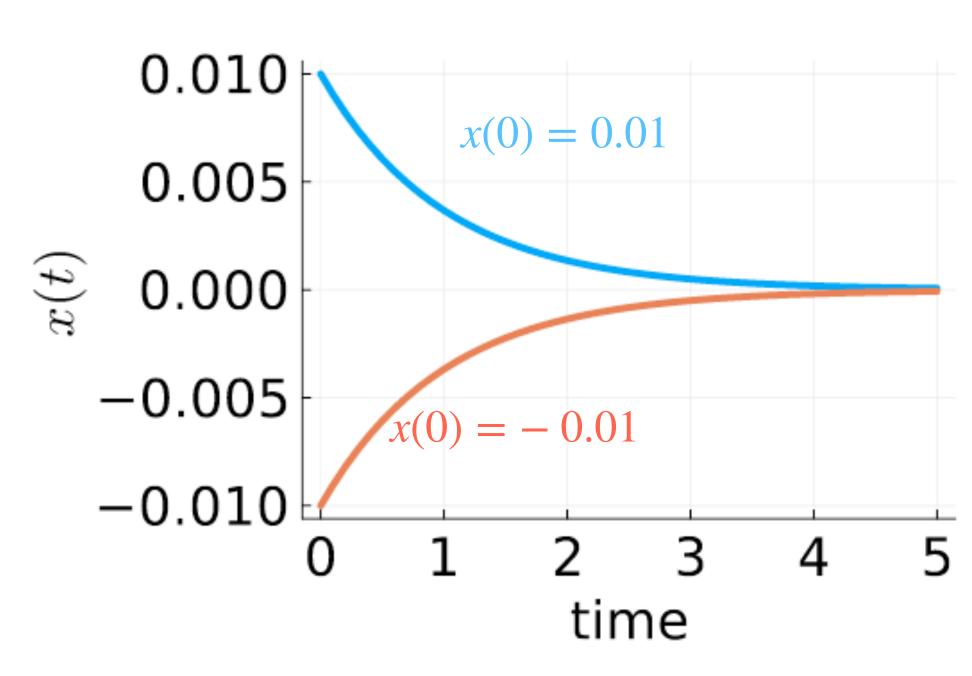
## Fixed points for scalar ODE

Small fixed point deviations with different effects:

$$\dot{x}(t) = x(t)$$

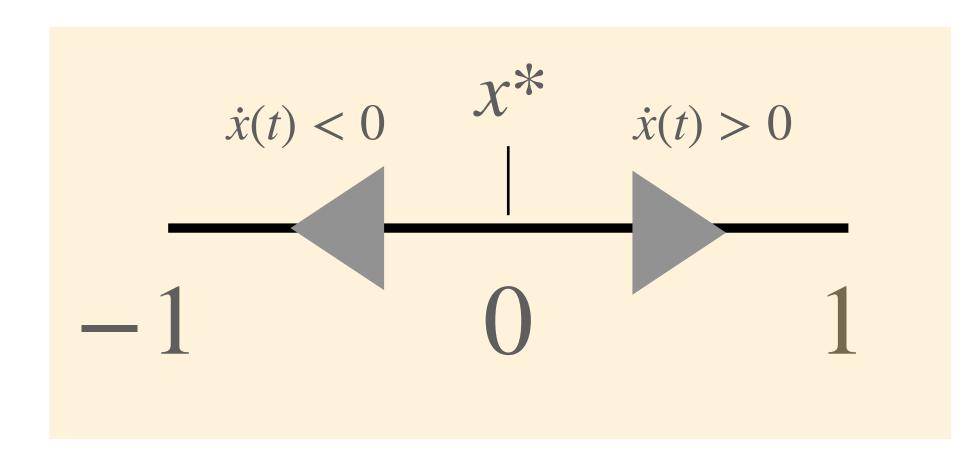


$$\dot{x}(t) = -x(t)$$



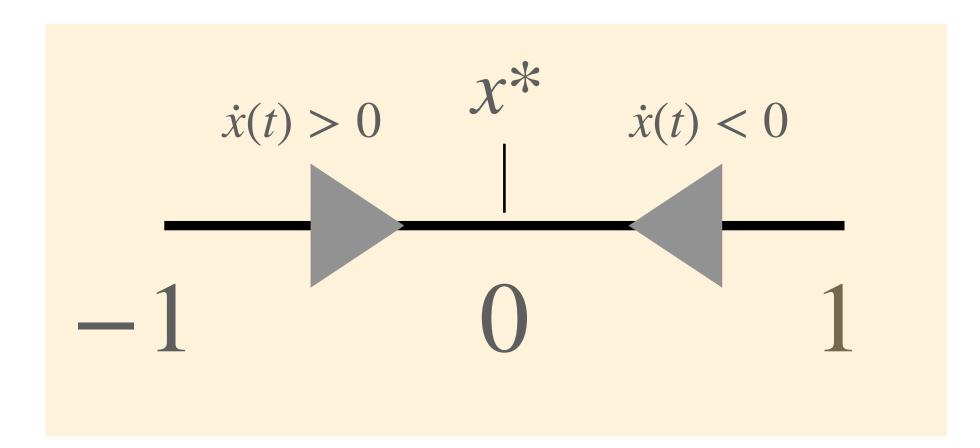
## Fixed points for scalar ODE

$$\dot{x}(t) = x(t)$$



Perturbation travels away from fixed point

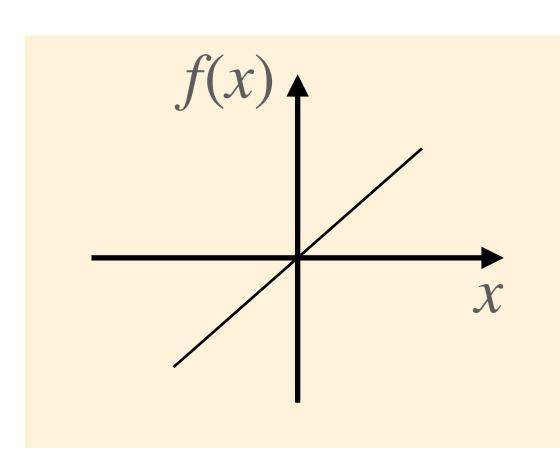
$$\dot{x}(t) = -x(t)$$



Perturbation travels back into fixed point

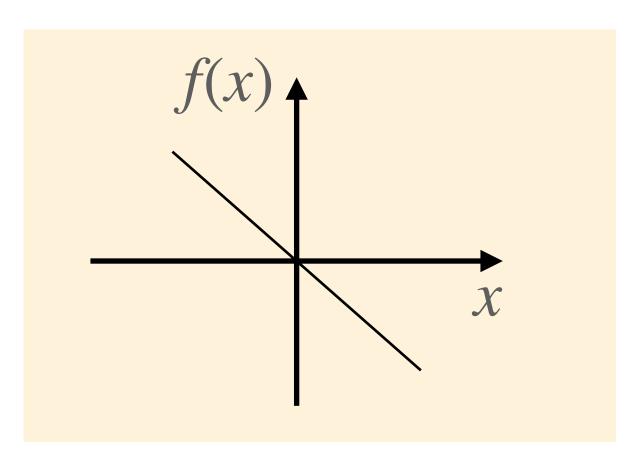
# Fixed points for scalar ODE $\dot{x}(t) = f(x(t))$

$$\dot{x}(t) = x(t)$$



$$\frac{\partial f}{\partial x} = 1 > 0$$

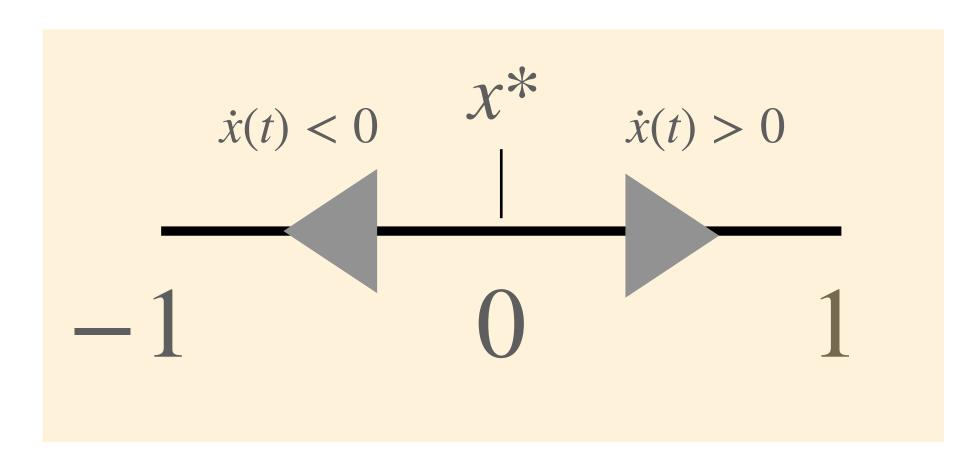
$$\dot{x}(t) = -x(t)$$



$$\frac{\partial f}{\partial x} = -1 < 0$$

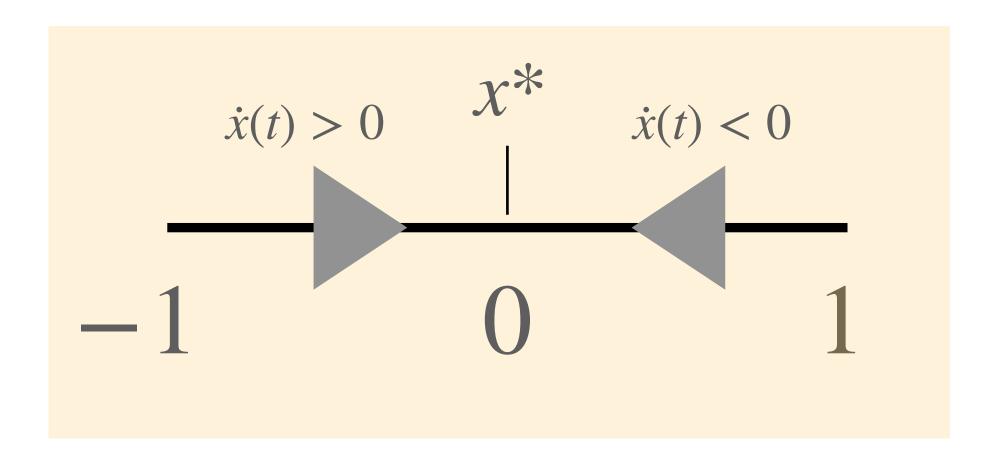
## Fixed points for scalar ODE $\dot{x}(t) = f(x(t))$

$$\dot{x}(t) = x(t)$$



$$\frac{\partial f}{\partial x} = 1 > 0$$

$$\dot{x}(t) = -x(t)$$



$$\frac{\partial f}{\partial x} = -1 < 0$$

## **Mathematical intuition**

$$\dot{x}(t) = f(x(t), t)$$

Fixed point:

$$f(x*(t)) = 0$$

Small perturbation from fixed point:

$$x(t) = x^* + \delta x(t)$$

Taylor expansion of derivative:

(Finite difference approximation)

$$\dot{x}^* + \dot{\delta x}(t) \approx f(x^*) + \delta x(t) \frac{\partial f}{\partial x}(x^*)$$

## **Mathematical intuition**

$$\dot{\delta x}(t) \approx \delta x(t) \frac{\partial f}{\partial x}(x^*)$$

$$\frac{\partial f}{\partial x} = 1 > 0:$$

Perturbation grows (instability)

$$\frac{\partial f}{\partial x} = -1 < 0$$
:

Perturbation shrinks (stability)

## Try for yourself

$$\dot{x}(t) = \sin(x(t)) - x(t)$$

$$\dot{x}(t) = x(t) - \sin(x(t))$$

Fixed point at zero: For which of these ODEs is it stable/unstable?

## Why was I so interested in the SIR model?

Most important skill in differential equation modelling is not maths

#### **Practice at:**

Making / justifying / criticising assumptions

Turning assumptions into equations

Turning equations into (qualified) insight

## Further improvements?

Reinfection, superspreader events, spatial modelling, ...

Play with seminar code at home!