## A Polynomial Time Incremental Algorithm for Regular Grammar Inference

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#### Abstract

We present an efficient incremental algorithm for learning regular grammars from labeled examples and membership queries. This algorithm is an extension of Angluin's ID procedure to an incremental framework. The learning algorithm is intermittently provided with labeled examples and has access to a knowledgeable teacher capable of answering membership queries. Based on the observed examples and the teacher's responses to membership queries, the learner constructs a deterministic finite automaton (DFA) with which all examples observed thus far are consistent. When additional examples are observed, the learner modifies this DFA suitably to encompass the information provided by the new examples. In the limit this algorithm is guaranteed to converge to a minimum state DFA corresponding to the target regular grammar. We prove the convergence of this algorithm in the limit and analyze its time and space complexities.

## 1 Introduction

Grammar Inference Biermann & Feldman, 1972; Fu & Booth, 1975; Miclet & Quinqueton, 1986; Langley, 1995] is an important machine learning problem with several applications in pattern recognition, language acquisition, and intelligent agent design. It is defined as the process of learning an unknown grammar given a finite set of labeled examples. Regular grammars describe languages that can be generated (and recognized) by deterministic finite state automata (DFA). Since they represent a widely used subset of formal languages, considerable research has been focused on regular grammar inference (or equivalently, identification of the corresponding DFA). However, given a finite set of positive examples and a finite, possibly empty set of negative examples the problem of learning a minimum state DFA equivalent to the unknown target is NP-hard [Gold, 1978. The learner's task is simplified, by requiring that the examples provided meet certain desired criteria (like structural completeness [Pao & Carr, 1978; Parekh & Honavar, 1996] or characteristic sample [Oncina & García, 1992]), or by providing the learner with access to sources of additional information, like a knowledgeable teacher who responds to queries generated by the learner, etc. The interested reader is referred to [Miclet & Quinqueton, 1986; Pitt, 1989; Langley, 1995; Parekh & Honavar, 1997] for recent surveys of different approaches to grammar inference.

In many practical learning scenarios, a live complete set of examples may not be available at the outset. Instead, a sequence of examples is provided intermittently and the learner is required to construct an approximation of the target DFA based on the examples and the queries answered by the teacher. In such scenarios, an on-line or incremental model of learning that is guaranteed to eventually converge to the target DFA in the limit is of interest. Particularly, in the case of intelligent autonomous agents, incremental learning offers an attractive framework for characterizing the behavior of the agents [Carmel & Markovitch, 1996]. Against this background, we present a provably correct, polynomial time, incremental, interactive algorithm for regular grammar infer-

ence that learns from *labeled examples* and *membership queries*. The proposed algorithm (IID) extends Angluin's ID algorithm [Angluin, 1981] to an incremental setting.

## 2 Preliminaries

Let  $\Sigma$  be a finite set of symbols called the *alphabet*.  $\Sigma^*$  denotes the set of strings over the alphabet.  $\alpha, \beta, \gamma$  will be used to denote strings in  $\Sigma^*$ .  $|\alpha|$  denotes the length of the string  $\alpha$ .  $\lambda$  is a special string called the *null* string and has length 0. Given a string  $\alpha = \beta \gamma$ ,  $\beta$  is the *prefix* of  $\alpha$  and  $\gamma$  is the *suffix* of  $\alpha$ . Let  $Pr(\alpha)$  denote the set of all prefixes of  $\alpha$ . Given two sets  $S_1$  and  $S_2$ , the *set difference* is denoted by  $S_1 \setminus S_2$  and the *symmetric difference* is denoted by  $S_1 \oplus S_2$ .

A Regular Grammar (G) is a finite set of rewrite (production) rules of the form  $A \longrightarrow aB$  or  $A \longrightarrow b$  where A and B are called non-terminals and a and b are called terminals. These rules are applied recursively to generate strings (containing terminal symbols only). The language, L(G), is the set of all strings generated by the grammar. Finite State Automata (FSA) are recognizers for regular grammars. A deterministic FSA (DFA), A, is a quintuple  $A = (Q, \delta, \Sigma, q_0, F)$  where, Q is a finite set of states,  $\Sigma$  is the finite set of input symbols called the alphabet,  $F \subseteq Q$  is the set of accepting states,  $q_0 \in Q$  is the start state, and  $\delta$  is the transition function:  $Q \times \Sigma \longrightarrow Q$  that gives the next state of the automaton upon reading a particular symbol. The extension of  $\delta$  to handle input strings is denoted by  $\delta^*$  and it maps  $Q \times \Sigma^* \longrightarrow Q$ . By definition,  $\delta^*(q,\lambda) = q \ \forall q \in Q$  and  $\delta^*(q,b\alpha) = \delta^*(\delta(q,b),\alpha)$ . The set of all strings accepted by A is its language, L(A).  $L(A) = \{\alpha | \delta^*(q_0,\alpha) \in F\}$ . Note that L(A) = L(G) if the DFA A is an acceptor for the regular grammar G. Fig. 1 shows the state transition diagram for a sample FSA.

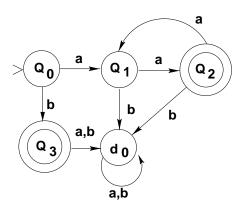


Figure 1: Finite State Automaton.

Given a regular language L(G) there exists a DFA A with minimum number of states that recognizes L(G). We call this minimum state acceptor for a regular language the canonical DFA and denote it as A(L(G)). Let N denote the number of states of A(L(G)).

Unless otherwise stated, we will now assume that A denotes the canonical DFA for a regular language L(G).

Given a canonical DFA A for a regular language L(G), a labeled example  $(\alpha, c(\alpha))$  is a 2-tuple with  $\alpha \in \Sigma^*$  and the classification function  $c: \Sigma^* \longrightarrow \{+, -\}$  is defined as follows:  $c(\alpha) = +$  if  $\alpha \in L(G)$  and  $c(\alpha) = -$  if  $\alpha \notin L(G)$ . A membership query is a query of the form " $\alpha \in L(G)$ ?". A teacher's response to the membership query is either yes or no depending on whether  $c(\alpha) = +$  or - respectively.

A state q of A is live if there exist strings  $\alpha$  and  $\beta$  such that  $\alpha\beta \in L(A)$ ,  $\delta^*(q_0, \alpha) = q$ , and  $\delta^*(q, \beta) \in F$ . A state that is not live is called dead. It can be verified that the canonical DFA for any regular language can have at most one dead state. We use  $d_0$  to denote this dead state. Given A, a finite set of strings P is said to be live-complete if for every live state q of A there exists a string  $\alpha \in P$  such that  $\delta^*(q_0, \alpha) = q$ . For example,  $P = \{\lambda, a, b, aa\}$  is a live-complete set for the DFA in Fig. 1. A live-complete set represents all the live states of A. We will assume that the string  $\lambda$  is part of any live-complete set to represent the start state of A. The set  $P' = P \cup \{d_0\}$  represents all states of A. To account for the state transitions, define a function  $f: P' \times \Sigma \longrightarrow \Sigma^* \cup \{d_0\}$  as follows:

$$f(d_0, b) = d_0$$
  
$$f(\alpha, b) = \alpha b$$

Note that  $f(\alpha, b)$  denotes the state reached on reading an input letter b from the state represented by the string  $\alpha$ . Let  $T' = P' \cup \{f(\alpha, b) | (\alpha, b) \in P' \times \Sigma\}$  and  $T = T' \setminus \{d_0\}$ .

## 3 The ID Algorithm

The *ID* algorithm for inference of regular grammars, its correctness proof, and complexity analysis are covered in detail in [Angluin, 1981]. Since the proposed incremental algorithm for grammar inference *IID*, extends *ID* to an incremental setting, to keep the discussion that follows self-contained, we review *ID* briefly in this section.

Given a canonical DFA A for a regular language and a live-complete set P for A, ID constructs a partition of the set T' (constructed from P as described above) such that elements of T' representing the same state of A are grouped together in the same block of the partition. In the process a set of strings V is constructed such that no two distinct states of A have the same behavior on all strings in V. When the set V has i elements, define function  $E_i: T' \longrightarrow 2^V$  as follows:

$$E_i(d_0) = \phi$$

$$E_i(\alpha) = \{v_j | v_j \in V, 0 \le j \le i, \alpha v_j \in L(A)\}$$

## Algorithm

**Input**: A live complete set P and a teacher to answer membership queries.

Output: A description of the canonical DFA for the target regular grammar.

```
begin
           i = 0, v_i = \lambda, V = {\lambda}, T = P \cup {f(\alpha, b) | (\alpha, b) \in P \times \Sigma} \text{ and } T' = T \cup {d_0}
           -E(d_0) = \phi
           - \forall \alpha \in T, pose the membership query "\alpha \in L(A)?".
                if the teacher's response is yes
                then E_0(\alpha) = \{\lambda\}
                else E_0(\alpha) = \phi
           while \exists \alpha, \beta \in P and b \in \Sigma such that
    3)
                    E_i(\alpha) = E_i(\beta) but E_i(f(\alpha, b)) \neq E_i(f(\beta, b))
           do
                - Let \gamma \in E_i(f(\alpha, b)) \oplus E_i(f(\beta, b))
                - Let v_{i+1} = b\gamma
                - Set V = V \cup \{v_{i+1}\} and i = i + 1
                -\forall \alpha \in T, pose the membership query "\alpha v_i \in L(A)?".
                        if the teacher's response is yes
                        then E_i(\alpha) = E_{i-1}(\alpha) \cup \{v_i\}
                        else E_i(\alpha) = E_{i-1}(\alpha)
           end while
           Output M computed as follows and STOP.
           - The states of M are the sets E_i(\alpha), where \alpha \in T
           - The initial state q_0 is the set E_i(\lambda)
           - The accepting states are the sets E_i(\alpha) where \alpha \in T and \lambda \in E_i(\alpha)
           -\mathbf{if} E_i(\alpha) = \phi
              then add self loops on the state E_i(\alpha) for all b \in \Sigma
              else \forall \alpha \in P and \forall b \in \Sigma, set the transition \delta(E_i(\alpha), b) = E_i(f(\alpha, b))
end
```

The following example demonstrates the working of the ID algorithm. Consider the DFA in Fig. 1 for which  $P = \{\lambda, a, b, aa\}$  is a live-complete set.  $T' = \{d_0, \lambda, a, b, aa, ab, ba, bb, aaa, aab\}$ . Table 1 shows the computation of  $E_i(\alpha)$  for strings  $\alpha \in T'$ . Note that the DFA returned by the procedure is exactly the DFA in Fig. 1. Angluin [Angluin, 1981] has shown that number of membership queries needed is  $\mathcal{O}(|\Sigma| \cdot N \cdot |P|)$ . Thus, ID runs in time polynomial in  $|\Sigma|$ , N, and |P|.

## 4 IID - An Incremental Extension of ID

We present the algorithm *IID* which extends *ID* to an incremental setting. Our learning model assumes the availability of a source of labeled examples and a teacher capable of answering membership queries posed by the learner. However, unlike in the case of *ID*,

i	0	1	2	3
$v_i$	λ	b	a	aa
$E(d_0)$	$\phi$	$\phi$	$\phi$	$\phi$
$E(\lambda)$	$\phi$	$\{b\}$	$\{b\}$	$\{b,aa\}$
E(a)	$\phi$	$\phi$	$\{a\}$	$\{a\}$
E(b)	$\{\lambda\}$	$\{\lambda\}$	$\{\lambda\}$	$\{\lambda\}$
E(aa)	$\{\lambda\}$	$\{\lambda\}$	$\{\lambda\}$	$\{\lambda, aa\}$
E(ab)	$\phi$	$\phi$	$\phi$	$\phi$
E(ba)	$\phi$	$\phi$	$\phi$	$\phi$
E(bb)	$\phi$	$\phi$	$\phi$	$\phi$
E(aaa)	$\phi$	$\phi$	{ <i>a</i> }	$\{a\}$
E(aab)	$\phi$	$\phi$	$\phi$	$\phi$

Table 1: Execution of ID.

a live-complete set of examples is not provided to the learner at the outset. Instead, the learner is required to gradually refine its model of the target DFA as new examples become available. Let  $M_t$  denote the DFA that corresponds to the learner's current model after observing t examples. Initially,  $M_0$  is a null automaton with only one state (the dead state) and it rejects every string in  $\Sigma^*$ . Clearly, every negative example encountered by the learner at this point is consistent with  $M_0$ . Without loss of generality we assume that the first example seen by the learner is a positive example. When the first positive example,  $\alpha$ , is observed  $M_0$  is modified to accept the positive example. With each additional observed example,  $\alpha$ , it is determined whether  $\alpha$  is consistent with  $M_t$ . i.e.,  $c(\alpha) = +$  and  $\alpha \in L(A)$  or  $c(\alpha) = -$  and  $\alpha \notin L(A)$  in which case  $M_{t+1} = M_t$ . Otherwise  $M_t$  is suitably modified such that  $\alpha$  is consistent with the resulting DFA,  $M_{t+1}$ . A detailed description of the algorithm follows:

## Algorithm

**Input**: A stream of labeled examples and a teacher to answer membership queries. **Output**: A DFA  $M_t$  with which all t examples observed by the learner are consistent.

#### begin

- 1)  $i = 0, k = 0, t = 0, P_k = \phi, T_k = \phi, V = \phi.$ Initialize  $M_t$  to the null DFA.
- 2) Wait for a positive example  $(\alpha, +)$   $-P_0 = Pr(\alpha)$  and  $P_0' = P_0 \cup \{d_0\}$   $-T_0 = P_0 \cup \{f(\alpha, b) | (\alpha, b) \in P_0 \times \Sigma\}$  and  $T_0' = T_0 \cup \{d_0\}$  $-v_0 = \lambda$  and  $V = \{v_0\}$

```
-E_0(d_0)=\phi
            -\forall \alpha \in T_0, pose the membership query "\alpha \in L(A)?".
                    if the teacher's response is yes
                    then E_0(\alpha) = \{\lambda\}
                    else E_0(\alpha) = \phi
           while \exists \alpha, \beta \in P_k and b \in \Sigma such that
    3)
                    E_i(\alpha) = E_i(\beta) but E_i(f(\alpha, b)) \neq E_i(f(\beta, b))
            do
                - Let \gamma \in E_i(f(\alpha, b)) \oplus E_i(f(\beta, b))
                - Let v_{i+1} = b\gamma
                - Set V = V \cup \{v_{i+1}\} and i = i + 1
                -\forall \alpha \in T_k, pose the membership query "\alpha v_i \in L(A)?".
                        if the teacher's response is yes
                        then E_i(\alpha) = E_{i-1}(\alpha) \cup \{v_i\}
                        else E_i(\alpha) = E_{i-1}(\alpha)
            end while
           Set t = t + 1 and construct M_t as follows:
           - The states of M_t are the sets E_i(\alpha), where \alpha \in T_k
           - The initial state q_0 is the set E_i(\lambda)
            - The accepting states are the sets E_i(\alpha) where \alpha \in T_k and \lambda \in E_i(\alpha)
           -\mathbf{if} E_i(\alpha) = \phi
              then add self loops on the state E_i(\alpha) for all b \in \Sigma
              else \forall \alpha \in P and \forall b \in \Sigma, set the transition \delta(E_i(\alpha), b) = E_i(f(\alpha, b))
           Wait for a new example (\alpha, c(\alpha))
           if \alpha is consistent with M_t
            then
                -M_{t+1} = M_t
                -t = t + 1
                - goto step 5
            else
                -P_{k+1} = P_k \cup Pr(\alpha) \text{ and } P'_{k+1} = P_{k+1} \cup \{d_0\}
                -T_{k+1} = T_k \cup \{f(\alpha, b) | (\alpha, b) \in \{P_{k+1} \setminus P_k\} \times \Sigma\} \text{ and } T'_{k+1} = T_{k+1} \cup \{d_0\}
                -\forall \alpha \in T_{k+1} \backslash T_k, fill in the entries for E_i(\alpha) by posing membership queries:
                        E_i(\alpha) = \{v_j | 0 \le j \le i, \alpha v_j \in L(A)\}
                -k = k + 1
                - goto step 3
end
```

### 4.1 Example

We show a sample run of the incremental algorithm for the DFA of Fig. 1.

The learner starts with a model  $M_0$  equivalent to the *null* DFA accepting no strings. Suppose the learner encounters the example (b, +). This causes the learner to take the following actions:

- $P_0 = \{\lambda, b\}$  and  $P'_0 = \{d_0, \lambda, b\}$
- $T_0 = \{\lambda, a, b, ba, bb\}$  and  $T'_0 = \{d_0, \lambda, a, b, ba, bb\}$
- The computation of the functions  $E_i$  is shown in Table 2.

i	0	1
$v_i$	λ	b
$E(d_0)$	$\phi$	$\phi$
$E(\lambda)$	$\phi$	$\{b\}$
E(a)	$\phi$	$\phi$
E(b)	$\{\lambda\}$	$\{\lambda\}$
E(ba)	$\phi$	$\phi$
E(bb)	$\phi$	$\phi$

Table 2: Execution of the incremental version of ID (k = 0).

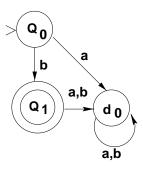


Figure 2: The intermediate DFA  $M_1$  in the incremental procedure.

At this point the learner constructs a model  $(M_1)$  of the target DFA (Fig. 2). Suppose the next example observed by the learner is (a, -). Since,  $M_1$  correctly rejects  $a, M_2 = M_1$  and the learner waits for additional examples.

Assume that the learner observes (aa, +) next. Since  $aa \notin L(M_2)$  the learner takes the following steps to update  $M_2$ :

$$\bullet \ P_1 = \{\lambda,a,b,aa\} \ \mathrm{and} \ P_1^{'} = \{d_0,\lambda,a,b,aa\}$$

- $T_1 = \{\lambda, a, b, aa, ab, ba, bb, aaa, aab\}$  and  $T'_1 = \{d_0, \lambda, a, b, aa, ab, ba, bb, aaa, aab\}$
- The function  $E_1$  is extended to cover the new elements belonging to  $T_1 \setminus T_0$ . The resulting computation of the various  $E_i$ 's is depicted in Table 3.

i	1	2	3
$v_i$	b	a	aa
$E(d_0)$	$\phi$	$\phi$	$\phi$
$E(\lambda)$	$\{b\}$	$\{b\}$	$\{b,aa\}$
E(a)	$\phi$	$\{a\}$	{ <i>a</i> }
E(b)	$\{\lambda\}$	$\{\lambda\}$	$\{\lambda\}$
E(ba)	$\phi$	$\phi$	$\phi$
E(bb)	$\phi$	$\phi$	$\phi$
E(aa)	$\{\lambda\}$	$\{\lambda\}$	$\{\lambda, aa\}$
E(ab)	$\phi$	$\phi$	$\phi$
E(aaa)	$\phi$	{ <i>a</i> }	{a}
E(aab)	$\phi$	$\phi$	$\phi$

Table 3: Execution of the incremental version of ID (k = 1).

This yield's a revised model  $(M_3)$  of the target DFA. It is easy to see that this is exactly the DFA we are trying to learn (Fig. 1). Note also that the set  $P_1$  is live-complete with respect to the target DFA.

#### 4.2 Correctness Proof

#### Theorem 1:

IID converges correctly to the canonical representation of the target DFA when the set  $P_k$  encompasses a live complete set  $(P_l)$  for the target.

#### Proof:

Consider an execution of ID given the live-complete set  $P_l$ . First we demonstrate that the execution of ID can be made to track that of IID in that the set V generated by both is the same and hence the values for  $E_i(\alpha) \forall \alpha \in T_l$  are the same for both executions. We prove this claim by induction.

#### Base Case:

Both ID and IID start with  $v_0 = \lambda$ .

At k = 0, IID has the set  $P_0$  available to it.  $P_0 \subseteq P_l$ . Clearly, for all strings  $\alpha, \beta \in P_0$  such that  $E_0(\alpha) = E_0(\beta)$  but  $E_0(f(\alpha, b)) \neq E_0(f(\beta, b))$  in the case of IID it is also the case that the same strings  $\alpha, \beta \in P_l$  for ID such that  $E_0(\alpha) = E_0(\beta)$  but  $E_0(f(\alpha, b)) \neq E_0(f(\beta, b))$ .

Assume that one such pair  $\alpha, \beta$  is selected by both ID and IID. The string  $\gamma \in E_0(f(\alpha, b)) \oplus E_0(f(\beta, b))$  can only be  $\lambda$ . Thus, the string  $v_1 = b\gamma$  is the same for both executions.

#### Induction Hypothesis:

Assume that after observing some t examples, at some value of k ( $0 \le k < l$ ), when  $P_k \subseteq P_l$  is available to IID, the sequence of strings  $v_0, v_1, \ldots, v_i$  and the values  $E_i(\alpha) \forall \alpha \in T_k$  are the same for both executions.

#### Induction Proof:

We now show that the same string  $v_{i+1}$  is the generated by both ID and IID. Following the reasoning presented in the base case, and the induction hypothesis we can state that for all strings  $\alpha, \beta \in P_k$  such that  $E_i(\alpha) = E_i(\beta)$  but  $E_i(f(\alpha, b)) \neq E_i(f(\beta, b))$  in the case of IID it is also the case that the same strings  $\alpha, \beta \in P_l$  for ID such that  $E_i(\alpha) = E_i(\beta)$  but  $E_i(f(\alpha, b)) \neq E_i(f(\beta, b))$ .

Assume that one such pair  $\alpha, \beta$  is selected by both executions. Then  $E_i(f(\alpha, b)) \oplus E_i(f(\beta, b))$  is the identical for both. Thus given that the same string  $\gamma \in E_i(f(\alpha, b)) \oplus E_i(f(\beta, b))$  is selected, the string  $v_{i+1} = b\gamma$  is identical for both executions.

Thus, we have shown that after observing some t examples when the live-complete set  $P_l$  is available to IID the values of  $E_i(\alpha) \, \forall \alpha \in T_l$  are exactly the same as the corresponding values of  $E_i(\alpha)$  for ID.

[Angluin, 1981] has shown that the DFA M returned by ID is isomorphic to the canonical DFA A for the target whenever ID is provided with a live-complete set. From above we know that at k = l the current model  $(M_t)$  of the target automaton maintained by IID is identical to one that arrived at by ID. Thus, we have proved that the incremental version correctly converges to a canonical representation of the target DFA.

#### Theorem 2:

At any time during the execution of the learning algorithm, all the (t) examples observed by the learner are consistent with the current representation of the target  $(M_t)$ .

#### Proof:

Suppose  $M_t$  is modified after observing an example  $\alpha$  not consistent with it. Upon observing  $\alpha$ ,  $P_k$  is modified to include  $\alpha$  and all its prefixes. Since  $T_{k+1}$  contains  $\alpha$  and we are assuming that the teacher correctly answers membership queries, we know that the function  $E_j$  from which  $M_{t+1}$  is constructed is such that  $E_j(\alpha)$  contains  $\lambda$  if  $c(\alpha) = +$  or does not contain  $\lambda$  if  $c(\alpha) = -$ . Thus,  $\alpha$  is consistent with  $M_{t+1}$ .

We now show that all strings  $\alpha$  consistent with  $M_t$  are also consistent with  $M_{t+1}$ .

By construction, the states of  $M_t$  are represented by  $E_i(\beta)$   $\forall \beta \in T_k$ , and for any state q of  $M_t$  that is represented by  $E_i(\beta)$ ,  $\delta^*(q_0, \beta) = q$ . Thus for any string  $\alpha$  such that  $\delta^*(q_0, \alpha) = q$ , it is clear that there is a corresponding string  $\beta \in T_k$  such that  $\delta^*(q_0, \alpha) = \delta^*(q_0, \beta)$ . Further, if  $\alpha$  is consistent with  $M_t$ , we know that  $\lambda \in E_i(\beta)$  if  $c(\alpha) = +$  or  $\lambda \notin E_i(\beta)$  if  $c(\alpha) = -$ . We prove that for all strings  $\alpha$  that are consistent with  $M_t$ , there exists a string  $\gamma \in T_{k+1}$  such that  $\delta^*(q_0, \alpha) = \delta^*(q_0, \gamma)$  (in  $M_{t+1}$ ) and for some  $j \geq i$ ,  $\lambda \in E_i(\gamma)$  if  $c(\alpha) = +$  or  $\lambda \notin E_i(\gamma)$  if  $c(\alpha) = -$ .

Consider the ID algorithm. The set T is partitioned such that all elements representing the same state are grouped together in the same block of the partition. The initial partition (corresponding to  $v_0 = \lambda$ ) separates the elements of T into accepting and non-accepting states. Further refinements of the partition correspond to the strings  $v_i$  that tell apart elements that do not represent the same state. These refinements involve splitting individual blocks of the current partition. The new blocks (obtained by splitting an existing block) differ from each other only in terms of the string  $v_i$ . Since  $v_0 = \lambda$  and  $v_i \neq \lambda$  ( $\forall i > 0$ ), we see that refinements of a block containing the string  $\lambda$  will still contain  $\lambda$  and refinements of a block not containing the string  $\lambda$  will not have  $\lambda$  as part of them now.

The situation is similar for IID. Consider a string  $(\alpha, c(\alpha))$  that is consistent with  $M_t$ . This means that  $\exists \beta \in T_k$  such that  $\delta^*(q_0, \alpha) = \delta^*(q_0, \beta)$  (in  $M_t$ ) and  $\lambda \in E_i(\beta)$  if  $c(\alpha) = + \text{ or } \lambda \notin E_i(\beta) \text{ if } c(\alpha) = -.$  After seeing an example that is not consistent with  $M_t$ , the learning algorithm modifies  $T_k$  to  $T_{k+1}$  and computes  $E_i$  for the strings belonging to  $T_{k+1} \setminus T_k$ . The extended  $E_i$  represents a partition of  $T_{k+1}$  that has the same number of blocks as the partition of  $T_k$  but with each block possibly having more elements now (since  $T_k \subseteq T_{k+1}$ ). Assume that strings  $v_{i+1}, v_{i+2}, \ldots, v_j$  are generated and the functions  $E_{i+1}, E_{i+2}, \ldots, E_j$  are computed thereby progressively refining the partition of  $T_{k+1}$  represented by  $E_i$ . The block represented by  $E_i(\beta)$  might be split and the state  $\delta^*(q_0,\alpha)$  will now correspond to one of these newly created blocks (say the one represented by  $E_i(\gamma)$ ). By following the argument for the ID we know that all the blocks created by splitting the block represented  $E_i(\beta)$  will contain (or not contain)  $\lambda$  depending on whether  $E_i(\beta)$ contained (or did not contain)  $\lambda$ . We have thus proved that there exists a string  $\gamma \in T_{k+1}$ such that  $\delta^*(q_0,\alpha) = \delta^*(q_0,\gamma)$  (in  $M_{t+1}$ ) and for some  $j \geq i, \lambda \in E_j(\gamma)$  if  $c(\alpha) = +$  or  $\lambda \notin E_i(\gamma)$  if  $c(\alpha) = -$ . i.e., all strings  $\alpha$  that were consistent with  $M_t$  are also consistent with  $M_{t+1}$ .

## 4.3 Complexity Analysis

Assume that at some k = l the set  $P_l$  encompasses a live-complete for the target DFA A. We have shown in the correctness proof of the incremental algorithm that at this point the algorithm's current representation of the target would be isomorphic to A.

The size of  $T_l$  is at most  $|\Sigma| \cdot |P_l| + 1$ . Also, the size of V is no more than N (the number of states of A). Thus the total number of membership queries posed by the

learner is  $\mathcal{O}(|\Sigma| \cdot |P_l| \cdot N)$ . Searching for a pair of strings  $\alpha, \beta$  to distinguish two states in the current representation of the target takes time that is  $\mathcal{O}(T_l^2)$ . Thus, the incremental algorithm runs in time polynomial N,  $|\Sigma|$ , and  $|P_l|$ .

Since the size of  $T_l$  is at most  $|\Sigma| \cdot |P_l| + 1$ , the size of V is no more than N, and the function  $E_i$  is replaced by the function  $E_{i+1}$  the space complexity of the algorithm is  $\mathcal{O}(|\Sigma| \cdot |P_l| \cdot N)$ .

## 5 Discussion

Efficient and provably convergent algorithms for grammar inference find applications in a broad range of problems in artificial intelligence, pattern recognition, and intelligent agent architectures. The proposed incremental algorithm for regular grammar inference, IID, is guaranteed to converge to an unknown target grammar and has polynomial time and space complexities. This extends previous work of Angluin [Angluin, 1981] to an incremental setting.

In related work, Parekh and Honavar have proposed a provably correct algorithm for regular grammar inference based on the version space approach for searching the candidate space of finite state automata [Parekh & Honavar, 1996]. Their approach searches a lattice of FSA generated by successive state mergings of a prefix tree automaton (PTA) which is essentially a lookup table for a set of positive examples of the target grammar. The lattice is represented compactly as a version space and is guaranteed to contain the target FSA (provided the set of positive examples is structurally complete). A candidate elimination algorithm which updates the version space based on the teacher's responses to membership queries is guaranteed to eventually converge to the target grammar. In the incremental framework they assume that the positive examples (needed to construct a structurally complete set) are provided intermittently. The algorithm augments the version space as needed in response to these new positive examples. Assuming that the examples are provided in increasing order by length, convergence to the target FSA is guaranteed when a structurally complete set of positive examples has been processed. Though provably correct, this algorithm has practical limitations because the size of the lattice grows exponentially with the number of states of the PTA.

Dupont has proposed an incremental version of the RPNI algorithm [Oncina & García, 1992] for regular grammar inference [Dupont, 1996]. This algorithm is also based on the idea of a lattice of partitions of the states of a PTA for a set of positive examples. It uses information from a set of negative examples to guide the ordered search through the lattice and is guaranteed to converge to the target DFA when the set of examples seen by the learner include a characteristic sample for the target automaton as a subset. The algorithm runs in time that is polynomial in the sum of lengths of the positive and negative examples. However, it requires storage of all the examples seen by the learner to ensure that each time the representation of the target is modified, it stays consistent with all examples seen previously.

Porat and Feldman [Porat & Feldman, 1991] have proposed an incremental algorithm for inference of regular grammars from a complete ordered sample. The algorithm is an iterative strategy that works with the current encoding of the examples seen thus far and modifies it suitably if this encoding is not consistent with the next labeled example. Their algorithm is also guaranteed to converge in the limit provided the examples appear in strict lexicographic order. The algorithm works with only a finite working storage which is an advantage over the incremental extension of the RPNI algorithm. Besides requiring an ordered presentation of the examples, this algorithm also requires a consistency check with all the previous examples when the current representation of the target is modified by the algorithm.

Our framework for incrementally learning a regular grammar from labeled examples does not require storage of all the examples. Only those examples that are inconsistent with the current representation of the target are required to be stored (implicitly) by the learner. The algorithm does not require any specific ordering of the labeled examples. Furthermore, the incremental modification of learner's representation of the target DFA is guaranteed to be consistent with all the examples processed by the learner at any stage during learning and no explicit consistency check is needed. The reader should note that like the *ID* algorithm, this incremental version also avails of a knowledgeable teacher capable of answering membership queries.

Regular grammars can be used to capture the behavior of *intelligent agents* like robots navigating in a finite world. Incremental regular grammar inference can provide a framework for these agents to learn from experience in an unfamiliar environment. Given its efficiency and guaranteed consistency with all examples seen thus far, our algorithm can provide an effective tool for agent learning, especially in an interactive setting.

The learner's reliance on the teacher to provide accurate responses to membership queries poses a potential limitation in applications where a reliable teacher is not available. We are exploring the possibility of learning in an environment where the learner does not have access to a teacher. The algorithms due to Dupont [Dupont, 1996] and Porat & Feldman [Porat & Feldman, 1991] operate in this framework. Some open problems include whether the limitations of these algorithms (e.g., need for storage of all the previously seen examples and complete lexicographic ordering of examples) can be overcome without sacrificing efficiency and guaranteed convergence to the target. In this context, it is of interest to explore alternative models of learning that: relax the convergence criterion (for example, allow approximate learning of the target within a given error bound); provide for some additional hints to the learning algorithm (like a bound on the number of states of the target DFA); include a helpful teacher that carefully guides the learner (perhaps by providing simple examples first).

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