

Abstract

1 Introduction

1.1 Geological and tectonic summary

- Large scale overview/summary of regions under study
- Justification for selecting these regions?

1.2 Previous geophysical studies

- Lithoprobe and attendant papers
- Teleseismic studies

2 Data and methods

Our analysis of bulk Canadian continental crust is based on estimates of crustal properties that can be accessed via seismic techniques, namely seismic wave velocities (or velocity ratio) and crustal thickness. This study draws on three sources for these crustal properties. The first and primary source is teleseismic receiver function (hereafter RF) analysis. The remaining two datasets are Crust 1.0, a widely published statistical average of similar regions with a global two degree resolution, and a compilation of pre-processed active source data (Mooney, 2012). Both Crust 1.0 and the active source compilation are used to qualify and compare with the primary dataset.

2.1 Teleseismic Data Set

The primary data utilized in this study are computed from teleseismic P wave seismograms originating from more than 700 earthquake sources. These earthquakes occurred between 2000 and 2012 and were recorded on subsets of 343 broadband seismic stations distributed across Canada. Seismic stations are selected from all available regional and national networks including

CNSN, POLARIS, FedNor and Chasme. Seismograms are included for analysis if they fall within a 30 to 100° epicentral distance window. Quality control is performed by admitting only those seismograms with sufficiently high signal to noise ratios to permit visual observation of the dominant P wave energy and with sufficiently impulsive first arrivals to allow arrival onsets to be accurately measured. After selection and filtering more than 80,000 events are available for further processing.

The first stage of processing requires the transformation of teleseismic data into receiver functions. In general terms, this transformation involves deconvolving an approximation of the earthquake source from horizontal recordings of ground motion [Langston, 1979]. The resulting waveforms contain discrete pulses corresponding to S waves scattered from subsurface discontinuities including the base of the crust, or Moho. Confident identification of these peaks is required to estimate crustal parameters, and improved results can be obtained by transforming the displacement seismogram into their P and S contributions based on a 1-D model of propagation. This procedure is accomplished by first rotating the N and E coordinates into radial and transverse directions and then performing a wave field decomposition using the radial and vertical channels [Kennet, 1991]. The direct P arrival of the signal on the resulting P wave component is used as an approximation to the source function as P component impulse response for teleseismic P approximates a delta function. This windowed source estimate is deconvolved from the S wave component computed from the wave field decomposition.

We employ an L_2 , multichannel, frequency domain approach to perform the deconvolution that has the advantage of computational efficiency and does not require *a priori* assumptions concerning the noise levels in the data. More specifically, we employ a simultaneous deconvolution of N seismograms sharing a similar slowness to compute a single impulse response or receiver function $r(t)$.

$$r(t) = \mathcal{F}^{-1} [G(\omega)] = \mathcal{F}^{-1} \left[\frac{\sum_n^N S_n(\omega) P_n^*(\omega)}{\sum_n^N P_n(\omega) P_n^*(\omega) + \delta} \right], \quad (1)$$

where \mathcal{F}^{-1} is the inverse Fourier transform, S_n represents the n^{th} S wave seismogram, P_n is the corresponding windowed P wave seismogram, $*$ denotes complex conjugation and δ is the regularization parameter controlling the trade off between model smoothness and data misfit. The parameter δ which is chosen programatically by minimizing the general cross validation function

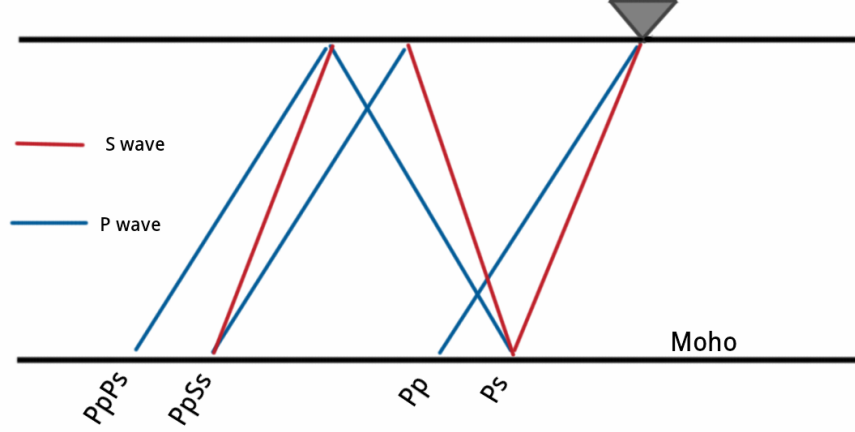


Figure 1: Schematic diagram illustrating geometry of phases for the velocity contrast representing the Moho

$GCV(\delta)$ is given by

$$GCV(\delta) = \frac{\sum_n^N \sum_m^M (S_n(\omega_m) - P_n(\omega_m)G(\omega_m))^2}{(NM - \sum_m^M X(\omega_m))^2}, \quad (2)$$

where

$$X(\omega_m) = \frac{\sum_n^N P_n(\omega_m)P_n^*(\omega_m)}{\sum_n^N P_n(\omega_m)P_n^*(\omega_m) + \delta}, \quad (3)$$

and ω is the frequency bin in the discrete Fourier transform. All resulting receiver functions, $r(t)$, are filtered between 0.04Hz and 3.0Hz.

2.2 V_p/V_s method

A well tested and widely published method for extracting the ratio of P velocity V_P to S velocity V_S , hereafter referred to as R , and crustal thickness (or depth to Moho) H , is outlined by Zhu and Kanamori [2000], hereafter ZK. This method exploits the dependence of these parameters to the differential

arrival times between the S wave reflected phases Ps , $PpPs$, $PsPs$, $PpSs$ and $PsSs$ and the direct P wave arrival Pp (Fig 1). Note that $PsPs$ and $PpSs$ are kinematic analogues, such that the energy for these two phases arrive simultaneously for a 1-D model. For a range of slowness values, p , the differential arrival times, $t(p)$, trace moveout curves for each phase arrival given by

$$t_{Ps}(p_n) = \frac{H}{V_P} \left[\sqrt{R^2 - V_P^2 p_n^2} - \sqrt{1 - V_P^2 p_n^2} \right] \quad (4)$$

$$t_{Pps}(p_n) = \frac{H}{V_P} \left[\sqrt{R^2 - V_P^2 p_n^2} + \sqrt{1 - V_P^2 p_n^2} \right] \quad (5)$$

$$t_{Pss}(p_n) = \frac{2H}{V_P} \sqrt{R^2 - V_P^2 p_n^2} \quad (6)$$

where p_n is the slowness for the n^{th} receiver function. Since strong reflected phases occur at sharp velocity contrasts, the Moho, the boundary targeted by ZK, tends to be well represented on most RF's.

The travel time equations, as employed by ZK, assume a value for crustal P wave velocity, V_P , that in practice will trade-off to some degree with crustal thickness H . In our implementation of the ZK approach, each station is assigned a V_P value corresponding to the Crust 1.0 value for the corresponding 2° containing cell. In the specific cases where data are being compared to previously published results for quality control, V_P values are chosen to match the values in the published study.

RFs are stacked along trial moveout curves for a range of candidate models of R and H to generate a fitness function $s(H, R)$. Within the stacking procedure, each phase is assigned a weight to account for the expected relative amplitudes of the phases for typical velocity contrasts, with the direct conversion Ps usually characterized by the highest quality signal followed by $PpPs$ and $PpSs$. We chose weights of $w1 = 0.5$, $w2 = 0.3$, $w3 = -0.2$ for the Ps , $PpPs$ and $PpSs$ phases, respectively. A negative weight for the combined $PpSs$ and $PsPs$ phases is required as the polarity of the signal is reversed. Semblance weighting [Eaton, 2006] is employed to reduce the effect of spurious large amplitude noise in the data. The semblance function assigns a weight between zero (incoherent noise) and one (coherent signal). The stacking function is therefore defined as

$$s(H, R) = \sum_{m=1}^3 S_m \sum_{n=1}^N w_m r_n(t_m) \quad (7)$$

where

$$S_m(H, R) = \frac{\left[\sum_{n=1}^N r_n(t_m) \right]^2}{\sum_{n=1}^N r_n^2(t_m)} \quad (8)$$

is the semblance weight for the m^{th} phase, time t_m is calculated from the corresponding travel time function for a given H , R pair as a function of slowness p_n and N is the total number of receiver functions. Multiplying by the semblance weighting sharpens the stacked image, $s(H, R)$, and results in better resolution when discriminating between different models. The function $s(H, R)$ can be thought of as a transformation that maps times of the Ps , $PpPs$ and $PpSs+PsPs$ phases into R and H space as positive bands, via Eq. 7. Constructive interference where these bands intersect produce a maximum in the stacking function. The model, R and H , that produces this maximum provides the best estimate for the bulk crustal parameters for a given seismic station.

A limitation of the ZK approach is the requirement of an initial V_P estimate. In principal we may compute the stacking function Eq. 7, as a function of all three seismic parameters, $s(H, R, V_P)$. Taking advantage of modern multi-core systems with reasonable quantities of data (fifty to a few hundred RFs) and a moderate search space (n^3 parameter candidates where $n \approx 150$) the computational time makes this method easily scalable to hundreds of stations. This “fullgrid” approach is analyzed to determine the viability of recovering V_P .

The trade-off between V_P and H (and other parameter combinations) and error resulting from data quality are quantified for both the full parameter search and ZK methods by bootstrap resampling [Efron and Tibshirani, 1986]. An estimate for the error is calculated in a bootstrap resampling approach by taking the standard deviation of 1024 parameter estimates each produced with randomly selected RFs, with replacement.

2.3 Additional data

We supplement receiver function estimates of crustal properties with data from controlled source experiments collected and compiled from GSC (Geo-

logical Survey of Canada) references by Walter Mooney (personal communication, 2012). The active source data provide V_P and a few V_S estimates for hundreds of locations across Canada, many along transects that cross major geological boundaries, faults and discontinuities. Some of these data are located within reasonable (<100 km) proximity to seismic stations used in this study and can be used to compare with the V_P and V_S estimates resulting from the RF full gridsearch.

The Crust 1.0 model [Laske et. al., 2013] employs many of these same active source data to provide regular, complete coverage across all of Canada. The model includes estimates of V_P and V_S information with depth at 1° resolution in latitude and longitude. In addition to employing local active source data, Crust 1.0 is also constrained by statistically aggregated data from geographically distant but geologically similar regions. It therefore affords a somewhat independent dataset suited for comparison with the crustal estimates calculated in this study.

3 Results

3.1 Comparisons

Three published studies have provided parameter estimates for R and H for subsets of the seismic stations considered here. The most recent study [Thompson et. al., 2010] focused on the northern Canadian Shield and employs both the linear stacking approach used by ZK as well as a phase weighted method. A 2007 study of the Superior Province [Darbyshire et. al, 2007] and a study of the Grenville Orogen [Eaton et. al., 2006] utilize the ZK + semblance approach outlined in section 2.2. Comparisons between crustal estimates of R for particular seismic stations are made for those values with corresponding standard errors of less than ± 0.06 . This error threshold is chosen empirically as that which best partitions those receiver function stacks with visually recognizable energy along phase moveout curves from those where lack of data or poor quality make these moveout curves difficult to distinguish. For each study under comparison, data are reprocessed using the V_P chosen by the study authors. For the 2006 and 2007 studies the ZK + semblance method is used whereas for the Thompson et. al study the linear stacking ZK approach is employed. Both correlation coefficient and mean difference are provided in (Table 1) as measures of similarity.

Study Authors	Region	Correlation Coeff.		RMS difference		
		Num. of Stns	H	R	$H(\text{km})$	R
Thompson et. al. (2010)	Northern Canadian Shield	29	0.97	0.70	0.78	0.70
Darbyshire et. al. (2007)	Superior Province	10	0.95	0.43	1.71	0.43
Eaton et. al. (2006)	Grenville Orogen	26	0.90	0.61	1.03	0.61

Table 1: Comparison of R and H estimates with three published studies

All three studies reported H estimates that correlate strongly with the crustal thickness parameters computed here. The data from the northern Canadian Shield shows strong correlation in both H and R . The lower correlation observed in estimates of R than H is not unexpected as the range of R is relatively narrow and small changes ($\approx 2\%$) are physically meaningful. A corollary of this is greater sensitivity of R to differences in procedure such as the choice of deconvolution algorithm and selection and scaling of data. The results from Thompson et. al. [2010] also correspond most closely to the parameter estimates computed here, with the mean difference for both parameters being less than half of the averaged bootstrap error computed in this study. Results published by Eaton et. al. [2006] show reasonable correlations in both R and H and a mean difference for both parameters that is roughly equal to the averaged uncertainty in the data. Parameter estimates from the Superior Province [Darbyshire et. al., 2007] show the lowest correlation in R as well as the highest mean difference in both parameters. These differences are well over the averaged computed error, and can not be easily explained by deviation related to noise in the data.

3.2 Full Grid Search Analysis

We now proceed to compare our results computed using the ZK approach with those from the full grid search (Table 2). We note that the velocity ratio R has a correlation between the two datasets of 0.76 whereas H has a correlation of 0.51. The low correlation between crustal thickness estimates can be explained by the strong tradeoff between H and V_P through the quantity

$$\frac{t_{Pps} - t_{Ps}}{2} = \frac{t_{Pss}}{2} - t_{Ps} = \frac{H}{V_P} \sqrt{1 - p^2 V_P^2}.$$

As a consequence, contours of the misfit surface $s(H, R, V_P)$ are highly ex-

tended along the kinematic curve in the $H - V_P$ space (Figure 5). This trade-off contributes to the low correlation in H between the two methods. Higher correlation in this quantity can be restored by dividing out V_P from H . The trade-off between the other parameters is lower as there is greater dependence between them such that a small change in one necessitates a large change in an other to maintain travel-time equality, which has the result of a well defined misfit surface (Figures 3-4).

For all but the cleanest stations, the trade-off between H and V_P renders recovery of V_P unfeasible using the full grid approach. A comparison between two stations, ULM, the station with the highest quality RFs, and DORN, a station exhibiting less resolution in the reflected phases, illustrates this difficulty. RFs are arranged vertically, ordered by increasing slowness, and shown in figures 2 and 6. Cross sections of $s(H, R, V_P)$ through each coordinate plane are displayed for ULM and DORN in figures 3-5) and figures 7-9. The lower resolution apparent in the $H - V_P$ cross section for DORN translates into a bootstrap error of $V_P \pm 0.64\text{km/s}$. Station ULM, with cleaner data, has less trade-off between H and V_P as indicated by the corresponding cross section and the lower bootstrap error of $V_P \pm 0.16\text{km/s}$.

Active source experiments located near broadband seismic stations provide independent crustal thickness and P wave velocity estimates to test against data derived from the full parameter search method. We select stations with low error in V_P and active source experiment locations within a 100 km radius. If several active source experiments are located within this radius, estimates are averaged. Four stations (ARVN, TYNO, ULM and WHY) meet these criteria and the parameter estimates are presented in figure 10-11. Estimates computed from the full grid approach are roughly 0.25 km/s higher than the active source data. This difference is consistent across all four stations and is exemplified by a 99% correlation, suggesting possible bias. However, the limited number of data means this bias is poorly constrained.

There is less correlation between the crustal thickness data, though this is largely attributed to an approximate 10 km difference between the ARVN estimates. The reason for this discrepancy is unknown though both the ZK method and a published study [Thompson et. al., 2010] provide an estimate of near 41 km for ARVN, much nearer the full grid value of 42 km. Despite lower correlation the apparent bias towards higher values computed from teleseismic data is also maintained for H . A positive bias in one parameter will tend to bias the other, owing to the relationship between

Parameter	correlation coeff
R (km)	0.76
H	0.51
H/V_P	0.96

Table 2: Correlation between parameters computed from ZK + semblance and full parameter search methods

thickness, velocity and times of a scattered phase. For a constant t_{ps} one may compute how much H must change for a 0.25 km/s bias in V_P [Zhu and Kanamori, 2000]. Using an average of the parameter estimates from the two cleanest stations, ULM and WHY, δH will be 1.3 km, this fits well with the actual bias in the values.

[[SOURCES REGARDING BIAS]] [[WHAT DOES THIS MEAN, IS VP USABLE FOR THE HIGHEST QUALITY STATIONS?]]

3.3 Crustal Discontinuities

We now consider the average crustal structure across Canada. We produce a depth profile for each station by stacking receiver functions along traveltime curves corresponding to a range of values in H (0 to 50 km in increments of 100 metres) using the estimates for R computed via the ZK + semblance method. The resulting profiles contain energy at depths corresponding to major velocity discontinuities and are shown in figure 13 arranged by increasing crustal thickness. By assembling all depth profiles into a matrix, we may decompose the data via SVD into their principal components. Figure 12 contains the first five singular vectors or modes normalized to unit magnitude that account for 78% of the variance in the profiles. Higher modes correspond to diminishing contributions to total variance. Each vector is normalized to unit magnitude. The first mode (blue) is effectively the average depth profile across all stations and captures 50% of the variance in the dataset. It features a maximum near 38.7 km that may be taken as an average Moho depth. The second and third modes are dominated by a high amplitude shallow structures (e.g. sedimentary layers) within the top 10 km and Moho variability between 30 and 46 km. The fourth and fifth modes account for a combined 11% of the variance in the dataset, contain energy at upper-mid crustal depths in the 10 km to 20 km range. All 5 modes display markedly lower energy within a depth window roughly between 20 km and

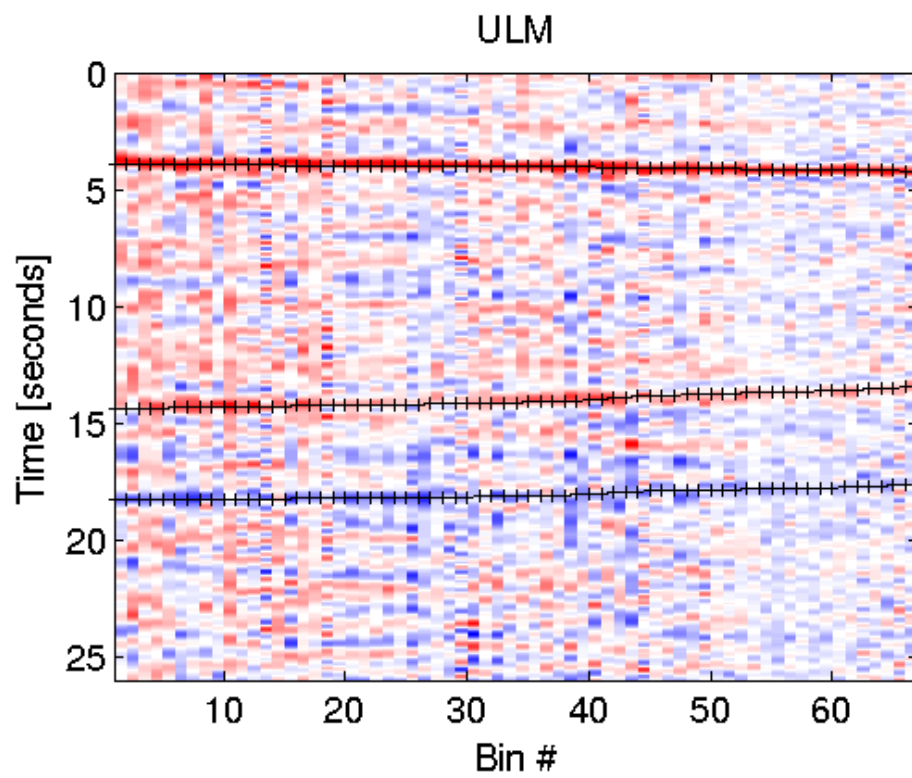


Figure 2:

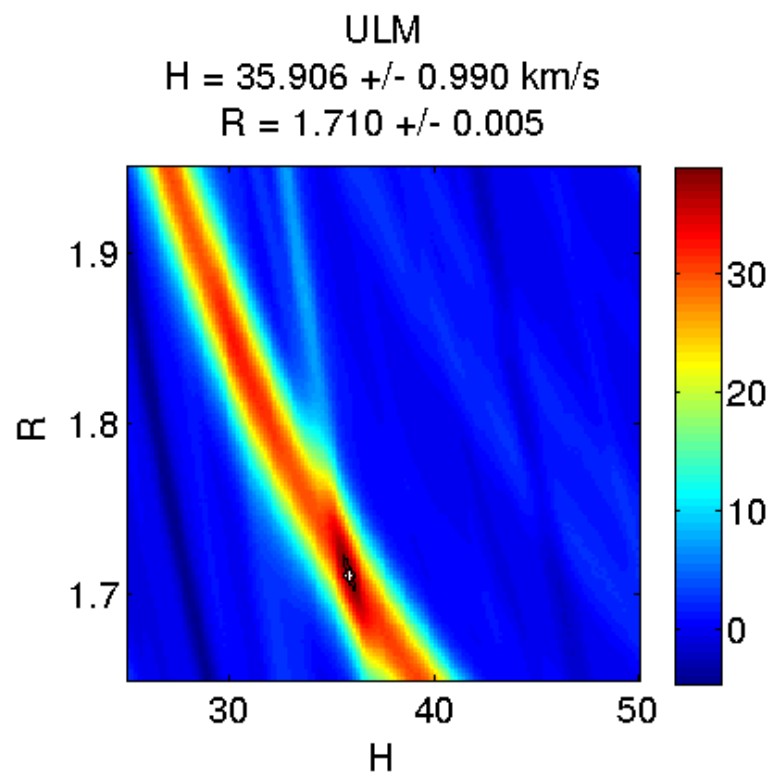


Figure 3:

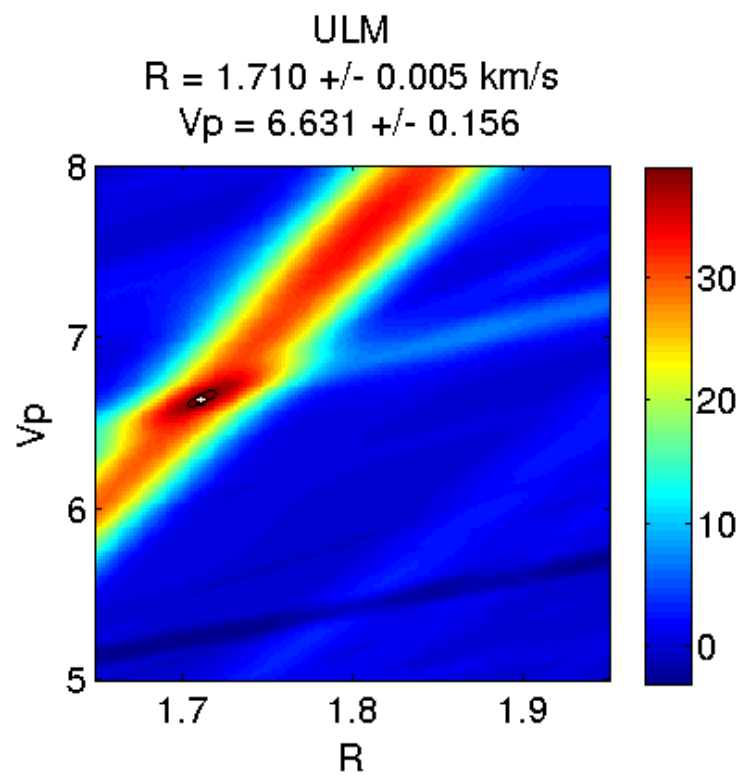


Figure 4:

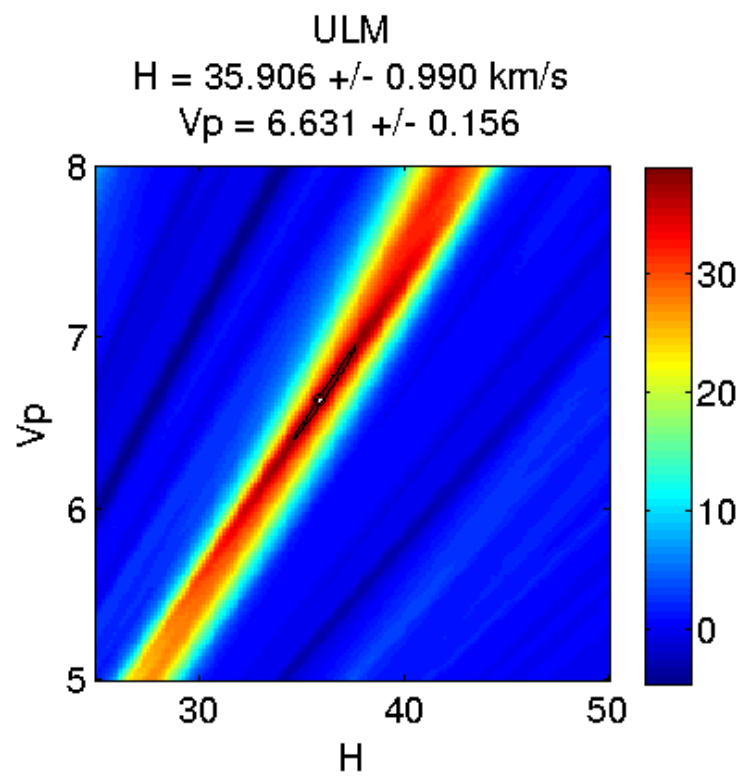


Figure 5:

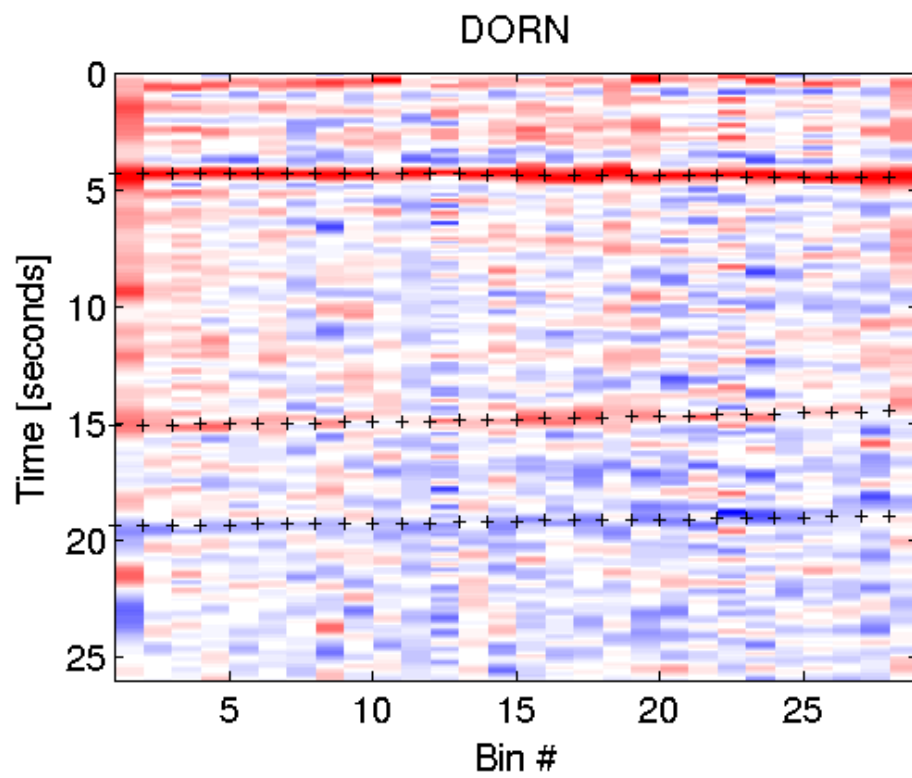


Figure 6:

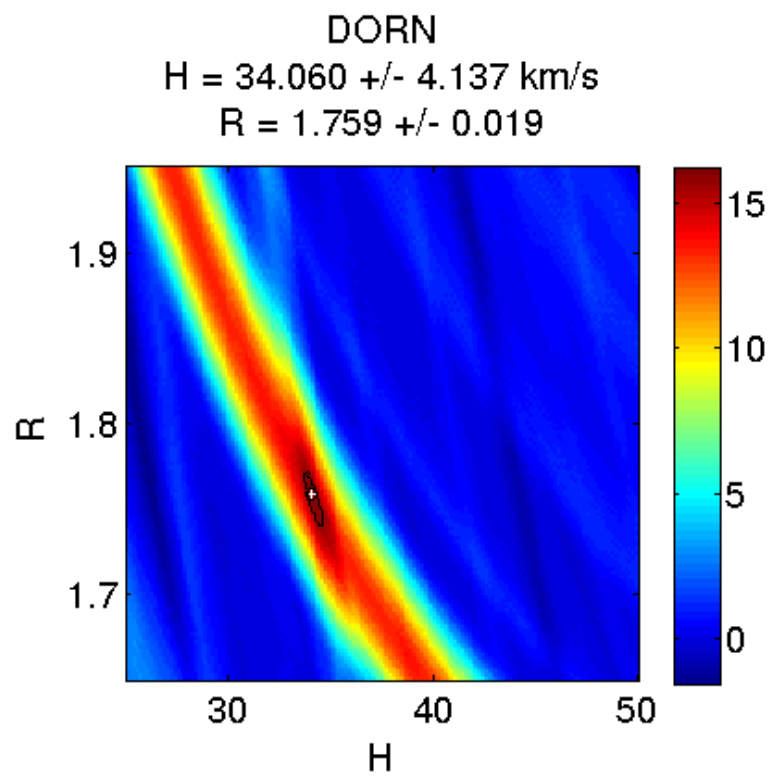


Figure 7:

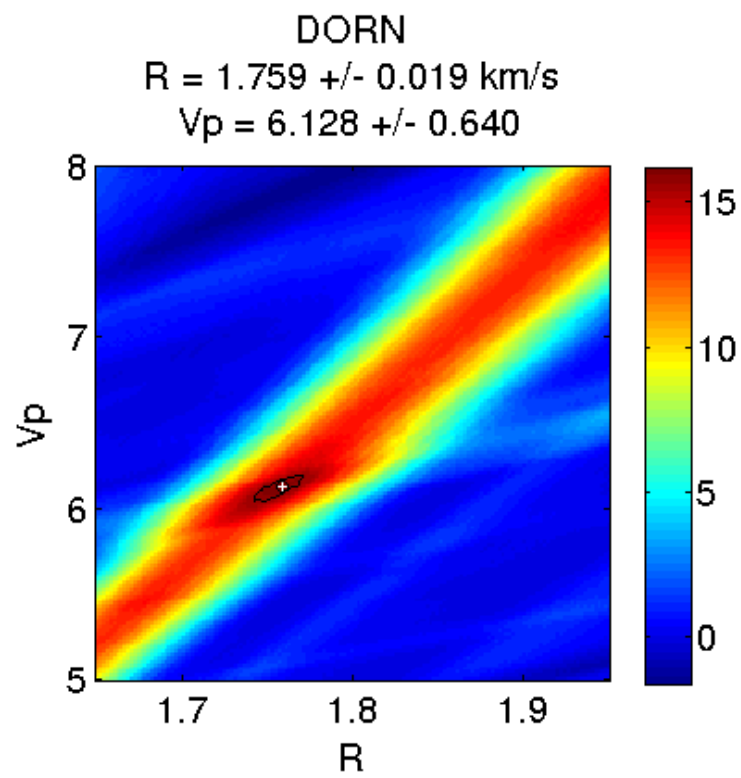


Figure 8:

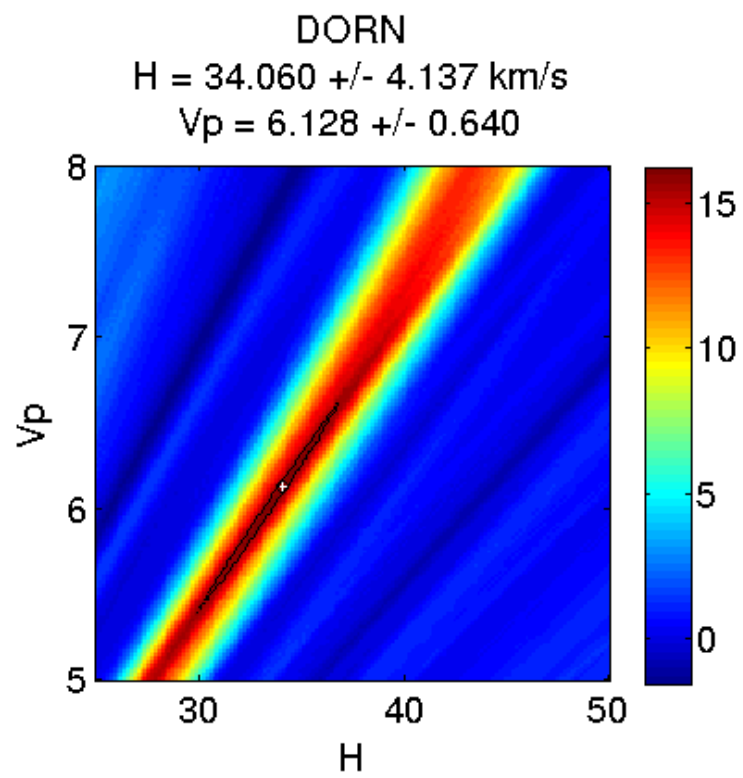


Figure 9:

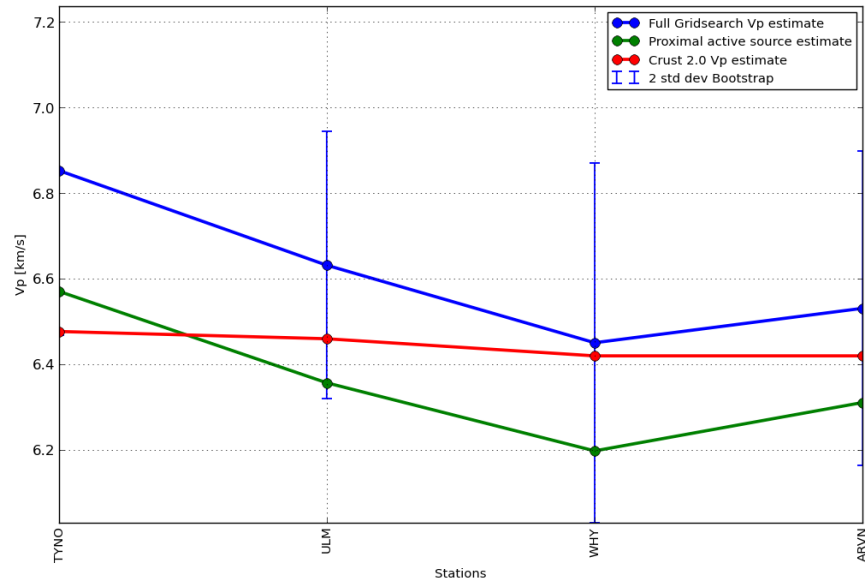


Figure 10: *P* wave velocity estimates computed from the full parameter search method compared to active source data and values from Crust 1.0

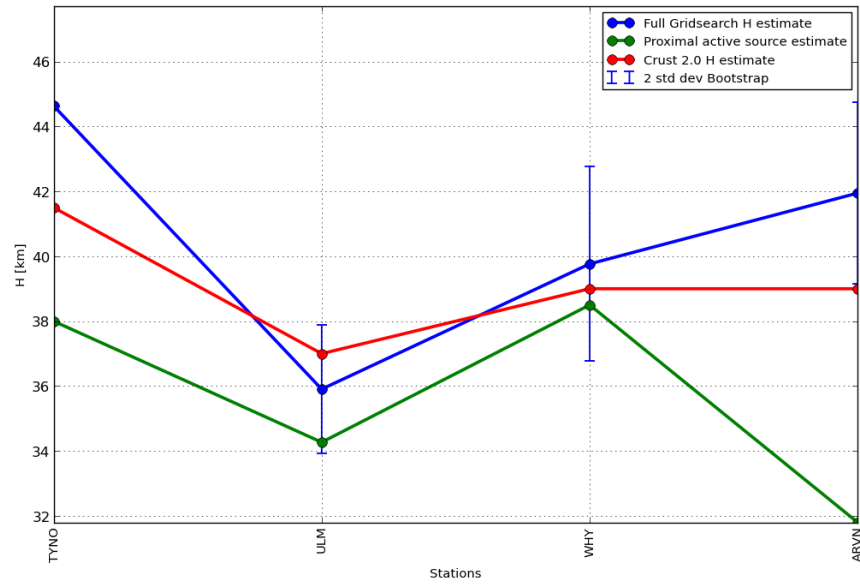


Figure 11: Crustal thickness estimates computed from the full parameter search method compared to active source data and values from Crust 1.0

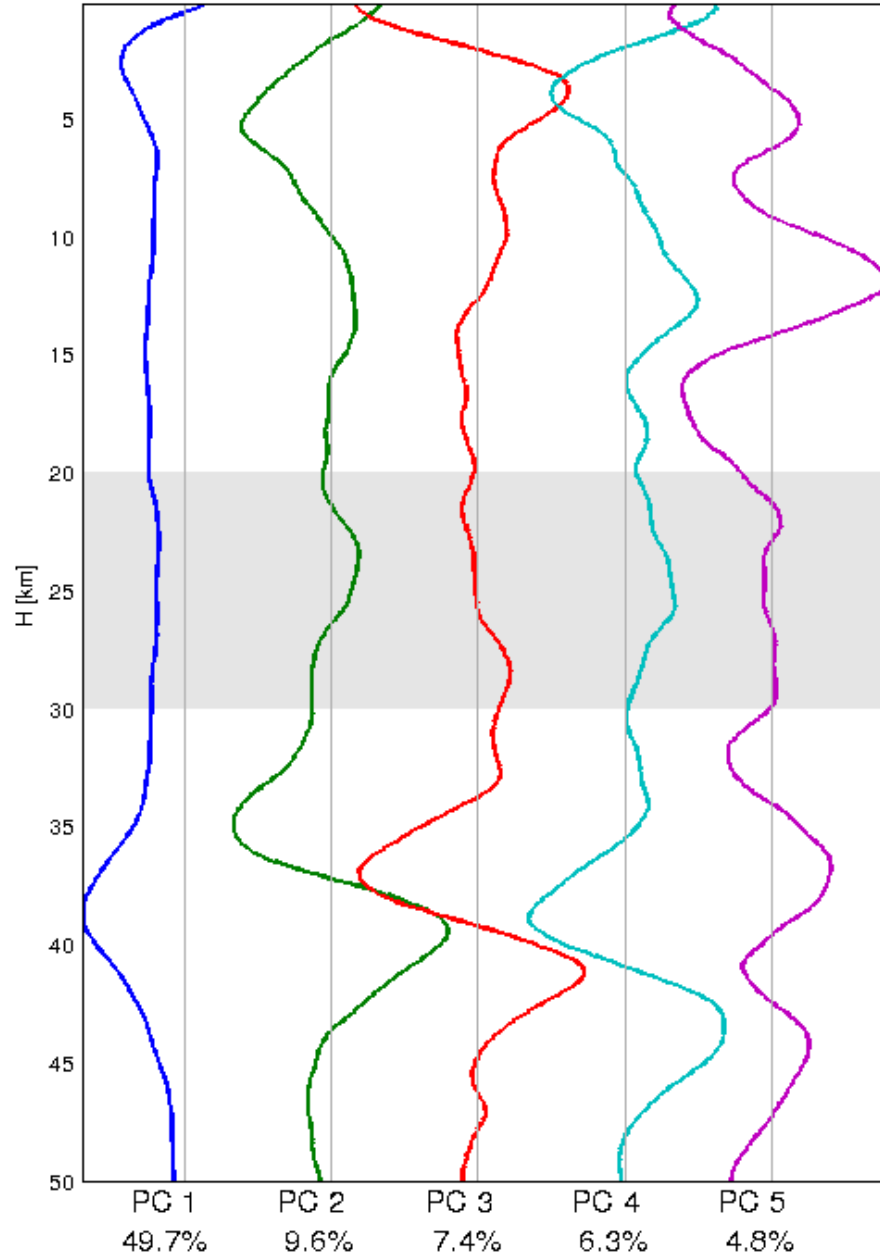


Figure 12: The SVD singular vectors (principal components) of the station depth profile matrix. Each principal component represents a mode that captures some part of the total variance in the dataset. Vertical lines are the axis each profile and vector is normalized about. A grey horizontal window highlights a region of low energy.

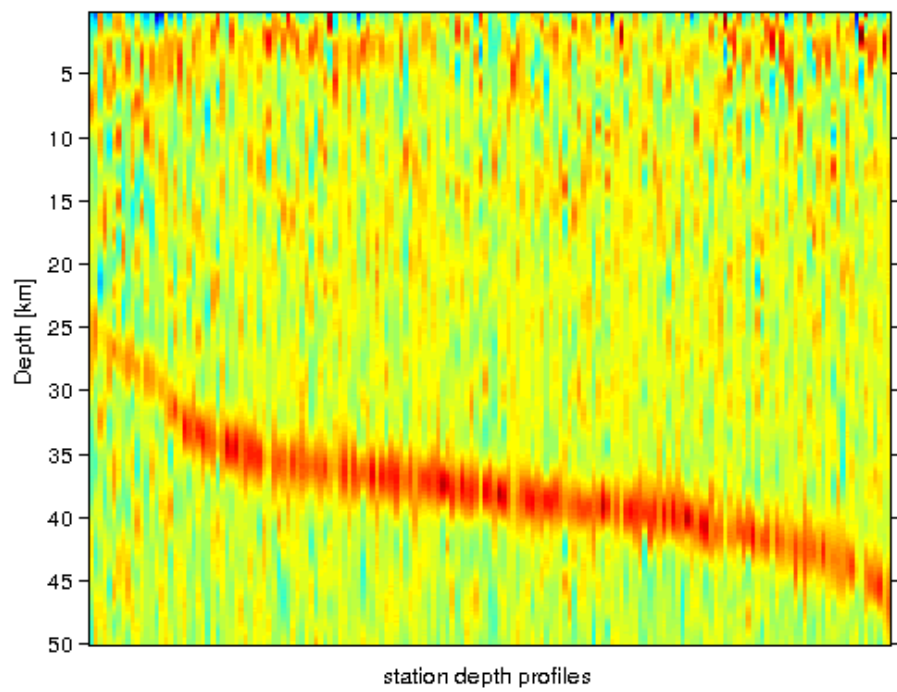


Figure 13:

30 km.

3.4 Regional Bulk Crustal Parameters

We proceed to consider crustal thickness H and velocity ratio, R , estimates for stations with assigned R bootstrap errors below ± 0.06 in a geographic context (figure 14). To compensate for the uneven distribution of seismic stations, weights are applied to both R and H estimates before averaging over a given region. Weights are calculated by projecting station locations onto a 2D plane using the Albers equal-area conic projection. A Voronoi diagram is then computed using all projected station locations. The ratio between the Voronoi cell surface encompassing each station and the total area of the convex hull bounding region is employed as that station's weight.

Table 3 displays the results of our regionalization in R and H . The weighted average crustal thickness for all stations (Canada) is 37 km, about two kilometres thinner than the average for the Canadian Shield. Crust 1.0 provides a slightly thicker crustal average for Canada (38.1 km) and a slightly thinner average for the Shield (38.3 km). The Slave Province averages are similar to those for the Churchill province with a crustal thickness and seismic velocity ratio comparable to Crust 1.0. Moving south and east from the Churchill Province through the Superior Province into the Grenville Province, we note an increase in the ZK + semblance R values as well as crustal thickness H , figures 15-16. The weighted R average is 1.73 in the Churchill Province increasing slightly to 1.74 in the Superior and jumping to 1.78 in the Grenville. In a similar fashion, the weighted average of H increases from 38.9 km in the Churchill Province to 39.7 in the Superior Province and 41.7 km in the Grenville Province. The southeastern trend towards increasing values is also expressed in weighted averaged active source V_P data as well as as the Crust 1.0 V_P data. The Crust 1.0 model is characterized by slightly thinner crust though the southward thickening trend is noticeable. The trend in the seismic velocity ratio is not, however, as apparent.

4 Discussion

Seismic reflectivity of the continental crust is a valuable constraint on the processes governing crustal evolution. Early efforts to characterize continental crust revolved around a slab model with a lower velocity upper crust

Region	ZK + semblance		Crust 1.0			Active Source
	$H[km]$	R	$H[km]$	R	$V_P[km/s]$	$V_P[km/s]$
Canada	37.0	1.75	38.1	1.74	6.41	6.33
Shield	39.2	1.74	38.3	1.74	6.47	6.42
Slave	38.2	1.74	38.0	1.73	6.47	6.44
Churchill	38.9	1.73	37.9	1.74	6.46	6.39
Superior	39.7	1.74	38.9	1.74	6.49	6.44
Grenville	41.7	1.78	39.7	1.74	6.50	6.48

Table 3: Comparison of R and H estimates with three published studies

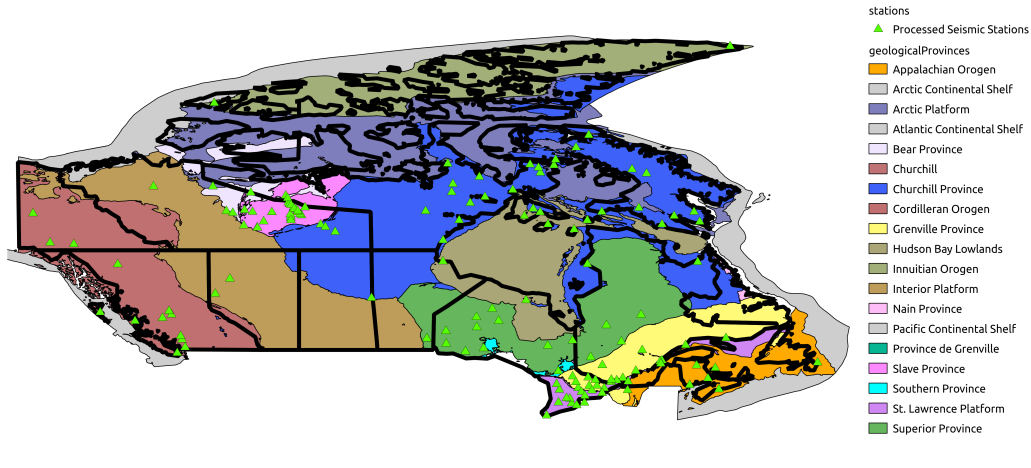


Figure 14:

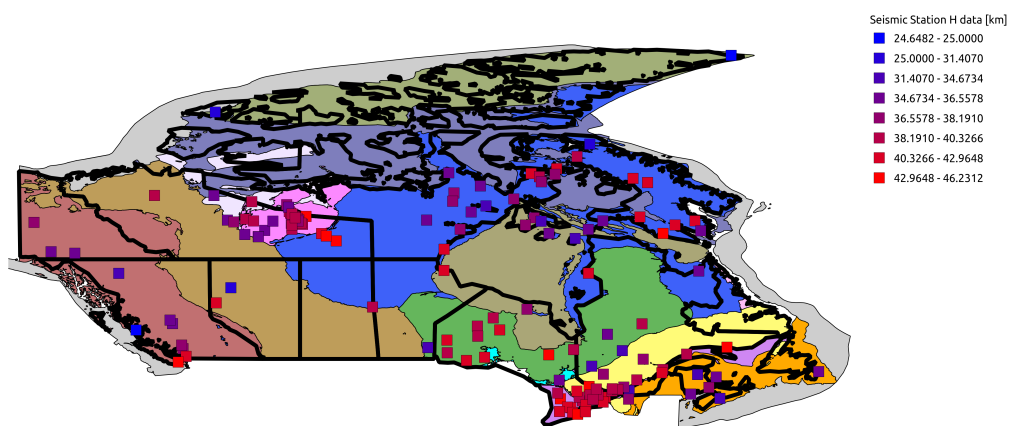


Figure 15:

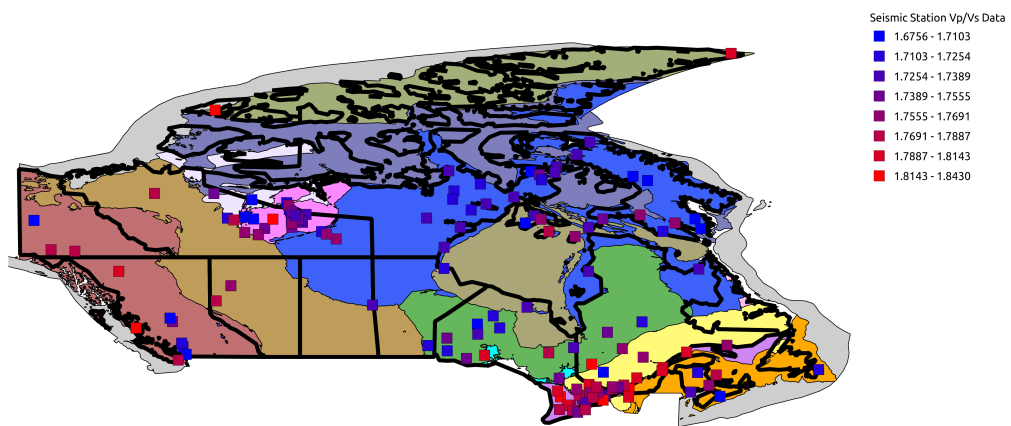


Figure 16:

and a higher velocity lower crust [Conrad, 1925; Jeffreys, 1926]. Evidence for this model was originally put forth by Conrad [1925] who suggested observable P arrivals were propagating along a mid-crustal interface similar to the deeper crust-mantle interface imaged by Andrija Mohorovii [Litak and Brown, 1989]. Both the crustal slab model and the Conrad Discontinuity, as the mid-crustal interface became known, persisted in the literature but were increasingly criticized as being too simplistic, in the case of the slab model, or, for the Conrad Discontinuity, lacking consistent evidence [Litak and Brown, 1989]. The development of reflection seismology allowed workers to further argue for a complex heterogeneous crust and propose a model whereby smooth random lateral inhomogeneities superimposed on a linearly increasing velocity gradient could produce seismic responses similar to that of a simple two layer model [Litak and Brown, 1989; Mereu and Ojo, 1981].

Despite the fading support for the Conrad Discontinuity as a discrete geological phenomena the generalization of the crust into seismically distinguishable upper and lower components continued. Mooney and Brocher [1987] argued for a model of the continental crust separated into a seismically reflective lower crust overlain by transparent upper crust. Their physical interpretation is of a poorly laminated upper crust dominated by features of short length scale contrasted with a lower crust composed of thin (100 metre) lamellae of significant length scales. Supporting evidence for a reflective lower crust confirms widespread laminated structure in the lower crust with thicknesses of 100m to 300m though these structures have been found to be localized and representational of extended as well as thicker warmer crusts [Ito, 1998; Mayer, 1996; Meissner et. al., 2006].

The lower energy noted in Section 3.3 in the 20km to 30km depth window for the station profiles given in figure 13 provides some evidence for seismically distinguishable crustal layers. To investigate this further we stretch and interpolate the profiles so that the Moho of each profile lines up on a common axis (Figure 17, left) and then take the magnitude of each profile and stack (Figure 17, right). The energy of the stack is most pronounced near the surface, associated with sedimentary layers, and at the Moho. There is a marked decrease in energy in the bottom third of the profile. This study employs S-wave energy using both direct and reflected arrivals and it has been shown that these waves interact with velocity gradients on scales lengths in the order of $\lambda/2$ for direct phases and $\lambda/4$ for reflected phases where λ is wavelength [Bostock, 1999]. For 1Hz teleseismic S-waves crustal structure in the scale lengths of 750m to 1500m is resolvable. Higher frequency ac-

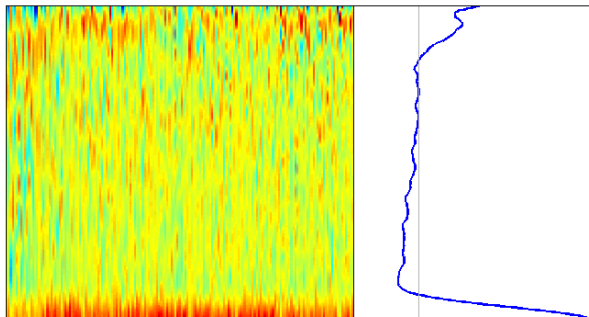


Figure 17: Left: Vertical station depth profiles interpolated to a common Moho. Right: Normalized stack of depth profiles, grey line shows mean

tive source data (10Hz - 40Hz) employing P-wave sources would be sensitive to structure roughly in the ranges of 75m to 300m. Lithoprobe transects [Hammer et. al., 2010] show significant heterogeneity throughout the crust including several transects, such as the Western Superior transect, that appear to contain higher reflectivity in the lower crust. One interpretation for these data, taken together, is that in general the Canadian lower crustal structure contains fewer thick (1km) velocity contrasts as compared to the upper crust. This interpretation allows for high reflectivity in the lower crust arising from thinner, less than 750m, contrasts.

Though the Conrad Discontinuity continues to be invoked, for example in a study of the Rhine Graben [Mayer, 1996], as terminology to describe the interface between a transparent upper crust and reflective lower crust, it does not appear to be a prevalent feature of the Canadian crust. The results from this study do suggest however, that in general, and with the seismic methods employed here, a distinction between the seismic properties of the upper crust and the bottom third of the crust can be resolved. Studies on crustal strength [Jackson, 2002] and on brittle and ductile models [Burov and Watts, 2006; Meisner and Rabbal, 1999] as well as the widely noted reduced seismicity of the lower crust indicate changes in crustal processes at similar depths, though see [Deichmann, 1991; Handy and Brun, 2004; Simpson, 1999] for competing evidence.

Mean crustal composition is another important parameter characterizing continental crust though it is important to distinguish it from actual litholog-

ical or mineralogical state of the crust. Rather, mean crustal composition is a representative average quantity that serves as a constraint on crustal structure and evolution in space and time. Early attempts at estimating mean crustal composition were largely performed through extrapolations based on the surface sampling of upper crustal rocks [Rudnick and Gao, 2003]. After the plate-tectonic revolution, Taylor [1967, 1977], proposed the 'island arc' or 'andesite' model which posited that bulk crustal composition is equivalent to the average convergent-margin andesite. Several problems with this theory subsequently emerged; for example, average surficial island arc composition is more basaltic than andesitic and any crustal growth via basaltic basal accretion will only serve to magnify this compositional contrast. Hence this model cannot account for the intermediate composition of post-Archean crust. Recognition of these shortcomings led to the analysis of data from crustal refraction seismic surveys to interrogate middle and lower crustal levels and place constraints on their composition [Christensen and Mooney, 1995; Rudnick and Fountain, 1995]. Unlike these latter studies, the present work adopts a bulk crustal seismic analysis along the lines of Smithson et. al. [1981] that combines V_P/V_S from teleseismic measurements with constraints on V_P from previous active source studies as presented in the crust 1.0 model.

In Figure 18 we plot our area-weighted seismic parameter estimates for the entire Canadian data set along with area-weighted average estimates for various tectonic subdivisions on a plot V_P versus V_S . Also plotted are values for a selection of mineral assemblages considered to be representative of common crustal rocks from the compilation of laboratory measurements by Christensen [1996], all quoted at average crustal pressures of 600 MPa. Dashed lines delimit isocontours in V_P/V_S . The choice of common shield lithologies is motivated by observations along 30km of paleo-depth represented in the Kapuskasing uplift of the Superior province [Percival and West, 1994]. The Kapuskasing uplift comprises Archean granite-greenstone terranes dominated by granitoid and gneissic rocks, and contains supracrustal assemblages generally metamorphosed from greenschist to amphibolite facies (hence the inclusion of hornblende and amphibolite) and early plutonic structures comprised largely of tonalites. Tonalites and granodiorites are also part of the TTG (tonalite-trondhjemite-granodiorite) suite which dominates Archean cratons [Rudnick, 1995].

Seismic parameter estimates for Canada and the Canadian Shield fall, to a first-order approximation, between those of two candidate end-member lithologies: granite gneiss and diorite. This intermediate or andesitic compo-

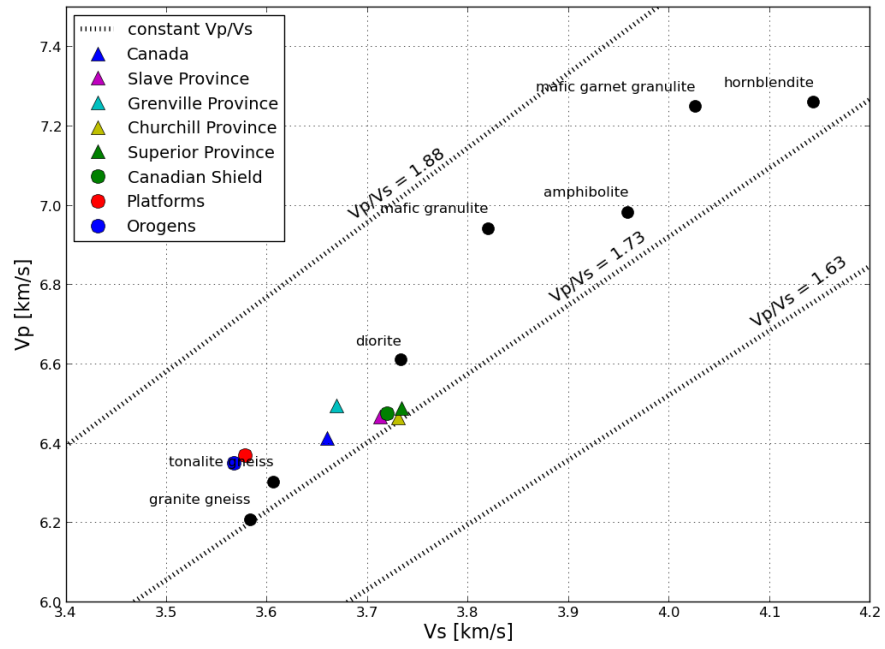


Figure 18: V_P and V_S estimates for common crust lithologies and for major Canadian-Shield provinces

sition is in general agreement with other earlier studies of bulk crustal composition [Rudnick and Fountain, 1995; Christensen and Mooney [1995]. The Slave, Superior and Churchill provinces possess comparable seismic parameters implying similar mean crustal compositions, with the Slave province represented as slightly more tonalitic in average composition. All three provinces cluster about the average value for the Canadian Shield. The Grenville Province, in contrast, displays markedly lower V_S and higher V_P/V_S implying a significant difference in mean composition. The high V_P/V_S estimate, 1.77, is similar to the averaged results from a previous seismic study [Eaton et. al., 2005] that included stations of the central Grenville Orogen, and might be interpreted to indicate that the Grenville province possesses a mean crustal composition corresponding composition that is more mafic than other Shield provinces. This interpretation is consistent with a tectonic model for the the central Grenville Province which suggests that the mid-crust has been completely excised locally [Eaton et. al., 2005; Rivers, 2008]. However, many stations in the south-east of the province also display V_P/V_S ratios greater than 1.78, similar to the high values common in the adjacent St. Lawrence Platform (where the geometric mean seismic ratio is 1.79). Moreover, and more importantly, the average V_P values for the Grenville province (a region well sampled by refraction profiles) requires low V_S values that are inconsistent with a more mafic composition. Alternative explanations that allow for both high V_P/V_S and reduced V_P , V_S include the possibility that Grenville crust contains higher fluid concentrations than that of other tectonic provinces. (NIK?? any others?)

Since our average seismic parameter estimates for the entire Canadian crust lie on a line connecting diorite with granite gneiss (18), we may estimate bulk crustal composition in proportion to these lithologies as 51% diorite and 49% granite. The corresponding chemical breakdown is provided in table 4 along with previous estimates from global crustal studies. The chemical estimates produced in our analysis reveal a crust with marginally higher average SiO_2 composition and lower Fe and Mg content than these previous studies. It is noteworthy that that the two studies involving greatest reliance on seismic attributes, ours and the P -wave velocity study by Smithson [1978], bear the closest similarity. Figure 19 displays the major crustal element contributions from the data in table 4 normalized to our average Canadian crustal composition. The gray-shaded region indicates the $\pm 30\%$ range from our reference average Canadian crustal model. Also included in this figure is the our average crustal composition estimate for the Canadian Shield. Its

Oxide, wt%	Smithson [1978]	Rudnick and Foun- tain [1995]	Christensen and Mooney [1995]	Rudnick and Gao [2003]	This Work
<i>SiO₂</i>	63.0	52.6	61.7	60.6	64.3
<i>TiO₂</i>	0.7	0.8	0.9	0.7	0.6
<i>Al₂O₃</i>	15.8	16.6	14.7	15.9	15.5
<i>Fe₂O₃</i>	2.0	—	1.9	—	1.9
<i>FeO</i>	3.4	6.6	5.1	6.7	3.3
<i>MnO</i>	0.1	0.1	0.1	0.1	0.1
<i>MgO</i>	2.8	4.4	3.1	4.7	2.2
<i>CaO</i>	4.6	6.4	5.7	6.4	4.3
<i>Na₂O</i>	4.0	3.2	3.6	3.1	3.6
<i>K₂O</i>	2.7	1.9	2.1	1.8	2.9
<i>H₂O</i>	—	—	0.8	—	1.1
<i>P₂O₅</i>	—	0.2	0.2	0.1	0.2
<i>CO₂</i>	—	—	—	—	0.1

Table 4: Bulk crustal composition comparison from selected sources. Rudnick and Fountain [1995] and Rudnick and Gao [2003] use a combined *Fe* quantity and is listed under *FeO*

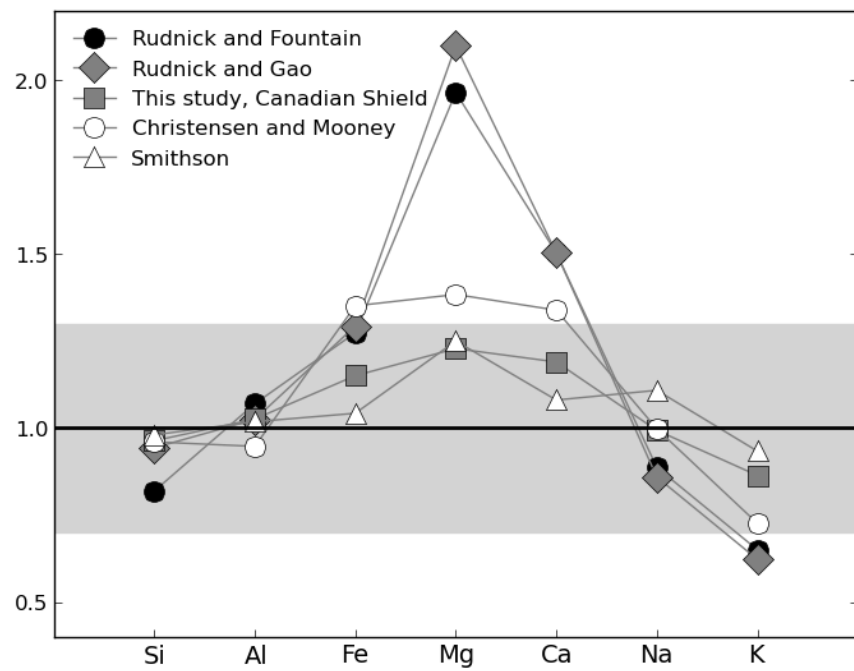


Figure 19: Comparison of major crustal elements from different studies. All estimates have been normalized to the results computed in this study.

values closely track the global crustal estimates of Christensen & Mooney [1995] and Smithson [1978]. These data imply that the extensive platform and orogenic regions of Canada skew the average composition away from the global estimates of previous studies through incorporation of a higher proportion of granite gneiss. In contrast, the Canadian Shield crust aligns more closely with these previous global estimates and is represented as 68% dioritic and 32% granitic using the two end-member model.

Other researchers have employed Poisson’s ratio [Zandt and Ammon, 1995] alone as an indicator of bulk crustal composition, and crustal thickness and P -wave velocity [Durrheim and Mooney, 1991] to constrain models of crustal formation. Zandt and Ammon [1995] report high V_P/V_S values for Archean Shields and concluded that no systematic difference between Archean and Proterozoic crust exists. Their average, $V_P/V_S = 1.84$, is much higher than our weighted average for the Canadian Shield of 1.74. These authors also report a low V_P/V_S value for Cenozoic-Mesozoic crust, 1.73 compared to the corresponding value for our data of 1.77. They interpret these high values for older crust and low values for younger crust as favouring either of two limiting models. In the uniformitarian model, a delamination type process operates to remove mafic lower crust during continental collisions and is subsequently followed by a stabilizing process involving basaltic underplating. This model implies that younger crust has yet to complete the full crustal genesis cycle. In their second model, Precambrian cratons evolve through unique processes and younger orogens involve the recycling and reworking of existing material with little net crustal growth.

Whereas Zandt and Ammon present evidence for increasing V_P/V_S with crustal age, our estimates signify the opposite trend. Our results are more consistent with those of Durrheim and Mooney [1991] who argue that Proterozoic crust is thicker with higher P -velocity than Archean crust. The crustal thickness data presented in this study is only marginally thicker for Proterozoic crust (38.9 km) than Archean crust (38.0 km) and this difference is significantly smaller than the 5 km difference reported by Durrheim and Mooney. Though the difference is not large, the higher seismic velocity ratio in the Proterozoic units (1.76) than in Archean units (1.74) aligns with their argument for an evolution of crustal processes throughout geological time. The hypothesis that Proterozoic crust is prone to basaltic underplating, thereby explaining higher velocities and thicker crust, suggested by Durrheim and Mooney [1991], has been persuasively augmented by recent work [Rudnick 1995; Rucknick and Gao, 2003] to now include a range of possible

processes that may explain the data.

One possible process is the preferential recycling of soluble ions such as Mg^{2+} and Ca^{2+} . These ions are weathered and carried into the oceans leaving behind silicon and aluminum [Rudnick and Gao, 2003] producing a net change to crustal composition over time. In another model, deep crustal roots expose lower crust to processes leading to eclogitization and subsequent delamination due to a density inversion with the underlying mantle peridotites. This model does not directly address the question as to why there is an apparent variance in average velocities between younger and older crusts, unless the delamination process has evolved over time. However, knowledge of the spatial or temporal extent of delamination is difficult to document [Rudnick, 1995]. A third model suggests that a mixture of silicic melts from subducting oceanic crust and basaltic melts from mantle peridotites were important in early crustal formation. This process is thought to be more common in the hotter Archean and is related to the TGG suites of Archean granitoids [Rudnick and Gao, 2003] and therefore provides a possible explanation for the data. It is important to state that all of these processes, as well as others, may have been operating throughout geologic time.

This study provides results that are in general agreement with other recent crustal studies and similarly argues for an intermediate or andesitic crust. There are several processes that have been suggested to explain this intermediate composition ...

5 Conclusions

6 bibliography

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