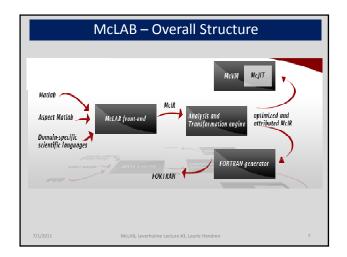
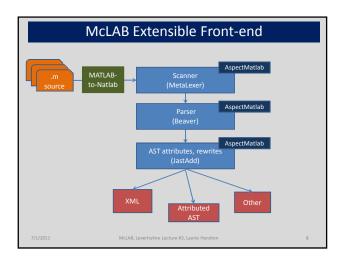
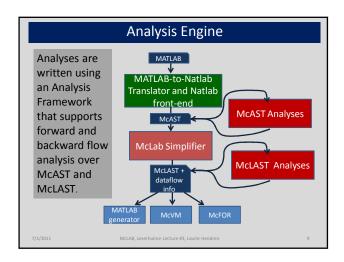


Goals of the McLab Project Improve the understanding and documentation of the semantics of MATLAB. Provide front-end compiler tools suitable for MATLAB and language extensions of MATLAB. Provide a flow-analysis framework and a suite of analyses suitable for a wide range of compiler/soft. eng. applications. Provide back-ends that enable experimentation with JIT and ahead-of-time compilation. Enable PL, Compiler and SE Researchers to work on MATLAB

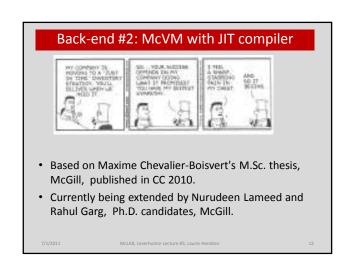








Back-end #1: MATLAB generator • McLAB can be used as a source-to-source translator: - source-level optimizations like loop unrolling - source-level refactoring tool • McLAB can generate: - xml files (used to communicate with McVM) - text .m files • Comments are maintained to enable readable output.



McVM-McJIT

- The dynamic nature of MATLAB makes it very suitable for a VM/JIT.
- MathWorks' implementation does have a JIT, although technical details are not known.
- McVM/McJIT is an open implementation aimed at supporting research into dynamic optimization techniques for MATLAB.

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Backends- 13

Design Choices for JITs

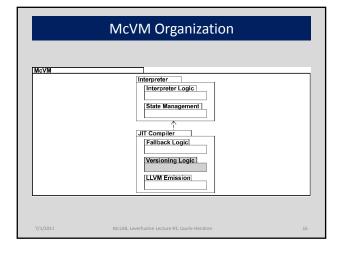
- 1. Interpreter + JIT compiler with various levels of optimizations.
- 2. Fast JIT for naïve code generation + optimizing JIT with various levels of optimizations.
- McVM uses the 1st option because it simplifies adding new features, if a feature is not yet supported by the JIT it can back-up to the interpreter implementation, which is easy to provide.

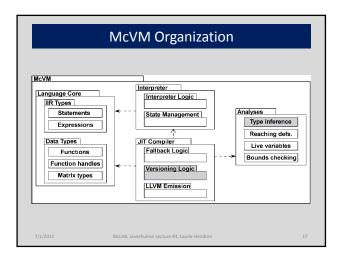
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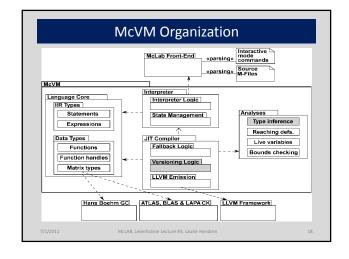
McVM Design

- A basic, but fast, interpreter for the MATLAB language.
- A garbage-collected JIT Compiler as an extension to the interpreter.
- Easy to add new data types and statements by modifying only the interpreter.
- Supported by the LLVM compiler framework and some numerical computing libraries.
- Written entirely in C++; interface with the McLAB front-end via a network port.

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```
MATLAB Optimization Challenges

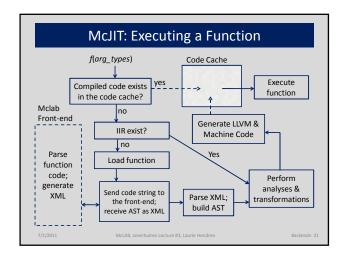
float sumvals(float start, float step, float
stop)
{
    float i = start;
    float s = i;
    while (i < stop)
    {
        i = i + step;
        s = s + i;
    }
    return s;
}</pre>
```

```
function s = sumvals(start, step, stop)
    i = start;
    s = i;

while i < stop
    i = i + step;
    s = s + i;
end
end

function caller()
    a = sumvals(1, 1, 10^6);
    b = sumvals([1 2], [1.5 3], [20^5 20^5]);
    c = [a b];
    disp(c);
end

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```



```
Just-In-Time Specialization (1)

>> a = sumvals(1, 1, 10^6);

>> b = sumvals([1 2], [1.5 3], [20^5 20^5]);

>> a = sumvals(1, 1, 500);

>> c = [a b];

>> disp(c);

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```

```
Just-In-Time Specialization (2)

>> a = sumvals(1, 1, 10^6);

Interpreter.runCommand("a = sumvals(1, 1, 10^6);");

Interpreter.callFunction(sumvals, [1, 1, 10^6]);

JIT.callFunction(sumvals, [1, 1, 10^6]);
```

```
Just-In-Time Specialization (3)

JITCompiler.callFunction(sumvals, [1, 1, 10^6]);

sumvals.JIT = JITCompiler.compileFunction(sumvals, [<scalar int>, <scalar int>, <scalar int>, <scalar int>);

function s = sumvals(start <scalar int>, step <scalar int>, step <scalar int>,

step <scalar int>,

i = start;
s = i;

while i < stop
i = i + step;
s = s + i;

end

end

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```

```
Just-In-Time Specialization - 2<sup>nd</sup> example

>> a = sumvals(1, 1, 10^6);
>> b = sumvals([1 2], [1.5 3], [20^5 20^5]);
>> a = sumvals(1, 1, 500);
>> c = [a b];
>> disp(c);

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```

```
JIT — second specialization (1)

JITCompiler.callFunction(sumvals, [[1 2], [1.5 3], [20^5 20^5]]);

sumvalsJIT2 = JITCompiler.compileFunction(sumvals, [<1x2 int>, <1x2 real>, <1x2 int>]);

function s = sumvals(start <1x2 int>, step <1x2 real>,
stop <1x2 int> = start;
s <1x2 int> = start;
s <1x2 int> = i;
while (i <1x2 int>) < (stop <1x2 int>)
i <1x2 real> = i + step;
end

and

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```

```
JIT — second specialization (2)

JITCompiler.callFunction(sumvals, [[1 2], [1.5 3], [20^5 20^5]]);

sumvals.JIT2 = JITCompiler.compileFunction(sumvals, [<1x2 int>, <1x2 real>, <1x2 int>]);

function s <1x2 real> = sumvals(start <1x2 int>, step <1x2 real>, stop <1x2 int>]

i <1x2 int> = start;
s <1x2 int> = i;
while (i <1x2 real>) < (stop <1x2 int>)
i <1x2 real> = i + step;
s <1x2 real> = s + i;
end
end

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```

```
JIT — third specialization same as first

>> a = sumvals(1, 1, 10^6);
>> b = sumvals([1 2], [1.5 3], [20^5 20^5]);
>> a = sumvals(1, 1, 500);
>> c = [a b];
>> disp(c);

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```

Type and Shape Inference

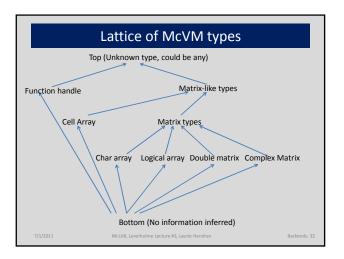
- In MATLAB, work with incomplete information
 - Dynamic loading: working with incomplete program
 - Dynamic typing : variables can change type
- . Know argument types, what can we infer?
 - Propagate type info to deduce locals type and return type
- Forward dataflow analysis
 - Based on abstract interpretation
 - . Structure-based fixed point
 - . Annotates AST with type info

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Flow Analysis Summary

- . Start from known argument types
- · Propagate type information forward
- . Use a transfer function for each expression
 - . Transfer functions provided for all primitive operators
 - . Library functions provide their own transfer functions
 - Function calls resolved, recursively inferred
- · Assignment statements can change var. types
- Merge operator
 - · Union + filtering

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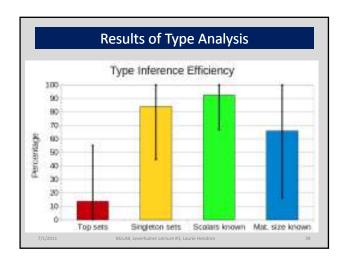


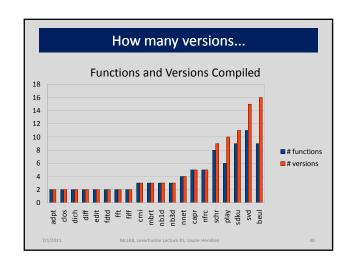
Type Abstraction Properties

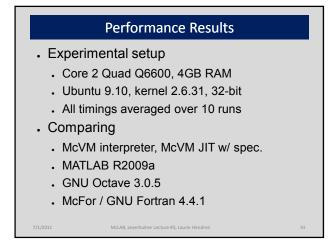
- Collection of simple abstractions
 - · Specific features computed in parallel
- Represent variable types with 8-tuples:

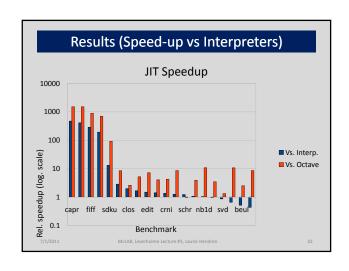
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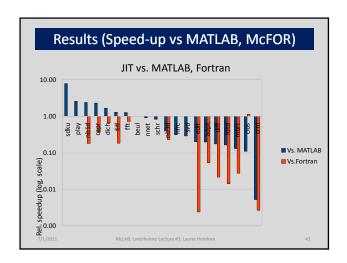
Experimental Results 20 benchmark programs FALCON, OTTER, etc. Some made by McLAB Measured Dynamic availability of type info. Number of versions compiled Compilation time 0.55s per benchmark, on average







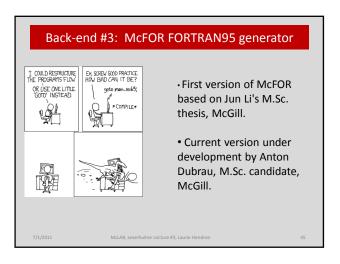




About Slow Benchmarks

- crni benchmark takes 1321s to execute in McVM, 6.95s in MATLAB
 - ~4x faster than Octave, but still slow
- . Why?
 - Scalars known 68.7%, one of the lowest ratios
 - Unknown types propagated through entire benchmark
- Weakness of type inference system to be fixed in future work

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Goals of McFOR

- Handle as large a sub-set of MATLAB as possible, while staying in the "static" setting.
- Generate code that can be effectively compiled by modern FORTRAN compilers.
- Make the generated code readable by programmers.
- Allow longer compile times and whole program analysis.
- · Limit the need for type annotations.

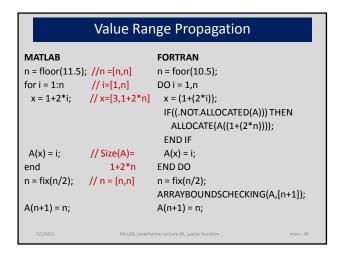
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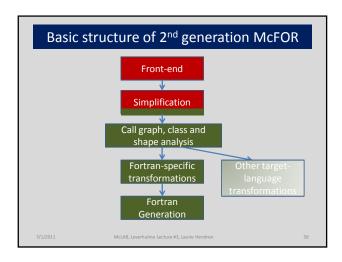
Challenges

- Determining which identifiers are variables and which are functions.
- Finding static types which match those of FORTRAN.
- Mapping high-level MATLAB array operations to the FORTRAN95 equivalents.
- Handling reshaping implicit in MATLAB operations, including concatenation.

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Handling Incompatible Types Alpha Nodes Eliminating Alpha Nodes x = 0; x = 0; if (i>0) if (i>0) S1: x = foo(i); x = foo(i);y = x; S2: x = bar(i); else x1 = bar(i)end x = alpha(S1,S2);y = x1; y = x; end





Related Work

- · Procedure cloning: Cooper et al. (1992)
- MATLAB type inference: Joisha & Banerjee (2001)
 - Suggested for error detection
- . MATLAB Partial Evaluator: Elphick et al. (2003)
 - Source-to-source transformation
- MaJIC: JIT compilation and offline code cache (2002)
 - . Speculative compilation MATLAB to C/Fortran
- Psyco: Python VM with specialization by need (2004)
- TraceMonkey: JIT optimization of code traces (2009)

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Ongoing Work

- McVM:
 - profile-guided optimization and reoptimization with on-stack replacement
 - . target GPU/multi-core
- . McFOR:
 - "decompile" to more programmer-friendly FORTRAN95
 - refactoring toolkit to help restructure
 "dynamic" features to "static" features

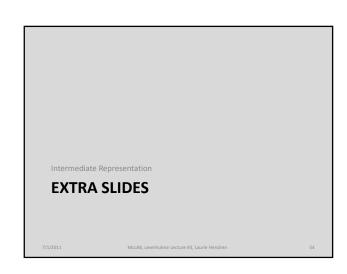
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Conclusions

- McLAB is a toolkit to enable PL, Compiler and SE research for MATLAB
- · front-end for language extensions
- analysis framework
- three back-ends including McVM and McFOR

http://www.sable.mcgill.ca/mclab

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Internal Intermediate Representation

- A simplified form of the Abstract Syntax Tree (AST) of the original source program
- It is machine independent
- All IIR nodes are garbage collected

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