ECE 298 Reservoir System Lab B4 Report

Shijie Xu Raiyan Samin

> LS-003 Group 14

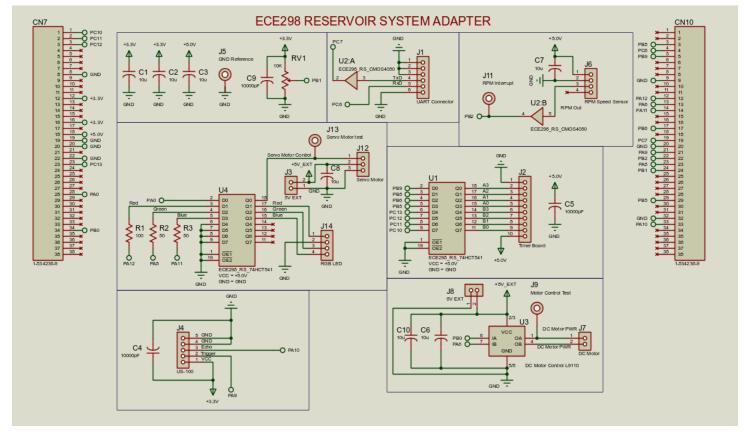
24-Hour Operating Cycle

Zone	Start Time	End Time	RPM	Power (kW)	Energy (kWh)	Water Transferred (Gallons)	Energy Rate (\$)	Energy Cost (\$)
Inlet	0	7	100	375	2625	71400	0.024	63.00
Inlet	7	10	88	250	750	22600	0.102	76.50
Zone 2	10	14	100	375	1500	30000	0.102	153.00
Zone 1	14	16	80	190	380	21000	0.102	38.76
Zone 1	16	18	70	125	250	17420	0.24	60.00
Zone 1*	21	22	100	375	375	11580	0.102	38.25
Zone 3	22	23	100	375	375	7000	0.102	38.25
Zone 3	23	24	100	375	375	7000	0.024	9.00
Total	0	24	-	-	6630	188000	-	476.76

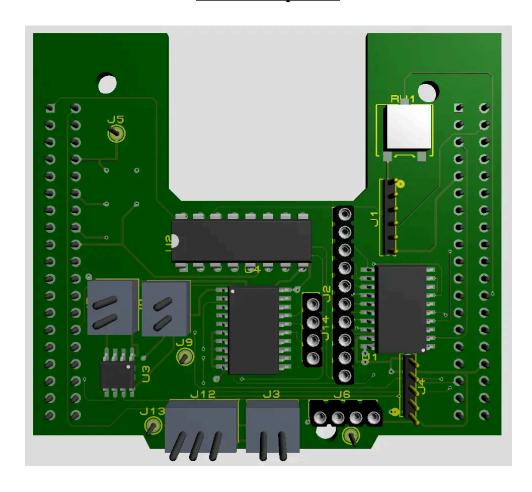
Using ULO rates, weekday only.

^{*}Operational time split to optimize cost.

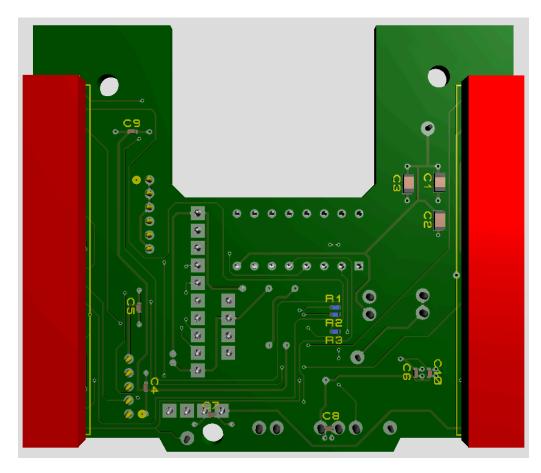
Schematic Diagram



PCB 3D Top View



PCB 3D Bottom View

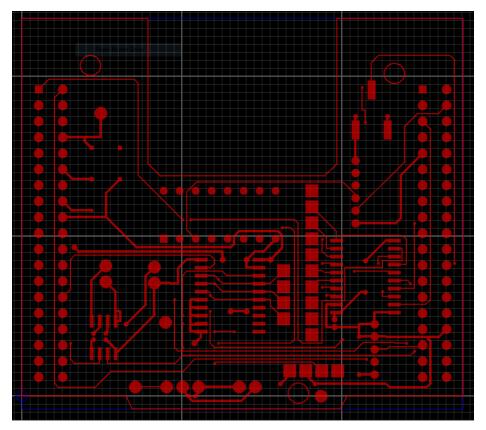


PPC Report

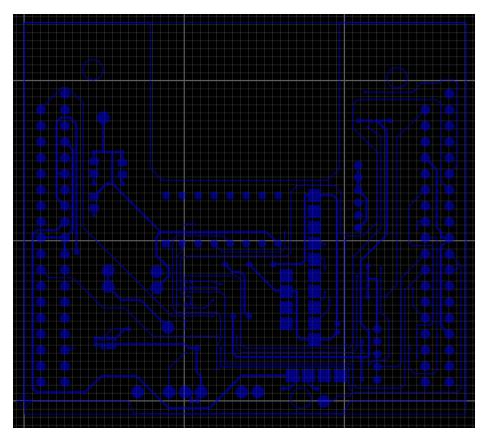
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Pre-production Check

Pre-production check start.
File: N:\28\ECE298\LAB B\ECE298_RS_Adapter.pdsprj
Date: July 26, 2024, 9:39:56 AM
TEST: Connectivity.
PASS: Connectivity valid.
TEST: Object validity.
PASS: Object valid.
TEST: DRC valid.
PASS: No DRC errors.
TEST: Zone overlap.|
Imaging Copper Layer TOP
Imaging Copper Layer II
Imaging Copper Layer III
Imagi
```

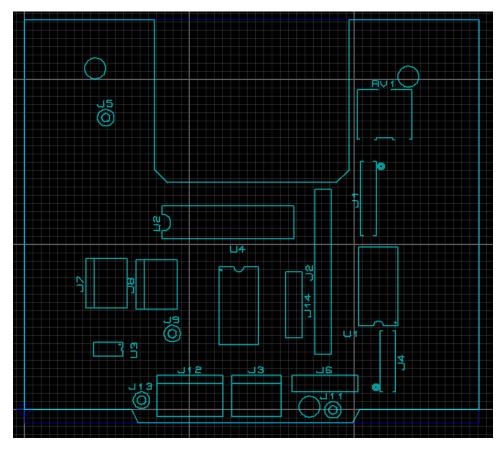
PCB Top Copper



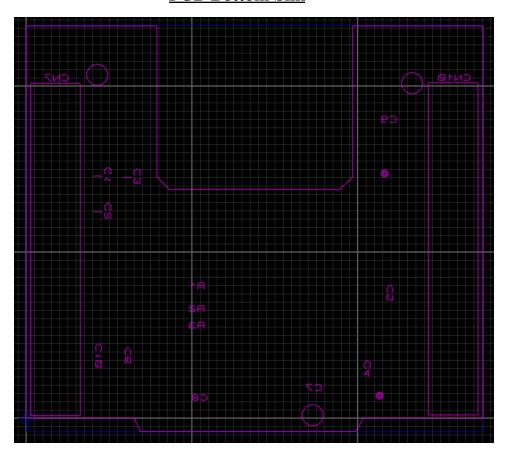
PCB Bottom Copper



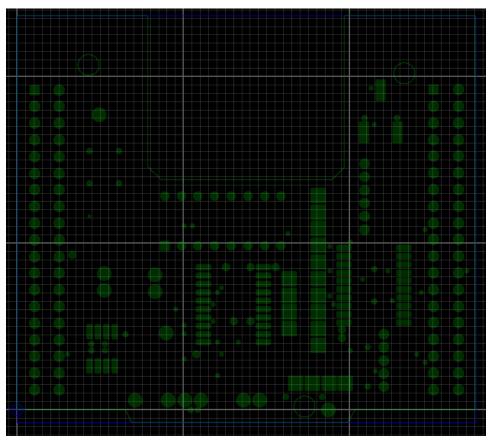
PCB Top Silk



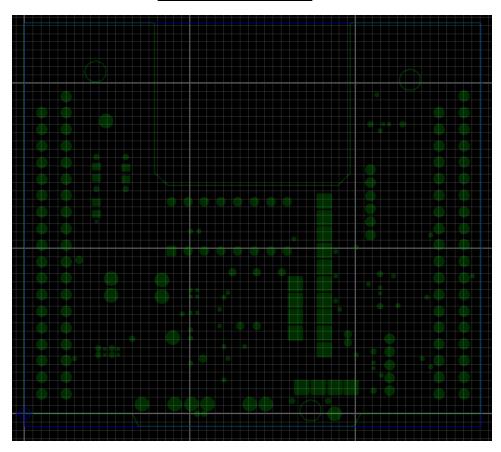
PCB Bottom Silk



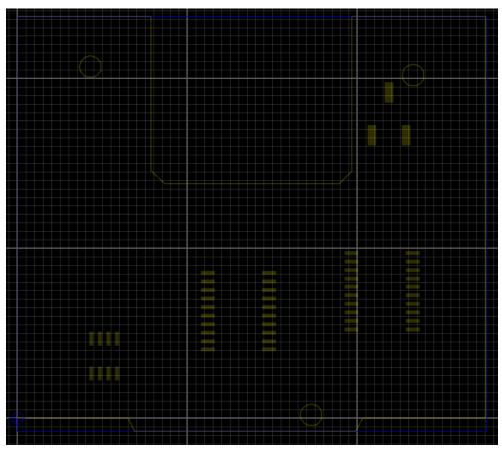
PCB Top Resist



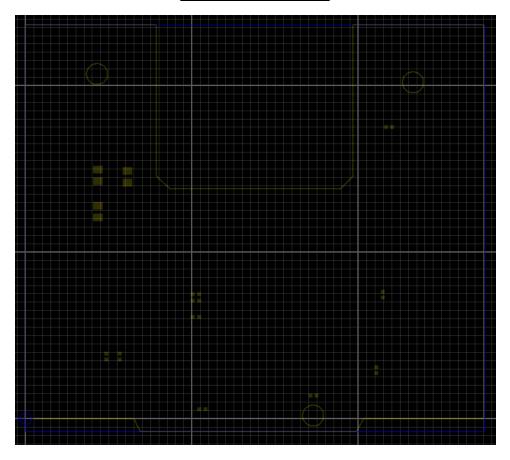
PCB Bottom Resist



PCB Top Paste



PCB Bottom Paste



Pick and Place File

	А	В	С	D	Е	F	G	Н
1	Part ID	Value	Package	Stock Code	Layer	Rotation	Х	Υ
2	CN7	1-534236-9	ECE298_REVTE	1-534236-9	BOT	0	177.362	1019.69
3	CN10	1-534236-9	ECE298_REVTE	1-534236-9	BOT	0	2577.36	1021.26
4	C1	10u	CAPC2012X100	Digikey PCC218	BOT	-90	433.071	1460.63
5	C3	10u	CAPC2012X100	Digikey PCC218	BOT	-90	610.236	1452.76
6	U3	DC Motor Contro	SO8		TOP	-90	508.661	367.539
7	J7	DC Motor	SIL-100-02		TOP	-270	521.654	766.929
8	C6	10u	CAPC1005X55	Digikey PCC103	BOT	90	563.976	373.031
9	C10	10u	CAPC1005X55	Digikey PCC103	BOT	90	485.236	373.031
10	J9	Motor Control Te	PIN		TOP	0	895.669	462.598
11	J5	GND Reference	PIN		TOP	0	492.126	1771.65
12	J4	US-100	CON5_1X5_U_2	NorComp 25630	TOP	270	2204.72	295.276
13	C4	10000pF	CAPC1005X55	Digikey PCC103	BOT	-90	2106.3	293.307
14	J12	Servo Motor	SIL-100-03		TOP	0	1005.51	59.0551
15	J3	5V EXT	SIL-100-02		TOP	0	1408.27	59.0551
16	U4	ECE298_RS_74	SO20W		TOP	0	1299.21	629.921
17	U2	ECE298_RS_CN	DIL16		TOP	0	1235.83	1134.25
18	U1	ECE298_RS_74	SO20W		TOP	180	2145.67	748.031
19	J2	Timer Board	CONN-SIL10		TOP	90	1811.02	837.402
20	J14	RGB LED	CONN-SIL4		TOP	270	1633.86	637.402
21	R2	50	RESC1005X40	Digikey 311-150	BOT	0	1023.62	708.661
22	R3	50	RESC1005X40	Digikey 311-200	BOT	180	1023.62	610.236
23	R1	100	RESC1005X40	Digikey 311-150	BOT	0	1023.62	748.031
24	J8	8V EXT	SIL-100-02		TOP	90	826.772	758.661
25	J13	Servo Motor test	PIN		TOP	0	708.661	59.0551
26	J6	RPM Speed Sen	CONN-SIL4		TOP	0	1823.23	157.48
27	J11	RPM Interrupt	PIN		TOP	0	1870.08	0
28	RV1	10K	TRIM_3361P	Digikey 3361P-1	TOP	0	2185.04	1791.34
29	C7	10u	CAPC1005X55	Digikey PCC103	BOT	180	1730.31	137.795
30	C8	10u	CAPC1005X55	Digikey PCC103	BOT	180	1061.02	59.0551
31	C9	10000pF	CAPC1005X55	Digikey PCC103	BOT	0	2183.07	1751.97
32	C5	10000pF	CAPC1005X55	Digikey PCC103	BOT	-90	2145.67	746.063
33	C2	10u	CAPC2012X100	Digikey PCC218	BOT	-90	433.071	1244.09
34	J1	UART Connecto	CON6_1X6_U_2	NorComp 25630	TOP	90	2086.61	1279.53

Bill Of Materials for ECE298_RS_ADAPTER

Design Title ECE298_RS_ADAPTER

Author

Document Number

Revision

Design Created July 7, 2023 **Design Last Modified** July 26, 2024

Total Parts In Design 33

10 Capacitors		
Quantity	References	<u>Value</u>
7	C1-C3,C6-C8,C10	10u
3	C4-C5,C9	10000pF
Sub-totals:		
3 Resistors		
Quantity	References	Value
1	R1	100
2	R2-R3	50
Sub-totals:		
4 Integrated Circuits		
Quantity	References	<u>Value</u>
2	U1,U4	ECE298_RS_74HCT541
1	U2	ECE298_RS_CMOS4050
1	U3	DC Motor Control L9110
Sub-totals:		
0 Transistors		
Quantity Sub-totals:	References	<u>Value</u>
0 Diodes		
Quantity Sub-totals:	References	Value
16 Miscellaneous		
Quantity	<u>References</u>	<u>Value</u>
2	CN7,CN10	1-534236-9
1	J1	UART Connector
1	J2	Timer Board
1	J3	5V EXT
1	J4	US-100
1	J5	GND Reference
1	J6	RPM Speed Sensor
1	J7	DC Motor
1	J8	8V EXT
1	J9	Motor Control Test
1	J11	RPM Interrupt
1	J12	Servo Motor
1	J13	Servo Motor test
1	J14	RGB LED
1	RV1	10K
Sub-totals:		

Totals:

ISIS SCHEMATIC DESCRIPTION FORMAT 8.0

Design: ECE298_RS_ADAPTER

Doc. no.: <NONE>
Revision: <NONE>
Author: <NONE>
Created: 2023-07-07
Modified: 2024-07-26

*PROPERTIES,0

*MODELDEFS,0

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*PARTLIST.33
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C1,ECE298_RS_CAP_10U,10u,CODE="Digikey PCC2182TR-ND",EID=B,PACKAGE=CAPC2012X100

C2,ECE298_RS_CAP_10U,10u,CODE="Digikey PCC2182TR-ND",EID=13,PACKAGE=CAPC2012X100

C3,ECE298_RS_CAP_10U,10u,CODE="Digikey PCC2182TR-ND",EID=C,PACKAGE=CAPC2012X100

C4,ECE298_RS_CAP_0U1,10000pF,CODE="Digikey

PCC103BQDKR-ND", EID=3, PACKAGE=CAPC1005X55

C5,ECE298_RS_CAP_0U1,10000pF,CODE="Digikey

PCC103BQDKR-ND", EID=A, PACKAGE=CAPC1005X55

C6,ECE298_RS_CAP_0U1,10u,CODE="Digikey

PCC103BQDKR-ND", EID=16, PACKAGE=CAPC1005X55

C7,ECE298 RS CAP 0U1,10u,CODE="Digikey

PCC103BQDKR-ND", EID=15, PACKAGE=CAPC1005X55

C8,ECE298_RS_CAP_0U1,10u,CODE="Digikey

PCC103BQDKR-ND",EID=28,PACKAGE=CAPC1005X55

C9,ECE298_RS_CAP_0U1,10000pF,CODE="Digikey

PCC103BQDKR-ND",EID=4,PACKAGE=CAPC1005X55

C10,ECE298 RS CAP 0U1,10u,CODE="Digikey

PCC103BQDKR-ND".EID=19.PACKAGE=CAPC1005X55

CN7,1-534236-9,1-534236-9,CODE=1-534236-9,EID=1,PACKAGE=ECE298_REVTRANS38DIL-1,SUPP LIER=TE CONNECTIVITY

CN10,1-534236-9,1-534236-9,CODE=1-534236-9,EID=2,PACKAGE=ECE298_REVTRANS38DIL-1,SUP PLIER=TE CONNECTIVITY

J1,25630601RP2,"UART Connector",CODE="NorComp

25630601RP2",EID=1B,PACKAGE=CON6_1X6_U_2563

J2,ECE298_RS_10PINREC,"Timer Board",EID=5,PACKAGE=CONN-SIL10

J3,ECE298 RS 2PINHDR, "5V EXT", EID=14, PACKAGE=SIL-100-02

J4,25630501RP2,US-100,CODE="NorComp 25630501RP2",EID=1C,PACKAGE=CON5_1X5_U_2563

J5,ECE298_TERMINAL_VIA,"GND Reference",EID=10,PACKAGE=PIN

J6,ECE298_RS_4PINREC,"RPM Speed Sensor",EID=12,PACKAGE=CONN-SIL4

J7,ECE298 RS 2PINHDR, "DC Motor", EID=11, PACKAGE=SIL-100-02

J8,ECE298_RS_2PINHDR,"8V EXT",EID=1A,PACKAGE=SIL-100-02

J9,ECE298_TERMINAL_VIA,"Motor Control Test",EID=F,PACKAGE=PIN

J11,ECE298_TERMINAL_VIA,"RPM Interrupt",EID=26,PACKAGE=PIN

J12,ECE298_RS_3PINHDR,"Servo Motor",EID=18,PACKAGE=SIL-100-03

J13,ECE298_TERMINAL_VIA, "Servo Motor test", EID=27, PACKAGE=PIN

J14,ECE298 RS 4PINREC, "RGB LED", EID=29, PACKAGE=CONN-SIL4

R1,9C04021A1500JLHF3,100,CODE="Digikey

311-150JDKR-ND", EID=2F, PACKAGE=RESC1005X40, PRIMTYPE=RESISTOR

R2,9C04021A1500JLHF3,50,CODE="Digikey

311-150JDKR-ND", EID=2C, PACKAGE=RESC1005X40, PRIMTYPE=RESISTOR

R3,9C04021A2000JLHF3,50,CODE="Digikey

311-200JCT-ND", EID=31, PACKAGE=RESC1005X40, PRIMTYPE=RESISTOR

RV1,ECE298_RS_POT10K,10K,CODE="Digikey

3361P-103GLFDKR-ND", EID=E, PACKAGE=TRIM 3361P, STATE=5

U1,ECE298_RS_74HCT541,ECE298_RS_74HCT541,EID=6,GND=GND,PACKAGE=SO20W,PINSWAP="1,19",VCC=+5.0V

U2,ECE298_RS_CMOS4050,ECE298_RS_CMOS4050,EID_A=7,EID_B=8,ITFMOD=CMOS,MODFILE=40BUF,PACKAGE=DIL16,VOLTAGE=+5.0V

U3,ECE298 RS L9110,"DC Motor Control L9110",EID=D,ITFMOD=TTL,PACKAGE=SO8

U4,ECE298_RS_74HCT541,ECE298_RS_74HCT541,EID=17,GND=GND,PACKAGE=SO20W,PINSWAP="1,19",VCC=+5.0V

*NETLIST,42

DC MOTOR PWR,6,CLASS=POWER

DC MOTOR PWR,LBL

J7,PS,2

U3.OP.4

J7,PS,1

U3,OP,1

J9,PS,1

RPM OUT,3,CLASS=SIGNAL

RPM OUT,LBL

J6,PS,3

U2,IP,5

PB0,3,CLASS=SIGNAL

PB0,GT

U3,IP,6

CN7,PS,34

PA6,3,CLASS=SIGNAL

PA6,GT

U3,IP,7

CN10,PS,13

PC7,3,CLASS=SIGNAL

PC7,GT

U2,OP,2

CN10,PS,19

PC6,4,CLASS=SIGNAL

PC6,GT

RXD,LBL

J1,PS,5

CN10,PS,4

PB2,4,CLASS=SIGNAL

PB2.GT

J11,PS,1

U2,OP,4

CN10,PS,22

PB9,3,CLASS=SIGNAL

PB9,GT

U1,IP,2

CN10,PS,5

PB8,3,CLASS=SIGNAL PB8,GT U1,IP,3 CN10,PS,3

PB6,3,CLASS=SIGNAL PB6,GT U1,IP,4 CN10,PS,17

PB5,3,CLASS=SIGNAL PB5,GT U1,IP,5 CN10,PS,29

PC13,3,CLASS=SIGNAL PC13,GT U1,IP,6 CN7,PS,23

PC12,3,CLASS=SIGNAL PC12,GT U1,IP,7 CN7,PS,3

PC11,3,CLASS=SIGNAL PC11,GT U1,IP,8 CN7,PS,2

PC10,3,CLASS=SIGNAL PC10,GT U1,IP,9 CN7,PS,1

A3,3,CLASS=SIGNAL A3,LBL U1,TS,18 J2,PS,2

A2,3,CLASS=SIGNAL A2,LBL U1,TS,17 J2,PS,3

A1,3,CLASS=SIGNAL A1,LBL U1,TS,16 J2,PS,4

A0,3,CLASS=SIGNAL A0,LBL U1,TS,15 J2,PS,5 B3,3,CLASS=SIGNAL B3,LBL U1,TS,14

J2,PS,6

B2,3,CLASS=SIGNAL

B2,LBL U1,TS,13

J2,PS,7

B1,3,CLASS=SIGNAL

B1,LBL

U1,TS,12

J2,PS,8

B0,3,CLASS=SIGNAL

B0,LBL

U1,TS,11

J2,PS,9

PB1,3,CLASS=SIGNAL

PB1,GT

RV1,PS,3

CN10,PS,24

SERVO MOTOR CONTROL,4,CLASS=SIGNAL

SERVO MOTOR CONTROL,LBL

J12,PS,1

J13,PS,1

U4,TS,18

PA0,3,CLASS=SIGNAL

PA0,GT

U4,IP,2

CN7,PS,28

PA8,3,CLASS=SIGNAL

PA8,GT

R2,PS,2

CN10,PS,23

PA12,3,CLASS=SIGNAL

PA12,GT

R1,PS,2

CN10,PS,12

PA11,3,CLASS=SIGNAL

PA11,GT

R3,PS,2

CN10,PS,14

BLUE,5,CLASS=SIGNAL

BLUE,LBL

R3,PS,1

U4,IP,5 J14,PS,4 U4,TS,15

GREEN,5,CLASS=SIGNAL

GREEN,LBL

R2,PS,1

U4,IP,4

J14,PS,3

U4,TS,16

RED,5,CLASS=SIGNAL

RED,LBL

R1,PS,1

U4,IP,3

J14,PS,1

U4,TS,17

PA10,4,CLASS=SIGNAL

PA10,GT

ECHO,LBL

J4,PS,3

CN10,PS,33

PA9,4,CLASS=SIGNAL

PA9,GT

TRIGGER,LBL

J4,PS,2

CN10,PS,21

TXD,3,CLASS=SIGNAL

TXD,LBL

U2,IP,3

J1,PS,4

{NC},53

CN7,PS,17

U2,PS,13

U2,PS,16

CN10,PS,37

CN10,PS,35

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CN7,PS,38
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U4,TS,11
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U4,TS,14
J6,PS,4
CN7,PS,14
CN10,PS,8
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CN7,PS,9
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CN7,PS,29
CN7,PS,27
CN7,PS,26
CN7,PS,25
CN7,PS,24
CN7,PS,11
CN7,PS,10
+3.3V,10,CLASS=POWER
+3.3V,PR
VCC,LBL
J4,PS,1
C4,PS,1
C2,PS,1
C1,PS,1
RV1,PS,2
C9,PS,1
CN7,PS,16
CN7,PS,12
+5.0V,9,CLASS=POWER
+5.0V,PR
J2,PS,10
U4,PP,20
C5,PS,1
C3,PS,1
U1,PP,20
J6,PS,1
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C7,PS,1
CN7,PS,18
+5V_EXT,5,CLASS=POWER
+5V EXT,PR
5V EXT,LBL
J12,PS,2
C8,PS,1
J3,PS,2
+8V EXT,6,CLASS=POWER
+8V_EXT,PR
U3,PP,2
U3,PP,3
C6,PS,1
C10,PS,1
J8,PS,2
GND,46,CLASS=POWER
GND,PR
VSS,PT
U4,PP,10
U4,IP,6
U4,IP,7
U4,IP,8
U4,IP,9
U4,IP,1
U4,IP,19
J1,PS,1
J1,PS,2
J1,PS,3
J1,PS,6
J4,PS,5
J4,PS,4
C4,PS,2
J14,PS,2
J12,PS,3
J3,PS,1
C8,PS,2
C5,PS,2
C3,PS,2
C2,PS,2
C1,PS,2
J5,PS,1
RV1,PS,1
C9,PS,2
U1,PP,10
U1,IP,1
U1,IP,19
J2,PS,1
J6,PS,2
C7,PS,2
U3,PP,5
U3,PP,8
C6,PS,2
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C10,PS,2 J8,PS,1 CN10,PS,9 CN10,PS,32 CN10,PS,20 CN7,PS,8 CN7,PS,22 CN7,PS,20 CN7,PS,19 U2,PP,8

VCC/VDD,3,CLASS=POWER VDD,PT VCC/VDD,PR U2,PP,1