single person pose

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[1]: import cv2
     import time
     import numpy as np
     import matplotlib.pyplot as plt
     %matplotlib inline
[2]: MODE = "MPI"
     if MODE is "COCO":
         protoFile = "pose/coco/pose_deploy_linevec.prototxt"
         weightsFile = "pose/coco/pose_iter_440000.caffemodel"
         nPoints = 18
         POSE_PAIRS = [
      \rightarrow [1,0],[1,2],[1,5],[2,3],[3,4],[5,6],[6,7],[1,8],[8,9],[9,10],[1,11],[11,12],[12,13],[0,14],
     elif MODE is "MPI" :
         protoFile = "pose/mpi/pose_deploy_linevec_faster_4_stages.prototxt"
         weightsFile = "pose/mpi/pose_iter_160000.caffemodel"
         nPoints = 15
         POSE_PAIRS = [[0,1], [1,2], [2,3], [3,4], [1,5], [5,6], [6,7], [1,14], 
      \rightarrow [14,8], [8,9], [9,10], [14,11], [11,12], [12,13]]
[3]: frame = cv2.imread("input/gym.jpeg")
     frameCopy = np.copy(frame)
     frameWidth = frame.shape[1]
     frameHeight = frame.shape[0]
     threshold = 0.1
[4]: net = cv2.dnn.readNetFromCaffe(protoFile, weightsFile)
     inWidth = 368
     inHeight = 368
     inpBlob = cv2.dnn.blobFromImage(frame, 1.0 / 255, (inWidth, inHeight),
                                (0, 0, 0), swapRB=False, crop=False)
     net.setInput(inpBlob)
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output = net.forward()
H = output.shape[2]
W = output.shape[3]
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[7]: # Empty list to store the detected keypoints
     points = []
     for i in range(nPoints):
         # confidence map of corresponding body's part.
         probMap = output[0, i, :, :]
         # Find global maxima of the probMap.
         minVal, prob, minLoc, point = cv2.minMaxLoc(probMap)
         # Scale the point to fit on the original image
         x = (frameWidth * point[0]) / W
         y = (frameHeight * point[1]) / H
         if prob > threshold :
             cv2.circle(frameCopy, (int(x), int(y)), 4, (0, 255, 255), thickness=-1, ___
      →lineType=cv2.FILLED)
             cv2.putText(frameCopy, "{}".format(i), (int(x), int(y)), cv2.
      →FONT_HERSHEY_SIMPLEX, 0.5, (0, 0, 255), 1, lineType=cv2.LINE_AA)
             cv2.circle(frame, (int(x), int(y)), 4, (0, 0, 255), thickness=-1,__
      →lineType=cv2.FILLED)
             # Add the point to the list if the probability is greater than the _{f L}
      \rightarrow threshold
             points.append((int(x), int(y)))
         else :
             points.append(None)
     # Draw Skeleton
     for pair in POSE_PAIRS:
         partA = pair[0]
         partB = pair[1]
         if points[partA] and points[partB]:
             cv2.line(frame, points[partA], points[partB], (0, 255, 255), 2)
     plt.figure(figsize=[15,15])
     plt.imshow(cv2.cvtColor(frameCopy, cv2.COLOR_BGR2RGB))
     plt.figure(figsize=[15,15])
     plt.imshow(cv2.cvtColor(frame, cv2.COLOR_BGR2RGB))
     plt.savefig('output/gym-pose.jpeg')
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