CONICAL REFRACTION POLARIMETER

BUILDING A STATE OF THE ART AFFORDABLE DEVICE TO MONITOR LINEAR POLARIZATION

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End-to-End Creation of a Conical Refraction Polarimeter

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Introduction

Abstract

Objectives

Guideline

Part A: Conical Refraction Essentials

In this first section, we will review the basic theoretical explanation of the Conical Refraction (CR) phenomenon in which the developed device will be based.

A.1. The Revival of Conical Refraction

Sartun Hamiltonegaz etc, esan zer dan en sí, ta zer implikeu ban beren egunien, zelan gero aztute geratu zan hasta tal eta formulaziño modernoak tal. Ipiñi dibujo klasiko bat del fenómeno, el cono ese, nik einde eskuz.

A.2. Berry's Mathematical Description of the Phenomenon

En más o menos detalle guredozulez azaldu fenomenoan matematikie eta batezbe heldu formula finalatara

A.3. Simulating the Phenomenon

Azaldu GPU/CPU tradeoffa, zelan implemente doten eta jarri imagenak. Azaldu zelan si lienar pol tal, si cricular pol tal imagenakaz. Sugeridu zer alko genun ein orduen linear polrztion aldaketak antzemateko.

A.4. A Natural Polarimeter

Esan zelan alko zendun argixen polarizaziño tal danak deskribatu einde bi besogaz et al, baia zelan simplifike al dan ze kiralidade temak LPgaz nahiko eta hori da polarimetroan merkatu handixetako bat.

Apppendix α : Jones and Stokes Representations of Polarization

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Part B: Designing the Hardware

B.1. Experimental Implementations of the Polarimeter

Azaldu bakjoitza dibujo bategaz eta identifike problemak, edo gubazun hori hobeto alrgazki batzuk ipiñitze hurrengo seksiñoan, esaten posibles razones a las ke se deba, al dozu citeu ah artikuloa ta beran imagena bebai.

B.2. Main Non-Idealities in the Experimental Rings

B.3. Final Proofs of Concept

Bat ya einde egioin zana, en el ke implementé la GUI akella, argazki bat, con fotos de la GUI etc.

Bestie, lortzen badogun eitzie housiñegaz y tal, planoa ein eskuz ni ke sea

COST ANALYSIS EGIN

Appendix β : Employed Optical Elements

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Part C: Designing the Software

C.1. Artificial Noise Generation

C.2. Simulated Image Datasets

C.3. Embedding Space Algorithms

- C.3.1. Data Manifold Dimension Identification
- C.3.2. Metric Learning
- C.3.3. Nearest Neighbors

C.3. Geometric Algorithms

Tos los geometricos y los optimizadores implementados.

C.4. Simulation Fitting Algorithms

C.5. The Best Algorithm and Pre-processing

Appendix γ : The Implemented Optimizers

Ba hori

Part D: The Final Device

- D.1. Performance on Experimental Data
- D.2. Commercial Polarimeters
- D.3. Potential Niches

Conclusions

References

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