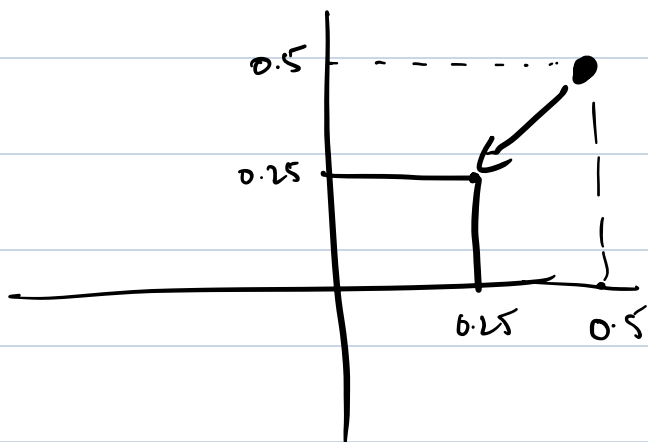


HW 1

1) $0.5 \times 0.5 \rightarrow 0.25 \times 0.25$

Scaling
$$\begin{bmatrix} C_x & 0 & 0 \\ 0 & C_y & 0 \\ 0 & 0 & 1 \end{bmatrix}$$



$$C_x = C_y = \frac{1}{2}$$

$$\begin{bmatrix} \frac{1}{2} & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$0.5 \times 0.5 \rightarrow 0.25 \times 0.5$ $C_x = \frac{1}{2}$ $C_y = 1$

$$\begin{bmatrix} \frac{1}{2} & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

2)

$$\begin{pmatrix} x_2 \\ y_2 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & t_x \\ 0 & 1 & t_y \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ y_1 \\ 1 \end{pmatrix}$$

$\xrightarrow{U_{12}}$

$$\begin{pmatrix} x_3 \\ y_3 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & t'_x \\ 0 & 1 & t'_y \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_2 \\ y_2 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$= \underbrace{\begin{pmatrix} 1 & 0 & t_x' \\ 0 & 1 & t_y' \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & t_x \\ 0 & 1 & t_y \\ 0 & 0 & 1 \end{pmatrix}}_{U_{13}} \begin{pmatrix} x_1 \\ y_1 \\ 1 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 & t_x + t_x' \\ 0 & 1 & t_y + t_y' \\ 0 & 0 & 1 \end{pmatrix}$$

$$U_{12} \cdot U_{23} \neq U_{13}$$

3)

matlab \rightarrow graph

$$\begin{pmatrix} x_g \\ y_g \\ 1 \end{pmatrix} = \begin{pmatrix} c_x & 0 & 0 \\ 0 & c_y & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_m \\ y_m \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} x_g' \\ y_g' \\ 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & t_x \\ 0 & 1 & t_y \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_g \\ y_g \\ 1 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 & t_x \\ 0 & 1 & t_y \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} c_x & 0 & 0 \\ 0 & c_y & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_m \\ y_m \\ 1 \end{pmatrix}$$

$$= \begin{pmatrix} c_x & 0 & t_x \\ 0 & c_y & t_y \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_m \\ y_m \\ 1 \end{pmatrix}$$

$$\begin{aligned} (x_g, y_g) &\longrightarrow (x_m, y_m) \\ 0, 635 &\longrightarrow (565, 1518) \\ 5, 635 &\longrightarrow (646, 1518) \end{aligned}$$

4) n control pts

$$\begin{array}{ccc} \underline{x_1, y_1} & \longrightarrow & \underline{x'_1, y'_1} \\ \vdots & & \vdots \\ \underline{x_n, y_n} & \longrightarrow & \underline{x'_n, y'_n} \end{array}$$

$$P_x = [a \ b \ c \ d \ e \ f]$$

$$P_y = [A \ B \ C \ D \ E \ F]$$

$$X' = H \circledast P_k$$

$$\begin{bmatrix} x'_1 \\ \vdots \\ x'_n \end{bmatrix}_{n \times 1} = \begin{bmatrix} x_1^2 & y_1^2 & x_1 y_1 & x_1 & y_1 & 1 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ x_n^2 & y_n^2 & x_n y_n & x_n & y_n & 1 \end{bmatrix}_{n \times 6} \begin{bmatrix} a \\ b \\ c \\ d \\ e \\ f \end{bmatrix}_{6 \times 1} =$$

$$y' = \textcircled{H} p_y$$

$\sqrt{\quad}$

$$\Rightarrow \begin{aligned} p_x &= H^{-1} x' \\ p_y &= \underline{H^T y'} \end{aligned}$$