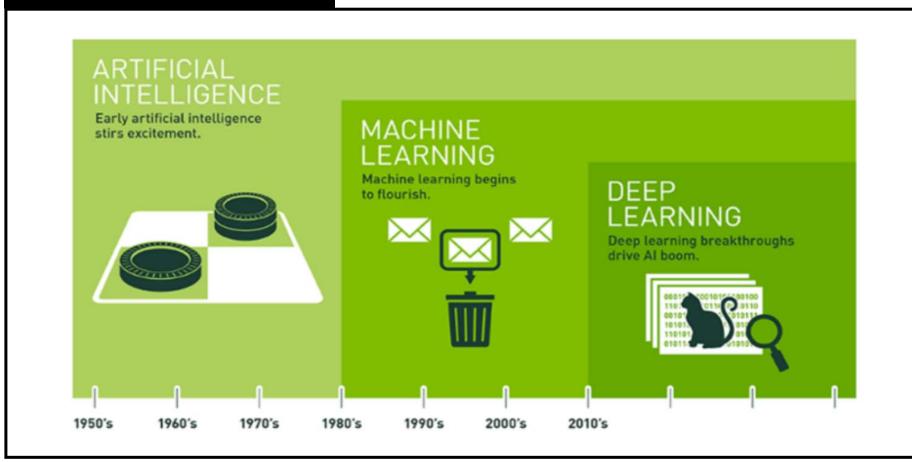
## 딥러닝(Deep Learning) 이론



#### 1. 인공지능, 머신러닝, 딥러닝

### 인공지능 > 머신러닝 > 딥러닝

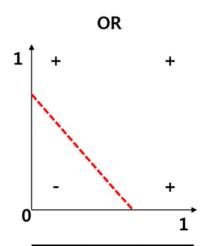




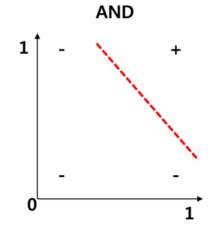
#### **Machine Learning Feature Extraction -> Train -> Test** Label Learning Algorithm Assignment Preprocessing Input image SVM, Cat or Features: HAAR, HOG, Random Background SIFT, SURF Forests, ANN hyperplane



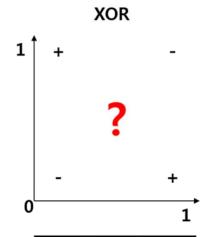
#### **Neural Network - XOR**



| $x_1$ | $x_2$ | y |
|-------|-------|---|
| 0     | 0     | 0 |
| 0     | 1     | 1 |
| 1     | 0     | 1 |
| 1     | 1     | 1 |

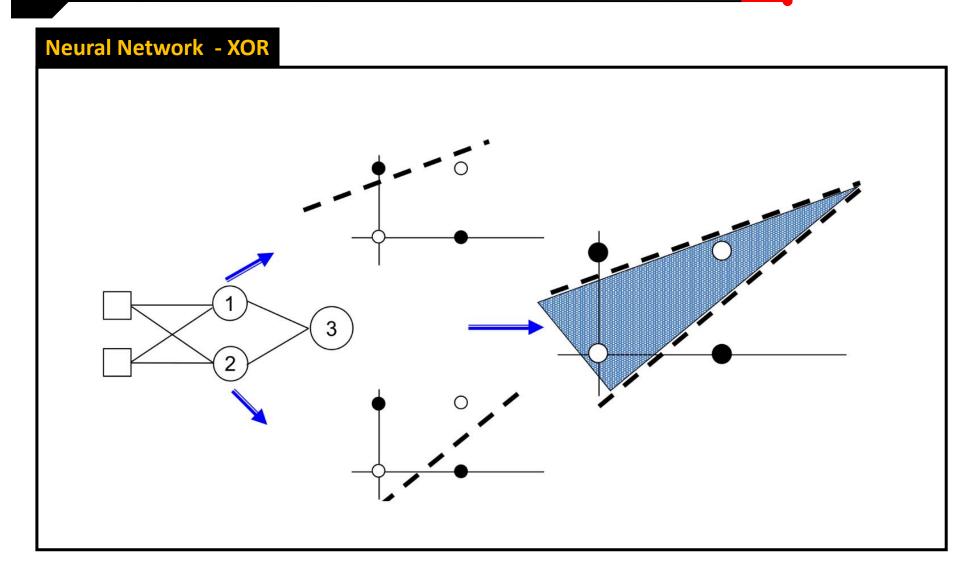


| $x_1$ | $x_2$ | y |
|-------|-------|---|
| 0     | 0     | 0 |
| 0     | 1     | 0 |
| 1     | 0     | 0 |
| 1     | 1     | 1 |



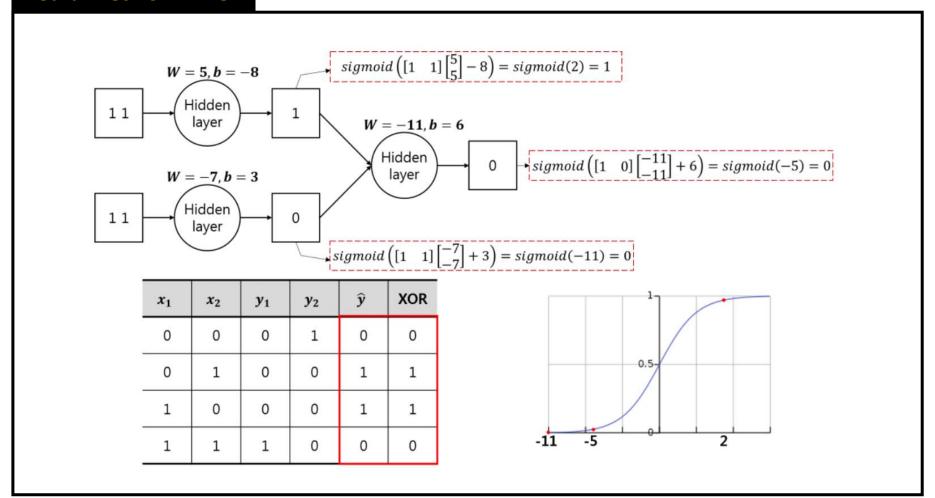
| $x_1$ | $x_2$ | y |
|-------|-------|---|
| 0     | 0     | 0 |
| 0     | 1     | 1 |
| 1     | 0     | 1 |
| 1     | 1     | 0 |





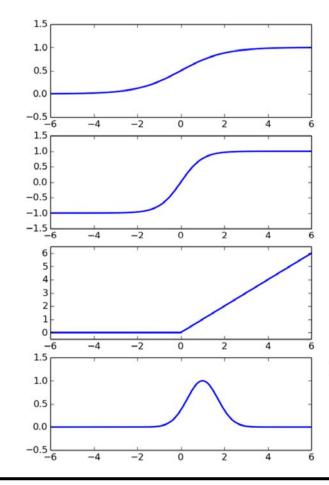


#### **Neural Network - XOR**





#### **Neural Network - activation function**



#### Sigmoid

$$\phi(z) = \frac{1}{1 + e^{-z}}$$

#### Hyperbolic Tangent

$$\phi(z) = \frac{e^z - e^{-z}}{e^z + e^{-z}}$$

#### Rectified Linear

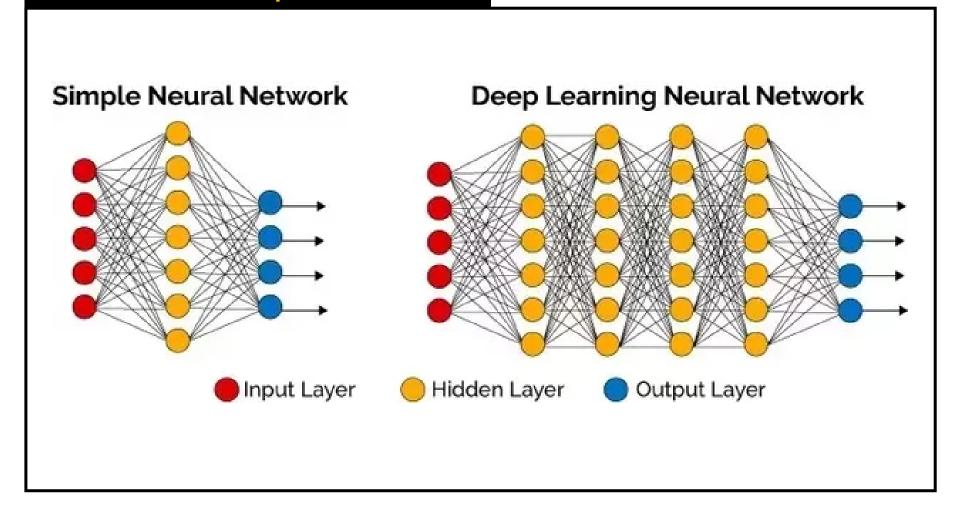
$$\phi(z) = \begin{cases} 0 & \text{if } z < 0 \\ z & \text{if } z \ge 0 \end{cases}$$

#### **Radial Basis Function**

$$\phi(z,c) = e^{-(\epsilon ||z-c||)^2}$$



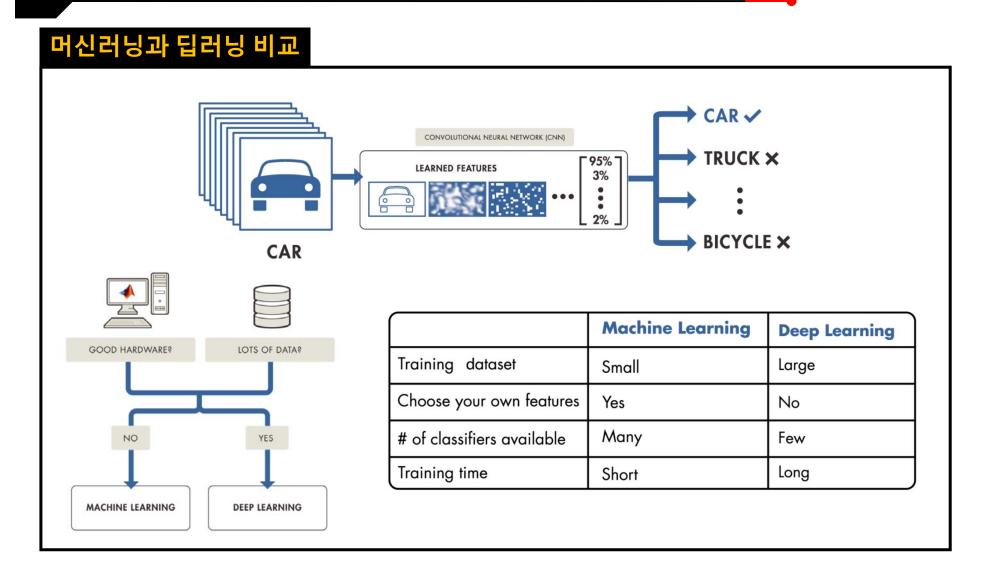
#### **Neural Network vs Deep Neural Network**



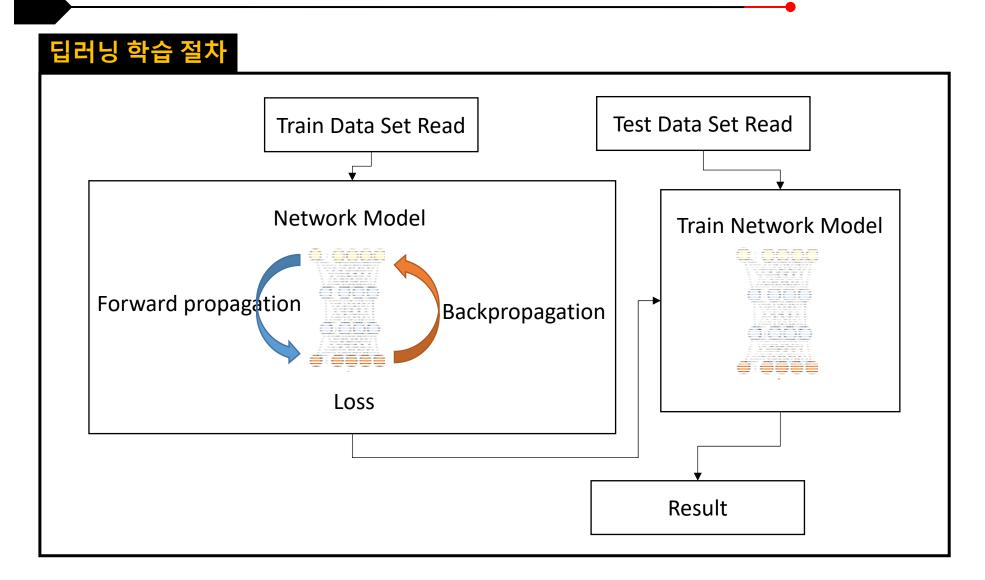


## 머신러닝과 딥러닝 비교 MACHINE LEARNING WORKFLOW TRAINING DATA **FEATURE EXTRACTION** MACHINE LEARNING MODEL CLASSIFICATION TEST DATA CAT **MACHINE LEARNING IMAGES FEATURES** WHAT THE OBJECT IS

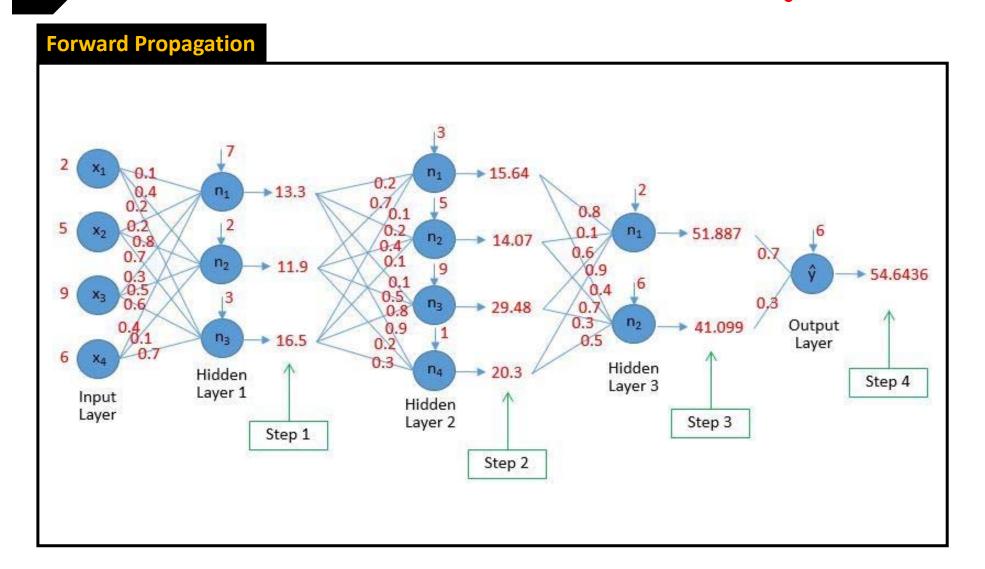














#### **Backpropagation**

- · 2 classes, 2 dim. input data
  - training set:

ex.1: 0.6 0.1 | class 1 (banana)

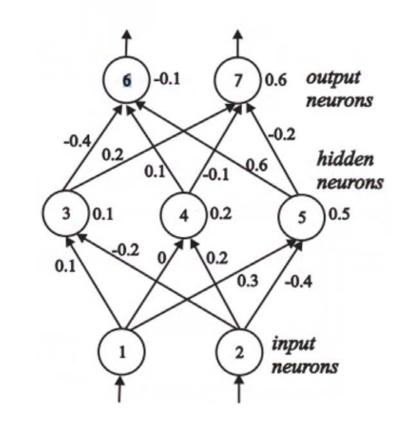
ex.2: 0.2 0.3 | class 2 (orange)

•••

- Network architecture
  - · How many inputs?
  - · How many hidden neurons?
    - · Heuristic:

n=(inputs+output\_neurons)/2

- · How many output neurons?
- · What encoding of the outputs?
  - ·10 for class 1, 01 for class 0
- · Initial weights and learning rate
  - Let's  $\eta$ =0.1 and the weights are set as in the picture





#### Backpropagation

1. Forward pass for ex. 1 - calculate the outputs o<sub>6</sub> and o<sub>7</sub>

$$o_1$$
=0.6,  $o_2$ =0.1, target output 1 0, i.e. class 1

· Activations of the hidden units:

$$net_3 = o_1 *w_{13} + o_2 *w_{23} + b_3 = 0.6*0.1+0.1*(-0.2)+0.1=0.14$$
  
 $o_3 = 1/(1+e^{-net3}) = 0.53$ 

$$net_4 = o_1 *w_{14} + o_2 *w_{24} + b_4 = 0.6*0 + 0.1*0.2 + 0.2 = 0.22$$
 $o_4 = 1/(1 + e^{-net4}) = 0.55$ 

$$net_5 = o_1 *w_{15} + o_2 *w_{25} + b_5 = 0.6*0.3+0.1*(-0.4)+0.5=0.64$$
 $o_5 = 1/(1 + e^{-net5}) = 0.65$ 

Activations of the output units:

$$\begin{array}{l} net_6 = o_3 *w_{36} + o_4 *w_{46} + o_5 *w_{56} + b_6 = 0.53 *(-0.4) + 0.55 *0.1 + 0.65 *0.6 - 0.1 = 0.13 \\ o_6 = 1/(1 + e^{-net6}) = 0.53 \end{array}$$

$$\begin{array}{l} net_7 = o_3 *w_{37} + o_4 *w_{47} + o_5 *w_{57} + b_7 = 0.53 *0.2 + 0.55 *(-0.1) + 0.65 *(-0.2) + 0.6 = 0.52 \\ o_7 = 1/(1 + e^{-net7}) = 0.63 \end{array}$$



#### **Backpropagation**

#### 2. Backward pass for ex. 1

• Calculate the output errors  $\delta_6$  and  $\delta_7$  (note that  $d_6=1$ ,  $d_7=0$  for class 1)

$$\delta_6 = (d_6 - o_6) * o_6 * (1 - o_6) = (1 - 0.53) * 0.53 * (1 - 0.53) = 0.12$$

$$\delta_7 = (d_7 - o_7) * o_7 * (1 - o_7) = (0 - 0.63) * 0.63 * (1 - 0.63) = -0.15$$

• Calculate the new weights between the hidden and output units ( $\eta$ =0.1)

$$\Delta w_{36} = \eta * \delta_6 * o_3 = 0.1*0.12*0.53=0.006$$

$$W_{36}^{\text{new}} = W_{36}^{\text{old}} + \Delta W_{36} = -0.4 + 0.006 = -0.394$$

$$\Delta w_{37} = \eta * \delta_7 * o_3 = 0.1*-0.15*0.53=-0.008$$

$$W_{37}^{\text{new}} = W_{37}^{\text{old}} + \Delta W_{37} = 0.2 - 0.008 = -0.19$$

Similarly for w46 new, w47 new, w56 new and w57 new

For the biases b<sub>6</sub> and b<sub>7</sub> (remember: biases are weights with input 1):

$$\Delta b_6 = \eta * \delta_6 * 1 = 0.1*0.12=0.012$$

$$\mathbf{b}_6^{\text{new}} = \mathbf{b}_6^{\text{old}} + \Delta \mathbf{b}_6 = -0.1 + 0.012 = -0.012$$



#### **Backpropagation**

• Calculate the errors of the hidden units  $\delta_3$ ,  $\delta_4$  and  $\delta_5$ 

$$\delta_3 = o_3 * (1-o_3) * (w_{36} * \delta_6 + w37 * \delta_7) =$$
= 0.53\*(1-0.53)(-0.4\*0.12+0.2\*(-0.15))=-0.019
Similarly for  $\delta_4$  and  $\delta_5$ 

• Calculate the new weights between the input and hidden units ( $\eta$ =0.1)

$$\Delta w_{13} = \eta * \delta_3 * o_1 = 0.1*(-0.019)*0.6 = -0.0011$$

$$w_{13}^{\text{new}} = w_{13}^{\text{old}} + \Delta w_{13} = 0.1 - 0.0011 = 0.0989$$
Similarly for an new are new are new are new and we

Similarly for w23 new, w14 new, w24 new, w15 new and w25 new; b3, b4 and b6



#### 3. 딥러닝(Deep Learning) - 프로그래밍 언어, 프레임워크, 네트워크

#### 프로그래밍 언어



- 범용 컴파일 프로그래밍 언어
- 다양한 라이브러리 포함



- Python 범용 인터프리터 프로그래밍 언어
  - Numpy, Scipy 등 과학계산 및 머신러닝을 위한 패키지가 발전됨



#### Matlab

- 과학 계산용 프로그래밍 언어(Mathworks사에서 개발)



- 통계 및 그래프용 프로그래밍 언어(뉴질랜드 오클랜드 대학교 개발)



#### 기타

- Java, Lua, Go, Scala



#### 프레임워크









theano



TensorFlow
Caffe
Keras
Torch
Theano

Deeplearning4j
MxNet
Microsoft Cognitive Toolkit (CNTK)
Lasagne
BigDL











#### 프레임워크

#### - TensorFlow

가장 인기있는 딥러닝 라이브러리 중 하나 Google Brain 팀에서 개발했으며 2015년 오픈소스로 공개 Python 기반 라이브러리, CPU 및 GPU와 모든 플랫폼, 데스크톱 및 모바일에서 사용 가능 C++ 및 R과 같은 다른 언어 지원 딥러닝 모델을 직접 작성, Keras 라이브러리를 사용하여 직접 작성 가능

#### - Caffe

최초의 딥러닝 라이브러리 중 하나, 표현, 속도 및 모듈성을 염두에 두고 개발 Python 인터페이스를 가지고 있는 C++ 라이브러리 CNN(Convolutional Neural Networks)을 모델링 할 때 기본 애플리케이션 사용 Caffe Model Zoo에서 미리 훈련된 여러 네트워크를 바로 사용 가능 CNN 모델링이나 이미지 처리 문제 해결 Caffe를 고성능 개방형 학습 모델을 구축 할 수 있는 Caffe2 출시

#### - Keras

직접 모델을 만드는 경우 Theano와 Tensorflow 보다 적용이 쉬움 K효율적인 신경망 구축을 위한 단순화 된 인터페이스로 개발 Theano 또는 Tensorflow에서 작동하도록 구성 Python으로 작성, 매우 가볍고 배우기 적합 적은 코드 작성으로 Keras를 사용하여 신경망을 만들 수 있음



#### 네트워크

**CNN (Convolutional Neural Network)** 

**RNN (Recurrent Neural Network)** 

**RBM (Restricted Boltzmann Machine)** 

#### CNN 모델

**AlexNet** 

GoogleNet

ResNet

**DenseNet** 

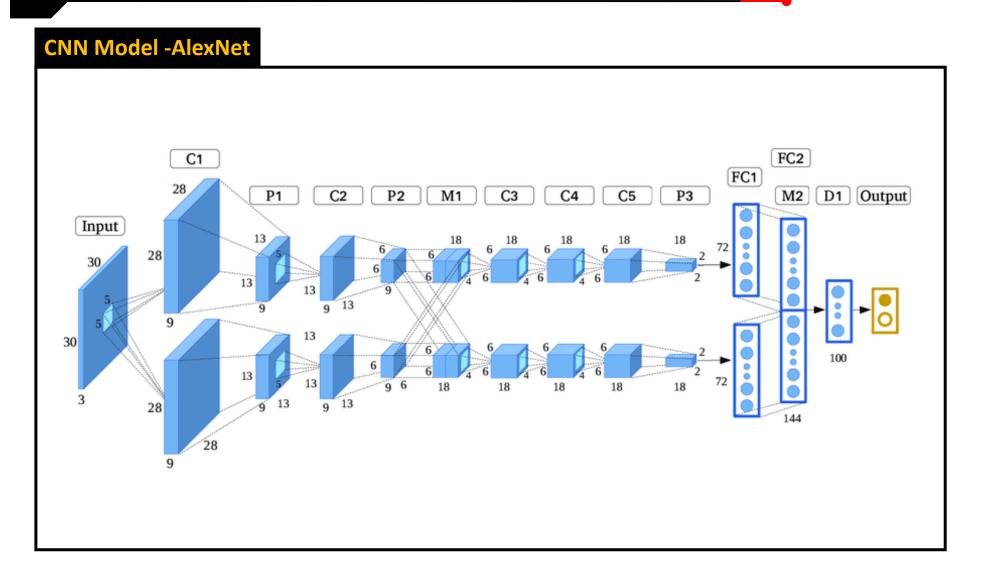
**RCNN(Region Based CNNs)** 

**CNNs for NLP** 

#### FAST 객체 탐색 기법

YOLO(You only Look Once)
SSD(Single Shot Detector)
Fast R-CNN, Faster R-CNN, Mask R-CNN



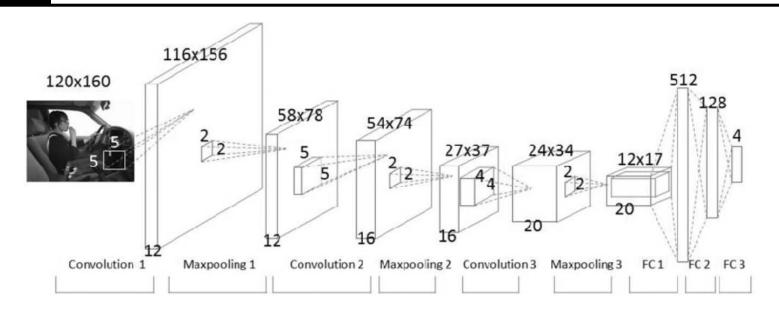




#### **CNN Model - GoogleNet** Nine Inception Modules Label SoftMax Average Linear MaxPool Pooling w/Loss **Inception Module** Traditional Input Convolutions (Conv + MaxPool + Previous Conv + MaxPool) Concatenate 3x3 Max



#### CNN 기초



- Filter
- ■Kernel
- Convolution
- ■Stride
- ■Feature Map

- Activation Function
- Channel
- Padding
- Activation Map

- ■Pooling Layer
- ■Fully Connected Layer
- Dropout
- ■Soft Max



### Filter, Kernel

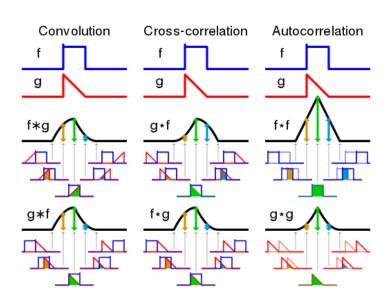
| Operation      | Kernel  | Image result | Sharpen   |  |
|----------------|---|--------------|---|--|
| Identity       | $\begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$         |              | Box blur<br>(normalized)                        |  |
| Edge detection | $\begin{bmatrix} 1 & 0 & -1 \\ 0 & 0 & 0 \\ -1 & 0 & 1 \end{bmatrix}$       |              | Gaussian bl                                     |  |
|                | $\begin{bmatrix} 0 & 1 & 0 \\ 1 & -4 & 1 \\ 0 & 1 & 0 \end{bmatrix}$        |              | Gaussian bl                                     |  |
|                | $\begin{bmatrix} -1 & -1 & -1 \\ -1 & 8 & -1 \\ -1 & -1 & -1 \end{bmatrix}$ |              | Unsharp ma Based on Ga with amount threshold as |  |

| Sharpen   | $\begin{bmatrix} 0 & -1 & 0 \\ -1 & 5 & -1 \\ 0 & -1 & 0 \end{bmatrix}$   |
|---|---|
| Box blur<br>(normalized)  | $\frac{1}{9} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$   |
| Gaussian blur 3 × 3 (approximation)   | $\frac{1}{16} \begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \end{bmatrix}$  |
| Gaussian blur 5 × 5 (approximation)   | $\frac{1}{256} \begin{bmatrix} 1 & 4 & 6 & 4 & 1 \\ 4 & 16 & 24 & 16 & 4 \\ 6 & 24 & 36 & 24 & 6 \\ 4 & 16 & 24 & 16 & 4 \\ 1 & 4 & 6 & 4 & 1 \end{bmatrix}$      |
| Unsharp masking 5 × 5 Based on Gaussian blur with amount as 1 and threshold as 0 (with no image mask) | $ \frac{-1}{256} \begin{bmatrix} 1 & 4 & 6 & 4 & 1 \\ 4 & 16 & 24 & 16 & 4 \\ 6 & 24 & -476 & 24 & 6 \\ 4 & 16 & 24 & 16 & 4 \\ 1 & 4 & 6 & 4 & 1 \end{bmatrix} $ |



#### Convolution

- 컨볼루션의 정의
  - 두 함수를 합성하여 만든 새로운 함수로 아래와 같이 정의  $h(x) = (f * g)(x) = \int f(a)g(x-a)da$
  - 개념적으로는 두 함수가 서로 볍치는 면적이 컨볼루션 함수의 값



| 1 | 1 | 1     | 0                      | 0                      |
|---|---|-------|------------------------|------------------------|
| 0 | 1 | 1 1 1 |                        | 0                      |
| 0 | 0 | 1,    | <b>1</b> <sub>×0</sub> | <b>1</b> <sub>×1</sub> |
| 0 | 0 | 1,0   | 1,                     | <b>O</b> <sub>×0</sub> |
| 0 | 1 | 1,    | 0,0                    | 0,                     |

Image

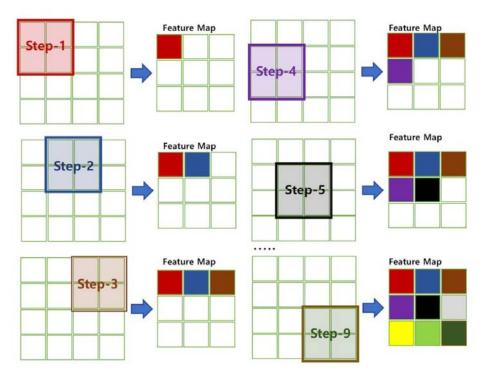
| 4 | 3 | 4 |
|---|---|---|
| 2 | 4 | 3 |
| 2 | 3 | 4 |

Convolved Feature

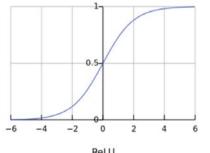


#### **Stride, Step, Feature Map, Activation Function**

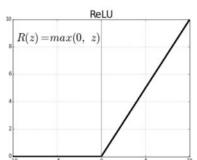
stride가 1로 필터를 입력 데이터에 순회하는 예시



#### **Activation Function**



Sigmoid



ReLu

stride가 2로 설정되면 필터는 2칸씩 이동하면서 합성곱 계산

Activation Map은 Feature Map 행렬에 활성 함수를 적용한 결과



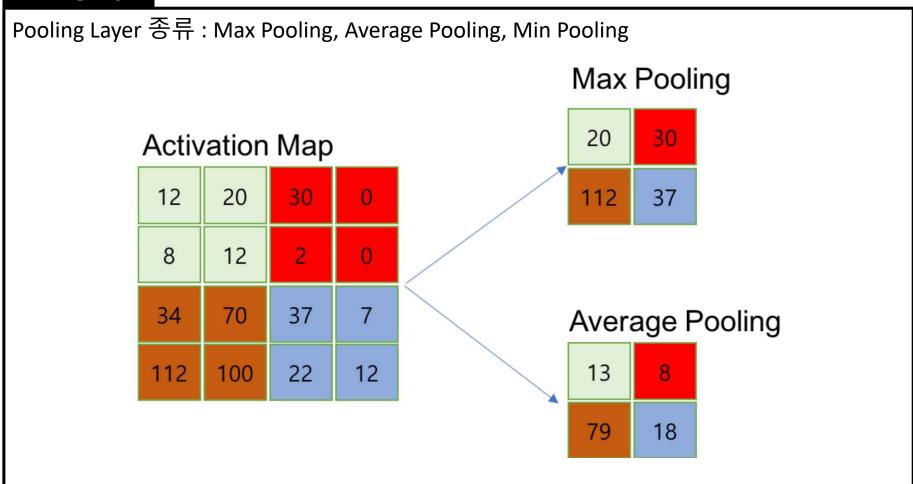
# Channel **RED** channel **GREEN** channel **BLUE** channel 24-bit RGB image



#### Multi- Channel, Feature Map, Activation Map, Padding Activation Map은 Feature Map 행렬에 활성 함수를 적용한 결과 Input data with 3 channel 0 channel 0 0 0 1 0 0 0 1 0 0 0 1 0 1 0 0 0 0 0 0000 32 x 32 x 3 0 0 0 36 1 0 0 1 0 0 0 0 0 100 1 0 1 1 0 1 0 0 1 0 1 0 Filter 0 0 0 1 1 0 1 1 Convolution Result of 3 4 Channel 36 **Feature Map**



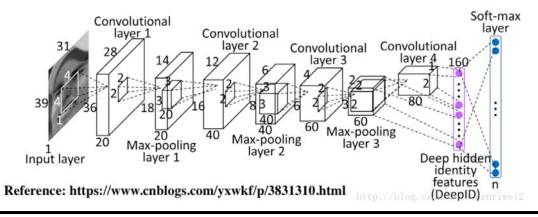
#### **Pooling Layer**





## 전체 파라미터 수와 레이어 Input/Output 요약

| layer                 | Filter     | Stride | Pooling | 활성함수    | Input Shape  | Output Shape | 파라미터 수  |
|-----------------------|------------|--------|---------|---------|--------------|--------------|---------|
| Convolution Layer 1   | (4, 4, 20) | 1      | x       | relu    | (39, 31, 1)  | (36, 28, 20) | 320     |
| Max Pooling Lyaer 1   | х          | 2      | (2, 2)  | х       | (36, 28, 20) | (18, 14, 20) | 0       |
| Convolution Layer 2   | (3, 3, 40) | 1      | x       | relu    | (18, 14, 20) | (16, 12, 40) | 360     |
| Max Pooling Lyaer 2   | х          | 2      | (2, 2)  | x       | (16, 12, 40) | (8, 6, 40)   | 0       |
| Convolution Layer 3   | (3, 3, 60) | 1      | 1       | relu    | (8, 6, 40)   | (6, 4, 60)   | 540     |
| Max Pooling Lyaer 3   | х          | 2      | (2, 2)  | х       | (6, 4, 60)   | (3, 2, 60)   | 0       |
| Convolution Layer 4   | (2, 2, 80) | 1      | 1       | relu    | (3, 2, 60)   | (2, 1, 80)   | 320     |
| Flatten               | х          | х      | x       | х       | (2, 1, 80)   | (160, 1)     | 0       |
| fully connected Layer | х          | х      | х       | softmax | (160, 1)     | (100, 1)     | 160,000 |

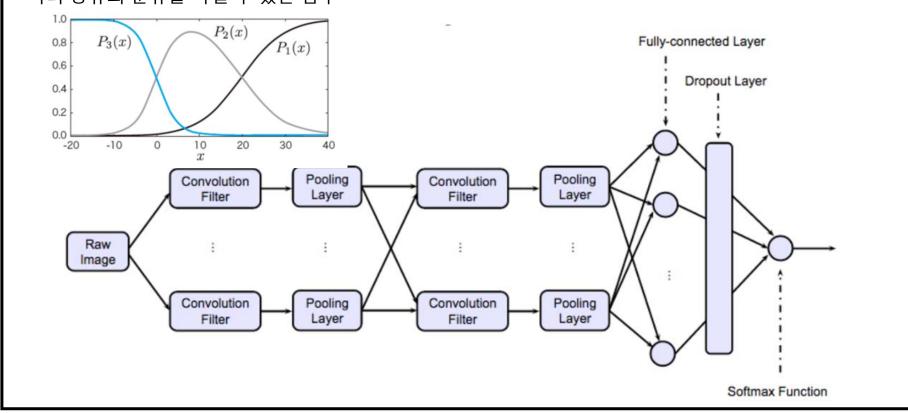




#### **Fully Connected Layer, Softmax Layer**

#### - Softmax

- 앞에서 언급한 sigmoid나 ReLu와 같은 Activation Function의 일종 여러 종류의 분류를 가질 수 있는 함수

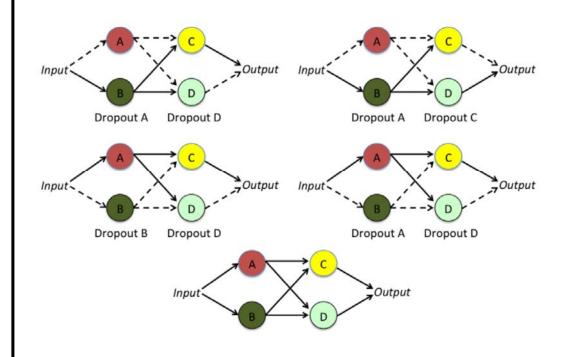


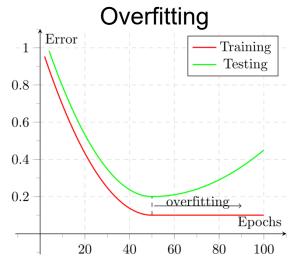


#### **Dropout Layer, Over-fitting**

- Dropout : Overfitting을 줄이기 위한 정규화 기법

CNN에서는 Dropout Layer를 Fully connected network 뒤에 놓지만, 상황에 따라 max pooling 계층 뒤에 놓기도 함







#### **Inception, Factorization, Asymmetric Factorization** Filter Concat Filter Concat Filter Concat 3x3 nx1 5x5 3x3 1x1 3x3 3x3 1x1 1x1 Pool 1x1 1x1 1x1 Pool 1x1 1x1 1x1 1x1 Pool Base Base Base Inception **Factorization Asymmetric Factorization**



# 감사합니다.

Thank you.

