

# ASSIGNMENT 5

①

Input: You are given a directed graph  $G_1$  modeling a flight network. There is an edge from airport A to B if there is a direct flight from A to B. The capacity of an edge  $e$  is labeled with the corresponding flight capacity  $\text{cap}(e)$ . Each edge has a start time  $s(e)$  and a finish time  $f(e)$ .

Task:- Given a source, and a target airport, our goal is to find the maximum number of passengers that can be sent from the source airport starting at 6AM to the target airport within 5 hours (11AM).

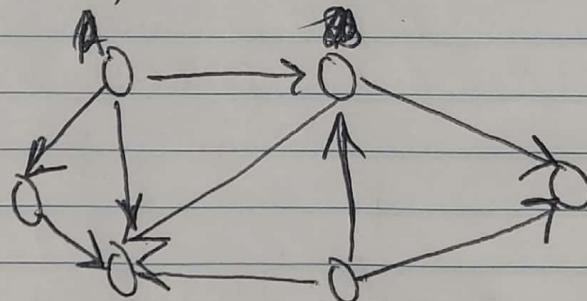
Solution

A → source  
C → target

e-1: A → B

e-2: A → B → D → C

e-3: A, B → C



⇒ Using Depth first Search

Step I:- I would first of all, find the path and calculate the flow for the path. Would search through the path from the source to the target.

Step II:- I would then reverse the first step flow and would do a check to determine if the new path can be implemented correctly.

Step III: Would then iterate each path & check whether the new flow was implemented and then it stops.

Step IV: <sup>else, it</sup> Would then reverse and check if the flow improves in the DTS

~~Start time~~  $\rightarrow$   $f_t$  of the capacity edge(e)  
Start time to finish time; the capacity of the edge e  
depends on the st (start time)  
there should be a condition to check if the start time  
 $st \geq f_t$  is equal or greater than  
of the previous edge.

Formal Proof of Correctness

Have a directed graph G; in the graph would want to move from point A to point B  $A \rightarrow B$ , with the goal to find the maximum number (max capacity)  
And to go, pass through path B would need to go by the minimized version of running the maximum flow algorithm  
 $\Rightarrow A \rightarrow C \rightarrow B$

Going from  $A \rightarrow e \rightarrow B$  by taking the most capacity that if it gets there correctly by the time constraint; would have the solution unless would go back and check the other best choice and iterate from there (repeat).  
With the maximum flow algorithm ~~will~~ will get the maximum source-target flow is equal to the capacity of the minimum ( $s, t$ ) cut.

Time Complexity Analysis:-

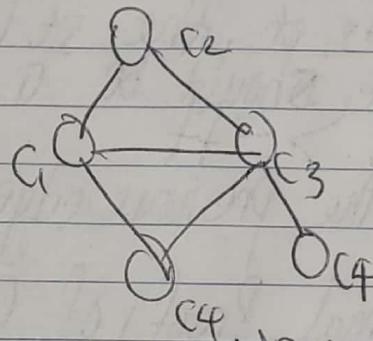
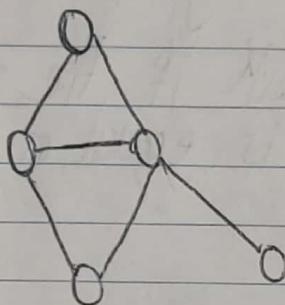
The time complexity of the algorithm would be

$$\underline{O(v * e)}$$

Q2 Let  $G_1$  be a graph with  $n$  vertices. The  $K$ -colouring problem is to decide whether the vertices of  $G_1$  can be labelled from the set  $\{1, 2, \dots, K\}$  such that for every edge  $(v, w)$  in the graph, the labels of  $v$  and  $w$  are different.

Is the  $(n-4)$ -colouring problem in P or NP?

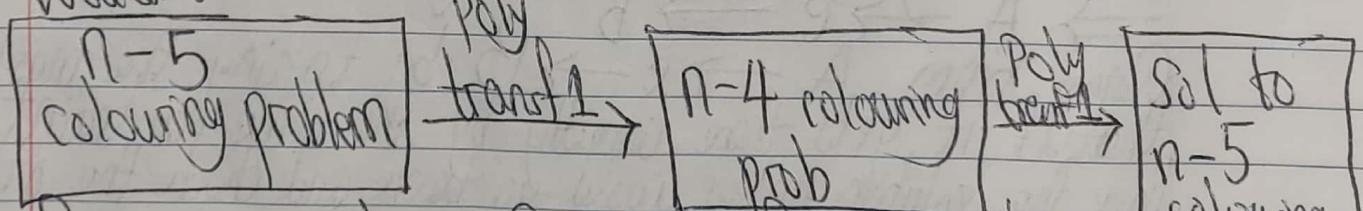
Solution



Firstly, I will try to prove  $n-4$  colouring is NP-hard

I would assume the  $n$  vertices is not bipartite. Would assume somebody proved  $n-5$  colouring problem is NP-hard.

Would be



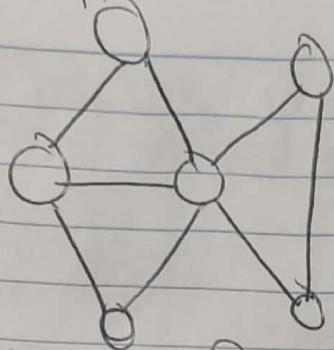
Given an instance  $G_1$  graph of  $n-5$  colouring problem, I will create an instance  $H$  of  $n-5$  colouring

Algorithms:-

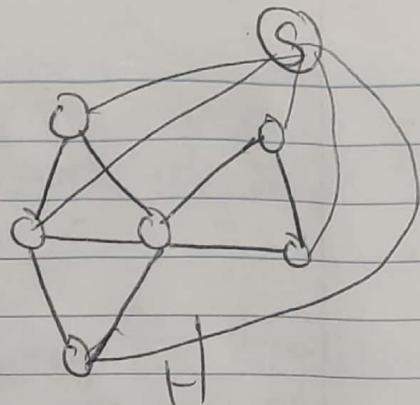
Step 1:- I would take a copy of  $G_1$  and add a new vertex  $s$ .

Step 2:- I would add the edges  $s$  to all other vertices to create  $H$

bipartite



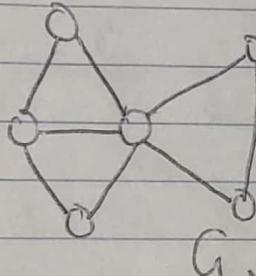
transfer - 1



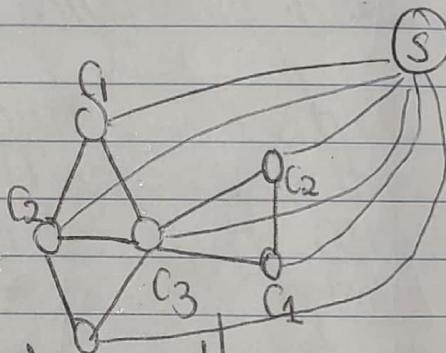
~~Equivalence~~  $G$

If there is a colouring of  $n-5$   $G$ , I can find a  $n-4$  colouring of  $H$  in poly time:

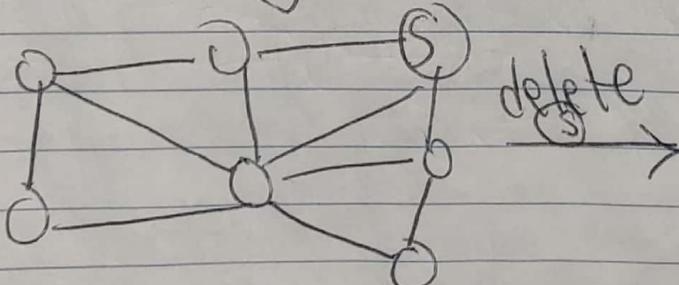
- Would take the given  $n-4$  colouring and add the  $n-5$  colouring to  $s$ .



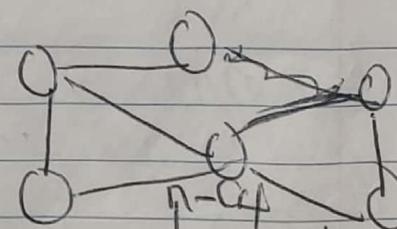
From  $n-4$  colouring  
to  $n-5$  colouring



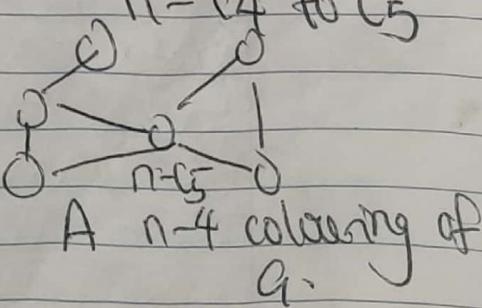
I can find  $n-5$  colouring of  $H$  in poly time if there is a colouring of  $n-4$  colouring of  $H$ .



delete



would rename  
 $n-4$  to  $C_5$



A  $n-4$  colouring of  
 $G$ .

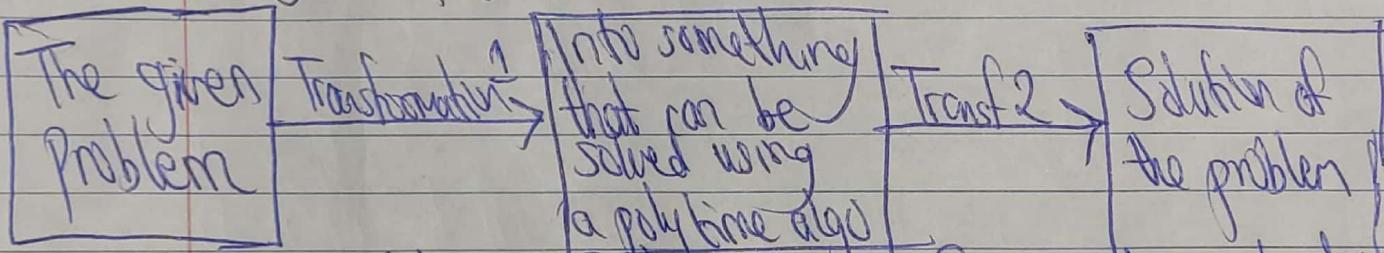
③

Let  $G$  be a graph of  $n$  vertices representing a set of gamers. There is an edge between two nodes if the corresponding gamers are friends. You want to partition the gamers into two disjoint groups such that no two gamers in the same group are friends.

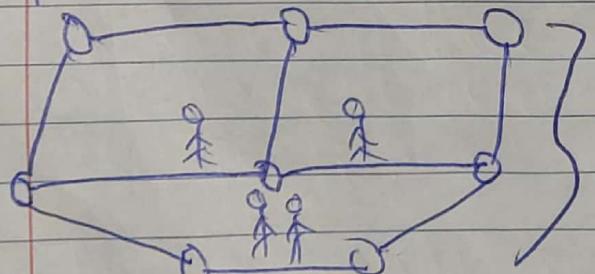
Solution

The problem is in P if there is a polynomial time algorithm for it.

I would prove the problem is in P by designing an algorithm and showing the time complexity and using a poly time algorithm as a black box to solve the problem.



This problem of the gamers,  $G$  can be solved using ~~bipartite~~. Would assume the gamers to be bipartite



This is not a correct solution because there are two gamers in the same group.

- Would use DFS

I → Using DFS, I would choose any random vertex and then set the value to one. And if there is another vertex in the DFS, we will have two options - either the vertex color is not 1 and we are going to set it 0 and then begin a DFS on that vertex

or the vertex value is 1 will then return False

Step II: - After the DFS is complete and we couldn't find any values that have the same vertex as the DFS has, will then return True

Partition the games, would assume the games to be a set of games where the subset A and B such that  $A \cup B = S$ ,  $A \cap B = \emptyset$

$$\sum_{a \in A} a = \sum_{b \in B} b$$

This problem can be solved using P. The given problem is in complexity class P.

And the running time of the problem is  $\underline{\mathcal{O}(v + e)}$  to be in P

(4) You are given a graph  $G$ , and the problem is to test whether there is a cycle of length at most 1000 or not.

### Solution

I can prove this problem by using the Hamiltonian Cycle Problem as in NP because it visits every vertex once.

Yes. Because if you give me a cycle and claim to be a Hamiltonian cycle, then I can take the following steps to verify in polynomial time:

Step 1: - I can count the sum of vertices on the path. If the cycle is a cuboid, I would check there is less than or exactly 3 vertices in the cycle/graph. Then the problem would still be in NP, because it is not a correct solution and is unlikely that we could find an effective algorithm.

Step 2: - I would check whether any vertex is repeated in the cycle  
- If repeated then the solution is incorrect

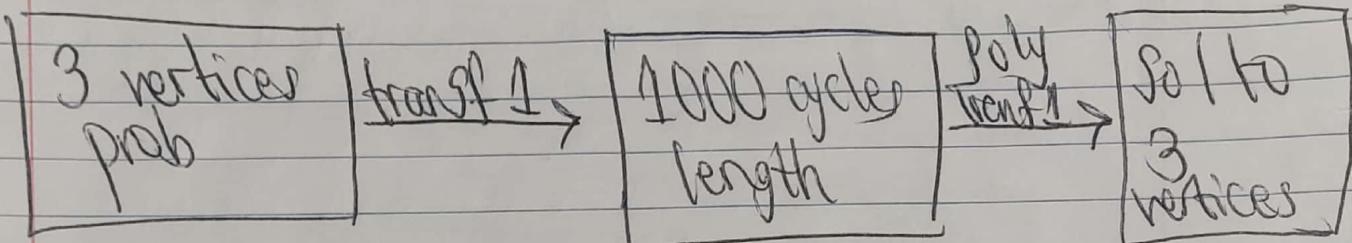
Step 3: - I would check if every pair of consecutive vertices on the path/cycle is connected by an edge - if not, then there is not a valid solution.  
Or you could solve the problem by using DFS; by checking the vertex ~~if visited~~ if yes, I would then calculate the cycle.  
Step 1-3 can be checked in polynomial time.  
Therefore, the Hamiltonian cycle problem is in NP.

NP

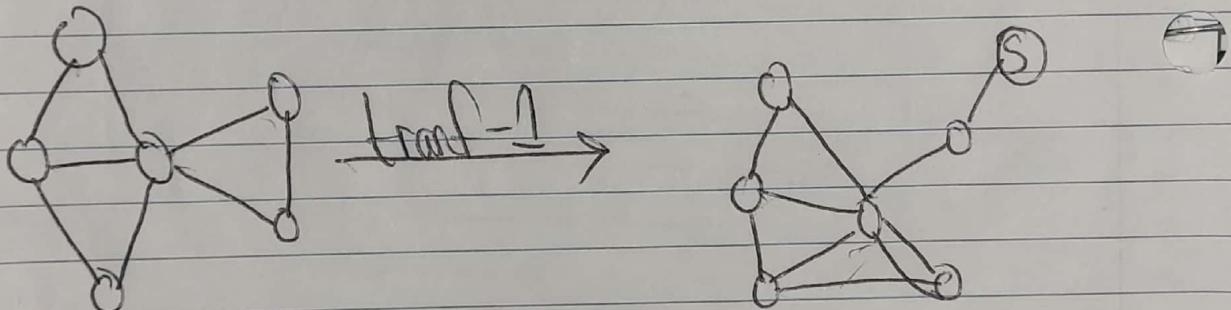
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## Formal Proof

I would try to prove that the cycle of length 15 is NP-hard.  
Would assume someone had already proved the cycle to be in a cubic plane set of three vertices is NP-hard.

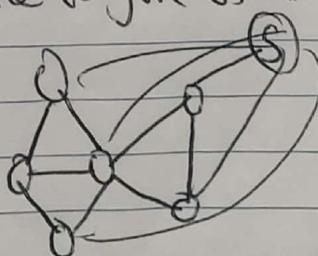
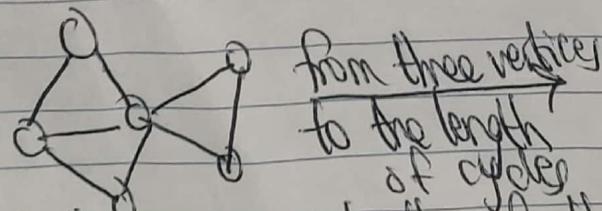


Transf 1:- Would give an instance of the Hamiltonian cycle problem as in NP. Would create an instance of H to be the 1000 cycles at most or not.



## Transf 2 (Equivalence)

If there is a cubic plane of G, then I can find the length of the cycles of H in a poly time - take the vertices and add the length of the cycle to S



If there is a length of the cycles, I can find the cubic vertices of G in poly time  
delete to the length of the cycle

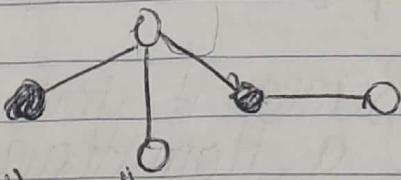
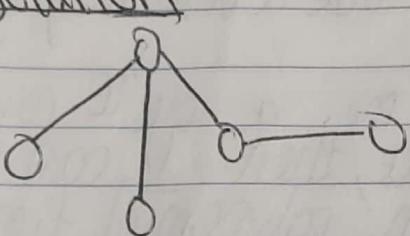
5.

### Problem (Bottleneck Path)

Input:- An edge-weighted undirected graph  $G$  and an integer  $K$ .

Question:- Does there exist a path such that the sum of the edge weights is at least  $K$

Solution



Here there is an integer  $K$ , if  $\exists$  a path that exists possible in the path

Graph  $G = (V, E)$  and an integer  $K$

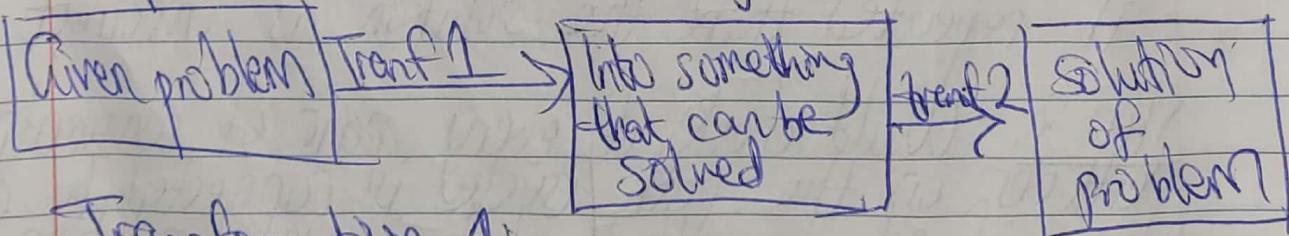
Step 1:- Show that the problem is in NP

Step 2:- Show that the problem is NP-hard

The first step can be done by showing a given solution can be verified in polynomial time

Step 2:- can be done by reducing a problem

Graph  $G = (V, E)$  and integer  $K$



Transformation 1:-

Given an instance  $G$  of IS (Independent set) problem, I will create an instance  $H$  of the bottleneck path problem

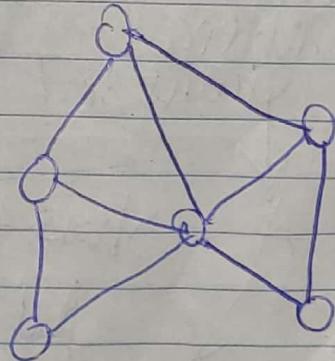
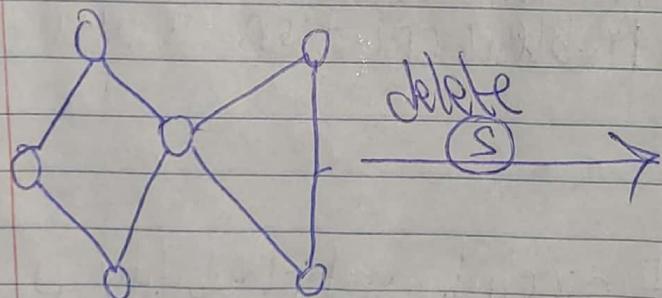
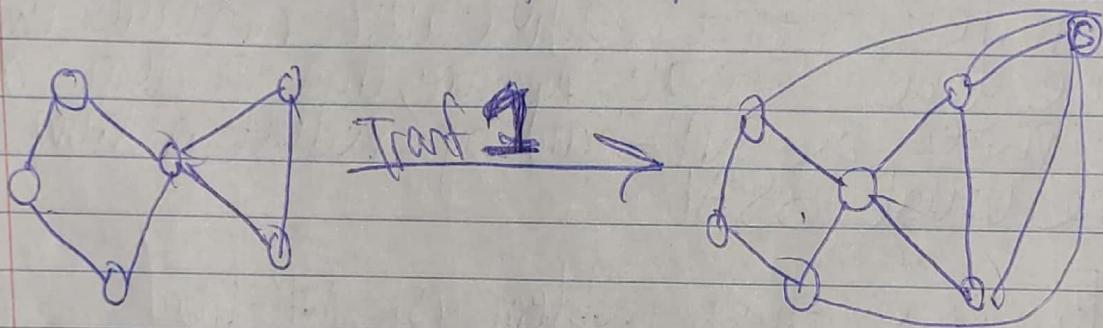
Step:- I would add the weight of  $G$  to the problem and it would become  $H$  of the instance

## Transformation 2:

trans-2

→ If there is IS of  $G_1$  if independent set of  $G_1$ , then I would find  $f_1$  in the polynomial algorithm time by adding the weights.  
Delete  $\{S\}$  delete the weight

and then for each pair of vertices in the independent set will then compute the sum of the edge weights in the paths between both pairs.  
∴ the Bottleneck Path Problem is NP-hard



+ the bottleneck problem  
edge weighted  
undirected graph  $G_7$

⑥

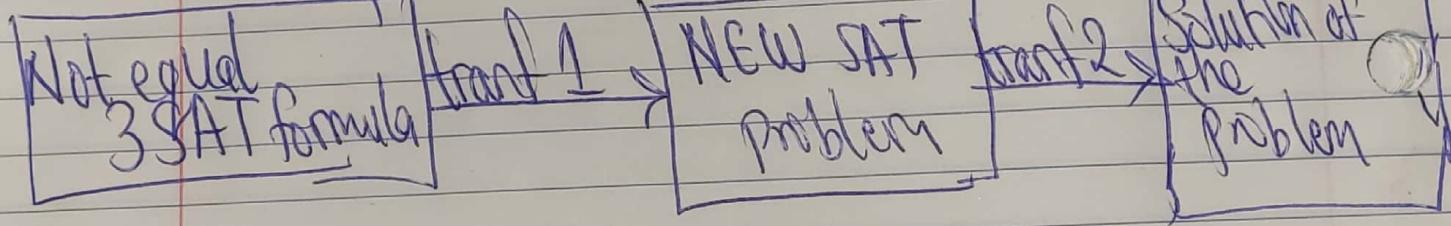
Problem (NEW-SAT)

Input: You are given a 3-SAT formula; A true value is considered as (+1) and a false value is considered (-1).

Question: Does there exist a truth-value assignment for each variable such that the sum of the three variables of each clause is between -1 and 1?

Solution

To prove this problem is NP-hard we would take NP-hard problem and then reduce it to a problem.



3-SAT

$$\text{Formula} = (v_1 \vee v_2 \vee \bar{v}_3) \wedge (\bar{v}_2 \vee \bar{v}_3 \vee \bar{v}_7) \wedge \dots \\ (v_1 \vee \bar{v}_2 \vee v_3) \wedge (\bar{v}_2 \vee v_1 \vee v_4) \wedge (v_1 \vee \bar{v}_4 \vee v_1)$$

As per 3-SAT

|          |           |          |           |          |          |           |          |           |           |
|----------|-----------|----------|-----------|----------|----------|-----------|----------|-----------|-----------|
| <u>1</u> | <u>-1</u> | <u>1</u> | <u>-1</u> | <u>1</u> | <u>1</u> | <u>-1</u> | <u>1</u> | <u>-1</u> | <u>-1</u> |
|----------|-----------|----------|-----------|----------|----------|-----------|----------|-----------|-----------|

-1

the 3SAT problem is going to be NP and that's because of the CNF formula checks whether the solution satisfies the problem

Transf 2:-

Would then deduce/reduce the problem.  
We are going to reduce the problem by NotAllEqual3SAT.

Given, the instance of NotAllEqual3SAT we will describe the New Sat so that the solution agree to the problem P.

$$P = (v_1 \vee v_2 \vee v_3) \wedge (\bar{v}_2 \vee v_1 \vee v_3) \wedge (v_1 \vee \bar{v}_2 \vee \bar{v}_3) \quad \begin{matrix} v & v & v \\ 1 & 0 & 1 \end{matrix} \quad \begin{matrix} v & v & v \\ 0 & 1 & 1 \end{matrix} \quad \begin{matrix} v & v & v \\ 1 & 1 & 0 \end{matrix} \quad \begin{matrix} v & v & v \\ 0 & 0 & 0 \end{matrix}$$

~~So for each clause we would change the inverse of the variable from 0 to -1.~~  
So for each clause we would change the inverse of the variable from 0 to -1. for P would give at least one negated variable and then the output is going to be between -1 and 1.

$$P' = (v_1 \vee v_2 \vee v_3) \wedge (v_1 \vee \bar{v}_2 \vee v_3) \wedge (v_1 \vee \bar{v}_2 \vee \bar{v}_3) \wedge (v_1 \vee \bar{v}_2 \vee \bar{v}_3) \quad \begin{matrix} v & v & v \\ 1 & -1 & 1 \end{matrix} \quad \begin{matrix} v & v & v \\ -1 & 1 & 1 \end{matrix} \quad \begin{matrix} v & v & v \\ 1 & -1 & 1 \end{matrix} \quad \begin{matrix} v & v & v \\ 1 & -1 & -1 \end{matrix}$$

IF  $P'$  has a solution set then P has a solution set.  
We are going to change the negative values from -1 to 0 and that way, we are going to get our P

$$P = (v_1 \vee v_2 \vee v_3) \wedge (v_2 \vee v_1 \vee v_3) \wedge (v_1 \vee v_2 \vee v_3) \wedge (v_1 \vee v_2 \vee v_3) \quad \begin{matrix} v & v & v \\ 1 & 0 & 1 \end{matrix} \quad \begin{matrix} v & v & v \\ 0 & 1 & 1 \end{matrix} \quad \begin{matrix} v & v & v \\ 0 & 0 & 1 \end{matrix} \quad \begin{matrix} v & v & v \\ 0 & 0 & 0 \end{matrix}$$

and is not equal 3SAT

So therefore, the NEW SAT problem is NP-complete if not equal.

1.  $1 + (-1) + 1 = 1$  and is not in range

2.  $1 + (-1) - 1 = -1$

the both front 1 & 2 are polytime then the NEW SAT is polytime  
then not equal 3SAT can be solved in polytime many of NP problems