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Name: Samit Dubey Roll no.: 22 Div: A

Batch: A1

```
Program:
#include<stdio.h>
#define INFINITY 9999
#define MAX 10
void dijkstra(int G[MAX][MAX],int n,int startnode);
int main()
  int G[MAX][MAX],i,j,n,u;
  printf("Enter no. of vertices:");
  scanf("%d",&n);
  printf("\nEnter the adjacency matrix:\n");
  for(i=0;i< n;i++)
    for(j=0;j< n;j++)
       scanf("%d",&G[i][j]);
  printf("\nEnter the starting node:");
  scanf("%d",&u);
  dijkstra(G,n,u);
  return 0;
}
void dijkstra(int G[MAX][MAX],int n,int startnode)
{
  int cost[MAX][MAX],distance[MAX],pred[MAX];
  int visited[MAX],count,mindistance,nextnode,i,j;
  //pred[] stores the predecessor of each node
  //count gives the number of nodes seen so far
  //create the cost matrix
  for(i=0;i< n;i++)
    for(j=0;j< n;j++)
       if(G[i][j]==0)
         cost[i][j]=INFINITY;
         cost[i][j]=G[i][j];
```

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Name: Samit Dubey Roll no.: 22 Div: A Batch: A1 //initialize pred[],distance[] and visited[] for(i=0;i<n;i++) distance[i]=cost[startnode][i]; pred[i]=startnode; visited[i]=0; } distance[startnode]=0; visited[startnode]=1; count=1; while(count<n-1) mindistance=INFINITY; //nextnode gives the node at minimum distance for(i=0;i< n;i++)if(distance[i]<mindistance&&!visited[i]) mindistance=distance[i]; nextnode=i; } //check if a better path exists through nextnode visited[nextnode]=1; for(i=0;i< n;i++)if(!visited[i]) if(mindistance+cost[nextnode][i]<distance[i]) distance[i]=mindistance+cost[nextnode][i]; pred[i]=nextnode; count++; //print the path and distance of each node for(i=0;i< n;i++)if(i!=startnode) printf("\nDistance of node%d=%d",i,distance[i]); printf("\nPath=%d",i);

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```
j=i;
    do
    {
        j=pred[j];
        printf("<-%d",j);
    } while(j!=startnode);
}</pre>
```

Output:

Enter no. of vertices:4

Enter the adjacency matrix:

05010

5030

0301

10010

Enter the starting node:0

Distance of node1=5

 $Path{=}1{<}{-}0$

Distance of node2=8

Path=2<-1<-0

Distance of node3=9

Path=3<-2<-1<-0