

DOCUMENTATION

2D Mixed–element mesh generator

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Abstract

This document will show you how to obtain mixed–elements meshes with the provided code. Two main alternatives are explained here. The first will show you how to use the code as a standalone program. The second will show you how to bundle your own code with the mixed–element mesh generator. In both cases, mixed–element are employed to manage transitions between fine and coarse regions and at the boundary of the domain. All the remaining regions will be meshed with structured regular quadrangles.

1 Data Structures and initialisation

Quadrant, QuadEdge, Polyline Final resulting Mesh

This mesh generator will allow you to create a mixed–element mesh starting from a boundary 2D mesh (polyline) composed of edges (Fig. 1(a)). Let this input surface mesh be \mathcal{S} . Two constraints must be fulfilled by \mathcal{S} : it must be unfolded (no self–intersection), and the normal of the edges must be pointing outside.

The algorithm will use \mathcal{S} for two purposes: to find out if a point is inside or outside the domain and to project a point onto \mathcal{S} . Therefore, if you have two different meshes representing the exact same domain, you should use the one with less edges. The algorithm will compute faster the output mesh.

The first step of the algorithm is to compute the Bounding box (Bbox) of \mathcal{S} . This Bbox will not necessarily be a perfect square. Therefore, an algorithm will be employed to automatically compute a set of squares containing \mathcal{S} (Fig. 1(b)).

Now it is possible to introduce the other important input: the Refinement Level (rl). This mesh generator is based on the Quadtree technique introduced in [1]. This technique recursively split a Quadrant in a finite number of equivalent sons. For instance if the Quadrant is a square, to refine it one level means that it will be replaced by 4 new QUadrants. All of them will be sons of the replaced Quadrant in the Quadtree structure. By allowing the use of quadrants with cut corners, this modeling technique overcomes some of the drawbacks of standard Quadtree encoding for finite element mesh generation [2]. In our case, Quadrants will continue to refine until a maximum provided level is reached. Quadrants lying completely outside \mathcal{S} will be removed.

1.1 Polyline as Input boundary

A **Polyline** is composed of (Fig. 1(a)):

- a vector of **3DPoint**, with coordinates, that are all lying inside the **BoundingBox** of the Polyline,
- and their associated angle. If the angle is not lying in the range [$MinAngle = 175, MaxAngle = 185$], then it's considered as a sharp point, and called a **Feature** in the remaining.
- a vector of **PolyEdge**, each one defined by the indexes of the extremity' nodes, and a normal. By convention, the normal is not normed and is pointing out the Input. For an oriented edge (i, j) , its

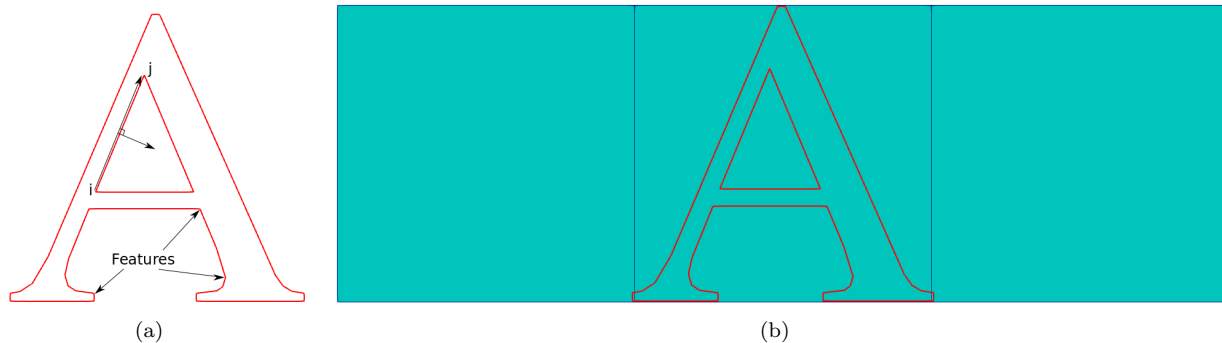


Figure 1: (a) An example of complex polyline with holes and sharp features. This corresponds to the Input to be meshed (source: a.poly) . (b) The embedding (poorly defined...) initial quadrants

right side will be outside and its left side inside. Thus, the Input must be defined by closed sets of connecting edges with counter-clockwise orientation. This way, holes may be simply created.

The format for Input file might be either `.poly` as described on the `Triangle.1.6` website; find an example here: `unit_square.poly`. It could also be defined as `.mdl` file, see `unit_square.mdl`:

1.2 Quadrant as support of surface mesh

The other important structure is the **Quadrant**:

- is composed of a *pointindex*, vector of 4 corner indices in a vector of **MeshPoint**: Note here that **MeshPoint** is embedding a previously seen **3DPoint**, as well as some information describing its state. More details below.
- When the Quadrant is subdivided into non quadrant elements (in *Transitions* for example), it contains a vector of *sub_elements*, each one described by a vector of indices as presented right above.
- It also contains a list of intersecting **PolyEdges**, and intersecting **Features**. These informations are useful to speed up the inside/outside discrimination for the Quadrant or to better handle the boundary and surface elements, for example.
- and some additional data, for processing purpose that will be described later.

Along with the Quadrant, comes the **QuadEdge**:

- defined by 3 indices, the 2 extremities and potential *midpoint* when this edge is split.

And finally, the **MeshPoint**:

- that is embedding a **3DPoint**, as coordinates of the Quadrant's corners, referenced as indices.
- **MeshPoint** are conversely connected to Quadrant by an index map of *elements*, referencing all the Quadrants having this point as corner.
- it also is the support for some crucial processing information on its *state*, merged in a single byte: the point is **inside**, has been **projected**, is representing a **feature**, has been previously **checked**, etc...

These three structures will be used together along with the Polyline by the **Mesher**, that will construct them gradually:

- a vector of **MeshPoint**,
- a vector of **Quadrant**,
- a set of **QuadEdge**. Note that this kind of structure is costly (quasi 30% of the whole computation time), as insertion is done in a sorted container, but it guarantees uniqueness of the element, and reasonably fast access. By the way, it might not be exactly dapted to parallelism...
- It also contains a list of **Refinement Regions**, which usage will be presented later on.

2 Main steps of the method

mixed-elements mesh generation, describe here the main steps of the method

2.1 A quadtree-based method

show different steps of the method:

Algorithm 1: Generation process

Result: A mixed-elements mesh

```

1 foreach Quadrant do
    repeat
2     Subdivide Quadrant;
        foreach new Sub-Quadrant do
            if Intersects Input or Is Inside then
                | Insert Sub-Quadrant
            end
        end
    until desired Refinement Level;
end
3 Create balanced quadtree;
4 Apply Transition Patterns;
```

1. subdivision, quad + ROI + off-domain quad removing
2. balanced : the resulting mesh is not balanced if one of the edges of a Quadrant is subdivided twice. In this case, subdivide the Quadrant as in Algorithm 1 step 2. And repeat until the mesh is balanced.
3. transition patterns (OMP)

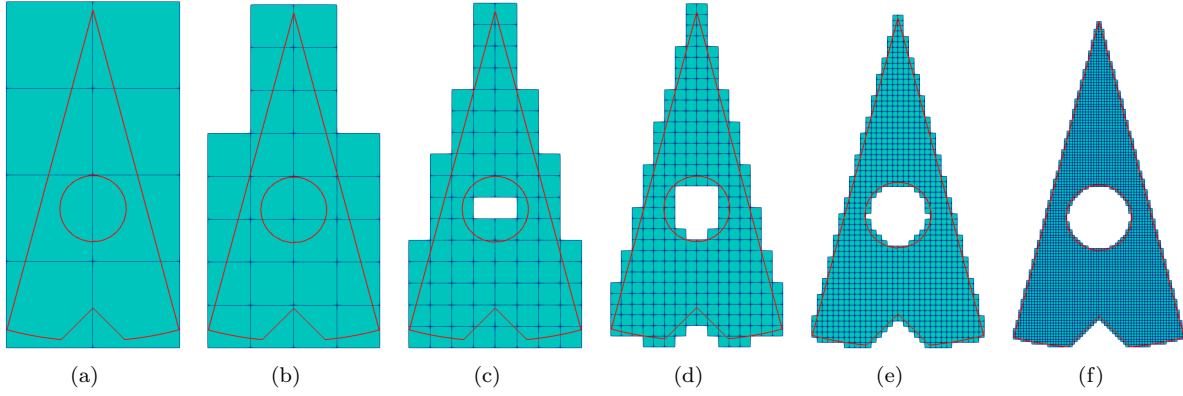


Figure 2: Effect of the refinement level applied on the complete structure (`-a` switch), (1 to 6)

2.2 Refinement, Balancing and Transition steps

3 Fitting quadrants to Input Surface

Algorithm 2: Generation process and Input surface fitting

Result: A mixed-elements mesh

```

/* Preprocess: handle boundary */
/* Generate quadtree */
1 foreach Quadrant do
    repeat
2         Subdivide Quadrant;
        foreach new Sub-Quadrant do
            if Intersects Input or Is Inside then
                Insert Sub-Quadrant
            end
        end
    until desired Refinement Level;
end
3 Create balanced quadtree;
4 Apply Transition Patterns;
/* Input surface fitting */
5 Detect Features in Input;
Project Close to Boundary;
Remove on Input Surface;
Shrink to Boundary;
6 Apply Surface Patterns;

```

3.1 Boundary and sharp features handling

preprocess

The first step to

// test1: if nb Features ≥ 2 // first condition is optimization if NbFeatures has been already computed //
test2: if distFProjectionFeature \geq distMax for each node // done: compute distMax before... // test3: if
the number of intersection of the Polyline and Quadrant edge ≥ 3

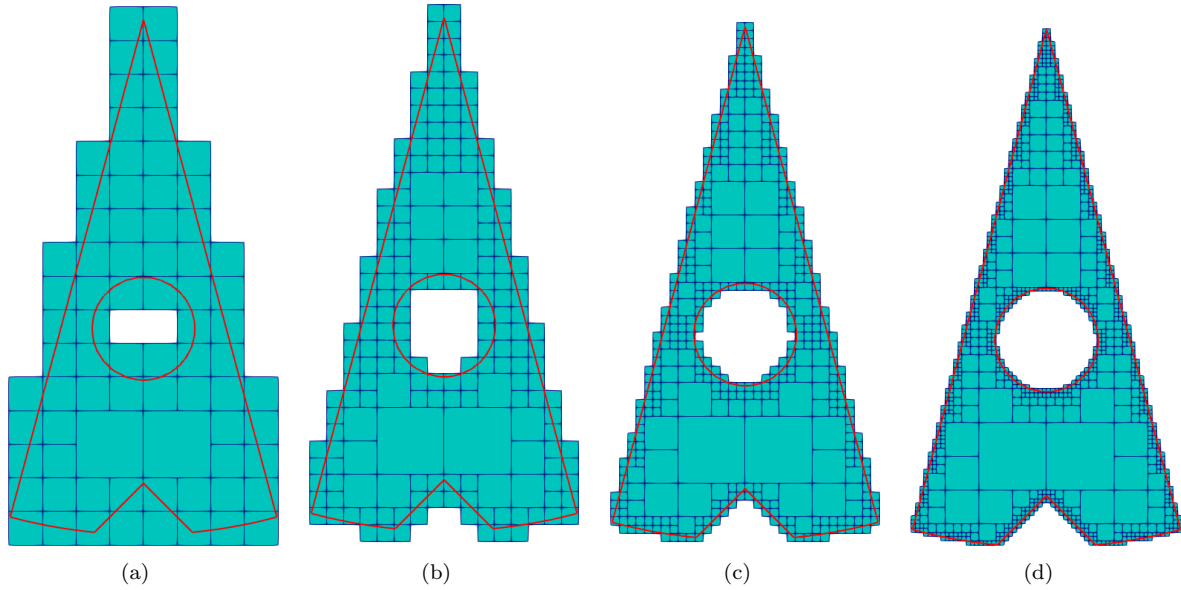


Figure 3: Effect of combined refinement levels, with level 2 applied on the complete structure (**-a** switch), and incremental refinement (3 to 6) only applied on surface quadrants (**-s** switch).

3.2 Generating first quadrants over boundary prepared mesh

3.3 Handling Input surface

4 Remeshing

Algorithm 3: Refinement process

Result: A refined mixed-elements mesh

foreach *Element to refine* **do**

 Identify containing Quadrant;

 Subdivide Quadrant;

foreach *Sub-quadrant* **do**

if *Intersect input or Is In* **then**

 Insert Sub-Quadrant

end

end

end

Goto *Algorithm 1, step 3*

identify which Quad contains the element, information from file

subdivide Quad + goto subsection balanced

(local remeshing? neighbourhood??)

5 Installing

In order to install this application you will need a Unix-based system, a **c++** compiler and **cmake**. You should do the following:

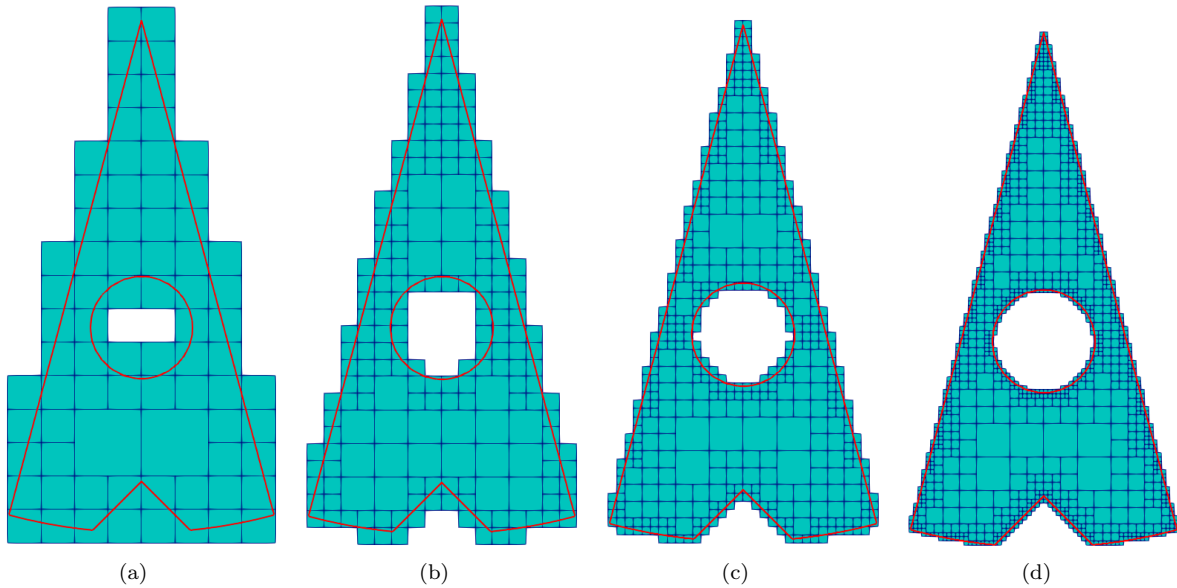


Figure 4: After the balancing step, note that in the first case, nothing is to be done.

5.1 Create an account on github.com

- go to github.com, then 'Signup and Pricing' \Rightarrow 'Free for open source' \Rightarrow 'Create a free account'
- choose Username/Email/Password and it's done
- you can also update your account settings (website, avatar...)

5.2 Git Fork MixedQuadTree

Let's fork the initial MEPP repository. So, once you're logged in on github

- go to <https://github.com/jaillet/MixedQuadTree/>
- click on the 'Fork' button
- once the fork is finished, you'll have your own copy of MixedQuadTree with the following path:
<https://github.com/yourUsername/MixedQuadTree>
- at this URL, you're able to browse the sources, see the commit log, report issues...

5.3 Compiling

```
$ git clone /https://github.com/jaillet/MixedQuadTree.git
$ cd MixedQuadTree/
$ git checkout branch develop
$ mkdir build ; cd build
$ cmake ../src -D_CMAKE_BUILD_TYPE=Debug (or Release) // Uppercase is important
$ cmake .
$ make -j#nproc
```

This has been tested on Linux and Mac without any known error nor warning.

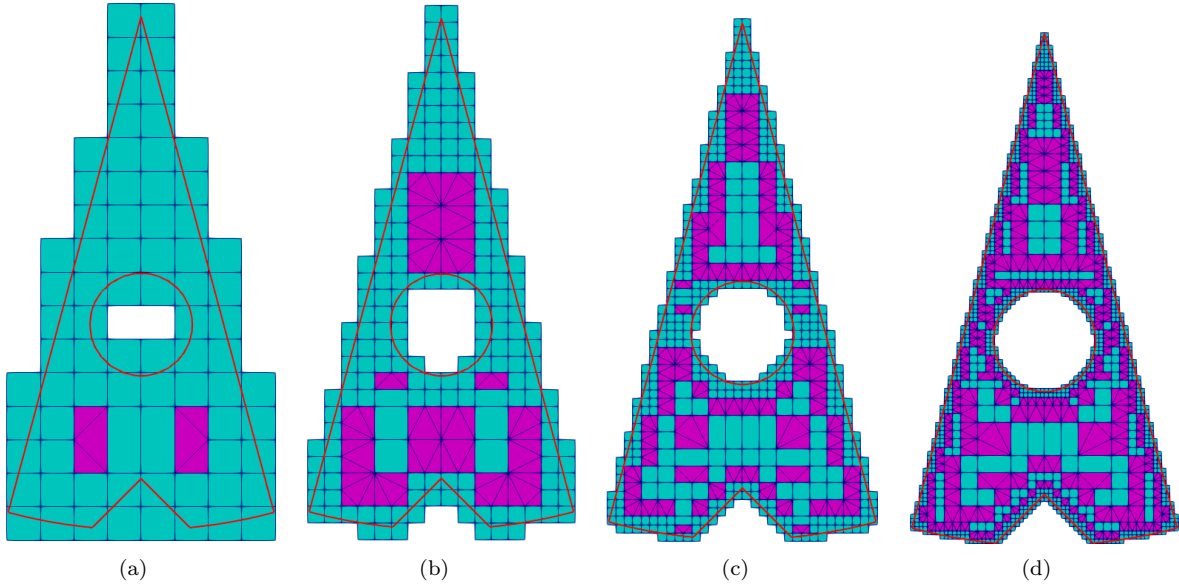


Figure 5: After the transition step, note that the more difference between levels, the more transition patterns are used...

5.4 Git usage

At this point, you can edit and commit files using the git workflow
but only push to your own fork of MixedQuadTree (origin) !!!

The merge between the original repository is done by ANOTHER DEVELOPER after a '**pull request**'. To make a 'pull request', go to <https://github.com/yourUsername/MixedQuadTree>, click on 'Pull Request'. Then, choose the two branches you would like to merge (master in *jaillet* and yourbranch in origin), write your comments and click on 'Send Pull Request'.

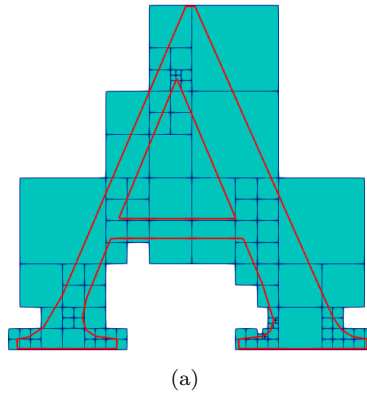


Figure 6: After boundary handling.

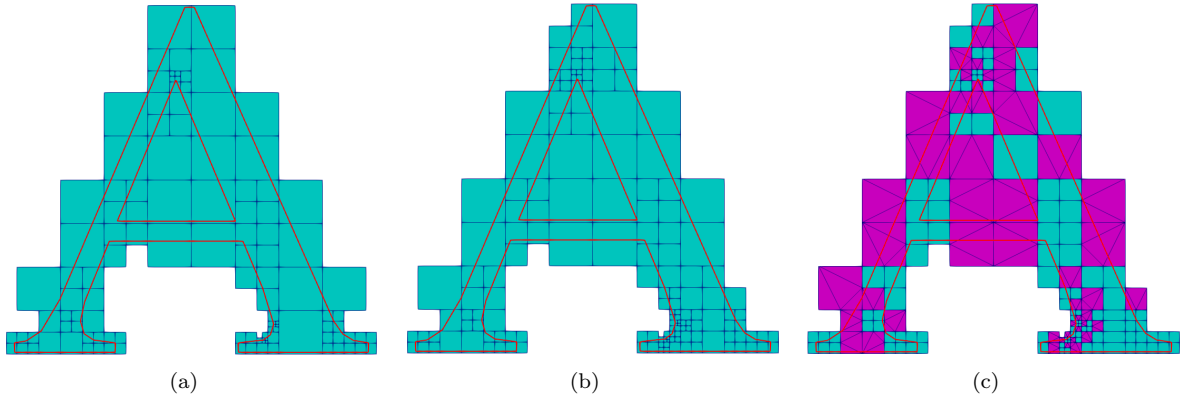


Figure 7: After refinement, balancing and transition steps, level 3.

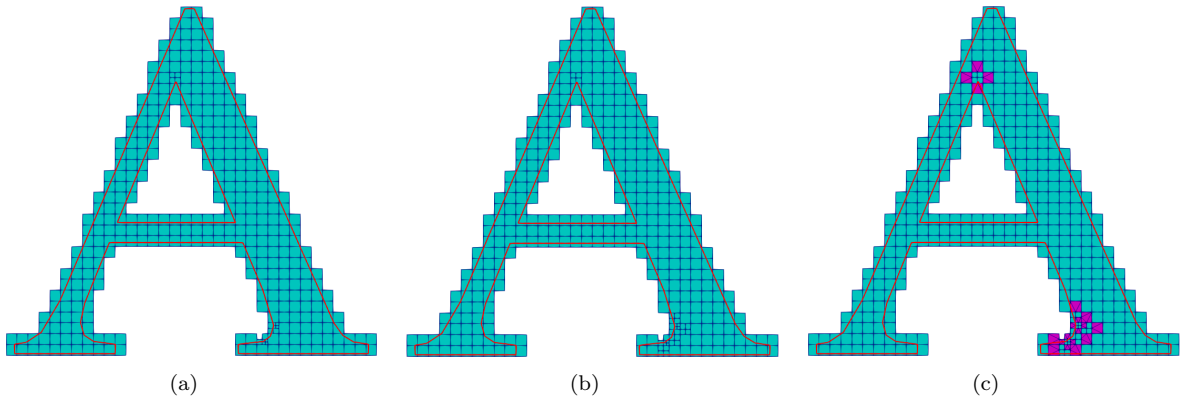


Figure 8: After refinement, balancing and transition steps, level 5.

Acknowledgement

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References

- [1] R. A. Finkel and J. L. Bentley. Quad trees a data structure for retrieval on composite keys. *Acta Inf.*, 4(1):1–9, March 1974.
- [2] M. Yerry and M. Shephard. A modified quadtree approach to finite element mesh generation. *IEEE Computer Graphics and Applications*, 3:39–46, 01 1983.

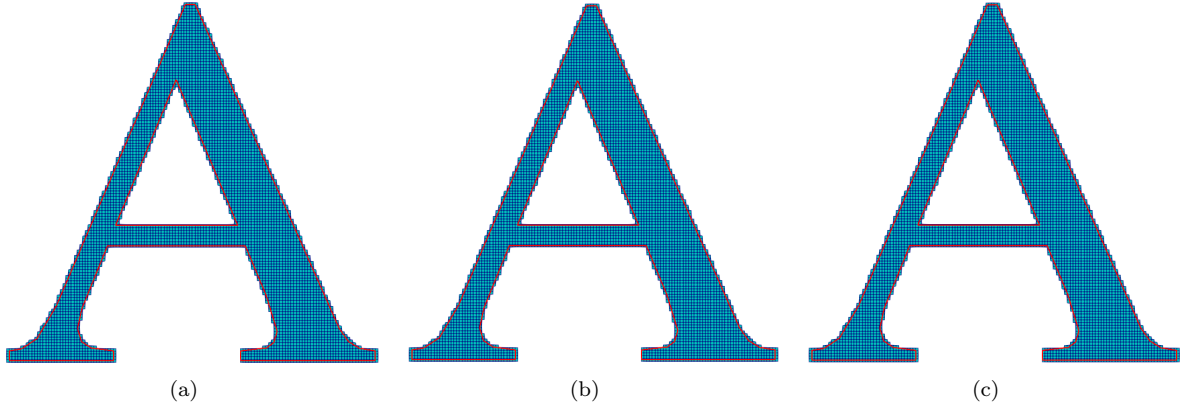


Figure 9: After refinement, balancing and transition steps, level 7.

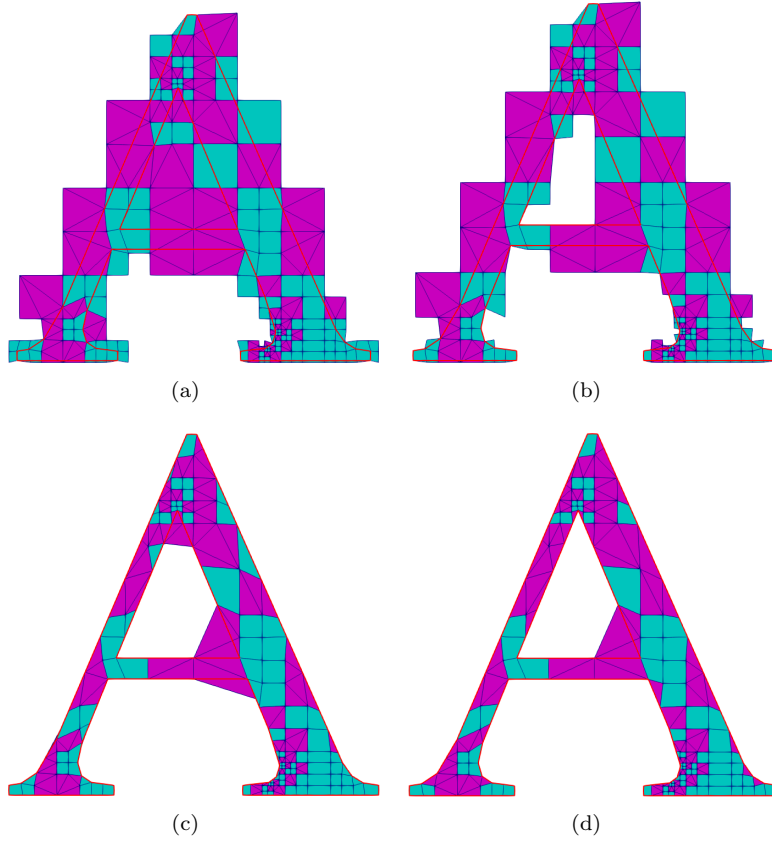


Figure 10: After projecting interior points close to boundary, , level 3.

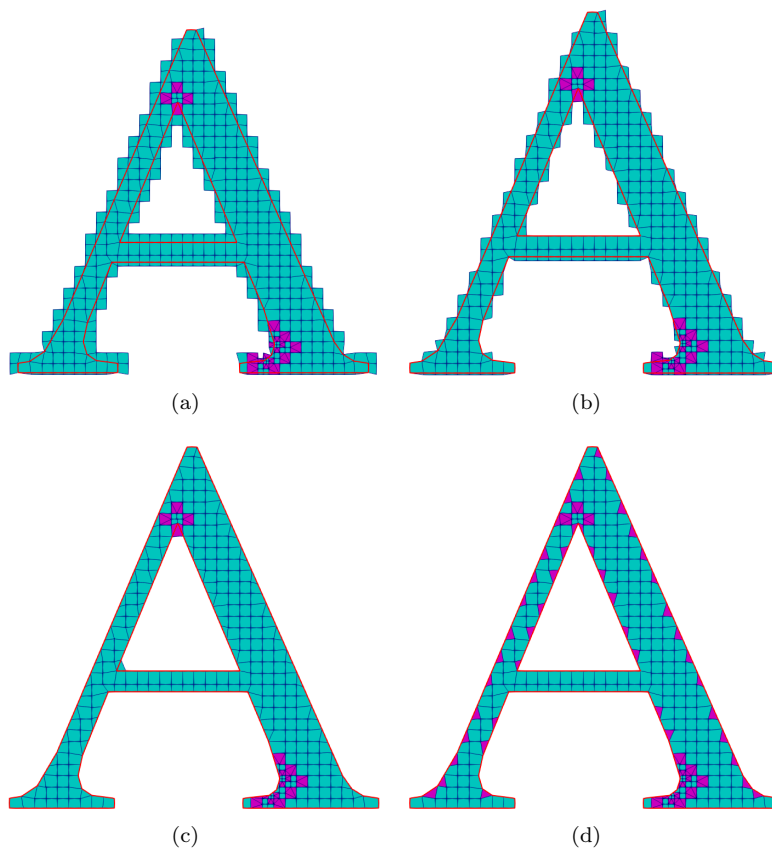


Figure 11: After projecting interior points close to boundary, level 5.

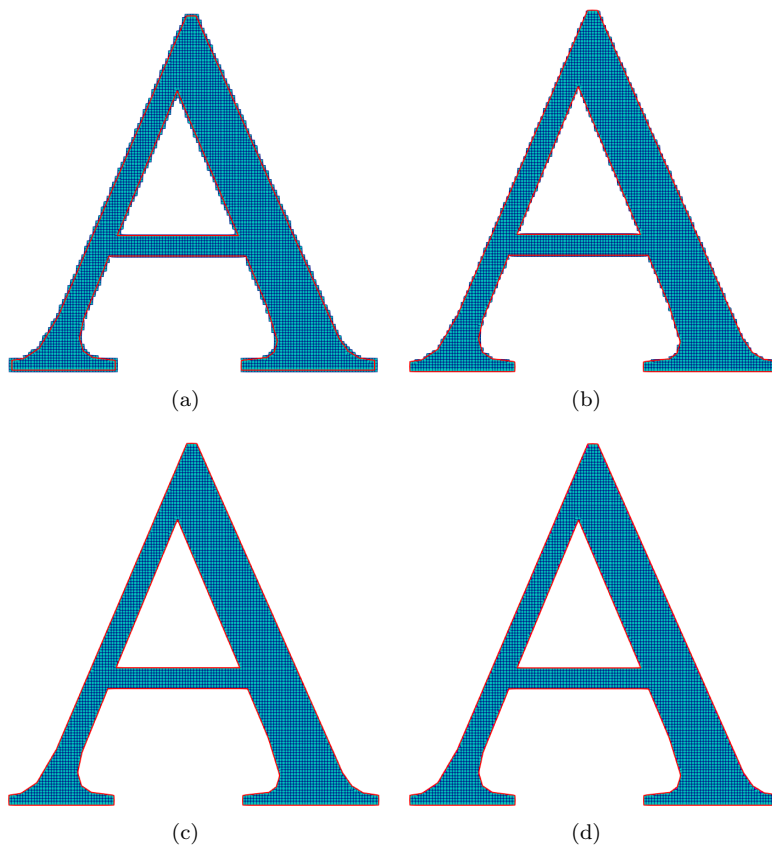


Figure 12: After projecting interior points close to boundary, level 7.