

# NMR - Nuclear Magnetic Resonance

Atomic nuclei have an intrinsic magnetic moment due to spin.

measure of "strength" of a magnetic dipole.

"Stern - Gerlach" Experiment  
~ 1920

<sup>1</sup>H <sup>nr. of protons</sup> Hydrogen

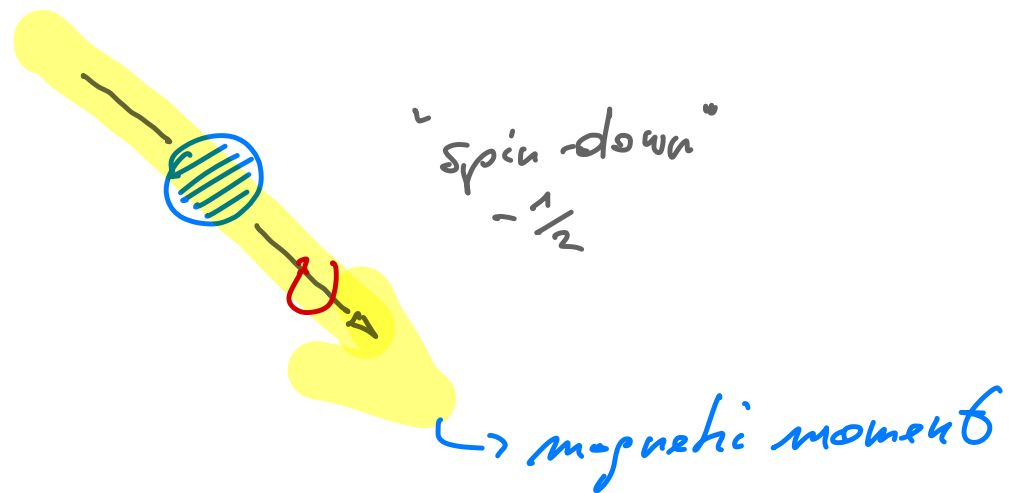
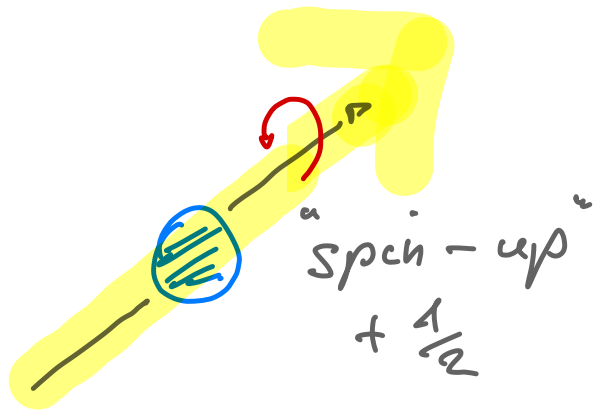
## Proton - spin

Spin is a quantum-mechanic property of elementary particles.  
=> intrinsic motion of angular momentum.  
(Drehimpuls)

As spin induces a magnetic moment, this allows particles to interact with an external magnetic field.

In case of an odd atomic number (e.g.  $^1\text{H}$ ), we have non-zero spin.

Quantum spin number of  $^1\text{H}$  is  $\pm \frac{1}{2}$ .



If placed in an external magnetic field, the protons experience torque.

$\Rightarrow$  this induces an angular momentum!

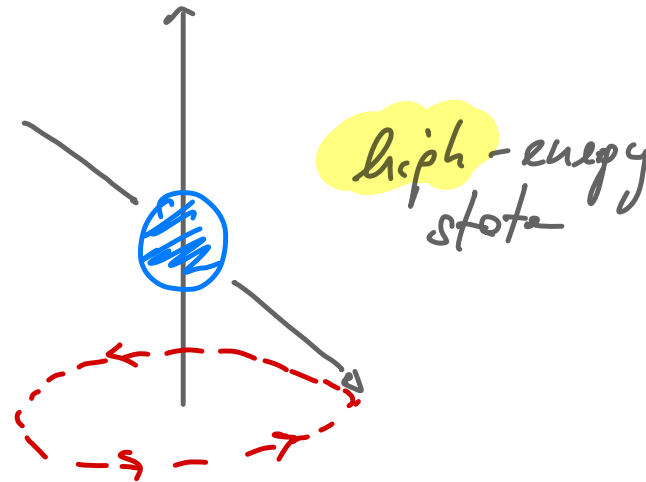
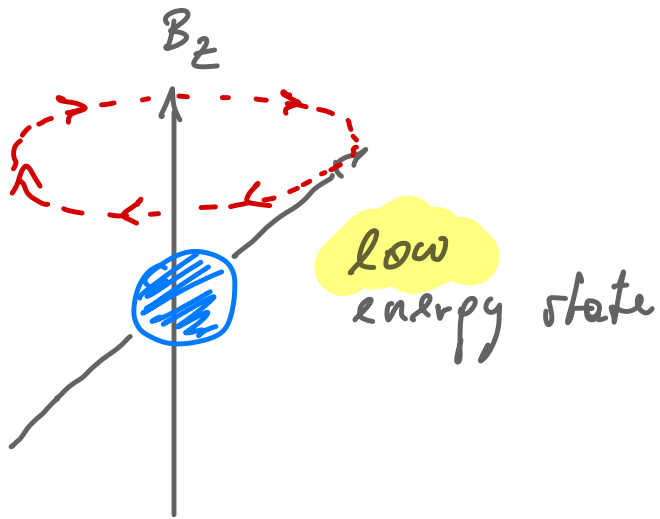
The protons start to "precess" at a specific frequency, called the LAMOR FREQUENCY.

In general

$$\tau = \mu \times B$$

$\tau$  torque       $\mu$  magnetic moment

$B$  magnetic flux density



When considering more than one proton (i.e., a bulk of protons), there is a slight surplus of those in low energy state.

⇒ This gives a slight magnetization (net magnetization) in the direction of the magnetic field!

We can get a measurement of the proton density from this net magnetization - BUT, it's hard to measure, as it is tiny relative to the strength of the external magnetic field!

In MRI, we will perturb the net magnetization in a direction orthogonal to the magnetic field!

Q: How? By inducing electromagnetic waves at exactly the LAMOR FREQUENCY → this will induce a torque on the magnetic moments. The system will be in a state of excitation!

Spin angular momentum ( $S$ )

$$|S| = \hbar \sqrt{Q \cdot (Q+1)} \quad Q = \frac{n}{2}$$

(for  $^1H$  we have  $n=1 \Rightarrow Q = \frac{1}{2}$ )

$$\left( \hbar = \frac{h}{2\pi} \right)$$

Associated magnetic moment ( $\mu$ )

$$\mu = \mu_B S$$

( $\mu_B$  Bohr magneton ratio)

In principle, we have  $(2Q+1)$  energy sublevels, i.e. for  $^1H$

$$2 \cdot \frac{1}{2} + 1 = 2$$

(Zeeman splitting)

Energy of nucleus :

$$E = - \langle \mu, \vec{B_0} \rangle \quad \left( \begin{smallmatrix} 0 \\ B_0 \end{smallmatrix} \right)$$

$\hookrightarrow$  magnetic moment

By convention,  $B_0$  points along the  $z$ -direction and the  $z$ -component of  $\mu$  is

$$\mu_z = \mu \cdot (\pm 1/2) \cdot h$$

$$E_z = -\mu_z \cdot B_0 = -\mu \cdot (\pm 1/2) \cdot h B_0$$

The two energy sublevels are

$$[1] \quad E_z^{(+1/2)} = -\mu \cdot \frac{1}{2} \cdot h B_0$$

$$[2] \quad E_z^{(-1/2)} = +\mu \cdot \frac{1}{2} \cdot h B_0$$

Diff. between energy levels is

$$\begin{aligned}\Delta E &= \mu \cdot \hbar B_0 \\ &= \mu \cdot \frac{h}{2\pi} B_0\end{aligned}$$

For the **torque** that the magnetic moment ( $\mu$ ) experiences, we have

$$\tau = \mu \times B_0 \quad (\mu = \gamma \cdot S)$$

Also,

$$\tau = \frac{d}{dt} S = \frac{1}{\gamma} \cdot \frac{d}{dt} \mu$$

↓  
spin angular momentum

$$\Rightarrow \frac{1}{\gamma} \cdot \frac{d}{dt} \mu = \mu \times B_0$$

$$\frac{d}{dt} \mu = \gamma \mu \times B_0$$

If we focus on the net magnetization ( $M$ ), we have

$$\frac{d}{dt} M = \frac{d}{dt} \sum_i \mu_i$$

$$= \sum_i \frac{d\mu_i}{dt} \quad \left( \text{using } \frac{d}{dt} \mu = \gamma \mu \times B_0 \right)$$

$$= \sum_i \gamma \cdot \mu_i \times B_0$$

$$= \gamma \cdot (M \times B_0)$$

$$\Rightarrow \frac{d}{dt} M = \gamma \cdot (M \times B_0)$$

$$\dot{M} = \gamma \cdot (M \times B_0)$$



Solving  $\dot{\vec{M}} = \gamma \cdot (\vec{M} \times \vec{B}_0)$ , will give us the motion eq. of the net magnetization vector  $\vec{M}$ .

First, we set up a (time-dependent) rotation around the z-axis:

$$P_\omega(t) = \begin{pmatrix} \cos(\omega t) & \sin(\omega t) & 0 \\ -\sin(\omega t) & \cos(\omega t) & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

rotation angle

3x3 rotation matrix

Let  $\vec{M}_p = \vec{M}(0)$  be the initial state at time  $t=0$ , and

$$\vec{B}_0 = P_\omega(t) \cdot \vec{B}_0.$$

So, we have

$$M(t) = P_w(t) \cdot M_p$$

$$\dot{K} = v \cdot (K + B_0)$$

$$\Rightarrow \underline{\dot{K}} = v \cdot (\underline{K} + \underline{B_0}) = \underline{\dot{P}_w} M_p - v \cdot (\underline{P_w} M_p) \times (\underline{P_w} B_0)$$

Remark:  $P_w^T P_w = I$

$$\Rightarrow \dot{K} = v \cdot (K + B_0) = P_w \cdot \left( \overset{K(0)}{P_w^T \dot{P}_w} M_p - v M_p \times B_0 \right)$$

What is  $P_w^T \dot{P}_w$ ?

$$-w \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = A$$

$$\left( A^T = -w \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \right)$$

So  $A^T = -A \Rightarrow$  skew-symmetric matrix

So  $(P_w^T \dot{P}_w) M_p$  is a matrix-vector product with  $(P_w^T \dot{P}_w)$  skew-symmetric, hence we can write

$$\begin{aligned}
 P_w^T \dot{P}_w M_p &= -\omega e_z \times M_p & e_z &= \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \\
 &= \omega M_p \times e_z & & \text{(by anti-commutative?)} \\
 &= \frac{\omega M_p}{\|B_0\|} \times B_0 \\
 &= \frac{\omega}{\|B_0\|} M_p \times B_0
 \end{aligned}$$

Overall, we get

$$\begin{aligned}
 \ddot{r} - \nu \cdot (M \times B_0) &= P_w \cdot \left( \frac{\omega}{\|B_0\|} M_p \times B_0 - \nu \cdot M_p \times B_0 \right) \\
 &= \left( \frac{\omega}{\|B_0\|} - \nu \right) \cdot P_w \cdot (M_p \times B_0)
 \end{aligned}$$

$\vec{r}(t) = P_{\omega}(t) \vec{M}_p$  is a solution to  $\vec{r}' = \gamma \vec{M} \times \vec{B}_0$  if  
our model

$$\omega = \gamma \cdot \|\vec{B}_0\|$$

(i.e., LAROR FREQUENCY)

Hence, we have shown that the net magnetization vector  $(\vec{r})$  precesses around the axis (z-axis) of the  $\vec{B}_0$  field at frequency of  $\gamma \cdot \|\vec{B}_0\|$