Computer Vision

(VO, 911.908, Winter term 22/23)

Roland Kwitt

Department of Artificial Intelligence and Human Interfaces (AIHI)
University of Salzburg, Austria

Schedule for today

- Logistics
- Resources
- What is computer vision?
- Some typical computer vision problems

Logistics

- **E-Mail:** Roland [dot] Kwitt [at] plus [dot] ac [dot] at
- Course material: available online at http://rkwitt.org (→ Teaching)

Logistics

Grading

1 final exam at the end of the course (see course website for details)

Resources

PyTorch (most recent version v1.12.1)

https://pytorch.org/

scikit-learn (Python)

http://scikit-learn.org/stable/

scikit-image (Python)

http://scikit-image.org

Resources

"Deep Learning"

Goodfellow, Bengio, Courville http://www.deeplearningbook.org/

Please check the course website for updates on relevant research papers.

Resources

Throughout the lecture, we will primarily cover "modern" approaches to computer vision, using (deep) neural networks.

However, I still do want to mention a "classic" vision book which is definitely worth reading.

"Computer Vision: Algorithms and Applications"

R., Szeliski, 2010

http://szeliski.org/Book/







Courtesy of Szeliski

(Luiz Gomez Photos)

The human visual system (HVS) is remarkably good at so many tasks, e.g.,

- detecting people & object's
- perceiving translucency, shape, color (see figure on the left),
- counting people & vehicles (see middle figure)
- recognizing scenes, etc.

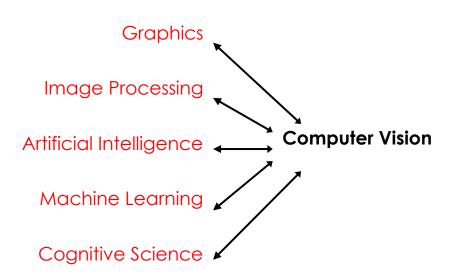
Remarkable fact:

A substantial fraction of the macaque's total cortical area is devoted to vision (approx. 15% according to [Hubel, "Eye, Brain and Vision"])

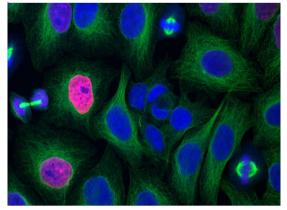
We want to build systems for automatic understanding of images/videos.

This includes, but is not limited to,

- 1) inferring properties of the 3D world (measurement)
- 2) enabling recognition of objects, people, scenes, etc. (perception)
- 3) mining, searching and interacting with visual data (search / organization)



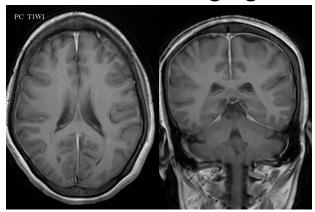
Bio-Imaging



Surveillance



Medical Imaging



Google

Autonomous Cars



Mapping



Robotics

Overview of the field

Conferences

Computer Vision

- Computer Vision and Pattern Recognition (CVPR)
- International Conference on Computer Vision (ICCV)
- European Conference on Computer Vision (ECCV)
- British Machine Vision Conference (BMVC)

Machine learning

- Neural Information Processing Systems (NIPS)
- International Conference on Machine Learning (ICML)
- International Conference on Learning Representations (ICLR)

Overview of the field

Some metrics: checkout Google scholar on that, <u>here!</u>

Recognition

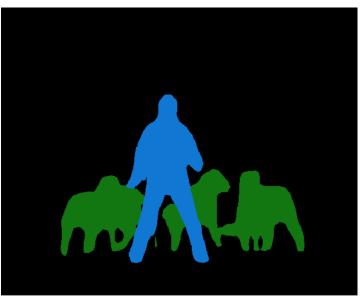


→ "Saiga antilope"

Task: Label an image by its class membership

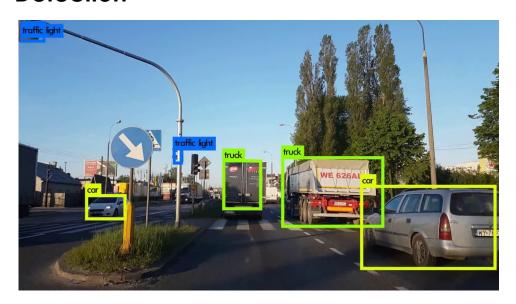
Segmentation





Task: Label each pixel of an image by its class membership.

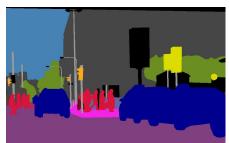
Detection



Task: Locate and label objects via, e.g., bounding boxes (i.e., coordinates)

Panoptic Segmentation

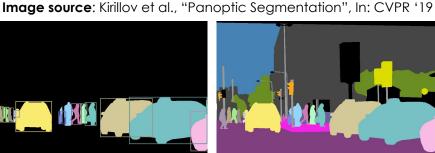




Semantic segmentation



Instance segmentation



Panoptic segmentation

Goal: Unify <u>semantic segmentation</u> and <u>instance segmentation</u>.

Image-to-Image translation



Arial → Map



BW → Color





Label map → Image

Text-to-Image Generation



Prompt: An extremely angry bird.



<u>Prompt</u>: A photo of a Persian cat wearing sunglasses and a red shirt skateboarding on a beach.

Synthesizing novel views



<u>Dalle-2 Demo</u> (not publicly available, you need to sign up and get approved).

Some interesting resources

Browse D. H. Hubel's online book (Nobel prize winner, 1981) http://hubel.med.harvard.edu/book/bcontex.htm

Read one of his and Torsten Wiesel's seminal papers, e.g.,

Receptive Fields and Functional Architecture of Monkey Striate Cortex,

D. H. Hubel and T. N. Wiesel

J. Physiol., 1968

http://www.ncbi.nlm.nih.gov/pubmed/4966457)