

**I2C** Drivers  
For  
**AVR** Microcontrollers

Nti Team

Software Requirement Specification Document

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## 1. Scope of Document

This document specifies requirements on the module DIO Driver.

### 1.1 Constraints

First scope for specification of requirements on basic software modules is systems which are not safety relevant. For this reason safety requirements are assigned to medium priority.

## 2. Requirements Structure

Each module specific chapter contains a short functional description of the Basic Software Module. Requirements of the same kind within each chapter are grouped under the following headlines (where applicable):

Functional Requirements: -

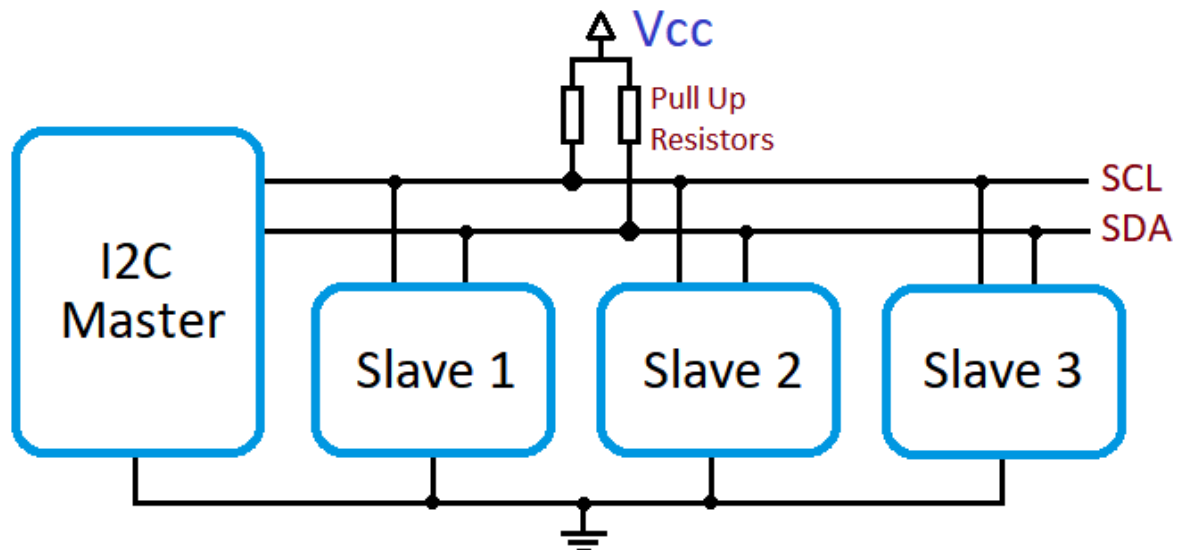
- Configuration (which elements of the module need to be configurable).
- Initialization.
- Normal Operation.
- Shutdown Operation.
- Fault Operation.
- .....

Non-Functional Requirements:-

- Timing Requirements.
- Resource Usage.
- Usability.
- Output for other WPs (e.g. Description Templates, Tooling,...).
- .....

### 3. Functional Overview

I2C, or Inter-Integrated Circuit, is a popular serial communication protocol used for connecting various digital devices within an embedded system or on a printed circuit board (PCB). It is widely used in a variety of applications, including sensors, displays, EEPROMs, and many other components.



### 4. Requirement Specification

#### 4.1 Functional Requirements

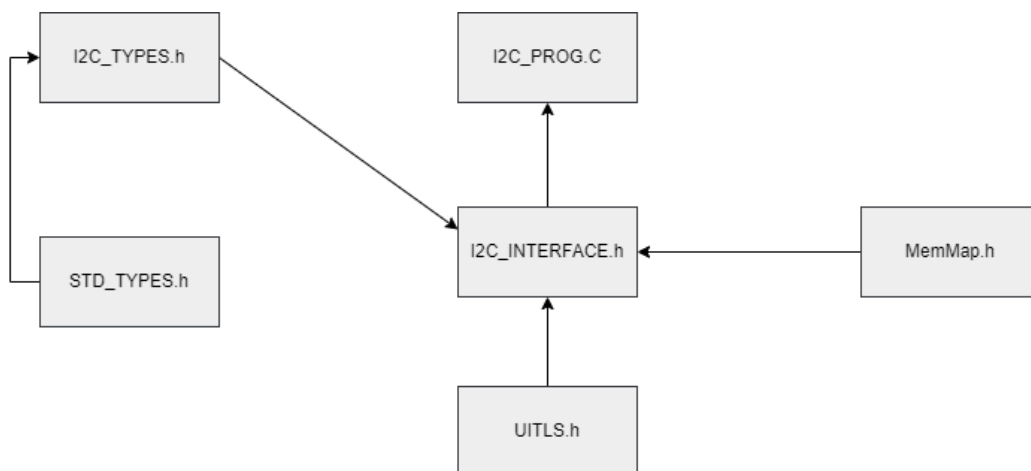
- [I2C\_001] the driver shall be compatible with all AVR microcontrollers.
- [I2C\_002] The AVR I2C driver shall not buffer data when providing read and write services.
- [I2C\_003] The AVR I2C driver shall provide initialization function to set specific configuration.
- [I2C\_004] The AVR I2C driver shall provide start function.
- [I2C\_005] The AVR I2C driver shall provide Stop function.
- [I2C\_006] The AVR I2C driver shall provide Write function and write with NACK function.

- [I2C\_007] The AVR I2C driver shall provide read function and read withACK /NACK function.
- [I2C\_008] The AVR I2C driver shall provide function to get status back.

#### 4.2 Non-functional requirements

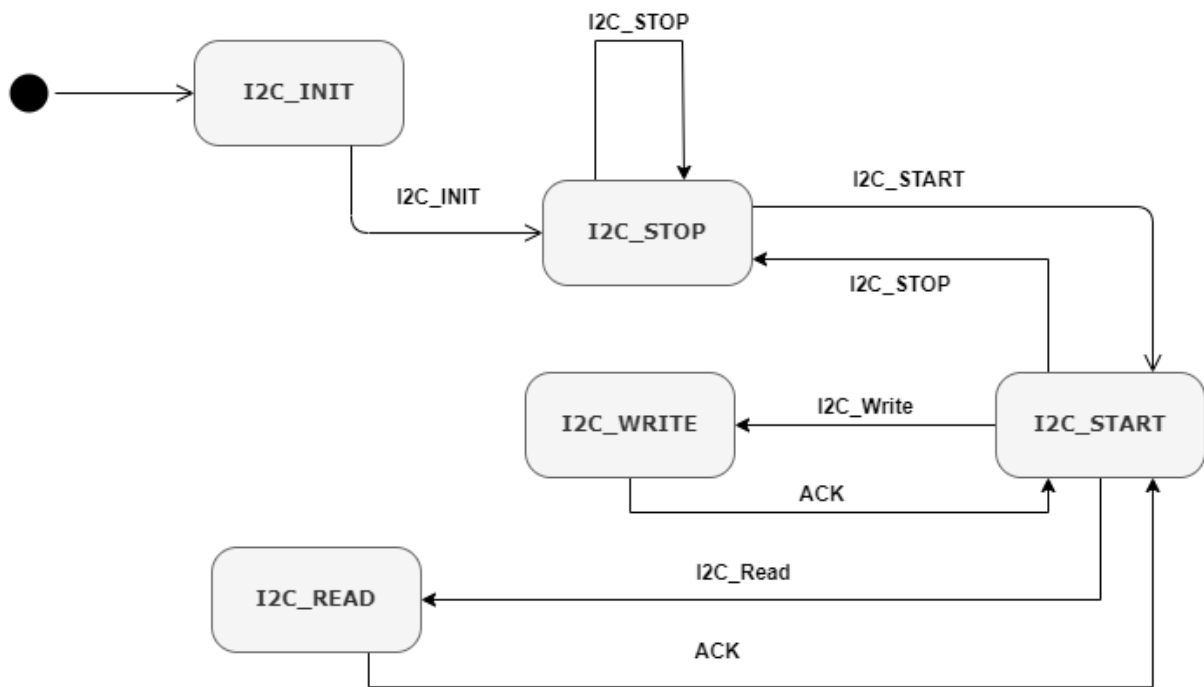
- The driver shall be easy to use and understand.
- The driver shall be well-documented.
- The driver shall be efficient and use minimal resources.
- The driver shall be reliable and robust.
- In addition to the above requirements, the I2C driver should also meet the following non-technical requirements.
- The driver should be open source and freely available to use.
- The driver should be actively maintained and supported by the community.
- The driver should be well-tested and documented.
- The driver should be compatible with a variety of development tools and environments.

#### File Structure



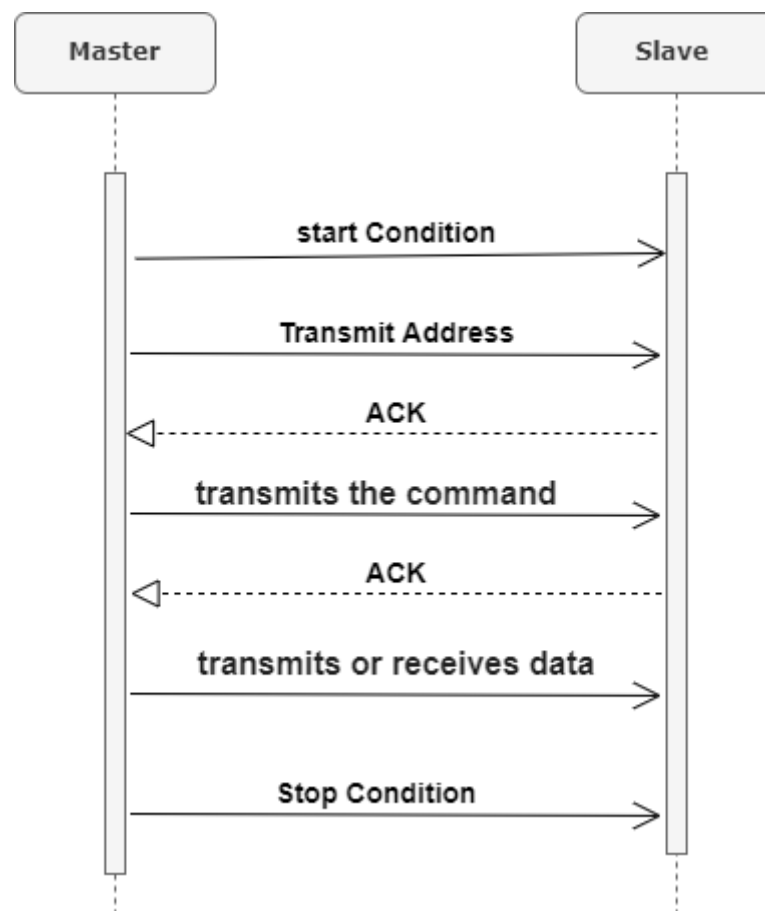
**Figure 1: I2C Files**

## 5. State Machine



**Figure 2: I2C State Machine**

## Sequence diagram



**Figure 3: I2C Sequence diagram**

## Acceptance Criteria

The I2C driver shall be accepted when it meets the following criteria:

- The driver shall compile and run without errors on all AVR microcontrollers.
- The driver shall pass all unit tests.
- The driver shall pass all integration tests.
- The driver shall pass all system tests

## 6. References

1. Developers of NTI team.
2. AVR Microcontroller Datasheets.