TIMER Driver for AVR Microcontrollers

Version: 1st Date: 26/10/2023

API specification

1.1 Type definitions

Name:	Timer_channel
Type:	Enum
Element:	timer0,timer1,timer2
Description:	These are the return which timer you use

Name:	Timer_mode
Type:	Enum
Element:	normal,pwm,ctc,fast_pwm
Description:	These are the return which mode you use

Name:	Timer_clock
Type:	Enum
Element:	t_noClock,t_prescaler_1,t_prescaler_8,t_prescaler_64,t_pr escaler_256,t_prescaler_1024,external_falling,external_ri sing, t2_noclock=0,t2_prescaler_1,t2_prescaler_8,t2_prescaler_3 2,t2_prescaler_64,t2_prescaler_128,t2_prescaler_256,t2_pr escaler_1024

Description:	These are the return which clock you use

Name:	TIMER_config
Type:	struct
Element:	Timer_channel channel;
	uint16 initial_value;
	Timer_clock clock;
	Timer_mode mode;
	Timer_clock prescaler;
	uint16 compare_value;
Description:	These are timer config (channel,mode,intial
	value, clock)

2. Function definitions

Service name:	Timer_init
Syntax:	<pre>void Timer_init(const TIMER_config *</pre>
	Config_Ptr)
Parameters (in):	pointer to <u>struct</u> (TIMER_congif)
Parameters	none
(in/out):	
Parameters (out):	none

Return value:	none
Description:	Initialize the Timer
NUM:	

Service name:	Timer_delnit
Syntax:	<pre>void Timer_deInit(Timer_channel channel);</pre>
Parameters (in):	channel of the timer -> timer 0,1,2
Parameters (in/out):	None
Parameters (out):	None
Return value:	None
Description:	<u>deinitialize</u> the Timer
NUM:	

Service name:	Timer_setCallBack
Syntax:	void Timer_setCallBack(Timer_channel
	channel, void (*a_ptr)(void))
Parameters (in):	channel of the timer -> timer 0,1,2
Parameters	None
(in/out):	
Parameters (out):	pointer to Call Back function

Return value:	None
Description:	
NUM:	